# TMA4250 Spatial Statistics

## Project 1 - Random Fields and Gaussian Random Fields

Christian Moen, Jim Totland

2/3/2022

#### Problem 1

**a**)

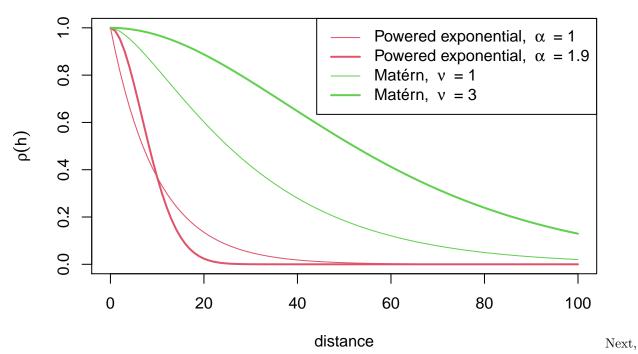
The positive semi-definite (PSD) property of the correlation function can be stated as follows.  $\forall m \in \mathbb{Z}_+, \forall a_1, \ldots, a_m \in \mathbb{R} \text{ and } \forall s_1, \ldots, s_m \in \mathcal{D}, \text{ we have}$ 

$$\sum_{i=1}^{m} \sum_{j=1}^{m} a_i a_j \rho(\boldsymbol{s}_i, \boldsymbol{s}_j) \ge 0.$$

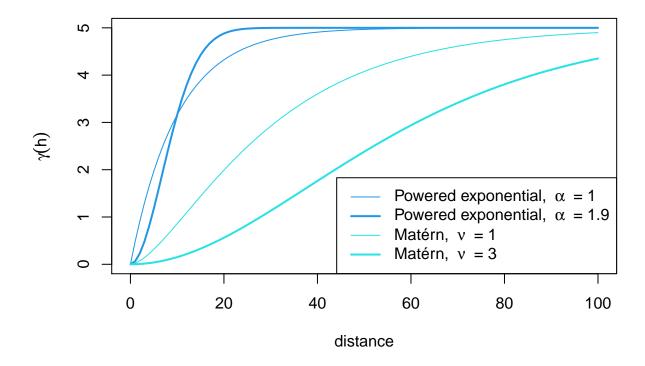
To explain why this requirement is necessary, we observe that (in this case)  $\rho(s_i, s_j) = \sigma^{-2}c(s_i, s_j)$ , where c is the covariance function. Consequently,

$$\sum_{i=1}^{m} \sum_{j=1}^{m} a_i a_j \rho(\mathbf{s}_i, \mathbf{s}_j) = \sigma^{-2} \sum_{i=1}^{m} \sum_{j=1}^{m} a_i a_j c(\mathbf{s}_i, \mathbf{s}_j)$$
$$= \sigma^{-2} \operatorname{Var} \left[ \sum_{i=1}^{m} a_i X(\mathbf{s}_i) \right].$$

Since the variance must be non-negative, it is clear that the PSD property above must be satisfied. Below, the different correlation functions are illustrated. ingen grunn til to plots, fordi ulik varians gir samme korrelasjon?!



we plot the semi-variograms. to figurer her kanskje? litt unødvendig? spør om dette.



b)

By the definition of a GRF,  $X \sim \mathcal{N}(\mu, \Sigma_X)$ . The parameters are calculated from the mean- and covariance function of the GRF, such that  $\mu = \mathbf{0}$  and  $(\Sigma_X)_{ij} = \sigma^2 \rho(\|i - j\|)$ . First, we create grids which span all the parameter combinations and summarize them in two tables.

```
# Parameters
sigma2 <- c(1, 5)
alpha <- c(1, 1.9)
nu <- c(1, 3)
a.exp <- 10
a.matern <- 20

params.exp <- expand.grid(sigma2, alpha, a.exp)
params.exp <- cbind(params.exp, 1:4)
colnames(params.exp) <- c("sigma2", "alpha", "a.exp", "combination")

params.matern <- expand.grid(sigma2, nu, a.matern)
params.matern <- cbind(params.matern, 1:4)
colnames(params.matern) <- c("sigma2", "nu", "a.matern", "combination")

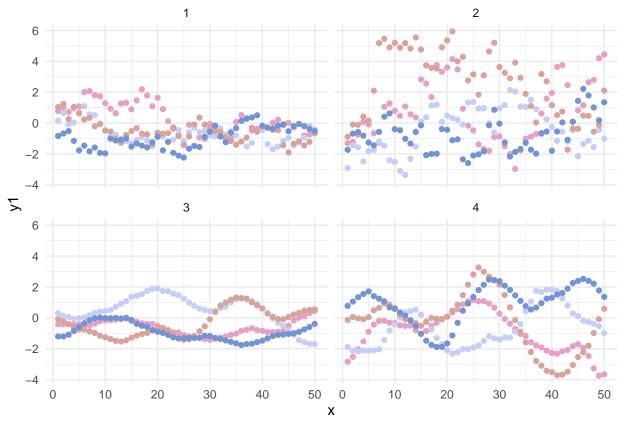
knitr::kable(params.exp)</pre>
```

sigma2	alpha	a.exp	combination
1	1.0	10	1
5	1.0	10	2
1	1.9	10	3
5	1.9	10	4

sigma2	nu	a.matern	combination
1	1	20	1
5	1	20	2
1	3	20	3
5	3	20	4

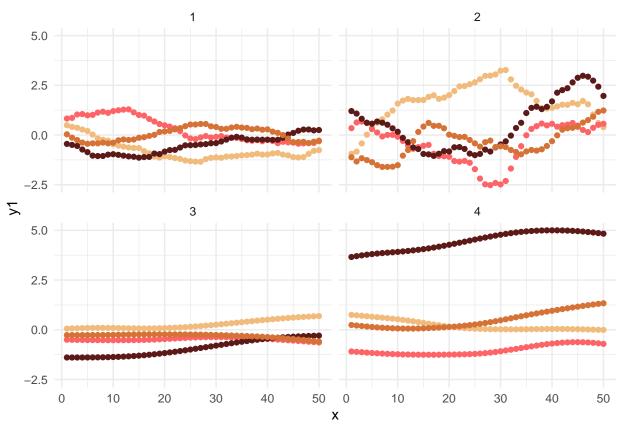
Then, we simulate the 4 realizations with the powered exponential covariance function for all the parameter combinations.

```
n <- 50 # Number of grid points
D.tilde <- 1:n # Grid
df.exp \leftarrow data.frame(x = rep(D.tilde, 4),
                      y1 = rep(NA, 4), y2 = rep(NA, 4), y3 = rep(NA, 4), y4 = rep(NA, 4),
                      combination = rep(NA, 4 * n))
for(i in 1:nrow(params.exp)){
  mu \leftarrow rep(0, n)
  Sigma <- cov.spatial(as.matrix(dist(expand.grid(D.tilde))),</pre>
                      cov.mod = "powered.exponential",
                      cov.pars = c(params.exp$sigma2[i], params.exp$a.exp[i]),
                      kappa = params.exp$alpha[i])
  X <- mvrnorm(4, mu, Sigma)</pre>
  df.exp$y1[((i-1)*n + 1):(i*50)] = X[1, ]
  df.exp$y2[((i-1)*n + 1):(i*50)] = X[2, ]
  df.exp$y3[((i-1)*n + 1):(i*50)] = X[3, ]
  df.exp$y4[((i-1)*n + 1):(i*50)] = X[4, ]
  df.exp$combination[((i-1)*n + 1):(i*50)] = rep(i, 50)
}
palette <- wes_palette("GrandBudapest2", n = 4)</pre>
df \leftarrow data.frame(t(X), D = D.tilde)
ggplot(df.exp, aes(x = x)) + geom_point(aes(y = y1), color = palette[1]) +
  geom_point(aes(y = y2), color = palette[2]) +
  geom_point(aes(y = y3), color = palette[3]) +
  geom_point(aes( y = y4), color = palette[4]) +
  facet_wrap( ~combination, nrow = 2) + theme_minimal()
```



Unsurprisingly, we see that higher variance (facet 2 and 4) leads to more variability in the simulations. When the power parameter  $\alpha = 1$ , the realizations are much more jagged and less smooth compared to when  $\alpha = 1.9$  (facet 3 and 4). We follow the same procedure to simulate with a Matérn covariance function.

```
df.matern \leftarrow data.frame(x = rep(D.tilde, 4),
                      y1 = rep(NA, 4), y2 = rep(NA, 4), y3 = rep(NA, 4), y4 = rep(NA, 4),
                      combination = rep(NA, 4 * n)
for(i in 1:nrow(params.matern)){
  mu \leftarrow rep(0, n)
  Sigma <- cov.spatial(as.matrix(dist(expand.grid(D.tilde))),</pre>
                      cov.mod = "matern",
                      cov.pars = c(params.matern$sigma2[i], params.matern$a.matern[i]),
                      kappa = params.matern$nu[i])
  X <- mvrnorm(4, mu, Sigma)</pre>
  df.matern\$y1[((i-1)*n + 1):(i*50)] = X[1,]
  df.matern\$y2[((i-1)*n + 1):(i*50)] = X[2, ]
  df.matern\$y3[((i-1)*n + 1):(i*50)] = X[3, ]
  df.matern\$y4[((i-1)*n + 1):(i*50)] = X[4,]
  df.maternscombination[((i-1)*n + 1):(i*50)] = rep(i, 50)
}
palette <- wes_palette("GrandBudapest1", n = 4)</pre>
ggplot(df.matern, aes(x = x)) + geom_point(aes(y = y1), color = palette[1]) +
  geom_point(aes(y = y2), color = palette[2]) +
  geom_point(aes(y = y3), color = palette[3]) +
  geom_point(aes( y = y4), color = palette[4]) +
  facet_wrap( ~combination, nrow = 2) + theme_minimal()
```



We also see here that higher variance (facet 2 and 4) leads to more variability in the simulations. A higher smoothness parameter,  $\nu$ , also leads to smoother realizations, as expected.

#### b)

We plan to observe  $Y_1$ ,  $Y_2$  and  $Y_3$  at locations  $s_1 = 10$ ,  $s_2 = 25$  and  $s_3 = 30$ , respectively. The observation model is given by

$$Y_i = X(s_i) + \varepsilon_i, \quad i = 1, 2, 3,$$

where  $\varepsilon_1, \varepsilon_2, \varepsilon_3 \stackrel{\text{iid}}{\sim} \mathcal{N}(0, \sigma_N^2)$  and independent of X. We let  $\mathbf{Y} = (Y_1, Y_2, Y_3)^T$ . Since  $\mathbf{Y}$  is a linear combination of multivariate normal distributions, it is multivariate normally distributed itself, with mean

$$E[Y] = 0,$$

and

$$\operatorname{Cov}[\boldsymbol{Y}] = \operatorname{diag}(\sigma_N^2) + \Sigma_X.$$

We consider the Matérn covariance model with  $\sigma^2 = 5$  and  $\nu = 3$  and pick one realization from b). When  $\sigma_N^2 = 0$ ,  $Y_i = X(s_i)$ , such that the realization  $\boldsymbol{Y} = \boldsymbol{y}$  becomes

```
s = c(10, 25, 30) # Positions of interest
realization = filter(df.matern, combination == 4)[, 2] # First realization over entire grid
(y = realization[s])
```

## [1] 0.52750288 0.05519770 0.02676082

When  $\sigma_N^2 = 0.25$ , the realization  $\boldsymbol{y}$  becomes

$$y + rnorm(3, mean = 0, sd = sqrt(0.25))$$

## [1] -0.006678549 0.270175038 -0.148404697

d)

We now consider X|Y = y. Its distribution is given by

$$[X|Y = y] = [X, Y][Y]^{-1} = [Y|X = x][X][Y]^{-1},$$

Where all factors have a multivariate normal distribution. We need to estimate the parameters associated with the GRF X, which we denote  $\theta_X$ , and we also need to estimate  $\sigma_N^2$ . In order to this, we can use MCMC or maximum likelihood estimation.

**e**)

Before coding up the simulation, we note that  $Y|X = x \sim \mathcal{N}_3(\mu_Y, \sigma_N^2 I_3)$ , where

### **Problem 3: Parameter Estimation**

We consider the stationary GRF  $\{X(s); s \in \mathcal{D} = [1, 30]^2 \subset \mathbb{R}\}$  with

$$\begin{split} \mathrm{E}[X(\boldsymbol{s})] &= \mu = 0, \quad \boldsymbol{s} \in \mathcal{D}, \\ \mathrm{Var}[X(\boldsymbol{s})] &= \sigma^2, \quad \boldsymbol{s} \in \mathcal{D}, \\ \mathrm{Corr}[X(\boldsymbol{s}), X(\boldsymbol{s}')] &= \exp(-\|\boldsymbol{s} - \boldsymbol{s}'\|/a), \quad \boldsymbol{s}, \boldsymbol{s}' \in \mathcal{D} \end{split}$$

We let  $\tilde{\mathcal{D}} = \{1, 2, \dots, 30\}^2$  be a regular grid of  $\mathcal{D}$ , and set the marginal variance  $\sigma^2 = 2$  and the spatial scale a = 3.