JINSEOK BAE

Interested in the data-driven approaches on physics-based character control and human-robot interaction.

Current at the PhD course in 3D Vision Lab, Seoul National University.

CONTACT

capoo95@snu.ac.kr

**** +82 10 5279 7144

♀ 1, Gwanak-ro, Gwanak-gu, Seoul

@jinseokbae

SKILLS

Java

Programming
Python
C++
JavaScript
Matlab

Operating Systems

Software & Tools

PyTorch
Jax
Tensorflow
Isaac Gym
Brax
Webots
Mujoco
OpenGL
WebGL
Blender
Unity
ROS

Languages
Korean
English
OPIc (AL level, 2021.09.25)
Japanese

CURRENT INTERESTS

- Deep Reinforcement Learning
 - multi agent RL
 - offline RL
- Generative Models
 - diffusion models
 - VAE
- Robots
 - multi-robot control
 - shared autonomy
- Physics-based Animation
 - human-object interaction
 - whole-body control
 - large scale motion learning
- 3D Vision
 - neural rendering
 - shape generation

EDUCATION

9/2022 - 8/2025 (expected)

Seoul National University

Ph.D in Electrical and Computer Engineering

GPA: 4.18/4.3

3/2020 - 2/2022

Seoul National University

M.S. in Electrical and Computer Engineering

GPA: 4.18/4.3

3/2014 - 2/2020

♀ Seoul National University

B.S. in Biosystems Engineering

B.S. in Electrical and Computer Engineering

GPA: 3.9/4.3 (Summa Cum Laude)

* military service completed (2/2016 - 2/2018)

WORK EXPERIENCE

1 01/2022-07/2022

• LG Al Research Digital Human Team, Vision Al Module

human motion generation

1 01/2019-02/2019

Samsung Electronics (Intern) Health H/W development, Mobile Division circuit design, c++ tools for debugging

血 SCHOLARSHIPS

- merit-based Scholarship (18'-fall, 19'-spring/fall), Seoul National University
- Agricultural Engineering Systems Scholarship (15'-spring/fall, 18'-spring), Agricultural Engineering Systems Scholarship Foundation

AWARDS

ICRA 2023 Simulated Humanoid Wrestling Challenge

Team Yeti (Jinseok Bae, Donggeun Lim, Minseok Kim, Young Min Kim, Jungdam Won)

% match, video

keywords:robot control, deep RL

TEACHING EXPERIENCE

2021 SummerSeoul Nat'l Univ.3D Computer Vision Track for AI Experts (Samsung) (T.A.)

2020 Spring

Signals and Systems (T.A.)

2018 Summer

Seoul Nat'l Univ. Korean Course for Exchange Students from Keio Univ. (T.A.)

▲ ACADEMIC ACTIVITIES

Conference Reviewer (AAAI 2023, ICCV 2023)

JINSEOK BAE

Interested in the data-driven approaches on physics-based character control and human-robot interaction.

Current at the PhD course in 3D Vision Lab, Seoul National University.

PUBLICATIONS

Dynamic Mesh Recovery from Partial Point Cloud Sequence

Hojun Jang, Minkwan Kim, Jinseok Bae, Young Min Kim

Spaper, video

keywords: 3D vision, kinematics learning

PMP: Learning to Physically Interact with Environments using Part-wise Motion Priors

Jinseok Bae, Jungdam Won, Donggeun Lim, Cheol-Hui Min, Young Min Kim

% paper, video

keywords: physics-based animation, deep RL, whole-body control

Neural Marionette: Unsupervised Learning of Motion Skeleton and Latent Dynamics from Volumetric Video

Jinseok Bae, Hojun Jang, Cheol-Hui Min, Hyungun Choi, Young Min Kim

2022 AAAI Conference on Artificial Intelligence (AAAI), Oral

Spaper, video

keywords: unsupervised learning, 3D vision, kinematics learning

Auto-rigging 3D Bipedal Characters in Arbitrary Poses

🥞 Jeonghwan Kim, Hyeontae Son, **Jinseok Bae**, Young Min Kim

2021 European Association for Computer Graphics (Eurographics) short paper

Spaper, video

keywords: neural rigging/skinning, pose estimation

GATSBI: Generative Agent-centric Spatio-temporal Object Interaction

Cheol-Hui Min, Jinseok Bae, Junho Lee, Young Min Kim

Spaper, video

keywords: unsupervised learning, video prediction, representation learning

CONTACT

capoo95@snu.ac.kr

**** +82 10 5279 7144

💡 1, Gwanak-ro, Gwanak-gu, Seoul

@jinseokbae

SKILLS

Programming

Python C++ JavaScript Matlab Java



Operating Systems

Linux Windows Mac

Software & Tools

PyTorch
Jax
Tensorflow
Isaac Gym
Brax
Webots
Mujoco
OpenGL
WebGL
Blender
Unity
ROS

Languages

Korean
English
OPIc (AL level, 2021.09.25)
Japanese

CURRENT INTERESTS

- Deep Reinforcement Learning
 - multi agent RL
 - offline RL
- Generative Models
 - diffusion models
 - VAE
- Robots
 - multi-robot control
 - shared autonomy
- Physics-based Animation
 - human-object interaction
 - whole-body control
 - large scale motion learning
- 3D Vision
 - neural rendering
 - shape generation