	Date:
	(2)
8	9
¢	a) with a non-standard estimator it may be too
1	difficult to derive an analytical expression for an estima
1	difficult to derive an analytical expression for an estimate of the standard error. Or in some cases, it may not even be a worth the effort.
-14	even here worth the effect.
+	Rootstrap estimate talps with the care. The
-	sootstrap estimate of the standard ever can be
+	ghen-Ly = 1
+	$\frac{1}{SD} \left[\frac{\alpha}{\alpha} \left(S^{\dagger} \right) \right] = \left[\frac{Z^{B}}{\alpha} \left(\alpha \left(S^{\dagger} \right) - \alpha^{\dagger} \right)^{2} \right]$ $\frac{1}{SD} \left[\frac{\alpha}{\alpha} \left(S^{\dagger} \right) \right] = \left[\frac{Z^{B}}{\alpha} \left(\alpha \left(S^{\dagger} \right) \right) - \alpha^{\dagger} \right]^{2}$ $\frac{1}{SD} \left[\frac{\alpha}{\alpha} \left(S^{\dagger} \right) \right] = \left[\frac{Z^{B}}{\alpha} \left(\alpha \left(S^{\dagger} \right) \right) - \alpha^{\dagger} \right]^{2}$ $\frac{1}{SD} \left[\frac{\alpha}{\alpha} \left(S^{\dagger} \right) \right] = \left[\frac{Z^{B}}{\alpha} \left(\alpha \left(S^{\dagger} \right) \right) - \alpha^{\dagger} \right]^{2}$ $\frac{1}{SD} \left[\frac{\alpha}{\alpha} \left(S^{\dagger} \right) \right] = \left[\frac{Z^{B}}{\alpha} \left(\alpha \left(S^{\dagger} \right) \right) - \alpha^{\dagger} \right]^{2}$ $\frac{1}{SD} \left[\frac{\alpha}{\alpha} \left(S^{\dagger} \right) \right] = \left[\frac{Z^{B}}{\alpha} \left(\alpha \left(S^{\dagger} \right) \right] - \alpha^{\dagger} \right]^{2}$ $\frac{1}{SD} \left[\frac{\alpha}{\alpha} \left(S^{\dagger} \right) \right] = \left[\frac{Z^{B}}{\alpha} \left(\alpha \left(S^{\dagger} \right) \right] - \alpha^{\dagger} \right]^{2}$ $\frac{1}{SD} \left[\frac{\alpha}{\alpha} \left(S^{\dagger} \right) \right] = \left[\frac{Z^{B}}{\alpha} \left(\alpha \left(S^{\dagger} \right) \right] - \alpha^{\dagger} \right]^{2}$ $\frac{1}{SD} \left[\frac{\alpha}{\alpha} \left(S^{\dagger} \right) \right] = \left[\frac{Z^{B}}{\alpha} \left(\alpha \left(S^{\dagger} \right) \right] - \alpha^{\dagger} \right]^{2}$ $\frac{1}{SD} \left[\frac{\alpha}{\alpha} \left(S^{\dagger} \right) \right] = \left[\frac{Z^{B}}{\alpha} \left(\alpha \left(S^{\dagger} \right) \right] - \alpha^{\dagger} \right]^{2}$ $\frac{1}{SD} \left[\frac{\alpha}{\alpha} \left(S^{\dagger} \right) \right] = \left[\frac{Z^{B}}{\alpha} \left(\alpha \left(S^{\dagger} \right) \right] - \alpha^{\dagger} \right]^{2}$ $\frac{1}{SD} \left[\frac{\alpha}{\alpha} \left(S^{\dagger} \right) \right] = \left[\frac{Z^{B}}{\alpha} \left(\alpha \left(S^{\dagger} \right) \right] - \alpha^{\dagger} \right]^{2}$ $\frac{1}{SD} \left[\frac{\alpha}{\alpha} \left(S^{\dagger} \right) \right] = \left[\frac{Z^{B}}{\alpha} \left(\alpha \left(S^{\dagger} \right) \right] - \alpha^{\dagger} \right]^{2}$ $\frac{1}{SD} \left[\frac{\alpha}{\alpha} \left(S^{\dagger} \right) \right] = \left[\frac{Z^{B}}{\alpha} \left(\alpha \left(S^{\dagger} \right) \right] - \alpha^{\dagger} \right]^{2}$ $\frac{1}{SD} \left[\frac{\alpha}{\alpha} \left(S^{\dagger} \right) \right] = \left[\frac{Z^{B}}{\alpha} \left(S^{\dagger} \right) \right] + \left[\frac{Z^{B}}{\alpha} \left(S^{\dagger} \right$
-	$\frac{3b}{b} = \frac{2}{a} \left(\frac{a(3, b)}{a(3, b)} \right)$
	Manda on Brief da
	As you can see the only input it requires is the
	Bootstrap distribution which in tun only requires a
	scriple of the population is - is to the
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2	- Wit was the super the surply of milecula to
((b) The Poolstrap perentile method for constructing
	confidence intervals is the following:
	- Fa a given sample S generale B tootstrap damples
	S, , So by sampling with replacement from
-4	the isample of soul and six
Ì	- For the both bootshap sample (b=1,, B) calculate
	- to (Spo) transplan with priliper or
	- Fron the values a,, - = , aB, find
	Plower = 9a (P/2) & supper = 9a (1-P/2)
<u> (</u>	Tours of the second of the sec
	- Then the 100(1-p) % confidence interval is
	[arower, aupper]

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(0) Suppose the tregression model is the in me is and y = d+p(xi-x)+ kite all + Where Ri ~ Fine the enforce come from some If we had a f B then IT; = [x+ B(x;-x)] and { r,, ..., rn} would be a sample from F. - We fit the model to find 2, \(\beta \) and then obtain the residuals

Fi = y; -y; -[x+\beta(x; -\beta)]

The sample of residuals or estimates of the errors is \(\beta = \beta(\beta), \beta(\beta) = \beta(\beta), \beta(\beta) \\ \end{arrow} - We can then use the sample of residuals to estimate Fusing the empirical afformation of (d) The time with a state of the st - We than perform the bootshap using it resampling with replacement from R, then y= 2+8 (n; -n) + K; * and then the bootstrap sample is $S_{n}^{*} = \{(x_{n}, y_{n}^{*}), (x_{n}, y_{n}^{*})\}$ 100(1-1) / confine suline : (4-1)001