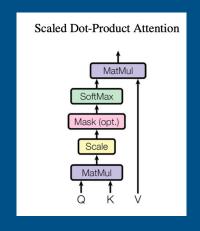
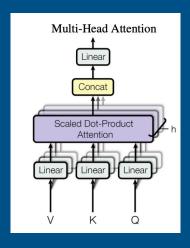
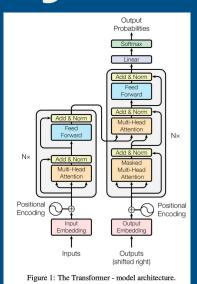
is all you need







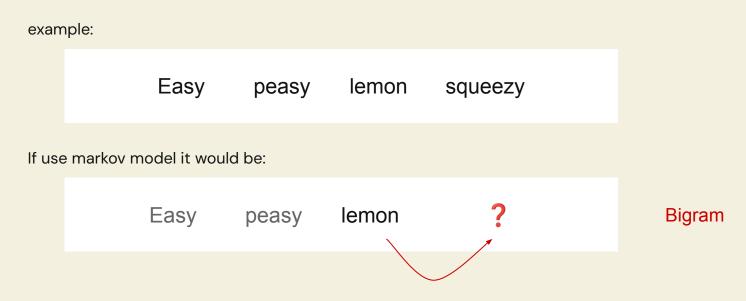
- <sup>1</sup> Motivation
- 2. Attention as context summary
- 3. How to calculate Attention?
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#### <sup>1</sup> Motivation

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# Motivation: review Markov property

- Markov Property: given the present, the future does not depend on the past.
- ? Is it sufficient in language modeling:



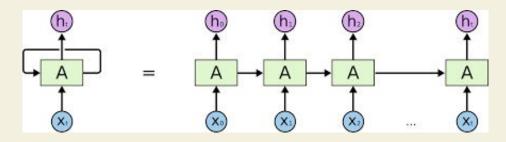
#### **Motivation**



# **Motivation: training**

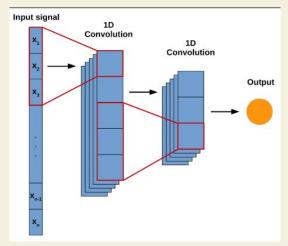
We have tried different methods to achieve it:

RNN (Recurrent NN)



✓ Long Dependency Xnot-Parallelizable at all

CNN (Convolutional NN)



- Parallelizable
- weak Long Dependency unless many layers

# **Motivation: training**

#### So here is the question:

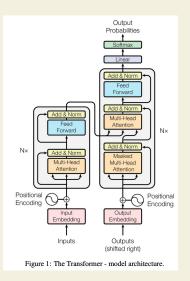


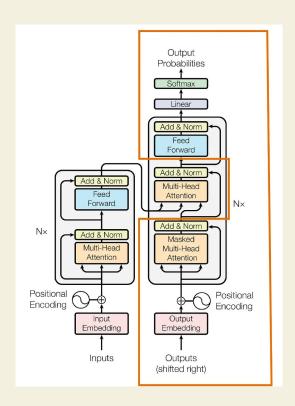
: Long Dependency(RNN) or Parallelizable(CNN)?

That is the question. Whether 'tis nobler in the mind to suffer......



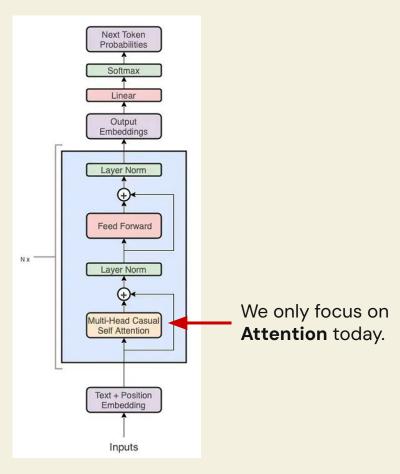
: Stop, enough. Here is the **Transformer**. You have both now.





abstract the right part

Encoder(left) + Decoder(right)



Decoder Only(e.g. GPT-like)

### **Motivation**



- <sup>1</sup> Motivation
- <sup>2.</sup> Attention as context summary
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Use ChatGPT to generate the example, it should looks like:

Easy

- Step 1: Understand what happened under the hood in Inference
  - Auto-regression: generate one token at a time.
  - Next token prediction: predict the next token based on all tokens before it.

Step 1: Understand what happened under the hood — in Inference

🤔 Step 2: So how should we achieve it? — in training

We train it to mimic that behavior:

- Train it to predict the next token, but only allow it to look back
- Calculate loss, back propagation, etc......

we call it "Causal" or "Masked"

we are all familiar with this, ignore

Step 1: Understand what happened under the hood — in Inference

Step 2: So how should we achieve it? — in Training

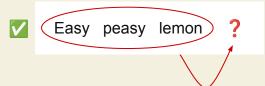
We train it to mimic that behavior:

• Train it to **predict the next token**, but only allow it to **look back** 

we call it "Causal" or "Masked"

Use matrix to visualize it: "Easy peasy lemon squeezy"---training data, what we've already knew

```
"Easy" [Easy, ?, X],-----see: Easy----->peasy
"peasy" [Easy, peasy, ?, X],-----see: Easy, peasy---->lemon
"lemon" [Easy, peasy, lemon, ?],-----see: Easy, peasy, lemon---->squeezy
```



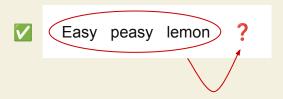
Step 1: Understand what happened under the hood — in Inference

```
Step 2: So how should we achieve it? — in Training
```

```
"Easy" [Easy, ?, X, ],-----see: Easy----->peasy

"peasy" [Easy, peasy, ?, X],-----see: Easy, peasy---->lemon

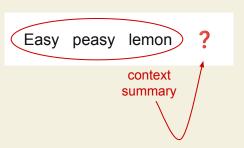
"lemon" [Easy, peasy, lemon, ?],-----see: Easy, peasy, lemon---->squeezy
```

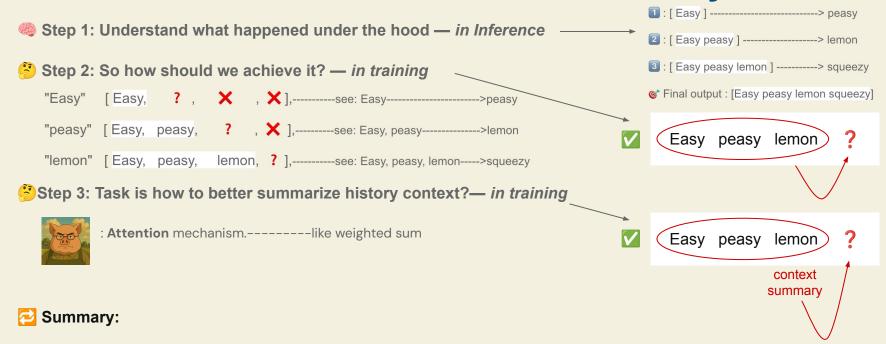


#### Step 3: Task is how to better summarize history context?— in Training



: All tokens are equal, but...but some tokens are **more equal** than others. Yes, I'm saying **Attention** mechanism.-----like weighted sum





Inference defines the goal → Training mimics the goal → **Attention** as a context summary shows the way!!

- <sup>1</sup> Motivation
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$$\operatorname{Attention}(Q, K, V) = \operatorname{softmax}(\frac{QK^T}{\sqrt{d_k}})V$$
weight

Every token has its own **q**, **k**, **v**:

or?" q: query-----> "What am I looking for?"

**s**k: key---->"A brief intro about me"

v: value---->"The real info of me"

|    | Easy | peasy | lemon | squeezy |
|----|------|-------|-------|---------|
| q: | q_0  | q_1   | q_2   | q_3     |
| k: | k_0  | k_1   | k_2   | k_3     |
| v: | v_0  | v_1   | v_2   | v_3     |

q\*k: "How much does your info match my need?"

softmax(q\_0\*k\_0, q\_1\*k\_1, ..., q\_n\*k\_n): attention weight

softmax(...)\*v: context summary

Q, K, V are matrix of q, k, v, for calculation efficiency. And divided by sqrt(d\_k) is for scaling, ensuring training stable.

Every token has its own **q**, **k**, **v**:

or: query-----> "What am I looking for?"

k: key----->"A brief intro about me"

v: value---->"The real info of me"

q\*k: "How much does your info match my need?"

**softmax(**q\_0\*k\_0, q\_1\*k\_1, ..., q\_n\*k\_n**)**: attention weight

softmax(...)\*v: context summary

#### 1**q\*k**:

| $\operatorname{Attention}(Q,K,V) =$ | $\operatorname{softmax}(rac{QK^T}{\sqrt{d_k}})V$ |
|-------------------------------------|---|
|                                     | weight  |

|    | Easy | peasy | lemon | squeezy |
|----|------|-------|-------|---------|
| q: | q_0  | q_1   | q_2   | q_3     |
| k: | k_0  | k_1   | k_2   | k_3     |
| V: | v_0  | v_1   | v_2   | v_3     |

| q \ k        | Easy(k_0) | peasy(k_1) | lemon(k_2) | squeezy(k_3) |
|--------------|-----------|------------|------------|--------------|
| Easy(q_0)    | q_0*k_0   | ×          | ×          | ×            |
| peasy(q_1)   | q_1*k_0   | q_1*k_1    | ×          | ×            |
| lemon(q_2)   | q_2*k_0   | q_2*k_1    | q_2*k_2    | ×            |
| squeezy(q_3) | q_3*k_0   | q_3*k_1    | q_2*k_2    | q_3*k_3      |
|              |           |            |            |              |

Every token has its own q, k, v:

g: query-----> "What am I looking for?"

k: key---->"A brief intro about me"

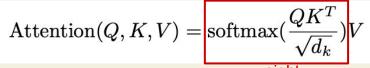
v: value---->"The real info of me"

q\*k: "How much does your info match my need?"

**softmax**(q\_0\*k\_0, q\_1\*k\_1, ..., q\_n\*k\_n): attention weight

softmax(...)\*v: context summary

| softmax(q*k), it mig | ght be:   |            | _          |              | _ |
|----------------------|-----------|------------|------------|--------------|---|
| q \ k                | Easy(k_0) | peasy(k_1) | lemon(k_2) | squeezy(k_3) |   |
| Easy(q_0)            | 1.0       | ×          | ×          | ×            |   |
| peasy(q_1)           | 0.4       | 0.6        | ×          | ×            |   |
| lemon(q_2)           | 0.3       | 0.2        | 0.5        | ×            |   |
| squeezy(q_3)         | 0.2       | 0.1        | 0.3        | 0.4          |   |



| weight |  |  |
|--------|--|--|
|        |  |  |
|        |  |  |

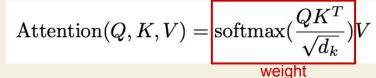
|    | Easy | peasy | lemon | squeezy |
|----|------|-------|-------|---------|
| q: | q_0  | q_1   | q_2   | q_3     |
| k: | k_0  | k_1   | k_2   | k_3     |
| v: | v_0  | v_1   | v_2   | v_3     |

Every token has its own **q**, **k**, **v**:

q: query-----> "What am I looking for?"

k: key-----> "A brief intro about me"

v: value-----> "The real info of me" **q\*k**: "How much does your info match my need?" **softmax**(q\_0\*k\_0, q\_1\*k\_1, ..., q\_n\*k\_n): attention weight



Easy lemon peasy squeezy q 3 q\_0 q\_1 q\_2 k 0 k 1 k 2 k 3 v 2 v 3 v 0 v 1

#### 3softmax(q\*k)\*v, it might be:

**softmax(...)\*v**: context summary

| q \ k        | Easy(k_0) |   | peasy(k_1 | l <b>)</b> | lemon(k_2 | 2) | squeezy(k_3) |  |
|--------------|-----------|---|-----------|------------|-----------|----|--------------|--|
| Easy(q_0)    | 1.0*v_0   |   | ×         |            | ×         |    | ×            |  |
| peasy(q_1)   | 0.4*v_0   | + | 0.6*v_1   |            | ×         |    | ×            |  |
| lemon(q_2)   | 0.3*v_0   | + | 0.2*v_1   | +          | 0.5*v_2   |    | ×            |  |
| squeezy(q_3) | 0.2*v_0   | + | 0.1*v_1   | +          | 0.3*v_2   | +  | 0.4*v_3      |  |

 $Attention(Q, K, V) = softmax(\frac{QK^T}{\sqrt{d_k}})V$ 

3softmax(q\*k)\*v, it might be:

| q \ k        | Easy(k_0) |   | peasy(k_1 | ) | lemon(k_2 | ) | squeezy(k_3) |
|--------------|-----------|---|-----------|---|-----------|---|--------------|
| Easy(q_0)    | 1.0*v_0   |   | X         |   | ×         |   | ×            |
| peasy(q_1)   | 0.4*v_0   | + | 0.6*v_1   |   | ×         |   | ×            |
| lemon(q_2)   | 0.3*v_0   | + | 0.2*v_1   | + | 0.5*v_2   |   | ×            |
| squeezy(q_3) | 0.2*v_0   | + | 0.1*v_1   | + | 0.3*v_2   | + | 0.4*v_3      |
|              |           |   |           |   |           |   |              |

What we just did:

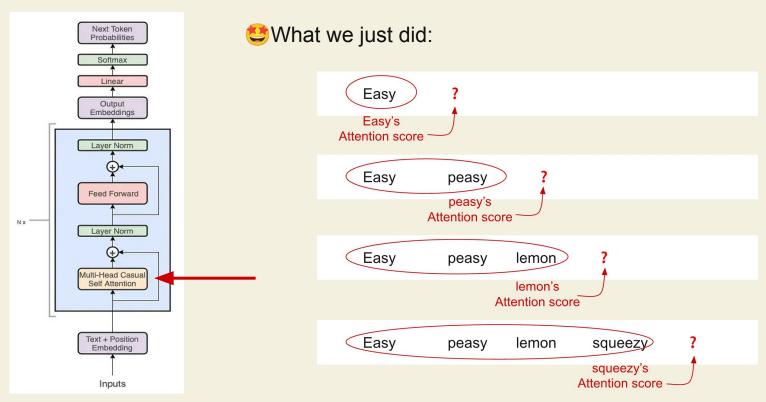


What we just did:

Transformer(Attention)



### To be continued...



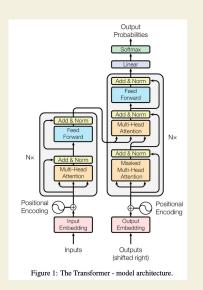
Decoder Only(e.g. GPT-like)

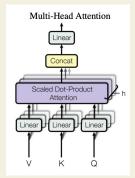
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# Further map

- Where does q, k, v come from ?
- Why we scale by sqrt(d\_k) exactly ?
- 🙋 What is Multi-Head Attention <mark>?</mark>
- What are the rest of the Transformer?

Attention $(Q, K, V) = \text{softmax}(\frac{QK^T}{\sqrt{d_k}})V$ 





# Further map

Why we scale by sqrt(d\_k) exactly ?
What is Multi-Head Attention ?
What are the rest of Transformer ?



: If you want it, you can have it !!

I left all the secrets of Attention..... in this following Map <a></a>:::

- **Deep Dive into LLMs like ChatGPT.** By Andrej Karpathy
- **Let's build GPT: from scratch, in code, spelled out.** By Andrej Karpathy
- **Attention Is All You Need**, Ashish Vaswani et al., 2017, v7

- <sup>1</sup> Motivation
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# Conclusion

**Attention as Context Summary** 

is all you need





: It is only with the **Attention** that one can see rightly.

# The End



# Thank U