

base_local_planner
::MapGrid

+ goal_x_
+ goal_y_
+ size_x_
+ size_y_
- map_

+ MapGrid()
+ MapGrid()
+ operator()()
+ operator()()
+ getCell()
+ ~MapGrid()
+ MapGrid()
+ operator=()
+ resetPathDist()
+ sizeCheck()
and 9 more...
+ adjustPlanResolution()