**base_local_planner
::LocalPlannerLimits**

+ max_vel_trans
+ min_vel_trans
+ max_vel_x
+ min_vel_x
+ max_vel_y
+ min_vel_y
+ max_vel_theta
+ min_vel_theta
+ acc_lim_x
+ acc_lim_y
and 8 more...

+ LocalPlannerLimits()
+ LocalPlannerLimits()
+ ~LocalPlannerLimits()
+ getAccLimits()