

# Directionally Differentiable Econometric Models

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## Abstract

The current paper examines the limit distribution of the quasi-maximum likelihood estimator obtained from a directionally differentiable quasi-likelihood function and represents its limit distribution as a functional of a Gaussian stochastic process indexed by direction. By this, the standard analysis that assumes a differentiable quasi-likelihood function is treated as a special case of our analysis. We also redefine the standard quasi-likelihood ratio, Wald, and Lagrange multiplier test statistics so that their null limit behaviors are regular under our model framework.

**Key Words:** directionally differentiable quasi-likelihood function, Gaussian stochastic process, quasi-likelihood ratio test, Wald test, and Lagrange multiplier test statistics.

**JEL Classification:** C12, C13, C22, C32.

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# 1 Introduction

Differentiability is one of the regularity conditions for analyzing standard econometric models. For example, Wald (1943) proposes it as one of the regularity conditions for his classic test statistic. As another example, Chernoff (1954) considers use of the likelihood ratio (LR) test statistic and approximates the log-likelihood function by Taylor's expansion that requires differentiability.

Many important econometric models are not estimated by differentiable quasi-likelihood functions. For example, the likelihood function examined by King and Shively (1993) is not differentiable. They attempt to resolve the so-called Davies's (1977, 1987) identification problem by reparameterizing the likelihood function using the polar coordinates. The consequent likelihood function, however, is not differentiable (D) and only directionally differentiable (D-D). As another example, Aigner, Lovell, and Schmidt (1977) specify the stochastic frontier production function model to capture inefficiently produced outputs. Their model inference cannot be conducted in the conventional way due to the non-differentiability of the likelihood function. In addition to these, many quasi-likelihood functions in prior literature are not D, and their model analysis should be different from the standard case.

The goal of this paper is therefore to extend the model scope to include non-differentiable models for quasi-likelihood estimation. Specifically, we suppose that model parameters are estimated by maximizing D-D quasi-likelihood functions. As it turns out, D quasi-likelihood function is a special case of D-D quasi-likelihood functions, so that the analysis assuming D-D quasi-likelihood function generalizes what is obtained by assuming D quasi-likelihood function condition. In more detail, the generalization is achieved by resorting to Billingsley's (1999) asymptotically tight probability measure condition. Each direction around the parameter of interest is regarded as an index indicating a particular value of directional derivatives. The asymptotically tight probability measure condition governs the stochastic interrelationship of the directional derivatives in a way to apply the functional central limit theorem (FCLT) and the uniform law of large numbers (ULLN) to the random functions indexed by direction. The large sample distribution of quasi-maximum likelihood (QML) estimator (or M-estimator) obtained by this process turns out to generalize what is obtained by D quasi-likelihood function.

Another goal of this study is to provide test statistics that can be properly used for D-D quasi-likelihood models. We achieve this goal by refining the conventional quasi-likelihood ratio (QLR), Wald, and Lagrange multiplier (LM) test statistics in the D-D function context, and we show that the three test statistics are asymptotically equivalent under the null hypothesis and mild regularity conditions detailed below. By this, we desire to achieve the dual purpose to estimate and infer D-D econometric models.

Our D-D model analysis is applicable to a number of empirically popular econometric models. As an

illustration of our analysis, we revisit King and Shively's (1993) reparameterized model and demonstrate that our analysis provides a vehicle that can be efficiently applied to their model analysis. In addition to this, we also collect other model analyses to the Supplement to this study and demonstrate its usefulness (see Cho and White, 2016). They include Aigner, Lovell, and Schmidt's (1977) stochastic frontier production function model and the Box-Cox transformation. The standard generalized method of moments (GMM) estimation is also revisited using the analysis of D-D quasi-likelihood functions.

The approach of the current study is related to the works in prior literature. First, Pollard (1985) examines stochastically differentiable quasi-likelihood functions that are not D although their population analogs are D. The D-D quasi-likelihood function is not stochastically differentiable because the population quasi-likelihood function is D-D, let alone its sample quasi-likelihood function. Second, Andrews (2001) examines inferencing when there is an unidentified parameter under a maintained null hypothesis that is possibly on the boundary of the parameter space. Although D-D quasi-likelihood functions may be derived by reparameterizing the parameter space as in King and Shively (1993), the analysis of here does not assume only D-D quasi-likelihood functions obtained through reparameterization. General D-D quasi-likelihood functions are assumed so that the likelihood function framework as in Aigner, Lovell, and Schmidt (1977) can be properly analyzed using the analysis of here. Finally, Fang and Santos (2014) examine a D-D transform of a consistent estimator and note that D transform is necessary and sufficient for a valid application of the standard bootstrap to the transformation. Instead of assuming the presence of a consistent estimator, we examine a consistent QML estimator obtained from D-D quasi-likelihood functions for our study.

The plan of this paper is as follows. In Section 2, D-D functions are defined and examined, and the D quasi-likelihood function is investigated as a special case of D-D quasi-likelihood functions. We also provide regularity conditions for D-D quasi-likelihood functions and consider the limit distribution of the QML estimator under these conditions. Section 3 considers data inferences using D-D quasi-likelihood functions. For this, we redefine the standard QLR, Wald, and LM test statistics and derive their null limit distributions. Furthermore, Section 4 examines King and Shively's (1993) reparameterized model for demonstration purpose. In the same section, we also conduct Monte Carlo experiments using the same model. Section 5 offers concluding remarks, and formal mathematical proofs are collected to the Appendix.

Before moving to the next section, we introduce mathematical notation that is used throughout this paper. For any  $x \in \mathbb{R}^r$ ,  $\|x\|$  stands for the Euclidean norm. Furthermore,  $\mathbf{1}_{\{\cdot\}}$  and  $\text{cl}(A)$  stand for an indication function and a closure of set  $A$ , respectively. The other is standard.

## 2 Directionally Differentiable Quasi-Likelihood Functions

To proceed with our discussion in a manageable way, we first introduce the regularity conditions maintained throughout this paper. The following is the data generating process (DGP) condition:

**Assumption 1** (DGP). *A sequence of random variables  $\{\mathbf{X}_t \in \mathbb{R}^m\}_{t=1}^n$  ( $m \in \mathbb{N}$ ) defined on a complete probability space  $(\Omega, \mathcal{F}, \mathbb{P})$  is strictly stationary and ergodic.*  $\square$

Assumption 1 is standard for stationary time-series data. Many economic data satisfy the given condition. For example, the standard ARMA process, hidden Markov processes, and GARCH processes are typical examples of this DGP. Next, we suppose the following quasi-likelihood function that is assumed to capture the DGP properties:

**Assumption 2** (Quasi-Likelihood Function). *A sum of measurable functions  $\{L_n(\boldsymbol{\theta}) := \sum_{t=1}^n \ell_t(\boldsymbol{\theta}; \mathbf{X}^t) : \boldsymbol{\theta} \in \Theta\}$  is the quasi-likelihood function for  $\mathbf{X}^n$  such that for each  $t$ ,  $\ell_t(\cdot; \mathbf{X}^t)$  is Lipschitz continuous on  $\Theta$  almost surely- $\mathbb{P}$  (a.s.- $\mathbb{P}$ ), where for each  $t$ ,  $\mathbf{X}^t$  denotes  $(\mathbf{X}_1, \dots, \mathbf{X}_t)$ , and  $\Theta$  is a compact and convex set in  $\mathbb{R}^r$  with  $r \in \mathbb{N}$ .*  $\square$

This quasi-likelihood function condition is widely used in the literature, and the quasi-maximum likelihood (QML) estimator is a typical estimator obtained from Assumption 2 that captures the key properties of the DGP. We further characterize the DGP by

**Assumption 3** (Existence and Identification). *(i) For each  $\boldsymbol{\theta}$ ,  $n^{-1}E[L_n(\boldsymbol{\theta})]$  exists in  $\mathbb{R}$  and is finite for any  $n$ ; (ii) For a unique  $\boldsymbol{\theta}_* \in \Theta$ ,  $E[n^{-1}L_n(\cdot)]$  is maximized at  $\boldsymbol{\theta}_* \in \Theta$  for any  $n$ .*  $\square$

Using Assumptions 2 and 3, we let the QML estimator  $\hat{\boldsymbol{\theta}}_n$  be such that  $L_n(\hat{\boldsymbol{\theta}}_n) = \max_{\boldsymbol{\theta} \in \Theta} L_n(\boldsymbol{\theta})$ .

Several remarks are warranted on these assumptions. First, Assumption 3(i) requires model identification. Even if models are not identified, model analysis using the framework of Davies (1977,1987) can still be made. Nevertheless, accommodating this renders the key aspects of D-D quasi-likelihood functions obscure. Therefore, we highlight the D-D quasi-likelihood function analysis by using identified models. Second,  $\boldsymbol{\theta}_*$  can be on the boundary of  $\Theta$  as often ensued by the reparameterization method of King and Shively (1993). Assumption 3(ii) permits this. Finally, for notational simplicity, we abbreviate  $\ell_t(\cdot; \mathbf{X}^t)$  into  $\ell_t(\cdot)$  from now.

Given Assumptions 1 to 3, the QML estimator is consistent, viz.,  $\hat{\boldsymbol{\theta}}_n$  converges to  $\boldsymbol{\theta}_*$  a.s.- $\mathbb{P}$ , and this is straightforward and well known in the literature (e.g., Andrews, 1999). The desired property is achieved by applying the ULLN to  $n^{-1}L_n(\cdot)$ , given that  $\boldsymbol{\theta}_*$  is unique. We therefore do not prove this in the Appendix. One of the implications is that the differentiability condition is not necessary for the consistency of the

QML estimator as Wald (1949) points out. On the other hand, the limit distribution of the QML estimator is dependent upon the differentiability as we discuss in the next subsection.

## 2.1 Directional Differentiability

The smoothness condition of D-D functions is important for the limit distribution of  $\hat{\theta}_n$ . In this subsection, we define the D-D quasi-likelihood function and characterize D quasi-likelihood functions using the D-D quasi-likelihood function.

**Definition 1** (D-D Functions). (i)  $f : \Theta \mapsto \mathbb{R}$  is called directionally differentiable (D-D) at  $\theta$  in the direction of  $d \in \Delta(\theta)$ , if

$$Df(\theta; d) := \lim_{h \downarrow 0} \frac{f(\theta + hd) - f(\theta)}{h}$$

exists in  $\mathbb{R}$ , where  $\Delta(\theta) := \{x \in \mathbb{R}^r : x + \theta \in \text{cl}\{C(\theta)\}, \|x\| = 1\}$ , and  $C(\theta) := \{x \in \mathbb{R}^r : \exists \theta' \in \Theta, x := \theta + \delta\theta', \delta \in \mathbb{R}^+\}$ ; (ii)  $f : \Theta \mapsto \mathbb{R}$  is said to be D-D on  $\Delta(\theta)$ , if for all  $d \in \Delta(\theta)$ ,  $Df(\theta; d)$  exists; (iii)  $f : \Theta \mapsto \mathbb{R}$  is said to be D-D on  $\Theta$ , if for all  $\theta \in \Theta$ ,  $f$  is D-D on  $\Delta(\theta)$ .  $\square$

Several remarks are in order on this definition. First, note that the definition of D-D function is weaker than that of D function. D-D functions can have different directional derivatives that is nonlinearly dependent upon the direction, and there can be a continuum number of directions if  $r$  is greater than unity. On the other hand, if  $f(\cdot)$  is D,  $Df(\theta; d)$  is represented as a linear combination of  $r$  different directional derivatives. Second,  $Df(\theta; \cdot)$  is defined on  $\Delta(\theta)$ . This requirement is adopted to accommodate Chernoff's (1954) device. Chernoff (1954) notes that it is essential to approximate the parameter space by a cone  $C(\theta)$  and obtains the limit distribution of the QML estimator. We define  $\Delta(\theta)$  to collect only directions relevant to  $C(\theta)$ , and it plays the role of domain of a Gaussian stochastic process that is introduced below. Third, even when  $\theta$  is on the boundary of  $\Theta$ ,  $\Delta(\theta)$  can still be defined not to contain the directions of boundary sides. Finally, another norm other than the Euclidean norm can also be used to define  $\Delta(\theta)$ . For example,  $\tilde{\Delta}(\theta) := \{x \in \mathbb{R}^r : x + \theta \in \text{cl}\{C(\theta)\}, \|x\|_\infty = 1\}$  can be used, where  $\|\cdot\|_\infty$  is the uniform norm, and it captures the same directions as given by  $\Delta(\theta)$ . We proceed our discussions with  $\Delta(\theta)$ .

There exists a regular relationship between D-D and D functions as Troutman (1996, p. 122) describes. That is, if (i) a function  $f : \Theta \mapsto \mathbb{R}$  is D-D on  $\Theta$ ; (ii) for each  $\theta, \theta'$  and for some  $M < \infty$ ,  $|Df(\theta'; d) - Df(\theta; d)| \leq M\|\theta' - \theta\|$  uniformly on  $\Delta(\theta) \cap \Delta(\theta')$ ; and (iii) for each  $\theta$ ,  $Df(\theta; d)$  is continuous and linear in  $d$ , then  $f : \Theta \mapsto \mathbb{R}$  is D on  $\Theta$ . The linearity condition of  $Df(\theta; d)$  in  $d$  is the key condition for a D-D function to be D. Without this, any directional derivative cannot be represented as a linear combination of other  $r$  different directional derivatives.

Before investing D-D quasi-likelihood functions, we provide the definition of the twice D-D function that also plays another key role in our analysis.

**Definition 2** (Twice D-D Functions). *A function  $f : \Theta \mapsto \mathbb{R}$  is called twice D-D on  $\Theta$ , if for each  $\theta$  and for all  $\tilde{d}$ ,  $D^2 f(\theta; \tilde{d}; d)$  exists, where*

$$D^2 f(\theta; \tilde{d}; d) := \lim_{h \downarrow 0} \frac{Df(\theta + h\tilde{d}; d) - Df(\theta; d)}{h}. \quad \square$$

Note that the first-order directional differentiability is necessary for defining the twice D-D function. Furthermore, for a twice D-D function to be twice D, it is necessary for  $D^2 f(\theta; \tilde{d}; d)$  to be bilinear in  $d$  and  $\tilde{d}$ . We state on this in the Supplement more precisely. From now, we denote  $D^2 f(\theta; \tilde{d}; d)$  as  $D^2 f(\theta; d)$  if  $d = \tilde{d}$ .

## 2.2 Asymptotic Distribution of the QML Estimator

As pointed out in the previous subsection, the most significant difference between D-D and D functions lies in the linearity condition of the directional derivative in  $d$ . Further regularity conditions are provided for the D-D quasi-likelihood function.

**Assumption 4** (D-D Quasi-Likelihood Function).  *$\ell_t : \Theta \mapsto \mathbb{R}$  is twice D-D on  $\Theta$  a.s.- $\mathbb{P}$ , and for each  $\theta \in \Theta$  and  $d \in \Delta(\theta)$ ,  $D^2 \ell_t(\cdot; d)$  is continuous on  $\Theta$  a.s.- $\mathbb{P}$ .*  $\square$

We use Assumption 4 to approximate D-D quasi-likelihood functions by a second-order directional Taylor expansion for each direction. For this goal, the following regularity conditions are also imposed:

**Assumption 5** (Regular D-Diffility). *(i) For each  $\theta \in \Theta$ ,  $D\ell_t(\theta; \cdot)$  and  $D^2 \ell_t(\theta; \cdot)$  are continuous on  $\Delta(\theta)$  a.s.- $\mathbb{P}$ ; (ii) For each  $\theta, \theta' \in \Theta$ ,  $|D\ell_t(\theta; d) - D\ell_t(\theta'; d)| \leq M_t \|\theta - \theta'\|$  and  $|D^2 \ell_t(\theta; d) - D^2 \ell_t(\theta'; d)| \leq M_t \|\theta - \theta'\|$  uniformly on  $\Delta(\theta) \cap \Delta(\theta')$ , where  $\{M_t\}$  is a sequence of stationary and ergodic variables; (iii) For each  $\theta \in \Theta$  and for all  $d_1, d_2 \in \Delta(\theta)$ , there is  $\lambda > 0$  such that  $|D\ell_t(\theta; d_1) - D\ell_t(\theta; d_2)| \leq M_t \|d_1 - d_2\|^\lambda$  and  $|D^2 \ell_t(\theta; d_1) - D^2 \ell_t(\theta; d_2)| \leq M_t \|d_1 - d_2\|^\lambda$ .*  $\square$

The example in Section 4 satisfies Assumptions 4 and 5. Here, Assumption 5(iii) is assumed to apply the asymptotic tightness and the ULLN to the first and second-order directional derivative, respectively. We detail the asymptotic tightness and the ULLN below, when they are more relevant. If Assumption 5(iii) is replaced by the following stronger Assumption 5(iii)\*, the quasi-likelihood function is twice D a.s.- $\mathbb{P}$  as examined in the Supplement:

**Assumption 5** (Regular D-Diffility). (iii)\* For each  $\theta$  and for all  $\mathbf{d} \in \Delta(\theta)$ ,  $D\ell_t(\theta; \mathbf{d})$  and  $D^2\ell_t(\theta; \tilde{\mathbf{d}}; \mathbf{d})$  is linear in  $\mathbf{d}$  and bilinear in  $(\mathbf{d}, \tilde{\mathbf{d}})$  a.s.- $\mathbb{P}$ , respectively, and for each  $\mathbf{d} \in \Delta(\theta)$ ,  $D^2\ell_t(\cdot; \mathbf{d})$  is continuous on  $\Theta$  a.s.- $\mathbb{P}$ .  $\square$

We let Assumption 5\* denote Assumptions 5(i, ii, and iii\*) going forward when D quasi-likelihood functions are referred. Unless otherwise stated, Assumption 5 stands for Assumptions 5(i, ii, and iii).

We impose further regularity conditions for the limit distribution of the QML estimator.

**Assumption 6** (CLT). (i) For any  $t$ ,  $E[D\ell_t(\theta_*; \mathbf{d})] = 0$  uniformly on  $\Delta(\theta_*)$ ; (ii) For any  $n$ ,  $A_*(\mathbf{d}) := E[n^{-1}D^2L_n(\theta_*; \mathbf{d})]$  is strictly negative and finite uniformly on  $\Delta(\theta_*)$ ; (iii) For any  $n$ ,  $B_*(\mathbf{d}, \tilde{\mathbf{d}})$  is strictly positive and finite uniformly on  $\Delta(\theta_*)$ , where for each  $\mathbf{d}, \tilde{\mathbf{d}}$ ,

$$B_*(\mathbf{d}, \tilde{\mathbf{d}}) := \text{acov}\{n^{-1/2}DL_n(\theta_*; \mathbf{d}), n^{-1/2}DL_n(\theta_*; \tilde{\mathbf{d}})\},$$

and ‘acov’ denotes the asymptotic covariance of given arguments; (iv) for some  $q > (r-1)/(\lambda\gamma)$  and  $s > q \geq 2$ , and for each  $f_t \in \bar{\mathbb{L}}$ ,  $\|f_t - E[f_t | \mathcal{F}_{t-\tau}^{t+\tau}]\|_q \leq \nu_\tau$ , where  $\bar{\mathbb{L}} := \{a_1f_1 + a_2f_2 : f_1, f_2 \in \{D\ell_t(\theta_*; \cdot, \mathbf{d}) : \mathbf{d} \in \Delta(\theta_*)\}, a_1, a_2 \in \mathbb{R}\}$ ;  $\nu_\tau$  is of size  $-1/(1-\gamma)$  with  $1/2 \leq \gamma < 1$ ;  $\mathcal{F}_{t-\tau}^{t+\tau} := \sigma(\mathbf{X}_{t-\tau}, \dots, \mathbf{X}_{t+\tau})$ ; and  $\{\mathbf{X}_t \in \mathbb{R}^k : t \in \mathbb{N}\}$  is a strong mixing sequence with size  $-sq/(s-q)$ . Furthermore,  $E[M_t^s] < \infty$  and  $\sup_{\mathbf{d} \in \Delta(\theta_*)} \sup_{t=1,2,\dots} \|D\ell_t(\theta_*; \mathbf{d})\|_s < \Delta < \infty$ .  $\square$

Assumption 6(i) is imposed to apply the central limit theorem (CLT). Note that Assumption 6(i) may not hold uniformly in  $\mathbf{d}$  if  $\theta_*$  is a boundary point of  $\Theta$ : for some  $\mathbf{d}$ ,  $E[D\ell_t(\theta_*; \mathbf{d})]$  can be strictly negative if  $\theta_*$  is a boundary point, although  $\theta_*$  maximizes  $E[\ell_t(\cdot)]$ . If so, the test statistics considered below can be degenerate. We impose Assumption 6(i) and prevents this. On the other hand, if  $\theta_*$  is an interior element, Assumption 6(i) can be derived from the condition that  $\theta_*$  maximizes  $E[\ell_t(\cdot)]$ . Assumption 6(iii) is also imposed for the same purpose. For notational simplicity, we let  $B_*(\mathbf{d})$  denote  $B_*(\mathbf{d}, \tilde{\mathbf{d}})$  if  $\mathbf{d} = \tilde{\mathbf{d}}$  from now. Assumption 6(iv) is imposed to apply corollary 3.1 of Wooldridge and White (1988) and theorem 4 of Hansen (1996a). It follows that  $n^{-1/2}DL_n(\theta_*; \cdot)$  obeys the FCLT mainly from Assumption 6(iv). Wooldridge and White (1988) provide regularity conditions for the CLT of near-epoch processes as a special case of the mixingale process. Hansen (1996a) generalizes this and provides the regularity conditions for the asymptotic tightness of Lipschitz continuous functions. In essence, Assumption 6 is used to apply both CLT and asymptotic tightness to  $n^{-1/2}DL_n(\theta_*; \cdot)$ . Finally, the focus of here is different from that of Fang and Santos (2014) in which a directionally differentiable transform of a consistent estimator is examined, whereas our QML estimator maximizes a directionally differentiable quasi-likelihood function.

The limit distribution of  $\hat{\theta}_n$  is obtained by using the regularity conditions provided so far. Our plan is to

approximate the quasi-likelihood function by a second-order directional Taylor expansion for each direction and relate this to other directional Taylor expansions. Specifically, we first derive the limit distribution of  $\hat{\theta}_n$  for a particular direction  $\mathbf{d}$  and call it *directional QML estimator (DQML estimator)*. Next, we examine how this is interrelated with another DQML estimator obtained by using a different direction. For this examination, we first let  $\hat{\theta}_n(\mathbf{d})$  denote the DQML estimator. That is,  $L_n(\hat{\theta}_n(\mathbf{d})) = \max_{\theta \in \Theta_*(\mathbf{d})} L_n(\theta)$ , where  $\Theta_*(\mathbf{d}) := \{\theta' \in \Theta : \theta' = \theta_* + h\mathbf{d}, h \in \mathbb{R}^+, \mathbf{d} \in \Delta(\theta_*)\}$ . Note that the DQML estimator is constrained by  $\mathbf{d}$ : for given  $\mathbf{d}$ ,  $\Theta_*(\mathbf{d})$  is a straight line starting from  $\theta_*$  with its endpoint at the boundary of  $\Theta$ . Therefore,  $\Theta_*(\mathbf{d}) \subset \Theta$ , so that for each  $\mathbf{d}$ ,  $L_n(\hat{\theta}_n(\mathbf{d})) \leq L_n(\hat{\theta}_n)$ .

We can also represent the DQML estimator  $\hat{\theta}_n(\mathbf{d})$  using the distance between  $\theta_*$  and  $\hat{\theta}_n(\mathbf{d})$ . By the constraint that  $\hat{\theta}_n(\mathbf{d}) \in \Theta_*(\mathbf{d})$ , we let  $\hat{h}_n(\mathbf{d})$  be such that  $\hat{\theta}_n(\mathbf{d}) \equiv \theta_* + \hat{h}_n(\mathbf{d})\mathbf{d}$ , from which the limit behavior of  $\hat{h}_n(\mathbf{d})$  is associated with that of  $\hat{\theta}_n(\mathbf{d})$ . We define the space of  $h$  as  $H_*(\mathbf{d}) := \{h \in \mathbb{R}^+ : \theta_* + h\mathbf{d} \in \Theta_*(\mathbf{d})\}$ , so that  $\max_{h \in H_*(\mathbf{d})} L_n(\theta_* + h\mathbf{d}) = L_n(\hat{\theta}_n(\mathbf{d}))$ . As  $\Theta$  is a compact and convex set in  $\mathbb{R}^r$ ,  $H_*(\mathbf{d})$  has to be a closed and bounded interval in  $\mathbb{R}^+$  with its left-end point equal to zero. We next apply the directional second-order Taylor approximation to  $L_n(\theta_* + (\cdot)\mathbf{d})$ , so that for some  $\bar{\theta}_n(\mathbf{d}) \in \Theta(\mathbf{d})$ , the following holds by the mean-value theorem:

$$L_n(\theta_* + h\mathbf{d}) = L_n(\theta_*) + DL_n(\theta_*; \mathbf{d})h + \frac{1}{2}D^2L_n(\bar{\theta}_n(\mathbf{d}); \mathbf{d})h^2. \quad (1)$$

This approximation can be carried out on  $H_*(\mathbf{d})$  because  $\hat{\theta}_n = \theta_* + o_{\mathbb{P}}(1)$ , so that for each  $\mathbf{d} \in \Delta(\theta_*)$ ,

$$2\{L_n(\hat{\theta}_n(\mathbf{d})) - L_n(\theta_*)\} \Rightarrow \max_{h \in \mathbb{R}^+} [2\mathcal{Z}(\mathbf{d})\tilde{h} + A_*(\mathbf{d})\tilde{h}^2], \quad (2)$$

where  $n^{-1/2}DL_n(\theta_*; \mathbf{d})$  and  $n^{-1}D^2L_n(\theta_*; \mathbf{d})$  are such that  $\{n^{-1/2}DL_n(\theta_*; \mathbf{d}), n^{-1}D^2L_n(\theta_*; \mathbf{d})\} \Rightarrow \{\mathcal{Z}(\mathbf{d}), A_*(\mathbf{d})\}$  as shown in the Appendix. Here,  $\tilde{h}$  captures the limit behavior of  $\sqrt{n}h$ , and the argument of the right side in (2) is simply obtained as  $\max[0, \mathcal{G}(\mathbf{d})]$ , where  $\mathcal{G}(\mathbf{d}) := \{-A_*(\mathbf{d})\}^{-1}\mathcal{Z}(\mathbf{d})$  by the Kuhn-Tucker theorem, so that  $\sqrt{n}\hat{h}_n(\mathbf{d}) \Rightarrow \max[0, \mathcal{G}(\mathbf{d})]$ . This also implies that  $\sqrt{n}(\hat{\theta}_n(\mathbf{d}) - \theta_*) \Rightarrow \max[0, \mathcal{G}(\mathbf{d})]\mathbf{d}$  by noting that  $\hat{\theta}_n(\mathbf{d}) = \theta_* + \hat{h}_n(\mathbf{d})\mathbf{d}$ , and  $2\{L_n(\hat{\theta}_n(\mathbf{d})) - L_n(\theta_*)\} \Rightarrow \max[0, \mathcal{Y}(\mathbf{d})]^2$ , where for each  $\mathbf{d}$ ,  $\mathcal{Y}(\mathbf{d}) := \{-A_*(\mathbf{d})\}^{1/2}\mathcal{G}(\mathbf{d})$ . Note that (1) implies that the quasi-likelihood function may not be stochastically differentiable with respect to  $\mathbf{d}$  because the given quasi-likelihood function may not be approximated by a second-order expansion with respect to  $\mathbf{d}$  (see Pollard, 1985).

This pointwise result (with respect to  $\mathbf{d}$ ) is not sufficient to derive the limit distribution of the QML estimator. It is necessary to examine the stochastic interrelationship of DQML estimators obtained by using



different directions. Note that

$$L_n(\hat{\boldsymbol{\theta}}_n) = \sup_{\mathbf{d} \in \Delta(\boldsymbol{\theta}_*)} L_n(\hat{\boldsymbol{\theta}}_n(\mathbf{d})). \quad (3)$$

That is, if we let  $\hat{\mathbf{d}}_n := \arg \max_{\mathbf{d} \in \Delta(\boldsymbol{\theta}_*)} L_n(\hat{\boldsymbol{\theta}}_n(\mathbf{d}))$ , then  $L_n(\hat{\boldsymbol{\theta}}_n) \equiv L_n(\hat{\boldsymbol{\theta}}_n(\hat{\mathbf{d}}_n))$ . The limit behavior of  $\hat{\boldsymbol{\theta}}_n$  is derived by examining how  $\hat{\boldsymbol{\theta}}_n$  is asymptotically associated with  $\hat{\boldsymbol{\theta}}_n(\cdot)$ , and for this purpose, we show in the Appendix that  $DL_n(\boldsymbol{\theta}_*; \cdot)$  is asymptotically tight: for all  $\varepsilon > 0$ , there is  $\delta > 0$  such that

$$\limsup_{n \rightarrow \infty} \mathbb{P}_n \left( \sup_{\|\mathbf{d}_1 - \mathbf{d}_2\| < \delta} n^{-1/2} |DL_n(\boldsymbol{\theta}_*; \mathbf{d}_1) - DL_n(\boldsymbol{\theta}_*; \mathbf{d}_2)| > \varepsilon \right) < \varepsilon,$$

where  $\mathbb{P}_n$  is the empirical probability measure. These facts imply that the first-order directional derivative weakly converges to a Gaussian stochastic process indexed by  $\mathbf{d}$  (e.g., Billingsley, 1999). In addition,  $n^{-1}D^2L_n(\boldsymbol{\theta}_*; \cdot)$  satisfies the ULLN under the given conditions provided so far.

If  $L_n(\cdot)$  is D, it is trivial to show the asymptotic tightness, because  $DL_n(\boldsymbol{\theta}_*; \mathbf{d}) = \nabla_{\boldsymbol{\theta}} L_n(\boldsymbol{\theta}_*) \mathbf{d}$ , so that

$$\sup_{\|\mathbf{d}_1 - \mathbf{d}_2\| < \delta} n^{-1/2} |DL_n(\boldsymbol{\theta}_*; \mathbf{d}_1) - DL_n(\boldsymbol{\theta}_*; \mathbf{d}_2)| \leq \|n^{-1/2} \nabla_{\boldsymbol{\theta}} L_n(\boldsymbol{\theta}_*)\| \delta,$$

implying that for any  $\varepsilon > 0$ ,

$$\mathbb{P}_n \left( \sup_{\|\mathbf{d}_1 - \mathbf{d}_2\| < \delta} n^{-1/2} |DL_n(\boldsymbol{\theta}_*; \mathbf{d}_1) - DL_n(\boldsymbol{\theta}_*; \mathbf{d}_2)| > \varepsilon \right) \leq \mathbb{P}_n \left( \|n^{-1/2} \nabla_{\boldsymbol{\theta}} L_n(\boldsymbol{\theta}_*)\| \delta > \varepsilon \right).$$

Thus, if  $n^{-1/2} \nabla_{\boldsymbol{\theta}} L_n(\boldsymbol{\theta}_*)$  obeys the CLT, we can choose  $\delta$  to have the right side be less than  $\varepsilon$ , and this shows the asymptotic tightness. Likewise, we can apply the ULLN to the second-order derivatives: for each  $\mathbf{d} \in \Delta(\boldsymbol{\theta}_*)$ ,  $D^2L_n(\boldsymbol{\theta}_*; \mathbf{d}) = \mathbf{d}' \nabla_{\boldsymbol{\theta}}^2 L_n(\boldsymbol{\theta}_*) \mathbf{d}$ , so that for a nontrivial norm,  $\|\cdot\|_{\infty}$  say,

$$\sup_{\mathbf{d}} |n^{-1} \{ \mathbf{d}' \nabla_{\boldsymbol{\theta}}^2 L_n(\boldsymbol{\theta}_*) \mathbf{d} - \mathbf{d}' E[\nabla_{\boldsymbol{\theta}}^2 L_n(\boldsymbol{\theta}_*)] \mathbf{d} \}| \leq \sup_{\mathbf{d}} \mathbf{d}' \mathbf{d} \|n^{-1} \{ \nabla_{\boldsymbol{\theta}}^2 L_n(\boldsymbol{\theta}_*) - E[\nabla_{\boldsymbol{\theta}}^2 L_n(\boldsymbol{\theta}_*)] \}\|_{\infty},$$

where the right side can be made as small as possible by applying the law of large numbers.

By the asymptotically tight directional derivatives, we now extend the pointwise limit result for  $\sqrt{n} \hat{h}_n(\mathbf{d})$  to the level of functional space, and from this, we obtain the limit distribution of the QML estimator as reported in the following theorem:

**Theorem 1.** *Given Assumptions 1 to 6, (i)  $\{n^{-1/2} DL_n(\boldsymbol{\theta}_*; \cdot), n^{-1} D^2L_n(\boldsymbol{\theta}_*; \cdot)\} \Rightarrow (\mathcal{Z}(\cdot), A_*(\cdot))$ , where for each  $\mathbf{d}$  and  $\mathbf{d}'$ ,  $E[\mathcal{Z}(\mathbf{d}) \mathcal{Z}(\mathbf{d}')] = B_*(\mathbf{d}, \mathbf{d}')$ ; (ii)  $\sqrt{n} \hat{h}_n(\cdot) \Rightarrow \max[0, \mathcal{G}(\cdot)]$ ; (iii)  $2\{L_n(\hat{\boldsymbol{\theta}}_n) - L_n(\boldsymbol{\theta}_*)\} \Rightarrow \sup_{\mathbf{d} \in \Delta(\boldsymbol{\theta}_*)} \max[0, \mathcal{Y}(\mathbf{d})]^2$ ; (iv) if  $\max[0, \mathcal{Y}(\cdot)]^2$  is uniquely maximized at  $\mathbf{d}_*$  a.s.  $-\mathbb{P}$ ,  $\sqrt{n}(\hat{\boldsymbol{\theta}}_n - \boldsymbol{\theta}_*) \Rightarrow$*

$$\max[0, \mathcal{G}(\mathbf{d}_*)]\mathbf{d}_*.$$

□

Note that the limit distribution of the QML estimator is now represented as a functional of the Gaussian stochastic process defined on  $\Delta(\boldsymbol{\theta}_*)$ . Here, Theorem 1(iv) follows from the argmax continuous mapping theorem (e.g., Kim and Pollard, 1990; van der Vaart and Wellner, 1996). If  $\max[0, \mathcal{Y}(\cdot)]^2$  is flat on  $\Delta(\boldsymbol{\theta}_*)$  almost surely, it is hard to think of  $\mathbf{d}_*$  as the limit of  $\widehat{\mathbf{d}}_n$ . The unique maximization condition on  $\mathbf{d}_*$  is imposed to prevent this. This result also implies that even when the model is correctly specified, so that  $2\{L_n(\widehat{\boldsymbol{\theta}}_n) - L_n(\boldsymbol{\theta}_*)\}$  is now the LR test statistic, its null limit distribution is not chi-squared.

Many statistics are known to follow limit distributions characterized by a Gaussian stochastic process. For example, Davies (1977, 1987), Andrews (2001), Cho and White (2007, 2010, 2011a), and Baek, Cho, and Phillips (2015) examine these statistics: unidentified parameters yield limit distributions characterized by a Gaussian stochastic process, and Theorem 1 can be thought of as a variational result of prior literature.

Theorem 1 accommodates the standard D quasi-likelihood function as a special case of D-D quasi-likelihood functions. For this examination, we impose

**Assumption 6 (CLT).** (ii)\* For a symmetric and negative definite matrix  $\mathbf{A}_*$  and each  $\mathbf{d}$ ,  $A_*(\mathbf{d}) = \mathbf{d}'\mathbf{A}_*\mathbf{d}$ ; (iii)\* For a symmetric and positive definite matrix  $\mathbf{B}_*$  and each  $\mathbf{d}, \tilde{\mathbf{d}}$ ,  $B_*(\mathbf{d}, \tilde{\mathbf{d}}) = \mathbf{d}'\mathbf{B}_*\tilde{\mathbf{d}}$ . □

Assumptions 6(ii and iii)\* correspond to assuming that  $\mathbf{A}_* := \lim_{n \rightarrow \infty} n^{-1}E[\nabla_{\boldsymbol{\theta}}^2 L_n(\boldsymbol{\theta}_*)]$  and  $\mathbf{B}_* := \text{acov}\{n^{-1/2}\nabla_{\boldsymbol{\theta}} L_n(\boldsymbol{\theta}_*)\}$  are negative and positive definite, respectively in the D quasi-likelihood function context. Using these assumptions, we can further refine the results in Theorem 1. We let Assumption 6\* denote Assumptions 6(i, ii\*, iii\*, and iv) going forward.

**Corollary 1.** Given Assumptions 1 to 4, 5\*, and 6\*, (i)  $\mathcal{Z}(\cdot)$  is linear in  $\mathbf{d} \in \Delta(\boldsymbol{\theta}_*)$ , so that for each  $\mathbf{d}$ ,  $\mathcal{Z}(\mathbf{d}) = \mathbf{Z}'\mathbf{d}$  in distribution, where  $\mathbf{Z} \sim N(\mathbf{0}, \mathbf{B}_*)$ ; (ii) for each  $\mathbf{d}$ ,  $\mathcal{G}(\mathbf{d}) = \mathbf{Z}'\mathbf{d}\{-\mathbf{d}'\mathbf{A}_*\mathbf{d}\}^{-1}$  in distribution; (iii) for each  $\mathbf{d}$ ,  $\sqrt{n}(\widehat{\boldsymbol{\theta}}_n(\mathbf{d}) - \boldsymbol{\theta}_*) \Rightarrow \max[0, \{\mathbf{Z}'\mathbf{d}\{-\mathbf{d}'\mathbf{A}_*\mathbf{d}\}^{-1}\}\mathbf{d}$ ; (iv)  $\sqrt{n}(\widehat{\boldsymbol{\theta}}_n - \boldsymbol{\theta}_*) \Rightarrow \max[0, -\mathbf{Z}'\mathbf{d}_*\{\mathbf{d}_*'\mathbf{A}_*\mathbf{d}_*\}^{-1}]\mathbf{d}_*$  with  $\mathbf{d}_* := \arg \max_{\mathbf{d}} \max[0, \mathbf{Z}'\mathbf{d}]^2 / \mathbf{d}'(-\mathbf{A}_*)\mathbf{d}$ ; (v)  $\sqrt{n}(\widehat{\boldsymbol{\theta}}_n - \boldsymbol{\theta}_*) \Rightarrow (-\mathbf{A}_*)^{-1}\mathbf{Z}$ , provided that  $\boldsymbol{\theta}_*$  is interior to  $\boldsymbol{\Theta}$ ; (vi)  $2\{L_n(\widehat{\boldsymbol{\theta}}_n) - L_n(\boldsymbol{\theta}_*)\} \Rightarrow \sup_{\mathbf{d} \in \Delta(\boldsymbol{\theta}_*)} \max[0, \mathbf{Z}'\mathbf{d}]^2 \{\mathbf{d}'(-\mathbf{A}_*)\mathbf{d}\}^{-1}$ ; (vii)  $2\{L_n(\widehat{\boldsymbol{\theta}}_n) - L_n(\boldsymbol{\theta}_*)\} \Rightarrow \mathbf{Z}'(-\mathbf{A}_*)^{-1}\mathbf{Z}$ , provided that  $\boldsymbol{\theta}_*$  is interior to  $\boldsymbol{\Theta}$ . □

Corollary 1 is the same consequence as for the standard case if  $\boldsymbol{\theta}_*$  is interior to  $\boldsymbol{\Theta}$ . Our analysis is more primitive because it involves directional derivatives. In particular, Corollaries 1(iv to vii) imply that  $\max[0, \mathcal{Y}(\cdot)]^2$  is uniquely maximized at  $\mathbf{d}_*$  a.s.- $\mathbb{P}$ . Cho (2011) exploits the D-D quasi-likelihood function analysis for D quasi-likelihood function estimation and examines other aspects that are not contained in Corollary 1.

### 3 Testing Using D-D Quasi-Likelihood Functions

In this section, we examine data inference using D-D quasi-likelihood functions. To this end, the standard QLR, Wald, and LM test statistics are redefined to accommodate the feature of directional differentiability.

It is efficient to first specify the role of each parameter. We partition  $\theta$  into  $(\pi', \tau')' = (\lambda', v', \tau')'$  such that the directional derivatives of  $L_n(\cdot)$  with respect to  $\lambda \in \mathbb{R}^{r_\lambda}$  and  $v \in \mathbb{R}^{r_v}$  are linear and possibly non-linear with respect to  $d_\lambda$  and  $d_v$ , respectively. The parameter  $\tau \in \mathbb{R}^{r_\tau}$  consists of other nuisance parameters that are asymptotically orthogonal to  $\pi := (\lambda', v')' \in \mathbb{R}^{r_\pi}$  in terms of the second-order directional derivative. More specifically, we suppose that for each  $d$ ,  $DL_n(\theta_*; d)$  can be written as

$$DL_n(\theta_*; d) = d_\lambda' DL_n^{(\lambda)} + DL_n^{(v)}(d_v) + DL_n^{(\tau)}(d_\tau)$$

such that for each  $(d_\lambda', d_v', d_\tau')'$ ,

$$\frac{1}{\sqrt{n}} \begin{bmatrix} DL_n^{(\pi)}(d_\pi) \\ DL_n^{(\tau)}(d_\tau) \end{bmatrix} := \frac{1}{\sqrt{n}} \begin{bmatrix} d_\lambda' DL_n^{(\lambda)} \\ DL_n^{(v)}(d_v) \\ DL_n^{(\tau)}(d_\tau) \end{bmatrix} \Rightarrow \begin{bmatrix} \mathcal{Z}^{(\pi)}(d_\pi) \\ \mathcal{Z}^{(\tau)}(d_\tau) \end{bmatrix} := \begin{bmatrix} d_\lambda' \mathbf{Z}^{(\lambda)} \\ \mathcal{Z}^{(v)}(d_v) \\ \mathcal{Z}^{(\tau)}(d_\tau) \end{bmatrix} \sim N(\mathbf{0}, \mathbf{B}_*(d)),$$

and  $n^{-1/2}(DL_n^{(\pi)}(\cdot), DL_n^{(\tau)}(\cdot)) \Rightarrow (\mathcal{Z}^{(\pi)}(\cdot), \mathcal{Z}^{(\tau)}(\cdot))$ , where for each  $d, \tilde{d} \in \Delta(\theta_*)$ ,

$$\begin{aligned} \mathbf{B}_*(d, \tilde{d}) &:= \begin{bmatrix} \mathbf{B}_*^{(\pi, \pi)}(d_\pi, \tilde{d}_\pi) & \mathbf{B}_*^{(\pi, \tau)}(d_\pi, \tilde{d}_\tau) \\ \mathbf{B}_*^{(\tau, \pi)}(d_\tau, \tilde{d}_\pi)' & \mathbf{B}_*^{(\tau, \tau)}(d_\tau, \tilde{d}_\tau) \end{bmatrix} \\ &:= \begin{bmatrix} d_\lambda' \mathbf{B}_*^{(\lambda, \lambda)} \tilde{d}_\lambda & d_\lambda' \mathbf{B}_*^{(\lambda, v)}(\tilde{d}_v) & d_\lambda' \mathbf{B}_*^{(\lambda, \tau)}(\tilde{d}_\tau) \\ \mathbf{B}_*^{(v, \lambda)}(d_v)' \tilde{d}_\lambda & \mathbf{B}_*^{(v, v)}(d_v, \tilde{d}_v) & \mathbf{B}_*^{(v, \tau)}(d_v, \tilde{d}_\tau) \\ \mathbf{B}_*^{(\tau, \lambda)}(d_\tau)' \tilde{d}_\lambda & \mathbf{B}_*^{(\tau, v)}(d_\tau, \tilde{d}_v) & \mathbf{B}_*^{(\tau, \tau)}(d_\tau, \tilde{d}_\tau) \end{bmatrix}, \end{aligned} \quad (4)$$

$DL_n^{(\lambda)} \in \mathbb{R}^{r_\lambda}$ ,  $DL_n^{(v)}(d_v) \in \mathbb{R}$ ,  $DL_n^{(\tau)}(d_\tau) \in \mathbb{R}$ ,  $\mathbf{B}_*^{(\lambda, \lambda)} \in \mathbb{R}^{r_\lambda} \times \mathbb{R}^{r_\lambda}$ ,  $\mathbf{B}_*^{(\lambda, v)}(d_v) \in \mathbb{R}^{r_\lambda}$ ,  $\mathbf{B}_*^{(\lambda, \tau)}(d_\tau) \in \mathbb{R}^{r_\lambda}$ ,  $\mathbf{B}_*^{(v, \lambda)}(d_v) = \mathbf{B}_*^{(\lambda, v)}(d_v)$ , and  $\mathbf{B}_*^{(\tau, \lambda)}(d_\tau) = \mathbf{B}_*^{(\lambda, \tau)}(d_\tau)$ . Thus, it follows that

$$\text{acov} \left\{ n^{-1/2} DL_n(\theta_*; d), n^{-1/2} DL_n(\theta_*; \tilde{d}) \right\} = \iota_3' \mathbf{B}_*(d, \tilde{d}) \iota_3,$$

where  $\boldsymbol{\iota}_\ell$  is the  $\ell \times 1$  vector of ones. Similarly, we also suppose that  $A_*(\mathbf{d}) = \boldsymbol{\iota}_3' \mathbf{A}_*(\mathbf{d}) \boldsymbol{\iota}_3$ , where

$$\begin{aligned} \mathbf{A}_*(\mathbf{d}) &:= \begin{bmatrix} \mathbf{A}_*^{(\pi, \pi)}(\mathbf{d}_\pi) & \mathbf{A}_*^{(\pi, \tau)}(\mathbf{d}_\pi, \mathbf{d}_\tau) \\ \mathbf{A}_*^{(\tau, \pi)}(\mathbf{d}_\tau, \mathbf{d}_\pi)' & \mathbf{A}_*^{(\tau, \tau)}(\mathbf{d}_\tau) \end{bmatrix} \\ &:= \begin{bmatrix} \mathbf{d}_\lambda' \mathbf{A}_*^{(\lambda, \lambda)} \mathbf{d}_\lambda & \mathbf{d}_\lambda' \mathbf{A}_*^{(\lambda, v)}(\mathbf{d}_v) & \mathbf{d}_\lambda' \mathbf{A}_*^{(\lambda, \tau)}(\mathbf{d}_\tau) \\ \mathbf{A}_*^{(v, \lambda)}(\mathbf{d}_v)' \mathbf{d}_\lambda & \mathbf{A}_*^{(v, v)}(\mathbf{d}_v) & \mathbf{A}_*^{(v, \tau)}(\mathbf{d}_v, \mathbf{d}_\tau) \\ \mathbf{A}_*^{(\tau, \lambda)}(\mathbf{d}_\tau)' \mathbf{d}_\lambda & \mathbf{A}_*^{(\tau, v)}(\mathbf{d}_\tau, \mathbf{d}_v) & \mathbf{A}_*^{(\tau, \tau)}(\mathbf{d}_\tau) \end{bmatrix}, \end{aligned} \quad (5)$$

$\mathbf{A}_*^{(\lambda, \lambda)} \in \mathbb{R}^{r_\lambda} \times \mathbb{R}^{r_\lambda}$ ,  $\mathbf{A}_*^{(\lambda, v)}(\mathbf{d}_v) \in \mathbb{R}^{r_\lambda}$ ,  $\mathbf{A}_*^{(\lambda, \tau)}(\mathbf{d}_\tau) \in \mathbb{R}^{r_\lambda}$ ,  $\mathbf{A}_*^{(v, \lambda)}(\mathbf{d}_v) = \mathbf{A}_*^{(\lambda, v)}(\mathbf{d}_v)$ , and  $\mathbf{A}_*^{(\tau, \lambda)}(\mathbf{d}_\tau) = \mathbf{A}_*^{(\lambda, \tau)}(\mathbf{d}_\tau)$ . We also let  $\boldsymbol{\pi}$  be orthogonal to  $\boldsymbol{\tau}$ : for each  $\mathbf{d}$ ,  $\mathbf{A}_*^{(\tau, \pi)}(\mathbf{d}_\tau, \mathbf{d}_\pi) = \mathbf{A}_*^{(\pi, \tau)}(\mathbf{d}_\pi, \mathbf{d}_\tau) = \mathbf{0}$ . This assumption is useful in eliminating the nuisance parameters from our analysis that are asymptotically irrelevant to testing the hypothesis given below. We also permit that  $r_v$ ,  $r_\lambda$ , and  $r_\tau$  can be zero, so that  $\lambda$ ,  $v$ , or  $\tau$  may be absent in the model. If  $r_v$  and  $r_\tau$  are zero, the quasi-likelihood function is twice D. These conditions are collected into

**Assumption 7 (D-Derivatives).** (i) For each  $\mathbf{d}$ ,  $DL_n(\boldsymbol{\theta}_*; \mathbf{d}) = DL_n^{(\pi)}(\mathbf{d}_\pi) + DL_n^{(\tau)}(\mathbf{d}_\tau)$ , and  $n^{-1/2}(DL_n^{(\pi)}(\cdot), DL_n^{(\tau)}(\cdot)) \Rightarrow (\mathcal{Z}^{(\pi)}(\cdot), \mathcal{Z}^{(\tau)}(\cdot))$ ; (ii) For each  $\mathbf{d}$  and  $\tilde{\mathbf{d}}$ ,  $B_*(\mathbf{d}, \tilde{\mathbf{d}}) = \boldsymbol{\iota}_3' \mathbf{B}_*(\mathbf{d}, \tilde{\mathbf{d}}) \boldsymbol{\iota}_3$ , where for each  $\mathbf{d}$ ,  $\mathbf{B}_*(\mathbf{d}, \mathbf{d})$  is symmetric and positive definite; (iii) For each  $\mathbf{d}$ ,  $A_*(\mathbf{d}) = \boldsymbol{\iota}_3' \mathbf{A}_*(\mathbf{d}) \boldsymbol{\iota}_3$ , where for each  $\mathbf{d}$ ,  $\mathbf{A}_*(\mathbf{d})$  is symmetric and negative definite; (iv)  $\mathbf{A}_*^{(\tau, \pi)}(\mathbf{d}_\tau, \mathbf{d}_\pi) = \mathbf{A}_*^{(\pi, \tau)}(\mathbf{d}_\pi, \mathbf{d}_\tau) = \mathbf{0}$  uniformly on  $\Delta(\boldsymbol{\theta}_*)$ ; (v)  $\boldsymbol{\Theta} = \boldsymbol{\Pi} \times \mathbf{T}$  and  $C(\boldsymbol{\theta}_*) = C(\boldsymbol{\pi}_*) \times C(\boldsymbol{\tau}_*)$ , where  $C(\boldsymbol{\pi}_*) := \{\mathbf{x} \in \mathbb{R}^{r_\pi} : \exists \boldsymbol{\pi}' \in \boldsymbol{\Pi}, \mathbf{x} := \boldsymbol{\pi}_* + \delta \boldsymbol{\pi}', \delta \in \mathbb{R}^+\}$  and  $C(\boldsymbol{\tau}_*) := \{\mathbf{x} \in \mathbb{R}^{r_\tau} : \exists \boldsymbol{\tau}' \in \mathbf{T}, \mathbf{x} := \boldsymbol{\tau}_* + \delta \boldsymbol{\tau}', \delta \in \mathbb{R}^+\}$ ; (vi)  $\boldsymbol{\Pi} = \boldsymbol{\Lambda} \times \boldsymbol{\Upsilon}$  and  $C(\boldsymbol{\pi}_*) = \mathbb{R}^{r_\lambda} \times C(\mathbf{v}_*)$ , where  $C(\mathbf{v}_*) := \{\mathbf{x} \in \mathbb{R}^{r_v} : \exists \mathbf{v}' \in \boldsymbol{\Upsilon}, \mathbf{x} := \mathbf{v}_* + \delta \mathbf{v}', \delta \in \mathbb{R}^+\}$ ; (vii)  $\boldsymbol{\lambda}_*$  is an interior element of  $\boldsymbol{\Lambda}$ .  $\square$

Assumptions 7(v and vi) let the parameter space  $\boldsymbol{\Theta}$  and  $\boldsymbol{\Pi}$  be the Cartesian products of two separate parameter spaces. We use this property to represent  $L_n(\cdot)$  as a sum of two independent functions at the limit as detailed below. Given this structure, we further let  $v$  be the parameter of interest, and the hypotheses of our interest are given as

$$H_0 : v_* = v_0, \quad \text{versus} \quad H_1 : v_* \neq v_0.$$

For our future reference, we also let  $\boldsymbol{\Theta}_0$  be the parameter space constrained by the null hypotheses. That is,  $\boldsymbol{\Theta}_0 := \{(v', \lambda', \tau')' \in \boldsymbol{\Theta} : v = v_0\}$ .

### 3.1 Qausi-Likelihood Ratio Test Statistic

The standard QLR test statistic defined by D quasi-likelihood functions can be used for D-D quasi-likelihood functions to test the given hypothesis. We formally define the QLR test statistic as

$$\mathcal{LR}_n := 2\{L_n(\hat{\theta}_n) - L_n(\ddot{\theta}_n)\},$$

where  $\ddot{\theta}_n$  is such that  $L_n(\ddot{\theta}_n) := \sup_{\theta \in \Theta_0} L_n(\theta)$ .

For the analysis of the QLR test statistic, we split  $\mathcal{LR}_n$  into  $\mathcal{LR}_n^{(1)}$  and  $\mathcal{LR}_n^{(2)}$  such that  $\mathcal{LR}_n^{(1)} := 2\{L_n(\hat{\theta}_n) - L_n(\theta_*)\}$  and  $\mathcal{LR}_n^{(2)} := 2\{L_n(\ddot{\theta}_n) - L_n(\theta_*)\}$ . Note that  $\mathcal{LR}_n^{(1)}$  tests whether the unknown parameter is  $\theta_*$  or not. Although Theorem 1(iii) already provides the limit distribution of  $\mathcal{LR}_n^{(1)}$ , we reexamine this here again by separating  $\Delta(\theta_*)$  into  $\Delta(\pi_*) := \{\mathbf{x} \in \mathbb{R}^{r_\pi} : \pi_* + \mathbf{x} \in \text{cl}\{C(\pi_*)\}, \|\mathbf{x}\| = 1\}$  and  $\Delta(\tau_*) := \{\mathbf{x} \in \mathbb{R}^{r_\tau} : \tau_* + \mathbf{x} \in \text{cl}\{C(\tau_*)\}, \|\mathbf{x}\| = 1\}$ . We denote their representative components as  $\mathbf{s}_\pi (= (s'_\lambda, s'_v)')$  and  $\mathbf{s}_\tau$ , respectively. Here, direction  $\mathbf{s}$  is used to distinguish its role from that of  $\mathbf{d} \in \Delta(\theta_*)$ . Note that  $\Delta(\pi_*)$  and  $\Delta(\tau_*)$  are subsets of  $\Delta(\theta_*)$ . This separation is useful in uncovering the limit distribution of  $\mathcal{LR}_n^{(2)}$ . The following theorem provides the null limit distribution of  $\mathcal{LR}_n$ :

**Theorem 2.** (i) Given Assumptions 1 to 7,  $\mathcal{LR}_n^{(1)} \Rightarrow \mathcal{H}_0 + \mathcal{H}_1 + \mathcal{H}_2$ , where

$$\mathcal{H}_0 := \sup_{\mathbf{s}_v \in \Delta(\mathbf{v}_*)} \max[0, \tilde{\mathcal{Y}}^{(v)}(\mathbf{s}_v)]^2; \quad \mathcal{H}_1 := \mathbf{Z}^{(\lambda)'} (-\mathbf{A}_*^{(\lambda, \lambda)})^{-1} \mathbf{Z}^{(\lambda)}; \quad \mathcal{H}_2 := \sup_{\mathbf{s}_\tau \in \Delta(\tau_*)} \max[0, \mathcal{Y}^{(\tau)}(\mathbf{s}_\tau)]^2$$

such that for each  $\mathbf{s}_v \in \Delta(\mathbf{v}_*) := \{\mathbf{x} \in \mathbb{R}^{r_v} : \mathbf{v}_* + \mathbf{x} \in \text{cl}\{C(\mathbf{v}_*)\}, \|\mathbf{x}\| = 1\}$ ,

$$\tilde{\mathcal{Y}}^{(v)}(\mathbf{s}_v) := (-\tilde{A}_*^{(v, v)}(\mathbf{s}_v))^{-1/2} \tilde{\mathcal{Z}}^{(v)}(\mathbf{s}_v); \quad \tilde{\mathcal{Z}}^{(v)}(\mathbf{s}_v) := \mathcal{Z}^{(v)}(\mathbf{s}_v) - \mathbf{A}_*^{(v, \lambda)}(\mathbf{s}_v)' (\mathbf{A}_*^{(\lambda, \lambda)})^{-1} \mathbf{Z}^{(\lambda)};$$

$$\tilde{A}_*^{(v, v)}(\mathbf{s}_v) := A_*^{(v, v)}(\mathbf{s}_v) - \mathbf{A}_*^{(v, \lambda)}(\mathbf{s}_v)' (\mathbf{A}_*^{(\lambda, \lambda)})^{-1} \mathbf{A}_*^{(\lambda, v)}(\mathbf{s}_v);$$

and for each  $\mathbf{s}_\tau$ ,  $\mathcal{Y}^{(\tau)}(\mathbf{s}_\tau) := \{-A_*^{(\tau, \tau)}(\mathbf{s}_\tau)\}^{-1/2} \mathcal{Z}^{(\tau)}(\mathbf{s}_\tau)$ ; (ii) Given Assumptions 1 to 3 and  $H_0$ ,  $\ddot{\theta}_n$  converges to  $\theta_*$  a.s.- $\mathbb{P}$ ; (iii) Given Assumptions 1 to 7 and  $H_0$ ,  $\mathcal{LR}_n^{(2)} \Rightarrow \mathcal{H}_1 + \mathcal{H}_2$ ; and (iv) Given Assumptions 1 to 7, and  $H_0$ ,  $\mathcal{LR}_n \Rightarrow \mathcal{H}_0$ .  $\square$

Several remarks are in order on Theorem 2. First, Theorem 2(iii) can be understood as a corollary of Theorem 2(i). Note that if  $r_v = 0$  as  $\mathbf{v}$  is fixed at  $\mathbf{v}_*$ , Theorem 2(i) implies that

$$\mathcal{LR}_n^{(2)} \Rightarrow \sup_{\mathbf{s}_\lambda \in \Delta(\lambda_*)} \left\{ \frac{\max[0, \mathbf{s}_\lambda' \mathbf{Z}^{(\lambda)}]^2}{\mathbf{s}_\lambda' (-\mathbf{A}_*^{(\lambda, \lambda)}) \mathbf{s}_\lambda} \right\} + \mathcal{H}_2 = \mathcal{H}_1 + \mathcal{H}_2. \quad (6)$$

Here, the final equality holds because  $\Delta(\boldsymbol{\lambda}_*) = \mathbb{R}^{r_\lambda}$  by Assumption 7(vi) and the null quasi-likelihood function is differentiable with respect to  $\boldsymbol{\lambda}$ . Second, the weak limit in Theorem 2(iii) is jointly achieved with that of  $\mathcal{LR}_n^{(1)}$  because all of these are obtained by applying the continuous mapping theorem (CMT) to Theorem 1(i). Furthermore,  $\mathcal{H}_1$  and  $\mathcal{H}_2$  in  $\mathcal{LR}_n^{(2)}$  are identical to those of  $\mathcal{LR}_n^{(1)}$ . Third,  $\tilde{\mathcal{Z}}^{(v)}(\cdot)$  is obtained by projecting  $\mathcal{Z}^{(v)}(\cdot)$  on  $\mathbf{Z}^{(\lambda)}$  because the QLR test statistic is constructed by minimizing the impact of the parameter estimation error that arises when estimating the unknown nuisance parameter  $\boldsymbol{\lambda}_*$ . Fourth, the orthogonality condition in Assumption 7(iv) and the parameter space condition in Assumption 7(v) asymptotically separate  $\mathcal{LR}_n^{(1)}$  into the sum of  $\mathcal{H}_0$ ,  $\mathcal{H}_1$ , and  $\mathcal{H}_2$  as given in Theorem 2(i). This implies that we can ignore the effects of  $\boldsymbol{\tau}$  when testing  $H_0$ . Fifth, the null limit distribution of the QLR test is more complicated than that in Theorem 2 in a general set-up. For example, if  $\boldsymbol{\lambda}_*$  is a boundary parameter or the Cartesian product representation in Assumption 7(vi) is not valid, the null limit distribution of the QLR test statistic is obtained as  $\mathcal{H}'_{01} - \mathcal{H}'_1$ , where

$$\mathcal{H}'_1 := \sup_{\mathbf{s}_\lambda \in \Delta(\boldsymbol{\lambda}_*)} \left\{ \frac{\max[0, \mathbf{s}_\lambda' \mathbf{Z}^{(\lambda)}]^2}{\mathbf{s}_\lambda' (-\mathbf{A}_*^{(\lambda, \lambda)}) \mathbf{s}_\lambda} \right\},$$

and

$$\mathcal{H}'_{01} := \sup_{(\mathbf{s}_\lambda, \mathbf{s}_\xi) \in \Delta(\boldsymbol{\pi}_*)} \left\{ \frac{\max[0, \mathcal{Z}^{(\xi)}(\mathbf{s}_\xi) + \mathbf{s}_\lambda' \mathbf{Z}^{(\lambda)}]^2}{-\mathbf{A}_*^{(\xi, \xi)}(\mathbf{s}_\xi) + 2\mathbf{s}_\lambda' (-\mathbf{A}_*^{(\lambda, \xi)}(\mathbf{s}_\xi)) + \mathbf{s}_\lambda' (-\mathbf{A}_*^{(\lambda, \lambda)}) \mathbf{s}_\lambda} \right\}.$$

Finally, Liu and Shao (2003) provide an alternative characterization of the quasi-likelihood ratio test using the Hellinger distance that obtains the null limit distribution as a functional of a Gaussian process as in Theorem 2. We leave the application of their methodology to the current context as a future research topic to satisfy the space constraint.

### 3.2 Wald Test Statistic

Before redefining the Wald test statistic, we first examine the null limit distribution of the distance between  $\hat{\mathbf{v}}_n$  and  $\mathbf{v}_0$ . Note that the distance between  $\hat{\boldsymbol{\theta}}_n$  and  $\boldsymbol{\theta}_*$  that is represented by  $\hat{h}_n(\cdot)$  cannot be used to test the null hypothesis because the inference on  $\mathbf{v}_*$  is mixed with that of the other nuisance parameters  $\boldsymbol{\lambda}_*$  and  $\boldsymbol{\tau}_*$ . The distance  $\hat{h}_n(\cdot)$  needs to be broken into pieces that correspond to  $\mathbf{v}$ ,  $\boldsymbol{\omega}$ , and  $\boldsymbol{\tau}$ , respectively, and this process is achieved by separating the set of directions  $\Delta(\boldsymbol{\theta}_*)$  into the sets of directions for  $\mathbf{v}$ ,  $\boldsymbol{\lambda}$ , and  $\boldsymbol{\tau}$ . Specifically, for any  $h\mathbf{d}$  and  $\mathbf{d} \in \Delta(\boldsymbol{\theta}_*)$ , there are  $h^{(v)}$ ,  $h^{(\lambda)}$ ,  $h^{(\tau)}$ , and  $(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau) \in \Delta(\mathbf{v}_*) \times \Delta(\boldsymbol{\lambda}_*) \times \Delta(\boldsymbol{\tau}_*)$  such that  $h\mathbf{d} = (h^{(v)}\mathbf{s}_v', h^{(\lambda)}\mathbf{s}_\lambda', h^{(\tau)}\mathbf{s}_\tau')'$  if each parameter space of  $\mathbf{v}$ ,  $\boldsymbol{\lambda}$ , and  $\boldsymbol{\tau}$  is approximated by a cone and the parameter space of  $\boldsymbol{\theta}$  is approximated by the Cartesian product of these cones, as assumed

in Assumptions 7. Therefore, the following equality holds:

$$\sup_{\mathbf{d}} \sup_h L_n(\boldsymbol{\theta}_* + h\mathbf{d}) = \sup_{\{\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau\}} \sup_{\{h^{(v)}, h^{(\lambda)}, h^{(\tau)}\}} L_n(\boldsymbol{\theta}_* + (h^{(v)}\mathbf{s}_v', h^{(\lambda)}\mathbf{s}_\lambda', h^{(\tau)}\mathbf{s}_\tau')'), \quad (7)$$

and we apply the Wald testing principle to  $\hat{h}_n^{(v)}(\cdot)$ .

For this purpose, we examine the limit distribution of  $\hat{\mathbf{h}}_n(\cdot) := (\hat{h}_n^{(v)}(\cdot), \hat{h}_n^{(\lambda)}(\cdot), \hat{h}_n^{(\tau)}(\cdot))'$ . For each  $(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau) \in \Delta(\mathbf{v}_*) \times \Delta(\boldsymbol{\lambda}_*) \times \Delta(\boldsymbol{\tau}_*)$ , we let

$$\begin{bmatrix} \mathcal{G}^{(v)}(\mathbf{s}_v, \mathbf{s}_\lambda) \\ \mathcal{G}^{(\lambda)}(\mathbf{s}_v, \mathbf{s}_\lambda) \\ \mathcal{G}^{(\tau)}(\mathbf{s}_\tau) \end{bmatrix} := \begin{bmatrix} \mathcal{G}^{(\pi)}(\mathbf{s}_v, \mathbf{s}_\lambda) \\ \mathcal{G}^{(\tau)}(\mathbf{s}_\tau) \end{bmatrix} := \begin{bmatrix} \{-\mathbf{A}_*^{(\pi, \pi)}(\mathbf{s}_v, \mathbf{s}_\lambda)\}^{-1} \mathcal{Z}^{(\pi)}(\mathbf{s}_v, \mathbf{s}_\lambda) \\ \{-\mathbf{A}_*^{(\tau, \tau)}(\mathbf{s}_\tau)\}^{-1} \mathcal{Z}^{(\tau)}(\mathbf{s}_\tau) \end{bmatrix},$$

where for each  $(\mathbf{s}_v, \mathbf{s}_\lambda)$ ,  $\mathcal{Z}^{(\pi)}(\mathbf{s}_v, \mathbf{s}_\lambda) := (\mathcal{Z}^{(v)}(\mathbf{s}_v), \mathbf{Z}^{(\lambda)'}\mathbf{s}_\lambda)'$ . Next, for each  $(\mathbf{s}_v, \mathbf{s}_\lambda) \in \Delta(\mathbf{v}_*) \times \Delta(\boldsymbol{\lambda}_*)$ , we also let

$$\begin{bmatrix} \dot{\mathcal{G}}^{(v)}(\mathbf{s}_v) \\ \dot{\mathcal{G}}^{(\lambda)}(\mathbf{s}_\lambda) \end{bmatrix} := \begin{bmatrix} \{-\mathbf{A}_*^{(v, v)}(\mathbf{s}_v)\}^{-1} \mathcal{Z}^{(v)}(\mathbf{s}_v) \\ \{\mathbf{s}_\lambda'(-\mathbf{A}_*^{(\lambda, \lambda)})\mathbf{s}_\lambda\}^{-1} \mathbf{Z}^{(\lambda)'}\mathbf{s}_\lambda \end{bmatrix}.$$

These constitute the limit behavior of  $\hat{\mathbf{h}}_n(\cdot)$ . First, note that both  $(\hat{h}_n^{(v)}(\cdot), \hat{h}_n^{(\lambda)}(\cdot))'$  and  $\hat{h}_n^{(\tau)}(\cdot)$  are initially defined on  $\Delta(\mathbf{v}_*) \times \Delta(\boldsymbol{\lambda}_*) \times \Delta(\boldsymbol{\tau}_*)$ , but supposing that  $\mathbf{A}_*^{(\pi, \tau)}(\mathbf{d}_\pi, \mathbf{d}_\tau) = 0$  renders the maximization process in the right side of (7) be asymptotically separated into two independent maximization procedures. Second,  $\hat{h}_n^{(v)}(\cdot)$  and  $\hat{h}_n^{(\lambda)}(\cdot)$  cannot be less than zero. Thus, for each  $(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau)$ , one of following four different events asymptotically arises: (i)  $\hat{h}_n^{(v)}(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau) > 0$  and  $\hat{h}_n^{(\lambda)}(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau) > 0$ ; (ii)  $\hat{h}_n^{(v)}(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau) > 0$ ,  $\hat{h}_n^{(\lambda)}(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau) = 0$ ; (iii)  $\hat{h}_n^{(v)}(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau) = 0$ ,  $\hat{h}_n^{(\lambda)}(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau) > 0$ ; and (iv)  $\hat{h}_n^{(v)}(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau) = 0$ ,  $\hat{h}_n^{(\lambda)}(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau) = 0$ . Note that these four different events are asymptotically determined by the sign of  $\mathcal{G}^{(\pi)}(\cdot)$  from the fact that it is asymptotically associated with the limit behavior of  $(\hat{h}_n^{(v)}(\cdot), \hat{h}_n^{(\lambda)}(\cdot))$ . Furthermore, their signs indicate how the parameter estimation error affects the asymptotic distribution of  $(\hat{h}_n^{(v)}(\cdot), \hat{h}_n^{(\lambda)}(\cdot))$ . For example, if  $\hat{h}_n^{(\lambda)}(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau) = 0$  and  $\hat{h}_n^{(v)}(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau) > 0$ , estimating the nuisance parameter  $\boldsymbol{\lambda}_*$  does not affect the limit distribution of  $\hat{h}_n^{(v)}(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau)$  because  $\hat{\boldsymbol{\lambda}}_n(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau) = \boldsymbol{\lambda}_*$  from the fact that  $\hat{h}_n^{(\lambda)}(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau) = 0$ , so that it does not have to be associated with the parameter estimation error of  $\hat{\boldsymbol{\lambda}}_n(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau)$ , implying that  $\sqrt{n}\hat{h}_n^{(v)}(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau) \Rightarrow \dot{\mathcal{G}}^{(v)}(\mathbf{s}_v)$ . For the cases of (iii) and (iv), the similar interpretations apply. If both  $\boldsymbol{\lambda}_*$  and  $\mathbf{v}_*$  are interior elements, both parameter estimation errors for  $\mathbf{v}_*$  and  $\boldsymbol{\lambda}_*$  cannot be avoided and have to be taken into account in obtaining the limit distribution of  $\hat{h}_n^{(v)}(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau)$  and  $\hat{h}_n^{(\lambda)}(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau)$ .

We now define the Wald test statistic as

$$\mathcal{W}_n := \sup_{\mathbf{s}_v \in \Delta(\mathbf{v}_0)} n \{ \tilde{h}_n^{(v)}(\mathbf{s}_v) \} \{ \widehat{W}_n(\mathbf{s}_v) \} \{ \tilde{h}_n^{(v)}(\mathbf{s}_v) \},$$

where  $\tilde{h}_n^{(v)}(\mathbf{s}_v)$  is such that for each  $\mathbf{s}_v \in \Delta(\mathbf{v}_0)$ ,  $L_n(\mathbf{v}_0 + \tilde{h}_n^{(v)}(\mathbf{s}_v)\mathbf{s}_v, \tilde{\boldsymbol{\lambda}}_n(\mathbf{s}_v), \tilde{\boldsymbol{\tau}}_n(\mathbf{s}_v)) = \sup_{\{h^{(v)}, \boldsymbol{\lambda}, \boldsymbol{\tau}\}} L_n(\mathbf{v}_0 + h^{(v)}\mathbf{s}_v, \boldsymbol{\lambda}, \boldsymbol{\tau})$ , and  $\widehat{W}_n(\cdot)$  is a weight function that estimates a non-random positive function  $\tilde{A}_*^{(v,v)}(\cdot)$  say, uniformly on  $\Delta(\mathbf{v}_0)$ . Note that  $\tilde{h}_n^{(v)}(\cdot)$  is equivalent to  $\widehat{h}_n^{(v)}(\cdot)$  under the null from the fact that  $\sup_{h^{(v)}, \boldsymbol{\lambda}, \boldsymbol{\tau}} L_n(\mathbf{v}_0 + h^{(v)}\mathbf{s}_v, \boldsymbol{\lambda}, \boldsymbol{\tau})$  is equivalent to  $\sup_{\{\mathbf{s}_\lambda, \mathbf{s}_\tau\}} \sup_{\{h^{(v)}, h^{(\lambda)}, h^{(\tau)}\}} L_n(\mathbf{v}_0 + h^{(v)}\mathbf{s}_v, \boldsymbol{\lambda}_* + h^{(\lambda)}\mathbf{s}_\lambda, \boldsymbol{\tau}_* + h^{(\tau)}\mathbf{s}_\tau)$ . This equivalency does not hold under the alternative, and from this, the power of the Wald test is acquired. As the weight function is an important component of the Wald test statistic, we formally state its condition as follows:

**Assumption 8** (Weight Function I).  $\widehat{W}_n(\cdot)$ , which is strictly positive uniformly on  $\Delta(\mathbf{v}_0)$  and for every  $n$ , converges to  $\tilde{A}_*^{(v,v)}(\cdot)$  a.s.- $\mathbb{P}$  uniformly on  $\Delta(\mathbf{v}_0)$  as  $n$  tends to infinity. That is,  $\sup_{\mathbf{s}_v} |\widehat{W}_n(\mathbf{s}_v) - \tilde{A}_*^{(v,v)}(\mathbf{s}_v)| \rightarrow 0$  a.s.- $\mathbb{P}$ .  $\square$

In the Wald testing context, the weight function  $\tilde{A}_*^{(v,v)}(\cdot)$  is typically the asymptotic variance function of  $\sqrt{n}\tilde{h}_n^{(v)}(\cdot)$ . If the parameter of interest is on the boundary, the weight function needs to be carefully chosen because the asymptotic variance function of  $\sqrt{n}\tilde{h}_n^{(v)}(\cdot)$  is different from the interior parameter case.

The null limit distribution of the Wald test statistic is obtained as follows:

**Theorem 3.** Given Assumptions 1 to 8, and  $H_0$ , if  $\max[0, \tilde{\mathcal{Y}}(\cdot)]^2$  is uniquely maximized a.s.- $\mathbb{P}$ ,  $\mathcal{W}_n \Rightarrow \mathcal{H}_0$ .  $\square$

Note that the weak limit of the Wald test statistic in Theorem 3 is identical to that given in Theorem 2. We prove Theorem 3 by noting that for each  $\mathbf{s}_v$ , maximizing  $2\{L_n(\mathbf{v}_0 + h^{(v)}\mathbf{s}_v, \boldsymbol{\lambda}, \boldsymbol{\tau}) - L_n(\mathbf{v}_0, \boldsymbol{\lambda}_*, \boldsymbol{\tau}_*)\}$  with respect to  $h^{(v)}$ ,  $\boldsymbol{\lambda}$ , and  $\boldsymbol{\tau}$  is equivalent to

$$\sup_{\{\mathbf{s}_\lambda, \mathbf{s}_\tau\}} \sup_{\{h^{(v)}, h^{(\lambda)}, h^{(\tau)}\}} 2\{L_n(\mathbf{v}_0 + h^{(v)}\mathbf{s}_v, \boldsymbol{\lambda}_* + h^{(\lambda)}\mathbf{s}_\lambda, \boldsymbol{\tau}_* + h^{(\tau)}\mathbf{s}_\tau) - L_n(\mathbf{v}_0, \boldsymbol{\lambda}_*, \boldsymbol{\tau}_*)\}. \quad (8)$$

For each  $(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau)$ , (8) is approximated by a quadratic function of  $(h^{(v)}, h^{(\lambda)}, h^{(\tau)})$ , and the signs of  $\widehat{h}_n^{(v)}(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau)$  and  $\widehat{h}_n^{(\lambda)}(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau)$  result in different approximations as discussed earlier. Using Assumption 7(vii), we show that the optimization process in (8) results in the consequence of Theorem 3.



### 3.3 Lagrange Multiplier Test Statistic

The standard LM test statistic can also be appropriately redefined for D-D quasi-likelihood functions to test whether the slopes of quasi-likelihood functions are distributed around zero under the null. We let the LM test statistic be defined as

$$\mathcal{LM}_n := \sup_{(\mathbf{s}_v, \mathbf{s}_\lambda) \in \Delta(\mathbf{v}_0) \times \Delta(\ddot{\boldsymbol{\lambda}}_n)} n \max \left[ 0, \frac{-DL_n(\ddot{\boldsymbol{\theta}}_n; \mathbf{s}_v)}{\widetilde{D}^2 L_n(\ddot{\boldsymbol{\theta}}_n; \mathbf{s}_v; \mathbf{s}_\lambda)} \right]^2 \widetilde{W}_n(\mathbf{s}_v, \mathbf{s}_\lambda),$$

where for each  $(\mathbf{s}_v, \mathbf{s}_\lambda)$ ,  $\Delta(\ddot{\boldsymbol{\lambda}}_n) := \{\mathbf{x} \in \mathbb{R}^{r_\omega} : \mathbf{x} + \ddot{\boldsymbol{\lambda}}_n \in \text{cl}\{C(\ddot{\boldsymbol{\lambda}}_n)\}, \|\mathbf{x}\| = 1\}$ ,

$$\widetilde{D}^2 L_n(\ddot{\boldsymbol{\theta}}_n; \mathbf{s}_v; \mathbf{s}_\lambda) := D^2 L_n(\ddot{\boldsymbol{\theta}}_n; \mathbf{s}_v) - DL_n(\ddot{\boldsymbol{\theta}}_n; \mathbf{s}_v; \mathbf{s}_\lambda) (D^2 L_n(\ddot{\boldsymbol{\theta}}_n; \mathbf{s}_\lambda))^{-1} DL_n(\ddot{\boldsymbol{\theta}}_n; \mathbf{s}_\lambda; \mathbf{s}_v),$$

$$DL_n(\ddot{\boldsymbol{\theta}}_n; \mathbf{s}_v; \mathbf{s}_\lambda) := \lim_{h \downarrow 0} h^{-1} \{DL_n(\mathbf{v}_0, \ddot{\boldsymbol{\lambda}}_n + h\mathbf{s}_\lambda, \ddot{\boldsymbol{\tau}}_n; \mathbf{s}_v) - DL_n(\ddot{\boldsymbol{\theta}}_n; \mathbf{s}_v)\},$$

$$DL_n(\ddot{\boldsymbol{\theta}}_n; \mathbf{s}_\lambda; \mathbf{s}_v) := \lim_{h \downarrow 0} h^{-1} \{DL_n(\mathbf{v}_0 + h\mathbf{s}_v, \ddot{\boldsymbol{\lambda}}_n, \ddot{\boldsymbol{\tau}}_n; \mathbf{s}_\lambda) - DL_n(\ddot{\boldsymbol{\theta}}_n; \mathbf{s}_\lambda)\},$$

and  $\widetilde{W}_n(\cdot)$  is a weight function that satisfies

**Assumption 9** (Weight Function II). *A weight function  $\widetilde{W}_n(\cdot)$ , which is strictly positive uniformly on  $\Delta(\mathbf{v}_0) \times \Delta(\ddot{\boldsymbol{\lambda}}_n)$  and for every  $n$ , converges to  $\widetilde{A}_*^{(v,v)}(\cdot)$  a.s.- $\mathbb{P}$  uniformly on  $\Delta(\mathbf{v}_0) \times \Delta(\ddot{\boldsymbol{\lambda}}_n)$  as  $n$  tends to infinity. That is,  $\sup_{(\mathbf{s}_v, \mathbf{s}_\lambda) \in \Delta(\mathbf{v}_0) \times \Delta(\ddot{\boldsymbol{\lambda}}_n)} |\widetilde{W}_n(\mathbf{s}_v, \mathbf{s}_\lambda) - \widetilde{A}_*^{(v,v)}(\mathbf{s}_v)| \rightarrow 0$  a.s.- $\mathbb{P}$ .  $\square$*

There are several remarks relevant to the definition of the LM test statistic. First, the LM test statistic has a structure that yields the same null limit distribution as those of the QLR and Wald tests. That is, the LM test statistic is defined using the first and second-order directional derivatives of  $L_n(\mathbf{v}_0 + h^{(v)}\mathbf{s}_v, \ddot{\boldsymbol{\lambda}}_n + h^{(\lambda)}\mathbf{s}_\lambda, \ddot{\boldsymbol{\tau}}_n + h^{(\tau)}\mathbf{s}_\tau)$  with respect to  $\mathbf{s}_v$  and  $\mathbf{s}_\lambda$ , where  $(\mathbf{v}_0', \ddot{\boldsymbol{\lambda}}_n', \ddot{\boldsymbol{\tau}}_n')' = \ddot{\boldsymbol{\theta}}_n$ , and ‘max’ operator is used to capture the non-negativity property of  $\sqrt{n}\widehat{h}_n^{(v)}(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau)$ . Second, the LM test statistic is asymptotically the supremum of a squared random score function with respect to  $(\mathbf{s}_v, \mathbf{s}_\lambda)$ , provided that  $\widetilde{W}_n(\cdot)$  is asymptotically equivalent to  $-n^{-1}\widetilde{D}^2 L_n(\ddot{\boldsymbol{\theta}}_n; \cdot)$ . Third,  $\widetilde{W}_n(\cdot)$  is defined on  $\Delta(\mathbf{v}_0) \times \Delta(\ddot{\boldsymbol{\lambda}}_n)$ , and  $\boldsymbol{\lambda}_*$  is an interior element of  $\boldsymbol{\Omega}$ . Note that the domain  $\Delta(\ddot{\boldsymbol{\lambda}}_n)$  estimates  $\Delta(\boldsymbol{\lambda}_*)$ . The interiority condition lets  $\Delta(\ddot{\boldsymbol{\lambda}}_n)$  converge to  $\Delta(\boldsymbol{\lambda}_*)$  asymptotically. If  $\boldsymbol{\lambda}_*$  is on the boundary,  $\Delta(\ddot{\boldsymbol{\lambda}}_n)$  can be different from  $\Delta(\boldsymbol{\lambda}_*)$ , and the null limit distribution of the LM test statistic is affected by this. Assumption 7(vii) precludes this possibility.

The null limit distribution of the LM test statistic is straightforwardly obtained as follows:

**Theorem 4.** *Given Assumptions 1 to 7, 9, and  $H_0$ , if  $\max[0, \widetilde{\mathcal{Y}}(\cdot)]^2$  is uniquely maximized a.s.- $\mathbb{P}$ ,  $\mathcal{LM}_n \Rightarrow \sup_{\mathbf{s}_v \in \Delta(\mathbf{v}_0)} \max[0, \widetilde{\mathcal{Y}}^{(v)}(\mathbf{s}_v)]^2$ .  $\square$*

Therefore, the QLR, Wald, and LM test statistics are asymptotically equivalent under the null.

## 4 Example: Conditional Heteroskedasticity

King and Shively (1993) examine a model for conditional heteroskedasticity. When a set of economic data  $\{(Y_t, \mathbf{Q}'_t)' := (Y_t, W_t, \mathbf{R}'_t)' \in \mathbb{R}^{2+k}\}$  is given, they assume

$$\mathbf{Y}^n = \mathbf{W}^n \alpha_* + \mathbf{R}^n \beta_* + \mathbf{U}^n, \quad \mathbf{U}^n | \mathbf{Q}^n \sim N[\mathbf{0}, \sigma_*^2 \{\mathbf{I}_n + \kappa_* \boldsymbol{\Omega}^n(\rho_*)\}],$$

where  $\mathbf{Y}^n := (Y_1, \dots, Y_n)'$ ,  $\mathbf{U}^n := (U_1, \dots, U_n)'$ ,  $\mathbf{W}^n := (W_1, \dots, W_n)'$ ,  $\mathbf{R}^n$  is an  $n \times k$  matrix with  $\mathbf{R}_t'$  at  $t$ -th row,  $\mathbf{Q}^n := (\mathbf{W}^n, \mathbf{R}^n)$ , and  $\boldsymbol{\Omega}^n(\rho_*)$  is an  $n \times n$  square matrix with  $t$ -th row and  $t'$ -th column element  $\Omega_{tt'}^n(\rho_*) := W_t W_{t'} \rho_*^{|t'-t|} / (1 - \rho_*^2)$ . Given this, they let  $(\gamma'_*, \sigma_*^2, \kappa_*, \rho_*) := (\alpha_*, \beta'_*, \sigma_*^2, \kappa_*, \rho_*)$  be an unknown parameter in  $\boldsymbol{\Gamma} \times [0, \bar{\sigma}^2] \times [0, \bar{\kappa}] \times [0, \bar{\rho}]$ , where  $\boldsymbol{\Gamma}$  is a compact and convex subset of  $\mathbb{R}^{k+1}$ ,  $\bar{\sigma}^2$  and  $\bar{\kappa}$  are positive real numbers, and  $\bar{\rho}$  is also a positive real number but less than one. For each  $(\gamma, \sigma^2, \kappa, \rho)$ , its log-likelihood is written as

$$L_n(\gamma, \sigma^2, \kappa, \rho) = -\frac{1}{2} \log \left( (2\pi)^n \det [\sigma^2 \{\mathbf{I}_n + \kappa \boldsymbol{\Omega}^n(\rho)\}] \right) - \frac{1}{2\sigma^2} \mathbf{U}^n(\gamma)' [\mathbf{I}_n + \kappa \boldsymbol{\Omega}^n(\rho)]^{-1} \mathbf{U}^n(\gamma),$$

where  $\mathbf{U}^n(\gamma) := \mathbf{Y}^n - \mathbf{Q}^n \gamma$ , and  $\gamma := (\alpha, \beta')'$ .

This model is motivated by Rosenberg (1973), who aims to test  $\kappa_* = 0$  and examine whether a systematic risk of an asset is time-varying or not. If  $\kappa_* \neq 0$ , the conditional covariance of  $\mathbf{U}^n | \mathbf{Q}^n$  depends on  $\mathbf{W}^n$ , so that it is conditionally heteroskedastic. On the other hand, if  $\kappa_* = 0$ ,  $\rho_*$  is not identified, and Davies's (1977, 1987) identification problem arises. This renders the null limit distributions of the standard tests non-standard as they often result in functionals of a Gaussian stochastic process.

King and Shively (1993) attempt to resolve the unidentified parameter problem by reparameterizing the original model using the polar coordinates:

$$\boldsymbol{\theta}'_* := (\theta_{1*}, \theta_{2*}) := (\kappa_* \cos(\rho_* \pi / 2), \kappa_* \sin(\rho_* \pi / 2)),$$

so that the parameter space of  $\boldsymbol{\theta}$  is now obtained as  $[0, \bar{\kappa} \cos(\bar{\rho} \pi / 2)] \times [0, \bar{\kappa} \sin(\bar{\rho} \pi / 2)]$ , and

$$\mathbf{U}^n | \mathbf{Q}^n \sim N[0, \sigma_*^2 \{\mathbf{I}_n + (\boldsymbol{\theta}_* \boldsymbol{\theta}_*)^{1/2} \boldsymbol{\Omega}^n(2 \tan^{-1}(\theta_{2*} / \theta_{1*}) / \pi)\}].$$

Furthermore, the original hypotheses are rephrased into  $H'_0 : \boldsymbol{\theta}_* \boldsymbol{\theta}_* = 0$  versus  $H'_1 : \boldsymbol{\theta}_* \boldsymbol{\theta}_* > 0$  by the

reparameterization, and the identification problem does no longer arise under  $H'_0$ .

On the other hand, the quasi-likelihood function obtained in this way is only D-D under  $H'_0$ , and the null parameter value is on the boundary: for each  $(\gamma, \sigma^2, \theta)$ , the log-likelihood is modified into

$$L_n(\gamma, \sigma^2, \theta) = -\frac{n}{2} \log(2\pi) - \frac{1}{2} \log \left( \det \left[ \sigma^2 \{ \mathbf{I}_n + (\theta' \theta)^{1/2} \boldsymbol{\Omega}^n (2 \tan^{-1}(\theta_2/\theta_1)/\pi) \} \right] \right) \\ - \frac{1}{2\sigma^2} \mathbf{U}^n(\gamma)' \left[ \mathbf{I}_n + (\theta' \theta)^{1/2} \boldsymbol{\Omega}^n (2 \tan^{-1}(\theta_2/\theta_1)/\pi) \right]^{-1} \mathbf{U}^n(\gamma),$$

and from this,  $\theta_{2*}/\theta_{1*}$  has the form of  $0/0$  under the null, and this lets  $\tan^{-1}(0/0)$  be undefined. In addition, for each  $\mathbf{d} := (\mathbf{d}'_\gamma, d_\sigma, d_1, d_2)'$  such that  $\theta_* = \mathbf{0}$  and  $\mathbf{d}'\mathbf{d} = 1$ ,

$$\lim_{h \downarrow 0} L_n(\gamma_* + \mathbf{d}_\gamma h, \sigma_*^2 + d_\sigma h, \theta_* + \mathbf{d}_\theta h) = -\frac{n}{2} \log(2\pi \det(\sigma_*^2)) - \frac{1}{2\sigma_*^2} \mathbf{U}^n(\gamma_*)' \mathbf{U}^n(\gamma_*)$$

because  $0 \times \tan^{-1}(\cdot) \equiv 0$  on the Euclidean real line. Therefore, the null log-likelihood desired by Rosenberg (1973) and King and Shively (1993) is obtained. We further note that

$$DL_n(\gamma_*, \sigma_*^2, \theta_*; \mathbf{d}) = -\frac{nd_\sigma^2}{2\sigma_*^2} - \frac{(d_1^2 + d_2^2)^{1/2}}{2} \text{tr}[\boldsymbol{\Omega}^n (2 \tan^{-1}(d_2/d_1)/\pi)] + \frac{d_\sigma^2}{2\sigma_*^4} \mathbf{U}^{n'} \mathbf{U}^n \\ + \frac{1}{\sigma_*^2} (\mathbf{Q}^n \mathbf{d}_\gamma)' \mathbf{U}^n + \frac{(d_1^2 + d_2^2)^{1/2}}{2\sigma_*^2} \mathbf{U}^{n'} \boldsymbol{\Omega}^n (2 \tan^{-1}(d_2/d_1)/\pi) \mathbf{U}^n \quad (9)$$

that is not linear with respect to  $(d_1, d_2)$ , implying that the quasi-likelihood function is not D. The second-order directional derivative is also obtained as

$$D^2 L_n(\gamma_*, \sigma_*^2, \theta_*; \mathbf{d}) = \frac{nd_\sigma^2}{2\sigma_*^4} - \frac{d_\sigma^2}{\sigma_*^6} \mathbf{U}^{n'} \mathbf{U}^n - \frac{1}{\sigma_*^2} (\mathbf{Q}^n \mathbf{d}_\gamma)' (\mathbf{Q}^n \mathbf{d}_\gamma) \\ - \frac{2d_\sigma^2}{\sigma_*^4} (\mathbf{Q}^n \mathbf{d}_\gamma)' \mathbf{U}^n - \sqrt{d_1^2 + d_2^2} \left\{ \frac{d_\sigma^2}{\sigma_*^4} \mathbf{U}^{n'} - \frac{2}{\sigma_*^2} (\mathbf{Q}^n \mathbf{d}_\gamma)' \right\} [\boldsymbol{\Omega}^n (2 \tan^{-1}(d_2/d_1)/\pi)] \mathbf{U}^n \\ + (d_1^2 + d_2^2) \left\{ \frac{1}{2} \text{tr} [\boldsymbol{\Omega}^n (2 \tan^{-1}(d_2/d_1)/\pi)^2] - \frac{1}{\sigma_*^2} \mathbf{U}^{n'} [\boldsymbol{\Omega}^n (2 \tan^{-1}(d_2/d_1)/\pi)]^2 \mathbf{U}^n \right\}. \quad (10)$$

Note that this is not quadratic with respect to  $\mathbf{d}$ , so that the quasi-likelihood function is not twice D.

We elaborate on the model assumption for an appropriate analysis. If  $d_1$  is zero,  $d_2/d_1$  is not properly defined. We avoid this by letting  $d_2/d_1$  have an upper bound. This restriction is equivalent to letting the parameter space of  $\rho$  in the original model have an upper bound strictly less than unity. We also do not allow that  $d_2 = 0$ . If it is allowed, the diagonal elements of  $\boldsymbol{\Omega}^n(0)$  contain  $0^0$ , so that the model is not again appropriately identified. Furthermore, Rosenberg's (1973) original purpose to test for conditional heteroskedasticity does not allow the null model to have a time-varying variance. We therefore let  $d_2$  be

strictly positive. Imposing this lower bound condition is equivalent to letting  $\rho$  be away from zero in terms of the original model. Consequently, our parameter space for  $\theta$  is refined into

$$\Theta := \{\theta \in [0, \bar{\kappa} \cos(\bar{\pi}/2)] \times [0, \bar{\kappa} \sin(\bar{\pi}/2)] : \underline{c} \times \theta_1 \leq \theta_2 \leq \bar{c} \times \theta_1 \exists \underline{c} \text{ and } \bar{c} > 0\}.$$

By this modification,  $d_2/d_1$  is constrained to  $[\underline{c}, \bar{c}]$ , and we can also avoid the multifold identification problem of Cho and Ishida (2012), Cho, Ishida, and White (2011,2014), Baek, Cho, and Phillips (2015), and Cho and Phillips (2016).

The first-order directional derivative in (9) can be partitioned into three pieces:  $DL_n(\gamma_*, \sigma_*^2, \theta_*; \mathbf{d}) = Z_{1,n}(\mathbf{d}) + Z_{2,n}(\mathbf{d}) + Z_{3,n}(\mathbf{d})$ , where for each  $\mathbf{d}$ ,

$$Z_{1,n}(\mathbf{d}) := \frac{\mathbf{d}\gamma_*'}{\sigma_*^2} \sum_{t=1}^n \mathbf{Q}_t U_t, \quad Z_{2,n}(\mathbf{d}) := \sum_{t=1}^n \left[ \frac{d_{\sigma^2}}{2\sigma_*^4} + \frac{(d_1^2 + d_2^2)^{1/2} W_t^2}{2\sigma_*^2 \{1 - m(d_2/d_1)^2\}} \right] (U_t^2 - \sigma_*^2),$$

$$Z_{3,n}(\mathbf{d}) := \frac{(d_1^2 + d_2^2)^{1/2}}{\sigma_*^2 \{1 - m(d_2/d_1)^2\}} \sum_{t=2}^n U_t W_t \sum_{t'=1}^{t-1} U_{t'} W_{t'} m(d_2/d_1)^{t-t'},$$

and  $m(d_2/d_1) := 2 \tan^{-1}(d_2/d_1)/\pi$ . Here,  $\{\mathbf{Q}_t U_t\}$  and  $\{U_t^2 - \sigma_*^2\}$  are sequences of identically and independently distributed (IID) random variables, and  $\{U_t W_t \sum_{t'=1}^{t-1} U_{t'} W_{t'} m(d_2/d_1)^{t-t'}\}$  is a martingale difference array (MDA), so that Assumption 6(iv) holds for  $Z_{1,n}(\mathbf{d})$ ,  $Z_{2,n}(\mathbf{d})$ , and  $Z_{3,n}(\mathbf{d})$ , and the CLT for MDA can be applied to them. Furthermore, the asymptotic tightness also holds for  $n^{-1/2} DL_n(\gamma_*, \sigma_*^2, \theta_*; \cdot)$ . As  $Z_{1,n}(\cdot)$  and  $Z_{2,n}(\cdot)$  are linear with respect to  $\mathbf{Q}_t U_t$  and  $(U_t^2 - \sigma_*^2)$ , respectively, it is trivial to show their asymptotic tightness. For the asymptotic tightness of  $Z_{3,n}(\cdot)$ , we let  $\varepsilon_t := W_t U_t$  and  $m := m(d_2/d_1)$  and show that  $\{n^{-1/2} \sum_{t=2}^n \varepsilon_t \sum_{t'=1}^{t-1} \varepsilon_{t'} m^{t-t'}\}$  is asymptotically tight by applying Hansen (1996b). First, his theorem 1 holds if  $E[W_t^4] < \Delta^4 < \infty$ . Next, his  $\lambda$  and  $a$  are identical to 1 in our context, so that

$$\limsup_{n \rightarrow \infty} \frac{1}{n} \sum_{t=1}^n E[\varepsilon_t^2 (\sum_{\tau=1}^{t-1} \varepsilon_\tau m^{t-\tau})^2] = (\sigma_* \Delta)^4 \left( \frac{m^2}{1 - m^2} \right) < \infty$$

for any  $m$ , and the Lipschitz constant  $M_t := \sum_{\tau=1}^{t-1} (t - \tau) \ddot{m}^{t-\tau-1} |\varepsilon_t \varepsilon_\tau|$  satisfies the moment condition:

$$\limsup_{n \rightarrow \infty} \frac{1}{n} \sum_{t=1}^n E[M_t^2] = (\sigma_* \Delta)^4 \left( \frac{1 + 2\ddot{m} - 2\ddot{m}^3 - \ddot{m}^4}{(1 - \ddot{m})^5 (1 + \ddot{m})^3} \right) < \infty$$

by the standard argument that  $|m|$  is uniformly and strictly bounded by 1 and  $E[|\varepsilon_t^2 \varepsilon_\tau \varepsilon_{t'}|] < (\sigma_* \Delta)^4 < \infty$ , where  $\ddot{m} := \max[|m(\underline{c})|, |m(\bar{c})|]$ . These facts imply that his theorem 2 holds, and Assumption 5(iii)

also follows from this:  $n^{-1/2}DL_n(\gamma_*, \sigma_*^2, \theta_*; \cdot) \Rightarrow \mathcal{Z}(\cdot)$ , where for each  $\mathbf{d}$  and  $\tilde{\mathbf{d}}$ ,  $E[\mathcal{Z}(\mathbf{d})\mathcal{Z}(\tilde{\mathbf{d}})] = B_*(\mathbf{d}, \tilde{\mathbf{d}}) := B_*^{(1)}(\mathbf{d}, \tilde{\mathbf{d}}) + B_*^{(2)}(\mathbf{d}, \tilde{\mathbf{d}}) + B_*^{(3)}(\mathbf{d}, \tilde{\mathbf{d}})$  with  $(\mathbf{d}, \tilde{\mathbf{d}})$ ,  $B_*^{(1)}(\mathbf{d}, \tilde{\mathbf{d}}) := \frac{1}{\sigma_*^2} \mathbf{d}_\gamma' E[\mathbf{Q}_t \mathbf{Q}_t'] \tilde{\mathbf{d}}_\gamma$ ,

$$B_*^{(2)}(\mathbf{d}, \tilde{\mathbf{d}}) := E \left\{ \left[ \frac{d_{\sigma^2}}{\sqrt{2}\sigma_*^2} + \frac{(d_1^2 + d_2^2)^{1/2} W_t^2}{\sqrt{2}\{1 - m^2\}} \right] \left[ \frac{\tilde{d}_{\sigma^2}}{\sqrt{2}\sigma_*^2} + \frac{(\tilde{d}_1^2 + \tilde{d}_2^2)^{1/2} W_t^2}{\sqrt{2}\{1 - \tilde{m}^2\}} \right] \right\},$$

$$B_*^{(3)}(\mathbf{d}, \tilde{\mathbf{d}}) := \frac{(d_1^2 + d_2^2)^{1/2} (\tilde{d}_1^2 + \tilde{d}_2^2)^{1/2}}{\{1 - m^2\}\{1 - \tilde{m}^2\}} \left[ \frac{m\tilde{m}E[W_t^2]^2}{1 - m\tilde{m}} \right],$$

and  $\tilde{m} := m(\tilde{d}_2/\tilde{d}_1)$ .

The limit behavior of the second-order directional derivative is related to  $B_*(\mathbf{d}, \tilde{\mathbf{d}})$ . By applying the law of large numbers to (10), we obtain

$$\begin{aligned} D^2 L_n(\gamma_*, \sigma_*^2, \theta_*; \mathbf{d}) &= -\frac{nd_{\sigma^2}^2}{2\sigma_*^4} - \frac{1}{\sigma_*^2} \mathbf{d}_\gamma' \mathbf{Q}^{n'} \mathbf{Q}^n \mathbf{d}_\gamma - \frac{d_{\sigma^2}(d_1^2 + d_2^2)^{1/2}}{\sigma_*^4} \mathbf{U}^{n'} [\boldsymbol{\Omega}^n(m)] \mathbf{U}^n \\ &\quad + \frac{(d_1^2 + d_2^2)}{2} \left\{ \text{tr} [\boldsymbol{\Omega}^n(m)^2] - \frac{2}{\sigma_*^2} \mathbf{U}^{n'} [\mathbf{D}^n(m) + \mathbf{O}^n(m)] \mathbf{U}^n \right\} + o_{\mathbb{P}}(n), \end{aligned}$$

where  $\mathbf{D}^n(\cdot)$  is a diagonal matrix with the diagonal elements of  $\boldsymbol{\Omega}^n(\cdot)^2$ , and  $\mathbf{O}^n(\cdot)$  is an off-diagonal elements of  $\boldsymbol{\Omega}^n(\cdot)^2$  with zero diagonal elements, so that  $\mathbf{D}^n(\cdot) + \mathbf{O}^n(\cdot) \equiv \boldsymbol{\Omega}^n(\cdot)^2$ . Applying theorem 3.7.2 of Stout (1974) shows that  $n^{-1}D^2 L_n(\gamma_*, \sigma_*^2, \theta_*; \mathbf{d}) = -B_*(\mathbf{d}, \mathbf{d}) + o_{\mathbb{P}}(1)$ . The ULLN further strengthens this:  $\sup_{\mathbf{d}} |n^{-1}D^2 L_n(\gamma_*, \sigma_*^2, \theta_*; \mathbf{d}) + B_*(\mathbf{d}, \mathbf{d})| = o_{\mathbb{P}}(1)$ , that also leads to the information matrix equality. This follows mainly because  $D^2 L_n(\gamma_*, \sigma_*^2, \theta_*; \cdot)$  is differentiable on  $\Delta(\theta_*)$ , so that Assumption 5(iii) holds with respect to the second-order directional derivatives. Therefore,  $2\{L_n(\hat{\gamma}_n, \hat{\sigma}_n^2, \hat{\theta}_n) - L_n(\gamma_*, \sigma_*^2, \theta_*)\} \Rightarrow \sup_{\mathbf{d}} [0, \mathcal{Y}(\mathbf{d})]^2$  by Theorem 1(iii), where  $\mathcal{Y}(\mathbf{d}) := \{B_*(\mathbf{d}, \mathbf{d})\}^{-1/2} \mathcal{Z}(\mathbf{d})$ , and for each  $\mathbf{d}$  and  $\tilde{\mathbf{d}}$ ,

$$E[\mathcal{Y}(\mathbf{d})\mathcal{Y}(\tilde{\mathbf{d}})] = \frac{B_*(\mathbf{d}, \tilde{\mathbf{d}})}{\{B_*(\mathbf{d}, \mathbf{d})\}^{1/2} \{B_*(\tilde{\mathbf{d}}, \tilde{\mathbf{d}})\}^{1/2}}.$$

The main interests of King and Shively (1993) can be analyzed by the three test statistics. First, we reconcile the parameters in the model with the parameters defined in the previous section. Specifically, we let  $\mathbf{v} = (\theta_1, \theta_2)'$ ,  $\lambda = \sigma^2$ ,  $\tau = \gamma$ , and  $\boldsymbol{\pi} = (\sigma^2, \theta_1, \theta_2)'$ . Then, for each  $\mathbf{d}$  and  $\tilde{\mathbf{d}}$ ,

$$\mathbf{B}_*(\mathbf{d}, \tilde{\mathbf{d}}) = \begin{bmatrix} \mathbf{B}_*^{(\boldsymbol{\pi}, \boldsymbol{\pi})}(\mathbf{d}_\pi, \tilde{\mathbf{d}}_\pi) & \mathbf{0}' \\ \mathbf{0} & \frac{1}{\sigma_*^2} \mathbf{d}_\gamma' E[\mathbf{Q}_t \mathbf{Q}_t'] \tilde{\mathbf{d}}_\gamma \end{bmatrix},$$

and

$$\mathbf{B}_*^{(\pi, \pi)}(\mathbf{d}_\pi, \tilde{\mathbf{d}}_\pi) = \begin{bmatrix} \frac{1}{2\sigma_*^4} d_{\sigma^2} \tilde{d}_{\sigma^2} & \frac{1}{2\sigma_*^2} d_{\sigma^2} \tilde{h} E[W_t^2] \\ \frac{1}{2\sigma_*^2} \tilde{d}_{\sigma^2} h E[W_t^2] & h \tilde{h} \left[ \frac{1}{2} E[W_t^4] + k E[W_t^2]^2 \right] \end{bmatrix},$$

where for each  $(d_1, d_2)$  and  $(\tilde{d}_1, \tilde{d}_2)$ ,  $\tilde{h} := h(\tilde{d}_1, \tilde{d}_2)$ ,  $h := h(d_1, d_2) := (d_1^2 + d_2^2)^{1/2}/(1 - m^2)$ , and  $k := k(d_2/d_1, \tilde{d}_2/\tilde{d}_1) := m\tilde{m}/(1 - m\tilde{m})$ . Because of the information matrix equality and the fact that  $\mathbf{B}_*(\mathbf{d}, \tilde{\mathbf{d}})$  is block diagonal, the null limit distribution associated with each block matrix can be separately examined. Furthermore,  $\sigma_*^{-2} \mathbf{d}_\gamma' E[\mathbf{Q}_t \mathbf{Q}_t'] \tilde{\mathbf{d}}_\gamma$  is associated only with  $\gamma$ , so that it can be ignored, when deriving the null limit distributions of the test statistics. We further note that  $\boldsymbol{\nu}_3' \mathbf{B}_*(\mathbf{d}, \tilde{\mathbf{d}}) \boldsymbol{\nu}_3 = B_*^{(1)}(\mathbf{d}, \tilde{\mathbf{d}}) + B_*^{(2)}(\mathbf{d}, \tilde{\mathbf{d}}) + B_*^{(3)}(\mathbf{d}, \tilde{\mathbf{d}})$ , where each  $B_*^{(i)}(\mathbf{d}, \tilde{\mathbf{d}})$  ( $i = 1, 2, 3$ ) is the covariance constituting the independent Gaussian stochastic processes that we have already derived above.

The null limit distributions of the test statistics are more easily obtained by the unique features of  $\mathbf{B}_*^{(\pi, \pi)}(\mathbf{d}_\pi, \tilde{\mathbf{d}}_\pi)$ : first, let

$$\tilde{\mathbf{B}}_*^{(\pi, \pi)}(\mathbf{d}_\pi, \tilde{\mathbf{d}}_\pi) := \begin{bmatrix} \ddot{\mathbf{B}}_*^{(\pi, \pi)}(\mathbf{d}_\pi, \tilde{\mathbf{d}}_\pi) & \mathbf{0} \\ \mathbf{0}' & qE[W_t^2]^2 \end{bmatrix},$$

$$\ddot{\mathbf{B}}_*^{(\pi, \pi)}(\mathbf{d}_\pi, \tilde{\mathbf{d}}_\pi) := \frac{1}{2\sigma_*^2} \begin{bmatrix} h\tilde{h}\sigma_*^2 E[W_t^4] & \tilde{d}_{\sigma^2} h E[W_t^2] \\ d_{\sigma^2} \tilde{h} E[W_t^2] & \frac{1}{\sigma_*^2} d_{\sigma^2} \tilde{d}_{\sigma^2} \end{bmatrix},$$

and  $q := q(d_1, d_2, \tilde{d}_1, \tilde{d}_2) := h\tilde{h}k$ , and note that  $\boldsymbol{\nu}_3' \tilde{\mathbf{B}}_*^{(\pi, \pi)}(\mathbf{d}_\pi, \tilde{\mathbf{d}}_\pi) \boldsymbol{\nu}_3 = B_*^{(2)}(\mathbf{d}, \tilde{\mathbf{d}}) + B_*^{(3)}(\mathbf{d}, \tilde{\mathbf{d}})$  and  $\boldsymbol{\nu}_2' \ddot{\mathbf{B}}_*^{(\pi, \pi)}(\mathbf{d}_\pi, \tilde{\mathbf{d}}_\pi) \boldsymbol{\nu}_2 = B_*^{(2)}(\mathbf{d}, \tilde{\mathbf{d}})$ . Here, the Gaussian stochastic process associated with  $\ddot{\mathbf{B}}_*^{(\pi, \pi)}(\mathbf{d}_\pi, \tilde{\mathbf{d}}_\pi)$  is independent of that associated with  $qE[W_t^2]^2$  because  $\tilde{\mathbf{B}}_*^{(\pi, \pi)}(\mathbf{d}_\pi, \tilde{\mathbf{d}}_\pi)$  is block diagonal. Furthermore,  $\ddot{\mathbf{B}}_*^{(\pi, \pi)}(\mathbf{d}_\pi, \tilde{\mathbf{d}}_\pi)$  is bilinear with respect to  $h(d_1, d_2)$  and  $d_{\sigma^2}$ . Using these facts, we can derive the null limit distributions of the three test statistics: first, the null limit distribution of the QLR test statistic is obtained as  $\mathcal{LR}_n \Rightarrow \sup_{s_2/s_1 \in [\underline{c}, \bar{c}]} \max[0, \tilde{\mathcal{Y}}^{(\theta)}(s_1, s_2)]^2$  by Theorem 2(iv), where  $\tilde{\mathcal{Y}}^{(\theta)}(\cdot)$  is a standard Gaussian stochastic process with covariance structure

$$\frac{c(s_2/s_1, \tilde{s}_2/\tilde{s}_1)}{\{c(s_2/s_1, s_2/s_1)\}^{1/2} \{c(\tilde{s}_2/\tilde{s}_1, \tilde{s}_2/\tilde{s}_1)\}^{1/2}}$$

and for each  $(s_2/s_1, \tilde{s}_2/\tilde{s}_1)$ ,  $c(s_2/s_1, \tilde{s}_2/\tilde{s}_1) := \frac{1}{2} \text{var}(W_t^2) + k(s_2/s_1, \tilde{s}_2/\tilde{s}_1) E[W_t^2]^2$ . This structure is homogenous of degree zero with respect to  $s_1$  and  $s_2$ , so that  $\tilde{\mathcal{Y}}^{(\theta)}(\cdot)$  can be equivalently stated as a function of  $s_2/s_1$ .

Second, we apply the Wald test statistic to this model. By the requirement of Theorem 3, we let the weight function be

$$\widehat{W}_n(\tilde{s}_2/\tilde{s}_1, s_2/s_1) := \frac{1}{(1-m^2)(1-m^2)} \left[ \frac{\widehat{\text{var}}_n(W_t^2)}{2} + k\widehat{E}_n[W_t^2]^2 \right],$$

where  $\widehat{E}_n[W_t^2] := n^{-1} \sum_{t=1}^n W_t^2$  and  $\widehat{\text{var}}_n[W_t^2] := n^{-1} \sum_{t=1}^n W_t^4 - (n^{-1} \sum_{t=1}^n W_t^2)^2$ . This statistic satisfies Assumption 8, and the Wald test statistic can be accordingly defined as

$$\mathcal{W}_n := n\{\tilde{h}_n^{(\theta)}(s_2/s_1)\}'\widehat{W}_n(s_2/s_1, s_2/s_1)\{\tilde{h}_n^{(\theta)}(s_2/s_1)\},$$

and  $\mathcal{W}_n \Rightarrow \sup_{s_2/s_1 \in [\underline{c}, \bar{c}]} \max[0, \tilde{\mathcal{Y}}^{(\theta)}(s_1, s_2)]^2$  under the null by Theorem 3, where  $\tilde{h}_n^{(\theta)}(s_2/s_1)$  is such that

$$L_n(\tilde{\gamma}_n, \tilde{\sigma}_n^2, \tilde{h}_n^{(\theta)}(s_2/s_1)s_1, \tilde{h}_n^{(\theta)}(s_2/s_1)s_2) = \sup_{(h^{(\theta)}, \gamma, \sigma^2)} L_n(\gamma, \sigma^2, h^{(\theta)}s_1, h^{(\theta)}s_2)$$

and  $s_1^2 + s_2^2 = 1$ .

Finally, we apply the LM test statistic. Following the definition of the LM test statistic, we let

$$\mathcal{LM}_n := \sup_{s_2/s_1 \in [\underline{c}, \bar{c}]} n \left\{ \frac{\max[0, DL_n(\ddot{\gamma}_n, \ddot{\sigma}_n^2, \mathbf{0}; s_1, s_2)]}{-\tilde{D}^2 L_n(\ddot{\gamma}_n, \ddot{\sigma}_n^2, \mathbf{0}; s_1, s_2, s_{\sigma^2})} \right\}^2 \widehat{W}_n(s_2/s_1, s_2/s_1),$$

where

$$DL_n(\ddot{\gamma}_n, \ddot{\sigma}_n^2, \mathbf{0}; s_1, s_2) := \{2\ddot{\sigma}_n^2\}^{-1} \{ \mathbf{U}^n(\ddot{\gamma}_n)' \boldsymbol{\Omega}^n(m(s_2/s_1)) \mathbf{U}^n(\ddot{\gamma}_n) - \ddot{\sigma}_n^2 \text{tr}[\boldsymbol{\Omega}^n(m(s_2/s_1))] \},$$

$$\begin{aligned} \tilde{D}^2 L_n(\ddot{\gamma}_n, \ddot{\sigma}_n^2, \mathbf{0}; s_1, s_2, s_{\sigma^2}) := & \frac{1}{2} \left\{ \text{tr}(\boldsymbol{\Omega}^n(m(s_2/s_1)^2)) - \frac{2}{\ddot{\sigma}_n^2} \mathbf{U}^n(\ddot{\gamma}_n)' \boldsymbol{\Omega}^n(m(s_2/s_1)^2) \mathbf{U}^n(\ddot{\gamma}_n) \right\} \\ & - \left[ \frac{n}{2} - \frac{1}{\ddot{\sigma}_n^2} \mathbf{U}^n(\ddot{\gamma}_n)' \mathbf{U}^n(\ddot{\gamma}_n) \right]^{-1} \{ \mathbf{U}^n(\ddot{\gamma}_n)' \boldsymbol{\Omega}^n(m(s_2/s_1)) \mathbf{U}^n(\ddot{\gamma}_n) \}^2, \end{aligned}$$

$(\ddot{\gamma}_n, \ddot{\sigma}_n^2)$  is such that  $L_n(\ddot{\gamma}_n, \ddot{\sigma}_n^2, \mathbf{0}) = \sup_{(\gamma, \sigma^2)} L_n(\gamma, \sigma^2, \mathbf{0})$ , and the same weight matrix is used as for the Wald test statistic. Here,  $\tilde{D}^2 L_n(\ddot{\gamma}_n, \ddot{\sigma}_n^2, \mathbf{0}; s_1, s_2, s_{\sigma^2})$  is indexed only by  $(s_1, s_2)$  because  $s_{\sigma^2}$  disappears by construction. Theorem 4 now implies that  $\mathcal{LM}_n \Rightarrow \sup_{s_2/s_1 \in [\underline{c}, \bar{c}]} \max[0, \tilde{\mathcal{Y}}^{(\theta)}(s_1, s_2)]^2$ , so that all three test statistics are asymptotically equivalent under the null.

The null limit distributions of the three test statistics can be uncovered by a simulation method. Note

that the covariance structure of  $\tilde{\mathcal{Y}}^{(\theta)}(\cdot)$  is the same as that of

$$\ddot{\mathcal{Y}}^{(\theta)}(s_1, s_2) := \frac{1}{c(s_2/s_1, s_2/s_1)^{1/2}} \left[ \left\{ \frac{\text{var}(W_t^2)}{2} \right\}^{1/2} Z_0 + E[W_t^2] \sum_{j=1}^{\infty} m(s_2/s_1)^j Z_j \right],$$

where  $Z_j \sim \text{IID } N(0, 1)$ . Due to this IID condition, it is not hard to simulate  $\ddot{\mathcal{Y}}^{(\theta)}(\cdot)$ . When simulating  $\ddot{\mathcal{Y}}^{(\theta)}(\cdot)$ ,  $\text{var}(W_t^2)$  and  $E[W_t^2]$  need to be estimated, and the running index  $j$  must be truncated at a moderately large level so that it does not significantly affect the null limit distribution.

We conduct Monte Carlo simulations using this method. The DGP for  $Y_t = U_t \sim \text{IID } N(0, 1)$  and  $W_t \sim \text{IID } N(0, 1)$  that is independent of  $U_t$ . We assume that the parameters other than  $\alpha_*$ ,  $\sigma_*^2$ ,  $\theta_{1*}$ , and  $\theta_{2*}$  are known and also let  $\underline{c} = 0.5$ ,  $\bar{c} = 1.5$ . Figure 1 shows the empirical distributions of the QLR test statistic for various sample sizes and the null limit distribution obtained by simulating  $\sup_{(s_1, s_2)} \max[0, \hat{\mathcal{Y}}^{(\theta)}(s_1, s_2)]^2$  2,000 times, where for each  $(s_1, s_2)$ ,

$$\hat{\mathcal{Y}}^{(\theta)}(s_1, s_2) := \frac{1}{\hat{c}_n(s_2/s_1, s_2/s_1)^{1/2}} \left[ \left\{ \frac{\widehat{\text{var}}_n(W_t^2)}{2} \right\}^{1/2} Z_0 + \hat{E}_n[W_t^2] \sum_{j=1}^{150} m(s_2/s_1)^j Z_j \right],$$

and  $\widehat{\text{var}}_n(W_t^2)$  and  $\hat{E}_n[W_t^2]$  are the method of moments estimators for  $\text{var}(W_t^2)$  and  $E[W_t^2]$ , respectively. The empirical distribution of the QLR test statistic approaches the limit distribution as  $n$  increases.

## 5 Conclusion

The current study examines the estimation and inference of D-D quasi-likelihood functions and provides conditions under which the QML estimator behaves regularly. Specifically, we show that the QML estimator has a distribution different from that of standard D quasi-likelihood functions by showing that it is represented as a functional of a Gaussian stochastic process indexed by direction. Furthermore, the analysis assuming D quasi-likelihood function can be treated as a special case of D-D quasi-likelihood function analysis. Furthermore, the standard QLR, Wald, and LM test statistics are redefined to fit the structure of D-D quasi-likelihood functions. These modifications are provided for general D-D quasi-likelihood functions, and we show that the three test statistics possess null limit distributions represented as functionals of the same Gaussian stochastic process. We further obtain that the three test statistics are asymptotically equivalent under the null and some mild regularity conditions that are popularly used for empirical examinations.



## Appendix: Proofs

Before proving the main claims of the paper, we provide the following preliminary lemmas:

**Lemma A1.** *Given Assumptions 1 to 6, for each  $\mathbf{d} \in \Delta(\boldsymbol{\theta}_*)$ , (i)  $n^{-1/2}DL_n(\boldsymbol{\theta}_*; \mathbf{d}) \Rightarrow \mathcal{Z}(\mathbf{d})$ , where  $\mathcal{Z}(\mathbf{d}) \sim N(0, B_*(\mathbf{d}))$ ; (ii)  $n^{-1}D^2L_n(\boldsymbol{\theta}_*; \mathbf{d})$  converges to  $A_*(\mathbf{d})$  a.s.- $\mathbb{P}$ ; (iii)  $\{n^{-1/2}DL_n(\boldsymbol{\theta}_*; \mathbf{d}), n^{-1}D^2L_n(\boldsymbol{\theta}_*; \mathbf{d})\} \Rightarrow \{\mathcal{Z}(\mathbf{d}), A_*(\mathbf{d})\}$ .  $\square$*

**Lemma A2.** *Given Assumptions 1 to 6, for each  $\mathbf{d} \in \Delta(\boldsymbol{\theta}_*)$ , (i)  $\sqrt{n}\hat{h}_n(\mathbf{d}) \Rightarrow \max[0, \mathcal{G}(\mathbf{d})]$ , where  $\mathcal{G}(\mathbf{d}) := \{-A_*(\mathbf{d})\}^{-1}\mathcal{Z}(\mathbf{d})$ ; (ii)  $\sqrt{n}(\hat{\boldsymbol{\theta}}_n(\mathbf{d}) - \boldsymbol{\theta}_*) \Rightarrow \max[0, \mathcal{G}(\mathbf{d})]\mathbf{d}$ ; (iii)  $2\{L_n(\hat{\boldsymbol{\theta}}_n(\mathbf{d})) - L_n(\boldsymbol{\theta}_*)\} \Rightarrow \max[0, \mathcal{Y}(\mathbf{d})]^2$ , where for each  $\mathbf{d}$ ,  $\mathcal{Y}(\mathbf{d}) := \{-A_*(\mathbf{d})\}^{1/2}\mathcal{G}(\mathbf{d})$ .  $\square$*

**Lemma A3.** *Given Assumptions 1 to 6, (i) for all  $\varepsilon > 0$ , there is  $\delta > 0$  such that*

$$\limsup_{n \rightarrow \infty} \mathbb{P}_n \left( \sup_{\|\mathbf{d}_1 - \mathbf{d}_2\| < \delta} n^{-1/2} |DL_n(\boldsymbol{\theta}_*; \mathbf{d}_1) - DL_n(\boldsymbol{\theta}_*; \mathbf{d}_2)| > \varepsilon \right) < \varepsilon,$$

*where  $\mathbb{P}_n$  is the empirical probability measure; (ii) for all  $\varepsilon > 0$ , there is  $n(\varepsilon)$  a.s.- $\mathbb{P}$  such that if  $n > n(\varepsilon)$ ,  $\sup_{\mathbf{d} \in \Delta(\boldsymbol{\theta}_*)} |n^{-1}D^2L_n(\boldsymbol{\theta}_*; \mathbf{d}) - A_*(\mathbf{d})| < \varepsilon$ .  $\square$*

Lemma A3(i) implies that the first-order directional derivative weakly forms a Gaussian stochastic process indexed by  $\mathbf{d}$  (e.g., Billingsley, 1999). In our time-series data context, theorem 1 of Hansen (1996b) provides sufficient regularity conditions for this. As Lemma A3(i) is needed to show the desired weak convergence with  $r > 1$ , we suppose that  $\Delta(\boldsymbol{\theta}_*)$  has an uncountable number of directions when proving Lemma A3(i).

**Proof of Lemma A1:** (i) To show the given claim, we verify the conditions of Wooldridge and White (1988). First, AC1 of Wooldridge and White (1988) is satisfied by Assumption 6(iii) because we can let  $n^{-1/2} \sum \ell_t(\boldsymbol{\theta}_*; \mathbf{d})$  be their  $\sum Z_{nt}$ . Second, the conditions (i, ii, iii) of AC2 in Wooldridge and White (1988) trivially hold by our assumptions that  $\|D\ell_t(\boldsymbol{\theta}_*; \mathbf{d})\|_s < \Delta$  for any  $t$ ,  $\nu_\tau$  is of size  $-1/(1 - \gamma) < -1/2$ , and  $\{\mathbf{Y}_t\}$  is a strong mixing sequence of size  $-sq/(s - q) < -s/(s - 2)$  because  $s > q \geq 2$ , respectively. Third, condition (iv) of AC2 can be easily defined from the fact that  $\|\ell_t(\boldsymbol{\theta}_*; \mathbf{d})\|_s < \Delta < \infty$  uniformly in  $\mathbf{d}$  for any  $t$ . Finally, their condition in Assumption 5 does not need to be proved as our goal is not to obtain the standard normal distribution.

(ii) We can apply the ergodic theorem given Assumptions 1 and 6(ii).

(iii) Given Lemmas A1(i and ii), the given weak convergence follows from theorem 3.9 of Billingsley (1999, p. 37).  $\blacksquare$

**Proof of Lemma A2:** (i) For given  $\mathbf{d}$ , if we maximize (1) with respect to  $h$  subject to  $h \geq 0$ , it follows that  $\hat{h}_n(\mathbf{d}) = \max[0, \{-D^2 L_n(\bar{\theta}_n(\mathbf{d}); \mathbf{d})\}^{-1} D L_n(\theta_*; \mathbf{d})]$  by using Khun-Tucker theorem. We further note that  $\bar{\theta}_n(\mathbf{d}) \rightarrow \theta_*$  a.s.- $\mathbb{P}$  because  $\hat{\theta}_n$  converges to  $\theta_*$  a.s.- $\mathbb{P}$ , so that  $\sqrt{n}\hat{h}_n(\mathbf{d}) \Rightarrow \max[0, \{-A_*(\mathbf{d})\}^{-1} \mathcal{Z}(\mathbf{d})]$  by Lemma A1(iii). The desired result now follows from the definition of  $\mathcal{G}(\mathbf{d})$ .

(ii) From the definition of  $\hat{h}_n(\mathbf{d})$ ,  $\hat{\theta}_n(\mathbf{d}) \equiv \theta_* + \hat{h}_n(\mathbf{d})\mathbf{d}$ . Lemma A2(i) yields the given result.

(iii) Given that  $\arg \max_{\tilde{h} \in \mathbb{R}^+} [2\mathcal{Z}(\mathbf{d})\tilde{h} + A_*(\mathbf{d})\tilde{h}^2] = \max[0, \mathcal{G}(\mathbf{d})]$ ,

$$\max_{\tilde{h} \in \mathbb{R}^+} [2\mathcal{Z}(\mathbf{d})\tilde{h} + A_*(\mathbf{d})\tilde{h}^2] = \max[0, \{-A_*(\mathbf{d})\}^{1/2} \mathcal{G}(\mathbf{d})]^2.$$

Thus, the desired result follows from (2). ■

**Proof of Lemma A3:** (i) Given the weak convergence of Lemma A1(i), if  $\{n^{-1/2} \sum D\ell_t(\theta_*; \cdot)\}$  is asymptotically tight, the desired result follows from the finite dimensional multivariate CLT based on the Cramér-Wold device, which we do not prove by its self-evidence.

The asymptotic tightness can be proved by verifying the conditions of theorem 4 in Hansen (1996a). First, from the fact that  $\{\mathbf{Y}_t\}$  is a strong mixing sequence of  $-sq/(s-q)$ , for some  $\epsilon > 0$ ,  $\alpha_\tau^{-(s-q)/(sq)} = O(\tau^{-1-\epsilon})$ , so that  $\sum_{\tau=1}^\infty \alpha_\tau^{-(s-q)/(sq)} < \infty$ . Second,  $\|M_t\|_s < \infty$  for any  $t$  from the stationarity assumption of  $\{M_t\}$  in Assumption 6(iv). Third,  $\|D\ell_t(\theta_*; \mathbf{d})\|_s < \infty$  uniformly in  $\mathbf{d}$  for any  $t$  from Assumption 6(iv). Fourth, given that  $\nu_\tau$  is of size  $-1/(1-\gamma)$ , for some  $\epsilon > 0$ ,  $\nu_\tau = O(\tau^{-1/(1-\gamma)-\epsilon})$ , implying that  $\sum_{\tau=1}^\infty \nu_\tau^{1-\gamma} < \infty$ . Finally, it is already assumed in Assumption 6(iv) that  $q > (r-1)/(\gamma\lambda)$ . These results verify the conditions in theorem 4 of Hansen (1996a), and the asymptotic tightness of  $\{n^{-1/2} \sum D\ell_t(\theta_*; \cdot)\}$  follows.

(ii) By Assumption 5(iii),  $|n^{-1} D^2 L_n(\theta; \mathbf{d}_1) - n^{-1} D^2 L_n(\theta; \mathbf{d}_2)| \leq n^{-1} \sum M_t \|\mathbf{d}_1 - \mathbf{d}_2\|^\lambda$ . Furthermore, we can apply the ergodic theorem to  $\{n^{-1} \sum M_t\}$ , so that for any  $\omega \in F$ ,  $\mathbb{P}(F) = 1$ , and  $\epsilon > 0$ , there is an  $n^*(\omega, \epsilon)$  such that if  $n \geq n^*(\omega, \epsilon)$ ,  $|n^{-1} \sum M_t - E[M_t]| \leq \epsilon$ , and this implies that  $n^{-1} \sum M_t \leq E[M_t] + \epsilon$ . For the same  $\epsilon$ , we may let  $\delta := \epsilon/(E[M_t] + \epsilon)$ . Then,  $n^{-1} \sum M_t \|\mathbf{d}_1 - \mathbf{d}_2\|^\lambda \leq \epsilon$ , whenever  $\|\mathbf{d}_1 - \mathbf{d}_2\|^\lambda \leq \delta$ , because  $n^{-1} \sum M_t \|\mathbf{d}_1 - \mathbf{d}_2\|^\lambda \leq n^{-1} \sum M_t \delta = n^{-1} \sum M_t \epsilon / (\epsilon + E[M_t]) \leq \epsilon$ . That is, for any  $\omega \in F$ ,  $\mathbb{P}(F) = 1$  and  $\epsilon > 0$ , there is  $n^*(\omega, \epsilon)$  and  $\delta$  such that if  $n \geq n^*(\omega, \epsilon)$  and  $\|\mathbf{d}_1 - \mathbf{d}_2\|^\lambda \leq \delta$ ,  $|n^{-1} D^2 L_n(\theta; \mathbf{d}_1) - n^{-1} D^2 L_n(\theta; \mathbf{d}_2)| < \epsilon$ , which means that  $\{n^{-1} D^2 L_n(\theta; \cdot)\}_{n^*(\omega, \epsilon)}^\infty$  is equicontinuous. Therefore, it follows that  $n^{-1} D^2 L_n(\theta; \cdot)$  converges to  $A_*(\cdot)$  uniformly on  $\Delta(\theta_*)$  a.s.- $\mathbb{P}$  by Rudin (1976, p. 168). ■

**Proof of Theorem 1:** (i) Given Lemmas A3(i and ii), the given weak convergence follows from theorem 3.9 of Billingsley (1999, p. 37).

(ii) The given result follows from Lemma A2(i), Theorem 1(i), and the definition of  $\mathcal{G}(\cdot)$ .

(iii) We can apply the CMT to (3).

(iv) To prove the given claim, we apply the argmax continuous mapping theorem in van der Vaart and Wellner (1996). Note that  $\Delta(\theta_*)$  is bounded, and  $L_n(\widehat{\theta}_n(\cdot)) - L_n(\theta_*) \Rightarrow \max[0, \mathcal{Y}(\cdot)]^2$  by (2) and Lemma A3. Given that  $D\ell_t(\theta; \cdot)$  and  $D^2\ell_t(\theta; \cdot)$  are continuous by Assumption 5,  $\max[0, \mathcal{Y}(\cdot)]^2$  must be continuous on  $\Delta(\theta_*)$  almost surely. Furthermore,  $\Delta(\theta_*)$  is a subset of a compact space, so that it trivially follows that  $\mathbf{d}_*$  is tight, and  $\widehat{\mathbf{d}}_n$  is uniformly tight. Given that  $\mathbf{d}_*$  is unique almost surely, the regularity conditions for the argmax continuous mapping theorem are satisfied. Theorem 3.2.2 of van der Vaart and Wellner (1996) holds by this.  $\blacksquare$

**Proof of Corollary 1:** For an efficient proof, we prove (vi) and (vii) before proving (iv) and (v).

(i) As the weak convergence is proved for a general function, we verify only the pointwise weak convergence for this case. From the definition of  $DL_n(\theta_*; \mathbf{d}) = \nabla_{\theta} L_n(\theta)' \mathbf{d}$ , and  $n^{-1/2} \nabla_{\theta} L_n(\theta_*) \Rightarrow \mathbf{Z}$  by theorem 1 of Doukhan, Massart, and Rio (1995). Therefore,  $n^{-1/2} DL_n(\theta_*; \mathbf{d}) \Rightarrow \mathbf{Z}' \mathbf{d}$  for every  $\mathbf{d} \in \Delta(\theta_*)$ .

(ii) We note that  $D^2 L_n(\theta; \mathbf{d}) = \mathbf{d}' \nabla_{\theta}^2 L_n(\theta_*) \mathbf{d}$ , so that  $n^{-1} \nabla_{\theta}^2 L_n(\theta_*) \rightarrow \mathbf{A}_*$  a.s.- $\mathbb{P}$  by the ergodic theorem. Therefore, the given result follows from the definition of  $\mathcal{G}(\mathbf{d})$ .

(iii) We can use the definition of  $\widehat{h}_n(\mathbf{d})$ . That is,  $\widehat{\theta}_n(\mathbf{d}) = \theta_* + \widehat{h}_n(\mathbf{d}) \mathbf{d}$ . The given result follows from the fact that  $\sqrt{n} \widehat{h}_n(\mathbf{d}) \Rightarrow \max[0, \mathcal{G}(\mathbf{d})]$  and Corollary 1(ii).

(vi) By the definition of  $\mathcal{Y}(\cdot)$  of Theorem 1, for each  $\mathbf{d}$ ,  $\mathcal{Y}(\mathbf{d}) = \{\mathbf{d}'(-\mathbf{A}_*) \mathbf{d}\}^{-1/2} \mathbf{Z}' \mathbf{d}$ , so that Theorem 1(iii) implies the desired result.

(vii) From the fact that  $\text{cl}\{C(\theta_*)\} = \bar{\mathbb{R}}^r$ , there is  $\mathbf{d}^* \in \Delta(\theta_*)$  such that  $\max[0, \mathbf{Z}' \mathbf{d}^*] = \mathbf{Z}' \mathbf{d}^*$  and  $\mathbf{d}^* = -\mathbf{d}$  if  $\max[0, \mathbf{Z}' \mathbf{d}] = 0$ . Thus, the given ‘max’ operator can be ignored in this case. That is,  $\mathbf{d}_* = \arg \max_{\mathbf{d} \in \Delta(\theta_*)} \mathbf{d}' \mathbf{Z} \mathbf{Z}' \mathbf{d} \{\mathbf{d}'(-\mathbf{A}_*) \mathbf{d}\}^{-1}$ . For notational simplicity, if we let

$$\mathbf{v} := \frac{(-\mathbf{A}_*)^{1/2} \mathbf{d}}{\{\mathbf{d}'(-\mathbf{A}_*) \mathbf{d}\}^{1/2}},$$

it follows that  $\mathbf{v}' \mathbf{v} = 1$  and  $\mathbf{v}'(-\mathbf{A}_*)^{-1/2} \mathbf{Z} \mathbf{Z}'(-\mathbf{A}_*)^{-1/2} \mathbf{v} = \mathbf{d}' \mathbf{Z} \mathbf{Z}' \mathbf{d} \{\mathbf{d}'(-\mathbf{A}_*) \mathbf{d}\}^{-1}$ . Given this, we note that  $\max_{\mathbf{v}} \mathbf{v}'(-\mathbf{A}_*)^{-1/2} \mathbf{Z} \mathbf{Z}'(-\mathbf{A}_*)^{-1/2} \mathbf{v} = \max_{\mathbf{d}} \mathbf{d}' \mathbf{Z} \mathbf{Z}' \mathbf{d} \{\mathbf{d}'(-\mathbf{A}_*) \mathbf{d}\}^{-1}$ , and it is equal to the maximum eigenvalue of  $(-\mathbf{A}_*)^{-1/2} \mathbf{Z} \mathbf{Z}'(-\mathbf{A}_*)^{-1/2}$ , which is equal to  $\mathbf{Z}'(-\mathbf{A}_*)^{-1} \mathbf{Z}$ . It is mainly because  $\text{rank}((-\mathbf{A}_*)^{-1/2} \mathbf{Z} \mathbf{Z}'(-\mathbf{A}_*)^{-1/2}) = 1$  (so that there is a single positive eigenvalue, and the other eigenvalues are zero), and the sum of eigenvalues is equal to  $\text{tr}[(-\mathbf{A}_*)^{-1/2} \mathbf{Z} \mathbf{Z}'(-\mathbf{A}_*)^{-1/2}] = \mathbf{Z}'(-\mathbf{A}_*)^{-1} \mathbf{Z}$ . These two facts lead to the desired result.

(iv) This follows trivially from the definition of  $\mathbf{d}_*$ .

(v) By the same reason as in the proof of (vii), we can ignore the ‘max’ operator, so that  $\sqrt{n}(\widehat{\theta}_n - \theta_*) \Rightarrow \mathbf{Z}'\mathbf{d}_*\{\mathbf{d}_*'(-\mathbf{A}_*)\mathbf{d}_*\}^{-1}\mathbf{d}_*$ .

Given this, also from the proof of (vii), if we let

$$\mathbf{v}_* := \frac{(-\mathbf{A}_*)^{1/2}\mathbf{d}_*}{\{\mathbf{d}_*'(-\mathbf{A}_*)\mathbf{d}_*\}^{1/2}},$$

$\mathbf{v}_*$  is the eigenvector of  $(-\mathbf{A}_*)^{-1/2}\mathbf{Z}\mathbf{Z}'(-\mathbf{A}_*)^{-1/2}$  corresponding to the maximum eigenvalue given as  $\mathbf{Z}'(-\mathbf{A}_*)^{-1}\mathbf{Z}$ , so that

$$(-\mathbf{A}_*)^{-1/2}\mathbf{Z}\mathbf{Z}'(-\mathbf{A}_*)^{-1/2}\mathbf{v}_* = \mathbf{Z}'(-\mathbf{A}_*)^{-1}\mathbf{Z}\mathbf{v}_* \quad (11)$$

by the definition of eigenvector. This implies that

$$\mathbf{v}_*'(-\mathbf{A}_*)^{-1/2}\mathbf{Z}\mathbf{Z}'(-\mathbf{A}_*)^{-1/2}\mathbf{v}_* = \mathbf{Z}'(-\mathbf{A}_*)^{-1}\mathbf{Z}\mathbf{v}_*\mathbf{v}_*' = \mathbf{Z}'(-\mathbf{A}_*)^{-1}\mathbf{Z} \quad (12)$$

because  $\mathbf{v}_*\mathbf{v}_*' = 1$ . Plugging the definition of  $\mathbf{v}_*$  to the left side of (12) leads to that  $\mathbf{Z}'\mathbf{d}_*\{\mathbf{d}_*'(-\mathbf{A}_*)\mathbf{d}_*\}^{-1} = (\mathbf{d}_*\mathbf{Z})^{-1}\mathbf{Z}'(-\mathbf{A}_*)^{-1}\mathbf{Z}$ . Thus,  $\mathbf{Z}'\mathbf{d}_*\{\mathbf{d}_*'(-\mathbf{A}_*)\mathbf{d}_*\}^{-1}\mathbf{d}_* = (\mathbf{d}_*\mathbf{Z})^{-1}\mathbf{Z}'(-\mathbf{A}_*)^{-1}\mathbf{Z}\mathbf{d}_*$ . Also, plugging the definition of  $\mathbf{v}_*$  to (11) yields that  $(\mathbf{d}_*\mathbf{Z})^{-1}\mathbf{Z}'(-\mathbf{A}_*)^{-1}\mathbf{Z}\mathbf{d}_* = (-\mathbf{A}_*)^{-1}\mathbf{Z}$ . Therefore,  $\sqrt{n}(\widehat{\theta}_n - \theta_*) \Rightarrow \mathbf{Z}'\mathbf{d}_*\{\mathbf{d}_*'(-\mathbf{A}_*)\mathbf{d}_*\}^{-1}\mathbf{d}_* = (-\mathbf{A}_*)^{-1}\mathbf{Z}$ . This completes the proof. ■

**Proof of Theorem 2:** (i) We note that for any  $h\mathbf{d}$  such that  $h \in \mathbb{R}^+$  and  $\mathbf{d} \in \Delta(\pi_*)$ , there are  $h^{(\pi)} \in \mathbb{R}^+$ ,  $h^{(\tau)} \in \mathbb{R}^+$ ,  $\mathbf{s}_\pi \in \Delta(\pi_*)$ , and  $\mathbf{s}_\tau \in \Delta(\tau_*)$  such that  $h\mathbf{d} = [h^{(\pi)}\mathbf{s}_\pi', h^{(\tau)}\mathbf{s}_\tau']'$  by Assumption 7. Thus,  $L_n(\theta_* + h\mathbf{d}) = L_n(\pi_* + h^{(\pi)}\mathbf{s}_\pi, \tau_* + h^{(\tau)}\mathbf{s}_\tau)$ , implying that

$$\begin{aligned} 2\{L_n(\pi_* + h^{(\pi)}\mathbf{s}_\pi, \tau_* + h^{(\tau)}\mathbf{s}_\tau) - L_n(\pi_*, \tau_*)\} &= 2DL_n(\pi_*, \tau_*; \mathbf{s}_\pi)h^{(\pi)} \\ &\quad + 2DL_n(\pi_*, \tau_*; \mathbf{s}_\tau)h^{(\tau)} + D^2L_n(\pi_*, \tau_*; \mathbf{s}_\pi)(h^{(\pi)})^2 + D^2L_n(\pi_*, \tau_*; \mathbf{s}_\tau)(h^{(\tau)})^2 \\ &\quad + 2DL_n(\pi_*, \tau_*; \mathbf{s}_\pi; \mathbf{s}_\tau)h^{(\pi)}h^{(\tau)} + o_{\mathbb{P}_{d\pi}}(1) + o_{\mathbb{P}_{d\tau}}(1), \end{aligned}$$

where  $DL_n(\pi_*, \tau_*; \mathbf{s}_\pi; \mathbf{s}_\tau)$  is the directional derivative of  $DL_n(\cdot, \cdot; \mathbf{s}_\pi)$  with respect to  $\mathbf{s}_\tau$  evaluated at  $(\pi_*, \tau_*)$ , and  $\sup_{\mathbf{d}} \sup_h L_n(\theta_* + h\mathbf{d}) = \sup_{\{\mathbf{s}_\pi, \mathbf{s}_\tau\}} \sup_{\{h^{(\pi)}, h^{(\tau)}\}} L_n(\pi_* + h^{(\pi)}\mathbf{s}_\pi, \tau_* + h^{(\tau)}\mathbf{s}_\tau)$ . Therefore,  $\mathcal{LR}_n^{(1)} = \sup_{\mathbf{d}} \sup_h 2\{L_n(\theta_* + h\mathbf{d}) - L_n(\theta_*)\}$  implies that

$$\begin{aligned} \mathcal{LR}_n^{(1)} &= \sup_{\mathbf{s}_\pi} \sup_{h^{(\pi)}} \{2DL_n(\theta_*; \mathbf{s}_\pi)h^{(\pi)} + D^2L_n(\theta_*; \mathbf{s}_\pi)(h^{(\pi)})^2 + o_{\mathbb{P}_{d\pi}}(1)\} \\ &\quad + \sup_{\mathbf{s}_\tau} \sup_{h^{(\tau)}} \{2DL_n(\theta_*; \mathbf{s}_\tau)h^{(\tau)} + D^2L_n(\theta_*; \mathbf{s}_\tau)(h^{(\tau)})^2 + o_{\mathbb{P}_{d\tau}}(1)\}, \end{aligned} \quad (13)$$

where we exploited the facts that  $n^{-1}DL_n(\pi_*, \tau_*; s_\pi, s_\tau)$  has probability limit  $\mathbf{0}$  by Assumption 7(iv) and that  $DL_n(\theta_*; \cdot)$  and  $DL_n(\theta_*; \cdot)$  are  $O_{\mathbb{P}}(n^{1/2})$  by Theorem 1(i).

Given this, note that  $H_{2,n} := \sup_{s_\tau} \sup_{h(\tau)} \{2DL_n(\theta_*; s_\tau)h(\tau) + D^2L_n(\theta_*; s_\tau)(h(\tau))^2\} \Rightarrow \mathcal{H}_2$ . Thus, we may focus on the weak limit of  $\sup_{s_\pi} \sup_{h(\pi)} \{2DL_n(\theta_*; s_\pi)h(\pi) + D^2L_n(\theta_*; s_\pi)(h(\pi))^2\}$  that is denoted as  $H_{01,n}$ . From the fact that for any  $h\mathbf{d}_\pi$  such that  $h \in \mathbb{R}^+$  and  $\mathbf{d}_\pi \in \Delta(\pi_*)$ , there are  $h^{(\lambda)} \in \mathbb{R}^+$ ,  $h^{(v)} \in \mathbb{R}^+$ ,  $s_\lambda \in \Delta(\lambda_*)$ , and  $s_v \in \Delta(\pi_*)$  such that  $h\mathbf{d}_\pi = [h^{(\lambda)}s_\lambda', h^{(v)}s_v']'$  and

$$H_{01,n} = \sup_{\{s_v, s_\lambda\}} \sup_{\{h^{(v)}, h^{(\lambda)}\}} 2DL_n(\theta_*; s_v)h^{(v)} + 2DL_n(\theta_*; s_\lambda)h^{(\lambda)} + 2DL_n(\theta_*; s_\lambda; s_v)h^{(\lambda)}h^{(v)} \\ + D^2L_n(\theta_*; s_v)(h^{(v)})^2 + D^2L_n(\theta_*; s_\lambda)(h^{(\lambda)})^2,$$

where  $DL_n(\theta_*; s_\lambda; s_v)$  is the directional derivative of  $DL_n(\cdot; s_\lambda)$  with respect to  $s_v$  evaluated at  $\theta_*$ . Given this, if we apply the ULLN and FCLT to  $H_{01,n}$  by Theorem 1,

$$H_{01,n} \Rightarrow \mathcal{H}_0 + \mathcal{H}_1 = \sup_{\{s_v, s_\lambda\}} \sup_{\{h^{(v)}, h^{(\lambda)}\}} 2\mathcal{Z}^{(v)}(s_v)h^{(v)} + 2s_\lambda' \mathbf{Z}^{(\lambda)}h^{(\lambda)} + 2s_\lambda' \mathbf{A}_*^{(\lambda, v)}(s_v)h^{(\lambda)}h^{(v)} \\ + A_*^{(v, v)}(s_v)(h^{(v)})^2 + s_\lambda' \mathbf{A}_*^{(\lambda, \lambda)}s_\lambda(h^{(\lambda)})^2, \quad (14)$$

and there are four different possible cases for the solutions of  $(h^{(v)}, h^{(\lambda)})$  in the right side of (14): for each  $(s_v, s_\lambda)$  if we let  $\hat{h}^{(v)}(s_v, s_\lambda)$  and  $\hat{h}^{(\lambda)}(s_v, s_\lambda)$  maximize the right side of (14), it follows either (i)  $\hat{h}^{(v)}(s_v, s_\lambda) > 0$  and  $\hat{h}^{(\lambda)}(s_v, s_\lambda) > 0$ ; (ii)  $\hat{h}^{(v)}(s_v, s_\lambda) > 0$  and  $\hat{h}^{(\lambda)}(s_v, s_\lambda) = 0$ ; (iii)  $\hat{h}^{(v)}(s_v, s_\lambda) = 0$  and  $\hat{h}^{(\lambda)}(s_v, s_\lambda) > 0$ ; or (iv)  $\hat{h}^{(v)}(s_v, s_\lambda) = 0$  and  $\hat{h}^{(\lambda)}(s_v, s_\lambda) = 0$ .

We examine the limit distribution of each case one by one. First, if  $\hat{h}^{(v)}(s_v, s_\lambda) > 0$  and  $\hat{h}^{(\lambda)}(s_v, s_\lambda) > 0$ , the right side of (14) is identical to

$$\sup_{\{s_v, s_\lambda\}} [\mathcal{Z}^{(v)}(s_v) \ s_\lambda' \mathbf{Z}^{(\lambda)}] \begin{bmatrix} -A_*^{(v, v)}(s_v) & -s_\lambda' \mathbf{A}_*^{(\lambda, v)}(s_v) \\ -s_\lambda' \mathbf{A}_*^{(\lambda, v)}(s_v) & -s_\lambda' \mathbf{A}_*^{(\lambda, \lambda)}s_\lambda \end{bmatrix}^{-1} \begin{bmatrix} \mathcal{Z}^{(v)}(s_v) \\ s_\lambda' \mathbf{Z}^{(\lambda)} \end{bmatrix},$$

and maximizing this with respect to  $s_\lambda$  for a given  $s_v$  yields  $\tilde{\mathcal{Y}}^{(v)}(s_v)^2 + (\mathbf{Z}^{(\lambda)})'(-\mathbf{A}_*^{(\lambda, \lambda)})^{-1}(\mathbf{Z}^{(\lambda)})$ . Second, if  $\hat{h}^{(\lambda)}(s_v, s_\lambda) > 0$  and  $\hat{h}^{(v)}(s_v, s_\lambda) = 0$ , the right side of (14) is identical to  $2s_\lambda' \mathbf{Z}^{(\lambda)} + s_\lambda' \mathbf{A}_*^{(\lambda, \lambda)}s_\lambda$ , and maximizing this with respect to  $s_\lambda$  leads to  $(\mathbf{Z}^{(\lambda)})'(-\mathbf{A}_*^{(\lambda, \lambda)})(\mathbf{Z}^{(\lambda)})$  as its maximum. Also,  $\tilde{\mathcal{Y}}^{(v)}(s_v)$  cannot be greater than zero. Otherwise, it must follow that  $\hat{h}^{(v)}(s_v, s_\lambda) > 0$  that is contradictory. Third, if  $\hat{h}^{(\lambda)}(s_v, s_\lambda) = 0$  and  $\hat{h}^{(v)}(s_v, s_\lambda) = 0$ , for the same  $s_v, s_\lambda$  cannot be optimal to maximizing the right side of (14) from the fact that  $\lambda_*$  is an interior element of  $\Lambda$ . We can ignore the case in which  $\hat{h}^{(\lambda)}(s_v, s_\lambda) =$

0. Therefore, combining the first two cases, we obtain that  $\mathcal{H}_0 = \sup_{\mathbf{s}_v \in \Delta(\mathbf{v}_*)} \max[0, \tilde{\mathcal{Y}}^{(v)}(\mathbf{s}_v)]^2$  and  $\mathcal{H}_1 = (\mathbf{Z}^{(\lambda)})'(-\mathbf{A}_*^{(\lambda, \lambda)})(\mathbf{Z}^{(\lambda)})$ . This also implies that it is necessary for  $\tilde{\mathcal{Y}}^{(v)}(\mathbf{s}_v)$  to be greater than zero, if  $\hat{h}^{(v)}(\mathbf{s}_v, \mathbf{s}_\lambda)$  is greater than zero.

(ii) We can apply the ULLN.

(iii) This follows as a corollary of (i).

(iv) The desired result is implied by (i), (iii), and continuous mapping. ■

**Proof of Theorem 3:** (i) We exploit (13) further. First, applying the CMT to Theorem 1(i) shows that  $(n^{-1/2}DL_n^{(\tau)}(\cdot), n^{-1}D^2L_n^{(\tau)}(\cdot)) \Rightarrow (\mathcal{Z}^{(\tau)}(\cdot), A_*^{(\tau, \tau)}(\cdot))$ . Thus,

$$\sup_{\sqrt{n}h^{(\tau)}} 2DL_n(\boldsymbol{\theta}_*; \mathbf{s}_\tau)h^{(\tau)} + D^2L_n(\boldsymbol{\theta}_*; \mathbf{s}_\tau)(h^{(\tau)})^2 \Rightarrow \sup_{h^{(\tau)} \in \mathbb{R}^+} 2\mathcal{Z}^{(\tau)}(\mathbf{s}_\tau)h^{(\tau)} + A_*^{(\tau, \tau)}(\mathbf{s}_\tau)(h^{(\tau)})^2,$$

so that  $\sqrt{n}\hat{h}_n^{(\tau)}(\mathbf{s}_\tau) \Rightarrow \max[0, \{-A_*^{(\tau, \tau)}(\mathbf{s}_\tau)\}^{-1}\mathcal{Z}^{(\tau)}(\mathbf{s}_\tau)] = \max[0, \mathcal{G}^{(\tau)}(\mathbf{s}_\tau)]$ . This holds even as a function of  $\mathbf{s}_\tau$ . That is,  $\sqrt{n}\hat{h}_n^{(\tau)}(\cdot) \Rightarrow \max[0, \mathcal{G}^{(\tau)}(\cdot)]$ .

Next, for any  $h^{(\pi)}\mathbf{d}_\pi$  such that  $h^{(\pi)} \in \mathbb{R}^+$  and  $\mathbf{d}_\pi \in \Delta(\pi_*)$ , there are  $h^{(v)} \in \mathbb{R}^+$ ,  $h^{(\lambda)} \in \mathbb{R}^+$ , and  $(\mathbf{s}_v, \mathbf{s}_\lambda) \in \Delta(\mathbf{v}_*) \times \Delta(\mathbf{\lambda}_*)$  such that  $h^{(\pi)}\mathbf{d}_\pi = [h^{(v)}\mathbf{s}_v', h^{(\lambda)}\mathbf{s}_\lambda']'$ . Therefore,

$$\begin{aligned} & \sup_{h^{(\pi)}} \{2DL_n(\boldsymbol{\theta}_*; \mathbf{d}_\pi)h^{(\pi)} + D^2L_n(\boldsymbol{\theta}_*; \mathbf{d}_\pi)(h^{(\pi)})^2\} \\ &= \sup_{(h^{(v)}, h^{(\lambda)})} 2\{DL_n(\boldsymbol{\theta}_*; \mathbf{s}_v)h^{(v)} + DL_n(\boldsymbol{\theta}_*; \mathbf{s}_\lambda)h^{(\lambda)} + DL_n(\boldsymbol{\theta}_*; \mathbf{s}_v, \mathbf{s}_\lambda)h^{(v)}h^{(\lambda)}\} \\ & \quad + D^2L_n(\boldsymbol{\theta}_*; \mathbf{s}_v)(h^{(v)})^2 + D^2L_n(\boldsymbol{\theta}_*; \mathbf{s}_\lambda)(h^{(\lambda)})^2 \\ &\Rightarrow \sup_{(h^{(v)}, h^{(\lambda)})} 2\{\mathcal{Z}(\mathbf{s}_v)h^{(v)} + \mathbf{s}_\lambda'\mathbf{Z}^{(\lambda)}h^{(\lambda)} + \mathbf{s}_\lambda'\mathbf{A}_*^{(\lambda, v)}(\mathbf{s}_v)h^{(v)}h^{(\lambda)}\} \\ & \quad + A_*^{(v, v)}(\mathbf{s}_v)(h^{(v)})^2 + \mathbf{s}_\lambda'\mathbf{A}_*^{(\lambda, \lambda)}\mathbf{s}_\lambda(h^{(\lambda)})^2. \end{aligned} \tag{15}$$

Given this,  $h^{(v)}$  and  $h^{(\lambda)}$  have to be at least greater than or equal to zero, so that the following four different inequality constraints can be possibly associated with this maximization process: first, if any equality condition does not bind,  $\sqrt{n}(\hat{h}_n^{(v)}(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau), \hat{h}_n^{(\lambda)}(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau))' \Rightarrow \mathcal{G}^{(\pi)}(\mathbf{s}_v, \mathbf{s}_\lambda)$  by the standard first-order condition and Lemma A1. This occurs if every component of  $\mathcal{G}^{(\pi)}(\mathbf{s}_v, \mathbf{s}_\lambda)$  is strictly greater than zero. Second, if  $\mathcal{G}^{(v)}(\mathbf{s}_v, \mathbf{s}_\lambda) < 0$ , it simply holds that  $\hat{h}^{(\lambda)}(\mathbf{s}_v, \mathbf{s}_\lambda) = \max[0, \dot{\mathcal{G}}^{(\lambda)}(\mathbf{s}_v, \mathbf{s}_\lambda)]$ , and  $\sqrt{n}(\hat{h}_n^{(v)}(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau), \hat{h}_n^{(\lambda)}(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau))' \Rightarrow (0, \max[0, \dot{\mathcal{G}}^{(\lambda)}(\mathbf{s}_v, \mathbf{s}_\lambda)])'$ . Third, if  $\hat{h}^{(\lambda)}(\mathbf{s}_v, \mathbf{s}_\lambda) = 0$  in the right side of (15) because  $\mathcal{G}^{(\lambda)}(\mathbf{s}_v, \mathbf{s}_\lambda) < 0$ ,  $\hat{h}^{(v)}(\mathbf{s}_v, \mathbf{s}_\lambda) = \max[0, \dot{\mathcal{G}}^{(v)}(\mathbf{s}_v, \mathbf{s}_\lambda)]$ . This implies that  $\sqrt{n}(\hat{h}_n^{(v)}(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau), \hat{h}_n^{(\lambda)}(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau))' \Rightarrow (\max[0, \dot{\mathcal{G}}^{(v)}(\mathbf{s}_v, \mathbf{s}_\lambda)], 0)'$ . Fourth, it must follow that

$\sqrt{n}(\widehat{h}_n^{(v)}(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau), \widehat{h}_n^{(\lambda)}(\mathbf{s}_v, \mathbf{s}_\lambda, \mathbf{s}_\tau))' \Rightarrow (0, 0)'$  for any other case. Therefore, if we combine all these and apply Theorem 1(i),

$$\sqrt{n} \begin{bmatrix} \widehat{h}_n^{(v)}(\cdot) \\ \widehat{h}_n^{(\lambda)}(\cdot) \\ \widehat{h}_n^{(\tau)}(\cdot) \end{bmatrix} \Rightarrow \begin{bmatrix} \mathcal{G}^{(v)}(\cdot) \\ \mathcal{G}^{(\lambda)}(\cdot) \\ 0 \end{bmatrix} \mathbf{1}_{\{\min[\mathcal{G}^{(v)}(\cdot), \mathcal{G}^{(\lambda)}(\cdot)] \geq 0\}} + \begin{bmatrix} \max[0, \dot{\mathcal{G}}^{(v)}(\cdot)] \mathbf{1}_{\{\mathcal{G}^{(v)}(\cdot) \geq 0 > \mathcal{G}^{(\lambda)}(\cdot)\}} \\ \max[0, \dot{\mathcal{G}}^{(\lambda)}(\cdot)] \mathbf{1}_{\{\mathcal{G}^{(\lambda)}(\cdot) \geq 0 > \mathcal{G}^{(v)}(\cdot)\}} \\ \max[0, \mathcal{G}^{(\tau)}(\cdot)] \end{bmatrix},$$

and this implies that

$$\sqrt{n}\widehat{h}_n^{(v)}(\cdot) \Rightarrow \max[0, \mathcal{G}^{(v)}(\cdot)] \mathbf{1}_{\{\min[\mathcal{G}^{(v)}(\cdot), \mathcal{G}^{(\lambda)}(\cdot)] \geq 0\}} + \max[0, \dot{\mathcal{G}}^{(v)}(\cdot)] \mathbf{1}_{\{\mathcal{G}^{(v)}(\cdot) \geq 0 > \mathcal{G}^{(\lambda)}(\cdot)\}}$$

under  $H_0$ . Therefore, it now follows that

$$\begin{aligned} \mathcal{W}_n \Rightarrow & \sup_{\mathbf{s}_v \in \Delta(\mathbf{v}_0)} \max[0, \mathcal{G}^{(v)}(\mathbf{s}_v, \bar{\mathbf{s}}_\lambda(\mathbf{s}_v))]^2 \widetilde{A}_*^{(v,v)}(\mathbf{s}_v) \mathbf{1}_{\{\min[\mathcal{G}^{(v)}(\mathbf{s}_v, \bar{\mathbf{s}}_\lambda(\mathbf{s}_v)), \mathcal{G}^{(\lambda)}(\mathbf{s}_v, \bar{\mathbf{s}}_\lambda(\mathbf{s}_v))] > 0\}} \\ & + \max[0, \dot{\mathcal{G}}^{(v)}(\mathbf{s}_v)]^2 \widetilde{A}_*^{(v,v)} \mathbf{1}_{\{\mathcal{G}^{(v)}(\mathbf{s}_v, \bar{\mathbf{s}}_\lambda(\mathbf{s}_v)) \geq 0 > \mathcal{G}^{(\lambda)}(\mathbf{s}_v, \bar{\mathbf{s}}_\lambda(\mathbf{s}_v))\}}, \end{aligned}$$

where for each  $\mathbf{s}_v$ ,

$$\bar{\mathbf{s}}_\lambda(\mathbf{s}_v) := \arg \sup_{\mathbf{s}_\lambda} [\mathcal{Z}^{(v)}(\mathbf{s}_v) \mathbf{s}_\lambda' \mathbf{Z}^{(\lambda)}] \begin{bmatrix} -A_*^{(v,v)}(\mathbf{s}_v) & -\mathbf{s}_\lambda' \mathbf{A}_*^{(\lambda,v)}(\mathbf{s}_v) \\ -\mathbf{s}_\lambda' \mathbf{A}_*^{(\lambda,v)}(\mathbf{s}_v) & -\mathbf{s}_\lambda' \mathbf{A}_*^{(\lambda,\lambda)} \mathbf{s}_\lambda \end{bmatrix}^{-1} \begin{bmatrix} \mathcal{Z}^{(v)}(\mathbf{s}_v) \\ \mathbf{s}_\lambda' \mathbf{Z}^{(\lambda)} \end{bmatrix},$$

Here, for given  $\mathbf{s}_v$ , optimizing process with respect to  $\bar{\mathbf{s}}_\lambda(\mathbf{s}_v)$  lets  $\mathcal{G}^{(\lambda)}(\mathbf{s}_v, \bar{\mathbf{s}}_\lambda(\mathbf{s}_v)) > 0$  because  $\boldsymbol{\lambda}_*$  is an interior element of  $\boldsymbol{\Lambda}$ . Therefore,

$$\mathcal{W}_n \Rightarrow \sup_{\mathbf{s}_v \in \Delta(\mathbf{v}_0)} \max[0, \mathcal{G}^{(v)}(\mathbf{s}_v, \bar{\mathbf{s}}_\lambda(\mathbf{s}_v))]^2 \widetilde{A}_*^{(v,v)} = \sup_{\mathbf{s}_v \in \Delta(\mathbf{v}_*)} \max[0, \widetilde{\mathcal{Y}}^{(v)}(\mathbf{s}_v)]^2 = \mathcal{H}_0,$$

and this completes the proof. ■

**Proof of Theorem 4:** For notational simplicity, we suppose that  $\boldsymbol{\tau}_*$  is known. By Theorem 2(i), this supposition simplifies our proof without losing generality.

To show the given claim, we derive the convergence limit of each component that constitutes the LM test statistic. First, there is  $n^*$  a.s.- $\mathbb{P}$  such that if  $n > n^*$ ,  $\Delta(\ddot{\boldsymbol{\lambda}}_n) = \Delta(\boldsymbol{\lambda}_*)$ . We note that  $\boldsymbol{\lambda}_*$  is an interior element by Assumption 7(vii), so that  $\Delta(\boldsymbol{\lambda}_*) = \{\mathbf{x} \in \mathbb{R}^{r_\omega} : \|\mathbf{x}\| = 1\}$ , and further for an open ball with radius  $\varepsilon > 0$  denoted as  $B(\boldsymbol{\lambda}_*, \varepsilon)$  such that  $B(\boldsymbol{\lambda}_*, \varepsilon) \subset \boldsymbol{\Lambda}$ , there is  $n(\varepsilon)$  a.s.- $\mathbb{P}$ , so that if  $n > n(\varepsilon)$ ,  $\ddot{\boldsymbol{\lambda}}_n \in B(\boldsymbol{\lambda}_*, \varepsilon)$  by Theorem 2(ii). This implies that  $\ddot{\boldsymbol{\lambda}}_n$  is an interior element, too. Thus, if we let  $n^* > n(\varepsilon)$ ,

$\Delta(\ddot{\lambda}_n) = \{\mathbf{x} \in \mathbb{R}^{r_\omega} : \|\mathbf{x}\| = 1\}$ , which is also  $\Delta(\lambda_*)$ . Second,  $n^{-1/2}DL_n(\ddot{\theta}_n; \cdot) \Rightarrow \ddot{Z}^{(v)}(\cdot; \ddot{s}_\lambda)$ .

Applying the mean-value theorem shows that for each  $\mathbf{s}_v$  there is  $\dot{\lambda}(\mathbf{s}_v)$  such that

$$\begin{aligned} DL_n(\ddot{\theta}_n; \mathbf{s}_v) - DL_n(\theta_*; \mathbf{s}_v) &= \{DL_n(\mathbf{v}_0, \dot{\lambda}_n(\mathbf{s}_v), \tau_*; \mathbf{s}_v; \ddot{s}_{\lambda,n})\} \{\ddot{h}_n^{(\lambda)}(\ddot{s}_{\lambda,n})\} \\ &= DL_n(\mathbf{v}_0, \dot{\lambda}_n(\mathbf{s}_v), \tau_*; \mathbf{s}_v; \ddot{s}_{\lambda,n}) \{-D^2L_n(\mathbf{v}_0, \bar{\lambda}_n(\mathbf{s}_v), \tau_*; \ddot{s}_{\lambda,n})\}^{-1} DL_n(\theta_*; \ddot{s}_{\lambda,n}), \end{aligned} \quad (16)$$

where  $(\ddot{h}_n^{(\lambda)}(\ddot{s}_{\lambda,n}), \ddot{s}_{\lambda,n}) := \arg \sup_{h^{(\lambda)}, s_\lambda} L_n(\mathbf{v}_0, \lambda_* + h^{(\lambda)} s_\lambda, \tau_*)$ , and the last equality follows from the mean-value theorem: there is  $\bar{\lambda}_n(\mathbf{s}_v)$  such that (16) holds. Given this and Theorem 2(ii), we can also apply the ULLN:

$$\sup_{\mathbf{s}_v, \mathbf{s}_\lambda} |n^{-1}DL_n(\mathbf{v}_0, \dot{\lambda}_n(\mathbf{s}_v), \tau_*; \mathbf{s}_v; \mathbf{s}_\lambda) - \mathbf{s}'_\lambda \mathbf{A}_*^{(v, \lambda)}(\mathbf{s}_v)| \xrightarrow{\mathbb{P}} 0, \quad \text{and}$$

$$\sup_{\mathbf{s}_v, \mathbf{s}_\lambda} |n^{-1}D^2L_n(\mathbf{v}_0, \bar{\lambda}_n(\mathbf{s}_v), \tau_*; \mathbf{s}_\lambda) - \mathbf{s}'_\lambda \mathbf{A}_*^{(\lambda, \lambda)} \mathbf{s}_\lambda| \xrightarrow{\mathbb{P}} 0.$$

Furthermore, it trivially holds that  $n^{-1/2}(DL_n(\theta_*; \cdot), DL_n(\theta_*; \ddot{s}_{\lambda,n})) \Rightarrow (\mathcal{Z}^{(v)}(\cdot), \ddot{s}'_\lambda \mathbf{Z}^{(\lambda)})$  by the facts that  $n^{-1/2}(DL_n(\theta_*; \mathbf{s}_v), DL_n(\theta_*; \mathbf{s}_\lambda))$  (as functions of  $\mathbf{s}_v$  and  $\mathbf{s}_\lambda$ , respectively) weakly converges to  $(\mathcal{Z}^{(v)}(\cdot), (\cdot)' \mathbf{Z}^{(\lambda)})$  and that  $\max[0, DL_n(\theta_*; \ddot{s}_{\lambda,n})]^2 \{-D^2L_n(\theta_*; \ddot{s}_{\lambda,n})\}^{-1} \Rightarrow \max[0, \mathcal{Y}^{(\lambda)}(\ddot{s}_\lambda)]^2$ , where  $\ddot{s}_\lambda := \arg \sup_{s_\lambda \in \Delta(\lambda_*)} \max[0, \mathcal{Y}^{(\lambda)}(s_\lambda)]^2$ . Thus, it follows that  $n^{-1/2}DL_n(\ddot{\theta}_n; \cdot) \Rightarrow \ddot{Z}^{(v)}(\cdot; \ddot{s}_\lambda)$  by applying the CMT, where

$$\ddot{Z}^{(v)}(\mathbf{s}_v; \ddot{s}_\lambda) := \mathcal{Z}^{(v)}(\mathbf{s}_v) - (\ddot{s}'_\lambda \mathbf{A}_*^{(v, \lambda)}(\mathbf{s}_v))(\ddot{s}'_\lambda \mathbf{A}_*^{(\lambda, \lambda)} \ddot{s}_\lambda)^{-1} \mathbf{Z}^{(\lambda)'} \ddot{s}_\lambda.$$

We also note that  $\ddot{Z}^{(v)}(\mathbf{s}_v; \ddot{s}_\lambda) = \mathcal{Z}^{(v)}(\mathbf{s}_v) - \mathbf{A}_*^{(v, \lambda)}(\mathbf{s}_v)' \{\mathbf{A}_*^{(\lambda, \lambda)}\}^{-1} \mathbf{Z}^{(\lambda)}$  by the definition of  $\ddot{s}_\lambda$  and Corollaries 1(iv and v), and the final entry was defined as  $\tilde{Z}^{(v)}(\mathbf{s}_v)$  earlier. Third, we apply the ULLN and obtain that  $\sup_{(\mathbf{s}_v, \mathbf{s}_\lambda)} |n^{-1}\tilde{D}^2(\ddot{\theta}_n; \mathbf{s}_v, \mathbf{s}_\lambda) - \tilde{A}_*^{(v, v)}(\mathbf{s}_v, \mathbf{s}_\lambda)| \rightarrow 0$  a.s.- $\mathbb{P}$ , where  $\tilde{A}_*^{(v, v)}(\mathbf{s}_v, \mathbf{s}_\lambda) := A_*^{(v, v)}(\mathbf{s}_v) - \mathbf{s}'_\lambda \mathbf{A}_*^{(v, \lambda)}(\mathbf{s}_v)(\mathbf{s}'_\lambda \mathbf{A}_*^{(\lambda, \lambda)} \mathbf{s}_\lambda)^{-1} \mathbf{A}_*^{(\lambda, v)}(\mathbf{s}_v)' \mathbf{s}_\lambda$ . Therefore, it follows that

$$\mathcal{LM}_n \Rightarrow \sup_{\mathbf{s}_v \in \Delta(\mathbf{v}_0)} \left( \frac{\max[0, \tilde{Z}^{(v)}(\mathbf{s}_v)]^2}{\inf_{\mathbf{s}_\lambda \in \Delta(\lambda_*)} \{-\tilde{A}_*^{(v, v)}(\mathbf{s}_v, \mathbf{s}_\lambda)\}} \right).$$

Here, note that  $\inf_{\mathbf{s}_\lambda \in \Delta(\lambda_*)} \{-\tilde{A}_*^{(v, v)}(\mathbf{s}_v, \mathbf{s}_\lambda)\} = -A_*^{(v, v)}(\mathbf{s}_v) + \sup_{\mathbf{s}_\lambda \in \Delta(\lambda_*)} \{\mathbf{A}_*^{(v, \lambda)}(\mathbf{s}_v)' \mathbf{s}_\lambda\} \{\mathbf{s}_\lambda' \mathbf{A}_*^{(\lambda, \lambda)} \mathbf{s}_\lambda\}^{-1} \{\mathbf{s}_\lambda' \mathbf{A}_*^{(\lambda, v)}(\mathbf{s}_v)\} = -\{A_*^{(v, v)}(\mathbf{s}_v) - \mathbf{A}_*^{(v, \lambda)}(\mathbf{s}_v)' \{\mathbf{A}_*^{(\lambda, \lambda)}\}^{-1} \mathbf{A}_*^{(\lambda, v)}(\mathbf{s}_v)\} = -\tilde{A}_*^{(v, v)}(\mathbf{s}_v)$ . Therefore,  $\mathcal{LM}_n \Rightarrow \sup_{\mathbf{s}_v \in \Delta(\mathbf{v}_0)} \max[0, \tilde{\mathcal{Y}}^{(v)}(\mathbf{s}_v)]^2$  as desired.  $\blacksquare$



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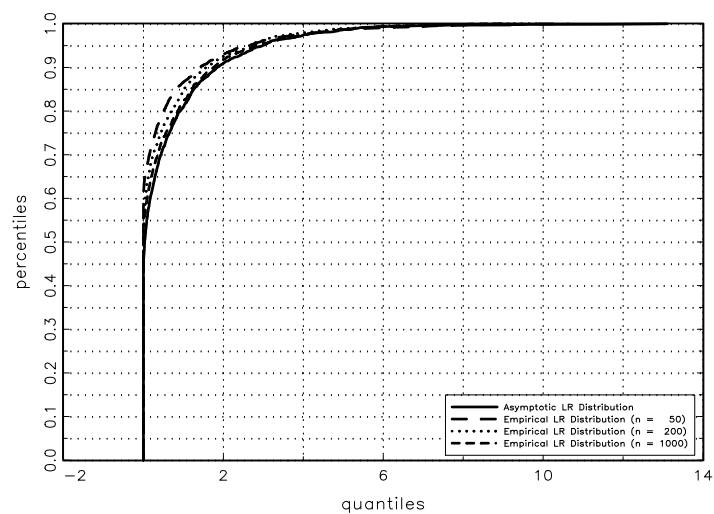


Figure 1: EMPIRICAL AND ASYMPTOTIC DISTRIBUTIONS OF THE QLR TEST STATISTIC. This figure shows the null limit distribution of the QLR test statistic and the empirical distributions of the QLR test statistic for  $n = 50, 200$ , and  $1,000$ . The number of iterations is  $2,000$ .