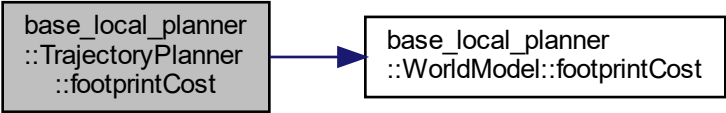


base\_local\_planner  
::TrajectoryPlanner  
::footprintCost



base\_local\_planner  
::WorldModel::footprintCost