

# Topics in Causal Inference

STAT41530

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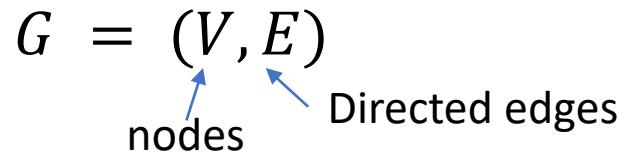
# Lecture 3

Topic: causal directed acyclic graph (DAG)

- Markov factorization
- Connection with the potential outcome framework
- D-separation and conditional independence

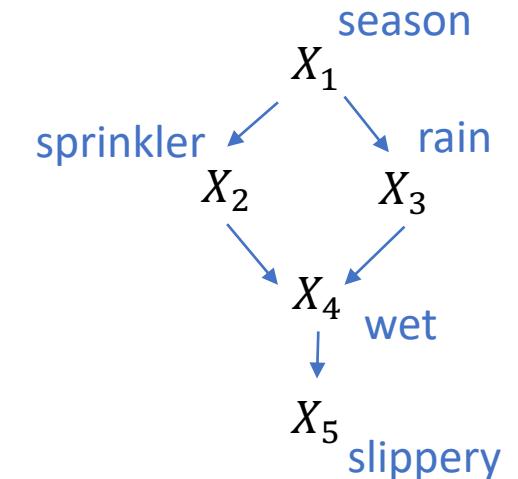
# Directed Acyclic Graphs (DAGs)

- DAG: a **directed graph** with no cycles



$A \rightarrow Y$   
parent      descendant

- Bayesian network: nodes are random variables



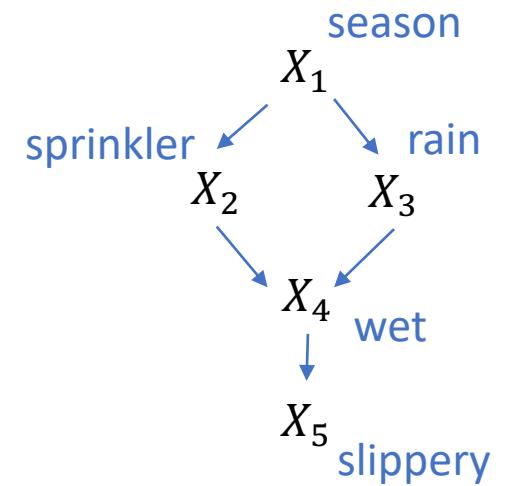
$$\mathbb{P}[V] = \mathbb{P}[X_1, X_2, \dots, X_J] = \prod_{j=1}^J \mathbb{P}[X_j \mid X_1, \dots, X_{j-1}]$$

# Markov Factorization

- Markov assumption:

$$\mathbb{P}[V] = \prod_{j=1}^J \mathbb{P}[X_j \mid PA_j]$$

$PA_j$ : parents of  $X_j$  (nodes that have direct arrows to  $X_j$ )



- In the example, the Markov assumption assume that

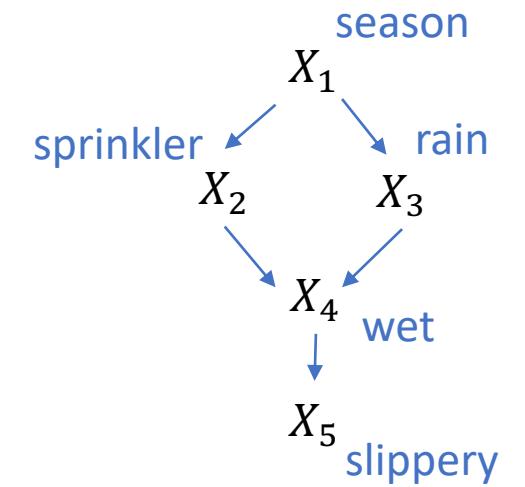
$$\mathbb{P}[X_1, X_2, X_3, X_4, X_5] = \mathbb{P}[X_1] \mathbb{P}[X_2 \mid X_1] \mathbb{P}[X_3 \mid X_1] \mathbb{P}[X_4 \mid X_2, X_3] \mathbb{P}[X_5 \mid X_4]$$

# Causal DAGs (Pearl 1995, Biometrika)

A DAG is a causal DAG if

- $X_j$  not a parent of  $X_m \Leftrightarrow$  absence of a direct causal effect
- The DAG satisfies Markov assumption

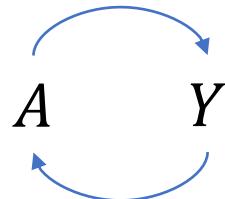
$$\mathbb{P}[V] = \prod_{j=1}^J \mathbb{P}[X_j \mid PA_j]$$



Conditional on its direct causes, any variable on the DAG is independent of any other variable for which it is not a cause

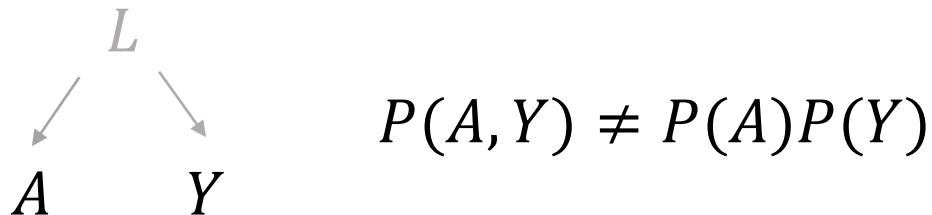
# What are assumed?

- No directed circle:



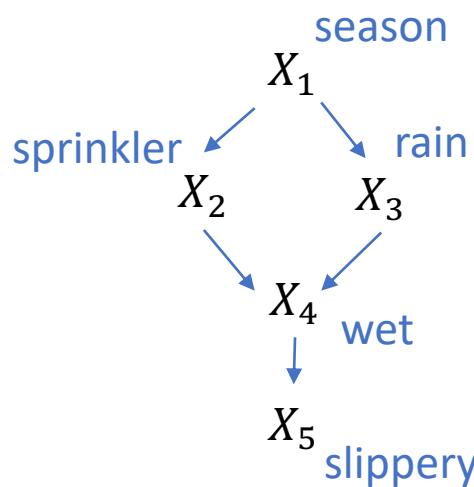
A can not cause itself,  $P(A, Y) \neq P(A|Y)P(Y|A)$

- The common causes of any pair of variables in the graph must be in the graph



- SUTVA: consistency and no interference
- Intervention can be done on any node that has an arrow out

# Connection with the potential outcome framework

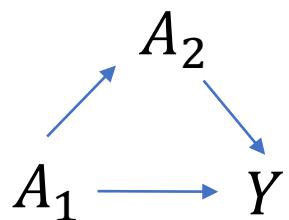


For each  $X_j$ , assume existence of random error  $E_{X_j} \perp PA_j$  and deterministic unknown function  $f_j$  for each node  $j$

$$X_j(pa_j) = f_j(pa_j, E_{X_j})$$

Potential outcomes  
for joint  
intervention on  
parents  $PA_j$

Non-parametric  
structure equation



Potential outcomes:

$$A_2(a_1) = f_2(a_1, E_{A_2})$$

$$Y(a_1, a_2) = f(a_1, a_2, E_Y)$$

$$Y(a_1) = f(a_1, A_2(a_1), E_Y)$$

Observed outcome:

$$Y = f(A_1, A_2, E_Y)$$

# Structural equations and the Markov assumption

Structural equations  $X_j(pa_j) = f_j(pa_j, E_{X_j})$

+  $\{E_{X_j}, j = 1, 2, \dots, J\}$  mutually independent

$\Rightarrow$

$$P(V) = \prod_{j=1}^J P[X_j \mid PA_j]$$

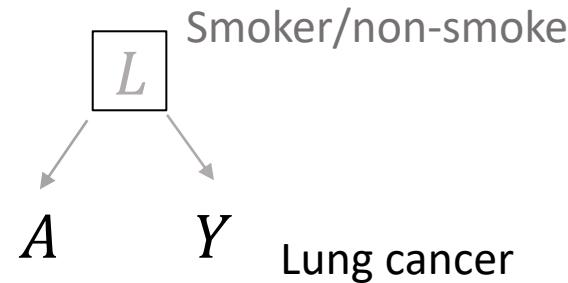
Proof idea:

- 1) (topological ordering) There exists an order so that for each  $j$ ,  $PA_j \subseteq \{X_1, X_2, \dots, X_{j-1}\}$  (proof by induction on  $J$ )
- 2) As  $\{E_{X_j}, j = 1, 2, \dots, J\}$  are mutually independent,  $E_{X_j} \perp S$  if set  $S$  do not contain  $X_j$ 's descendent
- 3)  $X_j = f_j(PA_j, E_{X_j}) \perp \{X_1, \dots, X_{j-1}\} / PA_j \mid PA_j$

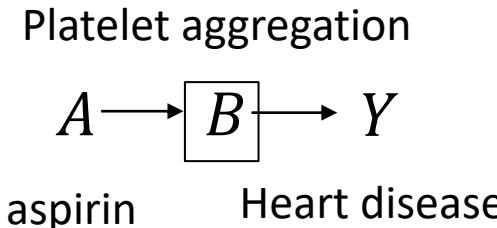
$$\mathbb{P}[V] = \mathbb{P}[X_1, X_2, \dots, X_J] = \prod_{j=1}^J \mathbb{P}[X_j \mid X_1, \dots, X_{j-1}] = \prod_{j=1}^J \mathbb{P}[X_j \mid PA_j]$$

# Causal DAG and marginal / conditional independence

A few examples:



$A \pm Y \quad A \perp Y | L$

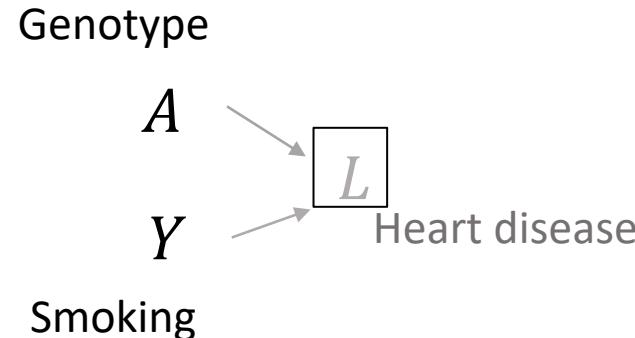


$A \pm Y \quad A \perp Y | B$

$B$  is a mediator

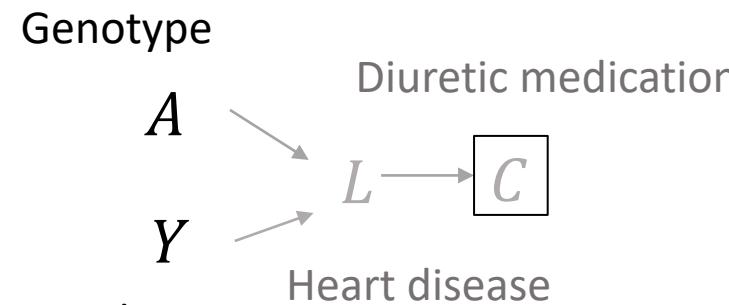
Carrying a lighter

$A \pm Y \quad A \perp Y | L$



$A \perp Y \quad A \pm Y | L$

$L$  is a Collider



$A \perp Y \quad A \pm Y | C$

$C$  is a consequence of the Collider

# D-separation

**Path:** A path between two nodes  $X_1$  and  $X_2$  is a route that connects  $X_1$  and  $X_2$  by a sequence of edges such that the route visits no variable more than once

**A path is blocked or open according to the following rules: (fine point 6.1)**

- If there are no variables being conditioned on, a path is blocked if and only if two arrowheads on the path collide at some node on the path.

$L \rightarrow A \rightarrow Y$ : open     $A \rightarrow L \leftarrow Y$ : blocked

- Any path that contains a non-collider that has been conditioned on is blocked  
 $L \rightarrow A \rightarrow Y$  blocked conditioning on  $A$

- A collider that has been conditioned on does not block a path  
 $A \rightarrow L \leftarrow Y$  open conditioning on  $L$

- A collider that has a descendant that has been conditioned on does not block a path

Two variables (nodes) are d-separated if all path between them are blocked

# D-separation

Let  $X, Y, Z$  be disjoint sets in a DAG  $G$ .

$X$  and  $Y$  are **d-separated by  $Z$**  ( $Z$  can be empty) if and only if  $Z$  blocks every path from a node in  $X$  to a node in  $Y$

$$(X \perp\!\!\!\perp Y \mid Z)_G$$

- D-separation is a purely graphical concept
- Conditional independence is a probabilistic property

# D-separation and conditional independence

D-separation  $\Rightarrow$  conditional independence (Pearl 1988)

The Markov assumption implies

$$(X \perp\!\!\!\perp Y | Z)_G \Rightarrow X \perp Y | Z$$

$$X \perp Y | Z \Rightarrow (X \perp\!\!\!\perp Y | Z)_G$$

Faithfulness assumption:

$$X \perp Y | Z \Rightarrow (X \perp\!\!\!\perp Y | Z)_G$$

# Examples of unfaithfulness

## Example 1:

$$\begin{pmatrix} Y(0) \\ Y(1) \end{pmatrix} \sim \mathcal{N} \left( \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 & \rho \\ \rho & 1 \end{pmatrix} \right)$$

Assume  $A \perp Y(a)$ , then

$$Y \mid A = 0 \sim \mathcal{N}(0, 1), \quad Y \mid A = 1 \sim \mathcal{N}(0, 1)$$

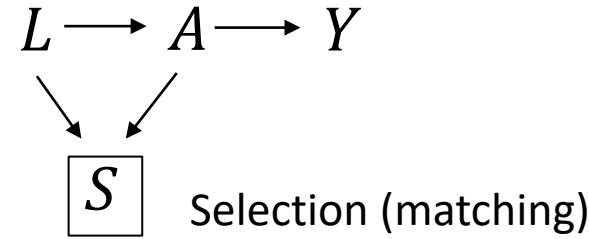
So  $Y \perp A$

On the other hand,  $A$  has a causal effect on  $Y$

so  $(A \not\perp\!\!\!\perp Y)_G$

Individual causal effects can cancel out

## Example 2:



- After matching  $A \perp L \mid S$  by design
- $(A \perp\!\!\!\perp L \mid S)_G$  is not true as shown on DAG

Two paths cancel out