

# Advanced Algorithms

## *Lecture 1* *Introduction* *&* *Dynamic Programming*

Center for Data-intensive Systems

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# Agenda

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- Introduction
- Dynamic Programming

# People

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- Lecturer: Bin Yang
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  - Office: 3.2.48
  - Homepage: <http://people.cs.aau.dk/~byang/>
  - DPW group: **Database**, Programming and Web Technologies
    - ◆ Big data, data science, data analytics (machine learning, artificial intelligence)
  - Daisy: Center for Data-Intensive Systems.  
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- Teaching Assistant: Simon Aagaard Pedersen
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  - Office: 3.2.46

# Location and Time

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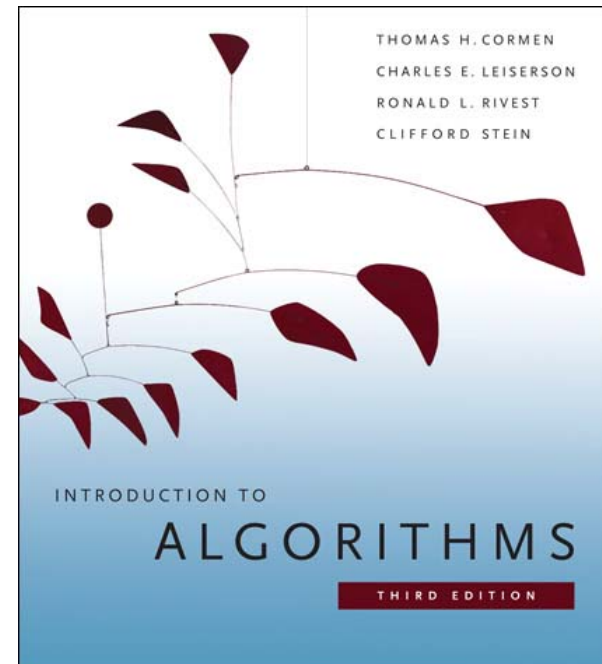
- Location
  - NJV 6A, 1.20, but with some exceptions.
- Time
  - Some Tuesdays and Fridays.
  - Lectures are from 8.15 to 10.00.
  - Exercises are from 10.15 to 12.00.
- Check the full schedule on Moodle before going to the classroom.

# Moodle Page and Textbook

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- Course page at Moodle
  - <https://www.moodle.aau.dk/course/view.php?id=28778>
  - Please check it frequently for notifications and updates!
- Textbook
  - “Introduction to Algorithms”, 3.ed, by Thomas H. Cormen, Charles E. Leiserson, Ronald L. Rivest, and Clifford Stein, The MIT Press.
  - ISBN:9780262533058
  - Abbreviation: CLRS
  - Available at the Factum book store <http://ftu.dk/>



# Course Structure

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- A total of 15 sessions
  - 12 regular sessions + 3 self-study exercise sessions
- A regular session = a lecture class + an exercise class.
- A lecture class
  - 2 \* 45 minutes
  - Each lecture studies a specific topic.
  - During a lecture, there may be mini-quizzes.
    - ◆ Have a pen and some papers.
- An exercise class
  - 2 \* 45 minutes
  - Solve exercises assigned in the session.
    - ◆ You are encouraged to work in groups.
    - ◆ Simon comes by from group to group during each exercise class.
  - Get a feeling of exam questions from enough exercises!

# Course Structure (2)

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- A self-study exercise session = 4 hours of exercises
  - You need to do it in groups.
  - Each group **can** submit to Simon/me one written solution no later than a week of the session.
  - Simon/I will give written feedback for each of the submitted solutions.
  - I recommend that each of you solves the problems **individually** first, and then you discuss, summarize, and hand in solutions **per group**.
  - In case you cannot agree with each other, you can hand in multiple solutions for one problem.

# Working hours

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- This is a 5 ECTS course, where each ECTS=30 hours
  - 150 hours
- 12 regular sessions
  - 2h exercises + 2h lecture.
  - 3h reading
  - In total,  $12 \times (2+2+2+1) = 84h$
- 3 self-study exercises sessions
  - $4+4=8h$  on solving the exercises.
  - 4h on checking the solutions/feedback in order to make sure you can solve each of the exercises.
  - In total,  $3 \times (8+4) = 36h$
- 30h for preparing the exam.
- In total,  $84+36+30=150h$



# Exam

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- Individual and written, but open-book
  - Electronic devices with communication capabilities, such as laptops and mobile phones, are NOT allowed.
  - You can bring old-fashion calculators.
  - You can freely use your copies of slides from the lectures, textbooks, and other course material.
- Exam in two parts
  - A set of quizzes, to test knowledge.
    - ◆ Choose the options that you think are correct.
  - A few (1 ~ 3) open problems, each with some sub-problems, to test competences and skills.
    - ◆ Given a real world problem, write pseudo code, give complexity analysis, etc.
  - You will get a better feeling when you participate self-study exercise sessions.
- The exam will have 100 points.

# Prerequisites

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- AD on DAT3/SW3 or AD2 on IT7
- Let's quickly recap the intended learning outcomes of AD/AD2
- Basic mathematical concepts such as recursion, induction, concrete and abstract complexity;
  - Solving recurrences, asymptotic notation.
- Basic data structures;
  - Queues, stacks, heaps, linked lists, priority queues.
- Algorithmic principles such as searching, search trees, sorting, dynamic programming, divide-and-conquer;
  - Binary search tree, merge sort, quick sort.
- Graphs and graph algorithms such as shortest path, connected components, spanning trees.
  - BFS, DFS, MST, topological sorting, shortest path.

# Mini quiz

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- From the AD1 exam in Jan 2019.

1.2. (3 points)  $700 \cdot n^2 + 999 \cdot n^2 \lg n + 0.1 \cdot n^2 \lg^2 n$  is:

- ☐ a)  $\Theta(n^2 \lg n)$     ☐ b)  $\Omega(n^2 \lg n)$     ☐ c)  $\Theta(n^2)$     ☐ d)  $\Theta(n^2 \cdot \lg^2 n)$

# Mini quiz

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- From the AD exam in Jan 2016.

1.2. (3 points)  $700 \cdot n^2 + 999 \cdot n^2 \lg n + 0.1 \cdot n^2 \lg^2 n$  is:

☐ a)  $\Theta(n^2 \lg n)$    ☒ b)  $\Omega(n^2 \lg n)$    ☐ c)  $\Theta(n^2)$    ☒ d)  $\Theta(n^2 \cdot \lg^2 n)$

# Intended Learning Outcomes (ILO)

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- After taking AALG, you should acquire the following knowledge
  - Algorithm **design** techniques such as divide-and-conquer, greedy algorithms, dynamic programming, back-tracking, branch-and-bound algorithms, and plane-sweep algorithms;
  - Algorithm **analysis** techniques such as recursion, amortized analysis;
  - A collection of **core** algorithms and data structures to solve a number problems from various computer science areas: algorithms for external memory, multiple-threaded algorithms, advanced graph algorithms, heuristic search and geometric calculations;
  - There will also enter into one or more **optional subjects** in advanced algorithms, including, but not limited to: *approximate algorithms*, randomized algorithms, search for text, linear programming and number theoretic algorithms such as crypto-systems.

# Course Content (1)

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- Lecture 1: Dynamic programming (CLRS 15)
  - Principles of DP.
  - Examples: Edit distance, activity selection.
- Lecture 2: All-pairs shortest paths (CLRS 25)
  - Distance matrix and predecessor matrix.
  - Floyd-Warshall algorithm, which uses DP.
- Lecture 3: Network flow algorithms (CLRS 26)
  - Formalize flow networks, flows, maximum-flow.
  - Ford-Fulkerson algorithms.
- Lecture 4: Greedy algorithm (CLRS 16)
  - Ideas/principles of greedy algorithm.
  - Examples: Activity selection, Huffman coding.

# Course content (2)

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- Lecture 5: Amortized analysis (CLRS 17)
  - Understand amortized analysis, difference from average-case analysis.
  - Aggregated analysis, accounting method, potential method.
- Lectures 6, 7, 8: Computational geometry (CLRS 33 + additional references)
  - Basic geometric operations in 2D, e.g., two line segments intersecting, orientation of two line segments?
  - Sweeping algorithms.
  - Graham's scan and Jarvis's march algorithm for convex hull.
  - Divide-and-conquer algorithm to find the closet pair of points in a set of points.
  - Range searching in d-dimensional space: kd-tree and range tree.

# Course Content (3)

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- Lecture 9: External-memory algorithms and data structures (CLRS 18 + additional references)
  - Balanced search trees, e.g., *B-trees* and *R-trees*.
  - External memory sorting: multi-way merge-sort algorithm.
- Lecture 10: Multi-threaded algorithms (CLRS 27)
  - Concurrency keywords: parallel, spawn, sync.
  - MT Fibonacci number computation, MT merge sort.
- Lecture 11 & 12: Algorithms for NP-complete problems (CLRS 35)
  - Approximation algorithms
  - Backtracking and branch-and-bound
  - Examples using the algorithms.
    - ◆ Vertex cover, traveling sales man.



# Tips

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- Your feedback is always welcome.
  - Esp. when you get confused.
  - Send me an email or drop by my office.
- Participate in every lecture.
- Play actively in every exercise class and self-study exercise session.
  - Exercises prepare you for the final exam!
  - Make sure you understand all exercises by YOURSELF after your group work in each exercise class.
- Check the course page frequently.

# Agenda

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- Introduction
- Dynamic Programming (DP)
  - To understand the principles of dynamic programming.
  - To understand the DP algorithm for edit distance.
  - To be able to apply the DP algorithm design technique.

# Recall algorithm design techniques from AD1

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- Algorithm design techniques so far:
  - Brute-force algorithms
    - ◆ Linear search
  - Incremental algorithms
    - ◆ Insertion sort
  - Algorithms that use ADTs (implemented using efficient data structures)
    - ◆ Heap sort
  - Divide-and-conquer algorithms
    - ◆ Merge sort, quick sort.
  - Dynamic-programming
    - ◆ Rod cutting
    - ◆ Top-down with memoization.
    - ◆ Bottom-up method.

# Divide and Conquer

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- If the problem size is small enough to solve it in a straightforward manner, solve it.
- Otherwise, meaning that the input size is too large to deal with in a straightforward manner, do the following
  - **Divide:** Divide the problem into two or more *disjoint* sub-problems.
  - **Conquer:** Use divide-and-conquer recursively to solve the sub-problems.
  - **Combine:** Take the solutions to the sub-problems and combine these solutions into a solution for the original problem.

# Merge Sort



```
Merge-Sort(A, p, r)
  if p < r then
    q ← (p+r)/2
    Merge-Sort(A, p, q)
    Merge-Sort(A, q+1, r)
    Merge(A, p, q, r)
```

- Mini-quiz: do you still recall the **recurrence** of merge sort?
  - A **recurrence** is an equation or inequality that describes a function in terms of its value on smaller inputs.
- $T(n)=$ 
  - $\Theta(1)$  if  $n=1$
  - $2T(n/2) + \Theta(n)$  if  $n>1$

# Dynamic programming

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- A powerful technique to solve ***optimization problems***.
- An optimization problem can have many possible solutions, each solution has a value, and we wish to find a solution with the optimal (i.e., minimum or maximum) value.
- An algorithm should compute *the* **optimal value** plus, if needed, *an* **optimal solution**.


# Rod cutting




- A steel rod of length  $n$  should be cut and sold in pieces.
- Pieces sold only in integer sizes according to a price table  $P[1..n]$ .
- *Goal*: cut up the rod to maximize profit.

Length	1	2	3	4	5	6	7
Price	4	5	13	16	23	24	27

Max profit (optimal value): 31  
Optimal cut (optimal solution): 1, 1, 5

Price:  23 + 5 = 28

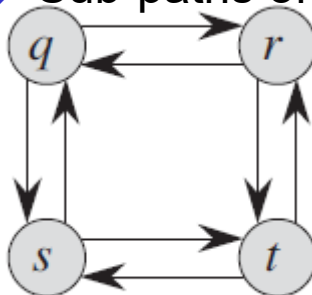
Price:  16 + 13 = 29

Price:  13 + 13 + 4 = 30

# Two key characteristics of DP



- Overlapping sub-problems
  - Sub-problems share sub-sub-problems.
  - A divide-and-conquer algorithm does more work than necessary, as it needs to repeatedly solve the common sub-sub-problems.
- Optimal substructure
  - The optimal solution to a problem incorporates optimal solutions to sub-problems.
  - Un-weighted shortest path (YES)
    - ◆ Shortest path  $\mathbf{A} = \langle q, r, t \rangle$  from  $q$  to  $t$ .
    - ◆ Sub-paths of  $\mathbf{A}$ ,  $\langle q, r \rangle$  and  $\langle r, t \rangle$ , are also the shortest paths.
  - Un-weighted longest simple path. (NO)
    - ◆ Longest path  $\mathbf{B} = \langle q, r, t \rangle$  from  $q$  to  $t$ .
    - ◆ Sub-paths of  $\mathbf{B}$ ,  $\langle q, r \rangle$  and  $\langle r, t \rangle$ , may not be the longest paths.



$\langle q, s, t, r \rangle$   
 $\langle r, q, s, t \rangle$



# Two approaches of DP

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- Top-down with memoization
  - Solve each sub-problem only **once** and **store** the answers to the solved sub-problems in a table.
  - Next time, when you need to solve a solved sub-problem, just look up the table to get the answer.
- Bottom-up without recursion.
  - Depending on some natural notion on the **size** of a sub-problem.
  - Solving any particular sub-problem depends only on solving **smaller** sub-problems.
  - Sort the sub-problems by size and solve them in size order, smallest first. And save the solutions.
- Pros and cons
  - Both should have the same asymptotic running time.
  - If all sub-problems must be solved, memoization (recursion) is usually slower (by a constant factor) than Bottom-up (loops).
  - If not all sub-problems need to be solved, memoization only solves the necessary ones.

# Structure of DP



- Construction:
  - Which choices have to be considered in each step of the algorithm?
  - What are the sub-problems?
  - How are the trivial sub-problems solved?
  - Write a memoized version of the algorithm or in which order do we have to solve the sub-problems (bottom-up)
  - Remember the (optimal) choices made
  - Use the remembered choices to construct a solution
- Analysis:
  - How many different sub-problems are there in total?
  - How many choices have to be considered when solving each sub-problem?

Constructing  
a solution

Recurrence for  
the optimal value

# Agenda

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- Introduction
- Dynamic Programming
  - To understand the principles of dynamic programming.
  - To understand the DP algorithm for edit distance.
  - To be able to apply the DP algorithm design technique.

# Edit distance

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- Problem definition:
  - Two strings:  $s[1..m]$  and  $t[1..n]$
  - Find **edit distance**  $dist(s, t)$  between the two input strings  $s$  and  $t$ .
    - ◆ The smallest number of **edit operations** that turns  $s$  into  $t$ .
  - Edit operations:
    - ◆ **Replace** one letter with another letter
    - ◆ **Delete** one letter
    - ◆ **Insert** one letter
- Example: let's turn “ghost” to “house”
  - **ghost**    delete **g**
  - **host**     insert **u**
  - **houst**    replace **t** by **e**
  - **house**

# Two examples

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- $s = \text{milk}$   $t = \text{windy}$ 
  - Option 1: Replace k by y,  $\text{dist}(s, t) = \text{dist}(\text{mil}, \text{wind}) + 1$
  - Option 2: Delete k,  $\text{dist}(s, t) = \text{dist}(\text{mil}, \text{windy}) + 1$
  - Option 3: Insert y in the end of s,  $\text{dist}(s, t) = \text{dist}(\text{milk}, \text{wind}) + 1$
  - $\text{dist}(s, t) = \min(\text{dist}(\text{mil}, \text{wind}) + 1, \text{dist}(\text{mil}, \text{windy}) + 1, \text{dist}(\text{milk}, \text{wind}) + 1)$
- $s = \text{milk}$   $t = \text{link}$ 
  - Option 1: Keep k,  $\text{dist}(s, t) = \text{dist}(\text{mil}, \text{lin})$
  - Option 2: Delete k,  $\text{dist}(s, t) = \text{dist}(\text{mil}, \text{link}) + 1$
  - Option 3: Insert k in the end,  $\text{dist}(s, t) = \text{dist}(\text{milk}, \text{lin}) + 1$
  - $\text{dist}(s, t) = \min(\text{dist}(\text{mil}, \text{lin}), \text{dist}(\text{mil}, \text{link}) + 1, \text{dist}(\text{milk}, \text{lin}) + 1)$
- Optimal sub-structure for edit distance?
  - YES! The optimal solution to a problem incorporates optimal solutions to sub-problems.
  - Formal proof: see additional references on Moodle.

# Sub-problems



- Sub-problem:
  - $d_{i,j} = \text{dist}(s[1..i], t[1..j])$
- Then  $\text{dist}(s, t) = d_{m,n}$
- Let's look at the last symbol:  $s[i]$  and  $t[j]$ . There are three options, do whatever is the cheapest:
- **Option 1:**
  - If  $s[i] = t[j]$ , then turn  $s[1..i-1]$  to  $t[1..j-1]$ 
    - ◆ Milk, link:  $d_{i,j} = d_{i-1,j-1}$
  - **Else replace**  $s[i]$  by  $t[j]$  and turn  $s[1..i-1]$  to  $t[1..j-1]$ 
    - ◆ milk, windy; **mily**, **windy**:  $d_{i,j} = 1 + d_{i-1,j-1}$
- **Option 2: Delete**  $s[i]$  and turn  $s[1..i-1]$  to  $t[1..j]$ 
  - milk, windy; **mil**, **windy**:  $d_{i,j} = 1 + d_{i-1,j}$
- **Option 3: Insert**  $t[j]$  at the end of  $s[1..i]$  and turn  $s[1..i]$  to  $t[1..j-1]$ 
  - Milk, windy; **milky**, **windy**:  $d_{i,j} = 1 + d_{i,j-1}$

# Recurrence, optimal substructure



$$d_{i,j} = \min \left\{ \begin{array}{ll} d_{i-1,j-1} + \begin{cases} 0 & \text{if } s[i] = t[j] \\ 1 & \text{else} \end{cases} & \begin{array}{l} \text{Do nothing} \\ \text{replace } s[i] \text{ by } t[j] \\ \text{delete } s[i] \end{array} \\ d_{i-1,j} + 1 & \\ d_{i,j-1} + 1 & \text{insert } t[j] \text{ at the end of } s[i] \end{array} \right.$$

- *How do we solve trivial sub-problems?*
  - To turn empty string to  $t[1..j]$ , do  $j$  **inserts**
  - To turn  $s[1..i]$  to empty string, do  $i$  **deletes**

# DP Algorithm, memoization



**EditDistance**(s[1..m], t[1..n])

```
01 for i = 0 to m do
02     for j = 0 to n do
03         dist[i, j] = ∞
04 return EditDistR(s, t, m, n)
```

*Initialization*

**EditDistR**(s, t, i, j)

```
01 if dist[i, j] == ∞ then
```

```
02     if j == 0 then dist[i, j] = i
```

```
03     else if i == 0 then dist[i, j] = j
```

```
04     else
```

```
05         if s[i] == t[j] then
```

```
06             dist[i, j] = min(EditDistR(s, t, i-1, j-1),
```

*Trivial sub-problems:*  
*i deletes and j inserts*

```
                                EditDistR(s, t, i-1, j)+1, delete s[i]
```

```
                                EditDistR(s, t, i, j-1)+1) insert t[j]
```

```
07         else
```

```
08             dist[i, j] = 1 + min(EditDistR(s, t, i-1, j-1)
```

*Replace*  
*s[i] by t[j]*

```
                                EditDistR(s, t, i-1, j), delete s[i]
```

```
                                EditDistR(s, t, i, j-1)) insert t[j]
```

```
09 return dist[i, j]
```



# Time Complexity

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- Analysis
  - If we solve it in a naïve D&C manner, what is the complexity?
    - ◆ *Exponential runtime.*
  - *How many different sub-problems are there in total?*
    - ◆  $n*m$
  - *How many choices have to be considered when solving each sub-problem?*
    - ◆ *3 (copy/replace, insert, and delete)*
  - *Thus,  $\Theta(nm)$*

# DP Algorithm, bottom-up



**EditDistance**(s[1..m], t[1..n])

```
01 for i = 0 to m do dist[i,0] = i
02 for j = 0 to n do dist[0,j] = j
03 for i = 1 to m do
04     for j = 1 to n do
05         if s[i] = t[j] then
06             dist[i,j] = min(dist[i-1,j-1], dist[i-1,j]+1,
                                dist[i,j-1]+1)
07         else
08             dist[i,j] = 1 + min(dist[i-1,j-1], dist[i-1,j],
                                dist[i,j-1])
09 return dist[m,n]
```

*Trivial sub-problems  
i deletes and j inserts*

*Fills in entries in the  
(m+1)\*(n+1) matrix in  
row-major order.*

- *What is the running time of this algorithm?*
- *How do we modify it to remember the edit operations?*

# s="GO" t="LOG"



- m=2, n=3, we have a 3\*4 matrix to fill in.

		j						
		0	1	L	2	O	3	G
i	0	0	1		2		3	
	1	G	1	1	2		2	
	2	O	2	2	1		2	

**EditDistance**(s[1..m], t[1..n])

01 **for** i = 0 **to** m **do** dist[i,0] = i

02 **for** j = 0 **to** n **do** dist[0,j] = j

03 **for** i = 1 **to** m **do**

04     **for** j = 1 **to** n **do**

05         **if** s[i] = t[j] **then**

06             dist[i,j] = min(dist[i-1,j-1], dist[i-1,j]+1,  
                                  dist[i,j-1]+1)

07         **else**

08             dist[i,j] = 1 + min(dist[i-1,j-1], dist[i-1,j],  
                                  dist[i,j-1])

09 **return** dist[m,n]

*Trivial sub-problems  
i deletes and j inserts*

*Fills in entries in the  
(m+1)\*(n+1) matrix in  
row-major order.*

- $m=2, n=3$ , we have a  $3 \times 4$  matrix to fill in.

0	1	L	2	O	3	G
---	---	---	---	---	---	---

0		0	1 I	2 I	3 I
1	G	1 D	1 R	2 R, I	2 C
2	O	2 D	2 R, D	1 C	2 I

### EditDistance (s[1..m], t[1..n])

```
01 for i = 0 to m do dist[i,0] = i
```

```
02 for j = 0 to n do dist[0,j] = j
```

```
03 for i = 1 to m do
```

```
04   for j = 1 to n do
```

```
05      if s[i] = t[j] then
```

```
06         dist[i,j] = min(dist[i-1,j-1], dist[i-1,j]+1,
                           dist[i,j-1]+1)
```

```
07         else
```

```
08         dist[i,j] = 1 + min(dist[i-1,j-1], dist[i-1,j],
                               dist[i,j-1])
```

```
09 return dist[m,n]
```

*Trivial sub-problems*  
*i deletes and j inserts*

*Fills in entries in the  $(m+1) \times (n+1)$  matrix in row-major order.*

# Remember edit operations



- $m=2$ ,  $n=3$ , we have a  $3 \times 4$  matrix to fill in.

	0	1	2	3
		L	O	G
0	0	1 I	2 I	3 I
1 G	1 D	1 R	2 R, I	2 C
2 O	2 D	2 R, D	1 C	2 I

$i=1$  Replace "L"

$i=2$  Copy "O"

$i=2$  Insert "G"

GO

LO

LO

LOG

*What is the running time of this algorithm?*

$\Theta(nm)$

# Mini quiz

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- $s = \text{"GO"}$   $t = \text{"LOGG"}$
- Fill in the  $3 \times 5$  matrix.
- Identify the edit distance and the corresponding edit operations.
- There may be more than one possible sequences of operations.

# Remember edit operations



- $m=2$ ,  $n=3$ , we **have** a  $3 \times 4$  matrix to fill in.

	0	1	L	2	O	3	G	4	G
0	0	1	I	2	I	3	I	4	I
1	G	1	D	1	R	2	R, I	2	C
2	O	2	D	2	R, D	1	C	2	I
								3	R, I

$i=1$  Replace "L"

$i=0$  Insert "L"

$i=2$  Copy "O"

GO

$i=0$  insert "O"

GO

LO

LGO

$i=2$  Insert "G"

LO

$i=1$  copy "G"

LOGO

LOG

LOGO

$i=2$  Insert "G"

LOGG

$i=2$  Replace "G"

LOGG

*Although we always have a single optimal value (edit distance = 3), we may have more than one optimal solution (two possible ways of turning s to t).*

# ILO of Lecture 1

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- Dynamic Programming
  - To understand the principles of dynamic programming.
    - ◆ Overlapping sub-problems and optimal sub-structure.
    - ◆ Top-down with memoization and bottom-up.
  - To understand the DP algorithm for edit distance.
  - To be able to apply the DP algorithm design technique.



# Lecture 2

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- All-pairs shortest paths (dynamic programming)
  - To understand the adjacency matrix and the predecessor matrix, which are the representations of the input and output of most of the all-pairs shortest-path algorithms.
  - To understand how the dynamic programming principles play out in the Floyd-Warshall algorithm.
- Activity selection (another example of using dynamic programming)