

① Vector, modify notation

⑤ Linear Combination (벡터의 가중 합)

② unit vector

$$A = \begin{bmatrix} \textcircled{1} & \textcircled{0} \\ \textcircled{0} & \textcircled{1} \end{bmatrix} = [a_1 \ a_2]$$

$a_1 \ a_2$

③ Norm & Regularization

$$\text{Span}(A) = \text{span}(w_1 a_1 + w_2 a_2 \mid w_1, w_2 \in \mathbb{R})$$

$$\therefore \text{Loss Function} = \sum_i (y - \hat{y})^2 + \sum_i \rho_i^2$$

$$A = \begin{bmatrix} 1 & 0 & 1 & 2 & \dots \\ 0 & 1 & 1 & 3 & \dots \end{bmatrix} = [a_1, a_2, \dots, a_{10}]$$

④ Inverse Matrix, Transaction

$\text{span}(A) \in \mathbb{R}^2$ Generating set of Vector Space

$$(AB)^{-1} = B^{-1}A^{-1} \quad (AB)^T = B^T A^T$$

↓
minimal \Rightarrow Basis
LI

$$(A^{-1})^T = A^T \quad (A^T)^T = A$$

Linear independent G.S.O.V.S

$$(A+B)^{-1} \neq A^{-1} + B^{-1} \quad (A+B)^T = A^T + B^T$$

⑥ Symmetric matrix $\rightarrow A = A^T \in \mathbb{R}^{n \times n}$ (square)

$$A = X \cdot X^T \quad A^T = (X \cdot X^T)^T = X \cdot X^T$$

⑦ Orthogonal Matrix

$$A = \begin{bmatrix} \textcircled{a_1} & \textcircled{a_2} & \textcircled{a_3} \end{bmatrix}$$

↓ ↓ ↓
orthonormal

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

↓
 $A^T = A$

$$A = \begin{bmatrix} \textcircled{3} & \textcircled{6} \\ \textcircled{6} & \textcircled{6} \end{bmatrix} = [a_1, a_2]$$

↓ ↓
not orthonormal

⑧ Rank : linear independent \vec{a}_i vector of A

$$A = \mathbb{R}^{m \times n} \rightarrow \text{rank}(A) \leq \min(m, n) \quad B = \begin{bmatrix} \textcircled{1} & \textcircled{0} & \textcircled{1} \\ \textcircled{0} & \textcircled{1} & \textcircled{1} \\ \textcircled{0} & \textcircled{0} & \textcircled{3} \end{bmatrix} \rightarrow \text{rank}(B) = 3 \quad B^{-1} \text{ exist}$$

$$A = \begin{bmatrix} \textcircled{1} & \textcircled{0} & \textcircled{1} \\ \textcircled{0} & \textcircled{1} & \textcircled{1} \\ \textcircled{0} & \textcircled{0} & \textcircled{0} \end{bmatrix} \rightarrow \text{rank}(A) = 2$$

↓
linear dependent
↓
linear independent

Linear independent

⑨ Range Space : $A \in \mathbb{R}^{m \times n} \quad Ax = b, x \in \mathbb{R}^{n \times 1}, b \in \mathbb{R}^{m \times 1}$

$$\mathcal{R}(A) = \{ b \in \mathbb{R}^m \mid Ax = b \text{ for } x \in \mathbb{R}^n \}$$

$$Ax = b \rightarrow A^T \cdot A x = A^T \cdot b \quad \therefore x = (A^T \cdot A)^{-1} \cdot A^T \cdot b$$

$\in \mathbb{R}^{m \times n}$

⑩ Null space $\rightarrow N(A) = \{x \in \mathbb{R}^n \mid Ax = 0\}$

ex) $A = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$ $R(A) = \{b = \begin{bmatrix} 0 \\ 0 \end{bmatrix}\}$ $N(A) = \{x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \mid x_1, x_2 \in \mathbb{R}\}$

ex) $B = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$ $R(B) = \{b = \begin{bmatrix} x_1 \\ 0 \end{bmatrix} \mid x_1 \in \mathbb{R}\}$ $\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} x_1 \\ 0 \end{bmatrix}$

$N(B) = \{x = \begin{bmatrix} 0 \\ x_2 \end{bmatrix} \mid x_2 \in \mathbb{R}\}$ $Bx = 0 \Rightarrow \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow x_1 = 0$

⑪ Norm & #1 Input operation output
 $\downarrow \quad \quad \downarrow \quad \quad \downarrow$
 vector $L1$ or $L2 \rightarrow$ scalar

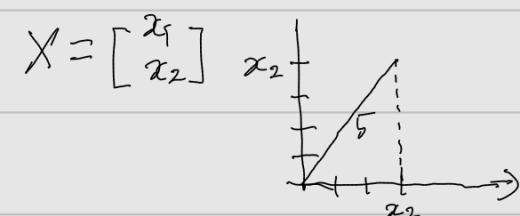
• $L1$ & #2 (Inner Product)

$\cdot \langle x, y \rangle = \|x\| \|y\| \cos \theta \quad x, y \in \mathbb{R}^n \quad x = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \quad y = \begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix}$
 $= \sum_{i=1}^n x_i y_i = x^T y$

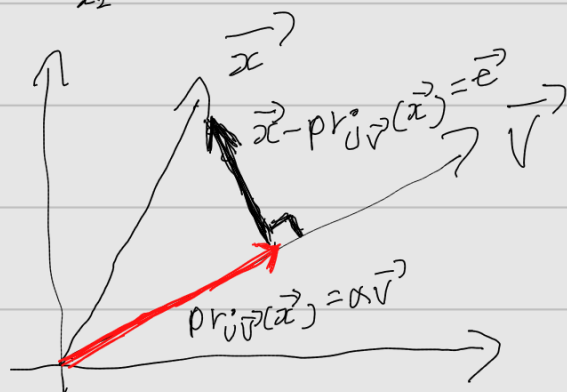
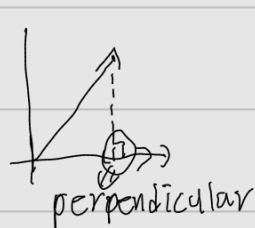
$\cdot \langle x, x \rangle = \sum_{i=1}^n x_i^2 = \|x\|_2^2 = x^T x$

• distance

$L1 = \sum |x_i| \quad L2 = \sqrt{\sum x_i^2} \quad d_1 = \sum_i (x_i - y_i) \quad d_2 = \sqrt{\sum_i (x_i - y_i)^2}$



⑫ projection



i) $\text{prj}_v(\vec{x}) = \alpha \vec{v}$

ii) $\vec{e} = \vec{x} - \text{prj}_v(\vec{x})$

iii) $\langle v, e \rangle = v^T e = 0$

$\hookrightarrow v^T (\vec{x} - \text{prj}_v(\vec{x})) = 0$

$\hookrightarrow v^T \vec{x} - v^T \text{prj}_v(x) = v^T x - v^T \alpha v$

$= v^T x - \alpha v^T v = 0$

$\therefore \alpha = \frac{v^T x}{v^T v} \quad \text{prj}_v(x) = \alpha v = \frac{v^T x}{v^T v} v = \frac{v v^T}{v^T v} x$