- FALSE! (A) A linear combination is a special case of affine combination
- TRUE! (B) A convex combination is a special case of linear combination
- TRUE! (C) A linear combination of vectors has the same number of dimensions as the vectors
- TRUE! (D) A vector in a linearly independent set of vectors cannot be written as a linear combination of other vectors

- (A) Any vector in a subspace can be written as a linear combination of the basis vectors for that subspace
- TRUE! (B) All basis vectors must be linearly independent of one another
- TRUE! (C) Any linearly independent set of vectors must be a basis
- TRUE! (D) It is possible for a basis to have non-orthogonal vectors
- TRUE! (E) Any orthonormal basis must be an orthogonal basis

- FALSE! (A) The outer product of two vectors is the transpose of their inner product
- TRUE! (B) The transpose of the transpose of a matrix is itself
- TRUE! (C) $(AB)^{T}$ is not necessarily the same as $A^{T}B^{T}$
- TRUE! (D) The outer product of a vector with itself must be a square matrix
- TRUE! (E) The inner product of two vectors of different dimensions cannot be computed

- (A) Left-singular vectors are not necessarily the same as right-singular vectors
- TRUE! (B) Right-singular vectors could be the same as eigenvectors
- TRUE! (C) Singular values of a matrix always exist
- TRUE! (D) Singular values are always non-negative
- TRUE! (E) Left-singular vectors could be the same as right-singular vectors

Q1: Which of the following is always a valid mathematical operation? (An operation that results in complex numbers is not considered valid.)

- No (A) Computing A^{-1} , where A is full-rank but non-square
- Yes (B) Computing $\sqrt{\vec{x}^T}A^TA\vec{x}$, where A is non-square
- No (C) Computing $\sqrt{\vec{x}^{T}A\vec{x}}$, where A is symmetric
- No (D) Computing the eigendecomposition of A, where A is non-square
- No (E) Computing $\frac{A}{B}$, where A and B are positive definite

Do each of the following characterize a convex function?

No a)
$$\vec{x}^{\mathsf{T}} \left(\frac{\partial^2 f}{\partial \vec{x} \partial \vec{x}^{\mathsf{T}}} (\vec{x}) \right) \vec{x} \geq 0 \ \forall \vec{x}$$

No a)
$$\vec{x}^{\mathsf{T}} \left(\frac{\partial^2 f}{\partial \vec{x} \partial \vec{x}^{\mathsf{T}}} (\vec{x}) \right) \vec{x} \ge 0 \ \forall \vec{x}$$

Yes b) $\vec{x}^{\mathsf{T}} \left(\frac{\partial^2 f}{\partial \vec{x} \partial \vec{x}^{\mathsf{T}}} (\vec{y}) \right) \vec{x} \ge 0 \ \forall \vec{x}, \vec{y}$

Yes C)
$$\frac{\partial^2 f}{\partial \vec{x} \partial \vec{x}^{\mathsf{T}}} (\vec{x}) \geqslant 0 \ \forall \vec{x}$$

- d) All eigenvalues of $\frac{\partial^2 f}{\partial \vec{x} \partial \vec{x} T}$ are non-negative $\forall \vec{x}$
- e) Let $U\Lambda U^{\mathsf{T}}=\frac{\partial^2 f}{\partial \vec{x} \partial \vec{x}^{\mathsf{T}}}$ be the eigendecomposition. The diagonal entries of Λ are all non-negative $\forall \vec{x}$

Q1: Which of the following facts about ridge regression is true?

- True (A) Ridge regression is less prone to overfitting compared to ordinary least squares
- True (B) Ridge regression always has a unique optimal parameter vector
- True (C) Compared to ordinary least squares, ridge regression adds a regularizer
- True (D) Ridge regression uses more hyperparameters than ordinary least squares
- False (E) Ridge regression uses more parameters than ordinary least squares
- True (F) Ridge regression uses a strictly convex loss function

Which one of the following must be a Gaussian random variable?

Yes (A)
$$X|Y=1$$
, where $\binom{X}{Y}\sim \mathcal{N}(\vec{0},I)$

Yes (B)
$$Y|X=100$$
, where $\binom{X}{Y}\sim \mathcal{N}(\vec{0},I)$

Yes
$$(C) \frac{1}{2}X - \frac{1}{3}Y$$
, where $\binom{X}{Y} \sim \mathcal{N}(\vec{0}, I)$

Yes (D)
$$-10X + 5$$
, where $\binom{X}{Y} \sim \mathcal{N}(\vec{0}, I)$

Yes (E)
$$Y-10X$$
, where $X \sim \mathcal{N}(0,1)$, $Y \sim \mathcal{N}(0,1)$ and $X \perp Y$

Yes (F)
$$X-Y$$
, where $X\sim \mathcal{N}(0,1)$, $Y\sim \mathcal{N}(0,1)$ and $\mathrm{Cov}(X,Y)=-1$

No (G)
$$X-Y$$
, where $X\sim \mathcal{N}(0,1)$, $Y\sim \mathcal{N}(0,1)$ and $Cov(X,Y)=-0.5$

Yes (H)
$$-10X + 5$$
, where $X \sim \mathcal{N}(0,1)$, $Y \sim \mathcal{N}(0,1)$ and $Cov(X,Y) = -0.5$

Which of the following statements about the difference between MLE and MAP parameter estimates is true?

- True (A) MLE does not depend on the prior, whereas MAP does
- False (B) MLE depends on the likelihood function, whereas MAP does not
- True (C) The derivation of MLE does not use Bayes' rule, whereas the derivation of MAP does
- True (D) Ridge regression can be interpreted as MAP, but not as MLE
- True (E) MAP corresponds to optimizing a loss function with a regularizer on the parameters, whereas MLE corresponds to optimizing a loss function without a regularizer

Which of the following statements about gradient descent is true?

- True (A) Gradient descent may not find the global minimum on non-convex functions
- True (B) Gradient descent may diverge on non-Lipschitz functions
- True (C) With a sufficiently small step size, gradient descent always converges at a rate of $\Theta(1/\epsilon^2)$ to the minimal objective value on convex Lipschitz functions
- False (D) With a sufficiently small step size, gradient descent always converges at a rate of $\Theta(1/\epsilon^2)$ to the minimal objective value on functions whose every local minimum is a global minimum
- False (E) With a sufficiently small step size, gradient descent always converges at a rate of $\Theta(1/\epsilon^2)$ to the optimal parameters when the objective function is both convex and Lipschitz

Q1: Which of the following optimization algorithms uses a non-diagonal preconditioner?

- No (A) Gradient descent
- (B) Gradient descent with momentum
- No (C) Nesterov's accelerated gradient
- No (D) AdaGrad
- No (E) Adam
- Yes (F) Newton's method

Which of the following would NOT be an effective way around optimization difficulties caused by exploding gradients?

- Effective (A) Perform gradient clipping
- Effective (B) Make the network shallower
- Not Effective (C) Use a non-saturating activation function like ReLU
- Effective (D) Add weight decay
- Effective (E) Add layer normalization
- Effective (F) Initialize the weights using the He initializer

Which of the following statements about support vector machines are true?

- True (A) An SVM is a binary classifier
- True (B) An SVM is a linear classifier
- True (C) The decision boundary of an SVM is a hyperplane
- False (D) The decision boundary of an SVM may not pass through the origin
- True (E) The width of the margin is not known a priori
- True (F) An SVM tries to maximize the margin

Which of the following statements about SVMs are true?

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True (A) Maximizing \frac{1}{\|\vec{w}\|_2} is equivalent to minimizing \|\vec{w}\|_2
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- True (B) Minimizing $\|\overrightarrow{w}\|_2$ is equivalent to minimizing $\|\overrightarrow{w}\|_2^2$
- True (C) \overrightarrow{w} is perpendicular to the decision boundary
- True (D) The decision boundary must pass through the origin when b=0
- False (E) Maximizing the margin is equivalent to maximizing $\|\vec{w}\|_2^2$

Consider a linearly inseparable dataset. Which of the following statements is true?

- True (A) Hard-margin SVMs with linear kernels never have a feasible solution.
- True (B) Hard-margin SVMs with quadratic kernels sometimes have a feasible solution.
- False (C) Hard-margin SVMs with quadratic kernels always have a feasible solution.
- True (D) Soft-margin SVMs with linear kernels always have a feasible solution.
- True (E) Soft-margin SVMs with quadratic kernels sometimes have a feasible solution.
- True (F) Soft-margin SVMs with quadratic kernels always have a feasible solution.