

Timing Diagrams for Accellera Standard OVL V1.8

Mike Turpin / ARM 18th October 2006

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 - **S** Types of OVL
 - **S OVL Release History & Major Changes**

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    pre-Accellera
    v1.0
    v1.1, v1.1a, b
    v1.5
    v1.6
    v1.7
    v1.8
    Aug 2005
    Dec 2005
    Mar 2006
    July 2006
    Oct 2006
```

- **Introduction to Timing Diagrams**
 - **S** Timing Diagram Syntax & Semantics
 - **S** Timing Diagram Template
- S OVL Timing Diagrams (alphabetical order)



Types of OVL Assertion

Combinatorial

Combinatorial Assertions

s assert_proposition, assert_never_unknown_async

Single-Cycle

Single-cycle Assertions

s assert_always, assert_implication, assert_range, ...

2-Cycles

Sequential over 2 cycles

s assert_always_on_edge, assert_decrement, ...

n-Cycles

Sequential over num_cks cycles

s assert_change, assert_cycle_sequence, assert_next, ...

Event-bound

Sequential between two events

s assert_win_change, assert_win_unchange, assert_window



OVL Release History and Major Changes

- pre-Accellera, April 2003
 - S Verilog updated in April, but VHDL still October 2002
- § v1.0, July 2005
 - S Changed: assert_fifo_index (no longer uses property_type in functionality)
- § v1.1, August 2005
 - S New: assert_never_unknown
 - S Changed:
 - § assert_implication: antecendent_expr typo fixed
 - s assert_change: window length fixed to num_cks
- § v1.1a, August 2005
 - § Fixed: assert_width
- v1.1b, August 2005 (minor updates to doc)



OVL Release History and Major Changes

- § v1.5, December 2005
 - § New:
 - S Preliminary PSL support
 - S `OVL_IGNORE property_type
 - § Fixed: assert_always_on_edge (startup delayed by 1 cycle)
- § v1.6, March 2006
 - S New: assert_never_unknown_async
- § v1.7, July 2006
 - S Consistent X Semantics & Coverage Levels
 - S PSL support
- § v1.8, Oct 2006
 - **Bug fixes**



Contents

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§ Introduction to OVL
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- **Types of OVL**
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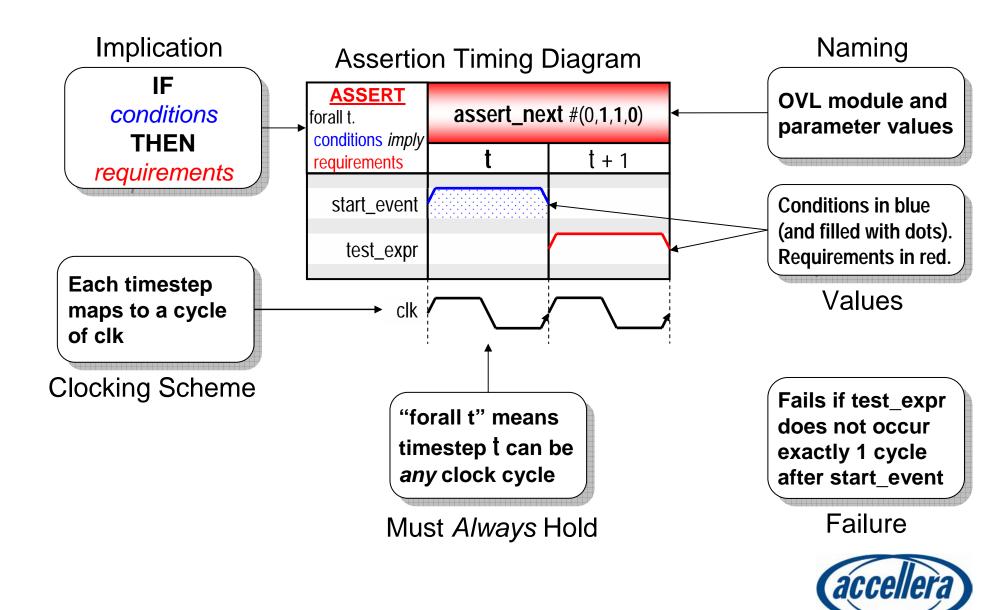
```
    pre-Accellera Apr 2003
    v1.1 July 2005
    v1.1a, b Aug 2005
    v1.5 Dec 2005
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    v1.8 Oct 2006
```

Introduction to Timing Diagrams

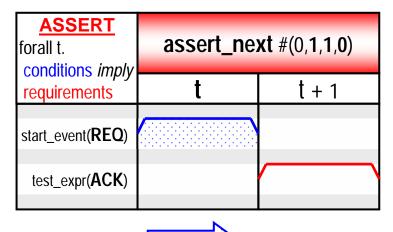
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Introduction: OVL Timing Diagram

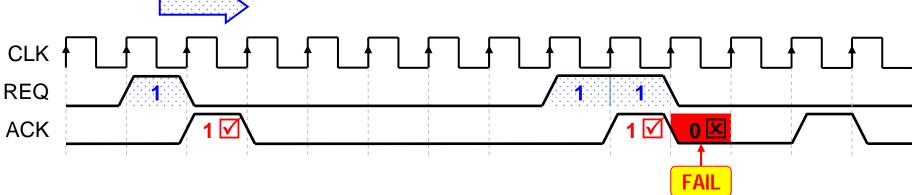


Introduction: Verification of Assertion



Imagine sliding the timing diagram, pipeline style, over each simulation cycle ...

... if all conditions match, then all requirements must hold.

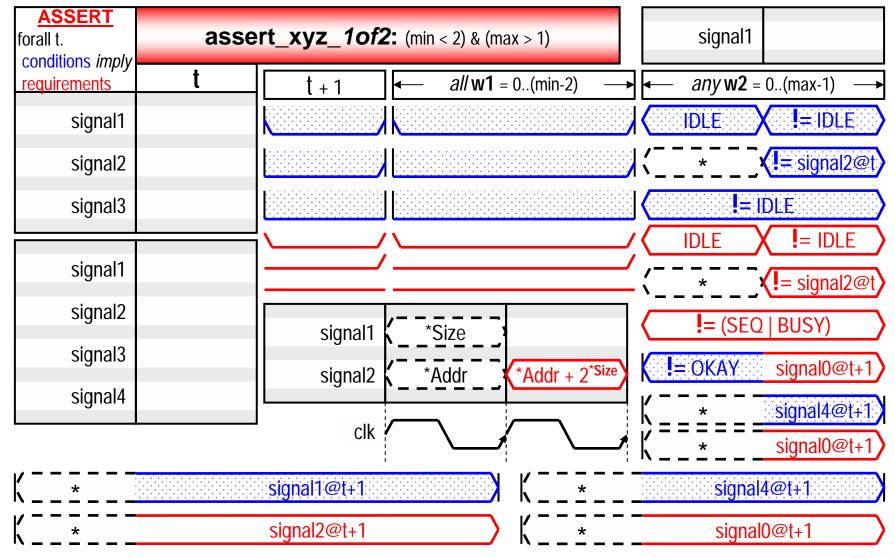


Simulation *might* show this failure, but only if stimulus covers back-to-back REQs.

Formal Verification would never pass this, and should show the failure with a short debug trace.



Template





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Introduction to Timing Diagrams

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- **Timing Diagram Template**
- S OVL Timing Diagrams (alphabetical order)

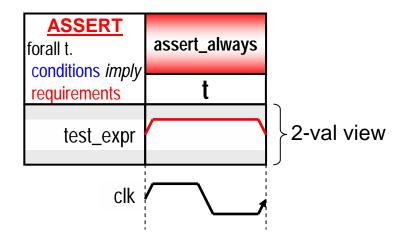


assert_always

#(severity_level, property_type, msg, coverage_level)
ul (clk, reset_n, test_expr)

test_expr must always hold

Single-Cycle



assert_always will also *pessimistically* fail if test_expr is X

Can disable failure on X/Z via:

`define OVL_XCHECK_OFF



assert_always_on_edge

#(severity_level, edge_type, property_type, msg, coverage_level)
u1 (clk, reset_n, sampling_event, test_expr)

test_expr is true immediately following the edge specified by the edge_type parameter

2-Cycles

ASSERT forall t. conditions imply	assert_always_on_edge #(0,1)		Rising
requirements	t	t + 1	
sampling_event			
test_expr			
clk			

ASSERT forall t. conditions imply	assert_always_on_edge #(0,2)		Fallin edge
requirements	t	t + 1	
sampling_event			
test_expr			
clk			

ASSERT forall t. conditions imply requirements	assert_always _on_edge t	edge_type=0 (default is no edge)
test_expr		Identical to assert_always

ASSERT forall t. conditions imply	assert_always_on_edge #(0,3)		Any
requirements	t	t + 1	
sampling_event	, , *SE	!= SE@t	
test_expr			

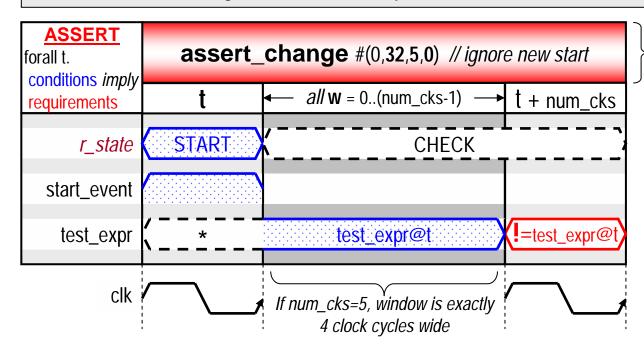


assert_change

#(severity_level, width, num_cks, action_on_new_start, property_type, msg, coverage_level)
u1 (clk, reset_n, start_event, test_expr)

test_expr must change within num_cks cycles of start_event

n-Cycles



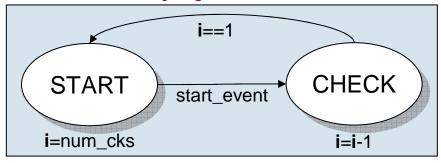
num_cks=5
-action_on_new_start=0
(`OVL_IGNORE_NEW_START)

Will pass if test_expr changes at *any* cycle: t+1, t+2, ..., t+num_cks Fails if test_expr is stable for all num_cks cycles.

Differs to April 2003

From OVL version 1.0 the check window spans the entire num_cks-1 cycles.

r_state (auxiliary logic)



Auxiliary logic necessary, to *ignore* new start.

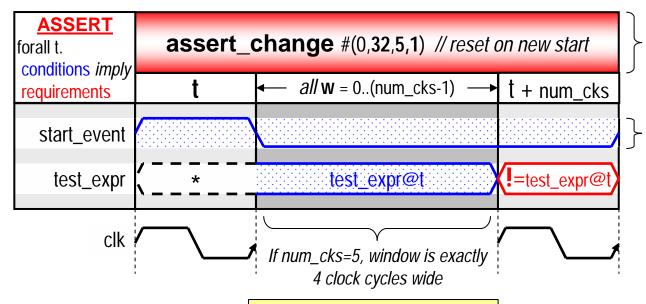
Checking only begins after start_event is true and r_state==START.



#(severity_level, width, num_cks, action_on_new_start, property_type, msg, coverage_level)
u1 (clk, reset n, start event, test expr)

test_expr must change within num_cks cycles of start_event

n-Cycles



num_cks=5
action_on_new_start=1
(`OVL_RESET_ON_NEW_START)

extra condition on start_event

"reset on new start" timing diagram does not require auxiliary logic (see note 2).

Differs to April 2003

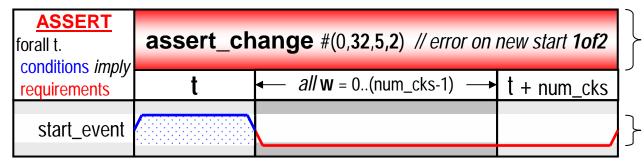
From OVL version 1.0 the check window spans the entire num_cks-1 cycles.



#(severity_level, width, num_cks, action_on_new_start, property_type, msg, coverage_level)
u1 (clk, reset n, start event, test expr)

test_expr must change within num_cks cycles of start_event

n-Cycles



num_cks=5
action_on_new_start=2
(`OVL_ERROR_ON_NEW_START)

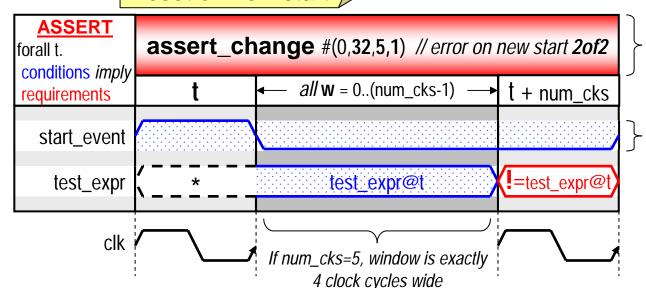
├ requirement on start_event



"error on new start" requires **two timing diagrams**, with 2nd being the same as "reset on new start"

Differs to April 2003

From OVL version 1.0 the check window spans the entire num_cks-1 cycles.



num_cks=5
action_on_new_start=2
(`OVL_ERROR_ON_NEW_START)

condition on start_event

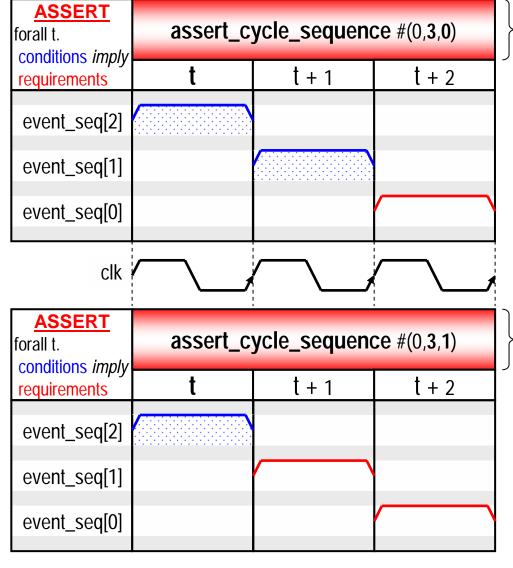


assert_cycle_sequence

#(severity_level, num_cks, necessary_condition, property_type, msg, coverage_level)
u1 (clk, reset_n, event_sequence)

If the initial sequence holds, the final sequence must also hold (final is 1-cycle or N-1 cycles)

n-Cycles



num_cks=3
-necessary_condition=0
(`OVL_TRIGGER_ON_MOST_PIPE)

Both timing diagrams are pipelined. They do not require any auxiliary logic.

num_cks=3 necessary_condition=1 (`OVL_TRIGGER_ON_FIRST_PIPE)

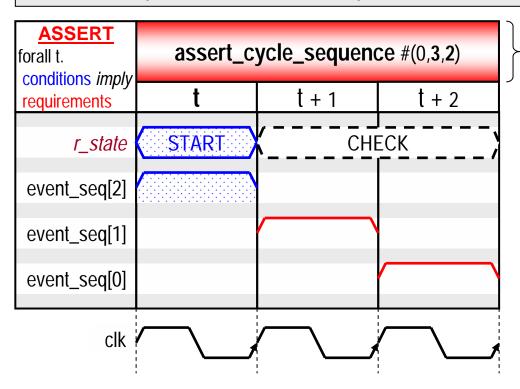


assert_cycle_sequence

#(severity_level, num_cks, necessary_condition, property_type, msg, coverage_level)
u1 (clk, reset_n, event_sequence)

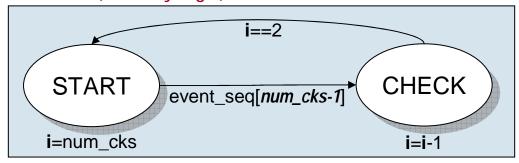
If the initial sequence holds, the final sequence must also hold (final is 1-cycle or N-1 cycles)

n-Cycles



num_cks=3
-necessary_condition=2
(`OVL_TRIGGER_ON_FIRST_NONPIPE)

r_state (auxiliary logic)



Need auxiliary logic, to *ignore* subsequent event_seq[num_cks-1] when non-pipelined.

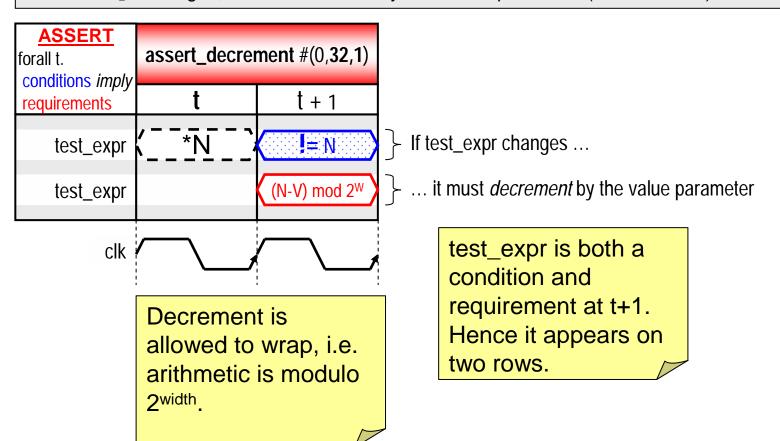


assert_decrement

#(severity_level, width, value, property_type, msg, coverage_level)
u1 (clk, reset_n, test_expr)

If test_expr changes, it must decrement by the value parameter (modulo 2^{width})

2-Cycles



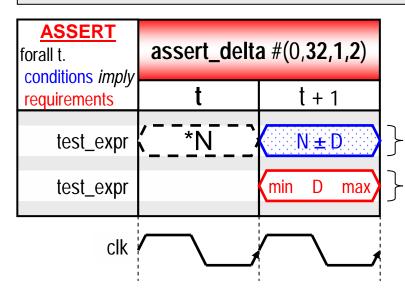


assert_delta

#(severity_level, width, min, max, property_type, msg, coverage_level)
u1 (clk, reset_n, test_expr)

If test_expr changes, the delta must be min and max

2-Cycles



If test_expr changes value by delta D ...

... then delta D must be within min/max limits

test_expr is both a condition and requirement at t+1. Hence it appears on two rows.

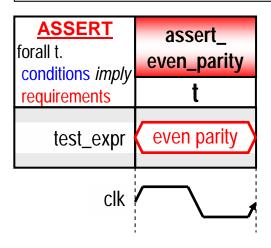


assert_even_parity

#(severity_level, width, property_type, msg, coverage_level)
u1 (clk, reset_n, test_expr)

test_expr must have an even parity, i.e. an even number of bits asserted.

Single-Cycle





assert_fifo_index

#(severity_level, depth, push_width, pop_width, property_type, msg, coverage_level, simultaneous_push_pop)
ul (clk, reset_n, push, pop)

FIFO pointers should never overflow or underflow.

2-Cycles

ASSERT forall t. conditions imply	assert_fi	fo_index	
requirements	t	t + 1	
push	(*H;		
рор	/\ (*P/		
cnt	(*C}	C+H-P depth	} Should not overflow
cnt	C+H < P		Should not underflow
clk			

The counter "cnt" changes by a (push-pop) delta every cycle.

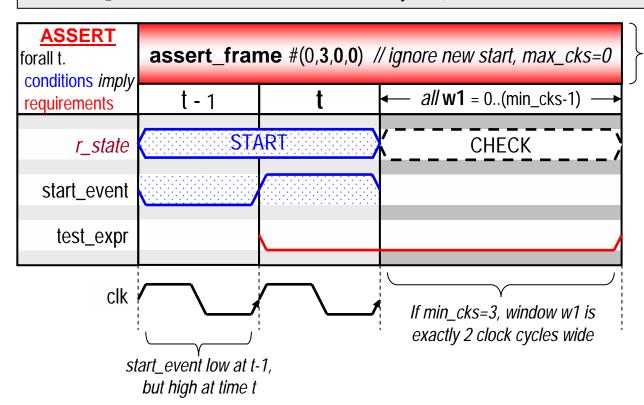
If simultaneous_push_pop is low, there is an additional check to ensure that push and pop are not both >1



#(severity_level, min_cks, max_cks, action_on_new_start, property_type, msg, coverage_level)
ul (clk, reset_n, start_event, test_expr)

test_expr must not hold before min_cks cycles, but must hold at least once by max_cks.

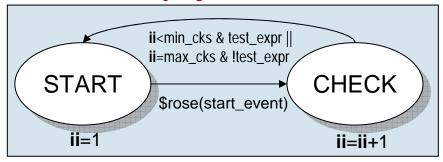
n-Cycles



min_cks>0, max_cks=0 action_on_new_start=0 (`OVL_IGNORE_NEW_START)

Shows min_cks>0 and max_cks=0 (no upper limit). Only checks that test_expr stays low up until t+(min_cks-1).

r_state (auxiliary logic)



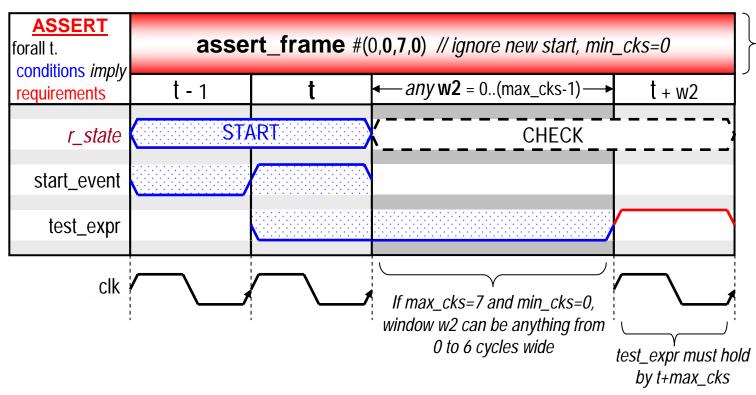
Auxiliary logic necessary, to *ignore* new rising edge on start_event. The \$rose syntax indicates high now but low in previous cycle.



#(severity_level, min_cks, max_cks, action_on_new_start, property_type, msg, coverage_level)
u1 (clk, reset_n, start_event, test_expr)

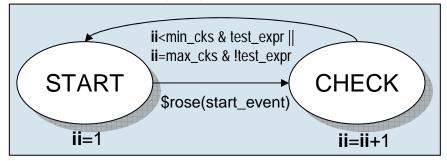
test_expr must not hold before min_cks cycles, but must hold at least once by max_cks.

n-Cycles



min_cks=0, max_cks>0 action_on_new_start=0 (OVL_IGNORE_NEW_START)

r_state (auxiliary logic)



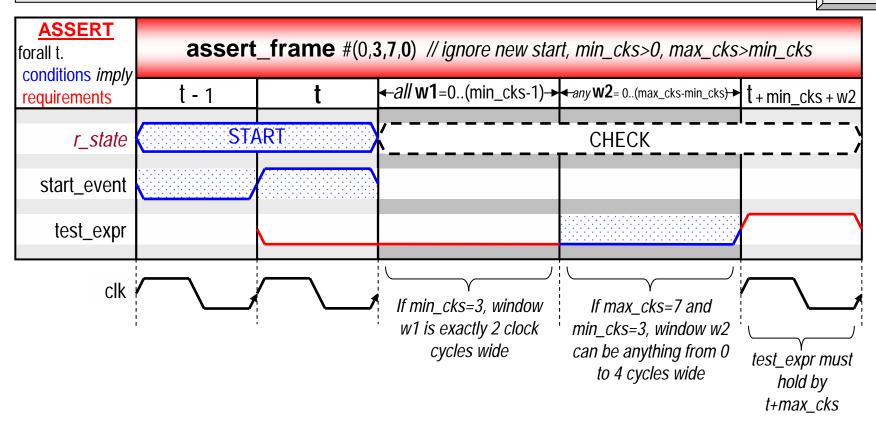
Important to have test_expr@t==1'b0 condition. Avoids extra checking if test_expr already holds at time t.



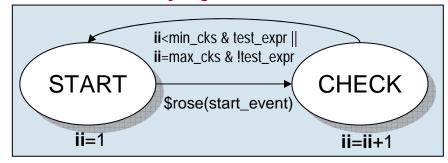
#(severity_level, min_cks, max_cks, action_on_new_start, property_type, msg, coverage_level)
u1 (clk, reset_n, start_event, test_expr)

test_expr must not hold before min_cks cycles, but must hold at least once by max_cks.

n-Cycles



r_state (auxiliary logic)

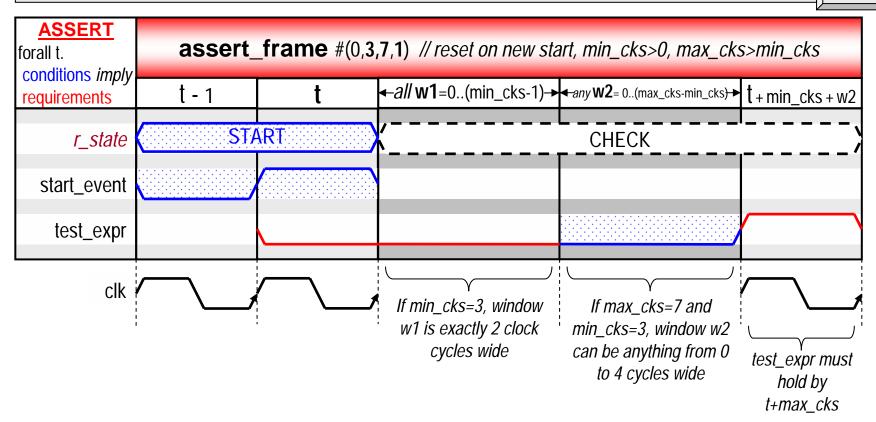




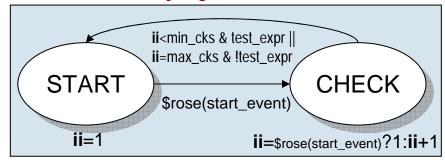
#(severity_level, min_cks, max_cks, action_on_new_start, property_type, msg, coverage_level)
u1 (clk, reset_n, start_event, test_expr)

test_expr must not hold before min_cks cycles, but must hold at least once by max_cks.

n-Cycles



r_state (auxiliary logic)



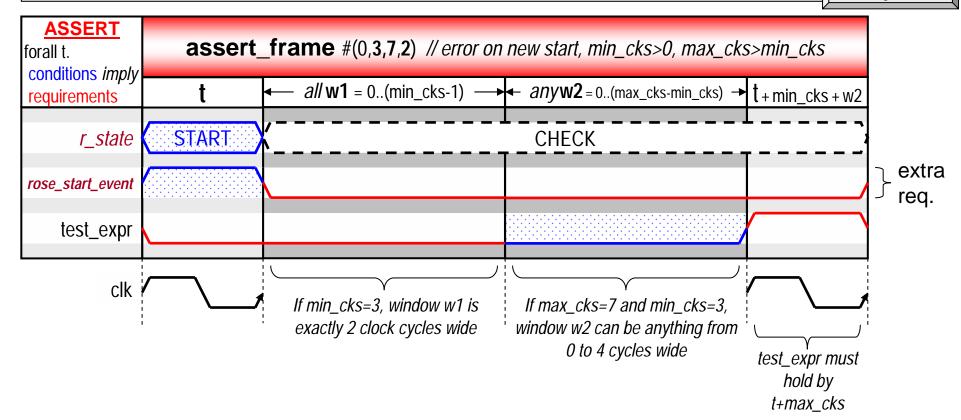
Auxiliary logic also necessary for "reset on new start", but counter resets to 1 on new rising edge of start_event.



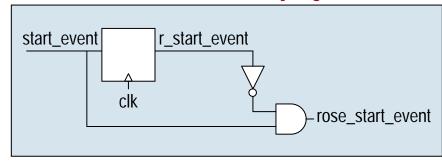
#(severity_level, min_cks, max_cks, action_on_new_start, property_type, msg, coverage_level)
u1 (clk, reset_n, start_event, test_expr)

test_expr must not hold before min_cks cycles, but must hold at least once by max_cks.

n-Cycles



rose_start_event (auxiliary logic)



"error on new start"
has an additional
requirement from t+1
(no new rising edge
on start_event).

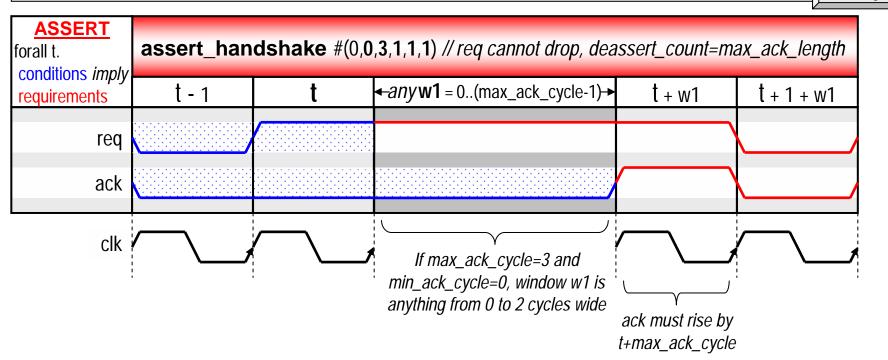


assert handshake

#(severity_level, min_ack_cycle, max_ack_cycle, req_drop, deassert_count, max_ack_length,
 property_type, msg, coverage_level) u1 (clk, reset_n, req, ack)

req and ack must follow the specified handshaking protocol

n-Cycles



assert_handshake is highly configurable. This timing diagram shows the most common usage.

Consider splitting up more complex uses into multiple OVL (simplifies formal property checking).



assert_implication

#(severity_level, property_type, msg, coverage_level)
u1 (clk, reset_n, antecedent_expr, consequent_expr)

If antecedent_expr holds then consequent_expr must hold in the same cycle

Single-Cycle

ASSERT forall t. conditions imply	assert_ implication
requirements	t
antecedent_expr	
consequent_expr	
clk	

Assertion will only fail if consequent_expr is low when antecedent_expr holds.

Assertion will trivially pass if conditions do not occur i.e. if antecedent_expr=0.

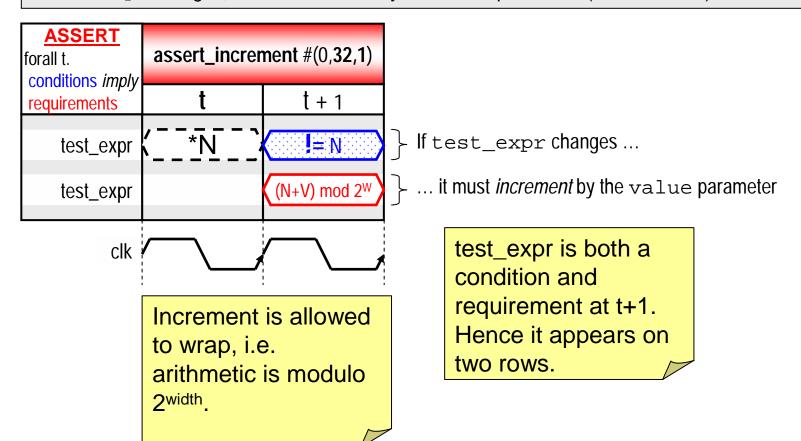


assert_increment

#(severity_level, width, value, property_type, msg, coverage_level)
u1 (clk, reset_n, test_expr)

If test_expr changes, it must increment by the value parameter (modulo 2^{width})

2-Cycles



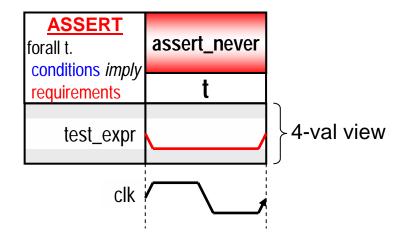


assert never

#(severity_level, property_type, msg, coverage_level)
ul (clk, reset_n, test_expr)

test_expr must never hold

Single-Cycle



assert_never will also pessimistically fail if test_expr is X

Can disable failure on X/Z via: `define OVL_XCHECK_OFF

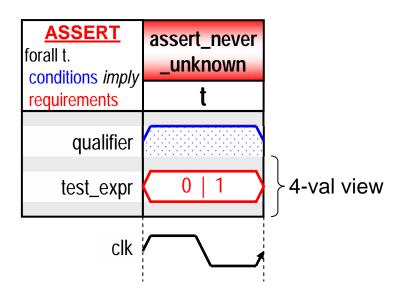


assert_never_unknown

#(severity_level, width, property_type, msg, coverage_level)
u1 (clk, reset_n, qualifier, test_expr)

test_expr must never be at an unknown value, just boolean 0 or 1.

Single-Cycle



Often used as an explicit X-checking assertion

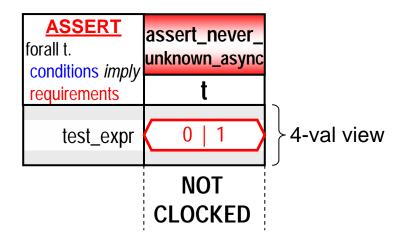


assert_never_unknown_async

#(severity_level, width, property_type, msg, coverage_level)
u1 (reset_n, test_expr)

test_expr must never go to an unknown value asynchronously (must stay boolean 0 or 1).

Combinatorial



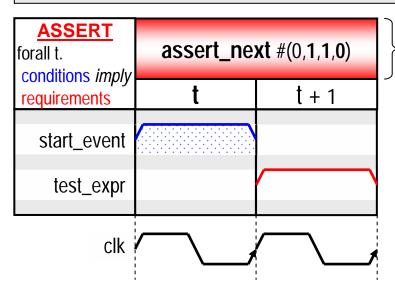
This is the asynchronous version of the clocked assert_never_unknown.



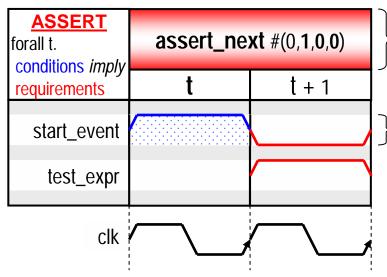
#(severity_level, num_cks, check_overlapping,check_missing_start, property_type, msg, coverage_level)
u1 (clk, reset_n, start_event, test_expr)

test_expr must hold num_cks cycles after start_event holds

N Cycles



num_cks=1
check_overlapping=1
check_missing_start=0



num_cks=1 ≻check_overlapping=0 check_missing_start=0

├ requirement on start_event

With check_overlapping at 0, assertion will error if there is a subsequent start_event.



#(severity_level, num_cks, check_overlapping,check_missing_start, property_type, msg, coverage_level)
u1 (clk, reset_n, start_event, test_expr)

test_expr must hold num_cks cycles after start_event holds

N Cycles

ASSERT forall t. conditions imply	assert_next #(0,1,1,1)	
requirements	t	t + 1
start_event		
test_expr		

num_cks=1 ≻check_overlapping=1 check_missing_start=1

condition on start_event



"check missing start" requires **two timing diagrams**, which together form an *if-and-only-if* check.

ASSERT forall t. conditions imply	assert_next #(0,1,1,1)	
requirements	t	t + 1
start_event		
test_expr		

num_cks=1 -check_overlapping=1 -check_missing_start=1

condition on test_expr

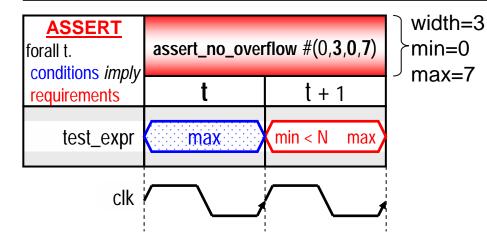


assert_no_overflow

#(severity_level, width, min, max, property_type, msg, coverage_level)
u1 (clk, reset_n, test_expr)

If test_expr is at max, in the next cycle test_expr must be > min and max

2-Cycles



Example can check that a 3-bit pointer cannot do a wrapping increment from 7 back to 0.

The min and max values do not need to span the full range of test_expr.



assert_no_transition

#(severity_level, width, property_type, msg, coverage_level)
ul (clk, reset_n, test_expr, start_state, next_state)

If test_expr equals start_state, then test_expr must not change to next_state

2-Cycles

ASSERT forall t. conditions imply	assert_no_transition	
requirements	t	t + 1
test_expr	start_state	!= next_state
clk		

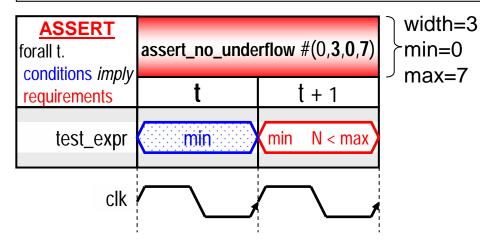


assert_no_underflow

#(severity_level, width, min, max,property_type, msg, coverage_level)
u1 (clk, reset_n, test_expr)

If test_expr is at min, in the next cycle test_expr must be min and < max

2-Cycles



Example can check that a 3-bit pointer cannot do a wrapping decrement from 0 to 7.

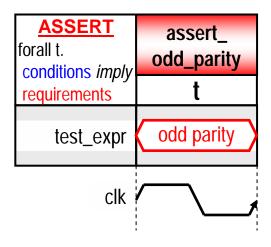
The min and max values do not need to span the full range of test_expr.



assert_odd_parity

#(severity_level, width, property_type, msg, coverage_level)
u1 (clk, reset_n, test_expr)

test_expr must have an odd parity, i.e. an odd number of bits asserted.





assert_one_cold

#(severity_level, width, inactive, property_type, msg, coverage_level)
ul (clk, reset_n, test_expr)

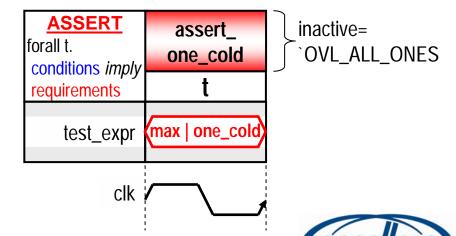
${\tt test_expr} \; {\tt must} \; {\tt be} \; {\tt one-cold}, \; {\tt i.e.} \; {\tt exactly} \; {\tt one} \; {\tt bit} \; {\tt set} \; {\tt low}$

Single-Cycle

ASSERT forall t. conditions imply	assert_ one_cold	inactive= `OVL_ONE_COLD
requirements	t	
test_expr	one_cold	
clk		

Unlike one_hot and zero_one_hot, just one configurable OVL is used for one_cold.

ASSERT forall t. conditions imply	assert_ one_cold	inactive= `OVL_ALL_ZEROS
requirements	t	
test_expr	0 one_cold	
clk		



assert_one_hot

#(severity_level, width, property_type, msg, coverage_level)
ul (clk, reset_n, test_expr)

 ${\tt test_expr} \ \textbf{must} \ \textbf{be} \ \textbf{one-hot}, \ \textbf{i.e.} \ \textbf{exactly} \ \textbf{one} \ \textbf{bit} \ \textbf{set} \ \textbf{high}$

ASSERT forall t. conditions imply requirements	assert_ one_hot t
test_expr	one_hot
clk	



assert_proposition

#(severity_level, property_type, msg, coverage_level)
u1 (reset_n, test_expr)

test_expr must hold asynchronously (not just at a clock edge)

Combinatorial

ASSERT forall t. conditions imply requirements	assert _proposition t
test_expr	
	NOT CLOCKED

This is an asynchronous version of the clocked assert_always

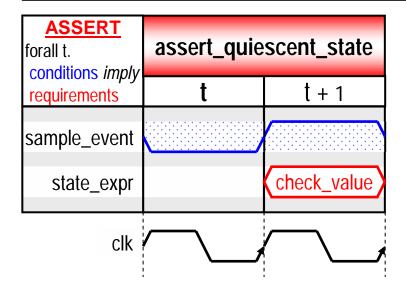


assert_quiescent_state

#(severity_level, width, property_type, msg, coverage_level)
u1 (clk, reset_n, state_expr, check_value, sample_event)

state_expr must equal check_value on a rising edge of sample_event

2-Cycles



Can also be checked on rising edge of:

OVL_END_OF_SIMULATION
Used for extra check at simulation end.

Can *just* trigger at end of simulation by setting sample_event to 1'b0 and defining:

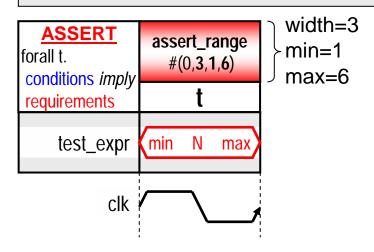
OVL_END_OF_SIMULATION



assert_range

#(severity_level, width, min, max, property_type, msg, coverage_level)
u1 (clk, reset_n, test_expr)

test_expr must be min and max



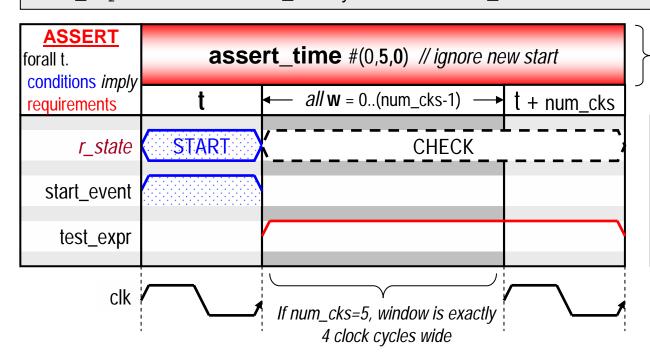


assert time

#(severity_level, num_cks, action_on_new_start, property_type, msg, coverage_level)
u1 (clk, reset n, start event, test expr)

test_expr must hold for num_cks cycles after start_event

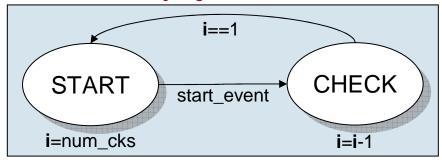
n-Cycles



num_cks=5
action_on_new_start=0
(`OVL_IGNORE_NEW_START)

Only passes if test_expr is high for *all* cycles: t+1, t+2, ..., t+num_cks
Fails if test_expr is low in any of these cycles.

r_state (auxiliary logic)

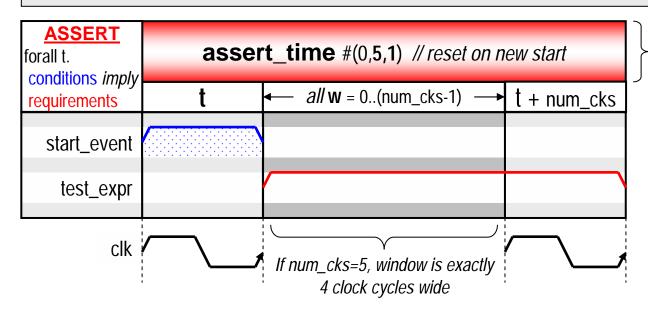




#(severity_level, num_cks, action_on_new_start, property_type, msg, coverage_level)
ul (clk, reset n, start event, test expr)

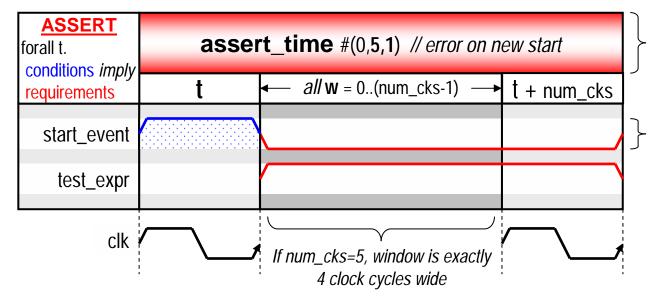
test_expr must hold for num_cks cycles after start_event

n-Cycles



num_cks=5
action_on_new_start=1
(`OVL_RESET_ON_NEW_START)

For assert_time, "reset on new start" effectively perfoms pipelined checking (see note 2).



num_cks=5
action_on_new_start=2
(`OVL_ERROR_ON_NEW_START)

├ requirement on start_event

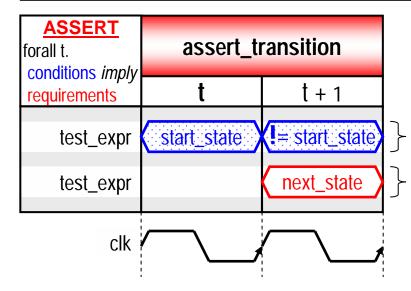


assert_transition

#(severity_level, width, property_type, msg, coverage_level)
u1 (clk, reset_n, test_expr, start_state, next_state)

If test_expr changes from start_state, then it can only change to next_state

2-Cycles



test_expr can remain in start_state (in which case the condition at t+1 does not hold).

If test_expr changes from start_state ...

... it can only change into next_state

test_expr is both a condition and requirement at t+1. Hence it appears on two rows.

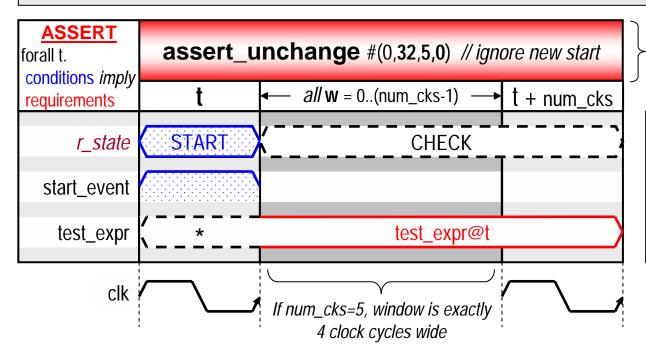


assert unchange

#(severity_level, width, num_cks, action_on_new_start, property_type, msg, coverage_level)
u1 (clk, reset_n, start_event, test_expr)

test_expr must not change within num_cks cycles of start_event

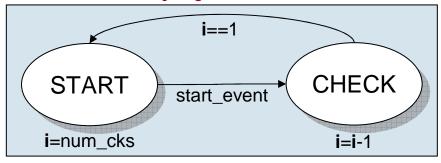
n-Cycles



num_cks=5
action_on_new_start=0
(`OVL_IGNORE_NEW_START)

Only passes if test_expr is stable for *all* cycles: t+1, t+2, ..., t+num_cks
Fails if test_expr changes in any of these cycles.

r_state (auxiliary logic)



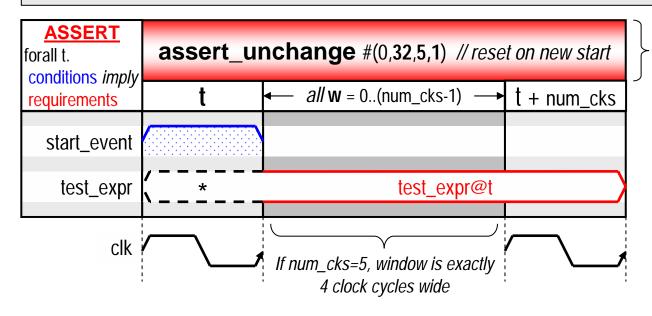
Need auxiliary logic to be able to *ignore* new start. Checking only begins after start_event is true and r_state==START.



#(severity_level, width, num_cks, action_on_new_start, property_type, msg, coverage_level)
ul (clk, reset n, start event, test expr)

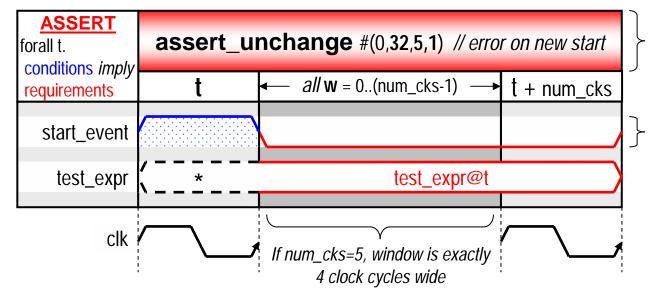
test_expr must not change within num_cks cycles of start_event

n-Cycles



num_cks=5
action_on_new_start=1
(`OVL_RESET_ON_NEW_START)

For assert_unchange "reset on new start" is *pipelined* checking. Don't need auxiliary logic to express this



num_cks=5
action_on_new_start=2
(`OVL_ERROR_ON_NEW_START)

├ requirement on start_event



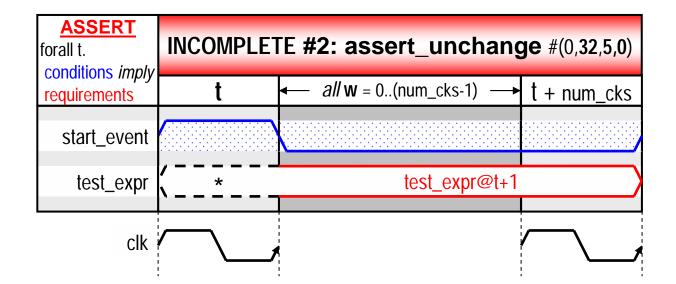
assert_unchange

#(severity_level, width, num_cks, action_on_new_start, property_type, msg, coverage_level)
u1 (clk, reset_n, start_event, test_expr)

test_expr must not change within num_cks cycles of start_event

n-Cycles

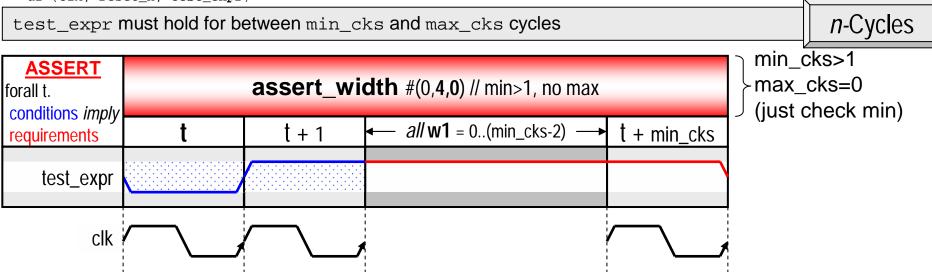
ASSERT for all t.	INCOMPLETE #1: assert_unchange #(0,32,5,0) // ignore new start				
conditions imply requirements	t - num_cks	← - <i>all</i> w1 =0(num-1)>	t	←all w2 =0(num-1) >	t + num_cks
start_event					
test_expr			\	test_expr	@t
clk					



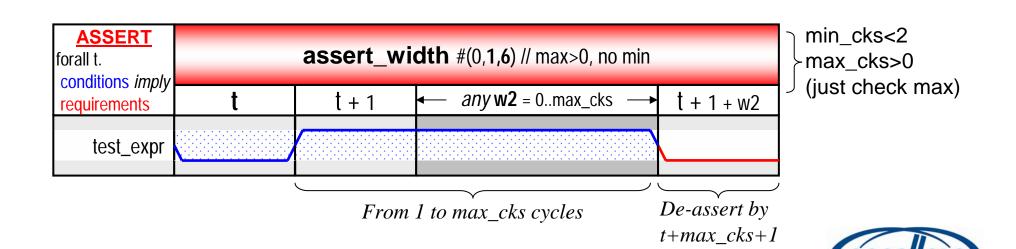
Both timing diagrams are incomplete for "ignore new start", as start_event=0 will mask some errors!



#(severity_level, min_cks, max_cks, property_type, msg, coverage_level)
u1 (clk, reset n, test expr)



Exactly min cks cycles

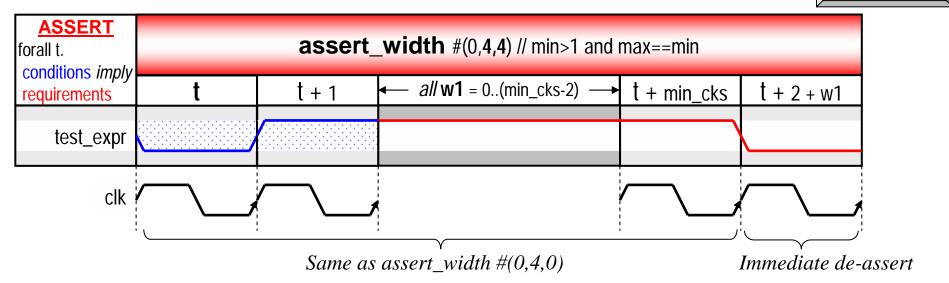


(page 2 of 2)

#(severity_level, min_cks, max_cks, property_type, msg, coverage_level)
u1 (clk, reset_n, test_expr)

test_expr must hold for between min_cks and max_cks cycles

n-Cycles



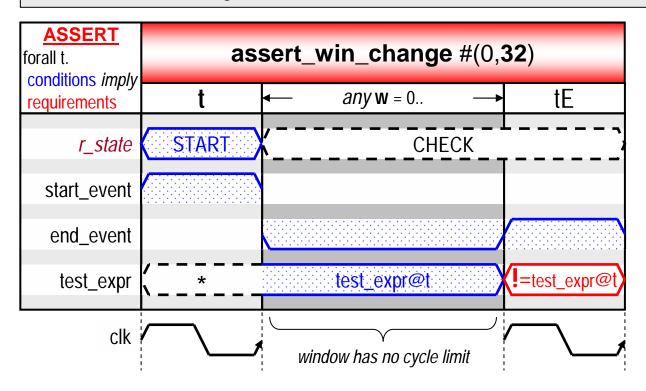
ASSERT forall t. conditions imply	assert_width #(0,4,6) // min>1 and max>min					
requirements	t	t + 1	← all w1 →	t + min_cks	← any w3 →	t + 2 + w1 + w3
test_expr						
		(0(min_cks-2)		0(max-min)	De-assert by t+max_cks+1

assert_win_change

#(severity_level, width, property_type, msg, coverage_level)
u1 (clk, reset_n, start_event, test_expr, end_event)

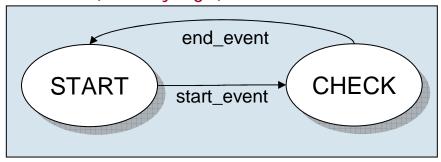
test_expr must change between start_event and end_event

Event-bound



Will pass if test_expr changes at *any* cycle during window: t+1, ...
Fails if test_expr is stable for all cycles after start.

r_state (auxiliary logic)



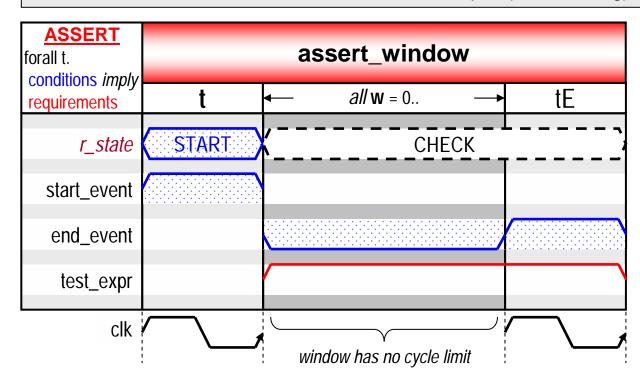


assert_window

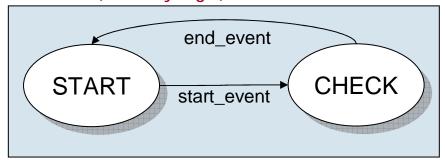
#(severity_level, property_type, msg, coverage_level)
u1 (clk, reset_n, start_event, test_expr, end_event)

test_expr must hold after the start_event and up to (and including) the end_event

Event-bound



r_state (auxiliary logic)



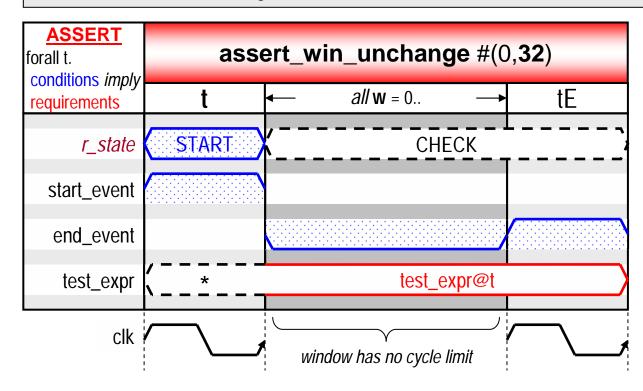


assert_win_unchange

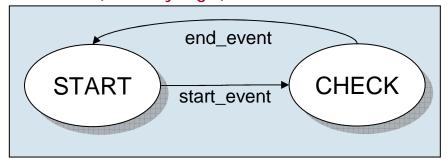
#(severity_level, width, property_type, msg, coverage_level)
u1 (clk, reset_n, start_event, test_expr, end_event)

test_expr must not change between start_event and end_event

Event-bound



r_state (auxiliary logic)





assert_zero_one_hot

#(severity_level, width, property_type, msg, coverage_level)
ul (clk, reset_n, test_expr)

test_expr must be one-hot or zero, i.e. at most one bit set high

ASSERT forall t. conditions imply	assert_ zero_one_hot		
requirements	t		
test_expr	0 one_hot		
clk			

