

Machine Intelligence

Lecture 10: Clustering

Thomas Dyhre Nielsen

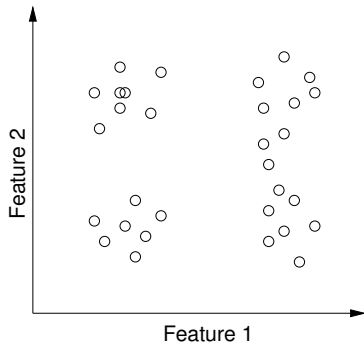
Aalborg University

Topics:

- Introduction
- Search-based methods
- Constrained satisfaction problems
- Logic-based knowledge representation
- Representing domains endowed with uncertainty.
- Bayesian networks
- Inference in Bayesian networks
- Machine learning: Classification
- **Machine learning: Clustering**
- Planning
- Multi-agent systems

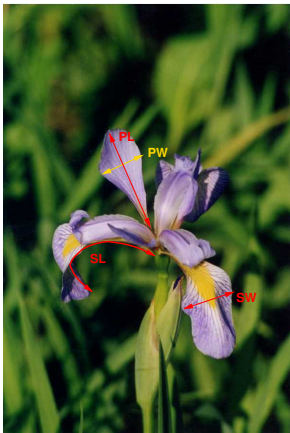
Clustering

The objective of clustering is to find structure in the data.



Examples:

- Based on customer data, find groups of customers with similar profiles.
- Based on image data, find groups of images with similar motif.
- Based on article data, find groups of articles with the same topics.
- ...



Measurement of petal width/length and sepal width/length for 150 flowers of 3 different species of Iris.

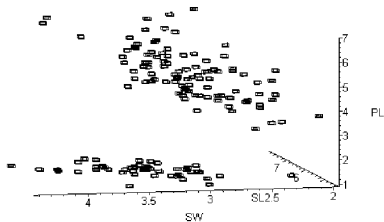
first reported in:

Fisher, R.A. "The use of multiple measurements in taxonomic problems" Annual Eugenics, 7 (1936).

| Attributes | | | | Class variable |
|------------|-----|-----|-----|----------------|
| SL | SW | PL | PW | Species |
| 5.1 | 3.5 | 1.4 | 0.2 | Setosa |
| 4.9 | 3.0 | 1.4 | 0.2 | Setosa |
| 6.3 | 2.9 | 6.0 | 2.1 | Virginica |
| 6.3 | 2.5 | 4.9 | 1.5 | Versicolor |
| ... | ... | ... | ... | ... |

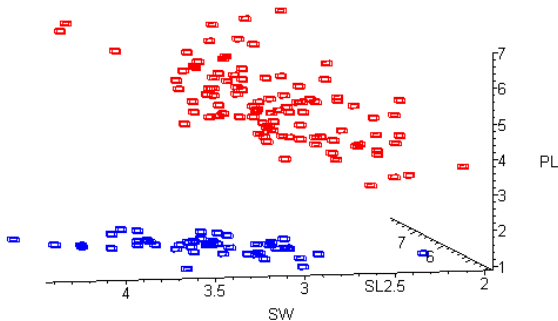
The Iris data with class labels removed:

| Attributes | | | |
|------------|-----|-----|-----|
| SL | SW | PL | PW |
| 5.1 | 3.5 | 1.4 | 0.2 |
| 4.9 | 3.0 | 1.4 | 0.2 |
| 6.3 | 2.9 | 6.0 | 2.1 |
| 6.3 | 2.5 | 4.9 | 1.5 |
| ... | ... | ... | ... |

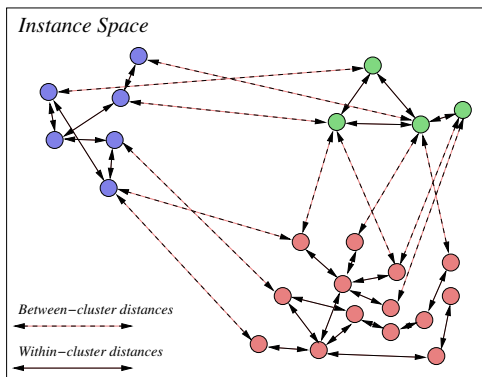


A clustering of the data $S = \mathbf{a}_1, \dots, \mathbf{a}_N$ consists of a set $C = \{c_1, \dots, c_k\}$ of *cluster labels*, and a *cluster assignment* $ca : S \rightarrow C$.

Clustering Iris with
 $C = \{\text{blue}, \text{red}\}$:



The k -means algorithm



A candidate clustering (indicated by colors) of data cases in instance space. Arrows indicate between- and within-cluster distances (selected).

General goal: find clustering with

- large between-cluster variation (sum of between-cluster distances)
- small within-cluster variation (sum of within-cluster distances)

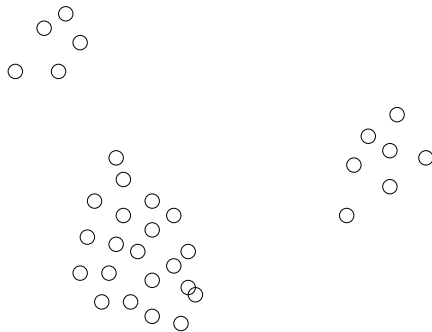
We consider the scenario, where

- the number k of clusters is known.
- we have a distance measure $d(\mathbf{x}_i, \mathbf{x}_j)$ between pairs of data points (feature vectors).
- we can calculate a centroid for a collection of data points $S = \{\mathbf{x}_1, \dots, \mathbf{x}_n\}$.

```
Initialize: randomly pick  $k$  data points as initial cluster centers  $\mathbf{c} = c_1, \dots, c_k$  from  $S$   
repeat  
    Form  $k$  clusters by assigning each point in  $S$  to its closest centroid.  
    Recompute the centroid for each cluster.  
until Centroids do not change
```

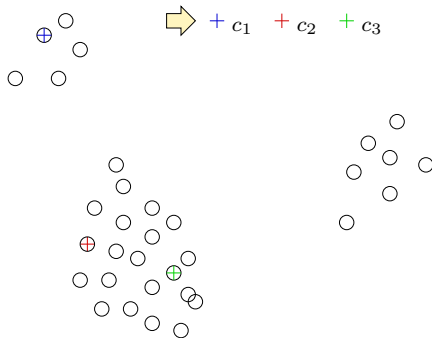
The k -means algorithm: Example

$k = 3$:



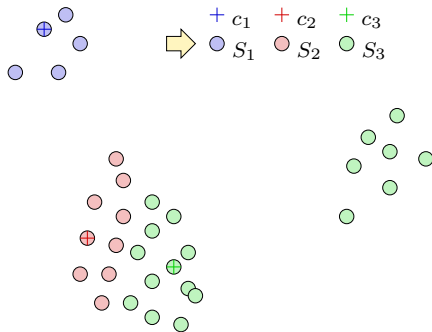
The k -means algorithm: Example

$k = 3$:



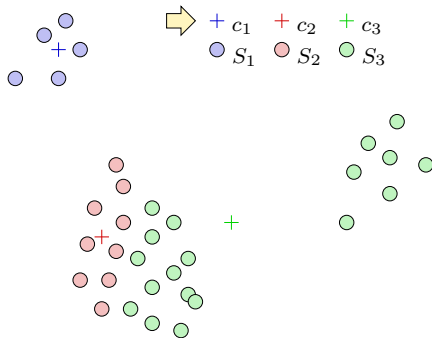
The k -means algorithm: Example

$k = 3$:



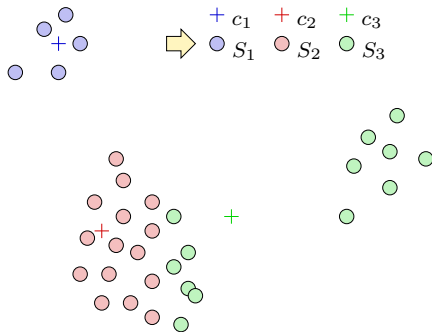
The k -means algorithm: Example

$k = 3$:



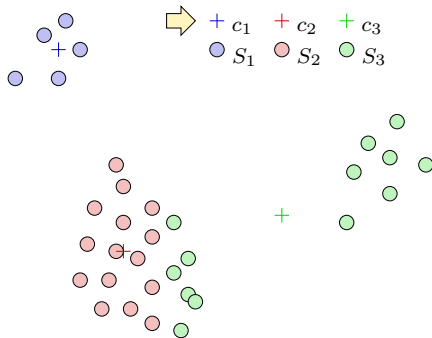
The k -means algorithm: Example

$k = 3$:



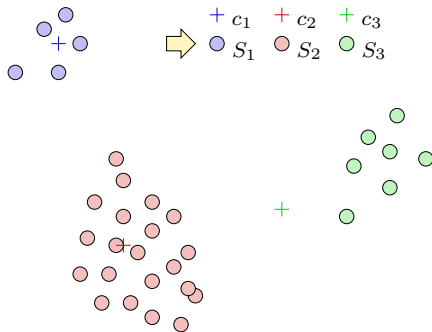
The k -means algorithm: Example

$k = 3$:



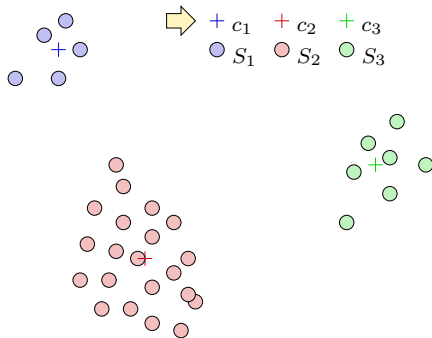
The k -means algorithm: Example

$k = 3$:



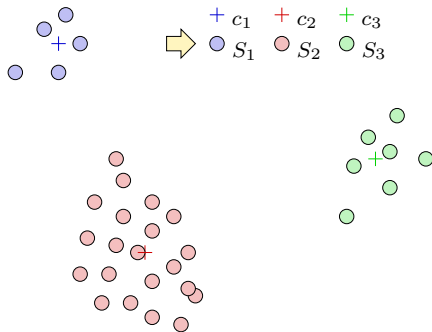
The k -means algorithm: Example

$k = 3$:



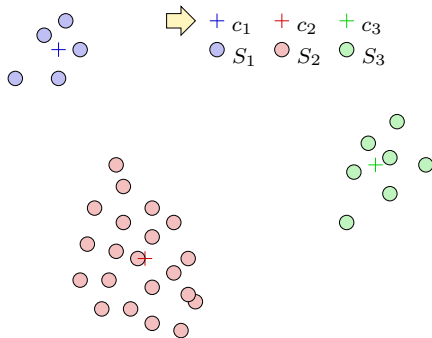
The k -means algorithm: Example

$k = 3$:

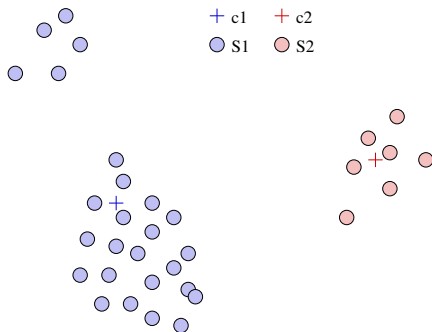


The k -means algorithm: Example

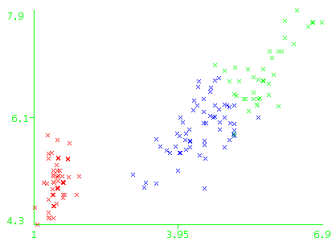
$k = 3$:



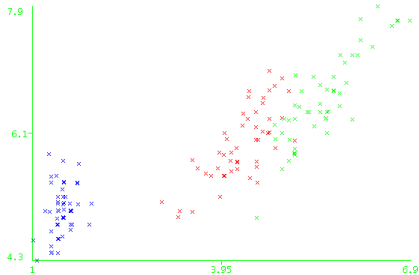
Result for clustering the same data with $k = 2$:



Result can depend on choice of initial cluster centers!



Iris 3-means clustered



Iris true classes

k -means as an optimization problem

Assume that we use the Euclidean distance d as proximity measure and that the quality of the clustering is measured by the sum of squared errors:

$$SSE = \sum_{i=1}^k \sum_{\mathbf{x} \in C_i} d(\mathbf{c}_i, \mathbf{x})^2,$$

where:

- \mathbf{c}_i is the i 'th centroid
- $C_i \subseteq S$ is the points closets to \mathbf{c}_i according to d .

In principle ...

We can minimize the SSE by looking at all possible partitionings \rightsquigarrow not feasible!

k -means as an optimization problem

Assume that we use the Euclidean distance d as proximity measure and that the quality of the clustering is measured by the sum of squared errors:

$$SSE = \sum_{i=1}^k \sum_{\mathbf{x} \in C_i} d(\mathbf{c}_i, \mathbf{x})^2,$$

where:

- \mathbf{c}_i is the i 'th centroid
- $C_i \subseteq S$ is the points closets to \mathbf{c}_i according to d .

In principle ...

We can minimize the SSE by looking at all possible partitionings \rightsquigarrow not feasible!

Instead, k -means

The centroid that minimizes the SSE is the *mean* of the data-points in that cluster:

$$\mathbf{c}_i = \frac{1}{|C_i|} \sum_{\mathbf{x} \in C_i} \mathbf{x}$$

Local optimum found by alternating between cluster assignments and centroid estimation.

Convergence

The k -means algorithm is guaranteed to converge

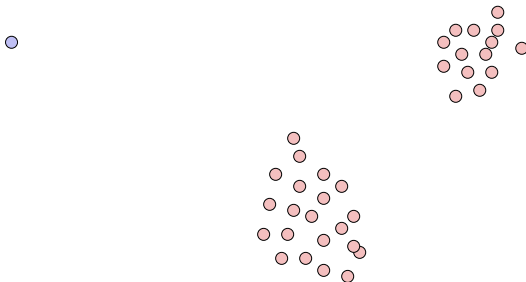
- Each step reduces the sum of squared errors.
- There is only a finite number of cluster assignments.

There is no guarantee of reaching the global optimum:

- Improve by running with multiple random restarts.

Some practical issues

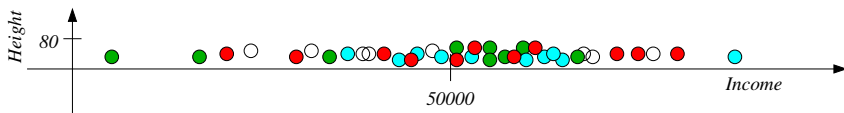
The result of partitional clustering can be skewed by outliers. Example with $k = 2$:



⇒ useful preprocessing: outlier detection and elimination.

Instances defined by attributes

$A_1 = \text{height in inches}$ and $A_2 = \text{annual income in \$}$:



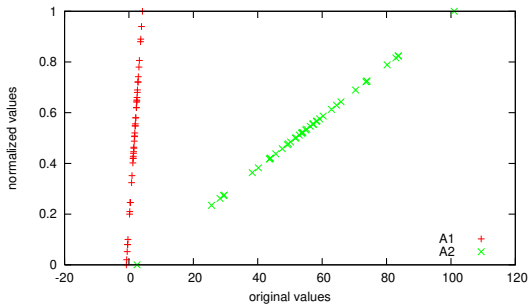
- all distance functions for continuous attributes dominated by *income* values
- \rightsquigarrow may need to *rescale* or *normalize* continuous attributes

Min-Max Normalization

replace A_i with

$$\frac{A_i - \min(A_i)}{\max(A_i) - \min(A_i)}$$

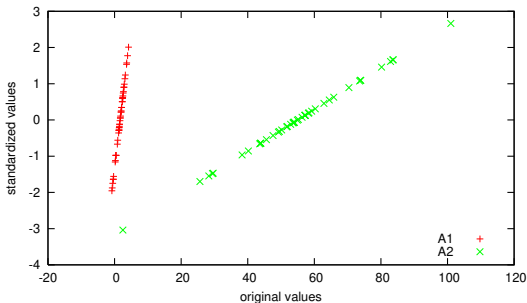
($\min(A_i)$, $\max(A_i)$ are
min/max values of A_i
appearing in the data)



Z-score Standardization

replace A_i with

$$\frac{A_i - \text{mean}(A_i)}{\text{standard deviation}(A_i)}$$



where

$$\text{mean}(A_i) = \frac{1}{n} \sum_{j=1}^n a_{j,i}$$

$$\text{standard deviation}(A_i) = \sqrt{\frac{1}{n-1} \sum_{j=1}^n (a_{j,i} - \text{mean}(A_i))^2}$$

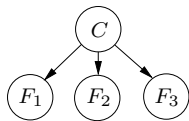
Soft clustering

The k -means algorithm generates a *hard* clustering: each example is assigned to a single cluster.

Alternatively: In *soft* clustering each example is assigned to a cluster with a certain probability.

The naive Bayes model for clustering

Model



Data

| F_1 | F_2 | F_3 | C |
|----------|----------|----------|----------|
| t | t | t | $?$ |
| t | f | t | $?$ |
| t | f | f | $?$ |
| f | f | t | $?$ |
| \vdots | \vdots | \vdots | \vdots |

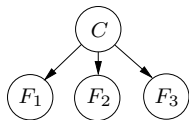
- C is the hidden cluster variable.
- F_1 , F_2 , and F_3 are the feature variables.

The k -means algorithm generates a *hard* clustering: each example is assigned to a single cluster.

Alternatively: In *soft* clustering each example is assigned to a cluster with a certain probability.

The naive Bayes model for clustering

Model



Data

| F_1 | F_2 | F_3 | C |
|----------|----------|----------|----------|
| t | t | t | $?$ |
| t | f | t | $?$ |
| t | f | f | $?$ |
| f | f | t | $?$ |
| \vdots | \vdots | \vdots | \vdots |

Procedure

- C is the hidden cluster variable.
- F_1 , F_2 , and F_3 are the feature variables.

- Set the number of clusters, i.e., the states of C
- Learn the probabilities of the model:
 - $P(C)$, $P(F_1|C)$, $P(F_2|C)$, and $P(F_3|C)$
- Use the learned probabilities to cluster the (future) instances.

When learning the probability distributions of the model, the variable C is hidden

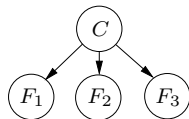
- \rightsquigarrow we *cannot* directly estimate the probabilities using frequency counts

Instead we employ the *Expectation-maximization algorithm*

The EM-algorithm

The main idea:

- Use hypothetical completions of the data using the current probability estimates.
- Infer the maximum likelihood probabilities for the model based on completed data set.



Probability tables:

$$P_0(C) = (0.6, 0.4)$$

| | $P_0(F_1 C)$ | |
|-----------|--------------|---------|
| | $C = 1$ | $C = 2$ |
| $F_1 = t$ | 0.6 | 0.4 |
| $F_1 = f$ | 0.4 | 0.6 |

Also $P_0(F_2|C)$ and $P_0(F_3|C)$

Data:

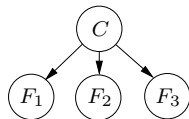
| F_1 | F_2 | F_3 |
|-------|-------|-------|
| t | t | t |
| t | f | t |
| t | f | f |
| f | f | t |

Expectation

Count table $A(F_1, F_2, F_3, C)$:

| F_1 | F_2 | F_3 | $P(C F_1, F_2, F_3)$ |
|-------|-------|-------|----------------------|
| t | t | t | |
| t | f | t | |
| t | f | f | |
| f | f | t | |

Maximization



Probability tables:

$$P_0(C) = (0.6, 0.4)$$

| | $P_0(F_1 C)$ | |
|-----------|--------------|---------|
| | $C = 1$ | $C = 2$ |
| $F_1 = t$ | 0.6 | 0.4 |
| $F_1 = f$ | 0.4 | 0.6 |

Also $P_0(F_2|C)$ and $P_0(F_3|C)$

Data:

| F_1 | F_2 | F_3 |
|-------|-------|-------|
| t | t | t |
| t | f | t |
| t | f | f |
| f | f | t |

Expectation

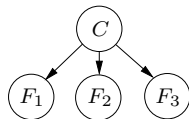
Count table $A(F_1, F_2, F_3, C)$:

| F_1 | F_2 | F_3 | $P(C F_1, F_2, F_3)$ |
|-------|-------|-------|----------------------|
| t | t | t | $(0.84, 0.16)$ |
| t | f | t | |
| t | f | f | |
| f | f | t | |

Maximization

Expectation

- Fractional counts are being calculated by probability updating.



Probability tables:

$$P_0(C) = (0.6, 0.4)$$

| | $P_0(F_1 C)$ | |
|-----------|--------------|---------|
| | $C = 1$ | $C = 2$ |
| $F_1 = t$ | 0.6 | 0.4 |
| $F_1 = f$ | 0.4 | 0.6 |

Also $P_0(F_2|C)$ and $P_0(F_3|C)$

Data:

| F_1 | F_2 | F_3 |
|-------|-------|-------|
| t | t | t |
| t | f | t |
| f | f | t |

Expectation

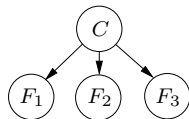
Count table $A(F_1, F_2, F_3, C)$:

| F_1 | F_2 | F_3 | $P(C F_1, F_2, F_3)$ |
|-------|-------|-------|----------------------|
| t | t | t | (0.84, 0.16) |
| t | f | t | (0.69, 0.31) |
| t | f | f | |
| f | f | t | |

Maximization

Expectation

- Fractional counts are being calculated by probability updating.



Probability tables:

$$P_0(C) = (0.6, 0.4)$$

| | $P_0(F_1 C)$ | |
|-----------|--------------|---------|
| | $C = 1$ | $C = 2$ |
| $F_1 = t$ | 0.6 | 0.4 |
| $F_1 = f$ | 0.4 | 0.6 |

Also $P_0(F_2|C)$ and $P_0(F_3|C)$

Data:

| F_1 | F_2 | F_3 |
|-------|-------|-------|
| t | t | t |
| t | f | t |
| t | f | f |
| f | f | t |

Expectation

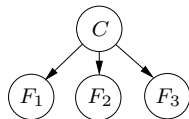
Count table $A(F_1, F_2, F_3, C)$:

| F_1 | F_2 | F_3 | $P(C F_1, F_2, F_3)$ |
|-------|-------|-------|----------------------|
| t | t | t | (0.84, 0.16) |
| t | f | t | (0.69, 0.31) |
| t | f | f | (0.5, 0.5) |
| f | f | t | |

Maximization

Expectation

- Fractional counts are being calculated by probability updating.



Data:

| F_1 | F_2 | F_3 |
|-------|-------|-------|
| t | t | t |
| t | f | t |
| t | f | f |
| f | f | t |

Probability tables:

$$P_0(C) = (0.6, 0.4)$$

| $P_0(F_1 C)$ | C | |
|--------------|---------|---------|
| | $C = 1$ | $C = 2$ |
| $F_1 = t$ | 0.6 | 0.4 |
| $F_1 = f$ | 0.4 | 0.6 |

Also $P_0(F_2|C)$ and $P_0(F_3|C)$

Expectation

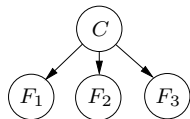
Count table $A(F_1, F_2, F_3, C)$:

| F_1 | F_2 | F_3 | $P(C F_1, F_2, F_3)$ |
|-------|-------|-------|----------------------|
| t | t | t | (0.84, 0.16) |
| t | f | t | (0.69, 0.31) |
| t | f | f | (0.5, 0.5) |
| f | f | t | (0.5, 0.5) |

Maximization

Expectation

- Fractional counts are being calculated by probability updating.



Data:

| F_1 | F_2 | F_3 |
|-------|-------|-------|
| t | t | t |
| t | f | t |
| t | f | f |
| f | f | t |

Probability tables:

$$P_0(C) = (0.6, 0.4)$$

| $P_0(F_1 C)$ | $C = 1$ | $C = 2$ |
|--------------|---------|---------|
| $F_1 = t$ | 0.6 | 0.4 |
| $F_1 = f$ | 0.4 | 0.6 |

Also $P_0(F_2|C)$ and $P_0(F_3|C)$

Expectation

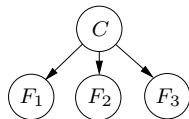
Count table $A(F_1, F_2, F_3, C)$:

| F_1 | F_2 | F_3 | $P(C F_1, F_2, F_3)$ |
|-------|-------|-------|----------------------|
| t | t | t | (0.84, 0.16) |
| t | f | t | (0.69, 0.31) |
| t | f | f | (0.5, 0.5) |
| f | f | t | (0.5, 0.5) |

Maximization

Maximization

$$\begin{aligned}
 P_1(C) &= \frac{1}{4} \sum_{F_1, F_2, F_3} A(F_1, F_2, F_3, C) = \frac{1}{4} (0.84 + 0.69 + 0.5 + 0.5, 0.16 + 0.31 + 0.5 + 0.5) \\
 &= (0.63, 0.37)
 \end{aligned}$$



Probability tables:

$$P_1(C) = (0.63, 0.37)$$

| $P_0(F_1 C)$ | $C = 1 \quad C = 2$ | |
|--------------|---------------------|---------|
| | $C = 1$ | $C = 2$ |
| $F_1 = t$ | 0.6 | 0.4 |
| $F_1 = f$ | 0.4 | 0.6 |

Also $P_0(F_2|C)$ and $P_0(F_3|C)$

Data:

| F_1 | F_2 | F_3 |
|-------|-------|-------|
| t | t | t |
| t | f | t |
| t | f | f |
| f | f | t |

Expectation

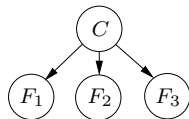
Count table $A(F_1, F_2, F_3, C)$:

| F_1 | F_2 | F_3 | $P(C F_1, F_2, F_3)$ |
|-------|-------|-------|----------------------|
| t | t | t | (0.84, 0.16) |
| t | f | t | (0.69, 0.31) |
| t | f | f | (0.5, 0.5) |
| f | f | t | (0.5, 0.5) |

Maximization

Maximization

$$\begin{aligned}
 P_1(C) &= \frac{1}{4} \sum_{F_1, F_2, F_3} A(F_1, F_2, F_3, C) = \frac{1}{4} (0.84 + 0.69 + 0.5 + 0.5, 0.16 + 0.31 + 0.5 + 0.5) \\
 &= (0.63, 0.37)
 \end{aligned}$$



Probability tables:

$$P_1(C) = (0.63, 0.37)$$

| | $P_0(F_1 C)$ | |
|-----------|--------------|---------|
| | $C = 1$ | $C = 2$ |
| $F_1 = t$ | 0.6 | 0.4 |
| $F_1 = f$ | 0.4 | 0.6 |

Also $P_0(F_2|C)$ and $P_0(F_3|C)$

Data:

| F_1 | F_2 | F_3 |
|-------|-------|-------|
| t | t | t |
| t | f | t |
| t | f | f |
| f | f | t |

Expectation

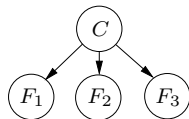
Count table $A(F_1, F_2, F_3, C)$:

| F_1 | F_2 | F_3 | $P(C F_1, F_2, F_3)$ |
|-------|-------|-------|----------------------|
| t | t | t | (0.84, 0.16) |
| t | f | t | (0.69, 0.31) |
| t | f | f | (0.5, 0.5) |
| f | f | t | (0.5, 0.5) |

Maximization

Maximization

$$\begin{aligned}
 P_1(F_1|C) &= \frac{\sum_{F_2, F_3} A(F_1, F_2, F_3, C)}{\sum_{F_1, F_2, F_3} A(F_1, F_2, F_3, C)} = \frac{\begin{pmatrix} 0.84 + 0.69 + 0.5 + 0 & 0.16 + 0.31 + 0.5 + 0 \\ 0 + 0 + 0 + 0.5 & 0 + 0 + 0 + 0.5 \end{pmatrix}}{(2.53, 1.47)} \\
 &= \begin{pmatrix} 0.8 & 0.65 \\ 0.2 & 0.35 \end{pmatrix}
 \end{aligned}$$



Probability tables:

$$P_1(C) = (0.63, 0.37)$$

Data:

| F_1 | F_2 | F_3 |
|-------|-------|-------|
| t | t | t |
| t | f | t |
| t | f | f |
| f | f | t |

$P_1(F_1|C)$

| | $C = 1$ | $C = 2$ |
|-----------|---------|---------|
| $F_1 = t$ | 0.8 | 0.65 |
| $F_1 = f$ | 0.2 | 0.35 |

Also $P_0(F_2|C)$ and $P_0(F_3|C)$

Expectation

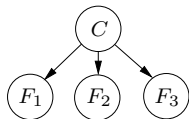
Count table $A(F_1, F_2, F_3, C)$:

| F_1 | F_2 | F_3 | $P(C F_1, F_2, F_3)$ |
|-------|-------|-------|----------------------|
| t | t | t | (0.84, 0.16) |
| t | f | t | (0.69, 0.31) |
| t | f | f | (0.5, 0.5) |
| f | f | t | (0.5, 0.5) |

Maximization

Maximization

$$\begin{aligned}
 P_1(F_1|C) &= \frac{\sum_{F_2, F_3} A(F_1, F_2, F_3, C)}{\sum_{F_1, F_2, F_3} A(F_1, F_2, F_3, C)} = \frac{\begin{pmatrix} 0.84 + 0.69 + 0.5 + 0 & 0.16 + 0.31 + 0.5 + 0 \\ 0 + 0 + 0 + 0.5 & 0 + 0 + 0 + 0.5 \end{pmatrix}}{(2.53, 1.47)} \\
 &= \begin{pmatrix} 0.8 & 0.65 \\ 0.2 & 0.35 \end{pmatrix}
 \end{aligned}$$



Data:

| F_1 | F_2 | F_3 |
|-------|-------|-------|
| t | t | t |
| t | f | t |
| t | f | f |
| f | f | t |

Probability tables:

$$P_1(C) = (0.63, 0.37)$$

| | $P_1(F_1 C)$ | |
|-----------|--------------|---------|
| | $C = 1$ | $C = 2$ |
| $F_1 = t$ | 0.8 | 0.65 |
| $F_1 = f$ | 0.2 | 0.35 |

Also $P_0(F_2|C)$ and $P_0(F_3|C)$

Expectation

Count table $A(F_1, F_2, F_3, C)$:

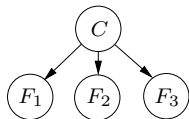
| F_1 | F_2 | F_3 | $P(C F_1, F_2, F_3)$ |
|-------|-------|-------|----------------------|
| t | t | t | (0.84, 0.16) |
| t | f | t | (0.69, 0.31) |
| t | f | f | (0.5, 0.5) |
| f | f | t | (0.5, 0.5) |

Maximization

Maximization

$$P_1(F_2|C) = \dots = \begin{pmatrix} 0.33 & 0.11 \\ 0.67 & 0.89 \end{pmatrix}$$

$$P_1(F_3|C) = \dots = \begin{pmatrix} 0.80 & 0.66 \\ 0.20 & 0.34 \end{pmatrix}$$



Probability tables:

$$P_1(C) = (0.63, 0.37)$$

Data:

| F_1 | F_2 | F_3 |
|-------|-------|-------|
| t | t | t |
| t | f | t |
| t | f | f |
| f | f | t |

$P_1(F_1|C)$

| | $C = 1$ | $C = 2$ |
|-----------|---------|---------|
| $F_1 = t$ | 0.8 | 0.65 |
| $F_1 = f$ | 0.2 | 0.35 |

Also $P_1(F_2|C)$ and $P_1(F_3|C)$

Expectation

Count table $A(F_1, F_2, F_3, C)$:

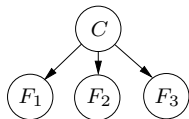
| F_1 | F_2 | F_3 | $P(C F_1, F_2, F_3)$ |
|-------|-------|-------|----------------------|
| t | t | t | (0.84, 0.16) |
| t | f | t | (0.69, 0.31) |
| t | f | f | (0.5, 0.5) |
| f | f | t | (0.5, 0.5) |

Maximization

Maximization

$$P_1(F_2|C) = \dots = \begin{pmatrix} 0.33 & 0.11 \\ 0.67 & 0.89 \end{pmatrix}$$

$$P_1(F_3|C) = \dots = \begin{pmatrix} 0.80 & 0.66 \\ 0.20 & 0.34 \end{pmatrix}$$



Data:

| F_1 | F_2 | F_3 |
|-------|-------|-------|
| t | t | t |
| t | f | t |
| t | f | f |
| f | f | t |

Probability tables:

$$P_1(C) = (0.63, 0.37)$$

| | $P_1(F_1 C)$ | |
|-----------|--------------|---------|
| | $C = 1$ | $C = 2$ |
| $F_1 = t$ | 0.8 | 0.65 |
| $F_1 = f$ | 0.2 | 0.35 |

Also $P_1(F_2|C)$ and $P_1(F_3|C)$

Expectation

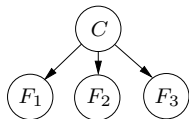
Count table $A(F_1, F_2, F_3, C)$:

| F_1 | F_2 | F_3 | $P(C F_1, F_2, F_3)$ |
|-------|-------|-------|----------------------|
| t | t | t | $(0.88, 0.12)$ |
| t | f | t | |
| t | f | f | |
| f | f | t | |

Maximization

Expectation

- Fractional counts are being calculated by probability updating.



Data:

| F_1 | F_2 | F_3 |
|-------|-------|-------|
| t | t | t |
| t | f | t |
| t | f | f |
| f | f | t |

Probability tables:

$$P_1(C) = (0.63, 0.37)$$

| | $P_1(F_1 C)$ | |
|-----------|--------------|---------|
| | $C = 1$ | $C = 2$ |
| $F_1 = t$ | 0.8 | 0.65 |
| $F_1 = f$ | 0.2 | 0.35 |

Also $P_1(F_2|C)$ and $P_1(F_3|C)$

Expectation

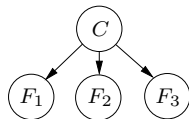
Count table $A(F_1, F_2, F_3, C)$:

| F_1 | F_2 | F_3 | $P(C F_1, F_2, F_3)$ |
|-------|-------|-------|----------------------|
| t | t | t | (0.88, 0.12) |
| t | f | t | (0.66, 0.34) |
| t | f | f | |
| f | f | t | |

Maximization

Expectation

- Fractional counts are being calculated by probability updating.



Data:

| F_1 | F_2 | F_3 |
|-------|-------|-------|
| t | t | t |
| t | f | t |
| t | f | f |
| f | f | t |

Probability tables:

$$P_1(C) = (0.63, 0.37)$$

| | $P_1(F_1 C)$ | |
|-----------|--------------|---------|
| | $C = 1$ | $C = 2$ |
| $F_1 = t$ | 0.8 | 0.65 |
| $F_1 = f$ | 0.2 | 0.35 |

Also $P_1(F_2|C)$ and $P_1(F_3|C)$

Expectation

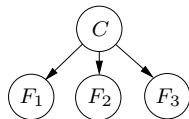
Count table $A(F_1, F_2, F_3, C)$:

| F_1 | F_2 | F_3 | $P(C F_1, F_2, F_3)$ |
|-------|-------|-------|----------------------|
| t | t | t | (0.88, 0.12) |
| t | f | t | (0.66, 0.34) |
| t | f | f | (0.48, 0.52) |
| f | f | t | |

Maximization

Expectation

- Fractional counts are being calculated by probability updating.



Probability tables:

$$P_1(C) = (0.63, 0.37)$$

Data:

| F_1 | F_2 | F_3 |
|-------|-------|-------|
| t | t | t |
| t | f | t |
| t | f | f |
| f | f | t |

$P_1(F_1|C)$

| | $C = 1$ | $C = 2$ |
|-----------|---------|---------|
| $F_1 = t$ | 0.8 | 0.65 |
| $F_1 = f$ | 0.2 | 0.35 |

Also $P_1(F_2|C)$ and $P_1(F_3|C)$

Expectation

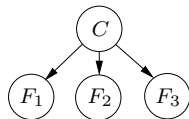
Count table $A(F_1, F_2, F_3, C)$:

| F_1 | F_2 | F_3 | $P(C F_1, F_2, F_3)$ |
|-------|-------|-------|----------------------|
| t | t | t | (0.88, 0.12) |
| t | f | t | (0.66, 0.34) |
| t | f | f | (0.48, 0.52) |
| f | f | t | (0.47, 0.53) |

Maximization

Expectation

- Fractional counts are being calculated by probability updating.



Probability tables:

$$P_1(C) = (0.63, 0.37)$$

Data:

| F_1 | F_2 | F_3 |
|-------|-------|-------|
| t | t | t |
| t | f | t |
| t | f | f |
| f | f | t |

| | $P_1(F_1 C)$ | |
|-----------|--------------|---------|
| | $C = 1$ | $C = 2$ |
| $F_1 = t$ | 0.8 | 0.65 |
| $F_1 = f$ | 0.2 | 0.35 |

Also $P_1(F_2|C)$ and $P_1(F_3|C)$

Expectation

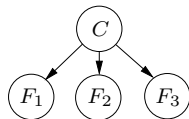
Count table $A(F_1, F_2, F_3, C)$:

| F_1 | F_2 | F_3 | $P(C F_1, F_2, F_3)$ |
|-------|-------|-------|----------------------|
| t | t | t | (0.88, 0.12) |
| t | f | t | (0.66, 0.34) |
| t | f | f | (0.48, 0.52) |
| f | f | t | (0.47, 0.53) |

Maximization

Maximization

$$\begin{aligned}
 P_2(C) &= \frac{1}{4} \sum_{F_1, F_2, F_3} A(F_1, F_2, F_3, C) = \frac{1}{4} (0.88 + 0.66 + 0.48 + 0.47, 0.12 + 0.34 + 0.52 + 0.53) \\
 &= (0.62, 0.38)
 \end{aligned}$$



Probability tables:

$$P_2(C) = (0.62, 0.38)$$

Data:

| F_1 | F_2 | F_3 |
|-------|-------|-------|
| t | t | t |
| t | f | t |
| t | f | f |
| f | f | t |

$P_1(F_1|C)$

| | $C = 1$ | $C = 2$ |
|-----------|---------|---------|
| $F_1 = t$ | 0.8 | 0.65 |
| $F_1 = f$ | 0.2 | 0.35 |

Also $P_1(F_2|C)$ and $P_1(F_3|C)$

Expectation

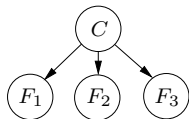
Count table $A(F_1, F_2, F_3, C)$:

| F_1 | F_2 | F_3 | $P(C F_1, F_2, F_3)$ |
|-------|-------|-------|----------------------|
| t | t | t | (0.88, 0.12) |
| t | f | t | (0.66, 0.34) |
| t | f | f | (0.48, 0.52) |
| f | f | t | (0.47, 0.53) |

Maximization

Maximization

$$P_2(C) = \frac{1}{4} \sum_{F_1, F_2, F_3} A(F_1, F_2, F_3, C) = \frac{1}{4} (0.88 + 0.66 + 0.48 + 0.47, 0.12 + 0.34 + 0.52 + 0.53) \\ = (0.62, 0.38)$$



Probability tables:

$$P_2(C) = (0.62, 0.38)$$

| | $P_1(F_1 C)$ | |
|-----------|--------------|---------|
| | $C = 1$ | $C = 2$ |
| $F_1 = t$ | 0.8 | 0.65 |
| $F_1 = f$ | 0.2 | 0.35 |

Also $P_1(F_2|C)$ and $P_1(F_3|C)$

Data:

| F_1 | F_2 | F_3 |
|-------|-------|-------|
| t | t | t |
| t | f | t |
| t | f | f |
| f | f | t |

Expectation

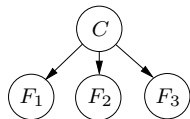
Count table $A(F_1, F_2, F_3, C)$:

| F_1 | F_2 | F_3 | $P(C F_1, F_2, F_3)$ |
|-------|-------|-------|----------------------|
| t | t | t | (0.88, 0.12) |
| t | f | t | (0.66, 0.34) |
| t | f | f | (0.48, 0.52) |
| f | f | t | (0.47, 0.53) |

Maximization

Maximization

$$\begin{aligned}
 P_2(F_1|C) &= \frac{\sum_{F_2, F_3} A(F_1, F_2, F_3, C)}{\sum_{F_1, F_2, F_3} A(F_1, F_2, F_3, C)} = \frac{\begin{pmatrix} 0.88 + 0.66 + 0.48 + 0 & 0.12 + 0.34 + 0.52 + 0 \\ 0 + 0 + 0 + 0.47 & 0 + 0 + 0 + 0.53 \end{pmatrix}}{(2.49, 1.51)} \\
 &= \begin{pmatrix} 0.81 & 0.65 \\ 0.19 & 0.35 \end{pmatrix}
 \end{aligned}$$



Probability tables:

$$P_2(C) = (0.62, 0.38)$$

$P_2(F_1|C)$

| | $C = 1$ | $C = 2$ |
|-----------|---------|---------|
| $F_1 = t$ | 0.81 | 0.65 |
| $F_1 = f$ | 0.19 | 0.35 |

Also $P_1(F_2|C)$ and $P_1(F_3|C)$

Data:

| F_1 | F_2 | F_3 |
|-------|-------|-------|
| t | t | t |
| t | f | t |
| t | f | f |
| f | f | t |

Expectation

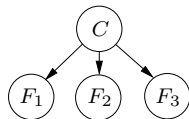
Count table $A(F_1, F_2, F_3, C)$:

| F_1 | F_2 | F_3 | $P(C F_1, F_2, F_3)$ |
|-------|-------|-------|----------------------|
| t | t | t | (0.88, 0.12) |
| t | f | t | (0.66, 0.34) |
| t | f | f | (0.48, 0.52) |
| f | f | t | (0.47, 0.53) |

Maximization

Maximization

$$\begin{aligned}
 P_2(F_1|C) &= \frac{\sum_{F_2, F_3} A(F_1, F_2, F_3, C)}{\sum_{F_1, F_2, F_3} A(F_1, F_2, F_3, C)} = \frac{\begin{pmatrix} 0.88 + 0.66 + 0.48 + 0 & 0.12 + 0.34 + 0.52 + 0 \\ 0 + 0 + 0 + 0.47 & 0 + 0 + 0 + 0.53 \end{pmatrix}}{(2.49, 1.51)} \\
 &= \begin{pmatrix} 0.81 & 0.65 \\ 0.19 & 0.35 \end{pmatrix}
 \end{aligned}$$

**Data:**

| F_1 | F_2 | F_3 |
|-------|-------|-------|
| t | t | t |
| t | f | t |
| t | f | f |
| f | f | t |

Probability tables:

$$P_2(C) = (0.62, 0.38)$$

 $P_2(F_1|C)$

| | $C = 1$ | $C = 2$ |
|-----------|---------|---------|
| $F_1 = t$ | 0.81 | 0.65 |
| $F_1 = f$ | 0.19 | 0.35 |

Also $P_1(F_2|C)$ and $P_1(F_3|C)$

Expectation

Count table $A(F_1, F_2, F_3, C)$:

| F_1 | F_2 | F_3 | $P(C F_1, F_2, F_3)$ |
|-------|-------|-------|----------------------|
| t | t | t | (0.88, 0.12) |
| t | f | t | (0.66, 0.34) |
| t | f | f | (0.48, 0.52) |
| f | f | t | (0.47, 0.53) |

Maximization

Maximization

... and so we continue until a termination criterion is reached.

Correctness

- The sequence of probability estimates generated by the EM algorithm converges to a local maximum (in rare cases: a saddle point) of the marginal likelihood given the data.
- To avoid sub-optimal local maxima: run EM several times with different starting points.

Correctness

- The sequence of probability estimates generated by the EM algorithm converges to a local maximum (in rare cases: a saddle point) of the marginal likelihood given the data.
- To avoid sub-optimal local maxima: run EM several times with different starting points.

Notes

- Any permutation of the cluster labels of a local maximum will also be a local maximum.
- Rather than keeping track of a full count table, it suffices to store counts for the variable families, $fa(X) = \{X\} \cup pa(X)$. Only one pass through the data is necessary.
- Clustering an existing or new instance \mathbf{x} amounts to calculating $P(C|\mathbf{x})$.

Cluster evaluation

A clustering algorithm applied to a dataset will return a clustering - even if there is no meaningful structure in the data!

Question: Do the clusters actually correspond to meaningful groups of data instances?

Question: Are all the clusters relevant, or are there some real and some meaningless clusters?

Unsupervised

- Uses only the data as given to the clustering algorithm, and the resulting clustering
- The realistic scenario
- Can be guided by considering changes in evaluation score.

Supervised

- Uses external information, e.g. a true class label as the “gold standard” for actual groups in the data
- Not representative for actual clustering applications
- Can be useful to evaluate *clustering algorithms*
- Caveat: no guarantee that the class labels actually describe the most natural or relevant groups in the data