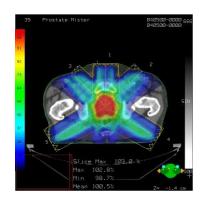
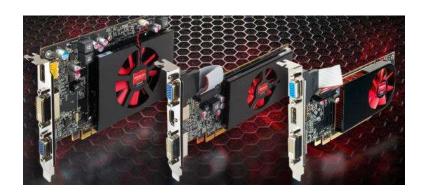


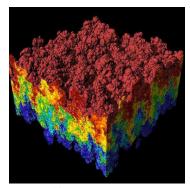


CS 179: GPU Programming

Lecture 1: Introduction







Images: http://en.wikipedia.org
http://www.pcper.com
http://northdallasradiationoncology.com/

The Problem

Are our computers fast enough?

AN x64 PROCESSOR IS SCREAMING ALONG AT BILLIONS OF CYCLES PER SECOND TO RUN THE XNU KERNEL, WHICH IS FRANTICALLY WORKING THROUGH ALL THE POSIX-SPECIFIED ABSTRACTION TO CREATE THE DARWIN SYSTEM UNDERLYING OS X, WHICH IN TURN IS STRAINING ITSELF TO RUN FIREFOX AND ITS GECKO RENDERER, WHICH CREATES A PLASH OBJECT WHICH RENDERS DOZENS OF VIDEO FRAMES EVERY SECOND

BECAUSE I WANTED TO SEE A CAT JUMP INTO A BOX AND FALL OVER.

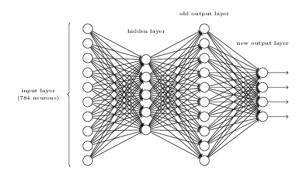


I AM A GOD.

Source: XKCD Comics (http://xkcd.com/676/)

The Problem

Are our computers really fast enough?

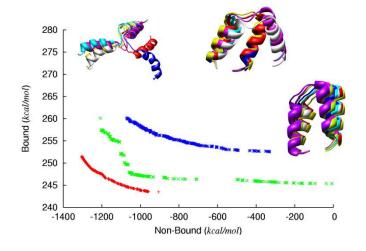


Billion-pixel Gaia camera to map galaxy in 3D

The European Space Agency successfully put its Gaia satellite into orbit, with the hopes of unrolling a stunning map of the Milky Way in 3D.





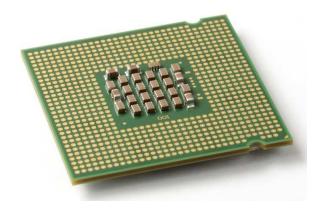


The Problem

 What does it mean to "solve" a computational problem?

The CPU

- The "central processing unit"
- Traditionally, applications use CPU for primary calculations
 - Powerful, general-purpose capabilities
 - R+D -> Moore's Law!
 - Established technology



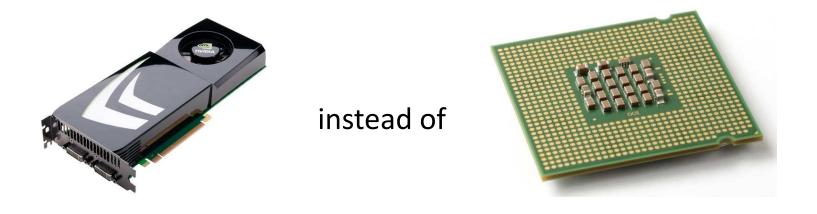
The GPU

- Designed for our "graphics"
- For "graphics problems", much faster than the CPU!
- What about other problems?



This course in 30 seconds

• For certain problems, use



This course in 60 seconds

- GPU: Hundreds of cores!
 - vs. 2,4,8 cores on CPU
- Good for highly parallelizable problems:
 - Increasing speed by 10x, 100x+

Questions

- What is a GPU?
- What is a parallelizable problem?
- What does GPU-accelerated code look like?
- Who cares?

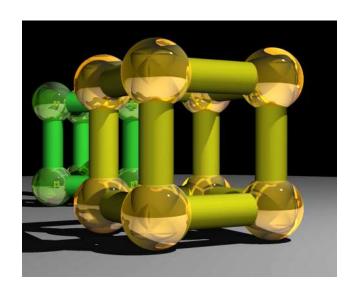
Outline

- Motivations
- Brief history
- "A simple problem"
- "A simple solution"
- Administrivia

- Screens!
 - 1e5 1e7 pixels
- Refresh rate: ~60 Hz
- Total: ~1e7-1e9 pixels/sec!

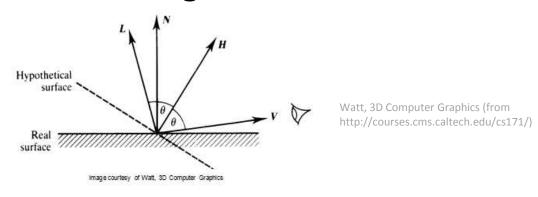
(Very approximate – orders of magnitude)

Lots of calculations are "the same"!

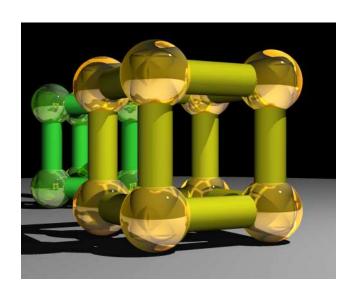


• e.g. Raytracing:

- Superquadric Cylinders, exponent 0.1, yellow glass balls, Barr, 1981
- Goal: Trace light rays, calculate object interaction to produce realistic image



 Lots of calculations are "the same"!



• e.g. Raytracing:

Superquadric Cylinders, exponent 0.1, yellow glass balls, Barr, 1981

```
for all pixels (i,j):
    Calculate ray point and direction in 3d space
    if ray intersects object:
        calculate lighting at closest object
    store color of (i,j)
```

Lots of calculations are "the same"!



e.g. Simple shading:
 for all pixels (i,j):
 replace previous color with new color according to rules

 Lots of calculations are "the same"!

$$T_{\mathbf{v}}\mathbf{p} = \begin{bmatrix} 1 & 0 & 0 & v_x \\ 0 & 1 & 0 & v_y \\ 0 & 0 & 1 & v_z \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} p_x \\ p_y \\ p_z \\ 1 \end{bmatrix} = \begin{bmatrix} p_x + v_x \\ p_y + v_y \\ p_z + v_z \\ 1 \end{bmatrix} = \mathbf{p} + \mathbf{v}$$

e.g. Transformations (camera, perspective, ...):
 for all vertices (x,y,z) in scene:

Obtain new vertex (x',y',z') = T(x,y,z)

Outline

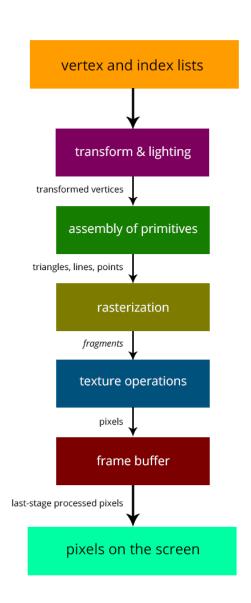
- Motivations
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GPUs – Brief History

- Fixed-function pipelines
 - Pre-set functions, limited options



http://gamedevelopment.tutsplus.com/articles/the-endof-fixed-function-rendering-pipelines-and-how-to-moveon--cms-21469 Source: Super Mario 64, by Nintendo



GPUs – Brief History

Shaders

- Could implement one's own functions!
- GLSL (C-like language)
- Could "sneak in" general-purpose programming!



GPUs – Brief History

- CUDA (Compute Unified Device Architecture)
 - General-purpose parallel computing platform for NVIDIA GPUs
- OpenCL (Open Computing Language)
 - General heterogenous computing framework

• ...

 Accessible as extensions to C! (and other languages...)

GPUs Today

 "General-purpose computing on GPUs" (GPGPU)

Demonstrations

Outline

- Motivations
- Brief history
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- "A simple solution"
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Add two arrays

$$-A[] + B[] -> C[]$$

• On the CPU:

```
float *C = malloc(N * sizeof(float));
for (int i = 0; i < N; i++)
    C[i] = A[i] + B[i];</pre>
```

– Operates sequentially... can we do better?

• On the CPU (multi-threaded, pseudocode):

```
(allocate memory for C)
Create # of threads equal to number of cores on processor
(around 2, 4, perhaps 8)
(Indicate portions of A, B, C to each thread...)
...
In each thread,
For (i from beginning region of thread)
        C[i] <- A[i] + B[i]
        //lots of waiting involved for memory reads, writes, ...
Wait for threads to synchronize...</pre>
```

Slightly faster – 2-8x (slightly more with other tricks)

 How many threads? How does performance scale?

- Context switching:
 - High penalty on the CPU
 - Low penalty on the GPU

• On the GPU:

```
(allocate memory for A, B, C on GPU)
Create the "kernel" - each thread will perform one (or a few)
additions
    Specify the following kernel operation:

For (all i's assigned to this thread)
        C[i] <- A[i] + B[i]

Start ~20000 (!) threads
Wait for threads to synchronize...</pre>
```

GPU: Strengths Revealed

- Parallelism / lots of cores
- Low context switch penalty!
 - We can "cover up" performance loss by creating more threads!



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GPU Computing: Step by Step

- Setup inputs on the host (CPU-accessible memory)
- Allocate memory for inputs on the GPU
- Allocate memory for outputs on the host
- Allocate memory for outputs on the GPU
- Copy inputs from host to GPU
- Start GPU kernel
- Copy output from GPU to host
- (Copying can be asynchronous)

The Kernel

- Our "parallel" function
- Simple implementation

```
__global__ void
cudaAddVectorsKernel(float * a, float * b, float * c) {
    //Decide an index somehow
    c[index] = a[index] + b[index];
}
```

Indexing

- Can get a block ID and thread ID within the block:
 - Unique thread ID!

```
__global__ void
cudaAddVectorsKernel(float * a, float * b, float * c) {
    unsigned int index = blockIdx.x * blockDim.x + threadIdx.x;
    c[index] = a[index] + b[index];
}
```

Calling the Kernel

```
void cudaAddVectors(const float* a, const float* b, float* c, size){
    //For now, suppose a and b were created before calling this function
   // dev a, dev b (for inputs) and dev c (for outputs) will be
   // arrays on the GPU.
    float * dev a;
    float * dev b;
    float * dev c;
   // Allocate memory on the GPU for our inputs:
    cudaMalloc((void **) &dev a, size*sizeof(float));
    cudaMemcpy(dev a, a, size*sizeof(float), cudaMemcpyHostToDevice);
    cudaMalloc((void **) &dev b, size*sizeof(float)); // and dev b
    cudaMemcpy(dev b, b, size*sizeof(float), cudaMemcpyHostToDevice);
   // Allocate memory on the GPu for our outputs:
    cudaMalloc((void **) &dev c, size*sizeof(float));
```

Calling the Kernel (2)

```
//At lowest, should be 32
//Limit of 512 (Tesla), 1024 (newer)
const unsigned int threadsPerBlock = 512;
//How many blocks we'll end up needing
const unsigned int blocks = ceil(size/float(threadsPerBlock));
//Call the kernel!
cudaAddVectorsKernel<<<blooks, threadsPerBlock>>>
    (dev a, dev b, dev c);
//Copy output from device to host (assume here that host memory
//for the output has been calculated)
cudaMemcpy(c, dev c, size*sizeof(float), cudaMemcpyDeviceToHost);
cudaFree(dev a);
cudaFree(dev b);
cudaFree(dev c);
```

Summary

- For many highly parallelizable problems...
 - GPU offers massive performance increase!

- Making difficult problems easy
- Putting impossible problems within reach

Outline

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This Course

- General topics:
 - GPU computing /parallelization
 - Audio, linear algebra, medical engineering, machine learning, finance, ...
 - CUDA (parallel computing platform)
 - Libraries, optimizations, etc
- Prerequisites:
 - C/C++ knowledge

Administrivia

- Course Instructors/TA's:
 - Kevin Yuh (kyuh@caltech.edu)
 - Eric Martin (emartin@caltech.edu)
- CS179: GPU Programming
 - Website: http://courses.cms.caltech.edu/cs179/
- Overseeing Instructor:
 - Al Barr (barr@cs.caltech.edu)
- Class time:
 - ANB 107, MWF 3:00 PM

Course Requirements

- Option 1:
 - Homework:
 - 7 assignments
 - Each worth 10% of grade
 - Due Wednesdays, 5 PM 3 PM (chg'd 4/3/2015)
 - Final project:
 - 3-week project
 - 30% of grade

Course Requirements

- Option 2:
 - Homework:
 - 5 assignments
 - Each worth 10% of grade
 - Due Wednesdays, 5 PM 3 PM (chg'd 4/3/2015)
 - Final project:
 - 5-week project
 - 50% of grade
 - Difference: Exchange sets 6,7 for more time on project

Projects

- Topic your choice!
- Project scale
 - 5-week projects: Significantly more extensive
- Solo or pairs
 - Expectations set accordingly
- Idea generation:
 - Keep eyes open!
 - Talk to us
 - We hope to bring guests!

Administrivia

- Collaboration policy:
 - Discuss ideas and strategies freely, but all code must be your own
 - "50 foot rule" (in spirit) don't consult your code when helping others with their code

Administrivia

- Office Hours: Located in ANB 104
 - Kevin: Mondays, 9-11 PM
 - Eric: Tuesdays, 7-9 PM
- Extensions on request
 - Talk to TAs

Machines

- Primary machines (multi-GPU, remote access): haru.caltech.edu
 - mako.caltech.edu (pending)
- E-mail me your preferred username!
- Change your password
 - Separately on each machine (once make is up)
 - Use passwd command

Machines

- Secondary (CMS) machines:
 - mx.cms.caltech.edu
 - minuteman.cms.caltech.edu
- Use your CMS login
- Not all assignments work here!

Machines

- Alternative: Use your own! (Harder):
 - Must have an NVIDIA CUDA-capable GPU
 - Virtual machines won't work!
 - Exception: Machines with I/O MMU virtualization and certain GPUs
 - Special requirements for:
 - Hybrid/optimus systems
 - Mac/OS X
- Setup is difficult! (But we have some instructions)
- May need to modify assignment makefiles

Final remarks for the day...



"Three RAAF FA-18 Hornets in formation after refueling" by U.S. Air Force photo by Senior Airman Matthew Bruch -

Welcome to the course!