```
base_local_planner
  ::TrajectoryCostFunction
```

- scale_

+ prepare()
+ scoreTrajectory()
+ getScale()
+ setScale()
+ ~TrajectoryCostFunction()
# TrajectoryCostFunction()

```
base_local_planner
  ::TwirlingCostFunction
```

+ TwirlingCostFunction()
+ ~TwirlingCostFunction()
+ scoreTrajectory()
+ prepare()