# CS 359, Spring 2019

# Project 1: Optimizing the Performance of a Pipelined Processor Assigned: April 6, Due: April 23, 11:59PM

Late Policy: no late submission is accepted.

#### 1 Introduction

In this project, you will learn about the design and implementation of a pipelined Y86 processor, optimizing both it and a benchmark program to maximize performance. You are allowed to make any semantics preserving transformations to the benchmark program, or to make enhancements to the pipelined processor, or both. When you have completed the lab, you will have a keen appreciation for the interactions between code and hardware that affect the performance of your programs.

The project is organized into three parts, each with its own handin. In Part A you will write some simple Y86 programs and become familiar with the Y86 tools. In Part B, you will extend the SEQ simulator with two new instructions. These two parts will prepare you for Part C, the heart of the lab, where you will optimize the Y86 benchmark program and the processor design.

# 2 Logistics

You can make a team with 2-3 members to complete this project. Of course, you are allowed to work on this project alone if you like. For a team, please select a corresponding leader from all members, which makes it convenient for us to contact with your team.

All handins must be electronic. Any necessary clarifications and revisions to the assignment will be posted on the oc Canvas platform.

#### 3 Handout Instructions

1. Start by copying the file project1-handout.zip to a working directory on a Linux machine in which you plan to complete this project.

- 2. Then give the command: tar xvf project1-handout.tar. This will cause the following files to be unpacked into the directory: README, Makefile, sim.tar, archlab.ps, archlab.pdf, and simguide.pdf.
- 3. Next, give the command tar xvf sim.tar. This will create the directory sim, which contains your personal copy of the Y86 tools. You will be doing all of your work inside this directory.
- 4. Finally, change to the sim directory and build the Y86 tools:

```
unix> cd sim
unix> make clean; make
```

#### 4 Part A

You will be working in directory sim/misc in this part.

Your task is to write and simulate the following three Y86 programs. The required behavior of these programs is defined by the example C functions in examples.c. Be sure to put your name and ID in a comment at the beginning of each program. You can test your programs by first assembling them with the program YAS and then running them with the instruction set simulator YIS.

In all of your Y86 functions, you should follow the IA32 conventions for the structure of the stack frame and for register usage instructions, including saving and restoring any callee-save registers that you use.

## sum.ys: Iteratively sum linked list elements

Write a Y86 program sum.ys that iteratively sums the elements of a linked list. Your program should consist of some code that sets up the stack structure, invokes a function, and then halts. In this case, the function should be Y86 code for a function (sum\_list) that is functionally equivalent to the C sum\_list function in Figure 1. Test your program using the following three-element list:

```
1 /* linked list element */
2 typedef struct ELE {
      int val;
      struct ELE *next;
5 } *list ptr;
^{7} /* sum list - Sum the elements of a linked list */
8 int sum_list(list_ptr ls)
9 {
10
      int val = 0;
11
      while (ls) {
          val += ls->val;
          ls = ls - > next;
13
14
     }
15
      return val;
16 }
17
18 /* rsum list - Recursive version of sum list */
19 int rsum_list(list_ptr ls)
21
      if (!ls)
22
          return 0;
      else {
23
          int val = ls->val;
          int rest = rsum list(ls->next);
25
26
          return val + rest;
27
      }
28 }
29
30 /* copy_block - Copy src to dest and return xor checksum of src */
31 int copy block(int *src, int *dest, int len)
32 {
      int result = 0;
33
34
      while (len > 0) {
35
          int val = *src++;
          *dest++ = val;
36
          result ^= val;
37
38
          len--;
     }
39
      return result;
40
41 }
```

Figure 1:  ${\bf C}$  versions of the Y86 solution functions. See  ${\tt sim/misc/examples.c}$ 

Table 1: Format of iaddl

Byte		1	2	3 4 5
iaddl V,	rВ	C 0	F rB	V

#### rsum.ys: Recursively sum linked list elements

Write a Y86 program rsum.ys that recursively sums the elements of a linked list. This code should be similar to the code in sum.ys, except that it should use a function rsum list that recursively sums a list of numbers, as shown with the C function rsum\_list in Figure 1. Test your program using the same three-element list you used for testing list.ys.

## copy.ys: Copy a source block to a destination block

Write a program (copy.ys) that copies a block of words from one part of memory to another (non-overlapping area) area of memory, computing the checksum (Xor) of all the words copied.

Your program should consist of code that sets up a stack frame, invokes a function <code>copy\_block</code>, and then halts. The function should be functionally equivalent to the C function <code>copy\_block</code> shown in Figure Figure 1. Test your program using the following three-element source and destination blocks:

#### 5 Part B

You will be working in directory sim/seq in this part.

Your task in Part B is to extend the SEQ processor to support a new instruction: iaddl. The function of iaddl is to add a constant value to a register. This requires first using an irmovl instruction to set a register to the constant, and then add addl instruction to add this value to the destination register. Supposewe want to add a new instruction iaddl with the format as illustrated in Table 1:

To add these instructions, you will modify the file seq-full.hcl, which implements the version of SEQ described in the CS:APP2e textbook. In addition, it contains declarations of some constants that you will need for your solution.

Your HCL file must begin with a header comment containing the following information:

- Leader's name and ID.
- A description of the computations required for the iaddl instruction. Use the descriptions of irmovl and OPl in Figure 4.18 in the CS:APP2e text as a guide.

# **Building and Testing Your Solution**

Once you have finished modifying the seq-full. hel file, then you will need to build a new instance of the SEQ simulator (ssim) based on this HCL file, and then test it:

• Building a new simulator. You can use make to build a new SEQ simulator:

```
unix> make VERSION=full
```

This builds a version of ssim that uses the control logic you specified in seq-full.hcl. To save typing, you can assign VERSION=full in the Makefile.

• Testing your solution on a simple Y86 program. For your initial testing, we recommend running simple programs such as a sumi.yo (testing iaddl) and a suml.yo (testing leave) in TTY mode, comparing the results against the ISA simulation:

```
unix> ./ssim -t ../y86-code/asumi.yo
unix> ./ssim -t ../y86-code/asuml.yo
```

If the ISA test fails, then you should debug your implementation by single stepping the simulator in GUI mode:

```
unix> ./ssim -g ../y86-code/asumi.yo
unix> ./ssim -g ../y86-code/asuml.yo
```

• Retesting your solution using the benchmark programs. Once your simulator is able to correctly execute small programs, then you can automatically test it on the Y86 benchmark programs in . . /y86-code:

```
unix> (cd ../y86-code; make testssim)
```

This will run ssim on the benchmark programs and check for correctness by comparing the resulting processor state with the state from a high-level ISA simulation. Note that none of these programs test the added instructions. You are simply making sure that your solution did not inject errors for the original instructions. See file ../y86-code/README file for more details.

• *Performing regression tests*. Once you can execute the benchmark programs correctly, then you should run the extensive set of regression tests in ../ptest. To test everything except iaddl and leave:

```
1 /*
2 * ncopy - copy src to dst, returning number of positive ints
3 * contained in src array.
4 */
5 int ncopy(int *src, int *dst, int len)
6 {
       int count = 0;
8
      int val;
9
      while (len > 0) {
10
          val = *src++;
11
           *dst++ = val;
12
           if (val > 0)
13
               count++;
14
15
           len--;
       }
16
17
      return count;
18 }
```

Figure 2: C version of the ncopy function. See sim/pipe/ncopy.c.

```
unix> (cd ../ptest; make SIM=../seq/ssim)
To test your implementation of iaddl:
unix> (cd ../ptest; make SIM=../seq/ssim TFLAGS=-i)
To test your implementation of leave:
unix> (cd ../ptest; make SIM=../seq/ssim TFLAGS=-1)
To test both iaddl and leave:
unix> (cd ../ptest; make SIM=../seq/ssim TFLAGS=-i1)
```

For more information on the SEQ simulator refer to the handout *CS:APP2e Guide to Y86 Processor Simulators* (simguide.pdf).

# 6 Part C

You will be working in directory sim/pipe in this part.

The ncopy function in Figure 2 copies a len-element integer array src to a non-overlapping dst, returning a count of the number of positive integers contained in src. Figure 3 shows the baseline Y86 version of ncopy. The file pipe-full.hcl contains a copy of the HCL code for PIPE, along with a declaration of the constant value IIADDL.

```
2 # ncopy.ys - Copy a src block of len ints to dst.
3 # Return the number of positive ints (>0) contained in src.
5 # Include your name and ID here.
6 #
7 # Describe how and why you modified the baseline code.
10 # Do not modify this portion
11 # Function prologue.
12 ncopy: pushl %ebp
                         # Save old frame pointer
13 rrmovl %esp,%ebp
                         # Set up new frame pointer
14
      pushl %esi
                         # Save callee-save regs
      pushl %ebx
1.5
       pushl %edi
16
       mrmovl 8(%ebp),%ebx
                         # src
17
      mrmovl 16(%ebp),%edx
                          # len
18
19
       mrmovl 12(%ebp),%ecx
                         # dst
20
22 # You can modify this portion
       # Loop header
                        # count = 0;
# len <= 0?
24
       xorl %eax, %eax
       andl %edx, %edx
25
       jle Done
                          # if so, goto Done:
26
27
28 Loop: mrmovl (%ebx), %esi # read val from src...
rmmovl %esi, (%ecx)
                         # ...and store it to dst
30
       andl %esi, %esi
                         # val <= 0?
                         # if so, goto Npos:
31
       ile Npos
       irmovl $1, %edi
32
       addl %edi, %eax
                         # count++
34 Npos: irmovl $1, %edi
subl %edi, %edx
                          # len--
36
       irmovl $4, %edi
       addl %edi, %ebx
                         # src++
37
       addl %edi, %ecx
                         # dst++
       andl %edx,%edx
                         # len > 0?
39
                          # if so, goto Loop:
4.0
       ja Loop
42 # Do not modify the following section of code
43 # Function epilogue.
44 Done:
4.5
      popl %edi
                          # Restore callee-save registers
46
       popl %ebx
       popl %esi
47
       rrmovl %ebp, %esp
48
       popl %ebp
49
       ret
52 # Keep the following label at the end of your function
53 End:
```

Figure 3: Baseline Y86 version of the ncopy function. See sim/pipe/ncopy.ys.

Your task in Part C is to modify ncopy.ys and pipe-full.hcl with the goal of making ncopy.ys run as fast as possible.

You will be handing in two files: pipe-full.hcl and ncopy.ys. Each file should begin with a header comment with the following information:

- Leader's name and ID.
- A high-level description of your code. In each case, describe how and why you modified your code.

#### **Coding Rules**

You are free to make any modifications you wish, with the following constraints:

- Your ncopy.ys function must work for arbitrary array sizes. You might be tempted to hardwire your solution for 64-element arrays by simply coding 64 copy instructions, but this would be a bad idea because we will be grading your solution based on its performance on arbitrary arrays.
- Your ncopy. ys function must run correctly with YIS. By correctly, we mean that it must correctly copy the srcblock *and* return (in %eax) the correct number of positive integers.
- The assembled version of your ncopy file must not be more than 1000 bytes long. You can check the length of any program with the ncopy function embedded using the provided script check-len.pl:

```
unix> ./check-len.pl < ncopy.yo
```

• Yourpipe-full.hclimplementation must pass the regression tests in . . /y86-code and . . /ptest (without the -i flags that test iaddl).

Other than that, you are free to implement the iaddl instruction if you think that will help. You may make any semantics preserving transformations to the ncopy.ys function, such as reordering instructions, replacing groups of instructions with single instructions, deleting some instructions, and adding other instructions. You may find it useful to read about loop unrolling in Section 5.8 of CS:APP2e.

#### **Building and Running Your Solution**

In order to test your solution, you will need to build a driver program that calls your ncopy function. We have provided you with the gen-driver.pl program that generates a driver program for arbitrary sized input arrays. For example, typing

```
unix> make drivers
```

will construct the following two useful driver programs:

- sdriver. yo: A *small driver program* that tests an ncopy function on small arrays with 4 elements. If your solution is correct, then this program will halt with a value of 2 in register %eax after copying the src array.
- ldriver.yo: A *large driver program* that tests an ncopy function on larger arrays with 63 elements. If your solution is correct, then this program will halt with a value of 31 (0x1f) in register %eax after copying the src array.

Each time you modify your ncopy. ys program, you can rebuild the driver programs by typing

```
unix> make drivers
```

Each time you modify your pipe-full.hcl file, you can rebuild the simulator by typing

```
unix> make psim VERSION=full
```

If you want to rebuild the simulator and the driver programs, type

```
unix> make VERSION=full
```

To test your solution in GUI mode on a small 4-element array, type

```
unix> ./psim -g sdriver.yo
```

To test your solution on a larger 63-element array, type

```
unix> ./psim -g ldriver.yo
```

Once your simulator correctly runs your version of ncopy. ys on these two block lengths, you will want to perform the following additional tests:

• Testing your driver files on the ISA simulator. Make sure that your ncopy.ys function works properly with YIS:

```
unix> make drivers
unix> ../misc/yis sdriver.yo
```

• Testing your code on a range of block lengths with the ISA simulator. The Perl script correctness.pl generates driver files with block lengths from 0 up to some limit (default 65), plus some larger sizes. It simulates them (by default with YIS), and checks the results. It generates a report showing the status for each block length:

```
unix> ./correctness.pl
```

This script generates test programs where the result count varies randomly from one run to another, and so it provides a more stringent test than the standard drivers.

If you get incorrect results for some length K, you can generate a driver file for that length that includes checking code, and where the result varies randomly:

```
unix> ./gen-driver.pl -f ncopy.ys -n K-rc > driver.ys
unix> make driver.yo
unix> ../misc/yis driver.yo
```

The program will end with register %eax having the following value:

0xaaaa : All tests pass.0xbbbb : Incorrect count

**Oxccc**: Function ncopy is more than 1000 bytes long.

**0xdddd**: Some of the source data was not copied to its destination.

**Oxeeee**: Some word just before or just after the destination region was corrupted.

• Testing your pipeline simulator on the benchmark programs. Once your simulator is able to correctly execute sdriver.ys and ldriver.ys, you should test it against the Y86 benchmark programs in ../y86-code:

```
unix> (cd ../y86-code; make testpsim)
```

This will run psim on the benchmark programs and compare results with YIS.

• Testing your pipeline simulator with extensive regression tests. Once you can execute the benchmark programs correctly, then you should check it with the regression tests in . . /ptest. For example, if your solution implements the iaddl instruction, then

```
unix> (cd ../ptest; make SIM=../pipe/psim TFLAGS=-i)
```

• Testing your code on a range of block lengths with the pipeline simulator. Finally, you can run the same code tests on the pipeline simulator that you did earlier with the ISA simulator

```
unix> ./correctness.pl -p
```

# 7 Evaluation

The project is worth 250 points: 30 points for Part A, 60 points for Part B, 100 points for Part C and 60 points for your report.

#### Part A

Part A is worth 30 points, 10 points for each Y86 solution program. Each solution program will be evaluated for correctness, including proper handling of the stack and registers, as well as functional equivalence with the example C functions in examples.c.

The programs sum.ys and rsum.ys will be considered correct if the graders do not spot any errors in them, and their respective sum\_list and rsum\_list functions return the sum 0xcba in register %eax.

The program copy.ys will be considered correct if the graders do not spot any errors in them, and the copy\_block function returns the sum 0xcba in register %eax, copies the three words 0x00a, 0x0b, and 0xc to the 12 contiguous memory locations beginning at address dest, and does not corrupt other memory locations.

#### Part B

This part of the lab is worth 60 points:

- 10 points for your description of the computations required for the iaddl instruction.
- 10 points for your description of the computations required for the leave instruction.
- 10 points for passing the benchmark regression tests in y86-code, to verify that your simulator still correctly executes the benchmark suite.
- 15 points for passing the regression tests in ptest for iaddl.
- 15 points for passing the regression tests in ptest for leave.

#### Part C

This part of the Lab is worth 100 points: You will not receive any credit if either your code for ncopy. ys or your modified simulator fails any of the tests described earlier.

- 20 points each for your descriptions in the headers of ncopy.ys and pipe-full.hcl and the quality of these implementations.
- 60 points for performance. To receive credit here, your solution must be correct, as defined earlier. That is, ncopy runs correctly with YIS, and pipe-full.hcl passes all tests in y86-code and ptest.

We will express the performance of your function in units of *cycles per element* (CPE). That is, if the simulated code requires C cycles to copy a block of N elements, then the CPE is C/N. The PIPE simulator displays the total number of cycles required to complete the program. The baseline version of the ncopy function running on the standard PIPE simulator with a large 63-element array requires 914 cycles to copy 63 elements, for a CPE of 914/63 = 14.51.

Since some cycles are used to set up the call to ncopy and to set up the loop within ncopy, you will find that you will get different values of the CPE for different block lengths (generally the CPE will drop as N increases). We will therefore evaluate the performance of your function by computing the average of the CPEs for blocks ranging from 1 to 64 elements. You can use the Perl script benchmark.pl in the pipe directory to run simulations of your ncopy.ys code over a range of block lengths and compute the average CPE. Simply run the command

```
unix> ./benchmark.pl
```

to see what happens. For example, the baseline version of the ncopy function has CPE values ranging between 46.0 and 14.51, with an average of 16.44. Note that this Perl script does not check for the correctness of the answer. Use the script correctness.pl for this:

```
unix> ./benchmark.pl -p
```

You should be able to achieve an average CPE of less than 10.0. Our best version averages 9.27. If your average CPE is *c*, then your score *S* for this portion of the lab will be:

$$S = \begin{cases} 0, & c > 12.5 \\ 24.0 \cdot (12.5 - c), & 10.0 \le c \le 12.5 \\ 60, & c < 10.0 \end{cases}$$

By default, benchmark.pl and correctness.pl compile and test ncopy.ys. Use the -f argument to specify a different file name. The -h flag gives a complete list of the command line arguments.

# **Project Report**

We prepare two report templates for you: latex-version and word-version. Please check them in directory *report-template*. and choose one template to write your report. Remember to delete all the tips (content in []) in the template.

You should fill in each single section with sentences and figures. That is, blank for any section is not permitted. However, any extended sections by yourselves are not limited and we will consider these content as **BONUS** for you.

#### 8 Handin Instructions

- To make our evaluation efficiently, please submit your work as following instructions. For your team, assume the leaders student ID as 000 you will be handing in three sets of files:
  - Part A: 000-sum.ys, 000-rsum.ys, and 000-copy.ys.
  - Part B: 000-seg-full.hcl.
  - Part C: 000-ncopy.ys and 000-pipe-full.hcl.

Then please put the three folders and your report file with PDF format named as 000-report.pdf into the final folder: 000 and zip it as "000.zip".

- Make sure you have included the leader's ID in a comment at the top of each of your handin files.
- To handin your files for part X, go to your archlab-handout directory and type:

```
unix> make handin-partX TEAM=teamname
```

where X is a, b, or c, and where teamname is your ID. For example, to handin Part A:

```
unix> make handin-parta TEAM=teamname
```

Finally, please upload your zip file through the Canvas Platform and remember that one handin is enough for one group. You can hand in as many times as you like before the deadline but only the latest modification will be considered for grading.

• **IMPORTANT:** Do add all the names and student IDs of all team members. The report is the only file that contains information of team members. And for each member, an available email is also needed.

#### 9 Hints

- By design, both sdriver. yo and ldriver. yo are small enough to debug with in GUI mode. We find it easiest to debug in GUI mode, and suggest that you use it.
- If you running in GUI mode on a Unix server, make sure that you have initialized the DISPLAY environment variable:

```
unix> setenv DISPLAY myhost.edu:0
```

- With some X servers, the "Program Code" window begins life as a closed icon when you run psim or ssim in GUI mode. Simply click on the icon to expand the window.
- With some Microsoft Windows-based X servers, the "Memory Contents" window will not automatically resize itself. You'll need to resize the window by hand.
- The psim and ssim simulators terminate with a segmentation fault if you ask them to execute a file that is not a valid Y86 object file.
- The psim and ssim simulators terminate with a segmentation fault if you ask them to execute a file that is not a valid Y86 object file. When make file, there might exist certain make errors. We recommend you to install libtk and libtel by using unix> sudo apt install libtk libtel.

#### 10 Last but not least

First, No late submission is accepted!

Second, please contact cs\_architecture@163.com if you meet any problems for this project. Good luck, everybody.