

dwa_local_planner::
DWAPlanerROS::isGoalReached



```
graph LR; A[dwa_local_planner::DWAPlanerROS::isGoalReached] --> B[base_local_planner::LatchedStopRotateController::isGoalReached];
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box is white with a black border and contains the text 'dwa_local_planner::' followed by 'DWAPlanerROS::isGoalReached' on the next line. The right box is gray with a black border and contains the text 'base_local_planner' followed by '::LatchedStopRotateController' on the next line, and '::isGoalReached' on the third line.

base_local_planner
::LatchedStopRotateController
::isGoalReached