

# Decentralized and Coordinated V-f Control for Islanded Microgrids Considering DER Inadequacy and Demand Control

Buxin She<sup>1</sup>, Fangxing Li<sup>1</sup>, Hantao Cui<sup>2</sup>, Jinning Wang<sup>1</sup>, Liang Min<sup>3</sup>, Oroghene Oboreh-Snapps<sup>4</sup>, Rui Bo<sup>4</sup> <sup>1</sup> The University of Tennessee, Knoxville <sup>3</sup> Stanford University

<sup>2</sup> Oklahoma State University <sup>4</sup> Missouri University of Sci. & Tech

## Introduction

This poster presents a decentralized and coordinated control framework to regulate the output of inverter-based generations and reallocate limited DER capacity for V-f regulation.

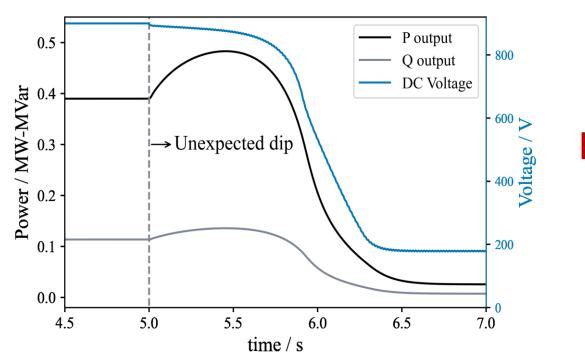


Fig. 1 DC voltage dip due to DER inadequacy

P (p.u.) **Motivate** Q (p.u.)

Fig. 2 constrained operation of inverters

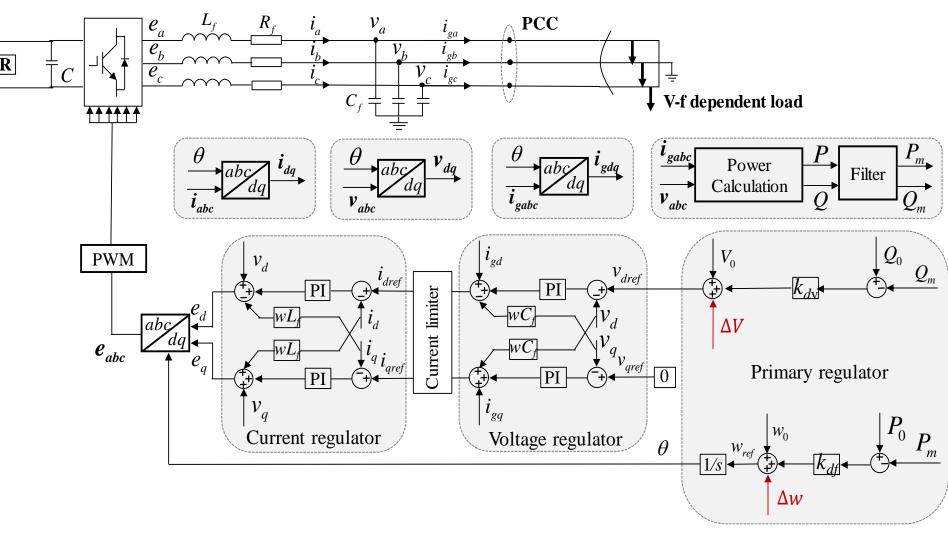


Fig. 3 Diagram of a droop-controlled GFM inverter supplying V-f dependent load

## Decentralized and Coordinated control framework

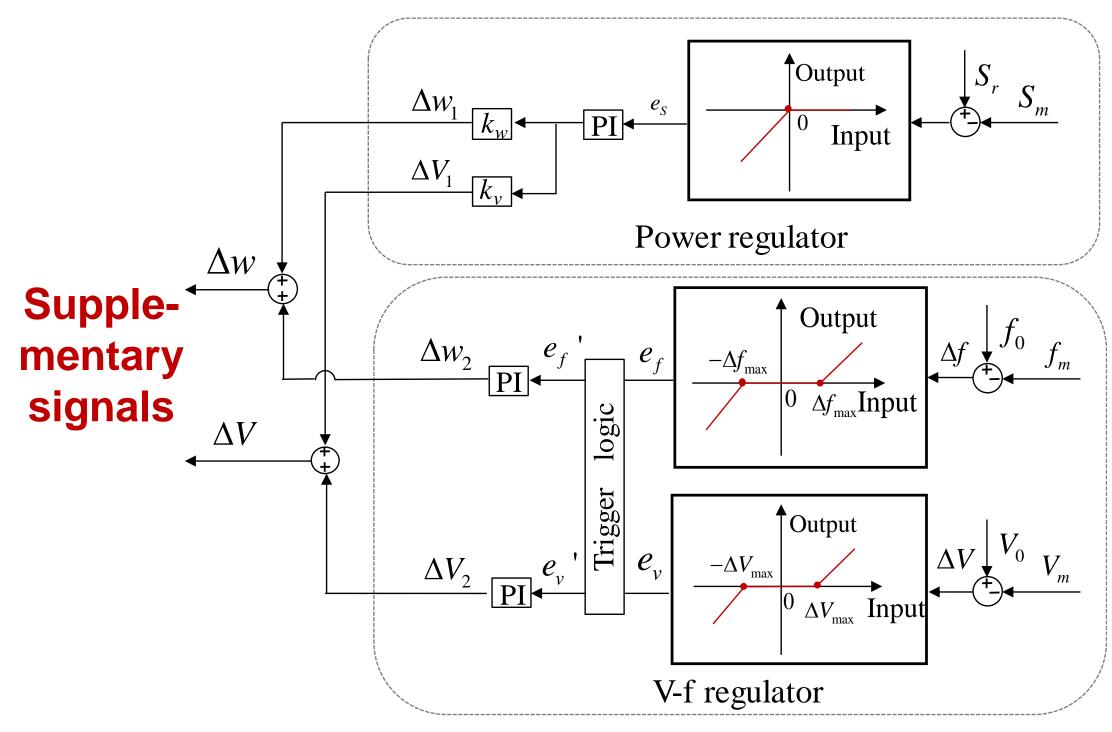


Fig. 4 Diagram of the proposed control framework

- > Power regulator generates control signals based on the error between inverter output and DER capacity, which help limit the output of grid-forming inverters
- > V-f regulator generates control signals based on voltage and frequency deviations, which reallocates limited generation for acceptable V-f deviations

# ☐ Theoretical validation

#### Droop equation

$$\begin{cases} f = f_{0,i} + k_{df} (P_{inv,i} - P_{inv0,i}) \\ V_i = V_{0,i} + k_{dv} (Q_{inv,i} - Q_{inv0,l}) \end{cases}$$

$$P_{g,i}^{2} + Q_{g,i}^{2} = S_{i}^{2}$$

V-f dependent load

$$\begin{cases} P_{l,i} = P_{l0,i} (p_1 V_i^2 + p_2 V_i + p_3) \left[ 1 + K_{pf} (f - f_0) \right] \\ Q_{l,i} = Q_{l0,i} (q_1 V_i^2 + q_2 V_i + q_3) \left[ 1 + K_{pf} (f - f_0) \right] \end{cases}$$

$$\begin{cases} P_{l0,i}' = P_0 + \Delta P \\ Q_{i0,i}' = Q_0 + \Delta Q \end{cases}$$

➤ Grid power flow

$$\begin{cases} P_{i} = P_{inv,i} + P_{l,ii} = G_{ij}V_{i}^{2} - G_{ij}\sum_{i \neq j}V_{i}V_{j}\cos\theta_{ij} - B_{ij}\sum_{i \neq j}V_{i}V_{j}\cos\theta_{ij} \\ Q_{i} = Q_{inv,i} + Q_{l,i} = G_{ij}V_{i}^{2} - G_{ij}\sum_{i \neq j}V_{i}V_{j}\cos\theta_{ij} - B_{ij}\sum_{i \neq j}V_{i}V_{j}\cos\theta_{ij} \end{cases}$$

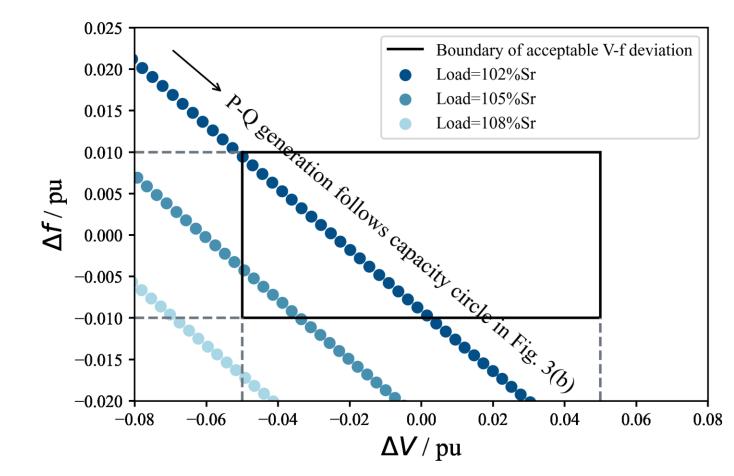


Fig. 5 V-f deviation under bounded generation constraints

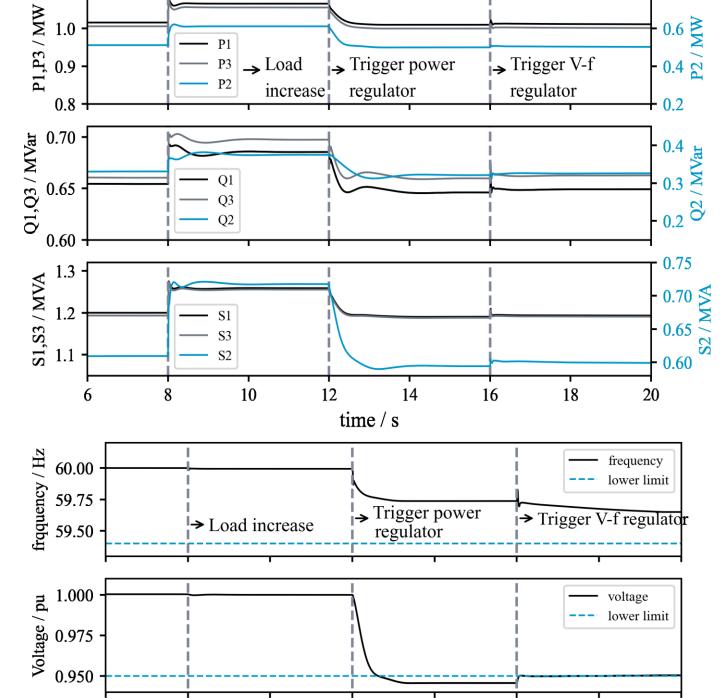
#### ☐ Case study

#### Basic settings

- a) Before 8 s, G1-G3 are controlled with the conventional droop method represented in Fig. 1. b) At 8 s, load C2 increases.
- c) At 12 s, the reference capacities of G1-G3 are and 1.2MVA, 1.2MVA, 0.6MVA, respectively. The power regulator starts working. d) At 16 s, the V-f regulator starts working.

#### **□** Conclusions

- > The power regulator regulates the output of GFM inverters, while the V-f regulator improves the V-f deviation by leveraging the load response to voltage and frequency.
- Three-level coordination is achieved within the proposed control framework, : 1). Generation and load, 2). V regulation and f regulation, and 3). P generation and Q generation.



10 time / s

Fig. 6: Scenario 1: Over voltage dip and recovery

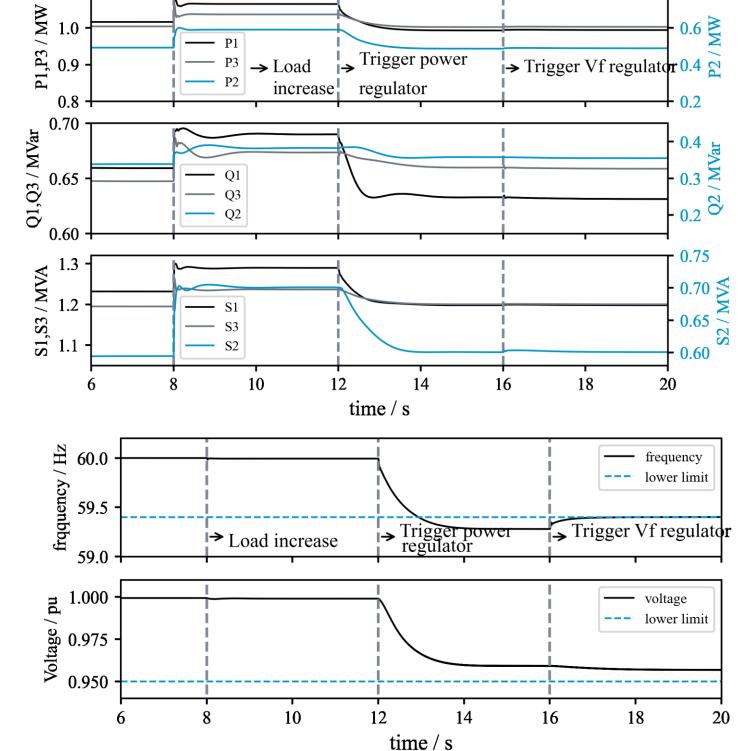


Fig. 7. Scenario 2: Over frequency dip and recovery





