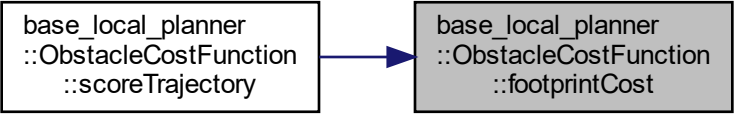


```
base_local_planner  
::ObstacleCostFunction  
  ::scoreTrajectory
```



The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box is white with a black border and contains the text 'base\_local\_planner', '::ObstacleCostFunction', and '::scoreTrajectory'. The right box is gray with a black border and contains the text 'base\_local\_planner', '::ObstacleCostFunction', and '::footprintCost'.

```
base_local_planner  
::ObstacleCostFunction  
  ::footprintCost
```