```
string
             -frame id
            odom topic
base local planner
 ::OdometryHelperRos
- odom sub
- base odom
- odom mutex
+ OdometryHelperRos()
+ ~OdometryHelperRos()
+ odomCallback()
+ getOdom()
+ getRobotVel()
+ setOdomTopic()
+ getOdomTopic()
```