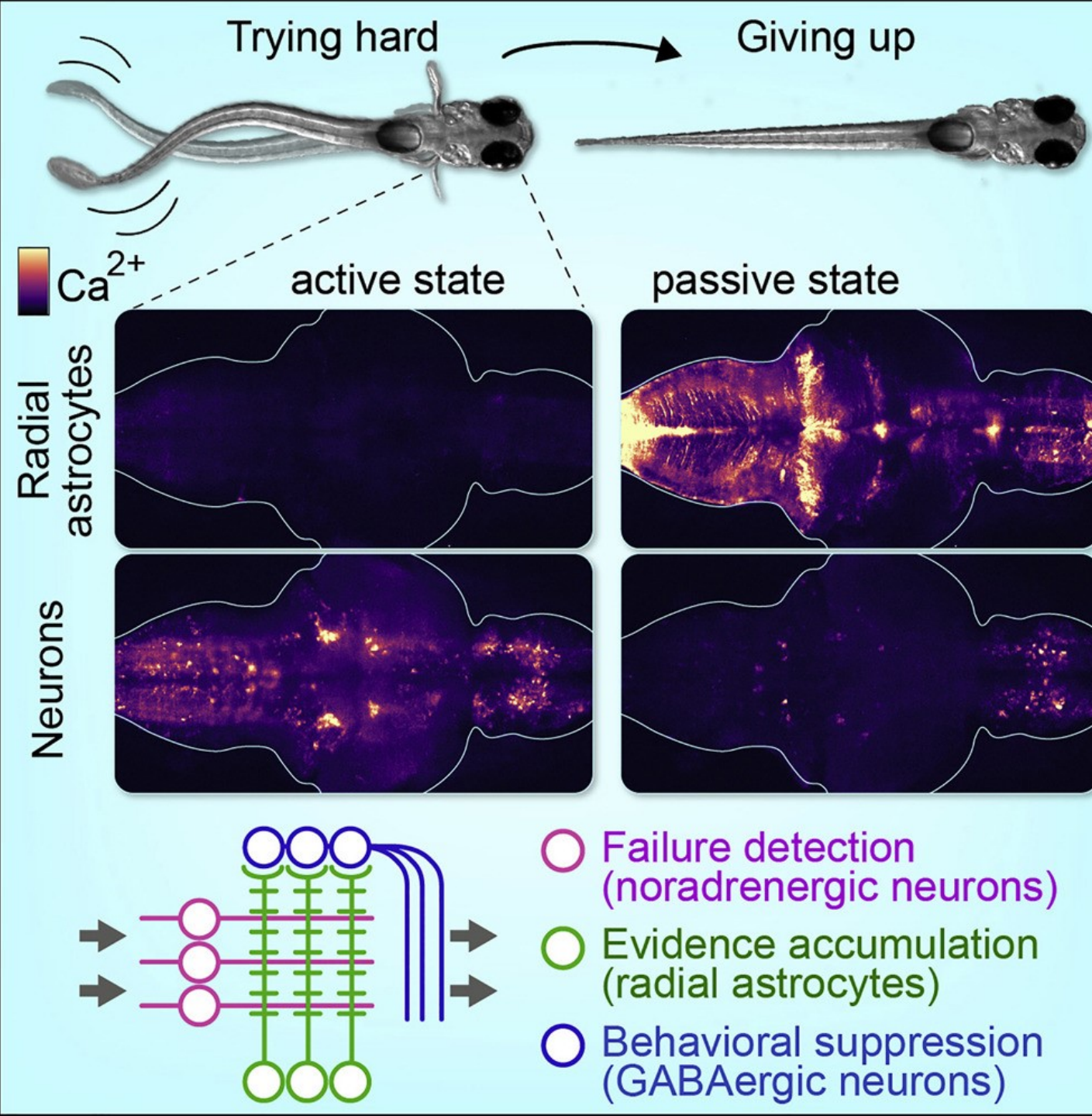


# Volumetric segmentation pipeline

Mika Rubinov

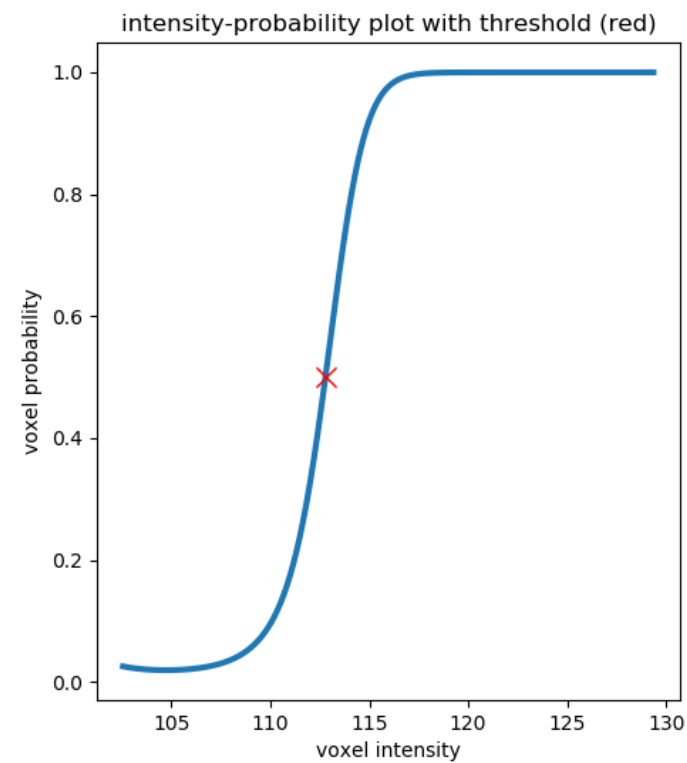
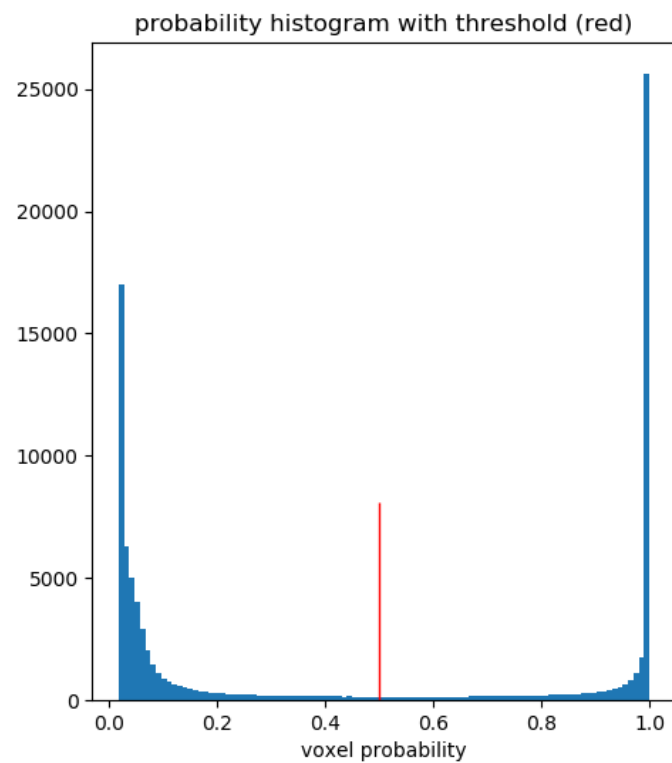
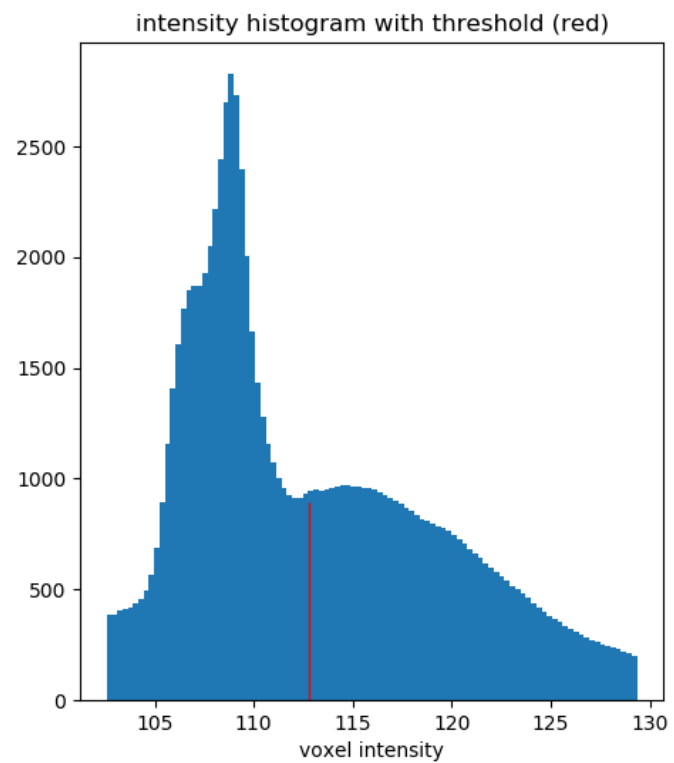
2020-03

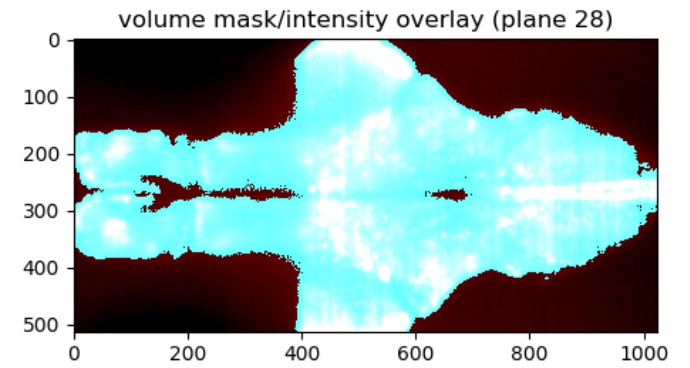
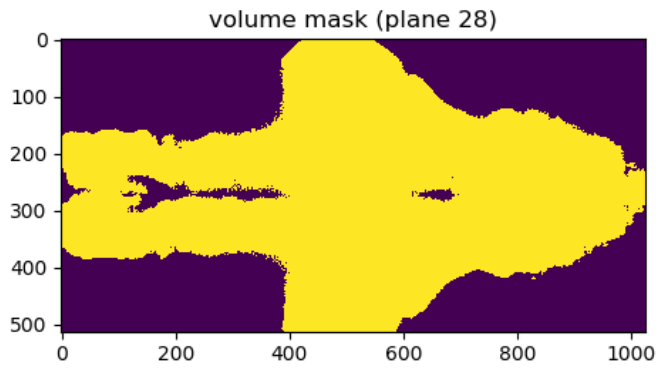
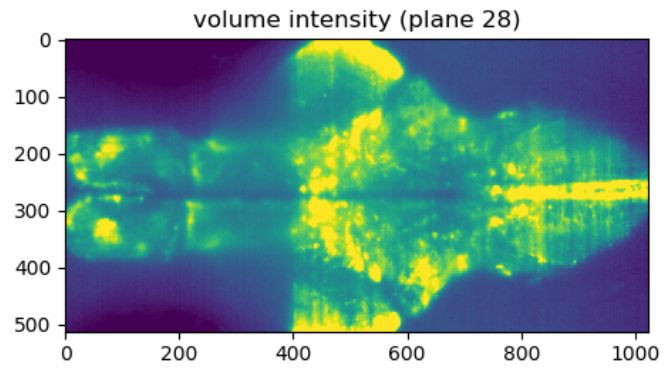


[github.com/mikarubi/voluseg](https://github.com/mikarubi/voluseg)

# Volumetric segmentation pipeline

1. Bin/downsample volumes (optional)
2. Register volumes with ANTS (optional)
3. Get average volume and brain mask





## 4. Cell segmentation

- a. Split volume into equally sized blocks
- b. Correct plane-acquisition time delays
- c. Initialize cell location using pixels that:
  - i. have local intensity peaks
  - ii. are sufficiently close in space
  - iii. are sufficiently highly correlated

## 4. Cell segmentation

d. Constrained factorization:

NMF:  $V_{n \times t} \approx W_{n \times (c+1)} H_{(c+1) \times t}$ , where:

$n \sim 10^7$  pixels;  $t \sim 10^4$  timepoints;  $c \sim 10^5$  cell segments.

Non-negativity constraints

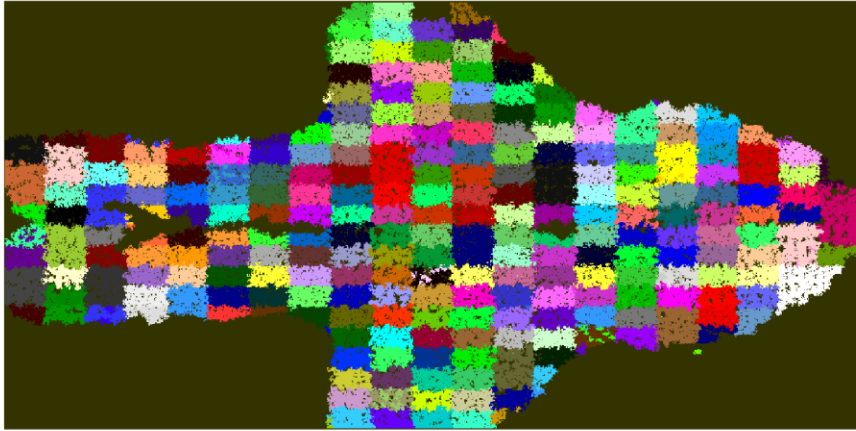
Hard spatial constraints

Sparseness projection

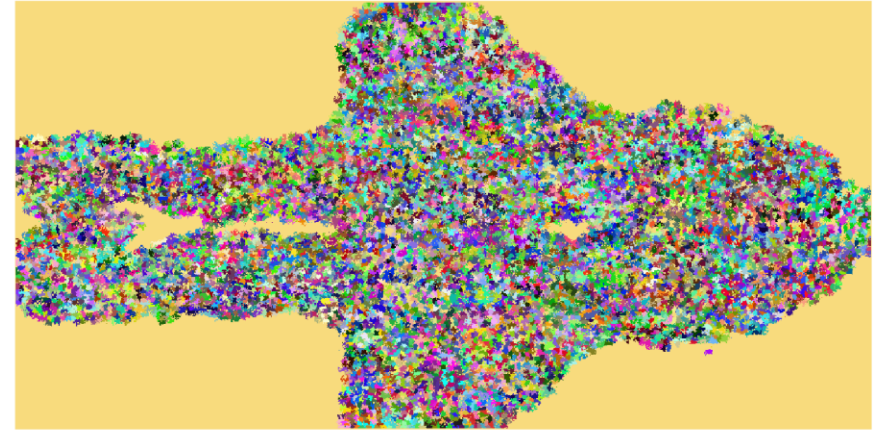
Background-signal removal



blocks (plane 28)



cells (plane 28)



## 5. Compute baseline

- a. Remove duplicate cells
- b. Detrend
- c. Compute baseline

# Dependencies

[preconfigured on ahrens\_lab1]

python: h5py, matplotlib, nibabel, numpy, pandas, scipy, skimage, sklearn

spark

ants for registration (optional)

# Installation

[preinstalled on ahrens\_lab1]

```
pip install git+https://github.com/mikarubi/voluseg.git
```

# Usage

1. Generate parameter file
2. Run segmentation

# Generate parameter file

## **# get parameter dictionary and set directories**

```
parameters = voluseg.parameter_dictionary()  
parameters['dir_input'] = '/path/to/input_directory'  
parameters['dir_output'] = '/path/to/output_directory'  
parameters['diam_cell'] = 5.0
```

## **# fetch z-resolution, exposure time, and stack frequency**

```
channel_file = os.path.join(parameters['dir_input'], 'cho.xml')  
stack_file = os.path.join(parameters['dir_input'], 'Stack_frequency.txt')  
parameters = voluseg.load_metadata(parameters, channel_file, stack_file)
```

## **# save parameters**

```
voluseg.stepo_process_parameters(parameters)
```

# Run registration

[on ahrens\_lab1, after parameter file saved in output directory]

**bsub -n32 voluseg\_spark\_janelia [nodes] /path/to/output/directory**

```
import os, voluseg
parameters = voluseg.parameter_dictionary()
```

```
{registration: medium,
  dir_ants: ,
  dir_output: ,
  planes_pad: 0,
  f_hipass: 0,
  n_cells_block: 100,
  res_x: 0.40625,
  res_z: 5.0,
  t_section: 0.01,
  diam_cell: 6.0,
  dir_input: ,
  ds: 2,
  nt: 1000,
  f_volume: 2.0,
  n_colors: 1,
  res_y: 0.40625,
  t_baseline: 300,
  thr_mask: 0.5}
```



voluseg.parameter\_dictionary??

registration: medium,	# registration quality: high, medium, low (none or None for no registration)
diam_cell: 6.0,	# cell diameter (microns)
dir_ants: ,	# path to ANTs directory
dir_input: ,	# path to image directory
dir_output: ,	# path to output directory
ds: 2,	# spatial coarse-graining in x-y dimension
planes_pad: 0,	# number of planes to pad the volume with (for robust registration)
nt: 1000,	# number of timepoints to use for cell detection (use all points if nt = 0)
f_hipass: 0,	# frequency (Hz) for high-pass filtering of cell timeseries
f_volume: 2.0,	# imaging frequency (Hz)
n_cells_block: 100,	# number of cells in block
n_colors: 1,	# number of brain colors (2 in two-color images)
res_x: 0.40625,	# x resolution (microns)
res_y: 0.40625,	# y resolution (microns)
res_z: 5.0,	# z resolution (microns)
t_baseline: 300,	# interval for baseline calculation (seconds)
t_section: 0.01,	# exposure time (seconds): time of slice acquisition
thr_mask: 0.5,	# threshold for volume mask: $0 < \text{thr} \leq 1$ (probability) or $\text{thr} > 1$ (intensity)

```
registration: medium,  
    # registration quality: high, medium, low (none or None for no registration)  
diam_cell: 6.0,  
    # cell diameter (microns)  
dir_ants: ,  
    # path to ANTs directory  
dir_input: ,  
    # path to image directory  
dir_output: ,  
    # path to output directory  
ds: 2,  
    # spatial coarse-graining in x-y dimension  
planes_pad: 0,  
    # number of planes to pad the volume with (for robust registration)  
nt: 1000,  
    # number of timepoints to use for cell detection (use all points if nt = 0)  
f_hipass: 0,  
    # frequency (Hz) for high-pass filtering of cell timeseries
```

f\_volume: 2.0,  
# imaging frequency (Hz)

n\_cells\_block: 100,  
# number of cells in block

n\_colors: 1,  
# number of brain colors (2 in two-color images)

res\_x: 0.40625,  
# x resolution (microns)

res\_y: 0.40625,  
# y resolution (microns)

res\_z: 5.0,  
# z resolution (microns)

t\_baseline: 300,  
# interval for baseline calculation (seconds)

t\_section: 0.01,  
# exposure time (seconds): time of slice acquisition

thr\_mask: 0.5,  
# threshold for volume mask:  $0 < \text{thr} \leq 1$  (probability) or  $\text{thr} > 1$  (intensity)

# Manual execution

```
filename_parameters = os.path.join(dir_output, 'parameters.pickle')
```

```
parameters = voluseg.load_parameters(filename_parameters)
```

```
voluseg.step1_process_images(parameters)
```

```
voluseg.step2_align_images(parameters)
```

```
voluseg.step3_mask_images(parameters)
```

```
voluseg.step4_detect_cells(parameters)
```

```
voluseg.step5_clean_cells(parameters)
```

# Pipeline output: parameters

- 'prepro.output'
  - spark configuration
  - parameters
  - run time
- 'parameters.pickle'
  - parameter dictionary, load with:
  - `parameters = voluseg.load_parameters(filename_parameters)`
  - dictionary required as input to individual pipeline steps

# Pipeline output: quality control

- 'mask\_plots'
  - directory of average volume plane images
  - brain mask superimposed on brain volume
  - can be used to assess goodness of brain masks
- 'transforms' directory
  - affine transforms for individual volumes
  - can be used to assess movement of individual volumes

# Pipeline output: 'volumeo.hdf5'

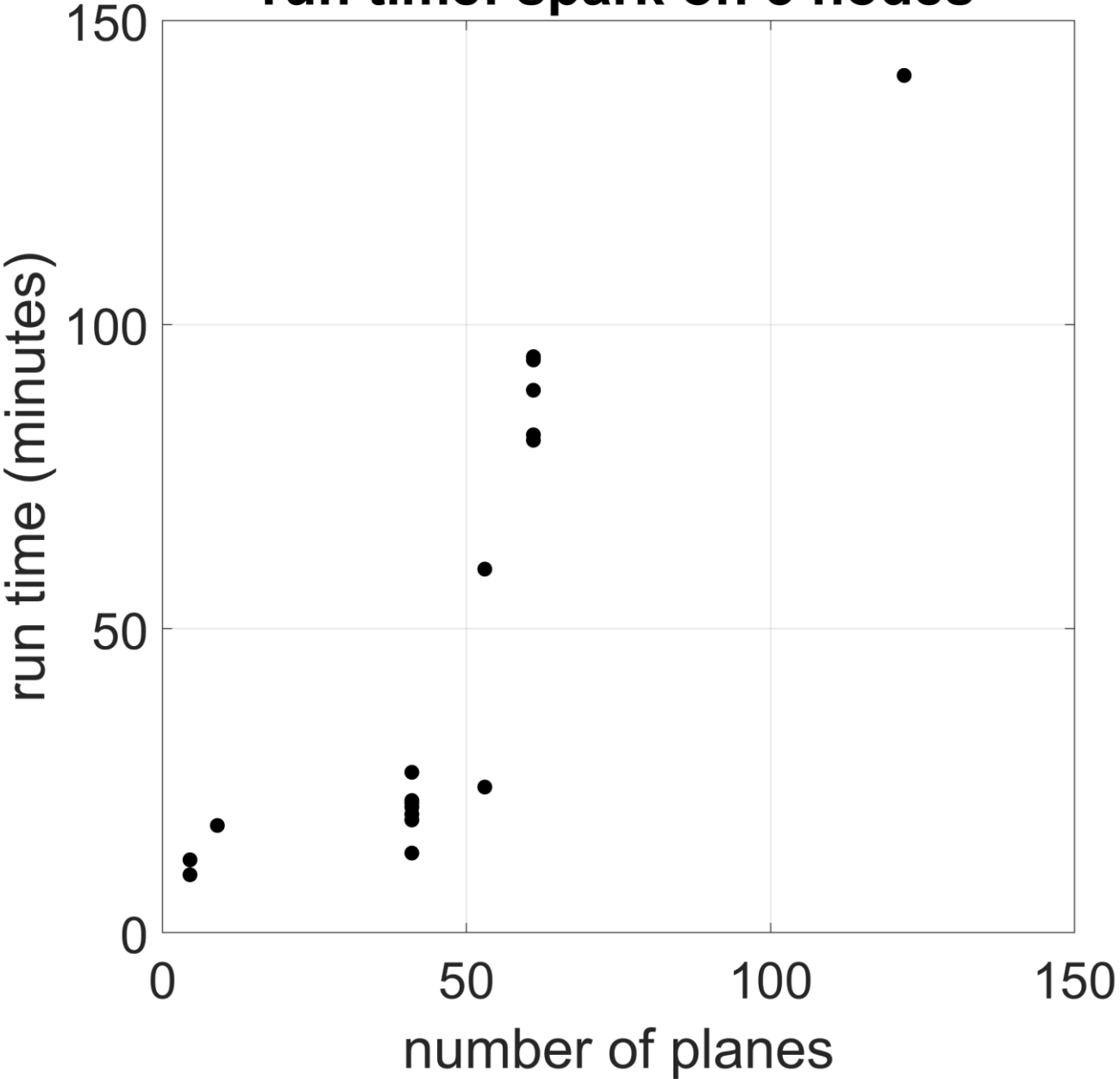
- 'background': estimated background fluorescence
- 'block\_valids': indices of blocks used for segmentation
- 'block\_xyz0/1': min/max block xyz coordinates
- 'n\_blocks': total number of blocks
- 'n\_voxels\_cells': approximate number of voxels in each cell
- 'thr\_intensity': brain-mask intensity threshold
- 'thr\_probability': brain-mask probability threshold
- 'timepoints': indices of timepoints used for cell segmentation
- 'timeseries\_mean': volume-mean timeseries
- 'volume\_mean/mask/peak': volume mean/mask/local peak intensity

# Pipeline output: 'cellso\_clean.hdf5'

- 'background': estimated background fluorescence
- 'cell\_baseline': computed cell baselines
- 'cell\_timeseries': detrended [+ optionally filtered] cell timeseries
- 'cell\_timeseries\_raw': 'raw' cell\_timeseries (direct output of segmentation)
- 'cell\_weights': cell spatial footprints (spatial NMF components)
- 'cell\_x/y/z': cell x, y, z coordinates
- 'n/t': number of cells/timepoints
- 'volume\_id': cell ids represented on a volume
- 'volume\_weight': cell spatial footprints represent on a volume
- 'x/y/z': x, y, z volume dimensions



run time: spark on 5 nodes



run time: spark on 5 nodes

