

dwa_local_planner::
DWAPlanner::findBestPath



```
graph LR; A[dwa_local_planner::DWAPlanner::findBestPath] --> B[base_local_planner::OscillationCostFunction::updateOscillationFlags]; B --> C[base_local_planner::OscillationCostFunction::setOscillationFlags];
```

base_local_planner
::OscillationCostFunction
::updateOscillationFlags

base_local_planner
::OscillationCostFunction
::setOscillationFlags