

JINGPEI LU

9192 Regents Road, La Jolla, CA 92037
(858)766-8161 ◇ lujingpei557@gmail.com ◇ jingpeilu.github.io

EDUCATION

M.S. in Electrical and Computer Engineering University of California San Diego, CA, USA Area of focus: Intelligent System, Robotics and Control	September 2018 - June 2020 Major GPA: 3.67 / 4.0
B.S. in Electrical and Computer Engineering University of California San Diego, CA, USA Area of focus: Machine Learning	September 2014 - June 2018 Major GPA: 3.71 / 4.0

RESEARCH EXPERIENCE

UCSD Advanced Robotics and Control Lab <i>Research Assistant</i> <i>Advisor: Michael C. Yip</i>	April 2019 - Present
<ul style="list-style-type: none">· Conduct research on surgical perception for automating robotics control· Collaborate with SRI International on developing the semi-autonomous telesurgery system· Proposed a novel surgical perception framework for surgical robotic control and successfully experimented on the da Vinci Surgical® System for tissue manipulation tasks	
The Statistical Visual Computing Laboratory at UCSD <i>Research Assistant</i> <i>Advisor: Nuno Vasconcelos</i>	January 2018 - September 2018
<ul style="list-style-type: none">· Developed a content-based image retrieval system for plankton images using a deep convolutional neural network which assisted biological oceanographers in researching and labeling the plankton images· Researched on different machine learning and deep learning methods, which accelerated the searching process and improved the precision of the baseline retrieval system by about 30%· Presented our work on UC San Diego's Summer Research Conference (SRC 2018)	

PUBLICATIONS

J. Lu, A. Jayakumari, F. Richter, Y. Li, and M. C. Yip, "SuPer Deep: A Surgical Perception Framework for Robotic Tissue Manipulation using Deep Learning for Feature Extraction," under review, 2020.

Y. Li, F. Richter, **J. Lu**, E. K. Funk, R. K. Orosco, J. Zhu, and M. C. Yip, "SuPer: A Surgical Perception Framework for Endoscopic Tissue Manipulation with Surgical Robotics," in *IEEE Robotics and Automation Letters*, vol. 5, no. 2, pp. 2294-2301, April 2020. (RA-L with ICRA presentation)

PROFESSIONAL EXPERIENCE

Educational Vision Technologies, Inc. <i>Machine Learning Lead</i>	July 2019 - December 2019 <i>La Jolla, CA, USA</i>
<ul style="list-style-type: none">· Lead the development of Machine Learning and Computer Vision applications for automating video content processing· Developed the automated slides video segmentation framework, which achieves 97% accuracy on recall and 74% accuracy on precision comparing to human labeling· Built the testing frameworks to ensure the product functions properly and meets the business needs	

Wangsu Science & Technology Co., Ltd.

Technical Support Engineer

July 2017 - September 2017

Xiamen, China

- Assisted the technical support team in diagnosing and resolving the system issues and creating standard procedures for proper escalation of unresolved issues to the appropriate internal teams
- Managed the company's recruiting training program

TEACHING EXPERIENCE

University of California, San Diego

January 2019 - December 2019

Teaching Assistant, Jacob School of Engineering

Course: Introduction to Digital Design (90.9% recommendation rate)

TECHNICAL SKILLS

Programming Python, C/C++, Matlab, Cuda

Tools Tensorflow, Pytorch, ROS, Git, Linux, Docker, L^AT_EX

Language Proficient in English and Chinese

GRADUATE COURSES

Neural Networks for Pattern Recognition; Robot Reinforcement Learning; Planning and Learning in Robotics; Sensing and Estimation in Robotics; Computer Vision (I, II, III); GPU Programming; Stochastic Processes and Dynamic System; Linear Algebra and Application; Statistical Learning; Digital Image Processing

SELECTED PROJECTS

Autonomous R/C Vehicle

- Built a remote control vehicle that can autonomously run on an outdoor scaled track from scratch
- Developed the traffic signs recognition functionality and speeded up the video processing efficiency **three times** using the multi-threaded approach

Drone Integration for RF Scanner Payload

- Integrated an RF scanning payload with a drone (DJI Matrice 100) to automate the processes of detecting wireless signal's strength in open area
- Developed a mobile app to record the signal strength data and generate the heatmap which can visualize the data better

EXTRA-CIRRICULAR

IEEE Quarterly Project Award

Certificate of Violin National Tenth Grade

UC San Diego Intramural Soccer Competition

Deep Learning Nanodegree Program at Udacity