```
base local planner
        ::TrajectorySearch
      + findBestTrajectory()
      + ~TrajectorySearch()
      # TrajectorySearch()
base local planner
 ::SimpleScoredSamplingPlanner
- gen list
- critics
- max samples
+ ~SimpleScoredSamplingPlanner()
```

+ SimpleScoredSamplingPlanner() + SimpleScoredSamplingPlanner()

+ scoreTrajectory() + findBestTrajectory()