## Gromov-Witten theory and mirror symmetry

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### Chapter 1

#### Gromov-Witten invariants

Roughly speaking, Gromov-Witten invariants is the number of algebraic curves (resp. pseduo-holomorphic curves) of a algebraic variety X (resp. complex manifold) passing through specific subvarieties (resp. submanifolds) under specific degree (homology class of the curves) and genus.

**Definition 1.0.1.** Let  $\gamma_1, \ldots, \gamma_n \in H^*(X; \mathbb{Q})$  and let  $\beta \in H^2(X; \mathbb{Q})$ . The Gromov-Witten invariant of genus g degree  $\beta$  curves is

$$\langle \gamma_1 \dots \gamma_n \rangle_{g,n,\beta} = \int_{[\overline{\mathcal{M}}_{g,n}(X,\beta)]^{vir}} ev_1^*(\gamma_1) \cup \dots \cup ev_n^*(\gamma_n).$$

Here, a point in  $[\overline{\mathcal{M}}_{g,n}(X,\beta)]^{vir}$  is  $[f:C\to X,1,\ldots,n]$ :

a map from the genus g curve C to the variety X modulo the automorphism of C.

The evaluation map  $ev_i : [\overline{\mathcal{M}}_{g,n}(X,\beta)]^{vir} \to X$  is given by

$$ev_i([f:C\to X,1,\ldots,n])=f(i).$$

Let  $\overline{\mathcal{M}}_{g,n}$  denote the moduli space (Deligne-Mumford stack) of genus g curves with n marked points, and let  $\overline{\mathcal{C}}_{g,n}$  be the universal family of  $\overline{\mathcal{M}}_{g,n}$ .

#### 1.1 Kontsevich's approach

Atiyah-Bott localization formula tells us: if there is a torus action  $\mathbb{T} = (\mathbb{C}^*)^n$  on X, then the fixed points of torus action could tells us some properties of X.

By the classifying space theory,  $B\mathbb{T} = (\mathbb{C}P^{\infty})^{\times n}$ , so  $H^*(B\mathbb{T}) = \mathbb{C}[\lambda_1, \dots, \lambda_n]$ . Let  $\mathcal{R}_{\mathbb{T}} = \mathbb{C}(\lambda_1, \dots, \lambda_n)$ . Let  $X_{\mathbb{T}} = E\mathbb{T} \times_{\mathbb{T}} X$ , the equivariant cohomology of X is defined by

$$H_{\mathbb{T}}^*(X) := H^*(X_{\mathbb{T}}) = H^*(E\mathbb{T} \times_{\mathbb{T}} X),$$

so naturally,  $H_{\mathbb{T}}^*(X)$  is a  $H_{\mathbb{T}}^*(pt) = H^*(B\mathbb{T})$ -module. The localization of  $H_{\mathbb{T}}^*(X)$  means  $H_{\mathbb{T}}^*(X) \otimes \mathcal{R}_{\mathbb{T}}$ .

**Theorem** (Atiyah-Bott). Let  $X^{\mathbb{T}}$  be fixed locus of  $\mathbb{T}$ , let  $Z_j$  be a connection component of  $X^{\mathbb{T}}$ , and let  $N_j$  be the normal bundle of  $Z_j$  in X. Let  $i_j: Z_j \to X$  and let  $i_{j!}: H^*_{\mathbb{T}}(Z_j) \to H^*_{\mathbb{T}}(X)$  be the pushforward defined by the Gysin map. Let  $\alpha \in H^*_{\mathbb{T}}(X) \otimes \mathcal{R}_{\mathbb{T}}$ , we have

$$\alpha = \sum_{j} \frac{i_{j!} i_{j}^{*} \alpha}{Euler_{T}(N_{j})},$$

In particular,

$$\int_{X_{\mathbb{T}}} \alpha = \sum_{j} \int_{(Z_{j})_{\mathbb{T}}} \frac{i_{j}^{*} \alpha}{Euler_{T}(N_{j})}.$$

Kontsevich's approach is to apply Atiyah-Bott localization formula in  $[\overline{\mathcal{M}}_{g,n}(X,\beta)]^{vir}$  so that we can simplify the computation. We can lift the  $\mathbb{T}$  action on X to  $[\overline{\mathcal{M}}_{g,n}(X,\beta)]^{vir}$  in the following way: let  $t \in \mathbb{T}$ ,  $[f:C \to X,1,\ldots,n] \in [\overline{\mathcal{M}}_{g,n}(X,\beta)]^{vir}$ ,  $x \in X$ 

$$(t \cdot f)(x) = f(t \cdot x).$$

In special, we will consider  $\overline{\mathcal{M}}_{g,n}(\mathbb{P}^n,d)$  in this section. As claimed before, we need to find  $[f:C\to X,1,\ldots,n]\in \overline{\mathcal{M}}_{g,n}(\mathbb{P}^n,d)^{\mathbb{T}}$ . The fixed points of  $\mathbb{C}P^n$  is

$${q_i = [0:0:\dots:1:0:\dots:0]}_{0 \le i \le n}.$$

The coordinate curve  $l_{ij}$  connecting  $q_i, q_j$  has one dimensional degree of freedom  $\mathbb{C}^*$  (as an invariant component). The curve  $C \in \overline{C}_{g,n}$  is stable (i.e.  $\operatorname{Aut}(C) < \infty$ ) if and only if 2g - 2 + n > 0. If a components C' of C is mapped to  $l_{ij}$ , then C' has two points mapped to  $q_i, q_j$  respectively (equivalent to with two marked points in C'), so  $2g - 2 + 2 \leq 0$  implies g = 0, i.e.  $C' \cong \mathbb{P}^1$  (see Fig 1.1). Meanwhile,  $f|_{C'}$  must be uniformly ramified, so  $f|_{C'}(z) = z^e, \forall z \in C' \cong \mathbb{P}^1$ , for some  $e \in \mathbb{N}^*$ .

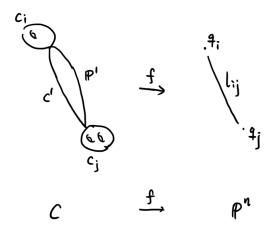


Figure 1.1:  $f(C_i) = q_i$ ,  $f(C') = l_{ij}$ ,  $f(C_i) = q_i$ 

It is convenient to use a decorated graph  $\vec{\Gamma} = (\Gamma, \vec{f}, \vec{d}, \vec{g}, \vec{s})$  (graph, maps, degrees, genus, marked points) to represent  $[f: C \to X, 1, \dots, n] \in \overline{\mathcal{M}}_{g,n}(\mathbb{P}^n, d)^{\mathbb{T}}$ . Let  $\operatorname{val}(v)$ , the valence of v, be the number of edges connecting vertex v, and let  $n(v) = |s_v| + val(v)$ . The stable map  $[f: C \to X, 1, \dots, n]$  with fixed graph  $\vec{\Gamma} = (\Gamma, \vec{f}, \vec{d}, \vec{g}, \vec{s})$  defines a substack

$$\overline{\mathcal{M}}_{\vec{\Gamma}} \subset \overline{\mathcal{M}}_{g,n}(\mathbb{P}^n, d).$$

On the other sides, consider

$$\varphi_{\vec{\Gamma}}: \prod_{\dim C_v=1} \overline{M}_{g_v, n(v)} \to \overline{\mathcal{M}}_{\vec{\Gamma}}.$$

If v, v' are connected by an edge e, then let  $C_v, C_{v'}$  connected by a  $C_e \cong \mathbb{P}^1$  associated with a degree  $d_e$  map to  $\mathbb{P}^n$ . Let  $\overline{M}_{\Gamma}$  be the product of above  $C_v, C_e$ . There is a group  $\mathbb{A}_{\Gamma}$  acting on  $\overline{M}_{\Gamma}$ . The group  $\mathbb{A}_{\Gamma}$  is defined by:

$$1 \to \prod_{edges} \mathbb{Z}/(d_e) \to \mathbb{A}_{\Gamma} \to Aut(\Gamma) \to 1.$$

and

$$\overline{\mathcal{M}}_{\vec{\Gamma}} = \overline{M}_{\Gamma}/\mathbb{A}_{\Gamma}.$$

Therefore, we know the  $\mathbb{T}$ -fixed locus of  $\overline{\mathcal{M}}_{g,n}(\mathbb{P}^n,d)$  is  $\overline{\mathcal{M}}_{\vec{\Gamma}}$ . Let  $N_{\Gamma}$  be the normal bundle of  $\overline{\mathcal{M}}_{\vec{\Gamma}}$  in  $\overline{\mathcal{M}}_{g,n}(\mathbb{P}^n,d)$ . Then there is an explicit formula for

the equivariant Euler class. Before doing that, we define some necessary notations. A flag F is a pair (v, e) such that e is an edge containing the vertex v. We put i(F) = v, j(F) the vertex of e different from v. Let

$$\omega_F = \frac{\lambda_{i(F)} - \lambda_{j(F)}}{d_e} \in H^2_{\mathbb{T}}(pt) = \mathbb{Q}[\lambda_0, \dots, \lambda_r],$$

which is the weight of T-action on  $T_{q_{in}}C_e$ .

**Theorem 1.1.1** ( $Euler_{\mathbb{T}}(N_{\Gamma})$ ).  $Euler_{\mathbb{T}}(N_{\Gamma}) = e_{\Gamma}^F e_{\Gamma}^v e_{\Gamma}^e$ , where

$$e_{\Gamma}^{F} = \prod_{n(i(F))\geq 3} (\omega_{F} - \psi_{F}) / \prod_{j\neq i(F)} (\lambda_{i(F)} - \lambda_{j}),$$

$$e_{\Gamma}^{v} = \prod_{v} \prod_{j\neq i_{v}} (\lambda_{i_{v}} - \lambda_{j}) \prod_{val(v)=2, s_{v}=\emptyset} (\omega_{F_{1}(v)} + \omega_{F_{2}(v)}) / \prod_{val(v)=1, s_{v}=\emptyset} \omega_{F(v)}$$

$$e_{\Gamma}^{e} = \prod_{e} \frac{(-1)^{d_{e}} (d_{e}!)^{2} (\lambda_{i} - \lambda_{j})^{2d_{e}}}{d_{e}^{2d_{e}}} \prod_{a+b=d_{e}, k\neq i, j} (\frac{a\lambda_{i} + b\lambda_{j}}{d_{e}} - \lambda_{k})$$

The proof is partially discussed in section 1.2.

#### 1.2 Tangent-obstruction sequence

Consider 
$$[f: C \to X, 1, ..., n] \in \overline{\mathcal{M}}_{\vec{\Gamma}}, \vec{\Gamma} = (\Gamma, \vec{f}, \vec{d}, \vec{g}, \vec{s})$$
. We put  $V^1(\Gamma) := \{v \in V(\Gamma) : g_v = 0, val(v) = 1, |s_v| = 0\}$   
 $V^2(\Gamma) := \{v \in V(\Gamma) : g_v = 0, val(v) = 2, |s_v| = 0\}$   
 $V^{1,1}(\Gamma) := \{v \in V(\Gamma) : g_v = 0, val(v) = 1, |s_v| = 1\}$   
 $V^s(\Gamma) := \{v \in V(\Gamma) : 2g_v - 2 + val(v) + n(v) > 0\}$   
 $y(v, e) := C_e \cap C_v$ 

The tangent-obstruction sequence is

$$0 \to Aut(C, 1, \dots, n)$$

$$\to Def(f) \to Def(C, 1, \dots, n, f) \to Def(C, 1, \dots, n)$$

$$\to Ob(f) \to Ob(C, 1, \dots, n, f) \to 0,$$

$$0 \to Hom(\Omega_C(p_1 + \dots + p_n), \mathcal{O}_C)$$
  
 
$$\to H^0(C, f^*T_X) \to T^1 \to Ext^1(\Omega_C(p_1 + \dots + p_n), \mathcal{O}_C)$$
  
 
$$\to H^1(C, f^*T_X) \to T^2 \to 0.$$

For simplicity:

$$0 \to B_1 \to B_2 \to T^1 \to B_4 \to B_5 \to T^2 \to 0.$$

The  $N^{vir} = T^{1,m} - T^{2,m}$  (m means moving part).

$$Euler_{\mathbb{T}}(N^{vir}) = \frac{Euler_{\mathbb{T}}(B_2^m)Euler_{\mathbb{T}}(B_4^m)}{Euler_{\mathbb{T}}(B_1^m)Euler_{\mathbb{T}}(B_5^m)}.$$

(1)  $Euler_{\mathbb{T}}(B_2^m)/Euler_{\mathbb{T}}(B_5^m)$ . The normalization sequence of C is:

$$0 \to \mathcal{O}_C \to \bigoplus_{v \in V^s(\Gamma)} \mathcal{O}_{C_v} \oplus \bigoplus_{e \in E(\Gamma)} \mathcal{O}_{C_e}$$
$$\to \bigoplus_{v \in V^2(\Gamma)} \mathcal{O}_{y_v} \oplus \bigoplus_{(e,v) \in F^s(\Gamma)} \mathcal{O}_{y(e,v)} \to 0.$$

Take  $\otimes f^*T_X$ :

$$0 \to H^{0}(C, f^{*}T_{X}) \to \bigoplus_{v \in V^{s}(\Gamma)} H^{0}(C_{v}, f^{*}T_{X}) \oplus \bigoplus_{e \in E(\Gamma)} H^{0}(C_{e}, f^{*}T_{X})$$

$$\to \bigoplus_{v \in V^{2}(\Gamma)} T_{f(y_{v})}X \oplus \bigoplus_{(e,v) \in F^{s}(\Gamma)} T_{f(y(e,v))}X$$

$$\to H^{1}(C, f^{*}T_{X}) \to \bigoplus_{v \in V^{s}(\Gamma)} H^{1}(C_{v}, f^{*}T_{X}) \oplus \bigoplus_{e \in E(\Gamma)} H^{1}(C_{e}, f^{*}T_{X}) \to 0.$$

$$H^1(C_v, f^*T_X) = H^1(C_v, \mathcal{O}_{C_v}) \otimes T_{f(C_v)} X \cong H^0(C_v, \omega_{C_v})^{\vee} \otimes T_{f(C_v)} X$$

Here  $H^0(C_v, \omega_{C_v})$  is Hodge bundle  $\mathbb{E}$ . By splitting principle, assume  $\mathbb{E} = L_1 \oplus \cdots \oplus L_g$ , then

 $H^0(C_v, f^*T_X) = T_{f(C_v)}X$ 

$$e(\mathbb{E}^{\vee} \otimes \mathbb{C}_{1}) = \prod_{i=1}^{g} c_{1}(L_{i}^{\vee} \otimes \mathbb{C}_{1}) = \prod_{i=1}^{g} c_{1}(L_{i}^{\vee}) + c_{1}(\mathbb{C}_{1})$$

$$= \prod_{i=1}^{g} (-c_{1}(L_{i}) + u) = \sum_{k=1}^{g} (-1)^{k} c_{k}(\mathbb{E}) u^{g-k} = \sum_{k=1}^{g} (-1)^{k} \lambda_{k} u^{g-k} =: \Lambda_{g}^{\vee}(u)$$

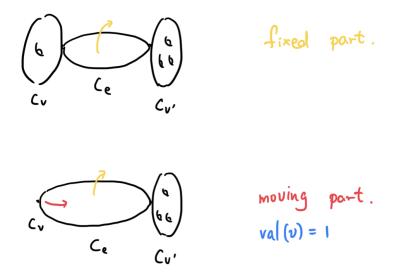


Figure 1.2: automorphism of (C, 1, ..., n)

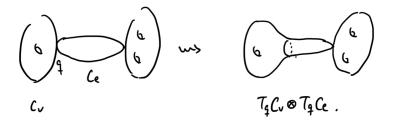


Figure 1.3: deformation of  $(C, 1, \ldots, n)$ 

- (2)  $Euler_{\mathbb{T}}(B_4^m)/Euler_{\mathbb{T}}(B_1^m)$ .
- (2.1)  $B_1 = Aut(C, 1, ..., n) = Hom(\Omega_C(p_1 + ... + p_n), \mathcal{O}_C)$ : We should classify what is moving and what is fixed. Basically, we have

$$B_1^m = \bigoplus_{v \in V^1(\Gamma), (e,v) \in F(\Gamma)} T_{y(e,v)} C_e.$$

(2.2)  $B_4 = Def(C, 1, ..., n) = Ext^1(\Omega_C(p_1 + ... + p_n), \mathcal{O}_C)$ :  $\mathbb{P}^1$  has just 1 complex structure, so we consider  $g(C) \geq 1$ . If we don't change node q, C will stay in the same class in  $\overline{\mathcal{M}}_{g,n}$ . Hence we must resolve the node, and

geometrically, resolution depends on  $T_qC_v\otimes T_qC_e$ . So basically we have

$$B_4^m = \bigoplus_{v \in V^2(\Gamma), E_v = (e, e')} T_{y_v} C_e \otimes T_{y_v} C_{e'} \oplus \bigoplus_{(e, v) \in F^s(\Gamma)} T_{y(e, v)} C_v \otimes T_{y(e, v)} C_e$$

# 1.3 Aspinwall Morrison formula; Faber Pandaripande formula

# Chapter 2 Quantum Cohomology

Chapter 3
Mirror Symmetry