

模式: 全部

左边文件: G:\ros111111\aoa_ros\package.xml 右边文件: G:\aoa_ros\package.xml

| | | | | |
|----|---|----|---|---|
| 1 | <?xml version="1.0"?> | = | 1 | <?xml version="1.0"?> |
| | | <> | 2 | <?xml-model href="http://download.ros.org/schema/package_format3.xsd" schematypens="http://www.w3.org/2001/XMLSchema" type="package_format3" /> |
| 2 | <package format="2"> | | 3 | <package format="3"> |
| 3 | <name>aoa_ros</name> | | 4 | <name>aoa_ros</name> |
| 4 | <version>0.0.0</version> | | 5 | <version>0.0.0</version> |
| 5 | <description>The aoa_ros package</description> | | 6 | <description>Package containing examples of how to use the rcl API.</description> |
| 6 | | | | |
| 7 | <!-- One maintainer tag required, multiple allowed, one person per tag --> | | | |
| 8 | <!-- Example: --> | | | |
| 9 | <!-- <maintainer email="jane.doe@example.com">Jane Doe</maintainer> --> | | | |
| 10 | <maintainer email="utrytest@todo.todo">utrytest</maintainer> <!-- One license tag required, multiple allowed, one license per tag --> | | 7 | <maintainer email="huchunxu@hust.edu.cn">Hu Chunxu</maintainer> |
| 11 | <!-- Commonly used license strings: --> | | | |
| 12 | <!-- BSD, MIT, Boost Software License, GPLv2, GPLv3, LGPLv2.1, LGPLv3 --> | | | |
| 13 | <license>TODO</license> <!-- Url tags are optional, but multiple are allowed, one per tag --> | | 8 | <license>Apache License 2.0</license> |
| 14 | <!-- Optional attribute type can be: website, bugtracker, or repository --> | | 9 | |
| 15 | <!-- Example: --> | | | |
| 16 | <!-- <url type="website">http://wiki.ros.org/beginner_tutorials</url> --> | | | |
| 17 | <!-- Author tags are optional, multiple are allowed, one per tag --> | | | |
| 18 | <!-- Authors do not have to be maintainers, but could be --> | | | |
| 19 | <!-- Example: --> | | | |
| 20 | <!-- <author email="jane.doe@example.com">Jane Doe</author> --> <!-- The <exec_depend> tags are used to specify dependencies --> | | | |
| 21 | <!-- Dependencies can be catkin packages or system dependencies --> | | | |
| 22 | <!-- Examples: --> | | | |
| 23 | <!-- Use depend as a shortcut for packages that are both build and execution dependencies --> | | | |
| 24 | <!-- <depend>roscpp</depend> --> | | | |
| 25 | <!-- Note that this is equivalent to the following: --> | | | |
| 26 | <!-- <build_depend>roscpp</build_depend> <exec_depend>roscpp</exec_depend> --> | | | |

左边文件: G:\ros111111\aoa_ros\package.xml 右边文件: G:\aoa_ros\package.xml (继续)

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» end> -->
27 <!-- Use build_depend for packages y
» ou need at compile time: -->
28 <!-- <build_depend>message_generat
» ion</build_depend> -->
29 <!-- Use build_export_depend for pac
» kages you need in order to build aga
» inst this package: -->
30 <!-- <build_export_depend>message_
» generation</build_export_depend> -->
31 <!-- Use buildtool_depend for build
» tool packages: -->
32 <!-- <buildtool_depend>catkin</bui
» ldtool_depend> -->
33 <!-- Use exec_depend for packages yo
» u need at runtime: -->
34 <!-- <exec_depend>message_runtime<
» /exec_depend> -->
35 <!-- Use test_depend for packages yo
» u need only for testing: -->
36 <!-- <test_depend>gtest</test_depe
» nd> -->
37 <!-- Use doc_depend for packages you
» need only for building documentatio
» n: -->
38 <!-- <doc_depend>doxygen</doc_depe
» nd> -->
39 <buildtool_depend>catkin</buildtool_
» depend>
40 <build_depend>roscpp</build_depend>
41 <build_depend>rospy</build_depend>
42 <build_depend>std_msgs</build_depend
» >
43 <build_export_depend>roscpp</build_e
» xport_depend>
44 <build_export_depend>rospy</build_ex
» port_depend>
45 <build_export_depend>std_msgs</build
» _export_depend>
46 <exec_depend>roscpp</exec_depend>
47 <exec_depend>rospy</exec_depend>
48 <exec_depend>std_msgs</exec_depend>
» <!-- The export tag contains other,
» unspecified, tags -->
49 <export>
50 <!-- Other tools can request addit
» ional information be placed here -->
51
52 </export>
53 <build_depend>serial</build_depend>
54 <build_export_depend>serial</build_exp

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```

10 <buildtool_depend>ament_cmake</bui
» ldtool_depend>
11
12 <buildtool_depend>rosidl_default_g
» enerators</buildtool_depend>
13
14 <build_depend>rcl</build_depend>
15 <build_depend>rmw_implementation</
» build_depend>
16 <build_depend>std_msgs</build_depe
» nd>
17 <build_depend>serial</build_depend
» >
18
19 <exec_depend>rcl</exec_depend>
20 <exec_depend>rmw_implementation</e
» xec_depend>
21 <exec_depend>std_msgs</exec_depend
» >
22 <exec_depend>serial</exec_depend>
23 <exec_depend>rosidl_default_runtim
» e</exec_depend>
24
25 <export>
26 <build_type>ament_cmake</build
» _type>
27 </export>

```

左边文件: G:\ros1111111\aoa_ros\package.xml

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| | | | | |
|----|--|---|----|------------|
| 55 | » ort_depend> | | | |
| 56 | <exec_depend>serial</exec_depend> | | | |
| 57 | <build_export_depend>message_generatio | | | |
| 58 | <exec_depend>message_runtime</exec_dep | | | |
| 59 | </package> | = | 28 | </package> |