

# Lecture 5

## GLM computation and data example



# Today's topics:

- GLM computation
- Example: building a GLM
- Reading: Agresti Chapters 4.5, 4.7

# GLM computation

- Only discuss the case of  $a(\phi) = 1$  to simplify notation
- If  $a(\phi)$  is not a constant, one can get  $\hat{\beta}$  from the score equations first, and then estimate  $\phi$  from MLE with  $\hat{\beta}$  plugged in

Score equation:

$$\dot{L}(\beta) = X^T DV^{-1}(y - \mu) = 0$$

where

$$L(\beta) = \sum [y_i \theta_i - b(\theta_i)] + const.$$

- Newton's method
- Fisher scoring method
- Iteratively reweighted least squares (IRLS): intuitive explanation for Fisher scoring

# Newton's method

Second-order approximation of  $L(\beta)$

$$L(\beta) \approx L(\beta^{(t)}) + \dot{L}(\beta^{(t)})^T(\beta - \beta^{(t)}) + \frac{1}{2}(\beta - \beta^{(t)})^T \ddot{L}(\beta^{(t)})(\beta - \beta^{(t)})$$

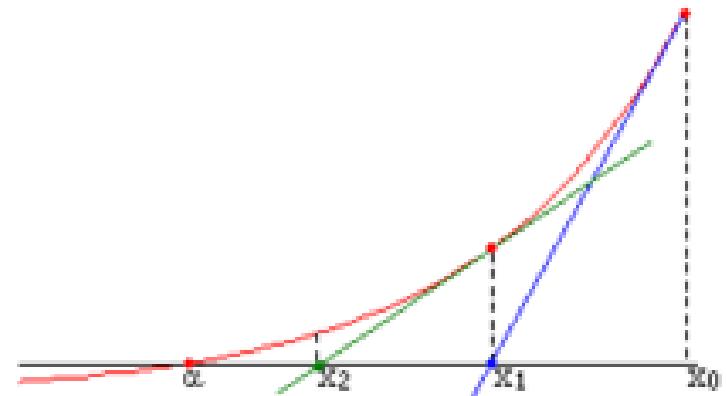
at  $t$ th iteration. If  $\ddot{L}(\beta^{(t)}) \preceq 0$ , then maximizing the second-order approximation is equivalent to solving

$$\dot{L}(\beta) \approx \dot{L}(\beta^{(t)}) + \ddot{L}(\beta^{(t)})(\beta - \beta^{(t)}) = 0$$

We have

$$\beta^{(t+1)} = \beta^{(t)} - \ddot{L}(\beta^{(t)})^{-1} \dot{L}(\beta^{(t)})$$

- Root finding algorithm for solving  $\dot{L}(\hat{\beta}) = 0$ 
  - Local linear approximation of  $\dot{L}(\hat{\beta})$

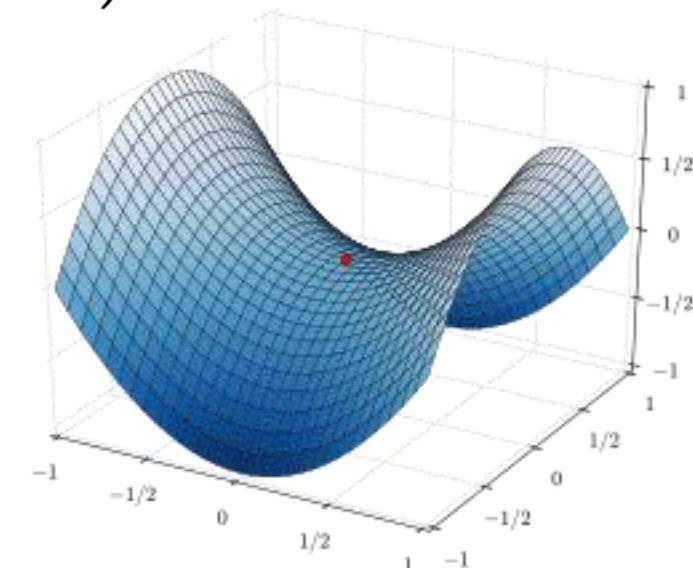


# Newton's method

- Newton's method is a general algorithm for optimizing twice-differentiable functions.
- Generally, it converges to the global maximum if  $L(\beta)$  is strongly concave
  - If  $g(\cdot)$  is the canonical link, then  $L(\beta)$  is concave in  $\beta$

$$-\ddot{L}(\beta^{(t)}) = X^T W^{(t)} X = \frac{1}{a(\phi)^2} X^T V^{(t)} X = -\mathbb{E} (\ddot{L}(\beta^{(t)})) \succeq 0$$

- If  $g(\cdot)$  is a general link, then  $L(\beta)$  is NOT guaranteed to be concave in  $\beta$
- If  $-\ddot{L}(\beta^{(t)})$  is not non-negative, then step  $t$  does not maximize the quadratic approximation (may find a saddle point) and Newton's method may be unstable.



# Fisher scoring method

- In lecture 2, we showed that  $-\mathbb{E}(\ddot{L}(\beta)) \geq 0$  for any  $\beta$ .
- Instead of using the Hessian  $\ddot{L}(\beta^{(t)})$  itself in the second order approximation, we use its expectation

$$J^{(t)} = \mathbb{E}(\ddot{L}(\beta^{(t)})) = -X^T W^{(t)} X$$

Each iteration becomes:

$$\mathcal{J}^{(t)} \quad \boxed{\beta^{(t+1)} = \beta^{(t)} - \left( \cancel{J^{(t)}} \right)^{-1} \dot{L}(\beta^{(t)})}$$

~~$J^{(t)}$~~

$$\begin{aligned} J^{(t)} &= -X^T W^{(t)} X \\ \dot{L}(\beta^{(t)}) &= X^T \cancel{V^{(t)}} (y - \mu^{(t)}) \end{aligned}$$

- For the canonical link, Fisher scoring = Newton's method
- For a general link, Fisher scoring works better in practice

# Iteratively reweighted least squares (IRLS)

- We can make a connection between the optimization for GLM and weighted least squares estimation.
- Think of GLM approximately fitting the linear model with transformation on outcome:

$$g(y_i) \sim X_i^T \beta + e_i$$

- $g(y_i)$  may not be computable
- $e_i$  should have different variances
- Assume that after step  $t$ , we already have an estimate of  $\mu = (\mu_1, \dots, \mu_n)$  as  $\mu^{(t)} = (\mu_1^{(t)}, \dots, \mu_n^{(t)})$
- Perform Taylor expansion of  $g(y_i)$  at  $\mu_i^{(t)}$ :  
$$g(y_i) \approx g(\mu_i^{(t)}) + g'(\mu_i^{(t)})(y_i - \mu_i^{(t)}) = X_i^T \beta^{(t)} + g'(\mu_i^{(t)})(y_i - \mu_i^{(t)})$$
- Define a “temporary response”:  $Z_i^{(t)} = X_i^T \beta^{(t)} + g'(\mu_i^{(t)})(y_i - \mu_i^{(t)})$
- Then  $\text{Var}[Z_i^{(t)}] = g'(\mu_i^{(t)})^2 \text{Var}[y_i] \approx \frac{V_{ii}^{(t)}}{(D_{ii}^{(t)})^2} = (W_{ii}^{(t)})^{-1}$
- Fit the linear regression  $Z_i^{(t)} \sim X_i^T \beta + e_i$  with weighted least square

# Iteratively reweighted least squares (IRLS)

- At the  $t+1$  th iteration, we solve the weighted least square

$$X^T W^{(t)} (z^{(t)} - X\beta) = 0 \quad \Leftrightarrow \quad \beta^{(t+1)} = (X^T W^{(t)} X)^{-1} X^T W^{(t)} z^{(t)}$$

which can be considered as a weighted linear regression with observations  $z_i^{(t)}$  and weight  $w_i$  for each sample  $i$ .

- IRLS is equivalent to Fisher scoring. The  $t$ th step of Fisher scoring satisfy

$$\begin{aligned} (X^T W^{(t)} X) \beta^{(t+1)} &= X^T W^{(t)} X \beta^{(t)} + X^T D^{(t)} (V^{(t)})^{-1} (y - \mu^{(t)}) \\ &= X^T W^{(t)} \left[ X \beta^{(t)} + (D^{(t)})^{-1} (y - \mu^{(t)}) \right] \\ &= X^T W^{(t)} z^{(t)} \end{aligned}$$

- Weight matrix  $W^{(t)} \approx \text{Var}(z^{(t)})^{-1}$

# Example: Building a GLM

- Check Example2 R notebook