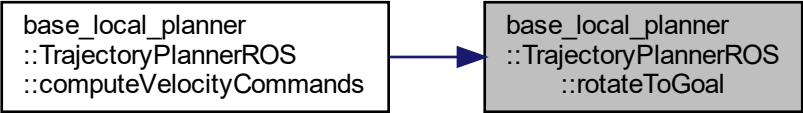


```
base_local_planner  
::TrajectoryPlannerROS  
::computeVelocityCommands
```



A diagram showing a call to the computeVelocityCommands method of the base\_local\_planner::TrajectoryPlannerROS class. A blue arrow points from this call to the rotateToGoal method of the same class.

```
base_local_planner  
::TrajectoryPlannerROS  
::rotateToGoal
```