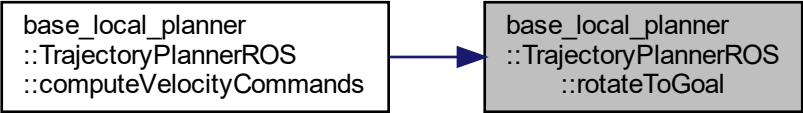


```
base_local_planner  
::TrajectoryPlannerROS  
::computeVelocityCommands
```



A diagram showing a call to the computeVelocityCommands method of the base_local_planner::TrajectoryPlannerROS class. A blue arrow points from the left box to the right box, indicating the flow of the call.

```
base_local_planner  
::TrajectoryPlannerROS  
::stopWithAccLimits
```