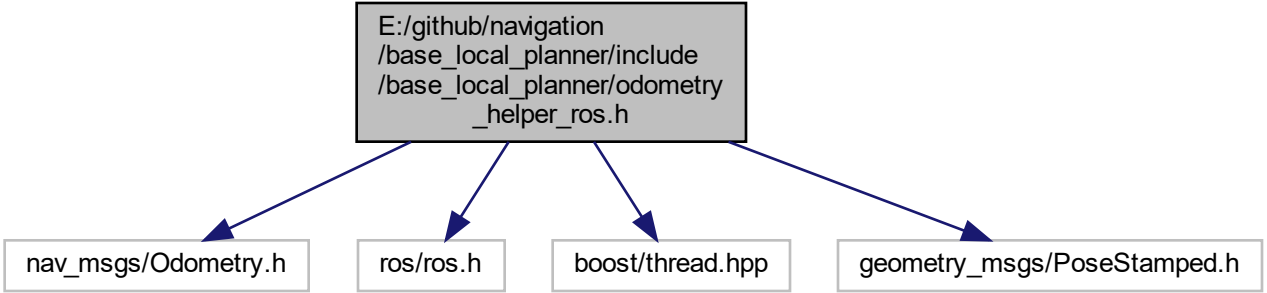


E:/github/navigation
/base_local_planner/include
/base_local_planner/odometry
_helper_ros.h



```
graph TD; A["E:/github/navigation  
/base_local_planner/include  
/base_local_planner/odometry  
_helper_ros.h"] --> B["nav_msgs/Odometry.h"]; A --> C["ros/ros.h"]; A --> D["boost/thread.hpp"]; A --> E["geometry_msgs/PoseStamped.h"];
```

The diagram illustrates the dependencies of the file `odometry_helper_ros.h` located at `E:/github/navigation/base_local_planner/include`. It is a hierarchical structure where a central box at the top points to four other boxes below it, each representing a file it depends on.

nav_msgs/Odometry.h

ros/ros.h

boost/thread.hpp

geometry_msgs/PoseStamped.h