

BASIC COMPUTING OF SOLUTION DENSITY

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1 INTRODUCTION

Basic computing of **Solution density**, the number of supports & currTable for each pair of (x, a) in the compactTable constraint of Oscar.

2 COMPACT TABLE

2.1 CURRTABLE

T	x	y	z
0	a	a	a
1	a	a	b
2	a	b	c
3	b	a	a
	a	c	b
4	a	b	b
5	b	a	b
6	b	b	a
7	b	b	b

(a) The indexed tuples

currTable	1	1	1	1	1	1	1
supports[x, a]	1	1	1	0	1	0	0
supports[x, b]	0	0	0	1	0	1	1
supports[y, a]	1	1	0	1	0	1	0
supports[y, b]	0	0	1	0	1	0	1
supports[y, d]	0	0	0	0	0	0	0
supports[z, a]	1	0	0	1	0	0	1
supports[z, b]	0	1	0	0	1	1	0
supports[z, c]	0	0	1	0	0	0	0

(b) The corresponding bit-sets

Fig. 2: Illustration of the data structures after the initialization of $\langle x, y, z \rangle \in T$. The tuple (a, c, b) will not be indexed and d will be removed from $dom(y)$.

For example, the solution density of **supports[x,a]** & **currTable** is the **number of ones** after computing, at this case the result is 4.

2.2 ALGORITHM OF SIMPLIFIED VERSION OF CT

Algorithm 1. Class ConstraintCT

```
1 Method updateTable()
2   foreach variable  $x \in \text{scp}$  do
3     mask  $\leftarrow 0$ 
4     if  $|\Delta_x| < |\text{dom}(x)|$  then           // Incremental Update
5       foreach value  $a \in \Delta_x$  do
6         mask  $\leftarrow \text{mask} \mid \text{supports}[x, a]$  // Use  $\text{supports}^*[x, a]$  in CT*
7       mask  $\leftarrow \sim \text{mask}$            //  $\sim$ : bitwise negation
8     else                                   // Reset-based Update
9       foreach value  $a \in \text{dom}(x)$  do
10        mask  $\leftarrow \text{mask} \mid \text{supports}[x, a]$  //  $\mid$ : bitwise or
11      currTable  $\leftarrow \text{currTable} \& \text{mask}$  //  $\&$ : bitwise and
12 Method filterDomains()
13   foreach variable  $x \in \text{scp}$  do
14     foreach value  $a \in \text{dom}(x)$  do
15       if  $\text{currTable} \& \text{supports}[x, a] = 0$  then
16         dom( $x$ )  $\leftarrow \text{dom}(x) \setminus \{a\}$ 
17 Method enforceGAC()
18   updateTable()
19   filterDomains()
```

Modify the **Method** *filterDomains()* and use the **Method** *nbOfOnes()*

3 CT WITH SOLUTION DENSITY

3.2 THE COUNTING OF NBOfONES

Count the number of elements in intersection between currTable and bs(bitset to intersect) and return number of elements in intersection.

```
/**
 * count the number of ones of supports and currTable
 */
def nbOfOnes(bs: BitSet): Int = {
  var count = 0
  var i : Int = nNonZero /*bit length of nWords*/
  while(i > 0){
    i -= 1
    val offset = nonZeroIdx(i)
    count += java.lang.Long.bitCount(words(offset) & bs.words(offset))
  }
  count
}
```

3.1 CT WITH SOLUTION DENSITY

sd is a 2-dimension array: `Array[Array[]]`, I used `ArrayBuffer` to store the counts in sd.

```
//sd is the solution density
val sd = Array.tabulate(x.length)(i => Array.tabulate(spans(i))(v => new ArrayBuffer[Int]()))

/* Create the final support bitSets and remove any value that is not supported */
for {
  varIndex <- variableValueSupports.indices
  valueIndex <- variableValueSupports(varIndex).indices
} {
  if (varValueSupports(varIndex)(valueIndex).nonEmpty) {
    variableValueSupports(varIndex)(valueIndex) = new
      validTuples.BitSet(varValueSupports(varIndex)(valueIndex))
    val count = validTuples.nbfOfOnes(variableValueSupports(varIndex)(valueIndex))

    sd(varIndex)(valueIndex) += count //sd is the solution density
    println(" var index " + varIndex + " value " + valueIndex + " count " + count )
  } else {
    /* This variable-value does not have any support, it can be removed */
    x(varIndex).removeValue(valueIndex)
  }
}
```

3.3 THE MAXOFCOUNT

Find the max count value of each variable. We can get a 3*6 2-dimension array. Variables: val x = Array.fill(5)(CPIIntVar(0 to 5)). When the size of the sd>=1, we will escape the empty ArrayBuffer.

```
// Print two dimensional array and find the max
for {
  varIndex <- variableValueSupports.indices
} {
  var maxOfCount = 0
  for {valueIndex <- variableValueSupports(varIndex).indices} {

    if(sd(varIndex)(valueIndex).size >= 1) {
      val c = sd(varIndex)(valueIndex).head
      //print(" " + c )
      maxOfCount = java.lang.Math.max(maxOfCount, c)
      print(" " + sd(varIndex)(valueIndex))
    }
  }
  print(" Max " + maxOfCount + "\n")
}
```

4. EXPERIMENT

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The origin table is on the left, which is a `Array[Array[]]` format table, including 3 variables and the domain of each variable is between 0-5. The output of count is on the right, for each $X[i]$ and the value in its domain.

```
val tableGround: Array[Array[Int]] = Array(  
  Array(1, 2, 3),  
  Array(2, 3, 4),  
  Array(1, 1, 1),  
  Array(0, 1, 5),  
  Array(1, 2, 5),  
  Array(5, 5, 5)  
)
```

Figure: Origin table

```
var index 0 value 0 count 1  
var index 0 value 1 count 3  
var index 0 value 2 count 1  
var index 0 value 5 count 1  
var index 1 value 1 count 2  
var index 1 value 2 count 2  
var index 1 value 3 count 1  
var index 1 value 5 count 1  
var index 2 value 1 count 1  
var index 2 value 3 count 1  
var index 2 value 4 count 1  
var index 2 value 5 count 3
```

Figure: The count of each (x,a)

4. EXPERIMENT

Table: The count Array[Array[]] format matrix

Variable	Count				MaxCount
X[0]	1	3	1	1	3
X[1]	2	2	1	1	2
X[2]	1	1	1	3	3

```
ArrayBuffer(1) ArrayBuffer(3) ArrayBuffer(1) ArrayBuffer(1) Max 3
ArrayBuffer(2) ArrayBuffer(2) ArrayBuffer(1) ArrayBuffer(1) Max 2
ArrayBuffer(1) ArrayBuffer(1) ArrayBuffer(1) ArrayBuffer(3) Max 3
```

5. CONCLUSION

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- In this project, I want to compute the basic **solution density**, the number of ones in of each pair(x,a) after calculating currTable & Supports(x,a).
- The modification of **Method** *filterDomains()* and use the **Method** *nbOfOnes()* to count the number of ones in currTable & Supports(x,a).
- Construct the 2-dimension array "**sd**" to store the "**counts**" and find the "**max**" of the count.
- Future work: Based on the maximum value and its index to modify the search.

Questions?