

Capacity Bounded Differential Privacy

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Intoduction

Privacy risks in ML: Richer model space, more details about small populations in data

Example: Jacob partakes in study on movie DBs

	1	2	3	4	5	6	...	N
Jacob	1	1	1	1	1	1	...	1
User 2	1	1	1	1	1	1	...	1
User 3	1	1	1	1	1	1	...	1
...								
User N	1	1	1	1	1	1	...	1

Model Insight
If you dislike movies 1&4, you will like movie N.

Jacob's Public Blog:

Post 1: Movie 1 had terrible acting!
Post 2: Movie 5 deserves 2 thumbs up!
Post 3: Movie 4 was less exciting than watching paint dry!

Adversary with blog and model insight could leak Jacob's Movie N rating!

Formalization: Let D, D' be two DBs one with population P and one without. Then, learner M satisfies (α, ϵ) -Renyi Differential Privacy (RDP) if:

$$R_\alpha(M(D), M(D')) \leq e^{(\alpha-1)\epsilon}$$

Interpretation: P cannot change the distribution of $M(D)$, so no one can even tell if P is in D .

Capacity Bounded Differential Privacy

Renyi-DP can be written dually (for some f^*) as

$$\sup_{h: \Omega \rightarrow \mathbb{R}} \left(\mathbb{E}_{x \sim M(D)} [h(x)] - \mathbb{E}_{x \sim M(D')} [f^*(h(x))] \right) \leq e^{(\alpha-1)\epsilon}$$

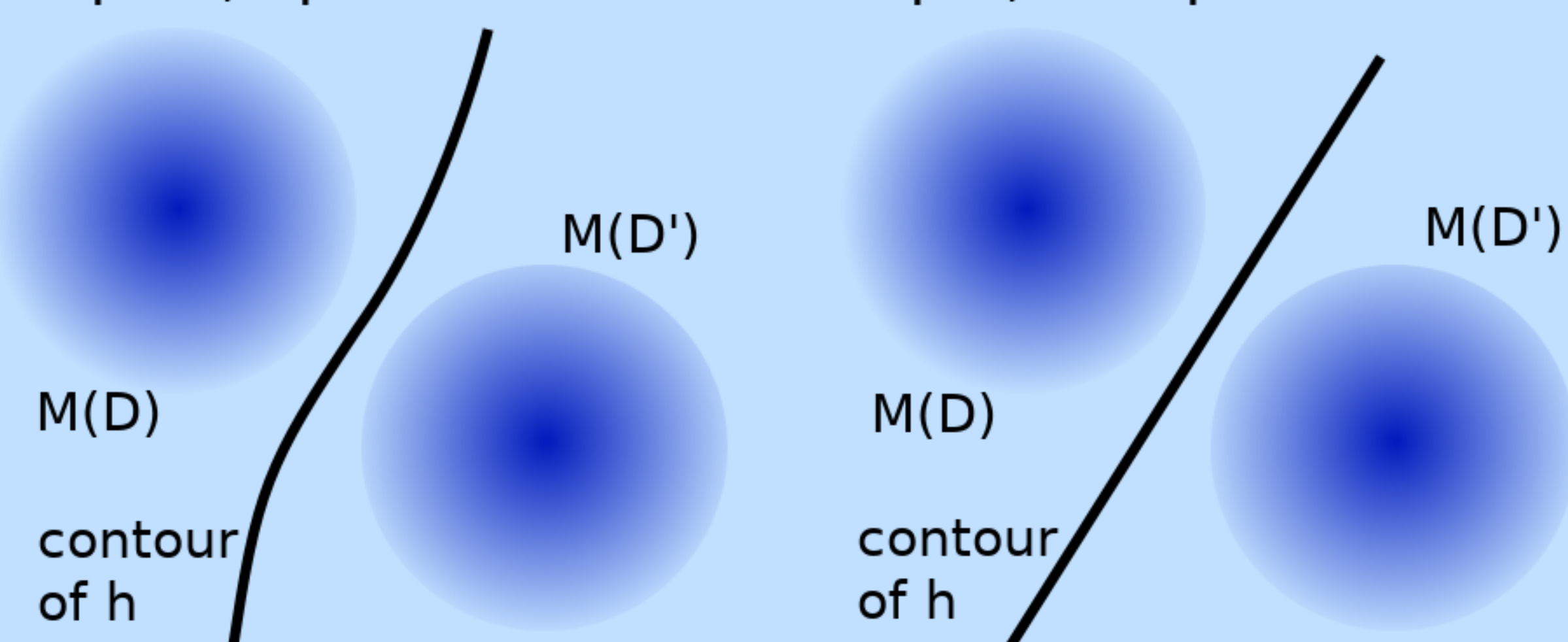
Same definition as f -GAN

Interpretation: How well can adversarial h distinguish $M(D)$ and $M(D')$?

Key Idea: In certain cases we know a restriction on h which limits its power to distinguish

Complex, optimal h

Simple, less powerful h

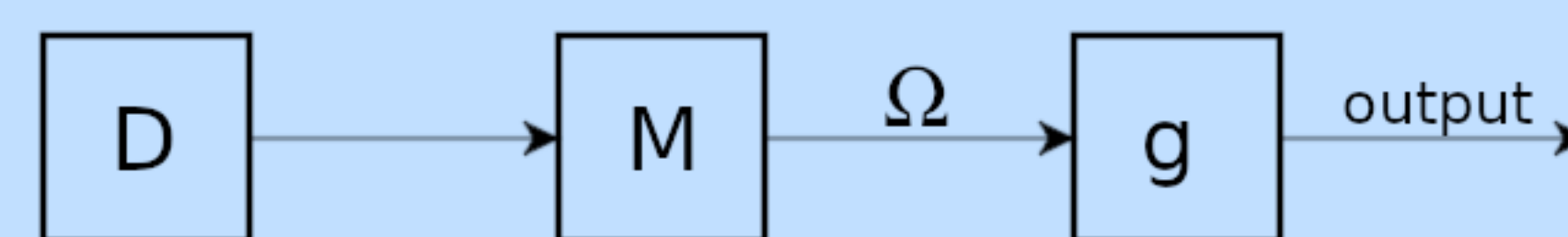


Definition (H -capacity bounded Renyi-DP):

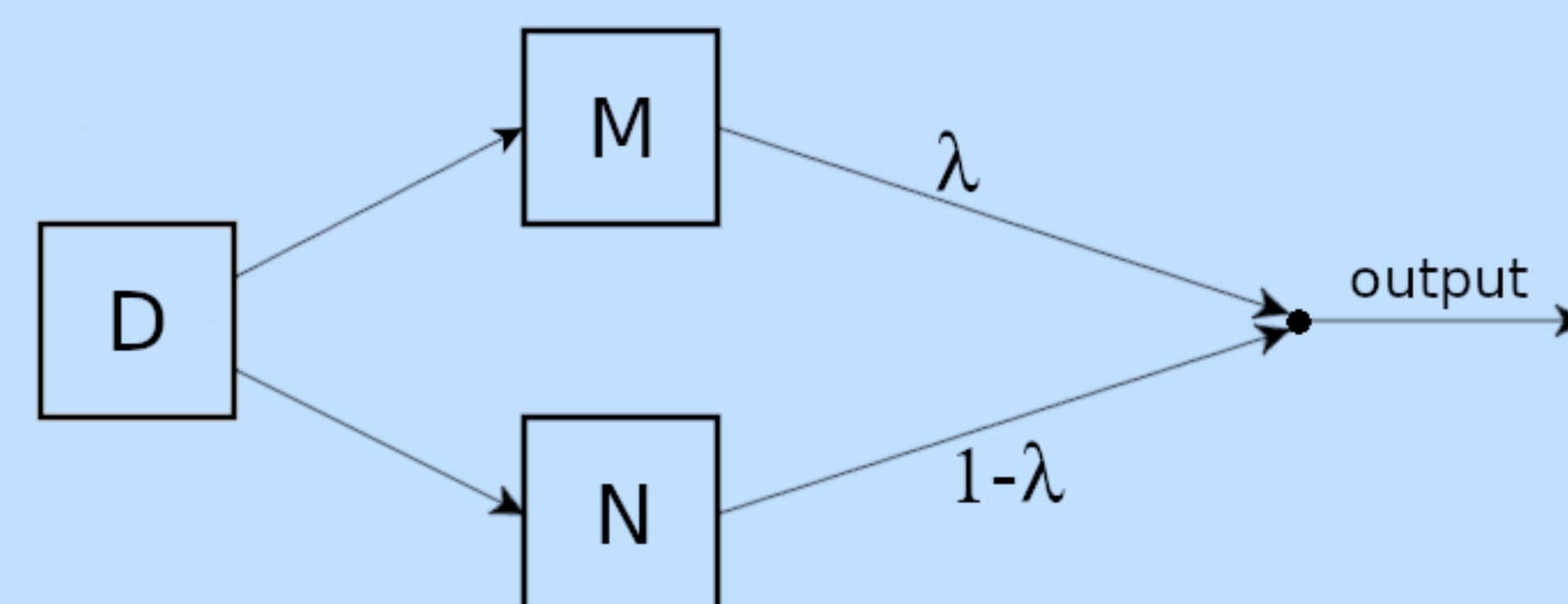
$$\sup_{h \in \mathcal{H}} \left(\mathbb{E}_{x \sim M(D)} [h(x)] - \mathbb{E}_{x \sim M(D')} [f^*(h(x))] \right) \leq e^{(\alpha-1)\epsilon}$$

Properties of CBP

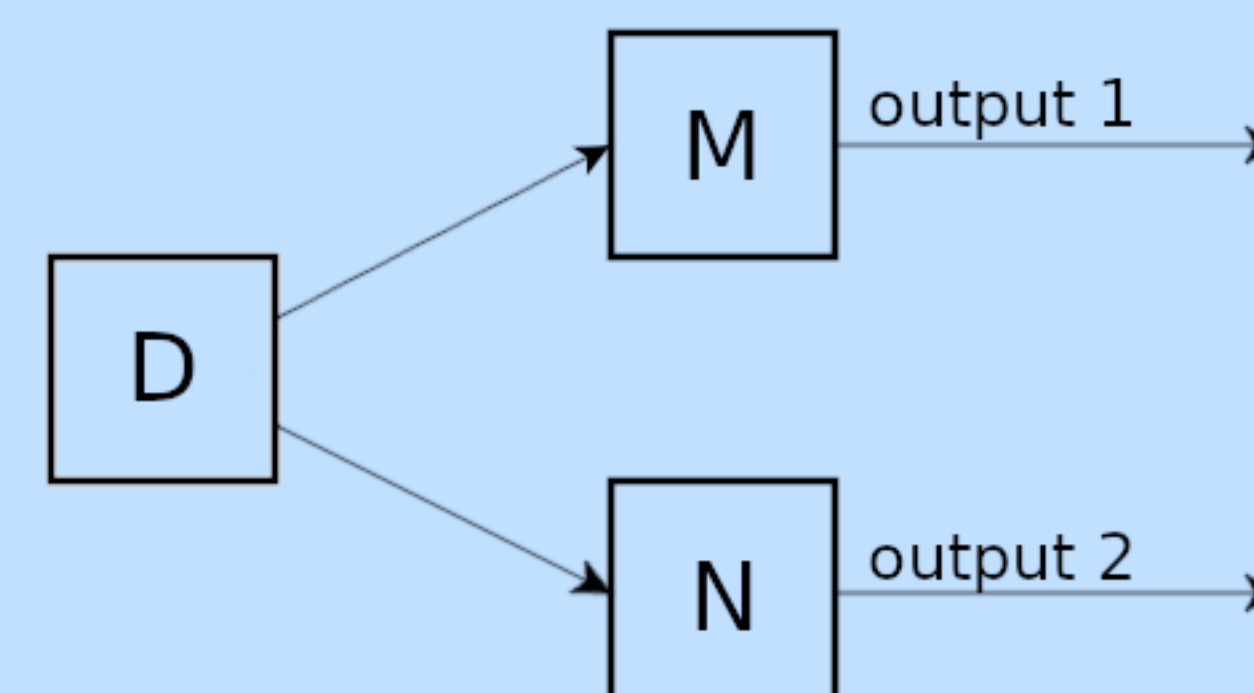
Let M, N satisfy H, K -CBP with params ϵ, γ respectively



Post-processing: H, G, I function classes such that $I \circ G \subseteq H$. Then, $g \circ M$ satisfies I -CBP with param ϵ .
Standard DP makes no restriction on G but that is necessary here



Convexity: $H=K$ and O is model that returns M w.p. λ and N w.p. $1-\lambda$. Then, O satisfies H -CBP with parameter $\lambda\epsilon + (1-\lambda)\gamma$.
Same result as standard DP



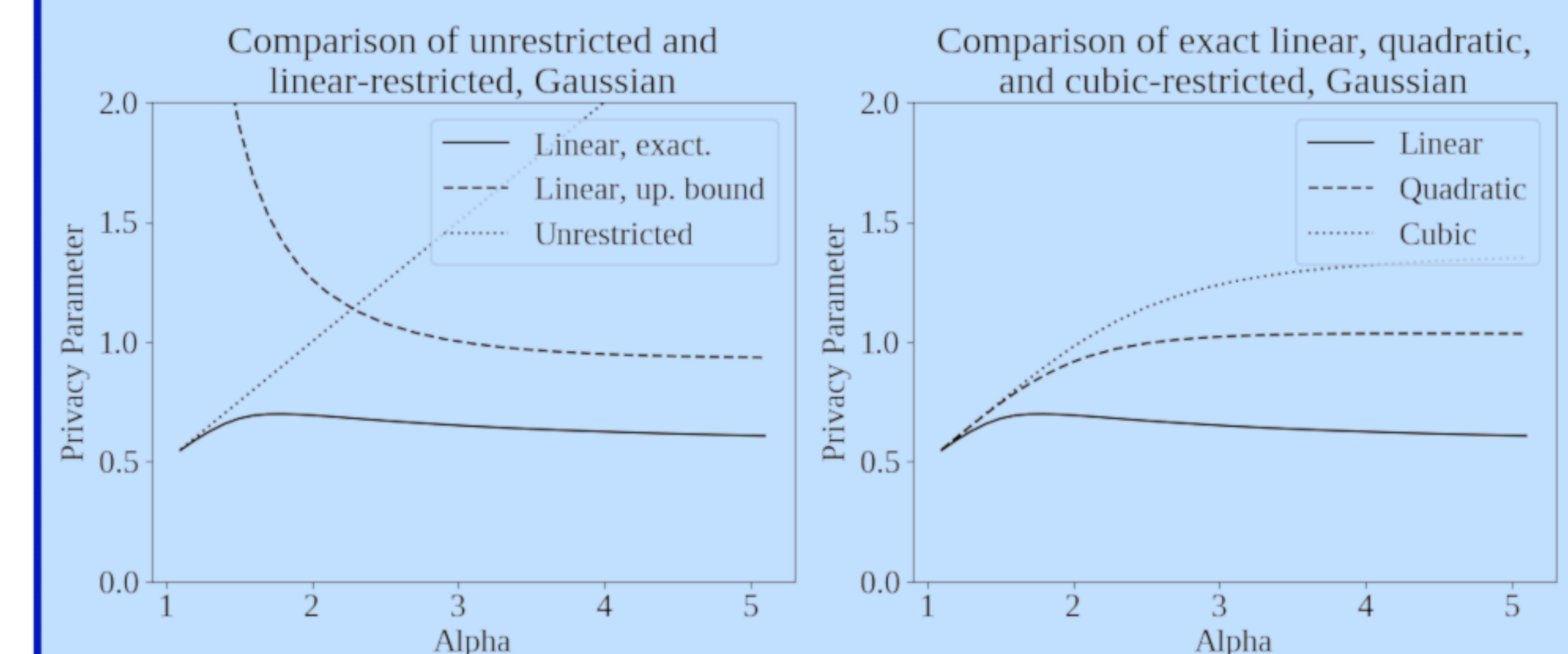
Composition: G is $\{h + k | h \in H, k \in K\}$, O is the model (M, N) . Then, O satisfies G -CBP with parameter $\epsilon + \gamma$.
Standard DP allows adaptive composition (N can look at M output)

Mechanisms

Gaussian: For $D \in \mathbb{R}^d$:
Renyi DP: $\frac{\alpha}{2\sigma^2}$
Lin-CBP: at most $\frac{1}{\alpha-1} \log \left(1 + \frac{2^{d(\alpha-1)} \sqrt{\pi/2}^{\alpha-1}}{\sigma^\alpha} \right)$
 $M(D) = D + \text{i.i.d. std} = \sigma$

Laplace: For $D \in \mathbb{R}^d$:
Renyi DP: at least $\epsilon - \frac{d \log(2)}{\alpha-1}$
Lin-CBP: at most $\frac{1}{\alpha-1} \log \left(1 + 2^{d(\alpha-1)} \epsilon^\alpha \right)$
 $M(D) = D + \text{i.i.d. std} = 1/\epsilon$

Mechanism Performance Plots

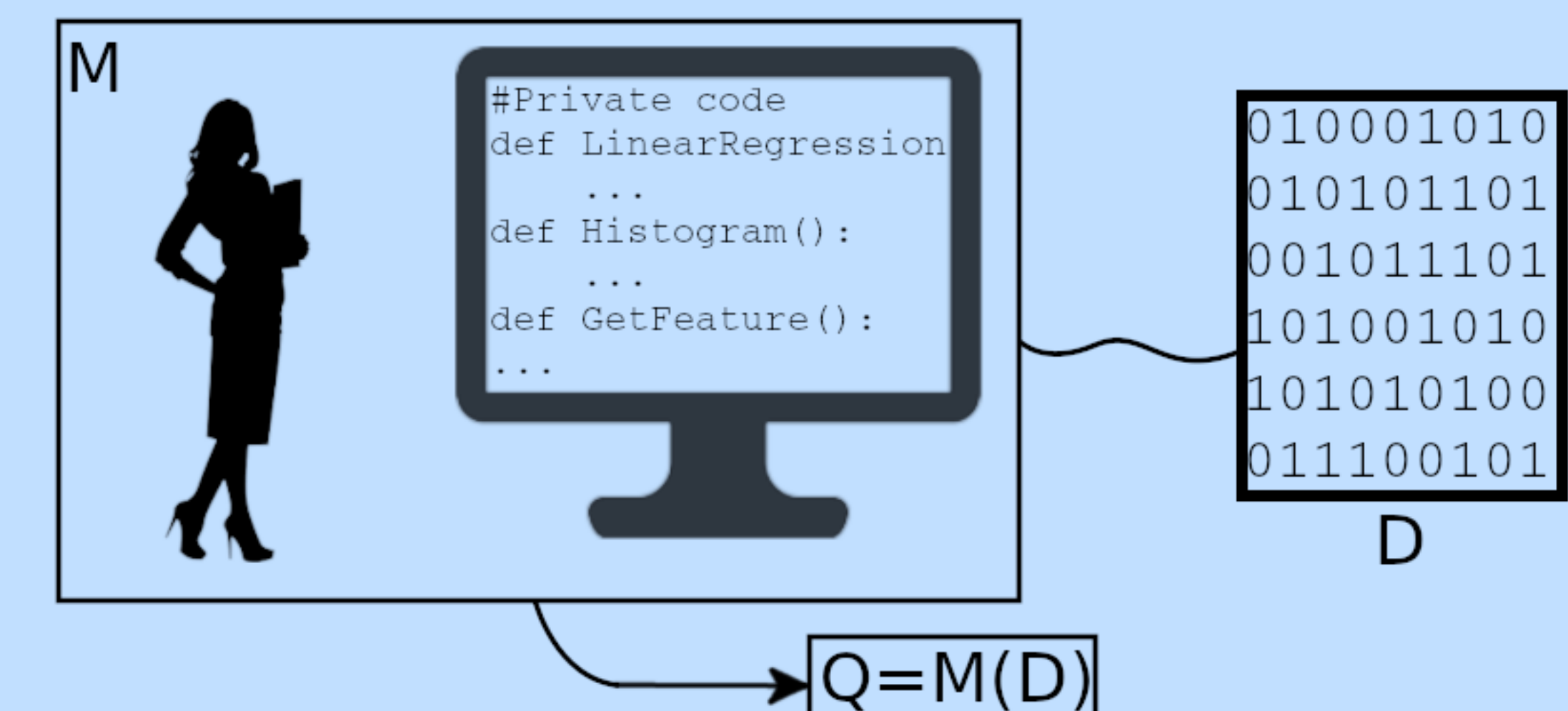


ϵ is much smaller for Poly-CBP

Subtle points: Poly-CBP eventually decreases with α
Our lin-CBP bound is worse than RDP for small α

Generalization Properties

Concrete Example: Analyst produces model Q using private library with access to D



Theorem: If M satisfies capacity-bounded DP then empirical loss and true loss are close:

$$\left| \mathbb{E}_{D \sim \mathcal{D}^d} \left(\frac{1}{d} \sum_{i=1}^d \ell(Q, x_i) - \mathbb{E}_{x \sim \mathcal{D}} [\ell(Q, x_i)] \right) \right| \leq 8\sqrt{\epsilon}$$

Conclusion

- CBP is novel privacy approach when adversary is known to be bounded
- Satisfies many information-theoretic properties that RDP satisfies
- For simple adversaries can prove stronger privacy than RDP for the same algorithm

Future Steps

- Find M which is not RDP but is H -CBP for finite parameter ϵ
- Make composition result adaptive
- Determine ϵ for more complex H
- Prove other generalization properties