Gromov-Witten theory and mirror symmetry

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Chapter 1

Gromov-Witten invariants

Roughly speaking, Gromov-Witten invariants is the number of algebraic curves (resp. pseduo-holomorphic curves) of a algebraic variety X (resp. complex manifold) passing through specific subvarieties (resp. submanifolds) under specific degree (homology class of the curves) and genus.

Definition 1.0.1. Let $\gamma_1, \ldots, \gamma_n \in H^*(X; \mathbb{Q})$ and let $\beta \in H^2(X; \mathbb{Q})$. The Gromov-Witten invariant of genus g degree β curves is

$$\langle \gamma_1 \dots \gamma_n \rangle_{g,n,\beta} = \int_{[\overline{\mathcal{M}}_{g,n}(X,\beta)]^{vir}} ev_1^*(\gamma_1) \cup \dots \cup ev_n^*(\gamma_n).$$

Here, a point in $[\overline{\mathcal{M}}_{g,n}(X,\beta)]^{vir}$ is $[f:C\to X,1,\ldots,n]$:

a map from the genus g curve C to the variety X modulo the automorphism of C.

The evaluation map $ev_i : [\overline{\mathcal{M}}_{g,n}(X,\beta)]^{vir} \to X$ is given by

$$ev_i([f:C\to X,1,\ldots,n])=f(i).$$

Let $\overline{\mathcal{M}}_{g,n}$ denote the moduli space (Deligne-Mumford stack) of genus g curves with n marked points, and let $\overline{\mathcal{C}}_{g,n}$ be the universal family of $\overline{\mathcal{M}}_{g,n}$.

1.1 Kontsevich's approach

Atiyah-Bott localization formula tells us: if there is a torus action $\mathbb{T} = (\mathbb{C}^*)^n$ on X, then the fixed points of torus action could tells us some properties of X.

By the classifying space theory, $B\mathbb{T} = (\mathbb{C}P^{\infty})^{\times n}$, so $H^*(B\mathbb{T}) = \mathbb{C}[\lambda_1, \dots, \lambda_n]$. Let $\mathcal{R}_{\mathbb{T}} = \mathbb{C}(\lambda_1, \dots, \lambda_n)$. Let $X_{\mathbb{T}} = E\mathbb{T} \times_{\mathbb{T}} X$, the equivariant cohomology of X is defined by

$$H_{\mathbb{T}}^*(X) := H^*(X_{\mathbb{T}}) = H^*(E\mathbb{T} \times_{\mathbb{T}} X),$$

so naturally, $H_{\mathbb{T}}^*(X)$ is a $H_{\mathbb{T}}^*(pt) = H^*(B\mathbb{T})$ -module. The localization of $H_{\mathbb{T}}^*(X)$ means $H_{\mathbb{T}}^*(X) \otimes \mathcal{R}_{\mathbb{T}}$.

Theorem (Atiyah-Bott). Let $X^{\mathbb{T}}$ be fixed locus of \mathbb{T} , let Z_j be a connection component of $X^{\mathbb{T}}$, and let N_j be the normal bundle of Z_j in X. Let $i_j: Z_j \to X$ and let $i_{j!}: H^*_{\mathbb{T}}(Z_j) \to H^*_{\mathbb{T}}(X)$ be the pushforward defined by the Gysin map. Let $\alpha \in H^*_{\mathbb{T}}(X) \otimes \mathcal{R}_{\mathbb{T}}$, we have

$$\alpha = \sum_{j} \frac{i_{j!} i_{j}^{*} \alpha}{Euler_{T}(N_{j})},$$

In particular,

$$\int_{X_{\mathbb{T}}} \alpha = \sum_{j} \int_{(Z_{j})_{\mathbb{T}}} \frac{i_{j}^{*} \alpha}{Euler_{T}(N_{j})}.$$

Kontsevich's approach is to apply Atiyah-Bott localization formula in $[\overline{\mathcal{M}}_{g,n}(X,\beta)]^{vir}$ so that we can simplify the computation. We can lift the \mathbb{T} action on X to $[\overline{\mathcal{M}}_{g,n}(X,\beta)]^{vir}$ in the following way: let $t \in \mathbb{T}$, $[f:C \to X,1,\ldots,n] \in [\overline{\mathcal{M}}_{g,n}(X,\beta)]^{vir}$, $x \in X$

$$(t \cdot f)(x) = f(t \cdot x).$$

In special, we will consider $\overline{\mathcal{M}}_{g,n}(\mathbb{P}^n,d)$ in this section. As claimed before, we need to find $[f:C\to X,1,\ldots,n]\in \overline{\mathcal{M}}_{g,n}(\mathbb{P}^n,d)^{\mathbb{T}}$. The fixed points of $\mathbb{C}P^n$ is

$${q_i = [0:0:\dots:1:0:\dots:0]}_{0 \le i \le n}.$$

The coordinate curve l_{ij} connecting q_i, q_j has one dimensional degree of freedom \mathbb{C}^* (as an invariant component). The curve $C \in \overline{C}_{g,n}$ is stable (i.e. $\operatorname{Aut}(C) < \infty$) if and only if 2g - 2 + n > 0. If a components C' of C is mapped to l_{ij} , then C' has two points mapped to q_i, q_j respectively (equivalent to with two marked points in C'), so $2g - 2 + 2 \leq 0$ implies g = 0, i.e. $C' \cong \mathbb{P}^1$ (see Fig 1.1). Meanwhile, $f|_{C'}$ must be uniformly ramified, so $f|_{C'}(z) = z^e, \forall z \in C' \cong \mathbb{P}^1$, for some $e \in \mathbb{N}^*$.

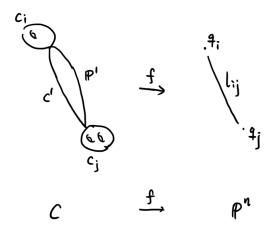


Figure 1.1: $f(C_i) = q_i$, $f(C') = l_{ij}$, $f(C_i) = q_i$

It is convenient to use a decorated graph $\vec{\Gamma} = (\Gamma, \vec{f}, \vec{d}, \vec{g}, \vec{s})$ (graph, maps, degrees, genus, marked points) to represent $[f: C \to X, 1, \dots, n] \in \overline{\mathcal{M}}_{g,n}(\mathbb{P}^n, d)^{\mathbb{T}}$. Let $\operatorname{val}(v)$, the valence of v, be the number of edges connecting vertex v, and let $n(v) = |s_v| + val(v)$. The stable map $[f: C \to X, 1, \dots, n]$ with fixed graph $\vec{\Gamma} = (\Gamma, \vec{f}, \vec{d}, \vec{g}, \vec{s})$ defines a substack

$$\overline{\mathcal{M}}_{\vec{\Gamma}} \subset \overline{\mathcal{M}}_{g,n}(\mathbb{P}^n, d).$$

On the other sides, consider

$$\varphi_{\vec{\Gamma}}: \prod_{\dim C_v=1} \overline{M}_{g_v, n(v)} \to \overline{\mathcal{M}}_{\vec{\Gamma}}.$$

If v, v' are connected by an edge e, then let $C_v, C_{v'}$ connected by a $C_e \cong \mathbb{P}^1$ associated with a degree d_e map to \mathbb{P}^n . Let \overline{M}_{Γ} be the product of above C_v, C_e . There is a group \mathbb{A}_{Γ} acting on \overline{M}_{Γ} . The group \mathbb{A}_{Γ} is defined by:

$$1 \to \prod_{edges} \mathbb{Z}/(d_e) \to \mathbb{A}_{\Gamma} \to Aut(\Gamma) \to 1.$$

and

$$\overline{\mathcal{M}}_{\vec{\Gamma}} = \overline{M}_{\Gamma}/\mathbb{A}_{\Gamma}.$$

Therefore, we know the \mathbb{T} -fixed locus of $\overline{\mathcal{M}}_{g,n}(\mathbb{P}^n,d)$ is $\overline{\mathcal{M}}_{\vec{\Gamma}}$. Let N_{Γ} be the normal bundle of $\overline{\mathcal{M}}_{\vec{\Gamma}}$ in $\overline{\mathcal{M}}_{g,n}(\mathbb{P}^n,d)$. Then there is an explicit formula for

the equivariant Euler class. Before doing that, we define some necessary notations. A flag F is a pair (v, e) such that e is an edge containing the vertex v. We put i(F) = v, j(F) the vertex of e different from v. Let

$$\omega_F = \frac{\lambda_{i(F)} - \lambda_{j(F)}}{d_e} \in H^2_{\mathbb{T}}(pt) = \mathbb{Q}[\lambda_0, \dots, \lambda_r],$$

which is the weight of T-action on $T_{q_{in}}C_e$.

Theorem 1.1.1 ($Euler_{\mathbb{T}}(N_{\Gamma})$). $Euler_{\mathbb{T}}(N_{\Gamma}) = e_{\Gamma}^F e_{\Gamma}^v e_{\Gamma}^e$, where

$$e_{\Gamma}^{F} = \prod_{n(i(F))\geq 3} (\omega_{F} - \psi_{F}) / \prod_{j\neq i(F)} (\lambda_{i(F)} - \lambda_{j}),$$

$$e_{\Gamma}^{v} = \prod_{v} \prod_{j\neq i_{v}} (\lambda_{i_{v}} - \lambda_{j}) \prod_{val(v)=2, s_{v}=\emptyset} (\omega_{F_{1}(v)} + \omega_{F_{2}(v)}) / \prod_{val(v)=1, s_{v}=\emptyset} \omega_{F(v)}$$

$$e_{\Gamma}^{e} = \prod_{e} \frac{(-1)^{d_{e}} (d_{e}!)^{2} (\lambda_{i} - \lambda_{j})^{2d_{e}}}{d_{e}^{2d_{e}}} \prod_{a+b=d_{e}, k\neq i, j} (\frac{a\lambda_{i} + b\lambda_{j}}{d_{e}} - \lambda_{k})$$

The proof is partially discussed in section 1.2.

1.2 Tangent-obstruction sequence

Consider
$$[f: C \to X, 1, ..., n] \in \overline{\mathcal{M}}_{\vec{\Gamma}}, \vec{\Gamma} = (\Gamma, \vec{f}, \vec{d}, \vec{g}, \vec{s})$$
. We put $V^1(\Gamma) := \{v \in V(\Gamma) : g_v = 0, val(v) = 1, |s_v| = 0\}$
 $V^2(\Gamma) := \{v \in V(\Gamma) : g_v = 0, val(v) = 2, |s_v| = 0\}$
 $V^{1,1}(\Gamma) := \{v \in V(\Gamma) : g_v = 0, val(v) = 1, |s_v| = 1\}$
 $V^s(\Gamma) := \{v \in V(\Gamma) : 2g_v - 2 + val(v) + |s_v| > 0\}$
 $y(v, e) := C_e \cap C_v$

The tangent-obstruction sequence is

$$0 \to Aut(C, 1, \dots, n)$$

$$\to Def(f) \to Def(C, 1, \dots, n, f) \to Def(C, 1, \dots, n)$$

$$\to Ob(f) \to Ob(C, 1, \dots, n, f) \to 0,$$

$$0 \to Hom(\Omega_C(p_1 + \dots + p_n), \mathcal{O}_C)$$

$$\to H^0(C, f^*T_X) \to T^1 \to Ext^1(\Omega_C(p_1 + \dots + p_n), \mathcal{O}_C)$$

$$\to H^1(C, f^*T_X) \to T^2 \to 0.$$

For simplicity:

$$0 \to B_1 \to B_2 \to T^1 \to B_4 \to B_5 \to T^2 \to 0.$$

The $N^{vir} = T^{1,m} - T^{2,m}$ (m means moving part).

$$Euler_{\mathbb{T}}(N^{vir}) = \frac{Euler_{\mathbb{T}}(B_2^m)Euler_{\mathbb{T}}(B_4^m)}{Euler_{\mathbb{T}}(B_1^m)Euler_{\mathbb{T}}(B_5^m)}.$$

(1) $Euler_{\mathbb{T}}(B_2^m)/Euler_{\mathbb{T}}(B_5^m)$. The normalization sequence of C is:

$$0 \to \mathcal{O}_C \to \bigoplus_{v \in V^s(\Gamma)} \mathcal{O}_{C_v} \oplus \bigoplus_{e \in E(\Gamma)} \mathcal{O}_{C_e}$$
$$\to \bigoplus_{v \in V^2(\Gamma)} \mathcal{O}_{y_v} \oplus \bigoplus_{(e,v) \in F^s(\Gamma)} \mathcal{O}_{y(e,v)} \to 0.$$

Take $\otimes f^*T_X$:

$$0 \to H^{0}(C, f^{*}T_{X}) \to \bigoplus_{v \in V^{s}(\Gamma)} H^{0}(C_{v}, f^{*}T_{X}) \oplus \bigoplus_{e \in E(\Gamma)} H^{0}(C_{e}, f^{*}T_{X})$$

$$\to \bigoplus_{v \in V^{2}(\Gamma)} T_{f(y_{v})}X \oplus \bigoplus_{(e,v) \in F^{s}(\Gamma)} T_{f(y(e,v))}X$$

$$\to H^{1}(C, f^{*}T_{X}) \to \bigoplus_{v \in V^{s}(\Gamma)} H^{1}(C_{v}, f^{*}T_{X}) \oplus \bigoplus_{e \in E(\Gamma)} H^{1}(C_{e}, f^{*}T_{X}) \to 0.$$

$$H^1(C_v, f^*T_X) = H^1(C_v, \mathcal{O}_{C_v}) \otimes T_{f(C_v)} X \cong H^0(C_v, \omega_{C_v})^{\vee} \otimes T_{f(C_v)} X$$

Here $H^0(C_v, \omega_{C_v})$ is Hodge bundle \mathbb{E} . By splitting principle, assume $\mathbb{E} = L_1 \oplus \cdots \oplus L_g$, then

 $H^0(C_v, f^*T_X) = T_{f(C_v)}X$

$$e(\mathbb{E}^{\vee} \otimes \mathbb{C}_{1}) = \prod_{i=1}^{g} c_{1}(L_{i}^{\vee} \otimes \mathbb{C}_{1}) = \prod_{i=1}^{g} c_{1}(L_{i}^{\vee}) + c_{1}(\mathbb{C}_{1})$$

$$= \prod_{i=1}^{g} (-c_{1}(L_{i}) + u) = \sum_{k=1}^{g} (-1)^{k} c_{k}(\mathbb{E}) u^{g-k} = \sum_{k=1}^{g} (-1)^{k} \lambda_{k} u^{g-k} =: \Lambda_{g}^{\vee}(u)$$

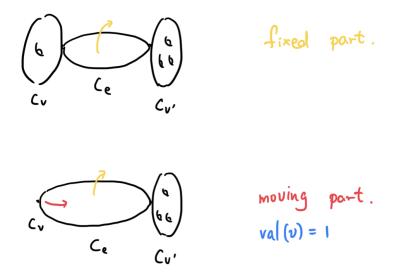


Figure 1.2: automorphism of (C, 1, ..., n)

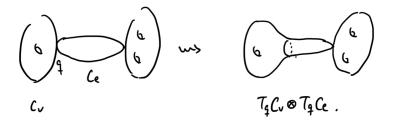


Figure 1.3: deformation of $(C, 1, \ldots, n)$

- (2) $Euler_{\mathbb{T}}(B_4^m)/Euler_{\mathbb{T}}(B_1^m)$.
- (2.1) $B_1 = Aut(C, 1, ..., n) = Hom(\Omega_C(p_1 + ... + p_n), \mathcal{O}_C)$: We should classify what is moving and what is fixed. Basically, we have

$$B_1^m = \bigoplus_{v \in V^1(\Gamma), (e,v) \in F(\Gamma)} T_{y(e,v)} C_e.$$

(2.2) $B_4 = Def(C, 1, ..., n) = Ext^1(\Omega_C(p_1 + ... + p_n), \mathcal{O}_C)$: \mathbb{P}^1 has just 1 complex structure, so we consider $g(C) \geq 1$. If we don't change node q, C will stay in the same class in $\overline{\mathcal{M}}_{g,n}$. Hence we must resolve the node, and

geometrically, resolution depends on $T_qC_v\otimes T_qC_e$. So basically we have

$$B_4^m = \bigoplus_{v \in V^2(\Gamma), E_v = (e, e')} T_{y_v} C_e \otimes T_{y_v} C_{e'} \oplus \bigoplus_{(e, v) \in F^s(\Gamma)} T_{y(e, v)} C_v \otimes T_{y(e, v)} C_e$$

Returning to the special case $X = \mathbb{P}^n$, we can get the theorem 1.1.1.

1.3 Aspinwall Morrison formula; Faber Pandaripande formula

In this section, we will use Kontsevich's approach to compute the multiple cover contribution of rigidly embedding curves \mathbb{P}^1 in a Calabi-Yau threefold X.

The geometry picture is this. The normal bundle N of $\mathbb{P}^1 \subset X$ is rank 2 and splits on \mathbb{P}^1 . Because X is Calabi-Yau and $c_1(\mathbb{P}^1) = 2$, the normal bundle is of degree 2. Embedded \mathbb{P}^1 's in a Calabi-Yau threefold (not necessary lines) with normal bundle $\mathcal{O}(-1) \oplus \mathcal{O}(-1)$ are called rigid. The degree 2 Gromov-Witten invariant of a generic quintic has two contributions:

- (1) rigid conics curves in X;
- (2) lines with double cover, so this part is related to $\overline{\mathcal{M}}_0(\mathbb{P}^1,2)$.

We want to compute the contribution of part (2). This problem finally leads to:

$$N_{g,d} = \int_{\overline{\mathcal{M}}_{g,0}(\mathbb{P}^1,d)} e(R^1 \pi_* f^* N),$$

where

$$\overline{C}_{g,0}(\mathbb{P}^1, d) \xrightarrow{f} \mathbb{P}^1$$

$$\downarrow^{\pi} \quad \text{and } N = \mathcal{O}(-1) \oplus \mathcal{O}(-1).$$

$$\overline{\mathcal{M}}_{g,0}(\mathbb{P}^1, d)$$

The decorated graphs $\vec{\Gamma} = (\Gamma, \vec{f}, \vec{d}, \vec{g}, \vec{s})$ in $\overline{\mathcal{M}}_{g,0}(\mathbb{P}^1, d)^{\mathbb{T}}$ are of the type in Figure 1.4. We can choose different lifts on $\mathcal{O}(-1) \oplus \mathcal{O}(-1)$ so that only $\vec{\Gamma} = (\Gamma, \vec{f}, \vec{d}, \vec{g}, \vec{s})$ with 1 edge contributing $N_{g,d}$.

(1) g = 0 (Aspinwall Morrison formula): $N_{0,d} = 1/d^3$;

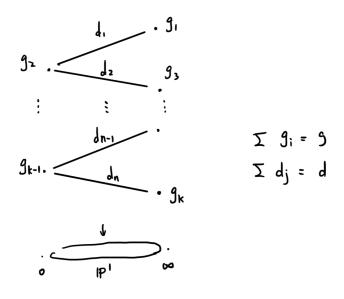


Figure 1.4: $\overline{\mathcal{M}}_{q,0}(\mathbb{P}^1,d)^{\mathbb{T}}$

(2) $g \ge 1$ (Faber-Pandharipande):

$$N_{g,d} = \sum_{g_1 + g_2 = g} \frac{1}{d} \int_{\overline{\mathcal{M}}_{g_1,1}} \lambda_{g_1} \psi^{2g_1 - 2} d^{2g_1 - 1}$$

$$\times \int_{\overline{\mathcal{M}}_{g_2,1}} \lambda_{g_2} \psi^{2g_2 - 2} d^{2g_2 - 1} = \sum_{g_1 + g_2 = g} b_{g_1} b_{g_2} d^{2g - 3}$$

$$b_0 = 0; b_g = \int_{\overline{\mathcal{M}}_{g,1}} \lambda_{g_2} \psi^{2g - 2} \quad (g > 0)$$

$$\sum_{g_2 = 0}^{\infty} b_g t^{2g} = \frac{t/2}{\sin t/2}.$$

Then use the Laurent series of $\cot t$, we have

$$N_{1,d}=\frac{1}{12d},$$

$$N_{g,d}=d^{2g-3}\frac{|B_{2g}|}{2g\cdot(2g-2)!}=|\chi(\overline{\mathcal{M}}_g)|\frac{d^{2g-3}}{(2g-3)!},\quad g\geq 2,$$
 where B_g is the Bernoulli number in $\frac{x}{e^x-1}$.

Chapter 2
Quantum Cohomology

Chapter 3
Mirror Symmetry

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