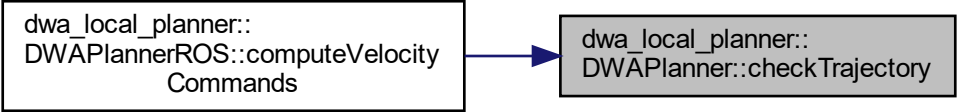


dwa_local_planner::
DWAPlannerROS::computeVelocity
Commands



```
graph LR; A["dwa_local_planner::  
DWAPlannerROS::computeVelocity  
Commands"] --> B["dwa_local_planner::  
DWAPlanner::checkTrajectory"]
```

The diagram illustrates a function call sequence. A white rectangular box on the left contains the text 'dwa_local_planner::', 'DWAPlannerROS::computeVelocity', and 'Commands'. A blue arrow points from the right side of this box to a gray rectangular box on the right. The gray box contains the text 'dwa_local_planner::' and 'DWAPlanner::checkTrajectory'.

dwa_local_planner::
DWAPlanner::checkTrajectory