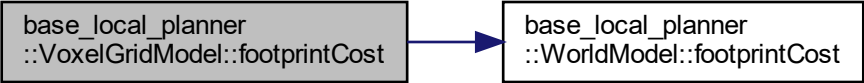


base\_local\_planner  
::VoxelGridModel::footprintCost



```
graph LR; A["base_local_planner  
::VoxelGridModel::footprintCost"] --> B["base_local_planner  
::WorldModel::footprintCost"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box has a light gray background and contains the text 'base\_local\_planner' followed by '::VoxelGridModel::footprintCost' on the next line. The right box has a white background and contains the text 'base\_local\_planner' followed by '::WorldModel::footprintCost' on the next line. A dark blue arrow points from the right side of the left box to the left side of the right box.

base\_local\_planner  
::WorldModel::footprintCost