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Section: Image Processing

Project: Final - Hough Transform

Due Date: Dec 13th

## **Source Code:**

```
#include <fstream>
#include <iostream>
using namespace std;
namespace Util{
    static int** getArray(int rows, int cols){
        int** array = new int*[rows];
        for(int i = 0; i < rows; i++){
            array[i] = new int[cols];
            for(int j = 0; j < cols; j++){
                array[i][j] = 0;
            }
        }
        return array;
    }
    static int findMax(int** array, int rows, int cols){
        int max = array[0][0];
        for(int i = 0; i < rows; i++){
            for(int j = 0; j < cols; j++){
                if(array[i][j] > max){
                    max = array[i][j];
                }
            }
        }
```

```
return max;
    }
    static int findMin(int** array, int rows, int cols){
        int min = array[0][0];
        for(int i = 0; i < rows; i++){</pre>
            for(int j = 0; j < cols; j++){
                if(array[i][j] < min){</pre>
                    min = array[i][j];
                }
            }
        }
        return min;
    }
}
class HoughTransform{
public:
    int numRows,
        numCols,
        minVal,
        maxVal,
        houghDist,
        houghAngle;
    int** imgAry;
    int** polarHoughAry;
    int angleInDegree,
        offset;
    double angleInRadian,
            PI;
    HoughTransform(ifstream& inFile){
        inFile >> numRows >> numCols >> minVal >> maxVal;
        int diagonal = sqrt(numRows * numRows + numCols * numCols);
```

```
offset = diagonal;
    imgAry = Util::getArray(numRows, numCols);
    PI = 3.14159265;
    houghDist = 2 * diagonal;
    houghAngle = 180;
    polarHoughAry = Util::getArray(houghDist, houghAngle);
    loadImage(inFile);
}
void loadImage(ifstream& inFile){
    int cur = 0;
    for(int i = 0; i < numRows; i++){
        for(int j = 0; j < numCols; j++){
            inFile >> cur;
            imgAry[i][j] = cur;
        }
    }
}
void buildHoughSpace(){
    double angleInR;
    int dist;
    for(int i = 0; i < numRows; i++){
        for(int j = 0; j < numCols; j++){</pre>
            if(imgAry[i][j] == 0) continue;
            for(int angleInD = 0; angleInD < 180; angleInD++){</pre>
                angleInR = (angleInD / 180.00) * PI;
                dist = (int) polarDist(i, j, angleInR);
                polarHoughAry[dist][angleInD]++;
            }
        }
    }
}
```

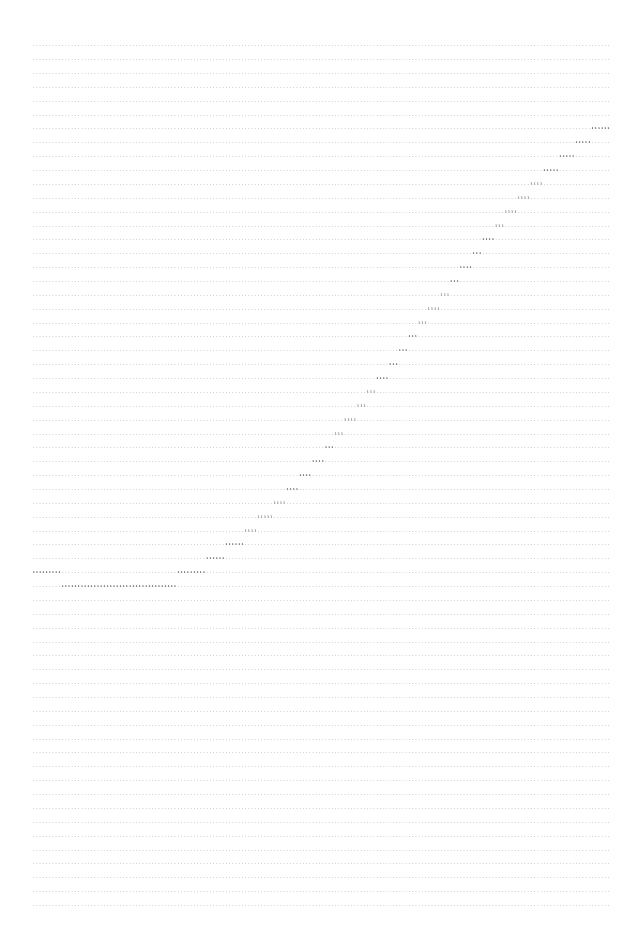
```
double polarDist(int i, int j, double angleInR){
        return (i * cos(angleInR) + j * sin(angleInR) + offset);
    }
    void reformatPrettyPrint(ofstream& outFile){
        int houghMinVal = Util::findMin(polarHoughAry, houghDist, houghAngle),
            houghMaxVal = Util::findMax(polarHoughAry, houghDist, houghAngle);
        outFile << houghDist << " " << houghAngle << " " << houghMinVal << " " << houghMaxVal <</pre>
'\n';
        string str;
        int curWidth,
            pixelWidth = to_string(houghMaxVal).length();
        for(int r = 0; r < houghDist; r++){</pre>
            for(int c = 0; c < houghAngle; c++){</pre>
                outFile << (polarHoughAry[r][c] == 0 ? "." : to_string(polarHoughAry[r][c]));</pre>
                 str = to_string(polarHoughAry[r][c]);
                curWidth = str.length();
                while(curWidth < pixelWidth){</pre>
                     outFile<<' ';
                     curWidth++;
                 }
                outFile<<' ';
            }
            outFile << '\n';</pre>
        }
    }
};
int main(int argc, const char* argv[]){
    ifstream inFile(argv[1]);
    ofstream outFile(argv[2]);
    HoughTransform houghTransform(inFile);
```

```
houghTransform.buildHoughSpace();
houghTransform.reformatPrettyPrint(outFile);
inFile.close();
outFile.close();
}
```

## **Program Output**

## Data 1 Output

90 180 0 1



Data 2 Output	
-	
90 180 0 2	
1111	

1111			1111	111221	11	111	
1111122	2211	111122	12211111	11			
	112211111111111111111111111111111						
	1111						
		111111		111121	1		
	11222						
			11	111			
	1111						
		111.	11111				
	111111						
	1111						
11111	1111	11					
D-4- 0 C	\						
Data 3 C	Jutput						
00 100 0	24						
90 180 0	) 21						

