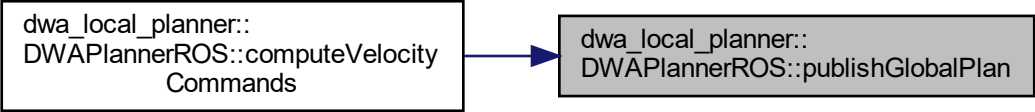


dwa_local_planner::
DWAPlannerROS::computeVelocity
Commands



```
graph LR; A["dwa_local_planner::  
DWAPlannerROS::computeVelocity  
Commands"] --> B["dwa_local_planner::  
DWAPlannerROS::publishGlobalPlan"]
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box is white with a black border and contains the text 'dwa_local_planner::', 'DWAPlannerROS::computeVelocity', and 'Commands' on three lines. The right box is gray with a black border and contains the text 'dwa_local_planner::' and 'DWAPlannerROS::publishGlobalPlan' on two lines.

dwa_local_planner::
DWAPlannerROS::publishGlobalPlan