```
#size x
                     # size_y
                     # resolution
                     # origin_x
# origin_y
                     # costmap_
                     # default_value_
                      - access
                     + Costmap2D()
                     + Costmap2D()
    string
                     + operator=()
                     + copyCostmapWindow()
                     + Costmap2D()
                     + ~Costmap2D()
                     + getCost()
                     + setCost()
                     + mapToWorld()
                     + worldToMap()
                     and 23 more.
                     # copyMapRegion()
                     # deleteMaps()
                     # resetMaps()
                     # initMaps()
                     # raytraceLine()
                     bresenham2D()
                     sign()
                   -global_frame_
                                   -costmap_
                   costmap_2d::LayeredCostmap
                   - rolling_window_
                   - current
                   - minx
                   - miny
                   maxx
                   - maxy
                   bx0
                   - bxn
                   - by0
                   - byn
      #name_
                   and 6 more...
                   + LayeredCostmap()
                   + ~LayeredCostmap()
                   + updateMap()
                   + getGlobalFrameID()
                   + resizeMap()
                   + getUpdatedBounds()
                   + isCurrent()
                   + getCostmap()
                   + isRolling()
                   + isTrackingUnknown()
                   and 9 more...
                        #layered_costmap_
    costmap_2d::Layer
 # current
 # enabled_
 # tf
 footprint_spec_
 + Layer()
 + initialize()
 + updateBounds()
 + updateCosts()
 + deactivate()
 + activate()
 + reset()
 + ~Layer()
 + isCurrent()
 + matchSize()
 + getName()
 + getFootprint()
 + onFootprintChanged()
 # onInitialize()
             Δ
costmap_2d::InflationLayer
# inflation_access_
# resolution
# inflation_radius
# inscribed_radius_
# weight_
# inflate unknown

    cell_inflation_radius

- cached_cell_inflation
 radius
inflation_cells_
- seen
- seen_size

    cached_costs

    cached_distances_

last_min_xlast_min_y
- last_max_x
last_max_y
dsrv
- need_reinflation
+ InflationLayer()
+ ~InflationLayer()
+ onlnitialize()
+ updateBounds()
+ updateCosts()
+ isDiscretized()
+ matchSize()
+ reset()
+ computeCost()
+ setInflationParameters()
# onFootprintChanged()
distanceLookup()
costLookup()
computeCaches()
deleteKernels()
- inflate_area()
cellDistance()
enqueue()
```

reconfigureCB()

costmap\_2d::Costmap2D