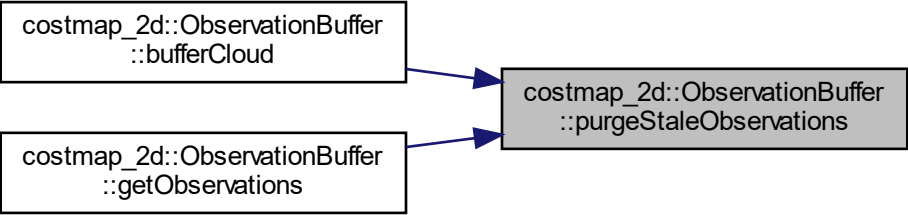


costmap\_2d::ObservationBuffer  
::bufferCloud

costmap\_2d::ObservationBuffer  
::getObservations

costmap\_2d::ObservationBuffer  
::purgeStaleObservations



```
graph LR; A["costmap_2d::ObservationBuffer::bufferCloud"] --> C["costmap_2d::ObservationBuffer::purgeStaleObservations"]; B["costmap_2d::ObservationBuffer::getObservations"] --> C;
```

The diagram illustrates a dependency or data flow. On the left, there are two white rectangular boxes with black borders. The top box contains the text 'costmap\_2d::ObservationBuffer::bufferCloud' and the bottom box contains 'costmap\_2d::ObservationBuffer::getObservations'. On the right, there is a gray rectangular box with a black border containing the text 'costmap\_2d::ObservationBuffer::purgeStaleObservations'. Two blue arrows point from the right side of the top white box and the right side of the bottom white box to the left side of the gray box.