**Todo**

1. Implement path planning algorithm
   1. Find out how to produce grid given set of points
   2. Find path after producing grid
2. Implement robot control and navigation.
   1. Implement a move() function
      1. Move should move 1 tile length
      2. Will count number of revolutions to determine distance.
         1. Run/Push robot to count number of revolutions in 1 tile length
   2. Implement a turnLeft() function and turnRight() function
      1. Both turns should turn 90 degrees.
      2. Apply both motors in opposite directions to turn
         1. Have to figure out how much motors need to turn
            1. Trial and Error