

E:/github/navigation
/base_local_planner/include
/base_local_planner/planar
_laser_scan.h

```
graph TD; A["E:/github/navigation  
/base_local_planner/include  
/base_local_planner/planar  
_laser_scan.h"] --> B["geometry_msgs/Point32.h"]; A --> C["sensor_msgs/PointCloud.h"]
```

geometry_msgs/Point32.h

sensor_msgs/PointCloud.h