```
base local planner
        ::TrajectorySearch
      + findBestTrajectory()
       + ~TrajectorySearch()
      # TrajectorySearch()
base local planner
```

```
::SimpleScoredSamplingPlanner
```

- critics

- gen list

- max samples
- + ~SimpleScoredSamplingPlanner() + SimpleScoredSamplingPlanner()
  - + SimpleScoredSamplingPlanner()
  - + scoreTrajectory()
- + findBestTrajectory()