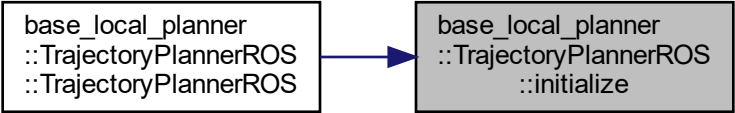


```
base_local_planner  
::TrajectoryPlannerROS  
::TrajectoryPlannerROS
```



The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box is white with a black border and contains three lines of C++ code: 'base\_local\_planner', '::TrajectoryPlannerROS', and another '::TrajectoryPlannerROS'. The right box is gray with a black border and contains two lines of C++ code: 'base\_local\_planner::TrajectoryPlannerROS' followed by an indented '::initialize' on the next line.

```
base_local_planner  
::TrajectoryPlannerROS  
    ::initialize
```