base_local_planner ::LatchedStopRotateController
- latch_xy_goal_tolerance_ - xy_tolerance_latch_ - rotating_to_goal_
+ LatchedStopRotateController() + ~LatchedStopRotateController() + isPositionReached() + isGoalReached() + resetLatching() + stopWithAccLimits() + rotateToGoal() + computeVelocityCommandsStop Rotate() - sign()