

Objective: To describe a scenario, simulate with an architecture and analyze the related results

The purpose of this lab is to describe a system scenario starting from an automatic skeleton, then simulate it with a preconfigured architecture and analyze the exploration results.

Procedure:

PART 1: create and refine a scenario skeleton from an existing architecture

- Open the Lab8.pdd file in the FlexNoC GUI by entering oFlexNoC -p FlexNoC_Lab8.pdd&ö at the command prompt.
- 2. In the FlexNoC project panel select the :step1øarchitecture within the Architecture folder, then from the Tools menu execute FlexExploration->Export Skeleton Script
 - i. Save it with the given default name
- 3. Open the generated script with a text editor
- 4. Refine the scenario according to the following traffic description

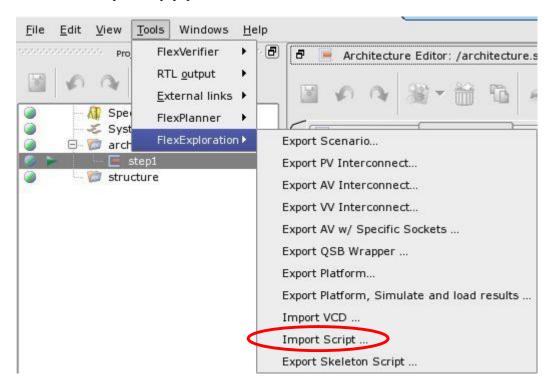
	Queue depth							
Process	аорит	From	То	Address generation	Burst Size	Avg Read BW	Avg Write BW	Efficiency
1	256 B	display.scan	DRAM	random	64 bytes	80 MB/s	0	1
±	1024B	display.rd0	±q	£	64 bytes	320 MB/s	0	1
±	1024B	display.rd1	±q	£	64 bytes	320 MB/s	0	1
±	1024B	display.wr	±q	£	64 bytes	0	320 MB/s	1
±	64 B	modem.cpu (*)	±q	£	32 bytes	40 MB/s	40 MB/s	0.7
±	1024B	modem.data	±q	£	32 bytes	300 MB/s	0	1
±	2048B	periph.sata	±q	£	1024 bytes	300 MB/s	0	0
±	2048B	periph.eth	±q	£	128 bytes	0	300 MB/s	0
±	16 kB	image.shade (**)	±q	£	256 bytes	400 MB/s	400 MB/s0	8.0
±	16 kB	image.texture (**)	±q	£	256 bytes	250 MB/s	250 MB/s0	8.0
±	16 kB	image.motion (**)	±q	£	256 bytes	175 MB/s	175 MB/s0	0.8
±	16 kB	image.raster (**)	£q	£	256 bytes	325 MB/s	325 MB/s0	0.8
4	128 B	cpu.data (***)	£q	£	128 bytes	(***)	(***)	0
4	64 B	cpu.inst (***)	£q	£	64 bytes	(***)	(***)	0

- i. (*) for modem.cpu create a procedure performing a write-back cache data refill (including block-write to memory) and apply a global space throughput equal to Read BW + Write BW
- ii. (**) create just a single process queuing on all the image.xx sockets; it has to choose among four sub-procedures, each one sending transactions to a single/different image.xx socket; the weight of each procedure has to be set equal to Read BW + Write BW (integer positive value, no metric suffix) of the associated socket; the whole procedure has to be spaced with an average (poisson) throughput of 2.3 GBytes/s
 - a. Each sub-procedure has at its turn to choose beween a Read and a Write with the same weight
- iii. (***) model a multi-threaded cpu using 4 processes,
 - a. each one has a couple of queues respectively associated to cpu.data and cpu.inst sockets
 - b. each process chooses (with the same weight) among a data-miss on socket cpu.data (block-reading from memory only), a write-back data-miss on socket cpu.data (including block-write to memory) and a instruction-miss on socket cpu.inst(block-reading from memory only);
 - c. the whole choose procedure has to be spaced with an average (poisson) throughput of 250 MBytes/s and, after that, be repeated to generate a volume of 1 MByte

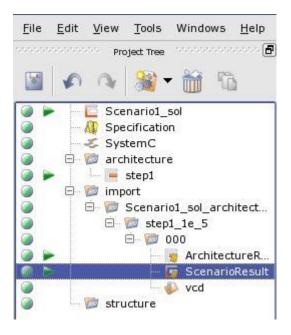
PART 2: simulate the new scenario with the existing step1 architecture and inspect the results



- 1. Import the new refined scenario
 - i. From the Tools menu invoke the command FlexExploration -> Import Script and select your refined script in the popup window

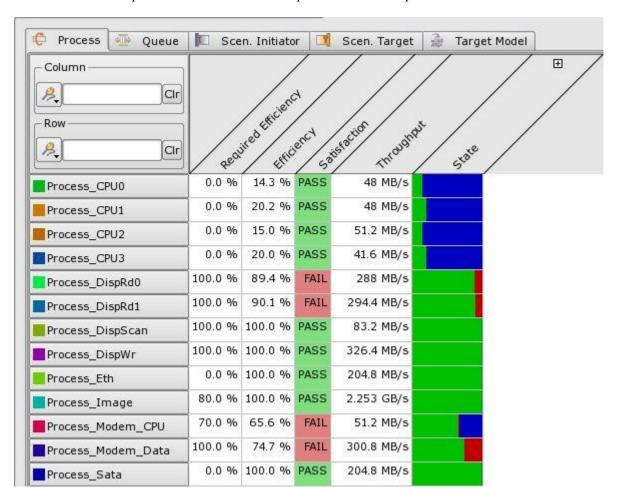


- ii. Once the new scenario is imported, from the Tools menu select FlexExploration -> Export Platform, Simulate and load results, select the imported scenario and the step1 architecture from the popup windows and leave the simulation time at the default value
- iii. A new õimportö folder is created including simulation results providing details for the Scenario and the Architecture

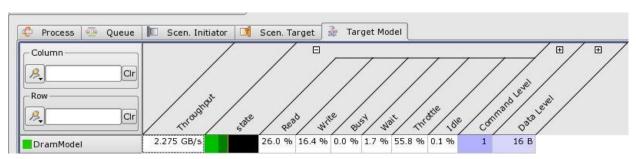




iv. Open the ScenarioResult and inspect the Process tab panel:



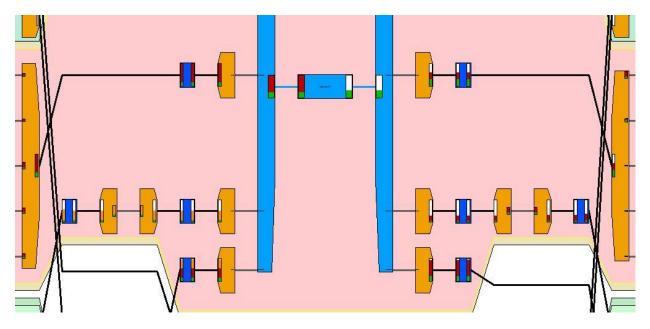
- a. What is going wrong there?
- v. Inspect the Target Model tab panel and inspect the DramModel state:



a. There is a lot of black in the state bar-graph: what is the throttle and why it is so high?



vi. Now, still within the import folder, open the ArchitectureResult and inspect the Topology panel



- a. What does it mean the red color in the vertical bar-graphs
- b. And the orange parts?
- c. How can I refine this design to match the required efficiencies?



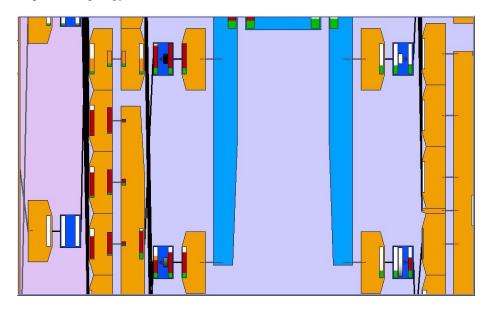
Objective: To refine a NoC architecture and match performance requirements

The purpose of this lab is to apply NoC refinement guidelines to improve the NoC bandwidth usage, increase the DRAM efficiency and guarantee the performance requirements of IPs (bandwidth and latency).

Procedure:

PART 1: create and refine step2 architecture removing congestion and burst holes

- 1. Re-open the Lab8 file in the FlexNoC GUI by entering oFlexNoC -p FlexNoC_Lab8.pdd&ö at the command prompt.
- 2. In the FlexNoC project panel select the -step1øarchitecture and duplicate it (right_click->Duplicate)
- 3. Inspect the Architecture results of Lab8 simulation (regenerate it in case you do not have it anymore simulating step1 with your imported scenario)
- 4. In step2 architecture
 - i. Remove congestion in the response network responsible of DRAM performance decrease
 - a. Inspect the Architecture result topology view (step 3.) and, for each link in response network where the BUSY state (RED) is high, enable FIFO buffering in the corresponding link of :step2ø architecture; set each fifo size to allow storing one or two largest packets flowing thorough this link;
 - ii. Remove bubbles from traffic feeding the DRAM
 - a. Similar to step 4.i.a but now related to links in the request network (just in front of the scheduler) where the WAIT states (ORANGE) are present; enable RATE_ADAPTER buffering function
 - To limit latency insertion due to rate adaptation, specify a suitable defaultThroughputRatio: this has to be set as the ratio ThroughputOut/ThroughputIn where ThroughputOut is the bandwidht peak at the rate adapter output (clk * bus_width) and ThroughputIn is the data throughput of the sending IP.
- 5. Simulate this new refined :step2øarchitecture with your scenario script (Tools->FlexExploration->Export Platform, Simulate and Load Results)
 - i. inspect the topology view of this new architecture results



- a. did the WAIT states disappear from the output bar-graphs of the schedulerøs request links as shown above?
- b. did the BUSY states disappear from the input bar-graphs of the schedulerøs response links as shown above?

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PART 2: refine step2 architecture's QoS instructing the memory scheduler

6. Remember on Lab8, the first exploration was showing the Target Model suffering of a considerable throttling time (the time spent by the controller in internal DRAM penalties)



- 7. Let stry to reduce as much as possible the DDR controller penalties and so enhance the DRAM efficiency suitably configuring the FlexMem scheduler
 - i. Open :step2øarchitecture, go to the Performance/Scheduler tab panel, click on the criteria>customize and in the pop up menu add two new arbitration criteria in order to improve
 DRAM memory effciency
 - a. Hint: try enabling BANK IDLE PAGE HIT and/or RW criteria
 - ii. Re-simulate this :step2øarchitecture with your scenario: does the target throttle decrease?
 - iii. Are all the efficiencies matched in the Processøresult panel?

PART 3: create and refine step3 architecture to improve CPU latency and match bandwidth requirements introducing QoS

- 8. Let stry now to introduce a QoS scheme based on pressure/hurry priority and capable of ensuring real-time answering for traffic to/from video, guarantying long-term throughput for display and low latency figure for both cpu and modem
 - i. The idea consists in classifying initiator traffics according to the following table

socket	Traffic class	QoS generator	Pressure (Max/Min)
display.scan	RT-GT		2/1
display.rd0	RT-GT		2/1
display.rd1	RT-GT		2/1
display.wr	RT-GT		2/1
image.shade	RT-GT		2/1
image.texture	RT-GT		2/1
image.motion	RT-GT		2/1
image.raster	RT-GT		2/1
cpu.inst	LL		3/1
cpu.data	LL		3/1
modem.cpu	GT		3/3
modem.data	GT		3/3

- a. Real-time guaranteed throughput sockets (RT-GT) will see their priority being increased dynamically to a maximum value whenever it is required, either directly through the hurry sideband input (for those IPs that can drive it) or through a bandwidth regulator;
- b. Modem, supposed to be guaranteed throughput (GT), will always have the highest priority;
- c. Low latency (LL) traffic IPs will have lower fixed priority so, when nobody in the other classes is raising its pressure for urgent bandwidth or accessing to the shared resource, they will be served first;
- ii. in the FlexNoC project panel create :step3øarchitecture from :step2ø(select this last and duplicate it))
- iii. Introduce QoS generators of type FIXED for LL traffic IPs as shown in the previous table

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- a. Open :step3øarchitecture and in the Generic NIU tab panel enable a FIXED QoS generator for each one of the three mentioned sockets
- b. Set the readUrgency to 3 and writeUrgency to 1 (higher priority for reads)
- iv. Similarly introduce QoS generators of type FIXED for modem.data, modem.cpu
 - a. Set both the readUrgency and writeUrgency to 3 (always higher priority)
- v. Assuming image.x IPs cannot directly drive the NoC with a priority signal, introduce a QoS generators of type Regulator for each one of them
 - a. set the priority1 (max priority) to 2 and priority0 to 1
 - b. set the bandwidth parameter as the 80% of the required value in order not to keep the driven pressure always to the highest value
 - c. leave the saturation to a value of 1Kbytes
- vi. To simulate dynamic increase/decrease of display.x pressure, modify your scenario script
 - a. For each display queue configure the hurryThreshold parameter in order to let the hurry priority being driven at least to 1 (all the time) and directly increased to 2 whenever the threshold of half the queueøs depth is reached
- vii. Finally dongt forget to add three more architecture criteria in the scheduler to take in count the dynamic pressure during arbitration
 - a. Try setting these three new criteria after the RW one, in the order URG3, URG2, URG1
- 9. Simulate the updated scenario with the \(\distriction{\text{-step3}\phi\) architecture
 - i. Do the scenario process results show all matching efficiencies?
 - ii. Check the Queue Full Latency result: are all the CPU achieving the smallest latency figure compared to those of the other IPs?



Objective: to implement a power domain partitioning over a specified SoC

The purpose of this lab is to learn how to define and introduce power domains on an existing SoC and the implement a power organization scheme using power bundles, controllers and disconnect modules.

Procedure:

PART 1: Specify a power domain partitioning

Starting from the SoC/NoC designed in FlexNoC_Power_Lab.pdd file, we want to partition it according to the following power organization scheme

NIU

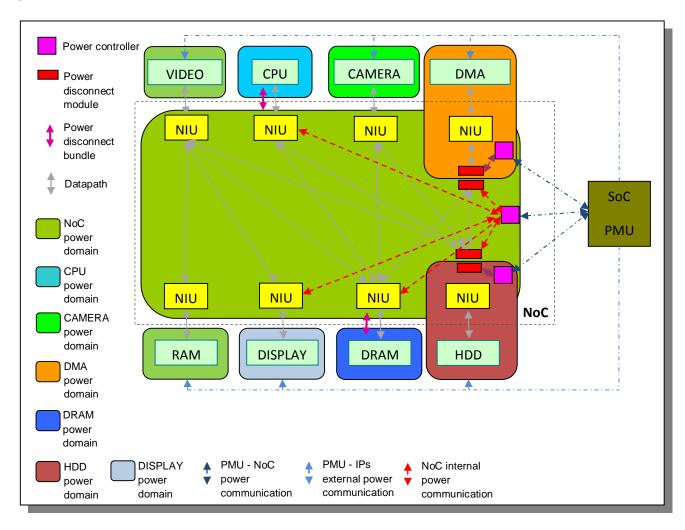


Fig.1 Power domain partitioning

We will define these 7 different power domains shown above in the existing SoC/NoC organization; power saving will occur on each one of them through either clock cut-off or power supply switch-off.

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Please note that:

- 1. All the external IPs have their own dedicated power domain, except for VIDEO and RAM that are in the NoC power domain
- 2. CPU and DRAM interfaces support each one a power disconnect bundle, a dedicated communication ports allowing IP/NoC power disconnection
- 3. CAMERA and DISPLAY have each one its own dedicated power domain but they do not support a power disconnect bundle;
- 4. DMA and HDD are placed each one in a dedicated power domain including also the attached NIU; this kind of power configuration does not require a power bundle at the socket interface between the IP and its NIU
- 5. Finally, VIDEO and RAM are placed in the same power domain as the NoC

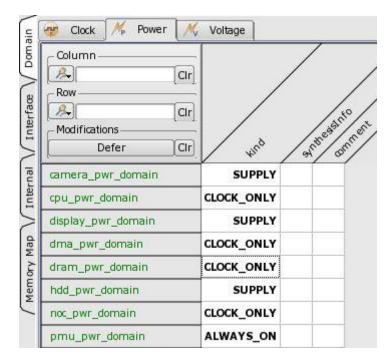
IMPORTANT: it is the PMU responsibility (SoC Power Management Unit, external to the NoC) to externally communicate with every IP not supporting a power disconnect bundle and ensuring

- I. fencing of further transaction sending (traffic to be stopped) and draining of pending transactions (all pending responses to be received back)
- II. completion of all the pending responses within every target IP (DISPLAY,DRAM) before to be switched off

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- 1. Open the power Lab file in the FlexNoC GUI by entering **öFlexNoC -p** FlexNoC_Power_Lab.pdd&ö at the command prompt.
- 2. Open the Specification Editor clicking twice on the õSpecificationö item in the Project Tree
- 3. Specifying power domains
 - i. In the õDomainö view select the õPowerö page
 - ii. Create a new Power domain (right_click->New->Power) and give it the name of onoc_pwr_domaino
 - a. Select õCLOCK_ONLYö in the kind column; this will inform the tool that this domain will only implement clock cutting (no power supply cut-off)
 - iii. As already done at step 3.ii, letøs now create new power domains respectively for CPU, DMA, CAMERA, DISPLAY, DRAM and HDD
 - iv. Please set õkindö to CLOCK_ONLY for all the IPs except HDD, CAMERA and DISPLAY for which SUPPLY management is required
 - v. Finally letøs introduce a power domain for the PMU and letøs set it as being õALWAYS_ONö

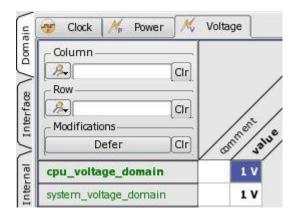


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4. Defining the voltage domain

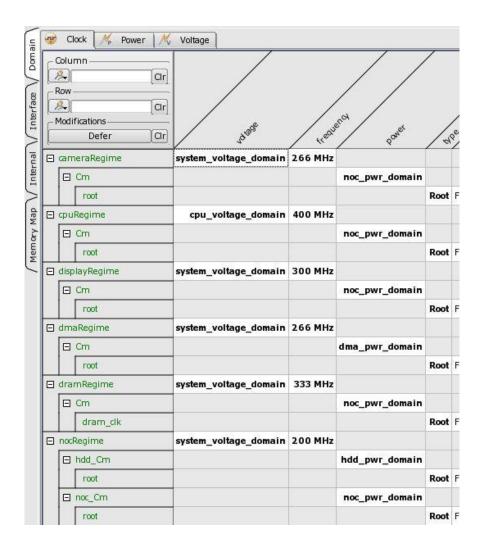
- i. When power domains are specified into the NoC, they need to be associated with a voltage domain.
- ii. Go to Domain view / Voltage page
- iii. Let screate two voltage domains, one for the cpu and one for the rest of the system. Right click, new voltage. Name it system_voltage_domain and set the value to 1 V.
- iv. Select it, right click then õduplicateö, rename it as cpu_voltage_domain and set the value to 1 V



5. Associating clock managers to power domains

- i. Preface: clock managers distribute clocks and resets to NoC components (NIUs and transport components) within clock domains. Please note that NIUs are synchronous to their connected IPs and also that every NIU interface (socket) is driven/associated of course by/to a clock (look at õInterfaceö view). Associating a clock manager to a power domain means that all the NoC components driven by this clock manager must belong to the specified power domain and so they will have the same power state (on-off).
- ii. Letøs proceed by associating every clock manager to a power domain; this important information will tell the tool how clocks are distributed in the power domain partitioning scheme. For this reason letøs select the õDomainö view and the õClockö page in the Specification editor
 - a. According to Fig.1, the CPU, DRAM, SRAM, VIDEO, DISPLAY and CAMERA NIUs are supposed to belong to the NoC power domain, for this reason in column õpowerö letøs select noc_pwr_domain for all of the associated clock manager
 - b. Of course, NoC transport components driven by nocRegime.noc_Cm clock managerøs output belong to the NoC power domain so we can do the same setting for this clock manager
 - c. Conversely, the DMA and HDD NIUs belong respectively to DMA and HDD IP power domains, so dma_pwr_domain and hdd_pwr_domain must instead be selected in the power column.
 - d. Note VIDEO and SRAM do not have a specific clock manager as they are supposed to be in the same clock and power domain than the main NoC
- iii. Finally, set the voltage domain to system_voltage_domain for all of the regimes except for the cpu one, for which cpu_voltage_domain has to be selected





6. Associating IPs to power domains

- i. Now we need to refine our power specification by telling the tool what power domain every IP belongs to:
 - a. In the õInterfaceö view, select the Socket page and expand the õpowerö parameter subgroup
 - b. Each IP belongs to a specific power domain; let@s select the right power domain association in the õIPpowerDomainö column (CPU to cpu_pwr_domain, DMA to dma_pwr_domain, etc)



c. setting the \tilde{o} disconnect \ddot{o} parameter

1. This parameter can force the instance of logic for power communication/disconnection, it can have the following values

	n/disconnection, it can have the following values
Disconnect value	Comment
None	No power bundle, no disconnect logic and active indication, no fencing/draining.
SYSTEM	Similar to previous one but required when the IP does not share the same power domain than the NIU:
	power communication must be provided externally to the NoC between
	the SoC Power Manager and the IP;
	fencing and draining must be performed by the initiator IP when the SoC Power Manager requests either IP or the NoC (or both) to be switched
	off
None with flush	Only at initiator side: no power bundle, no disconnect logic and active
	indication, no fencing
	Draining is only performed for posted writes
	The initiator IP must perform fencing and draining whenever the PMU
	notifies that either the IP itself or the attached NoC has to be switched
CVCTEM with fluck	off (before Idle request is sent to the NoC power controller).
SYSTEM with flush	Similar to previous one but available only when the initiator IP and its NIU do not share the same power domain
ARTERIS / OCP	A power bundle with the selected power protocol is provided at the
	socket interface to negotiate the power state of the socket connection
	<u>Initiator side</u> : fencing and draining must be performed by the initiator
	IP when a NoC disconnection request occurs through the power bundle
	<u>Target side</u> : fencing and draining are performed by the target NIU; the
	target IP must guarantee response completion before to disconnect;
	disconnect policy (Error, Stall) can be chosen statically at configuration
	time or dynamically through a suitable input; Active output indication is
	provided to either indicate socket activity (when it is not disconnected) or
	presence of a pending request when Stall mode is selected and the
	target IP is disconnected
MULTIPORT_ARTERIS/ OCP	Same as previous but only for multi-socket target NIUs
None with protection	Only at target side: no power bundle, but fencing and draining performed
_	by the target NIU under control of the NoC power controller
	The target IP must guarantee response completion before to be
	switched off
SYSTEM with	Similar to previous one but only when the targetIP and its NIU do not
protection	share the same power domain; active indication is available

It has to be set accordingly to the following rules

a. <u>Initiator side</u>

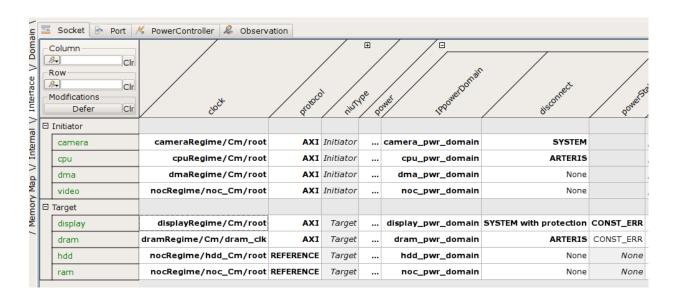
Conditions	Disconnect choice
the initiator NIU and the IP are in the same ClockOnly/SUPPLY power domain	None or None with flush if the socket has posted writes.
the initiator NIU is on an AlwaysOn power domain	None
the initiator NIU and the IP are on a different ClockOnly/SUPPLY power domain	ARTERIS OCP OCP_TI SYSTEM or SYSTEM with flush if the socket has posted writes

b. Target side

Conditions	Disconnect choice
the target NIU and the IP are in the same	None or None with protection
ClockOnly/SUPPLY power domain	-
the target NIU is on a different AlwaysOn power	None
domain	
the target NIU and the targetIP are on a	ARTERIS
different ClockOnly/SUPPLY power domain	• OCP
	OCP TI
	 MULTIPORT_ARTERIS/OCP if the

tannatia a multipoplat
target is a multisocket.
 SYSTEM or SYSTEM with
protection

- 2. In the columns õdisconnectö we must specify a disconnect setting for each socket; letøs select the õARTERISÖ one (this will provide power bundles made of õSlvRdyÖ and õSocketConö signals) for the CPU and the DRAM, õSYSTEMÖ and õSYSTEM with protectionö respectively for the CAMERA and DISPLAY and õNoneö for all the others
- d. Finally at the õpowerStallö column we can decide the behavior of the power disconnect module embedded in the DRAM target NIU when the DRAM is disconnected; possible values are
 - CONST_ERR: always reply with error whenever a request arrives while DRAM is off
 - CONST_STALL: always stall any incoming request to DRAM while it is off; PwrActive output is provided to signal to the PMU the controlled domain (DRAM) must wakeup
 - 3. SYNCH: a õPwrStallö input (to be driven by the PMU) to the target disconnect interface decides the disconnect behavior (ERR, STALL); with this setting it is supposed to be synchronous with the PMU clock domain
 - 4. ASYNCH: similar to previous setting but now õPwrStallö input is supposed to be asynchronous with the PMU clock domain
- e. Letøs leave the default õCONST_ERRö option.



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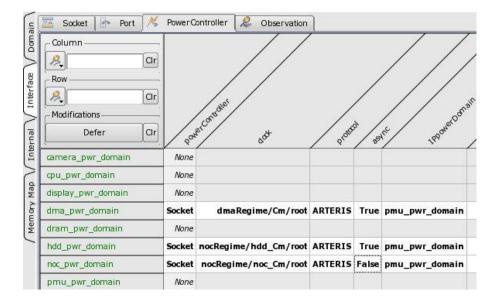
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7. Power controller settings

- i. Each power domain which is not of ALWAYS_ON type and containing NoC units is controlled by a power controller. The controller distributes Idle requests from the PMU to the power domain disconnect components (transport disconnects and NIUs) and centralizes IdleAck from the disconnect components/interfaces to the PMU. From Fig.1 we can see that the HDD, NoC and DMA power domains includes a power controller.
- ii. In the õInterfaceö view letøs select the õPowerControllerö page
 - a. For each one of the DMA, HDD and NoC power domains let see enable a power controller by setting the õpowerControllerö parameter to Socket.

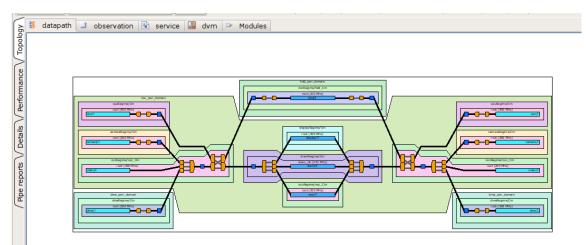
There are 2 possibilities:

- 1. Socket. In this case IdleReq, IdleAck and Idle signals will be present on the NoC interface ports for connection to the power manager.
- 2. Software. This option can only be used if there are only targets to be disconnected in the power domain. In this case, there will be a IdleReq/IdleAck register pair per slave. IdleReq is a software accessible writable register, and IdleAck is a readable register. When IdleReq is set to 1 and IdleAck status is 1, the corresponding target can be disconnected.
- b. Let select the clock for each power controller unit as shown in the figure below
- c. Finally let schoose the power protocol interface for the bundle between each power controller and the PMU: please select the õARTERISÖ one (protocol bundle provided with IdleReq, IdleAck and Idle signals)
- d. In the õIPpowerDomainö column let@s choose the power domain for the PMU setting õpmu_pwr_domainö for the whole column.
- e. Finally we need to inform the tool if re-synchronization is required between power controllers and the PMU by setting the õasynchö parameter either to True or to False. For this letes suppose the PMU is synchronous to the NoC regime and asynchronous with all the others.

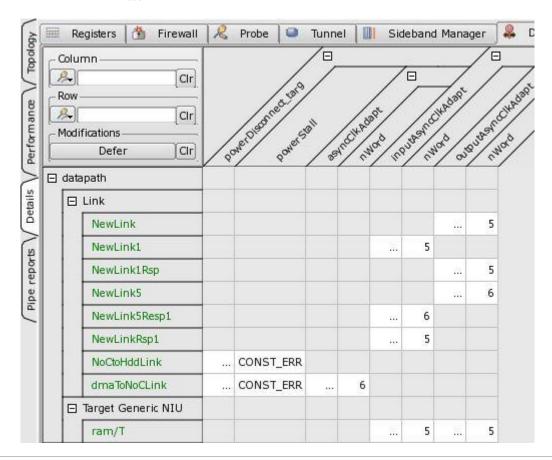


PART 2: Architecture view

1. In the Project tree let@s open the oArchitectureo item clicking it twice.



- i. You can inspect the power domain partitioning enabling õPowerö in the õSector displayö menu
- ii. Let s now have a look to the architecture details and configure the behavior for transport disconnect units
 - a. In the Architecture browser, select the õDetailsö major panel and the õDomain Crossingö tab



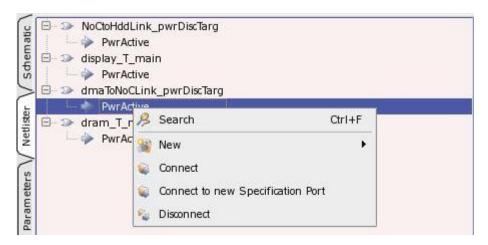
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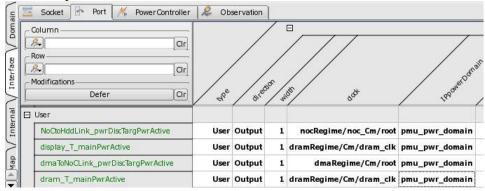
b. Here details for transport links are provided, in particular you can change õpowerStallö setting for power disconnect modules within õdmaToNocLinkö and õNoCtoHddLinkö; letøs keep current setting for which error responses are generated in case of incoming requests toward a power domain that is disconnected.

PART 3: connecting tactical ports

- 1. Finally, we need to connect Structure tactical outputs like the õPwrActiveö from the DRAM and the DISPLAY NIUs to the NoC top level; these signals provide activity indication when the connection is ON and a WAKEUP indication to the PMU when the target power domain is OFF.
 - i. In the Project panel open the õStructureö item
 - ii. In the õNetlisterö major panel select every PwrActive output and connect it to a port at the top level through right_click->Connect to New Specification Port



- 2. Some parameter setting is still missing for the new created ports
 - i. In the Specification Editor, open the Interface view at the Port page
 - ii. Set the IPpowerDomain parameter to pmu_pwr_domain for every new created Active output port

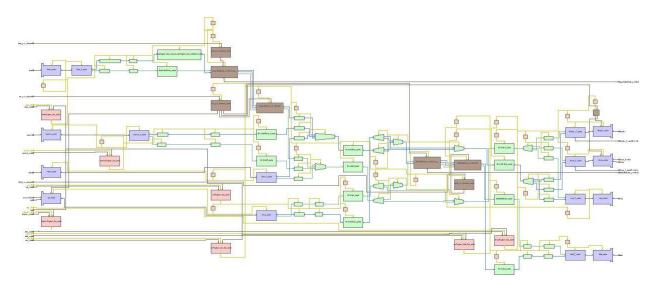


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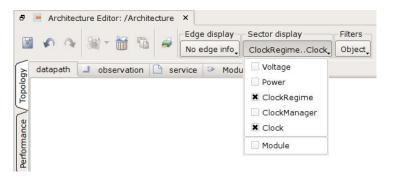
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PART 4: inspecting the NoC Structure: modules

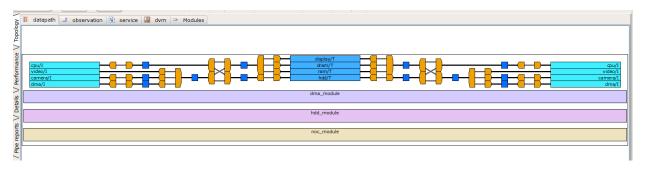
1. In the õSchematicö major panel of the Structure view a view of the NoC structure is provided:



- i. You can identify the power disconnect modules in the brown boxes
- 2. For a better design organization let@s introduce one module for DMA, HDD and NoC power domains
 - i. In the Architecture view, change the sector display from õClockRegime..Clockö to õModuleö (deselect õClockRegimeö and õClockö sector display and select the õModuleö one)



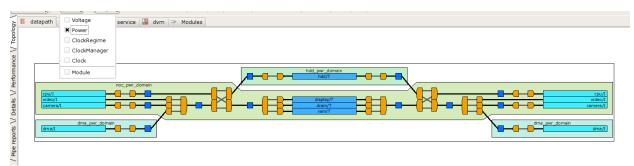
- ii. Let s create a new module for dma_power_domain
 - a. Right-click->New->Module
 - b. Give it a suitable name (example õdma_modö)
- iii. repeat steps a,b to create two more modules respectively for noc_pwr_domain and hdd_power_domain



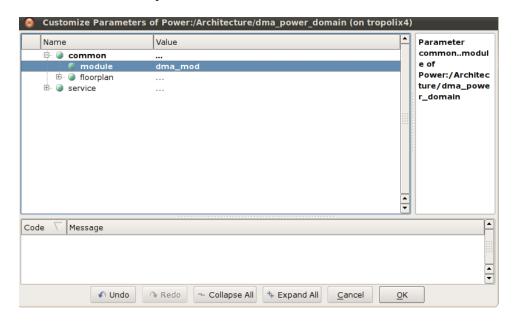
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iv. Letøs now change the sector display from õModuleö to õPowerö



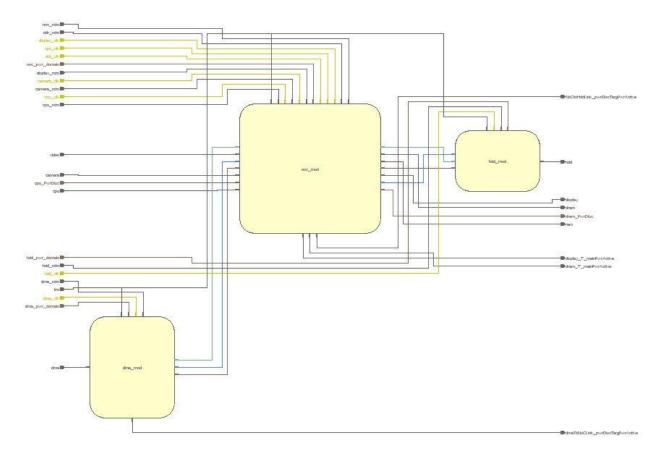
- v. Let sassociate each new created module to the corresponding power domain: let start from dma_pwr_domain
 - a. Select the corresponding power domain and double click on it
 - 1. this opens the related customizer box



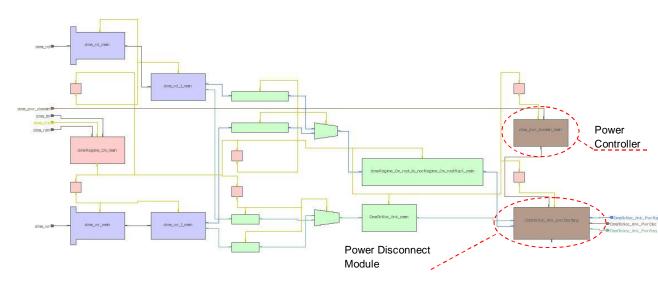
- 2. select the corresponding module
- b. repeat steps 1,2 for noc_pwr_domain and hdd_pwr_domain too.
- vi. Finally, let@s inspect the Structure view, it now shows the new three modules

Arter*is*

FlexNoC Lab-13



a. Double clicking on one of them, for example the DMA one, we can now easily distinguish power components like the power controller and the power target disconnect modules.



1. Selecting the target power disconnect modules in the view before and inspecting the õInformationö panel you can see



HwIpModule DmaToNoc_link_pwrDiscTarg

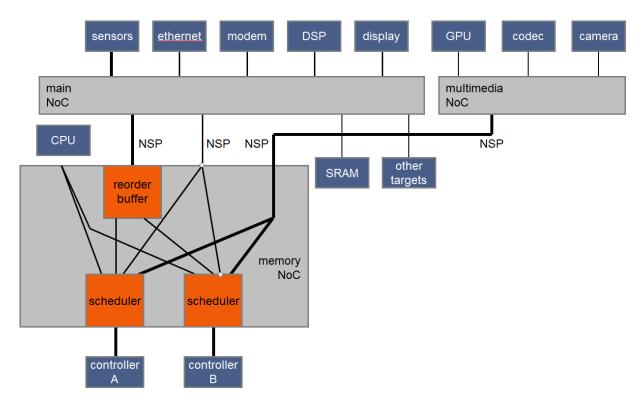
Synthetized IPs:

- PwrDiscTarg
- ReqPwrClkAdapt_Async
- RspPwrClkAdapt_Async

It includes the PwrDiscTarg hardware functionality as well the asynchronous clock adapters required at the boundaries of this domain.

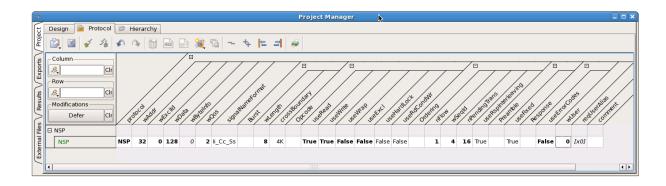
End of Power Lab

In this lab you will create a system NoC, multimedia NoC, and memory NoCs for a chip with two interleaved memory interfaces. You will configure a NoC composition with all three. You will connect the NoCs using NSP socket interfaces. You will create a low-latency path from CPU to DRAM.

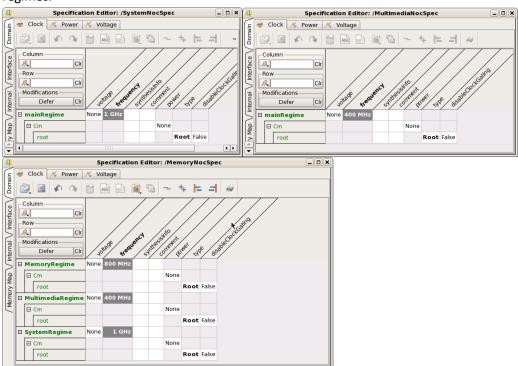


Step 1. Define a Reference Protocol for NSP with

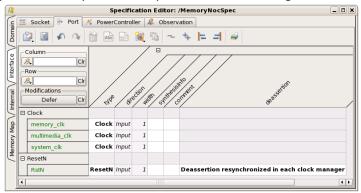
- a. 32-bit address
- b. no exclusive ID support
- c. 128 bit data
- d. 2 bits of binary-coded QoS
- e. 8 burst length bits
- f. support for reads and writes
- g. no support for wrapping bursts
- h. no support for exclusive access
- i. 1 flow
- j. 4 sequence ID bits
- k. 16 pending transactions
- I. no error code support
- m. no user bits



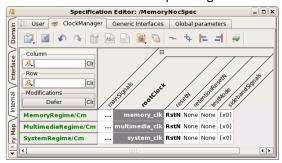
Step 2. Create specifications for a System NoC at 1 GHz, Multimedia NoC at 400 MHz, and Memory NoC with 1 GHz system, 400 MHz multimedia, and 800 MHz memory clock regimes.



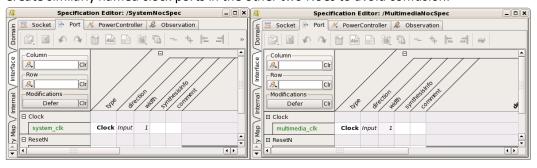
Step 3. Create separate clock ports for each clock regime in the memory NoC.



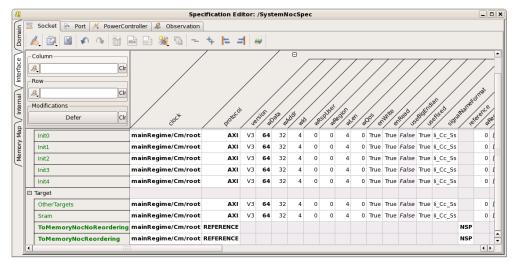
and connect them to corresponding clock managers.



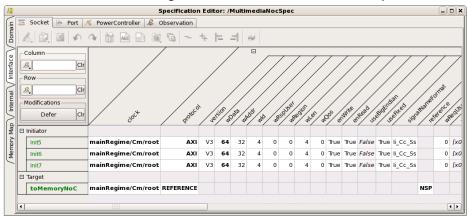
Create similarly named clock ports in the other two NoCs to avoid confusion.



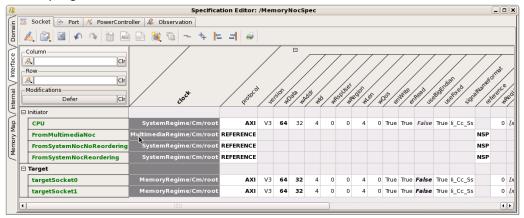
Step 4. In the system NoC create five initiator and four target sockets. Give all initiator sockets 64 bit AXI interfaces. Two targets sockets are for SRAM and for other interfaces. The other two target sockets should reference the NSP protocol. One will be connected to a reorder buffer and the other will have a direct connection to memory.



In the multimedia NoC create three initiator and one target sockets. Give all initiator sockets 64 bit AXI interfaces. The target socket should reference the NSP protocol.



In the memory NoC create four initiator and two target sockets. Give one initiator socket a 64 bit AXI interface for a CPU in the system clock regime. The other three initiator sockets should reference the NSP protocol, one for the multimedia NoC connection in the multimedia clock regime and the other two for two system NoC connections in the system clock regime. Give the two target sockets 64 bit AXI interfaces for DRAM controllers in the memory regime.



Specification Editor: /MemoryNocSpec Socket Port % PowerController & Observation 🔏 🔯 📓 🖍 🤏 🛗 🖦 🗃 🍃 -Column B Row B. Clr Modifications Memory CDU CDU ELLOW SystemRegime/Cm/root [x0] False [x0] FromMultimediaNoc MultimediaRegime/Cm/root REFERENCE Initiator [x0] False False FromSystemNocNoReordering SystemRegime/Cm/root REFERENCE Initiator [x0] False False True False FromSystemNocReordering SystemRegime/Cm/root REFERENCE Initiator [x0] targetSocket0 MemoryRegime/Cm/root AXI Target [x0] Not supported

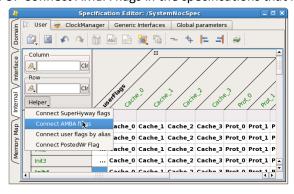
Enable a reorder buffer on the Reordering socket of the memory NoC.

Step 5. Connect AMBA flags in the specifications that have both AXI initiators and AXI targets.

AXI Target

[x0]

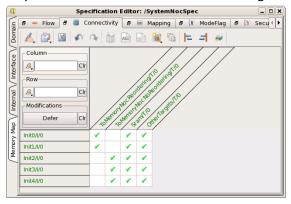
Not supported



MemoryRegime/Cm/root

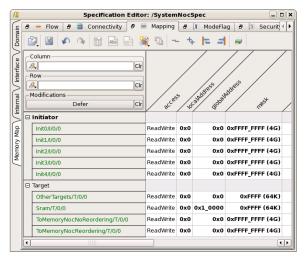
targetSocket1

Step 6. In the system NoC connect only initiators 0 and 1 to the reordering NSP target. Connect only the other initiators to the no reordering NSP target.

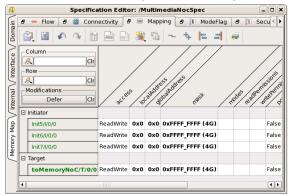


Step 7. Give all initiators a view of a full 4GB address space.

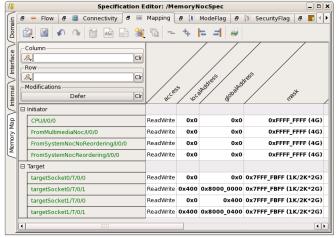
In the system NoC give the SRAM and other targets each a 64KB address space. Give the NSP memory target interfaces all of the remaining 4GB address space.



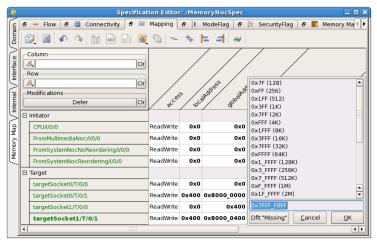
In the multimedia NoC give the one target the full 4G address range.



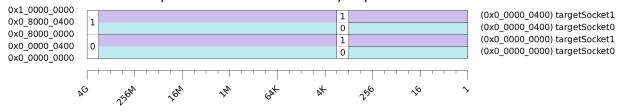
In the memory NoC set up interleaved memory address ranges for two 2GB memories interleaved on 1KB stripes.



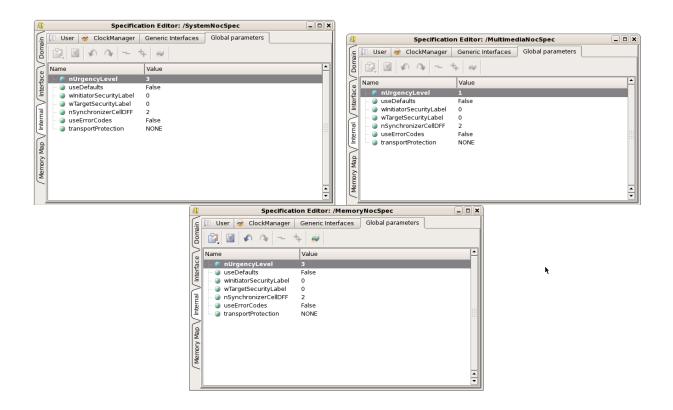
Do this by editing the address range masks for each mapping to leave address bit 10 masked to a zero.



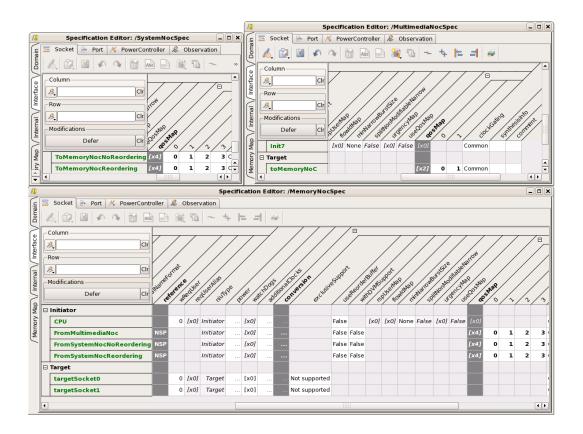
Note that there must be two mappings for each target, one in the upper and one in the lower half of the address space. Check this in the memory map viewer.



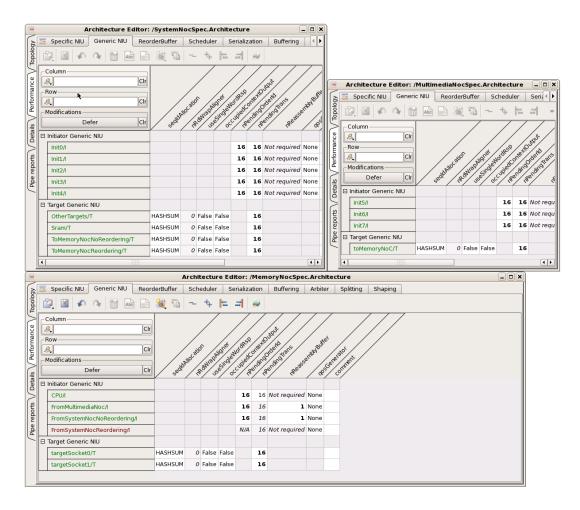
Step 8. Set four levels of urgency (nUrgencyLevel = 3) in the system and memory NoCs. Set two levels of urgency in the multimedia NoC.



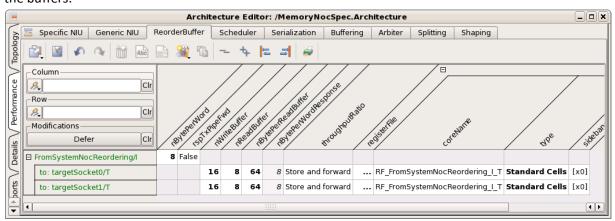
Step 9. It is necessary to map the QoS signals of the NSP interface to the QoS signals within the NoC. This enables NoCs with different numbers of QoS levels to be connected. Do this in the Socket interface conversion parameters.



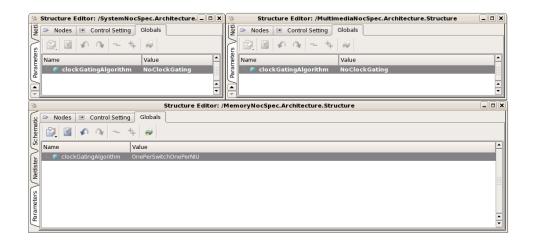
Step 10. Create architectures for each specification and set 16 for all numbers of pending transactions and order IDs.



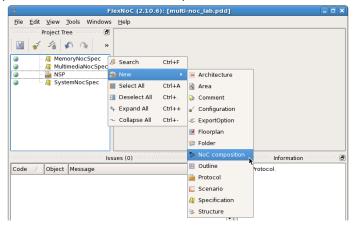
Step 11. Configure the reorder buffer in the memory NoC with 8 bytes per word, 16 write buffers, 8 read buffers of 64 bytes each per channel, and use standard cells to implement the buffers.



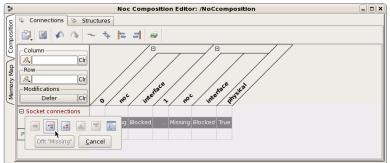
Step 12. Create structures for each NoC. For simplicity, disable clock gating in all structures.



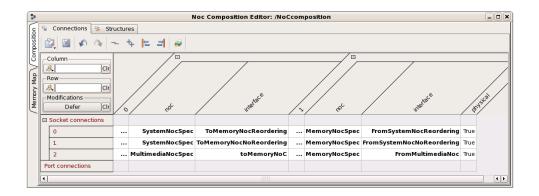
Step 13. Create a NoC composition.



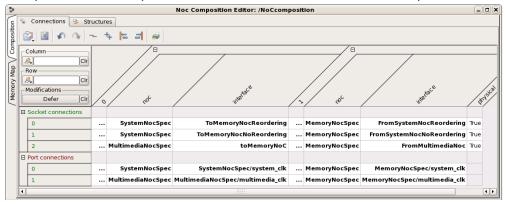
Step 14. In the NoC composition editor create three connections.



Step 15. Connect the two NSP target sockets of the system NoC to the appropriate memory NoC socket interfaces. Connect the NSP target socket of the multimedia NoC to the appropriate memory NoC initiator socket interface.



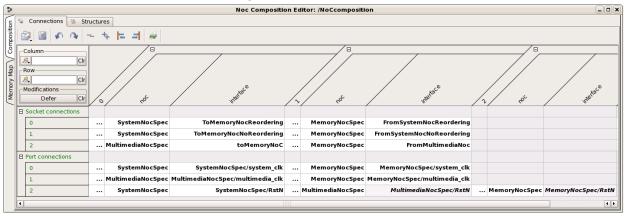
Step 16. Add two port connections to connect the corresponding clock signals between the system and memory NoC and between the multimedia and memory NoC.



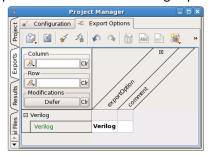
Step 17. Use the Add Child button



to create three connections of the reset signal between all three NoCs.



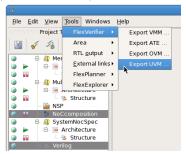
Step 18. Create a Verilog export option



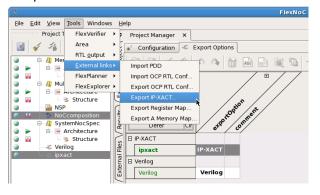
and export Verilog for the NoC composition. Review the NoCcomposition.v top level Verilog file.



Step 19. Export a UVM testbench.



Step 20. Create an IP-XACT export option and export an IP-XACT description of the NoC composition.



- Step 21. It is also possible to create scenarios for more than one NoC specification and run a FlexExplorer simulation that models traffic between the NoCs.
- Step 22. It is also possible to create a floorplan outline and run a FlexPlanner floorplan estimation that encompasses all NoCs within a NoC composition.