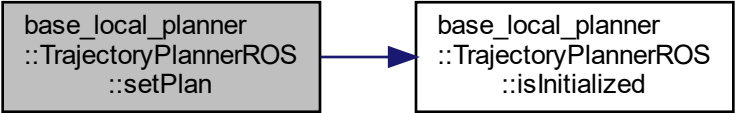


base_local_planner
::TrajectoryPlannerROS
::setPlan



```
graph LR; A["base_local_planner  
::TrajectoryPlannerROS  
::setPlan"] --> B["base_local_planner  
::TrajectoryPlannerROS  
::isInitialized"]
```

The diagram consists of two rectangular boxes connected by a horizontal blue arrow pointing from left to right. The left box has a light gray background and contains the text 'base_local_planner', '::TrajectoryPlannerROS', and '::setPlan' stacked vertically. The right box has a white background and contains the text 'base_local_planner', '::TrajectoryPlannerROS', and '::isInitialized' stacked vertically. The arrow is a solid blue line with a triangular arrowhead pointing towards the right box.

base_local_planner
::TrajectoryPlannerROS
::isInitialized