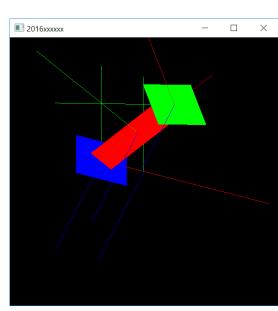
## **Daily Assignment 9**

- Starting from today's matrix stack example code,
- Add a green arm at the end of the red arm, and rotate the green arm about its local z axis like the live demo.
- Also render local frames of the blue base, red arm, green arm using drawFrame() from today's lecture slides.
- The blue base, red arm, green arm should be rendered using drawBox() from today's lecture slides.
- Set the window title to your student number.



```
def render(camAng, count):
    # ...
    # edit here
    # draw the global frame
    drawFrame()
    # blue base transformation
    glPushMatrix()
    qlTranslatef(-.5+(count %360) *.003, 0, 0)
    drawFrame()
    # blue base drawing
    glPushMatrix()
    qlScalef(.2, .2, .2)
    qlColor3ub(0, 0, 255)
    drawBox()
    glPopMatrix()
    # red arm transformation
    glPushMatrix()
    glRotatef(count %360, 0, 0, 1)
    qlTranslatef(.5, 0, .01)
    drawFrame()
    # red arm drawing
    glPushMatrix()
    glScalef(.5, .1, .1)
    qlColor3ub(255, 0, 0)
    drawBox()
    glPopMatrix()
```

```
# green arm transfomration
glPushMatrix()
glTranslatef(.5, 0, .01)
glRotatef(count%360, 0, 0, 1)
drawFrame()
glPushMatrix()
glScalef(.2, .2, .2)
glColor3ub(0, 255, 0)
drawBox()
glPopMatrix()
glPopMatrix()
qlPopMatrix()
glPopMatrix()
```