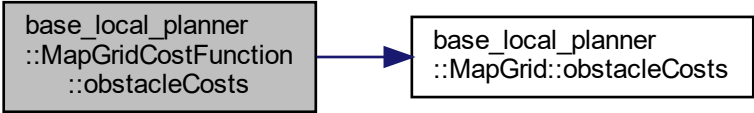


```
base_local_planner  
::MapGridCostFunction  
::obstacleCosts
```



A diagram illustrating a transformation of a C++ namespace and class name. On the left, a gray rectangular box contains the text 'base_local_planner', '::MapGridCostFunction', and '::obstacleCosts' stacked vertically. A blue arrow points from this box to a white rectangular box on the right. The white box contains the text 'base_local_planner', '::MapGrid::obstacleCosts' stacked vertically. The arrow indicates a mapping or transformation from the left state to the right state.

```
base_local_planner  
::MapGrid::obstacleCosts
```