

navfn::NavfnROS::makePlan

navfn::NavfnROS::validPoint  
Potential

navfn::NavfnROS::getPoint  
Potential

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graph LR; A[navfn::NavfnROS::makePlan] --> C[navfn::NavfnROS::getPoint Potential]; B[navfn::NavfnROS::validPoint Potential] --> C;
```

The diagram illustrates a dependency or call relationship. Two white rectangular boxes on the left, representing functions 'navfn::NavfnROS::makePlan' and 'navfn::NavfnROS::validPoint Potential', have blue arrows pointing to a single gray rectangular box on the right, 'navfn::NavfnROS::getPoint Potential'. This suggests that both 'makePlan' and 'validPoint Potential' utilize the 'getPoint Potential' function.