

# ASM EAGLE XTREME/TWIN EAGLE XTREME WIREBONDER

Host Programmers Manual

Revision 1.15 5 July 2012

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## 1. Revision History

Rev	<b>Document Generator</b>	Date	Reviewers	Description of Changes		
1.0	Baoping Li	25 May 2009		Base VERSION of Eagle Xtreme		
1.1	Chen Chen	23 July 2009		Standardize CEID, SVID with Eagle60		
1.2	Chen Chen	18 May 2010		Add auto save finish event		
1.3	Chen Chen	23 May 2010		Redefine all the alarm ID for Xtreme		
1.4	Chen Chen	01 June 2010		Add new SVID for scrub parameters		
1.5	Chu Yue	07 June 2010		<ul> <li>Add new CEID for message recognition.</li> <li>Modify CEID 51 definition.</li> </ul>		
1.6	Chen Chen	06 Aug 2010		Add new CEID, SVIDs.		
1.7	Chen Chen	21 Oct 2010		Add BSOB wire parameter in CEID 78     Update Alarm ID.		
1.8	Justin/Chu Yue	26 Dec 2010		Add alarm ID		
1.9	Justin	14 Jan 2011		Removed unused/duplicate SVIDs		
1.10	Chen Chen	16 May 2011		Add create default strip map function.		
1.11	Chu Yue	1 Sep 2011		Add CEID RPTID SVID for Idealine Add Multi Lot sequence		
1.12	Chen Chen	06 Jan 2012		Add CEID 117 && 118 for capillary count hit warning limit and stop limit.		
1.13	Chu Yue	24 April		Add CEID 478848 SVID 1400~1414, REPORTID125,CEID 125		
1.14	Chu Yue	18 May		Add SVID RPTID CEID		
1.15	Sun Zhaoyan	5 July 2012		Add SVID, CEID, ALARM ID		

## 2. Introduction

## 2.1. DOCUMENT HISTORY

This is the first release version of ASM Eagle Xtreme Gold Wire Bonder SECS Host Programmer's Manual.

## 2.2. SCOPE

This document defines ASM Eagle Xtreme/Twin Eagle Xtreme/Harrier Xtreme Gold Wire Bonder SECS-II communication capabilities and interactions between the wire bonder and a host computer. It is limited to the specific behavior of the wire bonder in a communication link. Communications in this document are intended for an equipment-to-host relationship and do not address equipment-to-equipment application.

## 2.3. INTENT

This document serves as an introduction to the capabilities of Eagle Xtreme Gold Wire Bonder in SECS communication aspect. It is also intended to provide a basis for implementing the interaction functions for the host computer with the wire bonder.

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## 2.4. OVERVIEW

This document is divided into sections as described below.

#### **SECTION 2: Introduction**

This section provides the revision history, scope and intent of this document. It also provides an overview of the structure of this document.

#### **SECTION 3 : State Model**

This section describes the behavior of Eagle Xtreme Gold Wire Bonder from a host perspective.

#### **SECTION 4 : Equipment Capabilities**

This section provides a brief description of the communication capabilities defined for and supported by the wire bonder. The description of each capability includes the purpose and a brief description.

#### **SECTION 5 : SECS Message Subset**

This section provides a composite list of the SECS-II message required to implement all capabilities described.

## 2.5. APPLICABLE DOCUMENTS

This document references specific portions of the SEMI standards listed below:

SEMI E4-0699 SEMI Equipment Communication Standard 1

470 Message Transfer (SECS-I)

SEMI E5-0999 SEMI Equipment Communication Standard 2

1. Message Content (SECS-II)

SEMI E30-0200A Generic Model for Communication and Control of SEMI Equipment (GEM)

SEMI E37 High Speed SECS Message Services
-Comparison of SECS-1 and HSMS

## 3. STATE MODELS

A state model is a collection of states and state transitions which combine to describe the behavior of a system. The basic unit of a state model is the state. A state is a static set of conditions. If the conditions are met, the state is current. These conditions may be stimulated by the operator input at the wire bonder, received SECS message, expired timer, and changes in the sensors reading.

This model includes definition of the conditions which delineate a state, the action/reactions possible within a state, the event which triggers transitions to other states, and the process of transiting between states. The following section contains the finite state models for Eagle Xtreme Gold Wire Bonder. Supporting figures are also included. These state models describe the behavior of the wire bonder from a host perspective in a compact and easy to understand format.

## 3.1. COMMUNICATIONS STATE

The communications state model defines the behavior of the wire bonder in relation to the existence or absence of a communication link with the host. It can be viewed as a logical connection between equipment and host rather than a physical connection.

There are two major states of SECS communications, DISABLED and ENABLED, where the ENABLED state has two sub states, NOT COMMUNICATING and COMMUNICATING.

#### **DISABLED**

In this state SECS-II communication with a host computer is non-existent. If the operator switches from ENABLED to DISABLED, all SECS-II communications cease immediately. All messages queued to

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send shall be discarded, and all further action on any open transactions and conversation shall be terminated.

A simulated ICON is displayed on the screen to give feedback on the current communications state.

Not Exists - DISABLED

RED - NOT COMMUNICATING

GREEN / YELLOW - COMMUNICATING (Color depends on Control State)

#### **ENABLED**

Whenever communication is enabled, either during system initialization or through operator selection, the sub state NOT COMMUNICATING is active until communications are formally established.

#### **NOT COMMUNICATING**

No message other than S1F13, S1F14 and S9Fx shall be sent while the wire bonder is in this sub state. The wire bonder will discard all messages received from the host other than S1F13 and S1F14. It also periodically attempts to establish communications with the host computer by issuing S1F13 until communications are successfully established.

#### **COMMUNICATING**

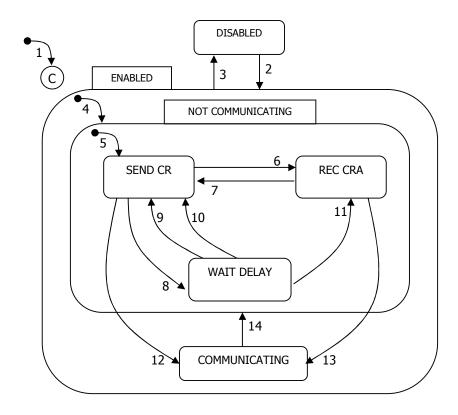
In this sub state, SECS communications with a host computer must be maintained. In the event of communications failure, the wire bonder will return to the NOT COMMUNICATING sub state and attempt to re-establish communications with the host system. The wire bonder will remain in this sub state until communications are disabled or a communication failure occurs.

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#### ASMGEM Communication State Diagram





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#### ASMGEM Communication State Table

#	CURRENT STATE	TRIGGER	NEW STATE	ACTION	Соммент
1	(Entry to COMMUNICATIONS)	System Initialization	System Default	None	System default may be ENABLED or DISABLED
2	DISABLED	Operator switches from DISABLED to ENABLED	ENABLED	None	SECS II communications are started
3	ENABLED	Operator switches from ENABLED to DISABLED	DISABLED	The simulated LED is removed	SECS II communications are prohibited
4	(Entry to ENABLED)	Any entry to ENABLED state	NOT COMMUNICATING	A simulated RED LED is displayed on the top right of the screen	May enter through system initialization to ENABLED, or through operator switch to ENABLED.
5	NOT COMMUNICATING	Any entry to NOT COMMUNICATING	SEND CR	Initialize communications, send S1,F13	Begin to establish communications, may receive S1,F13 from Host
6	SEND CR	Received S1,F13 from Host	REC CRA	Decode message and attempt to send S1,F14	If S1,F13 previously sent, wait for S1,F14 reply
7	REC CRA	COMMACK <> 0 of received S1,F14 or failed to send S1,F14	SEND CRA	Send S1,F13	Host disallowed a connection so try again
8	SEND CR	Connection Transaction Failure	WAIT DELAY	Initialize CommDelay timer. Dequeue all messages queued to send	Place dequeued messages on the spool buffer if spool enabled
9	WAIT DELAY	CommDelay Timer expired	SEND CR	Send S1,F13	Wait for S1,F14, may receive S1,F13 from Host
10	WAIT DELAY	Received a message other than S1,F13	SEND CR	Discard message, no reply and send S1,F13	Indicates opportunity to establish communication
11	WAIT DELAY	Received an S1,F13 message	REC CRA	Decode message and send S1,F14	Host attempting to establish communications
12	SEND CR	Received S1,F14 with COMMACK = 0	COMMUNICATING	The simulated LED becomes GREEN / YELLOW	Communication has been established
13	REC CRA	Sent S1,F14 successfully and any pending S1,F14 from Host completed without Transaction Failure	COMMUNICATING	The simulated LED becomes GREEN / YELLOW	Communication has been established. If a Transaction Fault occurs, send S9,F9
14	COMMUNICATING	Transaction Failure occurs	NOT COMMUNICATING	The simulated LED becomes RED	Communication has been lost

Upon equipment power-up, the wire bonder will establish its default setting for all constants and variables retained in non-volatile memory. Once system initialization has been achieved, the wire bonder will attempt to establish communications with the host computer. A successful attempt will cause the wire bonder to fall into COMMUNICATING STATE, whereas a failure will result in NOT COMMUNICATING state.

Once initialization has completed, the operator is able to enable/disable the communication at any time, by toggling the enable flag shown in the [Setup] [SECS/GEM Communication] [SECS/GEM Options] menu. There are no collection events linked to the Communications State Model.

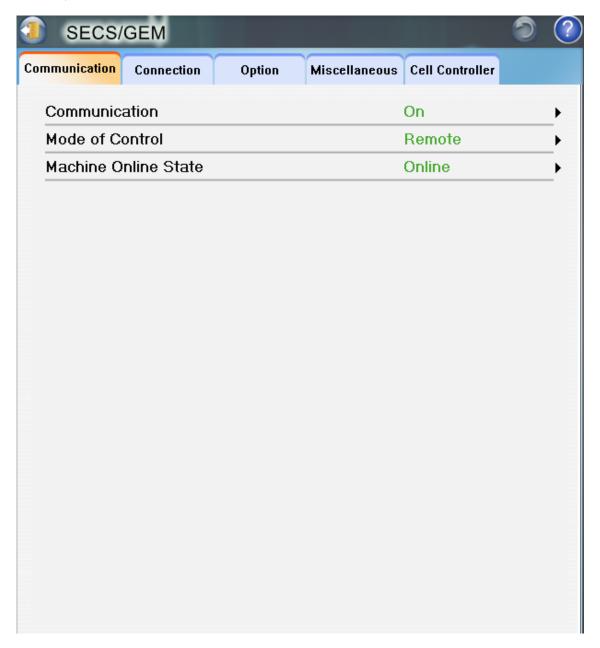
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## 3.2. CONTROL STATE

The intent of this capability is to allow flexibility in the control of the wire bonder in the manufacturing environment. The control state model defines the level of action / data extraction that can be exercised on the wire bonder by the host system.

The control state allows the Host 3 basic levels of control operations on the equipment, being OFFLINE, ONLINE/LOCAL and ONLINE/REMOTE.



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The operator can select between these 3 levels by changing the menu items

Mode Of Control (REMOTE / LOCAL)
 Machine Online State (ONLINE / OFFLINE)

in the [Configuration] [Factory Automation] [SECS/GEM] [Options] page.

The ONLINE/LOCAL control state is used when it is desired that the host have no direct control over the operation of the equipment but still allow the Host to obtain data. Where as the ONLINE/REMOTE control state is used to allow the host to have "front panel" control of the wire bonder and still allow data extraction.

The OFFLINE control state is used when no control or data collection will be allowed by the Host.

A simulated LED at the top right of the display screen indicates a summary of the control state:

RED - NOT COMMUNICATING
GREEN - ONLINE (LOCAL or REMOTE)
YELLOW - OFFLINE (User or Host initiated)
Not Exist - Communication DISABLED

A change in this control state will generate a collection event.

#### 3.2.1. LOCAL

When the wire bonder is in the LOCAL control state, the operator has sole control of the wire bonder and its related process. The host has absolutely no control over any aspect of the wire bonder's process. Any host directed activity which has a direct effect on the process will not be accepted and the wire bonder will respond with an appropriate acknowledge code.

There is no restriction on data collection by the host when the wire bonder is in LOCAL control state.

## 3.2.2. **REMOTE**

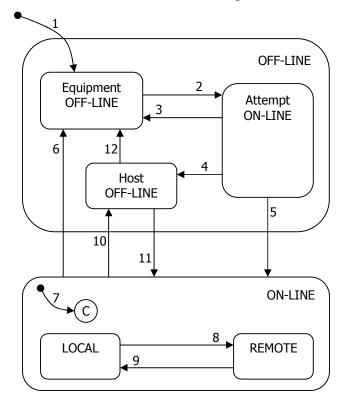
In the REMOTE control state, the host has the capability to start or stop processing. However, the operator has ultimate authority in overriding host control of the wire bonder. In this mode the Host is able to send Remote Command S2,F21 and Host Command S2,F41 to direct the operation of the equipment.

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## ASMGEM Control State Diagram



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#### ASMGEM Control State Table

#	CURRENT STATE	TRIGGER	NEW STATE	ACTION	COMMENT
1	(Undefined)	Entry into CONTROL state (system initialization)	Equipment OFF-LINE	None	Machine power up always resets the system to OFF-LINE
2	Equipment OFF-LINE	Machine Online State (menu) is set to ONLINE	Attempt ON-LINE	Send S1,F1	Trigger is based on the current menu setting, not on the action of toggling the state
3	Attempt ON-LINE	Communication failure during S1,F1 send	Equipment OFF-LINE	None	Unable to send the message causes a looping effect between Equipment OFF-LINE and Attempt ON-LINE
4	Attempt ON-LINE	Received S1,F0 or timeout from sending S1,F1	Host OFF-LINE	None	Assume that the Host is there because S1,F1 was successfully sent but incorrect reply.
5	Attempt ON-LINE	Host replied with S1,F2	ON-LINE	None	Host will be informed of the transition to ON-LINE at transition 7
6	ON-LINE	Operator toggles the Machine Online state (menu) to OFFLINE	Equipment OFF-LINE	Send event	"Equipment OFF-LINE" event is sent to the Host.
7	(Undefined)	Entry to ON-LINE state	(Sub-state conditional on REMOTE / LOCAL setting)	Send event	Sends either "Control State REMOTE" or "Control State LOCAL" depending on the Mode Of Control menu item
8	LOCAL	Operator toggles Mode Of Control to REMOTE	REMOTE	Send event	"Control State REMOTE" is sent to the Host. Machine is now able to accept remote commands from the Host.
9	REMOTE	Operator toggles Mode Of Control to LOCAL	LOCAL	Send event	"Control State LOCAL" is sent to the Host. Remote commands are no longer accepted
10	ON-LINE	Equipment accepts S1,F15 "Set OFF- LINE" message from Host	Host OFF-LINE	Send event	"Equipment OFF-LINE" event occurs
11	Host OFF-LINE	Equipment accepts request to go ON- LINE from Host, S1,F17	ON-LINE	None	Host will be informed of the transition to ON-LINE at transition 7
12	Host OFF-LINE	Operator toggles the Machine Online state (menu) to OFFLINE	Equipment OFF-LINE	None	Equipment was already OFFLINE so no new event is sent to the Host

NOTE: Communication is severely restricted under the OFFLINE states.

Equipment will only send

S1,F13 - To establish communication (Part of the Communication Model)

S1,F1 - To attempt to go ONLINE

S1,F14 - In response to S1,F13 (Part of the Communication Model)

S1,F18 - In response to S1,F17 (only from Host OFF-LINE state)

S9,Fx - In response to a receive error in S1,F13 or S1,F17
Sx,F0 - In response to all other primary messages (including S1,F17 if not in Host OFF-LINE state)

Equipment will discard all replies except S1,F14 and S1,F2.

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## 3.3. EQUIPMENT PROCESSING STATE

This model describes the typical operation of the wire bonder with the emphasis on SECS implementation issues. The behavior of the wire bonder in the performance of its function at any time can be classified under one of the following states. As the Eagle Xtreme Gold Wire Bonder is using menu driven control, entering each menu can cause a transition to a state corresponding to the function of the items in that menu. The wire bonder will generate collection events for each processing state transition.

## 3.3.1. INIT

Init state is not an actual processing state. It is shown here just to indicate that upon completion of wire bonder internal initialization, the IDLE state is entered. No communication is allowed before the initialization completed, as the wire bonder is setting the default values for the equipment constants and variables.

## 3.3.2. IDLE

In this state, the wire bonder is waiting for instructions. After going through the initialization procedure and success in establishing communication with the host computer, the wire bonder is ready to accept the next command. Besides initialization, this state can be re-entered after changing the process parameters, the completion of the processing cycle, or receipt of a STOP command when doing continuous bonding.

#### 3.3.3. SETUP

Entering this state means the operator is trying to setup the process variables or changing the control parameters. The wire bonder is in this state when the operator enters one of these menus: [Program Menu], [Configuration Menu], [Maintenance Menu], [Utility Menu], and [System Menu].

#### 3.3.4. EXECUTING

This is the state when the wire bonder is executing a process program automatically after receiving a start command from the operator, and will remain in this state until a STOP command is received or the process is completed. The occurrence of an event requiring external assistance will result in a transition to alarm state, where an alarm report will be sent if it is enabled and the wire bonder is in communicating state.

#### **EXECUTING - LOCAL**

Processing and remote control commands from the host are restricted. The host is unable to initiate a change of state. This state is entered if the START key I pressed when the wire bonder is in IDLE mode.

#### **EXECUTING - REMOTE**

Processing is under host control. However, the operator will have the ability to override the host control. The STOP command, and REMOTE / LOCAL selection is always available.

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### 3.3.5. **PAUSE**

In this state, processing is suspended and the equipment is awaiting a command. Transition to pause state may be operator initiated, i.e., when key '1' (Single Bond) is pressed, or host initiated at via the STOP command, when the wire bonder is doing auto bonding. Upon receipt of a START command from the host or when key '0' (Auto Bond) is processed, the wire bonder will request the operator to resume to the executing state.

#### 3.3.6. ALARM

Any event that may endanger people, equipment or material being processed will result in transition to the alarm state and the generation of an appropriate alarm. Processing will be suspended until the necessary actions have resulted in the alarm being cleared.

## 3.3.7. **UPLOAD**

The process program in AB339E Gold Wire Bonder refers to the entire set of process parameters and control parameters. The process programs transferred between the wire bonder and the host computer are unformatted process program. The UPLOAD action refers to transferring the process program from the wire bonder to the host computer, while the DOWNLOAD action means the opposite direction.

Uploading process programs can be initiated by either the operator at the wire bonder or by the Host system.

The process state will become UPLOAD only if the operator initiates the upload.

#### 3.3.8. DOWNLOAD

The program download operation can be initiated by either the operator or the Host computer. The process state will become DOWNLOAD only if the operator initiates the download.

With this method, the Host can send multiple programs to the wire bonder before the current process lot is completed. If the machine is bonding during the download process, the bonding may pause for a few seconds when a new process program is received, as the data must be decompressed and stored to hard disk. The bonding quality is not affected at any time. It has been taken into consideration that the operator is the person who knows when will the current lot completed, and therefore he should have the final decision to switch to the next process program.

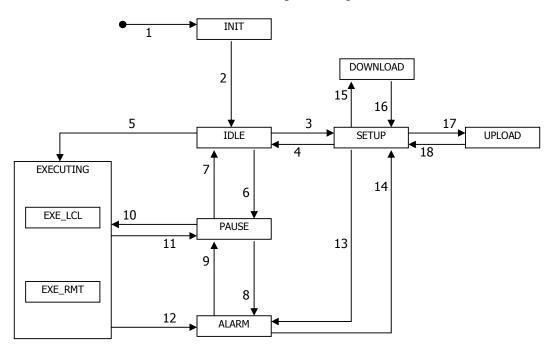
If the operator initiated the download, then the process program will automatically be loaded into memory when it is received. The DOWNLOAD state will remain until the process program is fully loaded into memory from its storage space.

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## ASMGEM Processing State Diagram



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ASMGEM Processing State Table

#	CURRENT STATE	TRIGGER	NEW STATE	ACTION	Соммент
1	(Entry to INIT)	System Initialization	INIT	None	No communication at this time as the system is still powering up
2	INIT	Initialization complete	IDLE	The tower lamp becomes YELLOW	Able to accept Remote commands and unformatted process programs if such options enabled.
3	IDLE	User navigates to one of the following menus  - Setup  - Teach  - Wire Parameters  - Parameter  - WH Menu  - WH Setup	SETUP	None	User has indicated that some parameters need adjustment or a new device is to be set up
4	SETUP	User finishes adjusting parameters or setting up a new device	IDLE	None	Returning to the Main menu or jumping to the Auto Bond menu
5	IDLE	User selects Start Auto bond from the menu and a valid process program is in memory	EXECUTING (EXE_LCL if Remote Control is DISABLED otherwise EXE_RMT)	Machine starts performing the bonding of devices. The tower lamp becomes GREEN	The operator has taught or loaded a valid process program and adjusted the parameters to a stage where the machine is ready to bond the device.
6	IDLE	User selects Start Single bond from the menu and a valid process program is in memory	PAUSE	Machine will perform any necessary PR, stop at the next wire to be bonded and show the Single Bond menu	The operator has taught or loaded a valid process program and adjusted the parameters to a stage where the machine is ready to bond the device
7	PAUSE	User quits from the Single Bond menu or the Host sends a remote command to exit from bonding	IDLE	None	The operator or the Host has cancelled any bonding operation
8	PAUSE	User attempts to start bonding but the machine detects an error and raises an alarm	ALARM	Alarm is set and the tower lamp becomes RED	The alarm message will display on the screen and wait for the operator to press a key.
9	ALARM	User responds to the alarm signal and presses a key	PAUSE	Alarm is cleared and the tower lamp becomes YELLOW	The alarm message is cleared and the operator is free to correct the cause of the alarm
10	PAUSE	User selects Start Auto Bond from the Single Bond menu	EXECUTING (EXE_LCL if Remote Control is DISABLED otherwise EXE_RMT)	Machine continues the bonding cycle and the tower lamp becomes GREEN	Operator has verified the bonding quality and now continues to bond devices
11	EXECUTING	User presses the Single Bond button, or the machine stops automatically because of an enabled Last LF or Pause function, or Host sent a relevant Remote Command	PAUSE	Single Bond menu is displayed and the tower light becomes YELLOW	Usually performed by the operator while checking on the quality of the bonding manually

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ASMGEM Processing State Table Continued

#	CURRENT STATE	TRIGGER	NEW STATE	ACTION	Соммент
12	EXECUTING	During the bonding of the device an error is encountered eg. PR Failure	ALARM	Alarm is set and the tower lamp becomes RED	The alarm message will display on the screen and wait for the operator to press a key.
13	SETUP	During the adjustment an error was encountered	ALARM	Alarm is set and the tower lamp becomes RED	The alarm message will display on the screen and wait for the operator to press a key.
14	ALARM	Operator responds to the error generated during any setup operations	SETUP	Alarm is cleared and the tower lamp becomes YELLOW	The alarm message is cleared and the operator is free to correct the cause of the alarm
15	SETUP	Operator selects Load from Host	DNLOAD	Asks the user to key in the name to get from the host	If the user inputs the name, then the file will be requested to be downloaded from the Host. A message is displayed on the screen informing the operator that a file is being downloaded
16	DNLOAD	File downloaded from the Host or the user cancelled the operation	SETUP	None	If the download is complete, then the operator will be asked whether to load the process program. If the operator answers affirmative, then the process program is loaded into memory before the state changes to SETUP
17	SETUP	Operator selects Save To Host or Copy Pgm To Host	UPLOAD	Asks the user to key in a filename to save or select an existing file from the file list	If the user selects the filename then the file will be sent to the Host in ".WB" format. A message is displayed on the screen informing the operator that the file is being uploaded
18	UPLOAD	File uploaded to Host or the user cancelled the operation	SETUP	None	

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## 4. EQUIPMENT CAPABILITIES

This section describes the wire bonder interface capabilities. These interface operations are initiated through the communications interface using SECS-II messages.

The ASM Eagle Xtreme Gold Wire Bonder supports the following capabilities:

- 4.1 Establish Communications
- 4.2 On-line Identification
- 4.3 Data Collection
  - 4.3.1 Status Data Collection
  - 4.3.2 Variable Data Collection
  - 4.3.3 Event Data Collection
- 4.4 Dynamic Event Report Configuration
- 4.5 Alarm Management
- 4.6 Remote Control
- 4.7 Equipment Constants
- 4.8 Process Program Management
- 4.9 Error Messages
- 4.10 Clock
- 4.11 Terminal Services
- 4.12 Diagnostics

## 4.1. ESTABLISH COMMUNICATIONS

The establish communications capability provides a means of formally establishing communications following power-up or any loss of communications between communicating partners. Communications between host and wire bonder are formally established through the use of the Establish Communications Reguest / Establish Communications Acknowledge Transaction (S1F13/S1F14).

In conjunction with the Communications State Model, when the wire bonder is in NOT COMMUNICATING state, it will disregard all host messages except the Establish Communication Request and Establish Communications Acknowledge Transaction. It will also attempt to establish communications by periodically sending the Establish Communications Request until the communications have been formally established. The host may also try establishing communications with the wire bonder at any time when the communications state is ENABLED.

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#### 4.1.1. **Establish Communications Messages**

#### S1, F13 Establish Communications Request (CR)

S, H ⇔ E, reply

Description

: Provides a formal means for the initialization of the communication, either upon power up or to re-establish after a break in communications. Ie. This should always be the first message that is sent in setting up the communications link. Please refer to the Communications State Model for details on the repeat interval and state transitions required before the equipment is said to be in the COMMUNICATING state.

Structure

: L, 2

1. <A MDLN>

2. <A SOFTREV>

Exception

: The host sends a zero-length list to the equipment.

Note

**MDLN** 

ASCII string with a maximum length of 6 bytes used to hold the machine model number. For the case of the Eagle Xtreme wire bonder it will always be "Eg XT"

**SOFTREV** 

ASCII string with a maximum length of 6 bytes used to hold the version number of the software running on the machine. This will always return the PC version number. Eg. If the machines PC software version is 09.05.92, then the data stored in this variable will be "090592"

#### S1, F14 Establish Communications Request Acknowledge (CRA)

S, H⇔E

Description : Accepts or denies the request from the originator to set up the communications link.

Structure

1. <B COMMACK>

2. L,2

: L,2

1. <A MDLN>

2. <A SOFTREV>

Exception

: The host sends a zero-length list for item 2 to the equipment. (ie. Doesn't send

MDLN or SOFTREV)

Note

COMMACK

1 byte binary informing whether establish communications is allowed at this time.

0 = Accepted

1 = Denied, Try Again

2~63 Reserved

MDLN and SOFTREV are only valid if COMMACK = 0

**MDLN** 

ASCII string with a maximum length of 6 bytes used to hold the machine model number. For the case of the Eagle Xtreme wire bonder it will always be "EAGLE"

**SOFTREV** 

ASCII string with a maximum length of 6 bytes used to hold the version number of the software running on the machine. This will always return the PC version number. Eg. If the machines PC software version is 09.05.92, then the data stored in this variable will be "090592"

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## 4.1.2. Establish Communications Scenarios

Host Attempts to Establish Communications COMMENT HOST	EQUIPMENT COMMENT Communications State is ENABLED
Establish Communications Request (CR) S1,F13 ÷	
	Establish Communications Request Acknowledge (CRA) ← S1,F14 Reply COMMACK = Accept (0) Communications State = COMMUNICATING
Host Attempts to Establish Communications	
COMMENT HOST	COMMENT Communications State = NOT COMMUNICATING [LOOP] [LOOP] - SEND Establish Communications Request (CR)
Establish Communications Request Acknowledge (CRA) S1,F14 ÷	,
51,117	[IF] S1,F14 received without timeout [THEN] exit loop – SEND
	[ELSE] Delay for Establish Communications Timeout [ENDIF] [END_LOOP] – SEND
	<pre>[IF] COMMACK = Accept (0) [THEN] Communications State = COMMUNICATING</pre>
	exit_loop
	[ELSE] Reset timer for delay, and delay for Establish Communications Timeout
	[ENDIF]
	[END_LOOP]

If the case arises where the Equipment and the Host both send the S1,F13 at the same time, please refer to the Communication State model earlier in this manual for details on the response.

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## 4.2. ON-LINE IDENTIFICATION

This capability allows the host to verify the presence and identify of the wire bonder. The wire bonder will respond with the equipment model and software revision included in the reply message.

## 4.2.1. ON-LINE Identification Messages

S1, F1 Are You There Request I

S, H ⇔ E, reply

**Description**: Establishes whether the equipment is ON-LINE. If the equipment responds with an

S1, F0, it means that the equipment is OFF-LINE. If the Host responds with an S1,

F0, the equipment will treat the message as a communication timeout.

**Structure**: Header only

S1, F2 On Line Data (D)

S, H⇔E

**Description**: Indicates that the equipment or the Host is ON-LINE (alive).

**Structure**: L,2

1. <A MDLN>
2. <A SOFTREV>

**Exception**: The host sends a zero-length list to the equipment. (ie. Doesn't send MDLN or

SOFTREV)

Note

MDLN ASCII string with a maximum length of 6 bytes used to hold the machine model

number. For the case of the Eagle Xtreme wire bonder it will always be "Eg XT"

SOFTREV ASCII string with a maximum length of 6 bytes used to hold the version number of

the software running on the machine. This will always return the PC version number. Eg. If the machines PC software version is 09.05.92, then the data stored in this

variable will be "090592"

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S1, F15 Request OFF-LINE (ROFL)

S,  $H \rightarrow E$ , reply

**Description**: Sent by the Host when it wants the equipment to transition to the OFF-LINE state.

**Structure**: Header only

S1, F16 OFF-LINE Acknowledge (OFLA)

 $S, H \leftarrow E$ 

**Description**: Replies to the Host acknowledge or error.

**Structure** : <B OFLACK>

Note

OFLACK Informs whether the equipment went to OFF-LINE state

0 = OFF-LINE Acknowledge

1~63 Reserved

S1, F17 Request ON-LINE (RONL)

S,  $H \rightarrow E$ , reply

**Description**: Sent by the Host when it wants the equipment to transition to the ON-LINE state.

**Structure**: Header only

S1, F18 ON-LINE Acknowledge (ONLA)

 $S, H \leftarrow E$ 

**Description**: Replies to the Host acknowledge or error.

**Structure** : <B ONLACK>

Note

OFLACK Informs whether the equipment went to ON-LINE state

0 = ON-LINE Acknowledge 1 = ON-LINE Not Allowed 2 = Equipment Already ON-LINE

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## 4.2.2. ON-LINE Identification Scenarios

Host Checks Equipment Is ON-LINE

**COMMENT**Are You There Request I

S1,F1 →

On Line Data (D) informing MDLN and SOFTREV

← S1,F2

Host Requests OFF-LINE

COMMENT HOST EQUIPMENT COMMENT

Request OFF-LINE (ROFL) S1,F15  $\rightarrow$ 

[IF] Equipment is OFF-LINE

[THEN] Equipment does not process requests

← S1, F0

[ELSE] Equipment acknowledges and goes OFF-LINE

← S1, F16

"Equipment OFF-LINE" event

← S6, F11

Event Report Acknowledge (ERA)

S6, F12  $\rightarrow$  [END\_IF]

Host Sets ON-LINE

COMMENT HOST EQUIPMENT COMMENT

Request ON-LINE (RONL)

S1, F17 →

[IF] Equipment is not in HOST OFF-LINE control state

[THEN] Equipment denies request (ONLACK = 1)

← S1, F18

[ELSE] Equipment acknowledges request (ONLACK = 0)

← S1, F18

"Control State LOCAL / REMOTE" event

← S6, F11

Event Report Acknowledge (ERA)

S6, F12 →

[END\_IF]

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## 4.3. DATA COLLECTION

Data collection allows the host to monitor wire bonder activity via event reporting and query of selected status variables.

#### STATUS DATA COLLECTION

This capability allows the host to query the wire bonder for selected status information by specifying the corresponding SVIDs. Upon a request from the host, the wire bonder sends the host the value of the selected status variables. The host may also request the description (name and units) of any or all available status variables.

#### **VARIABLE DATA COLLECTION**

This capability allows the host to query for the wire bonder data variables. The host may request a report containing data variables from the equipment by specifying the RPTID. It is assumed that the report has been previously defined, i.e., using the Define Report S2F33 transaction.

#### **EVENT DATA COLLECTION**

This capability allows the wire bonder to notify the host upon the occurrence of an equipment collection event and of any change in the equipment state. The event-based approach to data collection provides automatic notification to the host of equipment activities. A specific event report containing a set of predefined variables will be generated upon the occurrence of any event. Each collection event has unique identifier (CEID). The corresponding event report can consist of a list of report identified by RPTIDs and the variables attached to each report and are identified by SVIDs and/or EVIDs.

The wire bonder also responds to a host request for specific information from a specified event report.

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## 4.3.1. Data Collection Messages

## S1, F3 Selected Equipment Status Request (SSR)

S,  $H \rightarrow E$ , reply

**Description**: Host requests the equipment to report selected values of its status.

**Structure** : L, n  $\{n = \# \text{ of SVIDs following}\}$ 2.  $\langle U2 \text{ SVID}_1 \rangle$ 

(02 3 1 1 2 1

n. <U2 SVID<sub>n</sub>)

**Exception**: A zero length list means the Host is requesting the equipment to report ALL SVIDs.

S1, F4 Selected Equipment Status Data (SSD)

 $M, H \leftarrow E$ 

**Description**: Equipment reports the value of each SVID in the order requested by S1, F3.

**Structure** : L, n  $\{n = \# \text{ of SVIDs following}\}$ 

3.  $\langle V SV_1 \rangle$ 

. n. <V SV<sub>n</sub>)

**Exception** : A zero length returned for SV<sub>i</sub> means that SVID<sub>i</sub> does not exist.

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#### **S1, F11 Status Variable Namelist Request (SVNR)**

S,  $H \rightarrow E$ , reply

**Description**: Host requests the equipment to identify certain status variables.

**Structure** : L, n  $\{n = \# \text{ of SVIDs following}\}$ 4.  $\langle U2 \text{ SVID}_1 \rangle$ 

.

n. <U2 SVID<sub>n</sub>)

**Exception**: A zero length list means the Host is requesting the equipment to report ALL SVIDs.

#### S1, F12 Status Variables Namelist Reply (SVNRR)

 $M, H \leftarrow E$ 

**Description**: Equipment reports the name and units of each SVID in the order requested.

**Structure** : L, n  $\{n = \# \text{ of SVIDs following}\}$ 

1. L, 3

1. <U2 SVID<sub>1</sub>>

2. <A SVNAME<sub>1</sub>>

3. <A UNITS<sub>1</sub>>

2. L, 3

.

. I

n. L, 3

1. <U2 SVID<sub>n</sub>>

2. <A SVNAME<sub>n</sub>>

3. <A UNITS<sub>n</sub>>

**Note** : Empty strings will be returned for SVNAME<sub>i</sub> and UNITS<sub>i</sub> for an SVID<sub>i</sub> that does not exist.

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## S6, F15 Event Report Request (ERR)

S,  $H \rightarrow E$ , reply

**Description**: Host requests the equipment to send a given report group.

**Structure** : <U2 CEID>

## S6, F16 Event Report Data (ERD)

 $M, H \leftarrow E$ 

**Description**: Equipment sends reports linked to a given CEID.

**Structure**: L, 3

1. <U1 DATAID> 
2. <U2 CEID> 
3. L, a {a = # of linked reports} 
1. L, 2 
1. <U2 RPTID<sub>1</sub>> 
2. L, b {b = # of variables in report} 
1. <V  $V_1$ > 
b. <V  $V_b$ > 
1. <U2 RPTID<sub>a</sub>> 
2. L, c {c = # of variables in report} 
1. <V  $V_1$ > 
2. L, c {c = # of variables in report} 
3. <U2 RPTID<sub>a</sub>> 
4. <U2 RPTID<sub>a</sub>> 
5. <U3 RPTID<sub>a</sub>> 
6. <U3 RPTID<sub>a</sub>> 
7. <U3 RPTID<sub>a</sub>> 
8. <U3 RPTID<sub>a</sub>> 
9. <U3 RPTID<sub></sub>

**Exceptions** 

: If there are no reports linked to the event, a 'null' report is assumed. A zero-length list for # of reports means there are no reports linked to the given CEID.

c. <V  $V_c>$ 

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## S6, F19 Individual Report Request (IRR)

S,  $H \rightarrow E$ , reply

**Description**: Host requests a defined report from the equipment

**Structure** : <U2 RPTID>

S6, F20 Individual Report Data (IRD)

**M**, **H** ← **E** 

**Description**: Variable data defined for the given RPTID is sent to the host.

**Structure** : L, n {n = # of variable data items}

5. <V V<sub>1</sub>>

•

n. <V V<sub>n</sub>>

**Exceptions**: A zero length list means RPTID is not defined

S6, F5 Multi-block Data Send Inquire (MBI)

S,  $H \leftarrow E$ , reply

Description : If S6, F11 is multi-block, then the equipment will first request from the Host

permission to proceed to send it.

**Structure**: L, 2

1. <U1 DATAID>

2. <U2 DATALENGTH>

S6, F6 Multi-block Grant (MBG)

 $S, H \rightarrow E$ 

**Description**: Host grant status to equipment to send a multi-block report

**Structure** : <B GRANT6>

Note

GRANT6 Represents the permission to send granted by the Host

0 = Permission granted 1 = Busy, try again 2 = Not interested >2 = Other errors 3~63 Reserved

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## S6, F11 Event Report Send (ERS)

 $M, H \leftarrow E, reply$ 

**Description** 

: Equipment sends a defined, linked, and enabled group of reports to the host upon

the occurrence of an event (CEID).

If the data will require the sending of a multi-block message, this message will be

proceeded by the S6, F5 / S6, F6 Inquire / Grant transaction.

**Structure**: L, 3

```
1. <U1 DATAID>
2. <U2 CEID>
```

3. L, a  $\{a = \# \text{ of linked reports}\}$ 

1. L, 2

1. <U2 RPTID<sub>1</sub>>

2. L, b {b = # of variables in report}

1. <V V<sub>1</sub>>

. b. <V V<sub>b</sub>>

a. L, 2

1. <U2 RPTID<sub>a</sub>>

2. L, c  $\{c = \# \text{ of variables in report}\}$ 

1. <  $V_1>$ 

.

c. <V  $V_c>$ 

Exceptions

: If there are no reports linked to the event, a 'null' report is assumed. A zero-length

list for # of reports means there are no reports linked to the given CEID.

## S6, F12 Event Report Acknowledge (ERA)

 $S, H \rightarrow E$ 

Description

: Host acknowledges whether it was able to accept the report sent.

Structure

: <B ACKC6>

Note

:

ACKC6 I

Indicates whether the Host was able to accept the report.

0 = Accepted

>0 = Error, not accepted

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## 4.3.2. Data Collection Scenarios

Host Requests Equipment Status Report

COMMENT HOST EQUIPMENT COMMENT

Selected Equipment Status Request (SSR) with specified

**SVIDs** 

S1, F3 →
Selected Equipment Status Data (SSD)

← S1 F4

Host Requests Equipment Status Variable Name List

COMMENT HOST EQUIPMENT COMMENT

Status Variable Namelist Request (SVNR) with specified SVIDs S1, F11  $\rightarrow$ 

Status Variable Namelist Reply (SVNRR)

← S1, F12

Host Requests Event Report

COMMENT HOST EQUIPMENT COMMENT

Event Report Request (ERR) S6, F15 →

Event Report Data (ERD)

← S6, F16

Collection Event Occurs on the Equipment

COMMENT HOST EQUIPMENT COMMENT

[IF] Event Report will be Multi-block

[THEN] send Multi-block Data Send Inquire (MBI)

← S6, F5

Multi-block Grant (MBG)

S6, F6 →

[ENDIF]

Event Report Send (ERS)

← S6, F11

Event Report Acknowledge (ERA)

S6, F12 →

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## 4.4. DYNAMIC EVENT REPORT CONFIGURATION

This capability allows the host to increase or decrease the data flow according to need. The wire bonder supports the following event report configuration functionality through the SECS-II interface :

- Host definition / deletion of custom report
- · Host linking / unlinking of defined reports to specified collection event
- Host enabling / disabling the reporting of specified collection events

The wire bonder can be instructed by the host to enable or disable reporting of collection events on an individual or collective basis. Reports may be attached to an event report message. These reports are specifically linked to the desired event and typically contain variable data relating to that event.

The host is able to create reports and link them to events via the SECS-II interface. The basic steps are:

- 1. create reports with S2, F33,
- 2. link the reports to an event with S2, F35, and
- 3. enable event reporting with S2, F37.

Note: All details of the reports generated, linked and events enabled, are stored to non-volatile memory. Thus if the machine is turned off and then on, the setting by the Host will still be valid. This is not the case though if the machine undergoes a COLD START or has a SOFTWARE UPGRADE.

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## 4.4.1. Dynamic Event Report Configuration Messages

## S2, F33 Define Report (DR)

 $M, H \rightarrow E$ , reply

**Description**: All

: Allows the Host to define a group of reports for the equipment.

If the data will require the sending of a multi-block message, this message will be

processed by the S2, F39 / S2, F40 Inquire / Grant transaction.

Structure

```
: L, 2
```

```
1. <U1 DATAID>
```

2. L, a {a = # of reports to define}

1. L, 2

1. <U2 RPTID<sub>1</sub>>

2. L, b  $\{b = \# \text{ of variables in report}\}\$ 

1. <U2 VID<sub>1</sub>>

•

b. <U2 VID<sub>b</sub>>

a. L, 2

1. <U2 RPTID<sub>a</sub>>

2. L, c {c = # of variables in report}

1. <U2 VID<sub>1</sub>>

.

c. <U2  $VID_c>$ 

## Exceptions

: A list of zero length following DATAID deletes all report definitions and associated

links.

A list of zero length following RPTID, deletes report type RPTID. All CEID links to this

RPTID are also deleted.

#### S2, F34 Define Report Acknowledge (DRA)

S, H ← E

Description

: Acknowledge or error. If an error condition is detected, the entire message is

rejected and no change is made to any reports on the equipment.

Structure

: <B DRACK>

Note

:

DRACK

Indicates whether the Equipment was able to generate the reports.

0 = Accepted

1 = Denied. Insufficient space

2 = Denied. Invalid format

3 = Denied. At least one RPTID already defined

4 = Denied. At least one VID does not exist

>4 = Other Error, not accepted

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## S2, F35 Link Event Report (LER)

 $M, H \rightarrow E$ , reply

Description

: Allows the Host to link a group of defined reports to an event (CEID). Once linked

the event is by default DISABLED.

If the data will require the sending of a multi-block message, this message will be

processed by the S2, F39 / S2, F40 Inquire / Grant transaction.

**Structure**: L, 2

```
1. <U1 DATAID>
2. L, a {a = # of events }
1. L, 2
1. <U2 CEID<sub>1</sub>>
2. L, b {b = # of reports linked to CEID<sub>1</sub>}
1. <U2 RPTID<sub>1</sub>>
b. <U2 RPTID<sub>b</sub>>
1. <U2 CEID<sub>a</sub>>
2. L, c {c = # of reports linked to CEID<sub>a</sub>}
1. <U2 RPTID<sub>1</sub>>
2. L, c {c = # of reports linked to CEID<sub>a</sub>}
3. <U2 RPTID<sub>1</sub>>
4. <U2 RPTID<sub>1</sub>>
5. <U2 RPTID<sub>1</sub>>
6. <U2 RPTID<sub>2</sub>>
```

**Exceptions**: A list of zero length following CEID deletes all report links to that event.

#### S2, F36 Link Event Report Acknowledge(LERA)

S,  $H \leftarrow E$ 

Description

: Acknowledge or error. If an error condition is detected, the entire message is

rejected and no change is made to any events on the equipment.

**Structure** : <B LRACK>

Note

LRACK Indicates whether the Equipment was able to link the reports to the events.

0 = Accepted

1 = Denied. Insufficient space2 = Denied. Invalid format

3 = Denied. At least one CEID link already defined
4 = Denied. At least one CEID does not exists
5 = Denied. At least one RPTID does not exists

>5 = Other Error, not accepted

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#### S2, F37 Enable / Disable Event Report (EDER)

 $S, H \rightarrow E$ , reply

**Description**: Allows the Host to enable or disable the reporting for a group of collection events

(CEIDs).

**Structure**: L, 2

1. <BOOLEAN CEED> {enable / disable}

2. L, n {n = # of events} 1. <U2 CEID<sub>1</sub>>

•

n. <U2 CEID<sub>n</sub>>

**Exceptions**: A list of zero length following CEED means enable / disable all CEIDs that exist on

the equipment.

S2, F38 Enable / Disable Event Report Acknowledge (EERA)

 $S, H \leftarrow E$ 

**Description**: Acknowledge or error. If an error condition is detected, the entire message is

rejected and no change is made to any events on the equipment.

**Structure** : <B ERACK>

Note :

ERACK Indicates whether the Equipment was able to link the reports to the events.

0 = Accepted

1 = Denied. At least one CEID does not exists

>1 = Other Error, not accepted

2~63 Reserved

S2, F39 Multi-block Inquire (DMBI)

 $S, H \rightarrow E$ , reply

**Description**: If S2, F33 or S2, F35 are multi-block, they must be proceeded with this transaction.

**Structure**: L, 2

1. <U1 DATAID>

2. <U2 DATALENGTH>

S2, F40 Multi-block Grant (DMBG)

S, H ← E

**Description**: Grant permission to send multi-block message

**Structure** : <B GRANT>

Note

GRANT Permission code

0 = Permission Granted1 = Busy, Try Again2 = No Space Available3 = Duplicate DATAID

>3 = Equipment Specific Error Code

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## 4.4.2. Dynamic Event Report Configuration Scenarios

Host Sets up Collection Event Reporting COMMENT [IF] Define Report is Multi-block [THEN] send Multi-block Inquire (DMBI)	ноѕт	EQUIPMENT	COMMENT
	S2, F39 →	Multi-block Grant (DMBG) ← S2, F40	
[END_IF] Send Define Report (DR) with report definitions	S2, F33 →	Data received and reports generated.  Store details in non-volatile storage.  Send Define Report Acknowledge (DRA) with DR  ← S2, F34	ACK = 0
[IF] Link Event / Report is Multi-block [THEN] send Multi-block Inquire (DMBI)	S2, F39 →	Multi-block Grant (DMBG)	
← S2, F40  [END_IF]  Send Link Event Report (LER) with Event and Report details  S2, F35 →			
	·	Link made between the CEID and the RPTIDs. Store details in non-volatile storage. Send Link Event Report Acknowledge (LERA) wit	:h LRACK = 0
Enable CEID so that reports can be automatically on the Equipment. Send Enable / Disable Event Report (EDER)	generated	← S2, F36	
Seria Eriable / Disable Everit Report (EDER)	S2, F37 →	Send Enable / Disable Event Report Acknowledge ERACK = 0. Store details in non-volatile storage of which CEI enabled.	,
		← S2, F38	

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#### 4.5. ALARM MANAGEMENT

The alarm management capability provides for host notification and management of alarm conditions occurring on the wire bonder, through the Alarm Report Send / Acknowledge transaction (S5F1/S5F2). Each alarm defined in the wire bonder has a unique alarm identifier, ALID. Section 11 lists the ALID, alarm text and category code, for each alarm defined. Besides, the alarm management capability also provides mechanisms for :

- Uploading a list of alarm texts
- Enabling and disabling the notification of specific alarms
- Host query of alarms set and enabled status on the wire bonder

On the Eagle Xtreme the clearing of an alarm occurs when the operator presses a key in response to reading the alarm message on the screen, and not for the actual correction of the alarm.

### 4.5.1. Alarm Management Messages

S5, F1 Alarm Report Send (ARS)

 $S, H \leftarrow E, reply$ 

**Description**: Equipment uses this message to report a change in or presence of an alarm

condition. This message will be sent when the alarm is set, and again when the

alarm is cleared.

**Structure**: L, 3

1. <B ALCD> 2. <U2 ALID> 3. <A[40] ALTX>

Note

ALCD Alarm code byte

bit 8 = 1 means alarm set bit 8 = 0 means alarm cleared

bit 7-1 is alarm category (not used in GEM)

ALID Alarm Identification Code ALTX Alarm text description

#### S5, F2 Alarm Report Acknowledge (ARA)

 $S, H \rightarrow E$ 

**Description**: Acknowledge or error

**Structure** : <B ACKC5>

Note

ACKC5 Informs whether the alarm information was accepted

0 = Accepted

>0 = Error, not accepted

1~63 Reserved

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#### S5, F3 Enable / Disable Alarm Send (EAS)

 $S, H \rightarrow E$ , reply

**Description**: Changes the state of the enable bit in the equipment. The enable bit determines if

the alarm will be sent to the host.

**Structure**: L, 2

1. <B ALED> 2. <U2 ALID>

**Exception** : A zero length item for ALID means all alarms

Note :

**ALID** 

ALED Alarm code byte

bit 8 = 1 means enable alarm bit 8 = 0 means disable alarm bit 7-1 is not used in GEM Alarm Identification Code

#### S5, F4 Enable / Disable Alarm Acknowledge (EAA)

S, H  $\leftarrow$  E

**Description**: Acknowledge or error

**Structure** : <B ACKC5>

Note

ACKC5 Informs whether the alarm information was accepted

0 = Accepted

>0 = Error, not accepted

1~63 Reserved

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S5, F5 List Alarms Request (LAR)

 $S, H \rightarrow E$ , reply

**Description**: Requests the equipment to send alarm information to the host

**Structure** : <U2 ALID<sub>1</sub>, . . . ,U2 ALID<sub>n</sub>>

**Exception**: A zero length item means send all possible alarms regardless of the state of ALED.

Note :

ALID Alarm Identification Code

S5, F6 List Alarm Data (LAD)

 $M, H \leftarrow E$ 

**Description**: Contains the alarm data known to the equipment.

**Structure** : L, m  $\{m = \# \text{ of alarms}\}$ 

ì. L, 3

1. <B ALCD<sub>1</sub>>

2. <U2 ALID<sub>1</sub>> 3. <A[40] ALTX<sub>1</sub>>

2. L, 3

.

. m. L, 3

1. <B ALCD<sub>m</sub>>

 $2. < U2 \quad ALID_m >$ 

3. <A[40] ALTX<sub>m</sub>>

**Exception**: If m=0, no response can be made. A zero length item returned for ALCD<sub>i</sub> or ALTX<sub>i</sub>

means that alarm (ALID) does not exist.

Note :

ALCD Alarm code byte

bit 8 = 1 means alarm set bit 8 = 0 means alarm cleared

bit 7-1 is alarm category (not used in GEM)

ALID Alarm Identification Code ALTX Alarm text description

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#### S5, F7 List Enabled Alarm Request (LEAR)

 $S, H \rightarrow E$ , reply

**Description**: Requests the equipment to send information on the enabled alarms

**Structure**: Header only

### S5, F8 List Enabled Alarm Data (LEAD)

 $M, H \leftarrow E$ 

**Description**: Contains the alarm data known to the equipment, only for those alarms that are

currently enabled.

**Structure** : L, m {m = # of enabled alarms}

1. L, 3

1.  $\langle B ALCD_1 \rangle$ 

2. <U2 ALID<sub>1</sub>>

3. <A[40] ALTX<sub>1</sub>>

2. L, 3 .

. m. L, 3

1. <B ALCD<sub>m</sub>>

2. <U2 ALID<sub>m</sub>>

3. <A[40] ALTX<sub>m</sub>>

Note :

ALCD Alarm code byte

bit 8 = 1 means alarm set bit 8 = 0 means alarm cleared

bit 7-1 is alarm category (not used in GEM)

ALID Alarm Identification Code ALTX Alarm text description

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#### 4.5.2. **Alarm Management Scenarios**

Enable / Disable Alarms

COMMENT HOST **EQUIPMENT** COMMENT

Enable / Disable Alarm Send (EAS) S5, F3 →

Enable / Disable Alarm Acknowledge (EAA)

← S5, F4

Upload Alarm Information

COMMENT **HOST EQUIPMENT COMMENT** 

List Alarms Request (LAR) or List Enabled Alarm Request (LEAR)

S5, F5 or S5, F7  $\rightarrow$ 

List Alarm Data (LAD) or List Alarm Data (LEAD) ← S5, F6 or S5, F8

Send Alarm Report

COMMENT **HOST EQUIPMENT COMMENT** 

Alarm occurrence detected by the equipment.

[IF] Alarm report enabled [THEN] Alarm Report Send (ARS)

← S5, F1

Alarm Report Acknowledge (ARA)

S5, F2 →

[END\_IF] [IF] Alarm event enabled

[THEN] Event Report Send (ERS)

← S6, F11

Event Report Acknowledge (ERA)

S6, F12 →

[END\_IF]

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### 4.6. REMOTE CONTROL

This capability provides the host with a level of control over wire bonder operations. It allows the wire bonder to respond to host initiated commands which control the wire bonder operations while in the REMOTE state. The Remote Command Send (S2F21) is utilized to allow the host to send a remote command, specified by RCMD, to the wire bonder. The successful transaction a remote command will result in an action that generates a collection event upon completion.

### 4.6.1. Remote Control Messages

S2, F21 Remote Command Send (RCS)

 $S, H \rightarrow E$ , reply

**Description**: Causes the equipment to perform some predefined activity.

**Structure** : <U1 RCMD>

Note

RCMD Remote command code

S2, F22 Remote Command Acknowledge (RCA)

 $S, H \leftarrow E$ 

**Description**: Acknowledge or error

**Structure** : <U1 CMDA>

Note :

CMDA Remote command acknowledge code

0 = Completed or done 1 = Command does not exist 2 = Can not perform now

>2 = Other equipment specific error

3~63 Reserved

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#### S2, F41 Host Command Send (HCS)

 $S, H \rightarrow E$ , reply

: Causes the equipment to perform some predefined activity using the data in the Description

associated parameters.

Structure : L, 2

1. <A[20] RCMD>

2. L, n  $\{n = \# \text{ of parameters}\}$ 

1. L, 2

1. <A[20] CPNAME<sub>1</sub>>

2. <V CPVAL<sub>1</sub>>

n. L, 2

1. <A[20] CPNAME<sub>n</sub>>

2. <V CPVAL<sub>n</sub>>

Note

**RCMD** Remote command text

**CPNAME** Parameter text **CPVAL** Parameter data

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#### S2, F42 Host Command Acknowledge (HCA)

 $S, H \leftarrow E$ 

Description

: Acknowledge or error. If the command is not accepted due to one or more invalid parameters (ie. HCACK=3), then a list of the invalid parameters will be returned containing the parameter name and reason for being invalid.

Structure

Note

vote :

HCACK Host Command Parameter Acknowledge Code

0 = Acknowledge, command has been performed

1 = Command does not exists 2 = Can not perform now

3 = At least one parameter is invalid

4 = Acknowledge, command will be performed with completion signaled later by an

event

5 = Rejected, Already in the desired condition

6 = No such object exists

7~63 Reserved

CPNAME Parameter text

CPACK Command Parameter Acknowledge Code

1 = Parameter Name (CPNAME) does not exist

2 = Illegal Value specified for CPVAL3 = Illegal Format specified for CPVAL>3 = Other equipment specific error

3~63 Reserved

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#### 4.6.2. Remote Control Scenarios

Remote Command Send

COMMENT HOST EQUIPMENT COMMENT

Remote Command Send (RCS)  ${\rm S2,\,F21} \rightarrow$ 

Remote Command Acknowledge (RCA)

← S2, F22

Host Command Send

COMMENT HOST EQUIPMENT COMMENT

Host Command Send (HCS)  $\mbox{S2, F41} \rightarrow \mbox{}$ 

Host Command Acknowledge (HCA)

← S2, F42

[IF] Command Accepted (HCACK = 0 or 4) [THEN] Event Report Send (ERS)any State Change

← S6, F11

Event Report Acknowledge (ERA)

S6, F12 →

[END\_IF]

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### 4.7. EQUIPMENT CONSTANT

This capability provides a method for the host to read and to change the value of selected equipment constants on the wire bonder. The following operations are supported :

- Allows the host to change the value of one or more equipment constant
- Allows the host to determine the current value of equipment constants
- Allows the host to retrieve basic information about the equipment constants available at the equipment

### 4.7.1. Equipment Constant Messages

#### S2, F13 Equipment Constant Request (ECR)

 $S, H \rightarrow E$ , reply

**Description**: Host requests the equipment send data on the equipment constant variables.

**Structure** : L, n  $\{n = \# \text{ of ECIDs}\}\$  6. <U2 ECID<sub>1</sub>>

. n. <U2 ECID<sub>n</sub>>

**Exception**: A zero length list means report all ECV's according to the predefined order.

#### S2, F14 Equipment Constant Data (ECD)

 $M, H \leftarrow E$ 

**Description**: Replies all the EC data in the order requested.

**Exception**: A zero length ECV<sub>i</sub> means that ECID<sub>i</sub> does not exist.

Note :

ECV<sub>i</sub> Data for the ECID in the format defined for that particular variable.

If the Host requests a large (complete) list, the equipment may take a few seconds to reply as the data can be quite large.

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#### S2, F15 New Equipment Constant Send (ECS)

 $S, H \rightarrow E$ , reply

Description : Host requests a change to one or more equipment constant variables.

Structure

: L, n  $\{n = \# \text{ of ECIDs}\}$ 1. L, 2 1. <U2 ECID<sub>1</sub>> 2. <V ECV<sub>1</sub>> 2. L, 2 n. L, 2 1. <U2 ECID<sub>n</sub>>

Note

Must be in the same data format as specified for the particular ECID. ECV

2. <V ECV<sub>n</sub>>

#### S2, F16 Equipment Constant Acknowledge (ECA)

 $S, H \leftarrow E$ 

: Acknowledge or error. If EAC contains a non-zero error code, then it means that the Description

equipment has NOT changed any of the ECIDs specified in the S2, F15 request.

Structure : <B EAC>

Note

EAC

Indicates whether the equipment constants were updated.

0 = Acknowledge

1 = Denied. At least one constant does not exists

2 = Denied. Busy

3 = Denied. At least one constant out of range

>3 = Other equipment specific error

4~63 Reserved

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#### S2, F29 Equipment Constant Namelist Request (ECNR)

 $S, H \rightarrow E$ , reply

**Description**: Host requests for the equipment to send basic information about what equipment

constants are available.

**Structure** : L, n {n = # of ECIDs}

8. <U2 ECID<sub>1</sub>>

•

n. <U2 ECID<sub>n</sub>>

**Exception**: A zero length list means send information for all ECIDs.

#### S2, F30 Equipment Constant Namelist (ECN)

 $M, H \leftarrow E$ 

**Description**: Data of Equipment Constants in the order requested.

**Structure** : L, n {n = # of equipment constants}

1. L, 6

1. <U2 ECID<sub>1</sub>>

2. <A ECNAME<sub>1</sub>>

3. <V ECMIN<sub>1</sub>>

4. <V ECMAX<sub>1</sub>>

5. <V ECDEF<sub>1</sub>>

6. <A UNITS<sub>1</sub>>

•

n. L, 6

1. <U2 ECID<sub>n</sub>>

2. <A ECNAME<sub>n</sub>>

3. <V ECMIN<sub>n</sub>>

4. <V ECMAX<sub>n</sub>>

5. <V ECDEF<sub>n</sub>>

6. <A UNITS<sub>n</sub>>

Note

ECNAME Text description of the equipment constant

ECMIN, ECMAX,

ECDEF Min, Max, Default value of the constant in the required type. These are not valid for

textual type of equipment constants.

UNITS Text description of the data units.

If the Host requests a large (complete) list, the equipment may take a few seconds to reply as the data can be quite large.

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### 4.7.2. Equipment Constant Scenarios

Host Request a name list of Equipment Constants

COMMENT HOST EQUIPMENT COMMENT

Equipment Constant Namelist Request (ECNR)

S2, F29 →

Equipment Constant Namelist (ECN)

← S2, F30

Host Changes the Value of some Equipment Constants

COMMENT HOST EQUIPMENT COMMENT

New Equipment Constant Send (ECS)

S2, F15 →

Equipment Constant Acknowledge (ECA)

← S2, F16 (EAC = 0)

Host Requests for the Current Value of some Equipment Constants

COMMENT HOST EQUIPMENT COMMENT

Equipment Constant Request (ECR)

S2, F13 →

Equipment Constant Data (ECD)

← S2, F14

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#### 4.8. PROCESS PROGRAM MANAGEMENT

This capability allows the management and transfer of process programs between the host and the wire bonder. However, the wire bonder is able to load and execute only one process program at a time. No modification or uploading / downloading of any process program may occur while that program is being executed. The Eagle Xtreme Gold Wire Bonder supports only unformatted program operations. ASM Wire bonders support both host initiated as well as equipment initiated uploading and downloading. Please avoid uploading and downloading of bond program during the bonding, because during that time equipment is busy and so in host side the process may fail due to reply timeout error.

Note: **Uploading** refers data flow direction is from equipment to Host **Downloading** refers data flow direction is from host to equipment

#### 4.8.1. Process Program Management Messages

These messages are used to manage and transfer process program. Commonly known as Recipe Upload / Download, but also includes directory listing and file deletion.

#### S7, F1 Process Program Load Inquire (PPI)

S,  $H \Leftrightarrow E$ , reply

**Description**: This message is used to initiate the transfer of a process program or to select from

stored programs. The message may be used to initiate the transfer of an unformatted

process program ( S7,F3 / S7,F4 ).

**Structure**: L, 2

1. <A PPID>

2. <U4 LENGTH>

Note

PPID ASCII string with a maximum length of 24 bytes and includes and extension of ".WB"

(optional). Valid characters are A-Z, 0-9 and a single period.

Eq. "SIOC389238.WB"

LENGTH Indicates the size of the PPBODY that will be sent with S1,F3 in bytes. This is

required so that the machine can reserve sufficient memory to receive the incoming

file.

#### S7, F2 Process Program Load Grant (PPG)

S, H ⇔ E

**Description**: This message gives permission for the process program to be loaded.

**Structure** : <B PPGNT>

**Note** 

PPGNT 1 byte value representing the permission status as follows

0 = OK (allowed to download the file PPBODY with S7,F3)

1 = File already exists

2 = Insufficient space available to accept the file (memory)

3 = Invalid PPID 4= Busy, try later 5 = Will not accept > 5 Other error 6~63 Reserved

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#### S7, F3 Process Program Send (PPS)

M, H ⇔ E, reply

**Description**: The program is sent. If S7,F3 is multi-block, it must be preceded by the S7,F1 /

S7,F2 Inquire / Grant transaction.

**Structure**: L, 2

1. <A PPID>
2. <B PPBODY>

Note

PPID ASCII string with a maximum length of 24 bytes and includes and extension

(optional) of ".WB". Valid characters are A-Z, 0-9 and a single period.

Eg. "SIOC389238.WB"

This must match the PPID name sent in any preceding S7,F1 / S7,F3 transaction.

PPBODY Binary data of the entire WB archive. The length must be the same size as LENGTH

specified in any preceding S7,F1 / S7,F2 transaction.

#### S7, F4 Process Program Acknowledge (PPA)

S, H ⇔ E

**Description**: Acknowledge or error.

**Structure** : <B ACKC7>

Note

ACKC7 1 byte value representing the acknowledge of the file as follows

0 = Accepted without error 1 = Permission not granted

2 = Length or Data Corruption error

4 = PPID not found 6 = Equipment busy 7~63 Reserved

Warning

: If the S7,F3 message is multi-block and not preceded with the S7,F1 / S7,F2 transaction, then the equipment will respond with S9,F11 Data Too Long (DLN) followed by many S9,F7 Illegal Data (IDN) for each subsequent block. This is due to the equipment not having a sufficient receive buffer to accept a large primary message. After the S9,F11 is sent, all subsequent blocks will be decoded, but because it is a pure data block the format is invalid and thus the S9,F7 is sent.

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**S7, F5** Process Program Request (PPR)

S, H ⇔ E, reply

**Description**: This message is used to request the transfer of a process program.

**Structure** : <A PPID>

Note

PPID ASCII string with a maximum length of 24 bytes and includes and extension

(optional) of ".WB".(optional). Valid characters are A-Z, 0-9 and a single period.

Eg. "SIOC389238.WB"

S7, F6 Process Program Data (PPD)

M, H ⇔ E

**Description**: This message is used to transfer a process program.

**Structure**: L, 2

1. <A PPID>
2. <B PPBODY>

**Exception**: A zero-length list means request denied.

A zero length list in S7F6 will be sent under the following conditions:

1. File doesn't exist

2. File exists but is empty

3. Cannot allocate a memory buffer to hold the file contents

4. Unable to read the file contents

5. Callback to application function does not return GEMOK status.

Note :

PPID ASCII string with a maximum length of 24 bytes and includes and extension

(optional) of ".WB". Valid characters are A-Z, 0-9 and a single period.

Eg. "SIOC389238.WB"

This must match the PPID name sent in the preceding S7,F5.

PPBODY Binary data of the entire WB archive.

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#### S7, F17 Delete Process Program Send (DPS)

S,  $H \rightarrow E$ , reply

**Description**: This message is used by the host to request the equipment to delete process

programs from equipment storage.

**Structure**: L, n {n = Number of process programs to be deleted}

9. <A PPID<sub>1</sub>>

.

n. <A PPID<sub>n</sub>>

**Exception** : If n=0, then delete all Process Programs

Note :

PPID ASCII string with a maximum length of 24 bytes and includes and extension

(optional) of ".WB". Valid characters are A-Z, 0-9 and a single period.

Eg. "SIOC389238.WB"

S7, F18 Delete Process Program Acknowledge (DPA)

 $S, H \leftarrow E$ 

**Description**: Acknowledge or error

**Structure** : <B ACKC7>

**Note** ACKC7

1 byte binary indicating the status of the delete operation

0 = Accepted

1 = Permission not granted

2 = Length error 4 = PPID not found 6 = Equipment busy 7~63 Reserved

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S7, F19 Current EPPD Request (RER)

S,  $H \rightarrow E$ , reply

Description

: This message is used to request the transmission of the current equipment process program directory (EPPD). This is a list of all the PPIDs of the process programs

stored in the equipment.

**Structure**: Header only

S7, F20 Current EPPD Data (RED)

 $M, H \leftarrow E$ 

**Description**: This message is used to transmit the current EPPD.

**Structure** : L, n  $\{n = number of process programs in the directory\}$ 

10. <A PPID<sub>1</sub>>

.

n <A PPID<sub>n</sub>>

Note

PPID ASCII string with a maximum length of 24 bytes and includes and extension

(optional) of ".WB". Valid characters are A-Z, 0-9 and a single period.

Eg. "SIOC389238.WB"

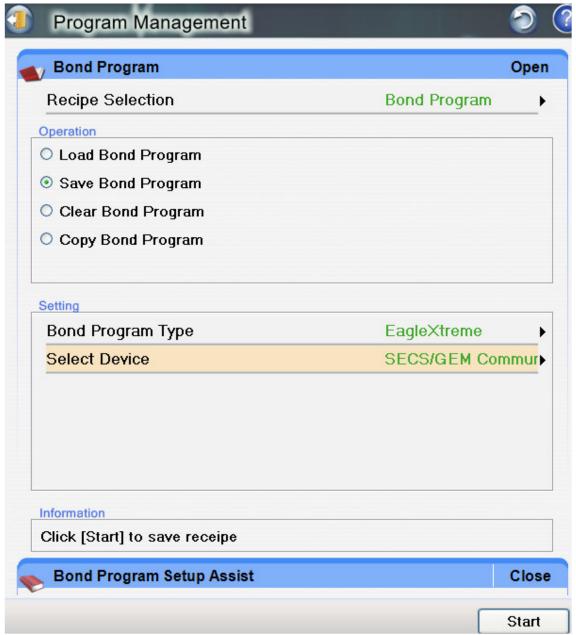
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### 4.8.2. Process Program Management

1. Equipment Sends a process program to Host



On the Equipment, this function will be called when the operator selects menu items

- 1. Save Bond Program
- 2. Copy Bond Program

from the Program management page.

The Select Device should be SECS/GEM Communication

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If the operator selects **Save Bond Program to Host** then the following steps will be performed:

- 2. The operator will be prompted to enter a name under which to save the Recipe currently stored in memory.
- 3. The Recipe will then be saved from memory to a temporary directory of the hard disk.
- 4. The relevant files will be compressed into a WB archive.
- 5. The compressed archive will be sent to the Host (S7,F1 / S7,F2 followed by S7,F3 / S7,F4) with an on screen message informing the user of the upload operation.
- 6. The files stored on temporary directory of the hard disk will be deleted.

If the operator selects **Copy Prog to Host**, then these steps will occur:

- 1. The operator will be presented with a list of all the available files stored on the hard disk. The operator will select which file should be sent to the Host.
- 2. The relevant files will be compressed into a WB archive and stored in a temporary directory of hard disk .
- 3. The compressed archive will be sent to the Host (S7,F1 / S7,F2 followed by S7,F3 / S7,F4) with an on screen message informing the user of the upload operation.
- 4. The compressed archive file stored on temporary directory of the hard disk will be deleted.

#### Note:

1)

If <u>Transfer PR Images</u> (from SECS/GEM Options) is set to ENABLE, then the PR pattern files will also be stored in the archive. If set to DISABLE, only the bonding co-ordinates and parameters will be stored. This can significantly reduce the size of the file transferred and thus reduce the transfer time. The side effect is that during the loading of the Recipe to memory, there will be a message "Unable to load templates" and the operator will need to manually reload the PR.

2)

- If **Download Recipe to** (from SECS/GEM Options) is set as
- a) **HDD only**: After downloading, the recipe will be stored in equipment's hard disk only.
- b) **RAM only**: After downloading, the recipe will be stored into equipment's RAM (Random Access Memory) only. In this case recipe after downloading will be automatically loaded into equipment's RAM. No copy will be stored in Hard disk.
- c) **HDD&RAM**: After downloading , the recipe will be first stored into equipment's hard disk and then it automatically loaded into equipment's RAM

3)

If **Host Recipe Extension** ( from SECS/GEM Options) is set to ENABLE , then the recipe name will be saved in host computer hard disk with extension ".WB". Eg: TSSOP24T.WB
If this option set to DISABLED then the recipe name will be saved in host computer hard disk without extension ".WB" eg: TSSOP24T

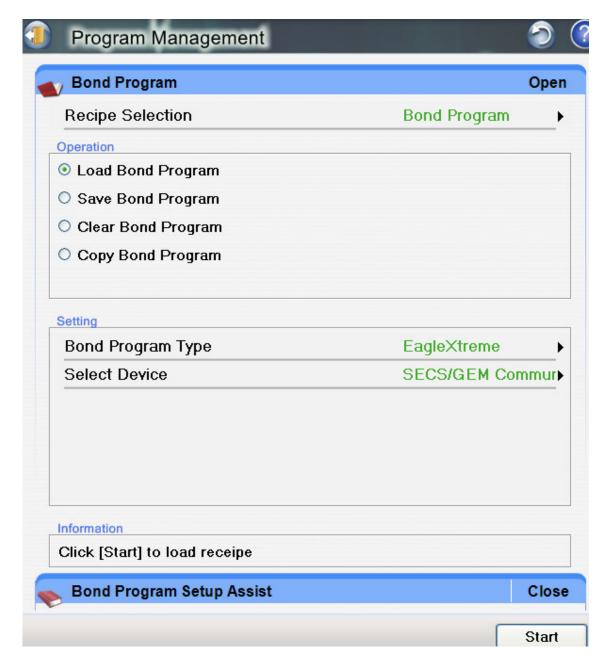
COMMENT  Process Program Load Crant (PDC)	HOST	<b>EQUIPMENT</b> Process Program Load Inquire (PPI) ← S7, F1	COMMENT
Process Program Load Grant (PPG)	(PPGNT = 0) S7, F2 $\rightarrow$	Process Program Send (PPS)  ← S7, F3	
Process Program Acknowledge (PPA)	S7, F4 →		

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### 1. Equipment requests Host send Process Program



On the Equipment, this function will be called when the operator selects the menu item 1. Load Bond Program

from the Program Management page.

The select Device should be SECS/GEM Communication

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If the operator selects **Load Bond Program from Host**, then the following steps will be performed:

- 1. The operator will be prompted to enter the name of a Recipe currently stored on the Host computer.
- 2. If the file selected is already available on the equipment's hard disk, then the operator will be asked to confirm whether to overwrite the existing file. If the operator answers negative the operation ceases at this point.
- 3. S7,F5 will be sent to the Host with the name encoded as PPID
- 4. If the file is available on the Host, then the replied S7,F6 will contain the data for the compressed file archive.
- 5. If the file is not available on the Host, then the replied S7,F6 will only contain an empty list. The equipment will display a message on the screen indicating that the load operation failed.
- 6. Once the file archive has been received, it will be placed on the hard disk in the appropriate format. If the option is "RAM only" then no copy will be stored in the hard disk
- 7. After successful (no corruption detected) downloading and storage, the operator will be asked to confirm whether to load this file into memory.
- 8. If the operator answers affirmative, then the Recipe will be loaded into memory and become the current Process Program in use.

Once the file has been downloaded and stored to the hard disk, it will be available at any time to be manually loaded by the operator using the normal Load from Hard Disk menu item.

COMMENT

HOST

Process Program Request (PPR)

← S7, F5

Frocess Program Data (PPD)

S7, F6 →

EQUIPMENT

Process Program Request (PPR)

← S7, F5

### 2. Host requests Equipment send Process Program

If the Host requests the file with S7,F5 and the file exists on the hard disk, then the following occurs:

- 1. Compress the files into a WB archive.
- 2. If the PPID doesn't exist, then an empty list will be sent to the Host via S7,F6.
- 3. If the PPID does exists, then the WB data will be sent to the Host via S7,F6.

COMMENT	HOST	EQUIPMENT	COMMENT
Process Program Request (PPR)	S7, F5 →	Process Program Data (PPD) ← S7, F6	
Host Sends Process Program to Equipmed COMMENT Process Program Load Inquire (PPI)	nent HOST	EQUIPMENT	COMMENT
Process Progra	S7, F1 →	Process Program Load Grant (PPG)  ← S7, F2 (PPGNT = 0)	
Process Progra	S7, F3 →	Process Program Acknowledge (PPA) ← S7, F4	

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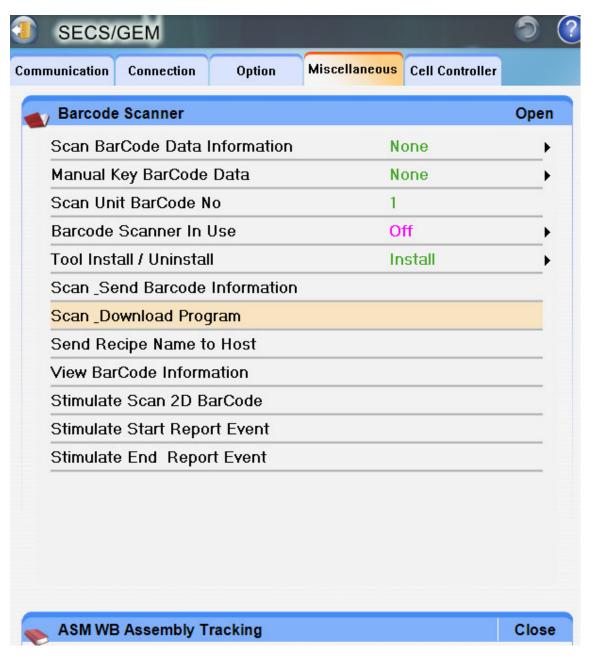


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# 3. Equipment download program through Barcode scanner

This allows the operator to download the bond program by scanning the Barcode

The menu is located under "SECS/GEM Communications"



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On the Equipment, this function will be called when the operator selects the menu item 1. Scan & Download Program from the Barcode Scanner page.

If the operator selects **Scan &Download Program**, then the following steps will be performed:

- 2) The operator will be prompted to Scan the Barcode with a Barcode scanner
- 3) After successful scan the Barcode string (the program name) will be displayed on the bonder monitor and user can press "Enter" button to send the program name to host or press "STOP" button to quit out from the message and discard the scan result.
- 4) Once operator press ENTER button after barcode scan, S7,F5 will be sent to the Host with the program name encoded as PPID
- 5) If the file is available on the Host, then the replied S7,F6 will contain the data for the compressed file archive.
- 6) If the file is not available on the Host, then the replied S7,F6 will only contain an empty list. The equipment will display a message on the screen indicating that the load operation failed.
- 7) Once the file archive has been received, it will be placed on the hard disk in the appropriate format. If the option is "RAM only" then no copy will be stored in the hard disk
- 8) After successful (no corruption detected) downloading and storage, the operator will be asked to confirm whether to load this program into memory.
- 9) If the operator answers affirmative, then the Recipe will be loaded into memory and become the current Process Program in use.

Once the file has been downloaded and stored to the hard disk, it will be available at any time to be manually load by the operator using the normal Load from Hard Disk menu item.

COMMENT

HOST

EQUIPMENT

Process Program Request (PPR)

← S7, F5

Process Program Data (PPD)

S7, F6 →

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### 1. Host requests Process Program Deletion

**Purpose**: Allows the Host to selectively delete Recipe files from the Equipment's hard disk (main directory only as the Host cannot access sub-directories). One reason to do this could be to ensure the operator cannot load the wrong Recipe from the hard disk.

Eg.

The host deletes all the Recipes on the hard disk before downloading the Recipe file to use for the next lot. It is then impossible for the operator to load the wrong file, because the latest download will be the only file available.

Eq.

Recipe files that are obsolete can be deleted from all the machines directories for better housekeeping practices.

COMMENT HOST EQUIPMENT COMMENT

Delete Process Program Send (DPS)

S7, F17 →

Delete Process Program Acknowledge (DPA)
Delete files from hard disk
← S7, F18

### 2. Host Request Process Program Directory Contents

**Purpose**: Allows the Host to find out what are the currently available Recipe files stored on the equipment's hard disk (main directory only as the Host cannot access sub-directories).

One reason to do this could be to check whether a Recipe (that is scheduled to be downloaded) is already on the hard disk of the machine, and thus doesn't need to be sent again.

Another use may be to double check that the file sent from the host has been received correctly and stored in the hard disk.

It could also be used to double check that the file selected for deletion has really been removed from the equipment's hard disk.

COMMENT HOST EQUIPMENT COMMENT

Current EPPD Request (RER)

S7, F19 →

Current EPPD Data (RED) ← S7, F20

#### 4.9. ERROR MESSAGE

Error messages provide the host with information describing the reason for a particular message or communication fault detected by the wire bonder. The wire bonder will inform the host that it cannot process a message due to an incorrect :

- device ID
- message stream type
- message function
- message format

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- data format
- message has more data than it can handle
- wire bonder transaction timer expires

The wire bonder treats the above conditions as application level errors and shall not take any further action on any message in error. Error messages are invoked whenever the wire bonder detects communication or message faults. Reader may refer to ASMGEM Protocol Reference for more detail.

### 4.9.1. Error Messages

#### S9, F1 Unrecognized Device ID (UDN)

 $S, H \leftarrow E$ 

**Description**: The Device ID in the message block header did not correspond to the setting of the

Device ID in the equipment.

**Structure** : <B MHEAD>

Note

MHEAD Block header of the message that generated the error.

#### S9, F3 Unrecognized Stream Type (USN)

S, H ← E

**Description**: The equipment does not recognize the stream type specified in the message.

**Structure** : <B MHEAD>

Note

MHEAD Block header of the message that generated the error.

#### S9, F5 Unrecognized Function Type (UFN)

 $S, H \leftarrow E$ 

**Description**: The equipment does not recognize the function type specified in the message.

**Structure** : <B MHEAD>

Note

MHEAD Block header of the message that generated the error.

#### S9, F7 Illegal Data (IDN)

S, H ← E

**Description**: The stream and function information in the message was recognized, but a data

format for an item was unexpected or unrecognized.

Structure : <B MHEAD>

Note

MHEAD Block header of the message that generated the error.

#### S9, F9 Transaction Timer Timeout (TTN)

 $S, H \leftarrow E$ 

**Description**: Informs the host that a reply message was not received within the T3 (Transaction

Timeout) limit.

**Structure** : <B SHEAD>

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Note :

SHEAD Block header of the primary message sent for which a reply was expected.

S9, F11 Data Too Long (DLN)

 $S, H \leftarrow E$ 

**Description**: Indicates that the equipment cannot handle a message because it contains more

data than the receive buffer can manage.

**Structure** : <B MHEAD>

Note :

MHEAD Block header of the message that generated the error.

S9, F13 Conversation Timeout (CTN)

 $S, H \leftarrow E$ 

**Description**: A message was expected (for which resources have been allocated), but never

received within the conversation timeout limit. The resources have been released

when this message was sent.

Structure : L, 2

1. <A[6] MEXP> 2. <V EDID>

Note

MEXP Expected message that was not received in the form "SxxFyy"

EDID Expected data identification. Currently conversation timeout only occurs when

waiting for an S7, F3. Under this condition, EDID is set to the expected PPID.

ie. <A EDID> = <A PPID>

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### 4.9.2. Error Message Scenarios

Message Content Faults
COMMENT

COMMENT
Host sends a message

HOST EQUIPMENT

COMMENT

Sx, Fy  $\rightarrow$ 

[IF] Message Device ID doesn't match equip Device ID [THEN] Unrecognized Device ID (UDN) ← S9, F1 (Header from Sx, Fy)

[ELSE\_IF] Stream type in message is not recognized [THEN] Unrecognized Stream Type (USN)
← S9, F3 (Header from Sx, Fy)

[ELSE\_IF] Function type in message is not recognized [THEN] Unrecognized Function Type (UFN) ← S9, F5 (Header from Sx, Fy)

[ELSE\_IF] Data content of message or item invalid [THEN] Illegal Data (IDN)
← S9, F5 (Header from Sx, Fy)

[ELSE\_IF] Sx, Fy is larger than the receive buffer [THEN] Data Too Long (DLN)
← S9, F5 (Header from Sx, Fy)
[END\_IF]

Message Transaction Timeout Fault COMMENT

HOST EQUIPMENT

**COMMENT** 

Equipment sends a message expecting a reply ← Sx. Fv

 $\leftarrow$  Sx, Fy

No reply message received causing the transaction timer to expire

Transaction Timer Timeout (TTN) ← S9, F9 (Header from Sx, Fy)

Conversation Timeout Fault

COMMENT

HOST

**EQUIPMENT** 

**COMMENT** 

Host sends a message warning that a message will follow that requires special set up of equipment resources (memory)  $\,$ 

Sx, Fy  $\rightarrow$ 

Equipment allocates resources, starts conversation timer, and replies. Equipment stores what is the next expected transaction.

← Sx, Fy+1

..

No new message received causing the conversation timer to expire OR message received that was not part of the expected transaction

Resources are released

Conversation Timer Timeout (CTN)
← S9, F13 (MEXP = Expected "SxxFyy")

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#### 4.10. CLOCK

The clock capability enables host management of time-related activities and occurrences associated with the wire bonder. The purpose of the clock capability is to enable time stamping of collection event and alarm reports. Time stamping is useful for resolving relative order of event/alarm occurrences and scheduling of wire bonder activities by the host.

The ability for the host to instruct the wire bonder to set an internal clock to a specified time value is needed for effective time management and synchronization between host and equipment.

The clock supports 2 different modes of operations.

- <A TIME> can be either:
  - 11. Non-Y2k Compliant 12 digit format "YYMMDDhhmmss"
  - 12. Y2k Compliant 16 digit format "YYYYMMDDhhmmsscc"

#### Where:

```
YY
       = Year
                      00 to 99
YYYY
       = Year2k
                      0000 to 9999
                      01 to 12
MM
       = Month
DD
       = Day
                      01 to 31
                      00 to 23
hh
       = Hour
                      00 to 59
       = Minute
mm
                      00 to 59
SS
       = Second
       = Centi-second 00 to 99
CC
```

The mode of operation is selected via the Equipment Constant TIMEFORMAT.

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#### 4.10.1. **Clock Messages**

S2, F17 Date and Time Request (DTR)

S, H ⇔ E

: Allows the equipment or the Host to request the current date and time settings on Description

the other party.

Structure : Header only.

S2, F18 Date and Time Data (DTD)

S, H ⇔ E

**Description**: Current date and time data

Structure : <A TIME>

Note

TIME 12 / 16 byte data of the date and time.

S2, F31 Date and Time Set Request (DTS)

 $S, H \rightarrow E$ 

Description : Allows the Host to set the date and time of the equipment.

Structure : <A TIME>

S2, F32 Date and Time Set Acknowledge (DTA)

 $S, H \leftarrow E$ 

: Acknowledge that the date and time has been set Description

Structure : <B TIACK>

Note

TIACK Time Acknowledge Code

0 = OK

1 = Error, not done 2~63 Reserved

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#### 4.10.2. **Clock Scenarios**

Get Current Equipment Date / Time

COMMENT HOST EQUIPMENT COMMENT

Host requests

Date and Time Request (DTR) S2, F17 →

Data and Time Data (DTD)

← S2, F18

Equipment Requests

Date and Time Request (DTR)

← S2, F17

Date and Time Data (DTD)

S2, F18 →

Set Equipment Date / Time

COMMENT **EQUIPMENT** HOST COMMENT Date and Time Set Request (DTS)

S2, F31 →

Date and Time Set Acknowledge (DTA)

← S2, F32

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### 4.11. TERMINAL SERVICES

The Eagle Xtreme supports a simple text display method that allows the Host to display an English text message to the operator. This could be used to inform the operator of why the equipment has been stopped by the host, or to give information on a QC result.

### 4.11.1. Terminal Service Messages

S10, F3 Terminal Display, Single (VTN)

S,  $H \rightarrow E$ , reply

**Description**: English message to be displayed

**Structure**: L, 2

1. <B TID> 2. <A TEXT>

Note

TID Terminal number should always be set to 0= Single or Main terminal

TEXT English display text (ASCII) less than 80 chars

S10, F4 Terminal Display, Single Acknowledge (VTA)

S,  $H \leftarrow E$ 

**Description**: Acknowledge or error

**Structure** : <B ACKC10>

Note :

ACKC10 Acknowledge Code

0 = Accepted for display

1 = Message will not be displayed

2 = Terminal not available

3~63 Reserved

#### 4.11.2. Terminal Service Scenarios

Host Displays an English Message on the Screen

COMMENT HOST EQUIPMENT COMMENT
Terminal Display, Single (VTN)

S10, F3 →

Message displayed on the screen Terminal Display, Single Acknowledge (VTA)  $\leftarrow$  S10, F4

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### 4.12. DIAGNOSTIC TESTS

To check that the hardware and software link is operational, a Loop back Diagnostics test can be performed periodically. This will send a block of data between the Host / Equipment and the other party will echo the data back exactly. If the received data does not match the sent data, then there is something wrong with the hardware and action needs to be taken to diagnose why.

#### 4.12.1. Diagnostic Messages

S2, F25 Loop back Diagnostic Request (LDR)

S, H ⇔ E, reply

**Description**: Sends a binary string that should be echoed to test the protocol and communication

circuits.

**Structure** : <B ABS>

Note :

ABS Any binary data (size < 200) that should be echoed back

S2, F26 Loop back Diagnostic Data (LDD)

S, H ⇔ E

**Description**: The echoed binary string

**Structure** : <B ABS>

Note

ABS Will be exactly the same as the sent data if the hardware / software link is working

correctly.

4.12.2. Diagnostic Scenarios

Loop back Test the Communication Link

COMMENT HOST EQUIPMENT COMMENT

Host Tests

Loop back Diagnostic Request (LDR)

S2, F25 →

Loop back Diagnostic Data (LDD)

← S2, F26

Equipment Tests

Loop back Diagnostic Request (LDR)

← S2, F25

Loop back Diagnostic Data (LDD)

S2, F26 →

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### **5. SECS MESSAGE SUBSET**

The following sections contain a summary of the SECS-II message subsets that are implemented on the Eagle Xtreme wire bonder.

### 5.1. Host Initiated Messages

The following table lists a set of host initiated messages and equipment responses.

	HOST INITIATES			WIRE BONDER RESPONSE	
S/F	NAME	MN	S/F	NAME	MN
S1F1	Are You There Request	R	S1F2	On Line Data	D
S1F3	Selected Equipment Status Request	SSR	S1F4	Selected Equipment Status Data	SSD
S1F11	Status Variable Namelist Request	SVNR	S1F12	Status Variable Namelist Reply	SVNRR
S1F13	Establish Communications Request	CR	S1F14	Establish Communications Request Acknowledge	CRA
S1F15	Request OFF-LINE	ROFL	S1F16	OFF-LINE Acknowledge	OFLA
S1F17	Request ON-LINE	RONL	S1F18	ON-LINE Acknowledge	ONLA
S2F13	Equipment Constant Request	ECR	S2F14	Equipment Constant Data	ECD
S2F15	New Equipment Constant Send	ECS	S2F16	New Equipment Constant Acknowledge	ECA
S2F17	Date and Time Request	DTR	S2F18	Date and Time Data	DTD
S2F21	Remote Command Send	RCS	S2F22	Remote Command Acknowledge	RCA
S2F25	Loop back Diagnostic Request	LDR	S2F26	Loop back Diagnostic Data	LDD
S2F29	Equipment Constant Namelist Request	ECNR	S2F30	Equipment Constant Namelist	ECN
S2F31	Date and Time Set Request	DTS	S2F32	Date and Time Set Acknowledge	DTA
S2F33	Define Report	DR	S2F34	Define Report Acknowledge	DRA
S2F35	Link Event Report	LER	S2F36	Link Event Report Acknowledge	LERA
S2F37	Enable/Disable Event Report	EDER	S2F38	Enable/Disable Event Report Acknowledge	EDEA
S2F39	Multi-Block Inquire	MBI	S2F40	Multi-Block Grant	MBG
S2F41	Host Command Send	HCS	S2F42	Host Command Acknowledge	HCA
S5F3	Enable/Disable Alarm Send	EAS	S5F4	Enable/Disable Alarm Acknowledge	EAA
S5F5	List Alarms Request	LAR	S5F6	List Alarm Data	LAD
S5F7	List Enabled Alarm Request	LEAR	S5F8	List Enabled Alarm Data	LEAD
S6F15	Event Report Request	ERR	S6F16	Event Report Data	ERD
S6F19	Individual Report Request	IRR	S6F20	Individual Report Data	IRD
S7F1	Process Program Load Inquire	PPI	S7F2	Process Program Load Grant	PPG
S7F3	Process Program Send	PPS	S7F4	Process Program Acknowledge	PPA
S7F5	Process Program Request	PPR	S7F6	Process Program Data	PPD
S7F17	Delete Process Program Send	DPS	S7F18	Delete Process Program Acknowledge	DPA
S7F19	Current EPPD Request	RER	S7F20	Current EPPD Data	RED
S10F3	Terminal Display, Single	VTN	S10F4	Terminal Display, Single Acknowledge	VTA

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### 5.2. Equipment Initiated Messages

The following table lists the wire bonder initiated messages and corresponding expected host response.

	WIRE BONDER INITIATES			HOST RESPONSE		
S/F	NAME	MN	S/F	NAME	MN	
S1F1	Are You There Request	R	S1F2	On Line Data	D	
S1F13	Establish Communications Request	CR	S1F14	Establish Communications Request Acknowledge	CRA	
S2F17	Date and Time Request	DTR	S2F18	Date and Time Data	DTD	
S5F1	Alarm report Send	ARS	S5F2	Alarm Report Acknowledge	ARA	
S6F5	Multi-block Data Send Inquire	MBI	S6F6	Multi-block Grant	MBG	
S6F11	Event Report Send	ERS	S6F12	Event Report Acknowledge	ERA	
S7F1	Process Program Load Inquire	PPI	S7F2	Process Program Load Grant	PPG	
S7F3	Process Program Send	PPS	S7F4	Process Program Acknowledge	PPA	
S7F5	Process Program Request	PPR	S7F6	Process Program Data	PPD	
S9F1	Unrecognized Device ID	UDN				
S9F3	Unrecognized Stream Type	USN				
S9F5	Unrecognized Function Type	UFN				
S9F7	Illegal Data	IDN				
S9F9	Transaction Timer Timeout	TTN				
S9F11	Data Too Long	DLN				
S9F13	Conversation Timeout	CTN				
S14F1	Get Attribute Request	GAR	S14F2	Get Attribute Data		
SxF0	Abort Transaction	SxF0				

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### **6. EQUIPMENT CONSTANTS**

ECID	Description	Туре	Default	Max	Min	Comment
0	EQUIPMENT_NAME	6-byte ASCII	Eg XT	-	-	Internal only
1	SOFTWARE_REVISION	6-byte ASCII	020537	-	-	Internal only
2	COMMUNICATION_RETRY	2-byte int(us)	3	1000	1	Internal only
3	MAX_SPOOL_TRANSMIT	2-byte int(us)	40	100	0	Internal only
4	OVER_WRITE_SPOOL	boolean	0	1	0	Internal only
22	TIMEFORMAT	1-byte int(us)	0	1	0	Internal only
28	Lot Validity	1-byte int (us)	0	1	0	Applicable only for ASM IDEALine
29	User Logon ID	32 Byte ASCII	-	-	-	Applicable only for ASM IDEALine
31	SOFT-START Timeout	1 Byte US	60	255	0	-
33	Establish Comm Timeout	2-byte int(us)	5000	20000	1000	-
34	Alarm Pager Timeout	1-byte int(us)	0	60	0	-
399	Select Loop Mode	1-byte int(us)	0	255	0	-
400 to 464	Defect in Strip		-	-	-	Applicable only for ASM IDEALine
550 to 558	New Lot Information	-	-	-	-	Applicable only for ASM IDEALine
572	No of column in strip defect map	2 byte int(us)	0	100	0	Applicable only for ASM IDEALine
573	No. of row in strip defect map	2 byte int (us)	0	100	0	Applicable only for ASM IDEALine
600	Trigger SPC instruction	40 byte ASCII	-	-	-	Applicable only for ASM IDEALine
601	Trigger SPC Reset	4 byte int (us)	31	256	0	Applicable only for ASM IDEALine
611	eCheck upon pgm modification	1 byte int (us)	0	1	0	0: No 1: Yes
612	eCheck Allow Bond status	1 byte int (us)	1	2	0	0: No 1: Yes
						2: Comparing
613	eCheck Bond sampling unit	2 bytes int (us)	0	30000	0	
614	eCheck by Host	1 byte int (us)	0	1	0	0: No 1: Yes
652	User name	30 bytes ASCII	-	-	-	(for ASM Internal QA)
653	Security PWD Level 1	10 bytes ASCII	-	-	-	To update Level 1
654	Security PWD Level 2	10 bytes ASCII	-	-	-	To update Level 2
655	Security PWD Level 3	10 bytes ASCII	-	-	-	To update Level 3
656	Security PWD Level 4	10 bytes ASCII	-	-	-	To update Level 4
658	User name	I byte int (us)	0	1		0: Login PASS
						1: Login FAIL
659	Operator ID	32 bytes ASCII	-	-	-	For Special Customer
670	Current Lot ID	32 bytes ASCII	-	-	-	For Special Customer
671	Current Lot Quantity	4 byte int (us)	0	141006 5407	0	For Special Customer
672	Remote Control Mode	1 byte int (us)	0	1	0	-
673	Statistic Start Time	32 Byte ASCII				Format "yyyy-mm-dd hh:mm:ss"
674	Statistic End Time	32 Byte ASCII				Format "yyyy-mm-dd hh:mm:ss"

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BPC sampling unit during bonding 2 bytes int (us) 0 30000 0

Comment:

Internal Only — Can be set by the host, but is not displayed on the bonder menu

Available to Operator — Can be set by the Host or the Operator. When changed by the operator, a

Change EC event will be sent to the Host informing of the variable adjusted.

### 7. STATUS VARIABLES

SVID	Description	Туре	Default	Max	Min	Comment
5	Clock	Date & Time TIMEFORMAT = 0 12 characters (Non Y2K Compliant) YYMMDDHHMMSS TIMEFORMAT = 1 16 characters (Y2K Compliant) YYYYMMDDHHMMSSCC	-	-	-	-
6	Control State	Binary	1-EQUIP OFFLINE	5- ONLINE REMOTE	1-EQUIP OFFLINE	1-EQUIP OFFLINE 2-ATTEMP ONLINE 3-HOST OFFLINE 4-ONLINE LOCAL 5-ONLINE REMOTE
7	Previous Process State	2-byte int(s)	2-Idle	11-Upload	1-INIT	1-Init 2-Idle 3-Setup 4-ReadyLocal 5-Exe-Local 6-Pause 7-Alarm 8-Ready-Remote 9-Exe-Remote 10-Download 11-Upload
8	Process State	2-byte int(s)	2-Idle	11-Upload	2-Idle	Same as Previous Process State
9	SPOOL_COUNT_ACTUAL	2-byte int(us)	0	1000	0	-
10	SPOOL_COUNT_TOTAL	2-byte int(us)	0	1000	0	-
11	SPOOL_FULL_TIME	Date & Time	-	-	-	-
12	SPOOL_START_TIME	Date & Time	-	-	-	-
13	AlarmID	2-byte int(us)	0	255	0	-
14	ALARM_SET	1-byte int(us)	0	255	0	-
15	PauseReason	2-byte int(s)	0	2	0	0-Alarm 1-Equip / Operator 2-Host
16	OPERATOR_COMMAND	1-byte int(us)	0	100	0	-
17	PPChangeName	24-byte ASCII	-	-	-	-
18	PPChangeStatus	1-byte int(us)	1	3	1	1-Created 2-Edited

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						3-Deleted
19	PPExecName	24-byte ASCII	-	-	-	-
20	TRANSITION_TYPE	1-byte int(us)				
21	EventsEnabled	List	-	-	-	List of current CEID enabled.
23	AlarmClock	16-byte ASCII	-	-	-	Date & Time
24	AlarmsSet	Variable list	-	-	-	ALID
25	Machine ID	11 Byte ASCII	-	-	-	-
26	Last PM Date	16 Byte ASCII	-	-	-	Date & Time
27	Installation Date	16 Byte ASCII	-	-	-	Date & TIME
30	EquipPerformLastDateRes et	16-byte ASCII	-	-	-	Date & Time
35	Soft Start Activation	1-byte int(s)	0	1	0	0: Disable 1: Enable
36	Type of Wire Parameter changed	2-byte int (S)	0	16	0	0: No change 1: Force1 2: Force2 3: Power1 4: Power2 5: Time1 6: Time2 7: Contact Force1 8: Contact Force2 9: Contact Power1 10: Contact Power2 11: 12: Scrub Control 13: Stick Detect 1 14: Stick Detect 2 15: BSOB/BBOS 16: Tail Length
37	Barcode String	32 bytes – ASCII	_	_	_	10. Tall Leligui
39	PPPreviousName	24-byte ASCII	_	_	_	_
41	AutoLoop – Reverse Height	2 byte-int (s)	10	100	10	
42	AutoLoop – Reverse Distance Factor	2 byte-int (s)	0	100	0	
43	AutoLoop – Loop Correction	2 byte-int (s)	0	100	-100	
44	AutoLoop – Loop Correction Slope	2 byte-int (s)	0	50	-50	
45	AutoLoop – Search Delay Base	2 byte-int (s)	1	50	1	
46	AutoLoop – Search Delay Factor	2 byte-int (s)	0	50	0	
47	AutoLoop – Sync Offset	2 byte-int (s)	0	32767	-32768	
48	AutoLoop – DEC Sample Offset	2 byte-int (s)	0	127	-127	
50	QautoLoop – Reverse Height	2 byte-int (s)	10	100	10	
51	QautoLoop – Reverse Distance Factor	2 byte-int (s)	0	500	0	
52	QautoLoop – Loop Correction	2 byte-int (s)	0	127	-127	

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53	QautoLoop – Loop Correction Slope	2 byte-int (s)	0	50	-50
54	QautoLoop – Search Delay Base	2 byte-int (s)	1	50	1
55	QautoLoop – Search Delay Factor	2 byte-int (s)	0	50	0
56	QautoLoop – Sync Offset	2 byte-int (s)	0	32767	-32768
57	QautoLoop – Reverse Height Ratio	1 byte-int (us)	0	255	0
58	QautoLoop – DEC Sample Offset	2 byte-int (s)	0	127	-127
60	TSOP – Reverse Height	2 byte-int (s)	10	100	10
61	TSOP – Reverse Distance Factor	2 byte-int (s)	0	100	0
62	TSOP – Loop Correction	2 byte-int (s)	0	100	-100
63	TSOP – Loop Correction Slope	2 byte-int (s)	0	50	-50
64	TSOP – Search Delay Base	2 byte-int (s)	1	50	1
65	TSOP – Search Delay Factor	2 byte-int (s)	0	50	0
66	TSOP – Sync Offset	2 byte-int (s)	0	32767	-32768
67	TSOP – Reverse Height Ratio	1 byte-int (us)	0	4	0
68	TSOP – DEC Sample Offset	2 byte-int (s)	0	127	-127
70	NormalLoop – Reverse Height	2 byte-int (s)	10	100	10
71	NormalLoop – Reverse Distance Factor	2 byte-int (s)	0	100	0
72	NormalLoop – Loop Correction	2 byte-int (s)	0	100	-100
73	NormalLoop – Loop Correction Slope	2 byte-int (s)	0	50	-50
74	NormalLoop – Search Delay Base	2 byte-int (s)	1	50	1
75	NormalLoop – Search Delay Factor	2 byte-int (s)	0	50	0
76	NormalLoop - Sync Offset	2 byte-int (s)	0	32767	-32768
77	NormalLoop – DEC Sample Offset	2 byte-int (s)	0	127	-127
80	NLSquareLoop – Loop Height	2 byte-int (s)	2	500	5
81	NLSquareLoop – Flat Length	2 byte-int (s)	50	100	10
82	NLSquareLoop – Reverse Height	2 byte-int (s)	10	100	10
83	NLSquareLoop – Reverse Distance Factor	2 byte-int (s)	0	100	0
84	NLSquareLoop – Loop Correction	2 byte-int (s)	0	100	-100
85	NLSquareLoop – Loop Correction Slope	2 byte-int (s)	0	50	-50
86	NLSquareLoop – Search	2 byte-int (s)	1	50	1

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	Delay Base				
87	NLSquareLoop – Search Delay Factor	2 byte-int (s)	0	50	0
88	NLSquareLoop – Sync Offset	2 byte-int (s)	0	32767	-32768
89	NLSquareLoop – Reverse Height Ratio	1 byte-int (us)	0	40	0
90	NLSquareLoop – DEC Sample Offset	2 byte-int (s)	0	100	0
91	NLSquareLoop – Horizontal Length	2 byte-int (s)	0	250	0
92	NLSquareLoop – Reverse Dist2 %	2 byte-int (s)	0	1000	0
93	NLSquareLoop – Reverse Dist2 Angle	1 byte-int (us)	0	255	0
95	LLSquareLoop – Loop Height	2 byte-int (s)	2	500	5
96	LLSquareLoop – Flat Length	2 byte-int (s)	50	100	10
97	LLSquareLoop – Reverse Height	2 byte-int (s)	10	100	10
98	LLSquareLoop – Reverse Distance Factor	2 byte-int (s)	0	100	0
99	LLSquareLoop – Loop Correction	2 byte-int (s)	0	100	-100
100	LLSquareLoop – Loop Correction Slope	2 byte-int (s)	0	50	-50
101	LLSquareLoop – Search Delay Base	2 byte-int (s)	1	50	1
102	LLSquareLoop – Search Delay Factor	2 byte-int (s)	0	50	0
103	LLSquareLoop – Sync Offset	2 byte-int (s)	0	32767	-32768
104	LLSquareLoop – Reverse Height Ratio	1 byte-int (us)	0	40	0
105	LLSquareLoop – DEC Sample Offset	2 byte-int (s)	0	100	0
106	LLSquareLoop – Horizontal Length	2 byte-int (s)	0	250	0
107	LLSquareLoop – Reverse Dist2 %	2 byte-int (s)	0	1000	0
108	LLSquareLoop – Reverse Dist2 Angle	1 byte-int (us)	0	255	0
110	NSSquareLoop – Loop Height	2 byte-int (s)	2	500	5
111	NSSquareLoop – Flat Length	2 byte-int (s)	50	100	10
112	NSSquareLoop – Reverse Height	2 byte-int (s)	10	100	10
113	NSSquareLoop – Reverse Distance Factor	2 byte-int (s)	0	100	0
114	NSSquareLoop – Loop Correction	2 byte-int (s)	0	100	-100
115	NSSquareLoop – Loop	2 byte-int (s)	0	50	-50

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	Compation Class				
116	Correction Slope NSSquareLoop – Search	2 byte-int (s)	1	50	1
117	Delay Base NSSquareLoop – Search	2 byte-int (s)	0	50	0
118	Delay Factor NSSquareLoop – Sync	2 byte-int (s)	0	32767	-32768
	Offset	, , ,			
119	NSSquareLoop – Reverse Height Ratio	1 byte-int (us)	0	40	0
120	NSSquareLoop – DEC Sample Offset	2 byte-int (s)	0	100	0
121	NSSquareLoop – Horizontal Length	2 byte-int (s)	0	250	0
122	NSSquareLoop – Reverse	2 byte-int (s)	0	1000	0
123	Dist2 % NSSquareLoop – Reverse	1 byte-int (us)	0	255	0
125	Dist2 Angle LSSquareLoop – Loop	2 byte-int (s)	2	500	5
126	Height LSSquareLoop – Flat	2 byte-int (s)	50	100	10
127	Length LSSquareLoop – Reverse	2 byte-int (s)	10	100	10
	Height				
128	LSSquareLoop – Reverse Distance Factor	2 byte-int (s)	0	100	0
129	LSSquareLoop – Loop Correction	2 byte-int (s)	0	100	-100
130	LSSquareLoop – Loop Correction Slope	2 byte-int (s)	0	50	-50
131	LSSquareLoop – Search Delay Base	2 byte-int (s)	1	50	1
132	LSSquareLoop – Search	2 byte-int (s)	0	50	0
133	Delay Factor LSSquareLoop – Sync	2 byte-int (s)	0	32767	-32768
134	Offset LSSquareLoop – Reverse	1 byte-int (us)	0	40	0
135	Height Ratio LSSquareLoop – DEC	2 byte-int (s)	0	100	0
	Sample Offset	, , ,			
136	LSSquareLoop – Horizontal Length	2 byte-int (s)	0	250	0
137	LSSquareLoop – Reverse Dist2 %	2 byte-int (s)	0	1000	0
138	LSSquareLoop – Reverse Dist2 Angle	1 byte-int (s)	0	255	0
140	NISquareLoop – Loop Height	2 byte-int (s)	2	500	5
141	NISquareLoop – Flat	2 byte-int (s)	50	100	10
142	Length NISquareLoop – Reverse	2 byte-int (s)	10	100	10
143	Height NISquareLoop – Reverse	2 byte-int (s)	0	100	0
144	Distance Factor NISquareLoop – Loop	2 byte-int (s)	0	100	-100
		= -100 (0)	•		-50

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	Correction				
145	NISquareLoop – Loop Correction Slope	2 byte-int (s)	0	50	-50
146	NISquareLoop – Search Delay Base	2 byte-int (s)	1	50	1
147	NISquareLoop – Search Delay Factor	2 byte-int (s)	0	50	0
148	NISquareLoop – Sync Offset	2 byte-int (s)	0	32767	-32768
149	NISquareLoop – Reverse Height Ratio	1 byte-int (us)	0	40	0
150	NISquareLoop – DEC Sample Offset	2 byte-int (s)	0	100	0
151	NISquareLoop – Horizontal Length	2 byte-int (s)	0	250	0
152	NISquareLoop – Reverse Dist2 %	2 byte-int (s)	0	1000	0
153	NISquareLoop – Reverse Dist2 Angle	1 byte-int (us)	0	255	0
155	LISquareLoop – Loop Height	2 byte-int (s)	2	500	5
156	LISquareLoop – Flat Length	2 byte-int (s)	50	100	10
157	LISquareLoop – Reverse Height	2 byte-int (s)	10	100	10
158	LISquareLoop – Reverse Distance Factor	2 byte-int (s)	0	100	0
159	LISquareLoop – Loop Correction	2 byte-int (s)	0	100	-100
160	LISquareLoop — Loop Correction Slope	2 byte-int (s)	0	50	-50
161	LISquareLoop – Search Delay Base	2 byte-int (s)	1	50	1
162	LISquareLoop – Search Delay Factor	2 byte-int (s)	0	50	0
163	LISquareLoop – Sync Offset	2 byte-int (s)	0	32767	-32768
164	LISquareLoop – Reverse Height Ratio	1 byte-int (us)	0	40	0
165	LISquareLoop – DEC Sample Offset	2 byte-int (s)	0	100	0
166	LISquareLoop – Horizontal Length	2 byte-int (s)	0	250	0
167	LISquareLoop – Reverse Dist2 %	2 byte-int (s)	0	1000	0
168	LISquareLoop – Reverse Dist2 Angle	1 byte-int (us)	0	255	0
180	File Transfer Mode	Boolean	True		
181	NSD – Stick detect 1	Boolean	False	-	-
182	NSD – Stick Detect 2	Boolean	False	_	_
183	Skip Bad Die	Boolean	False	_	_
184	Skip missing die	Boolean	False	_	_
185	Skip ink/bad unit	Boolean	False	_	_
186	Skip by checking special	Boolean	False	_	_
	p 5/ 5ssiding special	_ 00.00	1 4150		

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	pattern					
187	Skip Die by mark check	Boolean	False	-	-	
188	Check Max skip die	1 byte int (s)	0	1	0	
189	Max number of	2 byte int (US)	30	1000	2	
	continuous skip die					
190	Skip Non stick die	Boolean	False	-	-	
191	NSOP Skip Die	Boolean	False	-	-	
192	NSOL Skip Die	Boolean	False	-	-	
193	Missing ball skip die	Boolean	False	-	-	
195	VLL Lead Width Tol	2 byte int(s)	0	3000	0	
196	VLL Search Delay	2 byte int (s)	0	200	0	
197	WCL Open Force	2 byte int(s)	50	500	0	
198	WCL Close Force	2 byte int(s)	40	500	0	
201	Torch level	2-byte int(s)	0	50	-670	
202	Program valid flag	irebon	False	-	-	
203	Number of wire	2-byte int(s)	0	2000	0	
204	Number of reference	2-byte int(s)	0	2000	0	
205	Feed power	1-byte int(us)	10	255	0	
206	EFO delay	2-byte int(s)	3	32000	0	
207	Standby power 1	1-byte int(us)	33	255	0	
208	Fire Level Factor	2-byte int(s)	10	100	0	
209	Tail length	1-byte int(s)	35	100	0	
210	PR Tolerance Retry	2-byte int(s)	50	1000	0	
211	Head time	2-byte int(s)	10	30	0	
214	Contact force 1	2-byte int(s)	0	1000	0	
215	Contact force 2	2-byte int(s)	150	1000	0	
216	Power delay	1-byte int(us)	0	50	0	
217	Standby power 2	2-byte int(s)	2	1000	0	
218	Power delay 2	1-byte int(us)	90	255	0	
219	false alarm count	4-byte int(us)	0	999999	0	
221	Ball size – EFO Parameter	2-byte int(s)	30	100	0	
222	Fire Level – EFO	2-byte int(s)	25	1000	-1000	
	Parameter					
223	Bond Time Unit Factor	2-byte int(s)	0	1	0	0: 0.5ms
						1: 1ms
224	EFO FAB Block	2 byte int(s)	0	1	0	
225	EFO Current	4 byte int(s)	3250	40000	1000	
226	Wire Size – EFO	2-byte int(s)	10	250	5	
	Parameter					
227	FAB size – EFO Parameter	2-byte int(s)	24	255	1	
229	Ball Thickness- EFO parameter	2-byte int(s)	0	1000	0	
230	Heater Value	4-byte int(s)	0	1000	0	
231	Pre-Heater Value	4-byte int(s)	0	1000	0	
232	Post Bond Heater Value	4-byte int(s)	0	1000	0	
233	Fork Heater	4-byte int(s)	0	1000	0	
234	Over Hang Heater Value	4-byte int(s)	0	1000	0	
235	Heater2 Value	4-byte int(s)	0	1000	0	
236	Contact Time 1	1-byte int(us)	0	255	0	
237	Contact Time 2	1 byte int(us)	0	255	0	
238	Contact Power 1	2 byte int (s)	0	255	0	
239	Contact Power 2	2 byte int (s)	0	255	0	
241	Die alignment tolerance	2-byte int(s)	5	255	0	
242	Lead alignment tolerance	2-byte int(s)	50	255	0	

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243	Bond tip offset in x	4-byte float	0	32767	-32767	
244	Bond tip offset in y	4-byte float	0	32767	-32767	
245	Power factor	2-byte int(s)	10	50	0	
246	Force factor	2-byte int(s)	0	5	0	
247	Preheat time	1-byte int(us)	0	50	0	
248	Bond Time 1	2-byte int(s)	22	255	0	
249	Bond Time 2	2-byte int(s)	15	255	0	
250	Bond Force 1	2-byte int(s)	45	255	0	
251	Bond Force 2	2-byte int(s)	110	255	0	
252	Bond Power 1	2-byte int(s)	70	255	0	
253	Bond Power 2	2-byte int(s)	100	255	0	
254	Loop base	2-byte int(s)	40	100	10	
255	Lead tool offset	2-byte int(s)	0	10	0	
256	Number of rows	1-byte int(s)	1	127	0	-
257	Number of columns	1-byte int(s)	1	127	0	-
258	Step & repeat flag	1-byte int(s)	0	6	0	0: None (Single Unit) 1: Matrix 2: Hybrid Forward 3: Hybrid Reverse 4: PR Look Ahead 5: Hybrid Rev Matrix 6: Ahead Matrix
259	PR search delay for die	2-byte int(s)	30	32000	0	Unit Factor 0.5ms
260	PR search delay for lead	2-byte int(s)	20	32000	0	Unit Factor 0.5ms
261	Device Name	8-byte ASCII	"ADEFAU LT"	-	-	-
265	Operator ID	32 bytes ASCII	-	-	-	
270	Power Factor for 1 <sup>st</sup> bond	2-byte int (US)	0	255	0	
271	Force Factor1 for 1st bond	2-byte int (US)	0	255	0	
272	SIM Option	2-byte int (US)	0	1	0	
273	Pre-Heat All unit	1 byte int (US)	1	1	0	
274	EFO Current FAB BLK #0	2 byte int (US)	3250	40000	1000	
275	EFO Current FAB BLK #1	2 byte int (US)	3250	40000	1000	
276	EFO-Wire Type	1-byte int(s)	0	1	0	
277	EFO control Mode	1-byte int(s)	0	1	0	
278	EFO Enable Dual FAB	1-byte int(s)	0	1	0	
279	Auto Calc EFO Time	1-byte int(s)	1	1	0	
281	Number of unit bonded	8-byte float	0	999999999 9	0	-
282	Number of wire bonded	8-byte float	0	999999999 9	0	-
283	Capillary count	8-byte float	0	999999999 9	0	-
284	Number of ball missing	4-byte int(us)	0	99999999	0	-
285	Wire turn count	4-byte int(us)	0	9999999	0	-
286	Number of die skipped	4-byte int(us)	0	99999999	0	-
287	Number of time encounter skip die	4-byte int(us)	0	99999999	0	-
288	Number of lead quality fail	4-byte int(us)	0	99999999	0	-
289	Number of lead tolerance fail	4-byte int(us)	0	99999999	0	-
290	Number of die quality fail	4-byte int(us)	0	99999999	0	-

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291	Number of die tolerance fail	4-byte int(us)	0	99999999	0	-
292	Number of local lead fail	4-byte int(us)	0	99999999	0	-
293	Number of ejector error	4-byte int(us)	0	99999999	0	-
294	Number of output magazine fail	4-byte int(us)	0	99999999	0	-
295	Number of index error	4-byte int(us)	0	99999999	0	-
296	Number of window clamp error	4-byte int(us)	0	99999999	0	-
297	Number of 1 <sup>st</sup> non-stick error	4-byte int(us)	0	99999999	0	
298	Number of 2 <sup>nd</sup> non-stick error	4-byte int(us)	0	99999999	0	
299	Total Productive Time	4-byte int(us)	0	9999999	0	
300	Ideal UPH	4-byte f	0	99999999	0	
301	Net UPH	4-byte f	0	99999999	0	
303	MTBA	4-byte int(us)	0	9999999	0	Seconds
304	Number of Assists	4-byte int(us)	0	99999999	0	Seconds
305	MTBF	4-byte int(us)	0	9999999	0	Seconds
306	Number of Failures	4-byte int(us)	0	9999999	0	Seconds
307	Total Idle Time	4-byte int(us)	0	9999999	0	Seconds
308	Productive Time	4-byte int(us)	0	9999999	0	Seconds
309	Down Time	4-byte int(us)	0	9999999	0	Seconds
310	Up Time	4-byte int(us)	0	9999999	0	Seconds
311	Number of Skip ink die	4 byte int(us)	0	9999999	0	
312	Number of skip missing die	4 byte int(us)	0	99999999	0	
313	Number wire clamp errors	8 byte Float	0	99999999	0	
314	Number of Etorch errors	8 byte Float	0	99999999	0	
315	Number of Tail Short	4 byte int(us)	0	9999999	0	
316	Number of Index PR Fail	4 byte int(us)	0	99999999	0	
317	Number of Index Out of Tiebar	4 byte int(us)	0	99999999	0	
318	Number of Wire End	4 byte int(us)	0	9999999	0	
320	Processed Quantity	4-byte int(us)	0	99999999	0	
321	Rejected Quantity	4-byte int(us)	0	99999999	0	
322	Yield	4-byte float	0	100	0	%
323	E10-96 Equipment State	2-byte int(us)	1	6	1	1 Productive 2 Standby 3 Engineering 4 Sched Down 5 Unsh Down 6 NonSch Down
331	Param range – Time Base1 – Max value	2 byte int (s)	0	255	0	o Noriscii Dowii
332	Param range – Time Base1 – Min value	2 byte int (s)	0	255	0	
333	Param range – Time Base2 – Max value	2 byte int (s)	0	255	0	
334	Param range – Time Base2 – Min value	2 byte int (s)	0	255	0	
335	Param range – Power Base1 – Max value	2 byte int (s)	0	255	0	
336	Param range – Power	2 byte int (s)	0	255	0	

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	Base1 – Min value					
337	Param range – Power	2 byte int (s)	0	255	0	
337	Base2 – Max value	2 byte iii (3)	U	233	U	
338	Param range – Power	2 byte int (s)	0	255	0	
550	Base2 – Min value	2 byte iii (3)	O	233	U	
339	Param range – Force	2 byte int (s)	0	255	0	
333	Base1 – Max value	z byte me (b)	Ü	233	· ·	
340	Param range – force	2 byte int (s)	0	255	0	
	Base1 – Min value	= 5/55 (5/				
341	Param range – Force	2 byte int (s)	0	255	0	
	Base2 – Max value	, , , ,				
342	Param range – force	2 byte int (s)	0	255	0	
	Base2 – Min value					
361	1st Bond Scrub Control	2 byte int(s)	0	1	0	
362	1 <sup>st</sup> Bond Scrub Direction	2 byte int(s)	0	9	0	
363	1st Bond Scrub Force	2 byte int(s)	9	1000	0	
364	1st Bond Scrub Power	2 byte int(s)	30	255	0	
365	2 <sup>nd</sup> Bond Scrub Control	2 byte int(s)	0	8	0	
366	2 <sup>nd</sup> Bond Scrub Direction	2 byte int(s)	0	3	0	
367	2 <sup>nd</sup> Bond Scrub Force	2 byte int(s)	0	1000	0	
368	2 <sup>nd</sup> Bond Scrub Contact	2 byte int(s)	0	255	0	
	Power					
372	ECChangeStatus	2-byte int(us)	-	-	-	ECID change status
373	Set1 Impedance	4-byte f	0	99999999	0	
374	Set2 Impedance	4-byte f	0	99999999	0	
375	Set1 Bond Freq	2-byte int(us)	0	3	0	
376	Set2 Bond Freq	2-byte int(us)	0	3	0	
381	PR- Coaxial Light	2-byte int(s)	0	255	0	
382	PR-Side Light	2-byte int(s)	0	255	0	
383	Panel Coaxial Light	2-byte int(us)	0	255	0	
384	Panel Side Light	2-byte int(us)	0	255	0	
385	PR-Low Mag Coaxial Light	2-byte int(s)	0	255	0	
386	PR-Low Mag Side Light	2-byte int(s)	0	255	0	
387	Coaxial Blue Light-Hi Mag	2-byte int(s)	0	255	0	
388	Coaxial Blue Light-Low	2-byte int(s)	0	255	0	
	Mag					(=
470	Defect Out Strip ID	32 byte ASCII	-	-	-	(For ASM IDEALine)
471	Defect out strip status	2 byte int(s)	-	-	-	(For ASM IDEALine)
472	Defect Out Count	2 byte int(us)	-	-	-	(For ASM IDEALine)
473	Defect out Last block	Boolean	FALSE	-	-	(For ASM IDEALine)
474	Defect out X1	2 byte int (us)	-	-	-	(For ASM IDEALine) (For ASM IDEALine)
475	Defect Out Y1	2 byte int (us)	-	-	-	
476	Defect Out Code1	2 byte int(s)	-	-	-	(For ASM IDEALine) (For ASM IDEALine)
477	Defect out X2	2 byte int (us)	-	-	-	(For ASM IDEALine)
478	Defect Out Y2	2 byte int (us)	-	-	-	(For ASM IDEALine)
479	Defect Out Code2	2 byte int(s) 2 byte int (us)	-	-	-	(For ASM IDEALine)
480 481	Defect out X3	, , ,	-	-	-	(For ASM IDEALine)
	Defect Out Y3	2 byte int (us)	-	-	-	(For ASM IDEALine)
482 483	Defect Out Code3 Defect out X4	2 byte int(s) 2 byte int (us)	_	-	-	(For ASM IDEALine)
484	Defect Out Y4	2 byte int (us)	-	-	-	(For ASM IDEALine)
485	Defect Out 14  Defect Out Code4	2 byte int(us) 2 byte int(s)	-	-	_	(For ASM IDEALine)
486	Defect out X5	2 byte int (us)	_	_	_	(For ASM IDEALine)
487	Defect Out Y5	2 byte int (us)	_	_	_	(For ASM IDEALine)
,		= 57 to 1110 (d5)				/

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400	Data do Cada E	2 (- 1 - 1 - 1 - 1 - 1				(For ASM IDEALine)
488	Defect Out Code5	2 byte int(s)	-	-	-	(For ASM IDEALINE)
489	Defect out X6	2 byte int (us)	-	-	-	
490	Defect Out Y6	2 byte int (us)	-	-	-	(For ASM IDEALine)
491	Defect Out Code6	2 byte int(s)	-	-	-	(For ASM IDEALine)
492	Defect out X7	2 byte int (us)	-	-	-	(For ASM IDEALine)
493	Defect Out Y7	2 byte int (us)	-	-	-	(For ASM IDEALine)
494	Defect Out Code7	2 byte int(s)	-	-	-	(For ASM IDEALine)
495	Defect out X8	2 byte int (us)	-	-	-	(For ASM IDEALine)
496	Defect Out Y8	2 byte int (us)	-	-	-	(For ASM IDEALine)
497	Defect Out Code8	2 byte int(s)	-	-	-	(For ASM IDEALine)
498	Defect out X9	2 byte int (us)	-	-	-	(For ASM IDEALine)
499	Defect Out Y9	2 byte int (us)	-	-	-	(For ASM IDEALine)
500	Defect Out Code9	2 byte int(s)	-	-	-	(For ASM IDEALine)
501	Defect out X10	2 byte int (us)	-	-	-	(For ASM IDEALine)
502	Defect Out Y10	2 byte int (us)	-	-	-	(For ASM IDEALine)
503	Defect Out Code10	2 byte int(s)	-	-	-	(For ASM IDEALine)
504	Defect out X11	2 byte int (us)	-	-	-	(For ASM IDEALine)
505	Defect Out Y11	2 byte int (us)	-	-	-	(For ASM IDEALine)
506	Defect Out Code11	2 byte int(s)	-	-	-	(For ASM IDEALine)
507	Defect out X12	2 byte int (us)	-	-	-	(For ASM IDEALine)
508	Defect Out Y12	2 byte int (us)	-	-	-	(For ASM IDEALine)
509	Defect Out Code12	2 byte int(s)	-	-	-	(For ASM IDEALine)
510	Defect out X13	2 byte int (us)	-	-	-	(For ASM IDEALine)
511	Defect Out Y13	2 byte int (us)	-	-	-	(For ASM IDEALine)
512	Defect Out Code13	2 byte int(s)	-	-	-	(For ASM IDEALine)
513	Defect out X14	2 byte int (us)	_	_	-	(For ASM IDEALine)
514	Defect Out Y14	2 byte int (us)	_	_	-	(For ASM IDEALine)
515	Defect Out Code14	2 byte int(s)	_	_	-	(For ASM IDEALine)
516	Defect out X15	2 byte int (us)	_	_	_	(For ASM IDEALine)
517	Defect Out Y15	2 byte int (us)	_	_	_	(For ASM IDEALine)
518	Defect Out Code15	2 byte int(s)	_	_	_	(For ASM IDEALine)
519	Defect out X16	2 byte int (us)	_	_	_	(For ASM IDEALine)
520	Defect Out Y16	2 byte int (us)	_	_	_	(For ASM IDEALine)
521	Defect Out Code16	2 byte int(s)	_	_	_	(For ASM IDEALine)
522	Defect out X17	2 byte int (us)	_	_	_	(For ASM IDEALine)
523	Defect Out Y17	2 byte int (us)	_	_	_	(For ASM IDEALine)
524	Defect Out Code17	2 byte int(s)	_	_	_	(For ASM IDEALine)
525	Defect out X18	2 byte int(s) 2 byte int (us)	_	_		(For ASM IDEALine)
525 526	Defect Out Y18	2 byte int (us) 2 byte int (us)	_	-	-	(For ASM IDEALine)
	Defect Out Code18		-	-	-	(For ASM IDEALine)
527		2 byte int(s)	-	-	-	(For ASM IDEALine)
528	Defect out X19	2 byte int (us)	-	-	-	(For ASM IDEALine)
529	Defect Out Y19	2 byte int (us)	-	-	-	(For ASM IDEALINE)
530	Defect Out Code19	2 byte int(s)	-	-	-	,
531	Defect out X20	2 byte int (us)	-	-	-	(For ASM IDEALine)
532	Defect Out Y20	2 byte int (us)	-	-	-	(For ASM IDEALine)
533	Defect Out Code20	2 byte int(s)	-	-	-	(For ASM IDEALine)
560	Current Lot Id	32 byte ASCII				
561	Current Lot Product Id	32 Byte ASCII				
562	Current Lot Quantity	4-byte int(us)	0	141006540 7	0	
563	Current Lot unit per substrate	2-byte int(us)	0	34463	0	(For ASM IDEALine)
564	Current Lot PPID	32 byte ASCII	-	-	-	(For ASM IDEALine)
565	Current lot Gold Wire	32 byte ASCII	-	-	-	(For ASM IDEALine)
		·				

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566	Current Lot Capillary	32 byte ASCII	-	-	-	(For ASM IDEALine)
567	Current Lot Window	32 byte ASCII				(For ASM IDEALine)
	Clamp					
568	Current Lot Top Plate	32 byte ASCII	-	-	-	(For ASM IDEALine)
569	Current Lot Status	32 byte ASCII	-	-	-	(For ASM IDEALine)
570	Personnel ID	32 byte ASCII	-	-	-	(For ASM IDEALine)
571	Strip Process Status	Boolean	False	-	-	(For ASM IDEALine)
574	Cell Controller Lot Mgmt	1 byte int(us)	0	1	1	0: DISABLE
	Status					1: ENABLE
575	Stripmap Option	1 byte int(us)	0	1	1	0: DISABLE
						1: ENABLE
576	Recipe Target	2 byte int (us)	0	2	0	0: HDD only
						1: RAM only
						2: HDD & RAM
577	Host Recipe Extension	1 byte int (us)	0	1	0	0: DISABLE
						1: ENABLE
578	Magazine ID	32 byte ASCII	-	-	-	
579	Magazine Activity	32 byte ASCII	-	-	-	
580	Magazine Location	32 byte ASCII	-	-	-	
581	Stripmap Error	1 byte US	0	2	0	(For ASM IDEALine)
	Registration Option	,				0: No
						1: Manual
						2: Auto
700	Loop Mode 0 – Validity	Boolean	False			0-Invalid, 1-Valid
701	Loop Mode 1 – Validity	Boolean	False			0-Invalid, 1-Valid
702	Loop Mode 2 – Validity	Boolean	False			0-Invalid, 1-Valid
703	Loop Mode 3 – Validity	Boolean	False			0-Invalid, 1-Valid
704	Loop Mode 4 – Validity	Boolean	False			0-Invalid, 1-Valid
705	Loop Mode 5 – Validity	Boolean	False			0-Invalid, 1-Valid
706	Loop Mode 6 – Validity	Boolean	False			0-Invalid, 1-Valid
707	Loop Mode 7 – Validity	Boolean	False			0-Invalid, 1-Valid
708	Loop Mode 8 – Validity	Boolean	False			0-Invalid, 1-Valid
709	Loop Mode 9 – Validity	Boolean	False			0-Invalid, 1-Valid
710	Loop Mode 10 – Validity	Boolean	False			0-Invalid, 1-Valid
711	Loop Mode 11 – Validity	Boolean	False			0-Invalid, 1-Valid
712	Loop Mode 12 – Validity	Boolean	False			0-Invalid, 1-Valid
713	Loop Mode 13 – Validity	Boolean	False			0-Invalid, 1-Valid
714	Loop Mode 14 – Validity	Boolean	False			0-Invalid, 1-Valid
715	Loop Mode 15 – Validity	Boolean	False			0-Invalid, 1-Valid
716	Loop Mode 16 – Validity	Boolean	False			0-Invalid, 1-Valid
717	Loop Mode 17 – Validity	Boolean	False			0-Invalid, 1-Valid
718	Loop Mode 18 – Validity	Boolean	False			0-Invalid, 1-Valid
719	Loop Mode 19 – Validity	Boolean	False			0-Invalid, 1-Valid
720	Loop Mode 20 – Validity	Boolean	False			0-Invalid, 1-Valid
721	Loop Mode 21 – Validity	Boolean	False			0-Invalid, 1-Valid
722	Loop Mode 22 – Validity	Boolean	False			0-Invalid, 1-Valid
723	Loop Mode 23 – Validity	Boolean	False			0-Invalid, 1-Valid
724	Loop Mode 24 – Validity	Boolean	False			0-Invalid, 1-Valid
725	Loop Mode 25 – Validity	Boolean	False			0-Invalid, 1-Valid
726	Loop Mode 26 – Validity	Boolean	False			0-Invalid, 1-Valid
727	Loop Mode 27 – Validity	Boolean	False			0-Invalid, 1-Valid
728	Loop Mode 28 – Validity	Boolean	False			0-Invalid, 1-Valid
729	Loop Mode 29 – Validity	Boolean	False			0-Invalid, 1-Valid
730	Loop Mode 30 – Validity	Boolean	False			0-Invalid, 1-Valid
						•

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721	Loop Mode 21 Validity	Declare	Falso			O Involid 1 Valid
731 732	Loop Mode 31 – Validity Loop Mode 32 – Validity	Boolean Boolean	False False			0-Invalid, 1-Valid
732	Loop Mode 32 – Validity	Boolean	False			0-Invalid, 1-Valid 0-Invalid, 1-Valid
733 740	ALC- Loop Mode	2-byte int(s)	0	33	0	0-111valiu, 1-valiu
740 741	ALC - Loop Height	2-byte int(s) 2-byte int(s)	75	1500	75	z-step
742	ALC- Reverse Height	2-byte int(s)	6	100	6	z-step z-step
743	ALC- Reverse Distance	2-byte int(s)	0	150	0	2 3tcp
7 13	ratio	2 byte int(3)	O	150	U	
744	ALC- Reverse Distance	2-byte int(s)	0	85	-85	Deg
	Angle	= 2/32(5)				
745	ALC-Loop Height	2-byte int(s)	0	127	-127	z-step
	Correction	, (,				•
746	ALC-Span Length	2-byte int(s)	10	90	10	%
747	ALC-Span Length Unit	2-byte int(s)	0	100	0	%
748	ALC-Span Angle	2-byte int(s)	0	150	-150	Deg
	Correction					
749	ALC-Span Angle	1-byte int(us)	0	1	0	Corr Type
	Correction Type					
750	ALC-Wire Length Factor	2 bytes int(s)	400	550	400	
751	ALC-Loop Height Scale	2-byte int(s)	30	200	30	
	Factor %					
752	ALC-2 <sup>ND</sup> Kink Smoothness	2-byte int(s)	0	100	-100	
	%					
753	ALC- 2 <sup>nd</sup> Kink Height	2-byte int(s)	0	100	0	
	Factor %					
754	ALC-2 <sup>nd</sup> Kink Bump Factor	2-byte int(us)	0	100	0	
755	%	41	•	100	407	
755	ALC-Slope straightness %	1-byte int(s)	0	100	-127	5 (7
756	ALC-Loop Auto Tune Prof	2-byte int(s)	0	3	0	Prof Type
757	ALC-Search Delay Base	2-byte int(s)	0	20	0	ms
758 750	ALC-Search Delay Slope	2-byte int(s)	0	58	-58 16	%
759 760	ALC-Sync_Offset_Base	2-byte int(s)	0	16	-16 -0	xy step
760 761	ALC-Sync_Offset_Slope	2-byte int(s)	0	50 90	-50	% DEC
761 762	ALC-DEC_Sample_OS ALC-Y-Comp	2-byte int(s)	20 0	100	20 0	DEC %
762 763	ALC-Y-Comp_Pre_delay	2-byte int(s) 2-byte int(s)	0	100	0	ms
764	ALC-1-comp_rre_delay  ALC-Loop_Top_ABV_1 <sup>st</sup>	1-byte int(s)	0	2	0	Abv Type
704	Bond	1-byte ilit(3)	U	2	U	Abv Type
765	ALC-Loop Top DEC	2-byte int(s)	0	90	0	DEC
, 05	Samples	z byte me(b)	Ü	30	Ü	520
766	ALC-Loop Top Sync Offset	2-byte int(s)	0	40	-40	ms
767	ALC-Search Speed-2	2-byte int(s)	0	5	0	Srch Type
781	G84 stripmap – Origin	1 byte (us)	3	9	1	(For ASM IDEALine)
	Location	/ ( /				1:Upper Right topside
						2:Upper Left topside
						3:Lower Left topside
						4:Lower right topside
782	G84 stripmap – No of	2 byte (us)	1	34463	0	(For ASM IDEALine)
	rows					
783	G84 stripmap – No of	2 byte (us)	1	34463	0	(For ASM IDEALine)
	columns					
784	G84 stripmap – Cell	Array of 1 byte (us)	0	2	0	(For ASM IDEALine)
	Status					0: Functionally good
						1:Unknown CellStatus

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						2: Defective Cell
785	G84 stripmap – Defect Code status	Array of 2 byte(us)	0	1000	0	
801	Assembly Stage	30 bytes – ASCII	_	_	_	(for ASM internal QA)
001	Notification (ASN) –	50 bytes Asen				(101 ASM Internal QA)
	Username					
802	ASN-UserID	30 bytes ASCII	-	-	-	(for ASM internal QA)
803	ASN-STAGE	30 bytes ASCII	-	-	-	(for ASM internal QA)
804	ASN-SUBSTAGE	30 bytes ASCII	-	-	-	(for ASM internal QA)
805	ASN-ACTIVITY	30 bytes ASCII	-	-	-	(for ASM internal QA)
806	ASN-TIMESTAMP	30 bytes ASCII	-	-	-	(for ASM internal QA)
826	Wirebonder System	16 bytes ASCII	-	-	-	Eg: 09.05.96
	Software Base Version					
827	Software Ref number	16 bytes ASCII	-	-	-	
828	Site in Software Version	16 bytes ASCII	-	-	-	
829	WH software Version	16 bytes ASCII	-	-	-	
830	PR Software version	16 bytes ASCII	-	-	-	
831	BQM Version	16 bytes ASCII	-	-	-	
832	Servo Version	16 bytes ASCII	-	-	-	
833	Heater Version	16 bytes ASCII	-	-	-	
834	Software Date&Time	32 bytes ASCII	-	-	-	
835	Software Rev number	16 bytes ASCII	-	-	-	
836	Equipment System Type	16 bytes ASCII	-	-	-	
840	BSOB Ctrl – Ball	2 byte int (s)	0	2	0	
	Formation Direction	21			_	
841	BSOB Ctrl – Ball Thickness	2 bytes int(s)	0	255	0	
842	BSOB Ctrl – Tail Length	2 bytes int(s)	0	255	0	
843	BSOB Ctrl – Time Base1	2 bytes int(s)	0	255	0	
844	BSOB Ctrl – Time Base2	2 bytes int(s)	0	255	0	
845 846	BSOB Ctrl – Power Base1 BSOB Ctrl – Power Base2	2 bytes int(s)	0 0	255 255	0 0	
847	BSOB Ctrl – Force Base1	2 bytes int(s) 2 bytes int(s)	0	255 255	0	
848	BSOB Ctrl – Force Base2	2 bytes int(s) 2 bytes int(s)	0	255 255	0	
849	BSOB Ctrl – Standby	2 bytes int(s) 2 bytes int(s)	0	255	0	
073	Power1	2 bytes int(s)	U	233	U	
850	BSOB Ctrl – Standby	2 bytes int(s)	0	255	0	
030	Power2	2 bytes int(s)	O	233	U	
851	BSOB Ctrl – Contact	2 bytes int(s)	0	255	0	
031	Time1	2 bytes int(s)	· ·	233	Ü	
852	BSOB Ctrl – Contact	2 bytes int(s)	0	255	0	
	Time2					
853	BSOB Ctrl – Contact	2 bytes int(s)	0	255	0	
	power1					
854	BSOB Ctrl – Contact	2 bytes int(s)	0	255	0	
	Power2	, (,				
855	BSOB Ctrl - Contact	2 bytes int(s)	0	255	0	
	Force1	, , , ,				
856	BSOB Ctrl - Contact	2 bytes int(s)	0	255	0	
	Force2	, , , ,				
857	Twin Ball BSOB Ctrl -	2 bytes int(s)	0	255	0	
	Time Base1					
858	Twin Ball BSOB Ctrl -	2 bytes int(s)	0	255	0	
	Time Base2					
859	Twin Ball BSOB Ctrl -	2 bytes int(s)	0	255	0	

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Second   Twin Ball BSOB Ctrl		Power Base1				
Power Base2   2 bytes int(s)   0   255   0	860		2 bytes int(s)	0	255	0
Force Base1			= = /(= /			
862         Twin Ball BSOB Ctrl — 2 bytes int(s)         0         255         6           663         BSOB Ctrl — Loop Base         2 byte int (s)         0         100         3           864         BSOB Ctrl — Ball Offset         2 bytes int(us)         0         255         6           866         Contact Search Threshold         2 bytes int(us)         0         255         6           867         Contact Search Threshold         2 bytes int(us)         0         80         9           868         BSOB Wire Ctrl — Base         2 bytes int(us)         0         80         9           869         BSOB Wire Ctrl — Base         2 bytes int(us)         0         80         9           870         BSOB Wire Ctrl — Base         2 bytes int(us)         0         255         6           870         BSOB Wire Ctrl — Base         2 bytes int(us)         0         255         6           871         BSOB Wire Ctrl — Base         2 bytes int(us)         0         255         6           872         BSOB Wire Ctrl — Base         2 bytes int(us)         0         255         6           873         BSOB Wire Ctrl — Base         2 bytes int(us)         0         3         6	861	Twin Ball BSOB Ctrl –	2 bytes int(s)	0	255	0
Force Base2						
863         BSOB Ctrl – Loop Base         2 byte int (s)         -500         500         2           864         BSOB Ctrl – Ball Offset         2 bytes int (us)         -500         500         2           866         Contact Search Threshold         2 bytes int (us)         0         255         0           1         2         2         2         2         2           868         BSOB Wire Ctrl – Base         2 bytes int (us)         0         80         5           7 ime1         BSOB Wire Ctrl – Base         2 bytes int (us)         0         80         5           870         BSOB Wire Ctrl – Base         2 bytes int (us)         0         255         2           871         BSOB Wire Ctrl – Base         2 bytes int (us)         0         255         3           872         BSOB Wire Ctrl – Base         2 bytes int (us)         0         255         3           873         BSOB Wire Ctrl – Base         2 bytes int (us)         0         3         0           874         BSOB Ball Ctrl – Ball         2 bytes int (us)         0         3         0           875         BSOB Wire Ctrl – Base         2 bytes int (us)         0         3         0	862		2 bytes int(s)	0	255	0
866         Contact Search Threshold         2 bytes int(us)         0         255         0           867         Contact Search Threshold         2 bytes int(us)         0         255         0           868         BSOB Wire Ctrl – Base         2 bytes int(us)         0         80         1           869         BSOB Wire Ctrl – Base         2 bytes int(us)         0         255         2           870         BSOB Wire Ctrl – Base         2 bytes int(us)         0         255         2           871         BSOB Wire Ctrl – Base         2 bytes int(us)         0         255         2           872         BSOB Wire Ctrl – Base         2 bytes int(us)         0         255         3           Force1         Force2         874         BSOB Ball Ctrl – Ball         2 bytes int(us)         0         3         6           875         BSOB Wire Ctrl – Search         2 bytes int(us)         0         3         6           876         BSOB Wire Ctrl – Ball         2 bytes int(us)         0         3         6           875         BSOB Wire Ctrl – Ball         2 bytes int(us)         0         3         6           882         Scheduled Down Time         8 byte float         0	863	BSOB Ctrl – Loop Base	2 byte int (s)	0	100	11
1 867 Contact Search Threshold 2 bytes int(us) 0 255 0 2 868 BSOB Wire Ctrl – Base 2 bytes int(us) 0 80 5 Time1 869 BSOB Wire Ctrl – Base 2 bytes int(us) 0 80 5 Time2 870 BSOB Wire Ctrl – Base 2 bytes int(us) 0 255 6 Power1 871 BSOB Wire Ctrl – Base 2 bytes int(us) 0 255 6 Power2 872 BSOB Wire Ctrl – Base 2 bytes int(us) 0 255 6 Force1 873 BSOB Wire Ctrl – Base 2 bytes int(us) 0 255 6 Force2 874 BSOB Ball Ctrl – Ball 2 bytes int(us) 0 3255 6 Formation Shape 7 875 BSOB Wire Ctrl – Search 2 bytes int(us) 0 32767 6 Speed 2 882 Scheduled Down Time 8 byte float 0 999999999 0 883 Unscheduled Down Time 8 byte float 0 999999999 0 884 Nonscheduled Down Time 8 byte float 0 999999999 0 885 Standby Time 8 byte float 0 999999999 0 886 Adv Pre-Trigger Mode 2 byte int (s) 0 10 10 6 887 Rev Height Pre-Trigger Time 2 byte int (s) 0 100 6 888 Rev Dist Pre-Trigger Time 2 byte int (s) 0 100 6 889 Rev HT2 Pre-Trigger Time 2 byte int (s) 0 100 6 890 Rev Dist2 Pre-Trigger Time 2 byte int (s) 0 100 6 891 Rev HT3 Pre-trigger Time 2 byte int (s) 0 100 6 892 Rev Dist2 Pre-Trigger Time 2 byte int (s) 0 100 6 893 Bump Pre-trigger Time 2 byte int (s) 0 100 6 894 Twist Fwd Pre-Trigger 2 byte int (s) 0 100 6 895 Time 896 Loop Top – Pre-Trigger 2 byte int (s) 0 100 6 897 Time 898 Loop Top – Pre-Trigger 2 byte int (s) 0 100 6 899 Twist Rev Pre-Trigger 2 byte int (s) 0 100 6 899 Twist Rev Pre-Trigger 2 byte int (s) 0 100 6 899 Twist Rev Pre-Trigger 2 byte int (s) 0 100 6 899 Twist Rev Pre-Trigger 2 byte int (s) 0 100 6 899 Twist Rev Pre-Trigger 2 byte int (s) 0 100 6 899 Twist Rev Pre-Trigger 2 byte int (s) 0 100 6 890 Time 891 Twist Rev Pre-Trigger 2 byte int (s) 0 100 6 891 Twist Rev Pre-Trigger 2 byte int (s) 0 100 6 892 Twist Rev Pre-Trigger 2 byte int (s) 0 100 6 899 Twist Rev Pre-Trigger 2 byte int (s) 0 100 6 899 Twist Rev Pre-Trigger 2 byte int (s) 0 100 6 899 Twist Rev Pre-Trigger 2 byte int (s) 0 100 6 890 Trime 890 Loop Top – Pre-Trigger 2 byte int (s) 0 100 6 890 Trime 890 Loop Top – Pre-Trigger 2 byte int (s) 0 100 6 890 Trime 890 L	864	BSOB Ctrl – Ball Offset		-500	500	25
867         Contact Search Threshold         2 bytes int(us)         0         255         0           868         BSOB Wire Ctrl – Base         2 bytes int(us)         0         80         9           7 ime1         869         BSOB Wire Ctrl – Base         2 bytes int(us)         0         80         9           870         BSOB Wire Ctrl – Base         2 bytes int(us)         0         255         2           871         BSOB Wire Ctrl – Base         2 bytes int(us)         0         255         3           70 power2         BSOB Wire Ctrl – Base         2 bytes int(us)         0         255         3           872         BSOB Wire Ctrl – Base         2 bytes int(us)         0         255         3           873         BSOB Wire Ctrl – Base         2 bytes int(us)         0         3         6           874         BSOB Ball Ctrl – Ball         2 bytes int(us)         0         32767         6           875         BSOB Wire Ctrl – Search         2 bytes int(us)         0         32767         6           882         Scheduled Down Time         8 byte float         0         999999999         8           883         Hackeldled Down Time         8 byte float         0 <t< td=""><td>866</td><td></td><td>2 bytes int(us)</td><td>0</td><td>255</td><td>0</td></t<>	866		2 bytes int(us)	0	255	0
868         BSOB Wire Ctrl – Base Time1         2 bytes int(us)         0         80         9           869         BSOB Wire Ctrl – Base Time2         2 bytes int(us)         0         80         9           870         BSOB Wire Ctrl – Base Power1         2 bytes int(us)         0         255         2           871         BSOB Wire Ctrl – Base Power2         2 bytes int(us)         0         255         3           872         BSOB Wire Ctrl – Base Porce2         2 bytes int(us)         0         255         3           873         BSOB Ball Ctrl – Balse Porce2         2 bytes int(us)         0         3         0           874         BSOB Ball Ctrl – Ball Porce2         2 bytes int(us)         0         3         0           875         BSOB Wire Ctrl – Search Porce2         2 bytes int(us)         0         3         0           875         BSOB Wire Ctrl – Search Porce2         2 bytes int(us)         0         3         0           875         BSOB Wire Ctrl – Search Porce2         2 bytes int(us)         0         3         0           875         BSOB Wire Ctrl – Search Porce2         2 byte int(us)         0         3         0           876         Schoduled Down Time Porce Porce Porce Porce Porce Po	867	Contact Search Threshold	2 bytes int(us)	0	255	0
869         BSOB Wire Ctrl – Base Time2         2 bytes int(us)         0         80         3           870         BSOB Wire Ctrl – Base Power1         2 bytes int(us)         0         255         3           871         BSOB Wire Ctrl – Base Power2         2 bytes int(us)         0         255         4           872         BSOB Wire Ctrl – Base Power2         2 bytes int(us)         0         255         3           873         BSOB Wire Ctrl – Base Power2         2 bytes int(us)         0         3         6           874         BSOB Ball Ctrl – Ball Power2         2 bytes int(us)         0         3         6           875         BSOB Wire Ctrl – Search Power2         2 bytes int(us)         0         32767         6           882         Scheduled Down Time Power2         8 byte float         0         999999999         9           883         Unscheduled Down Time Power2         8 byte float         0         999999999         9           884         Nonscheduled Down Time Power2         8 byte float         0         999999999         9           885         Standby Time Power2         8 byte float         0         999999999         9           886         Adv Pre-Trigger Mode Pre-Trigger Diversity P	868	BSOB Wire Ctrl – Base	2 bytes int(us)	0	80	5
870         BSOB Wire Ctrl – Base Power1         2 bytes int(us)         0         255         2 bytes int(us)           871         BSOB Wire Ctrl – Base Power2         2 bytes int(us)         0         255         4 bytes int(us)           872         BSOB Wire Ctrl – Base Porce1         2 bytes int(us)         0         255         3 bytes int(us)           873         BSOB Wire Ctrl – Base Porce2         2 bytes int(us)         0         3 control of the contro	869	BSOB Wire Ctrl – Base	2 bytes int(us)	0	80	5
871       BSOB Wire Ctrl – Base Power2       2 bytes int(us)       0       255       4         872       BSOB Wire Ctrl – Base Force1       2 bytes int(us)       0       255       3         873       BSOB Wire Ctrl – Base Force2       2 bytes int(us)       0       255       3         874       BSOB Ball Ctrl – Ball Formation Shape       2 bytes int(us)       0       3 2767       6         875       BSOB Wire Ctrl – Search Speed 2       2 bytes int(us)       0       32767       6         882       Scheduled Down Time Speed 2       8 byte float       0       999999999       6         883       Unscheduled Down Time Speed Float       0       9999999999       6         884       Nonscheduled Down Time Speed Float       0       9999999999       6         885       Standby Time Speed Standby Time Speed Float       0       999999999       6         886       Adv Pre-Trigger Mode Speed Speed Float       0       100       6         887       Rev Height Pre-Trigger Speed Speed Speed Speed Float       0       100       6         888       Rev Dist Pre-Trigger Time Speed Speed Speed Float       0       100       6         889       Rev HT2 Pre-Trigger Time Speed Speed Float       0	870	BSOB Wire Ctrl – Base	2 bytes int(us)	0	255	75
872       BSOB Wire Ctrl – Base Force1       2 bytes int(us)       0       255       3         873       BSOB Wire Ctrl – Base Force2       2 bytes int(us)       0       255       3         874       BSOB Ball Ctrl – Ball Formation Shape       2 bytes int(us)       0       3 2767       0         875       BSOB Wire Ctrl – Search Speed 2       2 bytes int(us)       0       32767       0         882       Scheduled Down Time Speed 2       8 byte float       0       999999999       0         883       Unscheduled Down Time Speed Spe	871	BSOB Wire Ctrl – Base	2 bytes int(us)	0	255	40
873       BSOB Wire Ctrl – Base Force2       2 bytes int(us)       0       255       3         874       BSOB Ball Ctrl – Ball Formation Shape       2 bytes int(us)       0       3 2767       0         875       BSOB Wire Ctrl – Search Speed 2       2 bytes int(us)       0       32767       0         882       Scheduled Down Time Speed 2       8 byte float       0       999999999       0         883       Unscheduled Down Time Speed S	872	BSOB Wire Ctrl – Base	2 bytes int(us)	0	255	30
874       BSOB Ball Ctrl – Ball Formation Shape       2 bytes int(us)       0       3       0         875       BSOB Wire Ctrl – Search Speed 2       2 bytes int(us)       0       32767       0         882       Scheduled Down Time Speed 2       8 byte float       0       999999999       0         883       Unscheduled Down Time Speed Speed Standby Time Speed Standby Time Speed Standby Time Speed S	873	BSOB Wire Ctrl – Base	2 bytes int(us)	0	255	15
875       BSOB Wire Ctrl – Search       2 bytes int(us)       0       32767       0         Speed 2       Scheduled Down Time       8 byte float       0       9999999999       0         883       Unscheduled Down Time       8 byte float       0       9999999999       0         884       Nonscheduled Down Time       8 byte float       0       9999999999       0         885       Standby Time       8 byte float       0       9999999999       0         886       Adv Pre-Trigger Mode       2 byte int (s)       0       1       0         887       Rev Height Pre-Trigger       2 byte int (s)       0       100       0         888       Rev Dist Pre-Trigger Time       2 byte int (s)       0       100       0         889       Rev HT2 Pre-Trigger Time       2 byte int (s)       0       100       0         890       Rev Dist2 Pre-Trigger Time       2 byte int (s)       0       100       0         891       Rev HT3 Pre-trigger Time       2 byte int (s)       0       100       0         892       Rev Dist3 Pre-Trigger       2 byte int (s)       0       100       0         893       Bump Pre-trigger       2 byte int (s)       0	874	BSOB Ball Ctrl – Ball	2 bytes int(us)	0	3	0
882         Scheduled Down Time         8 byte float         0         9999999999         0           883         Unscheduled Down Time         8 byte float         0         9999999999         0           884         Nonscheduled Down Time         8 byte float         0         9999999999         0           885         Standby Time         8 byte float         0         9999999999         0           886         Adv Pre-Trigger Mode         2 byte int (s)         0         1         0           887         Rev Height Pre-Trigger         2 byte int (s)         0         100         0           888         Rev Dist Pre-Trigger Time         2 byte int (s)         0         100         0           889         Rev HT2 Pre-Trigger Time         2 byte int (s)         0         100         0           890         Rev Dist2 Pre-Trigger         2 byte int (s)         0         100         0           891         Rev HT3 Pre-trigger Time         2 byte int (s)         0         100         0           892         Rev Dist3 Pre-Trigger         2 byte int (s)         0         100         0           894         Twist Fwd Pre-Trigger         2 byte int (s)         0         100         0 </td <td>875</td> <td>BSOB Wire Ctrl – Search</td> <td>2 bytes int(us)</td> <td>0</td> <td>32767</td> <td>0</td>	875	BSOB Wire Ctrl – Search	2 bytes int(us)	0	32767	0
883         Unscheduled Down Time         8 byte float         0         9999999999         0           884         Nonscheduled Down Time         8 byte float         0         9999999999         0           885         Standby Time         8 byte float         0         9999999999         0           886         Adv Pre-Trigger Mode         2 byte int (s)         0         1         0           887         Rev Height Pre-Trigger         2 byte int (s)         0         100         0           887         Rev Dist Pre-Trigger Time         2 byte int (s)         0         100         0           888         Rev Dist Pre-Trigger Time         2 byte int (s)         0         100         0           889         Rev HT2 Pre-Trigger Time         2 byte int (s)         0         100         0           890         Rev Dist2 Pre-Trigger Time         2 byte int (s)         0         100         0           891         Rev HT3 Pre-trigger Time         2 byte int (s)         0         100         0           892         Rev Dist3 Pre-Trigger         2 byte int (s)         0         100         0           894         Twist Fwd Pre-Trigger         2 byte int (s)         0         100         <	882	•	8 byte float	0	99999999	0
884       Nonscheduled Down Time       8 byte float       0       9999999999       0         885       Standby Time       8 byte float       0       9999999999       0         886       Adv Pre-Trigger Mode       2 byte int (s)       0       1       0         887       Rev Height Pre-Trigger       2 byte int (s)       0       100       0         888       Rev Dist Pre-Trigger Time       2 byte int (s)       0       100       0         889       Rev HT2 Pre-Trigger Time       2 byte int (s)       0       100       0         890       Rev Dist2 Pre-Trigger Time       2 byte int (s)       0       100       0         891       Rev HT3 Pre-trigger Time       2 byte int (s)       0       100       0         892       Rev Dist3 Pre-Trigger       2 byte int (s)       0       100       0         893       Bump Pre-trigger Time       2 byte int (s)       0       100       0         894       Twist Fwd Pre-Trigger       2 byte int (s)       0       100       0         895       Twist Rev Pre-Trigger       2 byte int (s)       0       100       0         896       Loop Top - Pre-Trigger       2 byte int (s)       0			•			0
885         Standby Time         8 byte float         0         9999999999         0           886         Adv Pre-Trigger Mode         2 byte int (s)         0         1         0           887         Rev Height Pre-Trigger         2 byte int (s)         0         100         0           887         Rev Dist Pre-Trigger Time         2 byte int (s)         0         100         0           888         Rev Dist Pre-Trigger Time         2 byte int (s)         0         100         0           890         Rev Dist2 Pre-Trigger         2 byte int (s)         0         100         0           891         Rev HT3 Pre-trigger Time         2 byte int (s)         0         100         0           892         Rev Dist3 Pre-Trigger         2 byte int (s)         0         100         0           893         Bump Pre-trigger Time         2 byte int (s)         0         100         0           894         Twist Fwd Pre-Trigger         2 byte int (s)         0         100         0           895         Twist Rev Pre-Trigger         2 byte int (s)         0         100         0           896         Loop Top – Pre-Trigger         2 byte int (s)         0         100         0 <td></td> <td></td> <td></td> <td></td> <td></td> <td>0</td>						0
886       Adv Pre-Trigger Mode       2 byte int (s)       0       1       0         887       Rev Height Pre-Trigger       2 byte int (s)       0       100       0         888       Rev Dist Pre-Trigger Time       2 byte int (s)       0       100       0         889       Rev HT2 Pre-Trigger Time       2 byte int (s)       0       100       0         890       Rev Dist2 Pre-Trigger       2 byte int (s)       0       100       0         891       Rev HT3 Pre-trigger Time       2 byte int (s)       0       100       0         892       Rev Dist3 Pre-Trigger       2 byte int (s)       0       100       0         893       Bump Pre-trigger Time       2 byte int (s)       0       100       0         894       Twist Fwd Pre-Trigger       2 byte int (s)       0       100       0         895       Twist Rev Pre-Trigger       2 byte int (s)       0       100       0         896       Loop Top – Pre-Trigger       2 byte int (s)       0       100       0         7 ime       0       100       0       0       0       0         896       Loop Top – Pre-Trigger       2 byte int (s)       0       100       0						0
887       Rev Height Pre-Trigger       2 byte int (s)       0       100       0         7 Time       100       100       0       100       0         888       Rev Dist Pre-Trigger Time       2 byte int (s)       0       100       0         890       Rev Dist2 Pre-Trigger       2 byte int (s)       0       100       0         891       Rev HT3 Pre-trigger Time       2 byte int (s)       0       100       0         892       Rev Dist3 Pre-Trigger       2 byte int (s)       0       100       0         893       Bump Pre-trigger Time       2 byte int (s)       0       100       0         894       Twist Fwd Pre-Trigger       2 byte int (s)       0       100       0         895       Twist Rev Pre-Trigger       2 byte int (s)       0       100       0         896       Loop Top – Pre-Trigger       2 byte int (s)       0       100       0         7 ime       100       0       0       0       0       0         896       Loop Top – Pre-Trigger       2 byte int (s)       0       100       0         896       Loop Top – Pre-Trigger       2 byte int (s)       0       100       0		•	•			0
Time  888 Rev Dist Pre-Trigger Time 2 byte int (s) 0 100 6  889 Rev HT2 Pre-Trigger Time 2 byte int (s) 0 100 6  890 Rev Dist2 Pre-Trigger 2 byte int (s) 0 100 6  time  891 Rev HT3 Pre-trigger Time 2 byte int (s) 0 100 6  892 Rev Dist3 Pre-Trigger 2 byte int (s) 0 100 6  Time  893 Bump Pre-trigger Time 2 byte int (s) 0 100 6  894 Twist Fwd Pre-Trigger 2 byte int (s) 0 100 6  Time  895 Twist Rev Pre-Trigger 2 byte int (s) 0 100 6  Time  896 Loop Top – Pre-Trigger 2 byte int (s) 0 100 6  Time  897 Trigger 2 byte int (s) 0 100 6  Time  898 Loop Top – Pre-Trigger 2 byte int (s) 0 100 6  Time  901 Traveling Card ID 32 bytes ASCII		<del>-</del> -				0
889         Rev HT2 Pre-Trigger Time         2 byte int (s)         0         100         0           890         Rev Dist2 Pre-Trigger         2 byte int (s)         0         100         0           891         Rev HT3 Pre-trigger Time         2 byte int (s)         0         100         0           892         Rev Dist3 Pre-Trigger         2 byte int (s)         0         100         0           893         Bump Pre-trigger Time         2 byte int (s)         0         100         0           894         Twist Fwd Pre-Trigger         2 byte int (s)         0         100         0           895         Twist Rev Pre-Trigger         2 byte int (s)         0         100         0           896         Loop Top – Pre-Trigger         2 byte int (s)         0         100         0           7 ime         7         2 byte int (s)         0         100         0           896         Loop Top – Pre-Trigger         2 byte int (s)         0         100         0           890         Time         -         -         -         -           901         Traveling Card ID         32 bytes ASCII         -         -         -           902         Unit ID <td></td> <td>5 55</td> <td>.,</td> <td></td> <td></td> <td></td>		5 55	.,			
890       Rev Dist2 Pre-Trigger time       2 byte int (s)       0       100       0         891       Rev HT3 Pre-trigger Time       2 byte int (s)       0       100       0         892       Rev Dist3 Pre-Trigger       2 byte int (s)       0       100       0         893       Bump Pre-trigger Time       2 byte int (s)       0       100       0         894       Twist Fwd Pre-Trigger       2 byte int (s)       0       100       0         Time       0       100       0       0         895       Twist Rev Pre-Trigger       2 byte int (s)       0       100       0         Time       0       100       0       0       0       0         896       Loop Top – Pre-Trigger       2 byte int (s)       0       100       0         901       Traveling Card ID       32 bytes ASCII       -       -       -         902       Unit ID       32 bytes ASCII       -       -       -       -	888	Rev Dist Pre-Trigger Time	2 byte int (s)	0	100	0
time  891 Rev HT3 Pre-trigger Time 2 byte int (s) 0 100 0  892 Rev Dist3 Pre-Trigger 2 byte int (s) 0 100 0  Time  893 Bump Pre-trigger Time 2 byte int (s) 0 100 0  894 Twist Fwd Pre-Trigger 2 byte int (s) 0 100 0  Time  895 Twist Rev Pre-Trigger 2 byte int (s) 0 100 0  Time  896 Loop Top – Pre-Trigger 2 byte int (s) 0 100 0  Time  901 Traveling Card ID 32 bytes ASCII	889	Rev HT2 Pre-Trigger Time	2 byte int (s)	0	100	0
892       Rev Dist3 Pre-Trigger Time       2 byte int (s)       0       100       0         893       Bump Pre-trigger Time       2 byte int (s)       0       100       0         894       Twist Fwd Pre-Trigger 2 byte int (s)       0       100       0         Time       0       100       0         895       Twist Rev Pre-Trigger 2 byte int (s)       0       100       0         Time       0       100       0         896       Loop Top – Pre-Trigger 7 byte int (s)       0       100       0         Time       0       100       0       0         901       Traveling Card ID       32 bytes ASCII       -       -       -         902       Unit ID       32 bytes ASCII       -       -       -       -	890		2 byte int (s)	0	100	0
Time  893 Bump Pre-trigger Time 2 byte int (s) 0 100 0  894 Twist Fwd Pre-Trigger 2 byte int (s) 0 100 0  Time  895 Twist Rev Pre-Trigger 2 byte int (s) 0 100 0  Time  896 Loop Top – Pre-Trigger 2 byte int (s) 0 100 0  Time  901 Traveling Card ID 32 bytes ASCII	891	Rev HT3 Pre-trigger Time	2 byte int (s)	0	100	0
893       Bump Pre-trigger Time       2 byte int (s)       0       100       0         894       Twist Fwd Pre-Trigger       2 byte int (s)       0       100       0         895       Twist Rev Pre-Trigger       2 byte int (s)       0       100       0         Time       0       100       0       0       0       0         896       Loop Top – Pre-Trigger       2 byte int (s)       0       100       0       0         Time       7       -       -       -       -       -       -       -         901       Traveling Card ID       32 bytes ASCII       -       -       -       -       -       -       -       -         902       Unit ID       32 bytes ASCII       -       -       -       -       -       -       -       -	892		2 byte int (s)	0	100	0
Time   September 2   September 3   September 4   Septemb	893	Bump Pre-trigger Time	2 byte int (s)	0	100	0
Time  896	894		2 byte int (s)	0	100	0
896       Loop Top – Pre-Trigger       2 byte int (s)       0       100       0         Time         901       Traveling Card ID       32 bytes ASCII       -       -       -         902       Unit ID       32 bytes ASCII       -       -       -	895		2 byte int (s)	0	100	0
901         Traveling Card ID         32 bytes ASCII         -         -         -         -           902         Unit ID         32 bytes ASCII         -         -         -         -	896	Loop Top – Pre-Trigger	2 byte int (s)	0	100	0
902 Unit ID 32 bytes ASCII	901		32 bytes ASCII	-	-	-
,		•	•	-	-	-
Onic Starting Time 32 bytes ASCII	903	Unit Starting Time	32 bytes ASCII	-	-	-
904 Unit Finishing Time 32 bytes ASCII	904	-		-	-	-

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905	Etorch Information	32 bytes ASCII	-	-	-	
906	Gold Wire Information	32 bytes ASCII	-	-	-	
907	Capillary Information	32 bytes ASCII	-	-	-	
908	Transducer Information	32 bytes ASCII	-	-	-	
909	Unit Status	1 byte int (us)	0	1	0	0: Partially bonded /
						not processed
						1: Fully bonded
911	eCheck by Host	1 byte int (us)	0	1	0	0: No
						1: Yes
912	eCheck Sampling unit	2 bytes int (us)	0	30000	0	
913	Allow Bonding upon	1 byte int (us)	1	2	0	0: No
	eCheck					1: Yes
						2: Comparing
914	eCheck Upon pgm	1 byte int (us)	0	1	0	0: No
	modification					1: Yes
915	Verify eCheck	1 byte int (us)	0	3	0	0: No echeck need
						1: eCheck as pgm
						modified
						2: eCheck during
						bonding
						3: Manual eCheck
						request by user
918	Statistics Last Reset Date	17 bytes ASCII	-	-	-	
919	PBS FB Ball Oversize	4 bytes int (s)	0	99999999	0	
	count					
920	PBS FB Ball Undersize	4 bytes int (s)	0	99999999	0	
	count					
921	PBS FB Missing Bond	4 bytes int (s)	0	99999999	0	
	count					
922	PBS FB Broken Wire count	4 bytes int (s)	0	99999999	0	
923	PBS FB Ball Placement	4 bytes int (s)	0	99999999	0	
	count					
924	PBS FB Ball Offset count	4 bytes int (s)	0	99999999	0	
925	PB Data Last Reset Date	17 bytes ASCII	-	-	-	
926	Wire Base Group List	2 bytes int (s)	0	60	0	
927	Wire Loop Mode List	1 bytes int (s)	0	52	0	
961	Barcode Manual Key-in	1 bytes int (us)	0	9	0	
	Item					
962	Scanned Item	1 bytes int (us)	0	9	0	
967	PBS FB Unit Pass	4 bytes int (s)	0	99999999	0	
970	Capillary Part Number	32 bytes ASCII	-	-	-	
980	Calibration Message	32 bytes ASCII	-	-	-	
981	LF bonded number in lot	2 bytes int (us)	0	34463	0	(For ASM IDEALine)
982	Magazine bonded number	2 bytes int (us)	0	34463	0	(For ASM IDEALine)
	in lot					
984	Processed unit number in	4 bytes int (us)	0	99999999	0	(For ASM IDEALine)
	lot					
985	Process Yield in lot	4 bytes float	0.0	100.0	0.0	(For ASM IDEALine)
986	Input Magazine Activity	1 bytes int (us)	0	1	1	•
987	Output Magazine Activity	1 bytes int (us)	0	1	1	
990	Strip Out Status	1 bytes int (us)	0	10	0	
991	Tool Install/Uninstall	32 bytes ASCII	-	-	-	
	Message					
992	User Login Name	32 bytes ASCII	-	-	-	(For ASM IDEALine)
						•

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1000	Magazine length	4 bytes int (s)	15000	26500	21500
1001	Magazine Width	4 bytes int (s)	8500	1200	5400
1002	Magazine level	4 bytes int (s)	0	50	40
1003	Magazine Base	4 bytes int (s)	1	10000	1250
1004	Magazine pitch	4 bytes int (s)	30	3000	250
1005	Magazine top	4 bytes int (s)	1	10000	250
1006	LF unit number	2 bytes int (us)	1	300	8
1007	LF width	4 bytes int (s)	787	8500	3500
1008	LF device pitch	4 bytes int (s)	150	6600	2650
1010	LF length	4 bytes int (s)	150	99999	21200
1011	Wire spool radius	4 bytes int (s)	1000	6000	2540
1012	Delta step size	2 bytes int (us)	1	125	10
1013	Indexer offset	2 bytes int (s)	-32000	32000	0
1014	Left indexer offset	2 bytes int (s)	-32670	32670	0
1015	Right indexer offset	2 bytes int (s)	-32670	32670	0
1016	Device name	32 bytes ASCII	-	-	-
1017	Device Scale	2 bytes int (s)	0	1	0
1050	Zoom lens delay	2 bytes int (s)	0	2000	0
1051	Row Column PR	1 bytes int (s)	0	1	0
1052	Local Lead	1 bytes int (s)	0	1	0
1053	Backup PR	1 bytes int (s)	0	4	0
1054	Auto index flag	1 bytes int (s)	0	1	0
1055	Ball detect	1 bytes int (s)	0	1	0
1056	Enable PR	1 bytes int (s)	0	1	0
1057	Number of Lead PR	1 bytes int (s)	0	2	2
1037	alignment	1 5 7 655 1116 (5)	Ü	_	_
1061	Efo unit type	1 bytes int (s)	0	1	1
1062	GAP wide warning voltage	2 bytes int (s)	0	9999	4500
1063	Trajectory profile tune	2 bytes int (s)	0	2	1
1064	Speed percentage	2 bytes int (s)	30	100	30
1065	1 <sup>st</sup> bond release force	2 bytes int (s)	0	1000	0
1066	2 <sup>nd</sup> bond release force	2 bytes int (s)	0	1000	0
1067	1 <sup>st</sup> Wire power offset	2 bytes int (s)	-127	127	0
1068	1 <sup>st</sup> Wire time offset	2 bytes int (s)	0	20	0
1069	1 <sup>st</sup> bond release power	2 bytes int (s)	0	255	0
1070	2 <sup>nd</sup> bond release power	2 bytes int (s)	0	255	0
1070	2 <sup>nd</sup> bond PT offset (BSOB	2 bytes int (s) 2 bytes int (s)	-100	100	28
10/1	Wire)	2 bytes int (s)	-100	100	20
1072	Lead Search Range	2 bytes int (s)	1	13	7
1072	Die Search Range	2 bytes int (s)	1	13	7
1075			1	13	,
1085	Software Name	32 bytes ASCII	-	_	_
	Software File Type	32 bytes ASCII 32 bytes ASCII	-	-	-
1087 1088	Software Install Status	•	-	-	-
	Terminal Message	32 bytes ASCII	0.100	15.00	0.881
1091	EFO Time	4 bytes float	0.100	15.00	
1097	1 <sup>st</sup> bond Amplitude Ratio	2 bytes int (us)	0	100	0
1098	1 <sup>st</sup> bond Y Scrub Delay	2 bytes int (us)	0	1000	0
1106	2 <sup>nd</sup> bond Scrub Z Pos	2 bytes int (us)	0	1000	0
1167	Total Wire Length Limit	8 bytes int (s)	0	99999	0
1150	Setting	Abote St. (A	0	00000	0
1168	Capillary Warning Limit	4 bytes int (s)	0	99999	0
4465	Setting	41	•	00000	•
1169	Capillary Stop Limit	4 bytes int (s)	0	99999	0
	Setting				

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1170	Wire Clamp Stop Limit	4 bytes int (s)	0	99999	0	
1171	Etorch Stop Limit	4 bytes int (s)	0	99999	0	
1172	Missing Ball Stop Limit	4 bytes int (s)	0	99999	0	
1173	Skip Die Total Stop Limit	4 bytes int (s)	0	99999	0	
1174	Skip Die Count Stop Limit	4 bytes int (s)	0	99999	0	
1175	Statistic hit limit event	2 bytes int (s)	0	99999999	0	1: Wire End Detected.
	type					2: Capillary count hit
						stop limit.
						3: Wire clamp count
						hit stop limit.
						4: Etorch count hit
						stop limit.
						<ol><li>Missing ball count</li></ol>
						hit warn limit.
						6. Skip die Total hit
						stop limit.
						7: Skip die count hit
						stop limit.
1400	UPH Gross(Search Result)	4 bytes f	0	99999999	0	
1402	MTBA(Search Result)	4 bytes f	0	99999999	0	
1403	MTBF(Search Result)	4 bytes f	0	99999999	0	
1404	Production Time(Search	4 bytes f	0	99999999	0	
	Result)		_			
1405	Idle Time (Search Result)	4 bytes f	0	99999999	0	
1406	Output(Search Result)	4 bytes int (us)	0	99999999	0	
1407	NSOP(Search Result)	4 bytes int (us)	0	99999999	0	
1408	Short Tail(Search Result)	4 bytes int (us)	0	99999999	0	
1409	Lead PR Fail(Search	4 bytes int (us)	0	99999999	0	
1.410	Result)	Albertan tot ( a)	0	0000000	0	
1410	Lead PR Tol(Search	4 bytes int (us)	0	99999999	0	
	Result)	A hadaa Sah Cas	0	0000000	0	
1411	Die PR Fail(Search Result)	4 bytes int (us)	0	99999999	0	
1412	Die PR Tol(Search Result)	4 bytes int (us)	0	99999999	0	
1413	VLL Fail(Search Result)	4 bytes int (us)	0	99999999	0	
1414	NSOL(Search Result)	4 bytes int (us)	0	99999999	0	
1500	Capillary count warning limit	4 bytes int (s)	0	99999999	0	
1501	Capillary count stop limit	4 bytes int (s)	0	99999999	0	



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The SVIDs 700 to 733 stands for 34 Loop Mode, These SVIDs will return the value either T (TRUE) or F(FALSE). True means that particular Loop mode is active and False means it is not active. Before retrieving these parameter values from bonder, host need to send ECID 399 with ECV=255

To monitor which all are the Adv.Loop mode are active

Step 1: Host need to send S2F15 with ECID = 399 and ECV =255

Then Equipment will acknowledge S2F16 Ack=0 to host

Step 2: Host need to send S1F3 with SVIDs 700 to 733

Then Eqpt will return either 0 or 1 for each SVID 700 to 733, depends on the which all are the loop mode active

For each Loop mode there are lot of Loop parameters and the SVIDs 740 to 767 stands for these parameters. For details of individual parameter please refer the Host manual document SVID section.

To monitor advanced loop parameters of one particular Loop Mode, first host need to send S2F15 with ECID 399 and ECV = Loop Mode (0 to 33). If host receives S2F16 Ack=0 from irebonder, host can send SVIDs 740 to 767 (one or more) to get the updated Loop parameter of that particular Loop Mode

eg

Host want to monitor Advanced Loop parameters (Loop Height, Reverse Height and Reverse Distance Angle) for Loop mode 5

Step 1: Host need to send S2F15 with ECID = 399 and ECV = 5

Then Equipment will acknowledge S2F16 Ack=0 to host

Step 2: Then Host need to send S1F3 with SVIDs 741, 742 and 744

(SVID 741 – Loop Height, SVID 742 – Reverse Height, SVID 744 – Rev Distance Angle)

Then Eqpt will return S1F4 with values for SVIDs 741, 742 and 744

Next Host want to monitor Advanced Loop parameters (Loop Height, Reverse Height and Reverse Distance Angle) for Loop mode 8

Step 1: Host need to send S2F15 with ECID = 399 and ECV = 8

Then Equipment will acknowledge S2F16 Ack=0 to host

Step 2: Then Host need to send S1F3 with SVIDs 741, 742 and 744

(SVID 741 – Loop Height, SVID 742 – Reverse Height, SVID 744 – Rev Distance Angle)

Then Eqpt will return S1F4 with values for SVIDs 741, 742 and 744

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### 8. REPORT ID

These are default reports defined by ASM. Some of them are linked as event report. User may redefine or delete them if necessary. The wire bonder is able to handle one hundred and one reports with RPTID ranges from 0 to 100. Please note that some are only valid if the Eagle Xtreme is connected to the ASM Cell Controller.

RPTID	Description	VID	Variable name	
0	General Equipment Info	0	Equipment Name	
		1	Software Revision	
1	Control State Change	5	Clock	
		6	ControlState	
2	Operator Command	16	Operator Command	
3	Previous Process State	5	Clock	
		7	Previous Process State	
4	Current Process State	5	Clock	
		8	Process State	
5	Pause Reason	15	Pause Reason	
6	Alarm Info	13	Alarm ID	
		14	Alarm Set	
		23	Alarm Clock	
		24	Secs_Alarmset	
7	Process Program	17	PPChangeName	
	Upload/Download info	18	PPChangeStatus	
8	Current Process Program Name	564	Current Lot PPID	
9	Current Time & Date	5	Clock	
10	Spool Info	12	Spool Start Time	
11	Spool Info	10	Spool Count Total	
12	Spool Info	5	Clock	
12	Spool 11110	9	Spool Count Actual	
13	Current Process Program Info	203	Number of wire	
13	Current Process Program Inio	203	Number of reference	
		261	Device name	
14	Current Process Program's Bond	205	Feed Power	
	Power Control	207	Standby Power	
	1 OWEL CONTROL	217	Standby Power2	
		245	Power Factor	
		252	Power Base 1	
		253	Power Base 2	
15	Current Process Program's Bond	214	Contact Force 1	
13	Force Control	215	Contact Force 2	
	Torce condition	250	Force Base 1	
		251	Force Base 2	
16	Current Process Program's Bond	216	Power Delay 1	
10	Time Control	218	Power Delay 2	
	Time Condo	216	Force Factor	
		248	Time Base 1	
		249	Time Base 2	
17	Current Process Program's Step	256	Number of Rows	
1/	& Repeat Info	257	Number of Columns	
	a vehear tillo	257 258	Step & Repeat Flag	
10	Current Operator Info			
18	Current Operator Info	265 560	Operator ID	
		560 561	Current Product ID	
		561	Current Product ID	

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RPTID	Description	VID	Variable name
.9	Process Statistics	265	Operator ID
		281 - 300	Statistical Information
		306	Number of Failure
		560	Cur Lot ID
20	Lot Transition Information	261	Device Name
		265	Operator ID
		302	ACK Code
		560	Current Lot ID
21	SMI Transition Report	272	SMI OPTION
	·	560	Current Lot ID
.2	Process Info	320	Processed Quantity
		321	Rejected Quantity
		322	Yield
3	Semi E10 Statistics	30	Performance Data Last Reset
		303	MTBA
		304	Num Of Assists
		305	MTBF
		306	Num Of Failures
		307	Total Idle Time
		308	Productive Time
		309	Down Time
!4	Equipment Status	323	Equipment State
5	Lot ID	560	Current Lot ID
. <u>5</u> .6	Lot Information	560	Current Lot ID
.0	Lot Information	564	Current Lot PPID
		569	Current Lot Status
7	Strip Map Defect codes	470 – 533	Strip Map Defect Codes
./	Strip Map Defect codes	571	Strip process status
10	Lot Info & Personal Info	561	Current Lot Product ID
28	Lot Inio & Personal Inio	561 564	Current Lot PPID
0	Machine ID and DM date	570	Personal ID
9	Machine ID and PM date	25	Machine ID
		26	Last PM Date
0	Constation of Heit Boarding	27	Installation Date
0	Completion of Unit Bonding	281	Number of Unit bonded
5	Soft Start Activation	35	Soft Start Activation
7	Update Lot Mgmt status	574	Cell Controller Lot Mgmt Status
8	Update strip mgmt option	575	Strip map option
		576	Recipe Target
		577	Host Recipe Extension
		581	Stripmap Error Reg Option
0	Last Equipment Constant Changed	372	ECChangeStatus
ł1	Lead frame Indexing-in	37	Barcode String(2D label)
	-	470	Defect Out Strip Id(Input Magazine 1D Label)
12	Lead Frame Indexing-out	37	Barcode String(2D label)
	<u> </u>	470	Defect Out Strip Id(Output Magazine 1D Label)
13	Magazine Management	560	Lot ID
	(For ASM IDEALine only)	578	Magazine ID
		589	Magazine Activity
		580	Magazine Location
		265	Operator ID

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		560	Lot ID
		562	Lot Quantity
46	Lot Finish Information	265	Operator ID
		320	Processed Quantity
		321	Rejected Quantity
		560	Lot ID
		562	Lot Quantity
47	Lot Start – TI	265	Operator ID
		560	Lot ID
		562	Lot Quantity
		565	Lot Gold Wire
		566	Lot Capillary
		567	Lot Window Clamp
		568	Lot Top Plate
48	Lot End – TI	265	Operator ID
		560	Lot ID
		562	Lot Quantity
		565	Lot Gold Wire
		566	Lot Capillary
		567	Lot Window Clamp
		568	Lot Top Plate
51	Change in control parameter	195	VLL Lead Width Tolerance
		196	VLL Search Delay
		197	WCL Open Force
		198	WCL Close Force
		241	Die Alignment Tolerance
		242	Lead Alignment Tolerance
		245	Power Factor
		246	Force Factor
		247	Pre Heat Time
		248	Bond Time 1
		249	Bond Time 2
		250	Bond Force 1
		251	Bond Force 2
		252	Bond Power 1
		253	Bond Power 2
		255	Lead Tool Offset
		259	PR Search Delay for Die
		260	PR search delay for Lead
		273	Pre Heat All Units
		866	Contact Search Threshold 1
		867	Contact Search Threshold 2
52	Change in Global Parameter	207	Standby Power 1
	-	214	Contact Force 1
		215	Contact Force 2
		216	Power Delay 1
		217	Standby Power 2
		218	Power Delay 2
		236	Contact Time1
		237	Contact Time 2
		238	Contact Power 1
		239	Contact Power 2
53	Change in Wire Parameter	36	Type of Wire Param modified
54	Change in EFO Parameter	208	Fire Level Factor
54	Sharige in El O l'alametei	_50	Tail Length

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		224	FFO FAD Blade growther
		224	EFO FAB Block number
		226	Wire Size – EFO Parameter
		227	FAB size – EFO parameter
		274	EFO Current FAB Block #0
		275	EFO Current FAB Block #1
		276	EFO – Wire Type
		277	EFO Control Mode
		278	EFO Enable Dual FAB
		279	Auto Calc EFO Time
		1091	EFO Time
56	Change in Capillary	283	Capillary Count
57	Wire Turn count Info	285	Wire Turn Count
58	Barcode Scan	37	Barcode String
		962	Scanned Item
59	Change in REF RECORD	-	
61	Assembly Stage Notification	801	ASN Username
	(ASN)	802	ASN User-ID
	(only for ASM Internal QA)	803	ASN Stage
		804	ASN Substage
		805	ASN Activity
		806	ASN Timestamp
62	ASN – User Name request	802	ASN User-ID
	(only for ASM Internal QA)		
65	Wirebonder Software Revision	826	Software Version
	Information	827	Software Ref Number
		828	Site in Software Version
		829	WH Software version
		830	PR software version
		831	BQM version
		832	Servo Version
		833	Heater Version
		834	Software Date & Time
		835	Software Rev Number
67	G84 – Stripmap data	470	Strip ID (indexing out)
	(only for ASM IDEALine)	571	Strip process status – G84
	(0, 0 0 0 0 0,	781	Origin Location of strip – G84
		782	No of rows in strip – G84
		783	No. of columns in strip – G84
		784	Cell Status in strip – G84
		785	Defect Code – G84
68	Calibration starts	980	Calibration message
69	Calibration finishes	980	Calibration message
71	Barcode – Unit start report	265	Operator ID
, -	barcode offic start report	901	Traveling card ID
		902	Unit ID
		903	Unit Starting Time
		906	Gold wire information
		906	Capillary Information
		907	Transducer Information
72	Parcodo Unit finish ronart		
72	Barcode – Unit finish report	265	Operator ID
		901	Traveling card ID
		902	Unit ID
		904	Unit Finishing Time
		906	Gold wire information
		907	Capillary Information

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		908	Transducer Information
		909	Unit Status
73	Manual key in barcode	49	Barcode String
		961	Barcode manual key it item
76	1st Bond Scrub Modification	361	1st Bond Scrub Control
		362	1 <sup>st</sup> Bond Scrub Direction
		363	1 <sup>st</sup> Bond Scrub Force
		364	1 <sup>st</sup> Bond Scrub Power
77	2 <sup>nd</sup> Bond Scrub Modification	365	2 <sup>nd</sup> Bond Scrub Control
		366	2 <sup>nd</sup> Bond Scrub Direction
		367	2 <sup>nd</sup> Bond Scrub Force
		368	2 <sup>nd</sup> Bond Scrub Power
78	BSOB Ctrl Modification	840	BSOB Ctrl- Ball Formation direction
		841	BSOB Ctrl-Ball Thickness
		842	BSOB Ctrl - Tail Length
		843	BSOB Ctrl – Time Base1
		844	BSOB Ctrl – Time Base2
		845	BSOB CTRL – Power Base1
		846	BSOB Ctrl – Power Base2
		847	BSOB Ctrl – Force Base 1
		848	BSOB Ctrl-Force Base2
		849	BSOB Ctrl – Standby Power1
		850	BSOB Ctrl – Standby Power2
		851	BSOB Ctrl – Contact Time 1
		852	BSOB Ctrl – Contact Time 2
		853	BSOB Ctrl - Contact Power1
		854	BSOB Ctrl – Contact Power 2
		855	BSOB Ctrl – Contact Force 1
		856	BSOB Ctrl –Contact Force 2
		863	BSOB Ctrl – Loop Base
		864	BSOB Ctrl – Ball Offset
		868	BSOB Wire- Time Base 1
		869	BSOB Wire- Time Base 2
		870	BSOB Wire- Power Base 1
		871	BSOB Wire- Power Base 2
		872	BSOB Wire- Force Base 1
		873	BSOB Wire- Force Base 2
79	Twin Ball BSOB Ctrl	857	Twin Ball BSOB Ctrl – Time Base1
		858	Twin Ball BSOB Ctrl – Time Base2
		859	Twin Ball BSOB Ctrl –Power Base1
		860	Twin Ball BSOB Ctrl – Power Base 2
		861	Twin Ball BSOB Ctrl – Force Base1
		862	Twin Ball BSOB Ctrl – Force Base2
86	Verify eCheck	915	Verify eCheck
87	eCheck flag status	911	eCheck by Host
		912	eCheck Sampling unit
		913	Allow Bonding upon eCheck
		914	eCheck Upon pgm modification
89	User Login information	897	User Login ID
	-	898	Login Password
90	Active Group information	564	Current lot PPID
-	<del>-</del>	926	Wire Base Group List
		927	Wire Loop Mode List
91	Bond Parameter Information	926	Wire Base Group
	Zona i arameter imormation	930	Bond Time1

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		931	Bond Time2
		932	Bond Power1
		933	Bond Power2
		934	Bond Force1
		935	Bond Force2
		936	Standby Power 1
		937	Standby Power2
		939	Power Delay 2
		940	Contact Time1
		941	Contact Time2
		942	Contact Power1
		943	Contact Power2
		944	Contact Force1
		945	Contact Force2
92	Loop Parameter Information	927	Wire Loop Mode List
		952	Loop Height
		953	Reserve Height
		954	Reserve Distance
		955	Reserve Distance Angle
		956	Loop Height Correction
		958	Span Length
		959	Span Length Correction
93	Input Magazine Activity	986	Input Magazine Activity
95	Current PPID Dos Name	975	Current PPID Dos Name
96	Output Magazine Activity	987	Output Magazine Activity
104	System Software Status	1085	Software Name
		1086	Software File Type
		1087	Software Install Status
105	Clear Terminal Message	1088	Terminal Message
111	Statistic data hit limit	1175	Statistic data hit limit event type
117	Capillary count hit warning limit	1500	Capillary count warning limit
118	Capillary count hit stop limit	1501	Capillary count stop limit
120	Strip id inform	470	Defect Out Strip ID
121	QA finishing	470	Defect Out Strip ID
122	User Login	992	User Login Name
125	Retrieve Statistic(TI)	1400	UPH Gross(Search result)
		1402	MTBA(Search result)
		1403	MTBF(Search result)
		1404	Production Time(Search result)
		1405	Idle Time(Search result)
		1406	Output(Search result)
		1407	NSOP(Search result)
		1408	Short Tail(Search result)
		1409	Lead PR fail(Search result)
		1410	Lead PR Tol(Search result)
		1411	Die PR fail(Search result)
		1412	Die PR Tol(Search result)
		1413	VLL Fail(Search result)
		1414	NSOL(Search result)
	Upload 2D label	37	Barcode String(2D label)
150		470	Defect Out Strip Id(2D label)
			5 1 5 1 (15 1 1 °)
150	Input Magazine Unload	37	Barcode String(1D label)
	Input Magazine Unload		Barcode String(1D label) Defect Out Strip Id(1D label) Input Magazine Activity

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470	Defect Out Strip Id(1D label)
987	Output Magazine Activity

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### 9. EVENT ID

The following list contains of events defined in Eagle Xtreme Gold Wire Bonder and the default reports linked to each of them. User may modify and re-link the reports. Please note that some events are not generated by the equipment but are provided to the Host to query important data.

Event ID	Description	Reports Linked	Trigger
0	Enable SECS or Power On	0	Equipment
1	Equipment OFF-LINE	1	Equipment
2	Operator Command	2	Equipment
3	Previous Process State	3	Host
4	Process Stopped	3,4	Host
5	Process State Change	3, 4, 5	Equipment
6	Alarm Detected	6	Equipment
7	Previous Process State	4	Equipment
8	Process Program Change	7	Equipment
9	Process Program Selected	8	Equipment
10	Current Time	9	Host
20	Statistical Data Collection	19,23	Equipment
22	Equipment State Changed	24	Equipment
23	Lot Info	26	Equipment
25	Defect Out Strip Status	27	Equipment
26	Lot Info	28	Equipment
27	Production info	22	Equipment
28	Inst Date, Machine ID	29	Host
29	Rej quantity	22,26	Host
30	Processed Quantity	22,25	Host
31	Soft Start Timeout	1	Equipment
33	Unit Bond completion	30	Equipment
36	Soft Start Activation	35	Equipment
37	CC Lot Mgmt Status	37	Equipment
38	Strip Mgmt status	38	Equipment
41	Lead frame index-in	41	Equipment
42	Lead frame Index-out	42	Equipment
43	Lot Mgmt Status	43	Equipment
45	Lot Start Information	45	Equipment
46	Lot Finish Information	46	Equipment
47	Lot Start for TI	47	Equipment
48	Lot End for TI	48	Equipment
51	Change in Control	51	Equipment
	Parameter		
52	Change in Global	52	Equipment
	Parameter		
53	Change in Wire Parameter	53	Equipment
54	Change in EFO Parameter	54	Equipment
56	Replace Capillary	56	Equipment
57	Wire usage Info	57	Equipment
58	Auto Save Finished	8	Equipment
59	Change in REF RECORD	59	Equipment
60	Barcode Event	58	Equipment
61	Assembly Stage Notification	61	Equipment
62	ASN – UserID	62	Equipment

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65	Wirebonder Software Info	65	Equipment
67	G84- Stripmap Data	67	Equipment
68	Calibration starts	68	Equipment
69	Calibration finishes	69	Equipment
71	Barcode – Unit start event	71	Equipment
72	Barcode – Unit finish event	72	Equipment
73	Barcode manually key in	73	Equipment
76	1 <sup>st</sup> Bond Scrub	76	Equipment
	Modification		
77	2 <sup>nd</sup> Bond Scrub	77	Equipment
	Modification		
78	BSOB Ctrl Modification	78	Equipment
79	Twin Ball BSOB Ctrl	79	Equipment
	Modification		<u> </u>
80	NSOP or NSOL increment	(no RPTID)	Equipment
86	Verify eCheck	86	Equipment
87	eCheck flag Status	87	Equipment
89	User Login information	89	Equipment
90	Active Group information	90	Equipment
91	Bond Parameter	91	Equipment
	Information		
92	Loop Parameter	92	Equipment
	Information		
93	Input Magazine Activity	93	Equipment
95	Current PPID Dos Name	95	Equipment
96	Output Magazine Activity	96	Equipment
97	Lot Ready	8	Equipment
104	Host Install Software	104	Equipment
	Complete		
105	MC Ready To Backup	104	Equipment
106	Host Restore Data	104	Equipment
107	System Shutdown	24	Equipment
108	System Restart	24	Equipment
109	System Initialization	24	Equipment
110	Clear Terminal Message	105	Equipment
111	Statistic data hit limit	111	Equipment
117	Capillary count hit warning limit	117	Equipment
118	Capillary count hit stop	118	Equipment
120	Strip id inform	120	Equipment
121	QA Finishing	121	Equipment
122	User Login	122	Equipment
125	Statistic Retrieve(TI)	125	Equipment
150	Leadframe 2D Label Upload	150	Equipment
151	Input Magazine Unload	151	Equipment
152	Output Magazine Unload	152	Equipment
	- aspatagazine onioad	1	_qa.pc.ic

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### 10. REMOTE COMMAND CODE

#### **Remote Commands Recognized (S2,F21)**

Remote Command Codes, which are defined in Eagle Xtreme Gold Wire Bonder and used in S2F41 messages, are as follows. These are accepted only if the wire bonder is under remote control state.

Remote Command	<b>Command Code</b>	Valid Processing States
START BOND	13	IDLE, SETUP
STOP BOND	24 or 109	EXECUTING, PAUSE
PAUSE	33 or 117	EXECUTING, PAUSE, IDLE, SETUP
RESUME	35 or 111	IDLE, SETUP
SOFT START	37 or 118	IDLE,SETUP
To Upload wire record data file	50 or 119	IDLE,SETUP,PAUSE (Should have a valid
(WIRE_RCD.DAT) **		bond program in Memory)
To Upload Bond point	51 or 120	IDLE,SETUP,PAUSE (Should have a valid
coordinate file (BONDPT.TXT)		bond program in Memory)
**		
To upload Reference record	52 or 122	IDLE,SETUP,PAUSE (Should have a valid
data file (REF_RCD.DAT) **		bond program in Memory)
REQ CHANGE LOT	100	IDLE, SETUP
(Only for ASM IDEALINE)		
Reset Production count	106	IDLE,SETUP,PAUSE
(Only for ASM IDEALINE)		
Reset EPD (Equipment	107	IDLE,SETUP,PAUSE
Performance Data)		
Pause after current strip	108	EXECUTING, PAUSE
bonding (only for ASM		
IDEALine)	110	EVECUTING DALICE
Pause after current wire bonding (only for ASM	110	EXECUTING, PAUSE
bonding (only for ASM IDEALine)		
Reset Capillary and False-alarm	114	IDLE,SETUP,PAUSE
(only for ASM IDEALINE)	117	IDLL,SLTOF,FAOSL
AUTO SAVE BOND PROGRAM	121	IDLE,SETUP,PAUSE
Reset Statistics count	133	IDLE,SETUP,PAUSE
Upload Wire Layout Data	134	IDLE,SETUP,PAUSE
Upload loop data file	135	IDLE,SETUP,PAUSE
Reset PBI data	136	IDLE,SETUP,PAUSE
Reset statistics Tools usage	137	IDLE,SETUP,PAUSE
reset statistics 100is usage	13/	IDLL, SLIUP, PAUSE

<sup>\*\*</sup> Note: When Upload REF\_RCD.DAT or WIRE\_RCD.DAT or BONDPT.TXT using the corresponding remote command, the file will be uploaded using S7F1, S7F2, S7F3 and S7F4

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### **Host Commands Accepted (S2,F41)**

Description	<a host<br="">Command&gt;</a>	<a parameters=""></a>	Valid Processing States
Stop the bonding	"STOP"		EXECUTING, PAUSE
Pause the bonding	"PAUSE"		EXECUTING, PAUSE, IDLE, SETUP
Start the bonding	"START"		IDLE, SETUP
Resume the bonding	"RESUME"		IDLE, SETUP
Soft Start Bonding	"SOFTSTART"		IDLE,SETUP
Change the device	"PP_SELECT"	1. PPID <a "filename.wb"=""> 2. PROMPT <b00lean f="" t=""></b00lean></a>	IDLE, SETUP
Enable Lot Mgmt (For IDEALine only)	"ELM"	13. CPNAME <a "cclotmanagement"=""> CPVALUE <a "disable"="" "enable"=""></a></a>	IDLE, SETUP
CC Settings	"CCSETTING"	1. CPNAME <a "stripmanagement"="">     CPVALUE <a "disable"="" "enable"=""></a></a>	IDLE, SETUP
(For IDEALine only)		14. CPNAME <a "recipedestination"<="" td=""><td></td></a>	
		> CPVALUE <u1 0,="" 1="" 2="" or=""> 0:HDDonly, 1:RAMonly, 2:HDD&amp;RAM</u1>	
		15. CPNAME <a "hostrecipeext"=""> CPVALUE <a "disable"="" "enable"=""></a></a>	
Magazine Management	"UNLOADMAGAZIN E"	1. CPNAME <a "location"=""> CPVALUE <a "input"="" "output"=""></a></a>	All States
(For IDEALine only)		2. CPNAME <a "lotid"=""> CPVALUE <a 32="" bytes=""></a></a>	
		3. CPNAME <a "stripid"=""> CPVALUE <a 32="" bytes=""></a></a>	
		16. CPNAME <a "condition"=""> CPVALUE <a 32="" bytes"=""></a></a>	
Reset Lot Information (For IDEALine only)	"RESETLOTINFO"	17. CPNAME <a "lotid"=""> CPVALUE <a 32="" bytes=""></a></a>	IDLE , SETUP
Assembly Stage Notification (For ASM in-house	"ASN"	1. CPNAME <a "stage"=""> CPVALUE <a></a></a>	IDLE, SETUP
usage)		2. CPNAME <a "substage"=""> CPVALUE <a></a></a>	
		3. CPNAME <a "activity"=""> CPVALUE <a 32="" bytes=""></a></a>	
		18. CPNAME <a "timestamp"=""> CPVALUE <a></a></a>	
StripID Verify Command	"STRIPRECIP ECOMMAND"	1. CPNAME <a "stripid"=""> CPVALUE <a></a></a>	
		2. CPNAME <a "recipeid"=""> CPVALUE <a></a></a>	
Central Password	"APPLYSECUR ITY"	1. CPNAME <a "fullpath"=""> CPVALUE <a></a></a>	Using Share folder download password file from host side
Retrieve Statistic	"COLLECTINFO"		All States
Leadframe Resume	"LF_RESUMECMD"	CPNAME <a "lf_resumecmd"=""> CPVALUE <a "0"="" "1"=""></a></a>	All States

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Magazine Resume	"MAG_RESUMECM	CPNAME <a "mag_resumecmd"=""></a>	All States
	D"	CPVALUE <a "0"="" "1"=""></a>	

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### 11. ALARM ID

Alarm Code Byte stands for

- 0- Not Used
- 1- Personal Safety
- 2- Equipment Safety
- 3- Parameter Control warning
- 4- Parameter Control error
- 5- Irrecoverable error
- 6- Equipment Status warning
- 7- Attention Flag
- 8- Data Integrity

Alarm ID	Alarm Code Byte	Description
0	0	Net Comm Error;
1	5	Motor board Error;
2	6	Window Clamp Error;
3	6	Kicker Error;
4	6	Ejector Error;
5	6	Indexer Position Error;
6	6	Input Sensor Error;
7	6	Output Sensor Error;
8	3	No Vacuum;
9	4	No Pressure;
10	7	No Leadframe Input;
11	7	Input Magazine Empty;
12	7	No Output mag or mag orient err;
13	7	Platform Full;
14	6	WH Wait For Input;
15	7	WH Input Hit Limit;
16	6	WH Wait For Output;
17	7	WH Output Hit Limit;
21	4	1 <sup>st</sup> PR Not Loaded;
22	4	2nd PR Not Loaded;
23	6	PR Lead Tol Failure;
24	6	PR Die Tol Failure;
25	6	Manual Align Lead Tol Failure;
26	7	Manual Align Die Tol Failure;
27	7	PR Lead Quality Rejected;
28	7	PR Die Quality Rejected;
29	7	This unit not taught;
30	7	Invalid Reference;
31	6	PR Setup Err;
32	<b>]</b> 6	Index PR not taught;
33	6	Index PR Fail;
34	6	Index PR Not Loaded;
41	6	Contact Search Failed;
42	6	Contact Search 1 Failed;
43	6	Contact Search 2 Failed;
44	7	1 <sup>st</sup> Bond Non Stick;

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45	7	2 <sup>nd</sup> Bond Non Stick;
46	7	Tail too Short;
47	7	Missing Ball;
48	6	Double Bond;
49	6	EFO No High Voltage;
50	6	EFO No Current;
51	6	EFO Gap Wide;
52	6	EFO Short Tail;
60	6	Wire End Warning;
61	6	Wire Used Up Replace;
62	6	BND WH Comm Err;
63	6	BND TCH Comm Err;
64	6	BND EFO Comm Err;
65	6	BND buf overflow;
66	6	BND comm number err;
67	6	BND not req msg;
68	6	BND no msg;
69	6	BND invalid Argument;
70	6	BND oper failed;
71	6	BND timeout:
72	6	BND si Timeout;
73	6	B18 This Unit Is Bonded:
74	6	Missed sync signal;
75	6	Heater Open Circuit;
76	6	B23 Ctact At Srch Ht;
77	6	B24 Check 2 <sup>nd</sup> Ctact Lvl;
78	6	BQM Calibration Failure;
79	6	BQM Timeout;
80	6	Capillary Hit Stop Limit;
81	6	Temperature is not Even;
82	6	No Program exist;
83	6	This Unit Not Taught;
84	6	Warning EFO Gap Wide;
85	6	Warning EFO Short Tail;
86	6	Ball Detect Disabled;
87	6	Stick Detect Disable;
88	6	Ball Non Stick;
89	6	Capillary Hit Warn Limit;
100	6	Other Error;
101	6	Process Program Not Found;
110	6	VLL Pos Out Of Tolerance;
111	6	VLL Load Lead Fail;
112	3	VLL Search Lead Fail;
113	3	VLL Cannot Find Lead Tip;
114	3	VLL Load Angle Too Large;
115	4	VLL No Signal Or Timeout;
116	4	VLL Set Scan Mode Fail;
117	3	VLL Cannot Find Lead Edge;
118	3	VLL Out of Lead Width Tolerance;
119	3	VLL Check Clearance Fail;
120	3	VLL Load Template Out of Range;
140	<u> </u>	VLL Load Template Out of Hange,

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404		\(\( \) \( \
121	3	VLL Load Bin Lead Fail;
122	3	VLL Tip Offset Too Large; VLL Grab Image Error;
123 124	3	VLL Grab image Error; VLL Unknown Error;
130	3	Postbond success;
131	3	PB FB Ball Oversize;
132	3	PB FB Ball Undersize;
133	3	PB FB Exceed ball Place;
134	3	PB FB missing Bond;
135	7	PB FB Ball Broken Wire;
136	7	PB FB Exceed balls Offset;
137	6	PB FB Exceed balls Distance;
138	6	PB FB Fail 2 Wire Dist;
139	6	PB FB Fail Ball Roundness;
180	6	PB SB Weld Missing Bond;
181	6	PB SB Broken Wire;
182	6	PB SB Fail Weld Clearance;
183	6	PB SB Exceed Weld Width;
184	6	PB SB Weld Accuracy;
185	6	PB SB Weld Width Undersize;
186	6	PB SB Weld Length Oversize;
187	6	PB SB Weld Length Undersize;
188	6	Strip Map Dimension Error;
230	3	PB WT Missing or Sway Wire;
231	6	BFM Error;
232	6	Wire loop error;
233	6	EFO Error;
234	6	Calibration Memory Alloc failure;
235	6	Illegal LF Adjust Error;
236	6	No unit on bond side;
237	6	LF Adjust offset out of range;
238	6	LF Adjust not finished;
239	6	LF Position calculation error;
240	6	Current bond head inactive;
241	6	WH Cover not closed;
242	6	PB Bond Tip offset Error;
260	6	Host Reject LF 2D Label;
261	6	Upload LF 2D Label Fail;
262	6	Read LF 2D Label Fail;
263	6	Host Reject Mag 1D Label;
264	6	Upload Mag 1D Label Fail;
265	6	Read Input Mag 1D Label Fail;
266	6	Read Output Mag 1D Label Fail;

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### 12. PROTOCOL BASED ON SECS I

### 12.1. Physical Link

#### **Electrical Interface**

The connection includes a serial interface according to **EIA** Standard **RS-232-C** for interface Type **E**, full duplex communication.

#### Connector

The standard 25-pin connector described in **ISO 2110-1980** should be used. The screw locks should be contained.

#### Signal Pins

Pins on connector have functions and defined in Table 1

Table 1
Signal Connections

Pin Num	RS-232C Circuit	Description
1	AA	Shield
2	BA	Data From Equipment
3	BB	Data To Equipment
7	AB	Signal Ground

#### Data rate

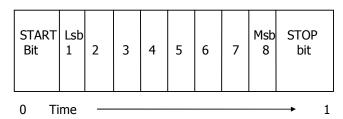
The supported data rates on signal pins are 19200, 9600, 4800, 2400, 1200, 300 baud.

NB: Though the AB339E does display higher baud rates (up to 115200) and can communicate at these higher speeds, the maximum throughput is limited by how busy the machine CPU is at the time of communications.

### 12.2. Character Structure

Data is transmitted or received in a serial bit stream of 10 bits per character at one of the specified data rates.

Start bit1 bit
Data bit8 bits ( = 1 byte )
Stop bit 1 bit



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### 12.3. Block Transfer Protocol

#### Handshake Bytes

Name	Code	Function
	( <i>b8 b7 b1</i> )	
ENQ	00000101	Request to send
EOT	00000100	Ready to receive
ACK	00000110	Correct reception
NAK	00010101	Incorrect reception

#### Header Structure in a Block

	8	7 6 5 4 3 2 1	
1	R upper device		
2		lower device	
3	<b>W</b> upper message		Stream ID
4	lower message		Function ID
5	<b>E</b> upper block num		
6		lower block num	
7	system bytes		
8	system bytes		
9	system bytes		
10	system bytes		

**R -bit --** Reverse Bit signifies the direction of a message. The R-bit is set to 0 for messages to the equipment and set to 1 for messages to the host. The R-bit is included in the header so that the direction of the message is contained in every block.

**W-bit** -- Wait Bit is used to indicate that the sender of a primary message expects a reply. A value of one in W-bit means that a reply is expected. A value of zero in the W-bit means no reply is expected. The W-bit must be set to zero in all secondary messages. For multi-block messages, the sender must ensure that the W-bit is the same in every block of the message. In ASMGEM all primary messages must expect a reply.

**E-bit** -- End bit is used to determine if a block is the last block of a message. A value of one in the E-bit means that the block is the last block. A value of zero means that more blocks are to follow.

**Block Number** -- A message sent as more than one block is called a multi-block message. The first block number is given a block number of one, and the block number is incremented by one for each subsequent block until the entire message is sent.

Multi-block message are supported when ASMGEM is receiver or sender.

**System Byte --** The secondary message is a copy of the data sent from the host. and is transmitted to the host when **W-bit** is 1.

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### 12.4. Message Protocol

#### Message Blocking

Message blocking is the division of the message data into blocks to be sent to the **Block Transfer Protocol**. Equipment fill all blocks of a multi-block message, except possibly the last block, with maximum 254 bytes.

#### Message Length

The maximum data length in a single block of a message is 244 bytes. The maximum number of of block is 256, and so the maximum data length allowed in one message is 244 x 256.

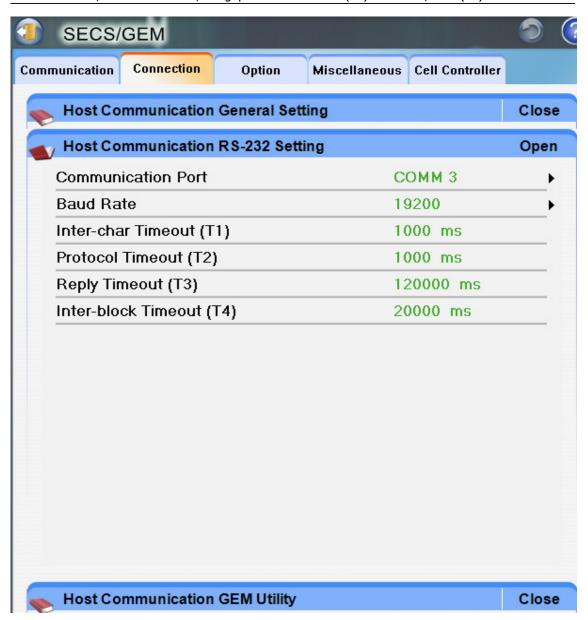
#### Header

The message protocol must establish the header in each block of the message according to 12.3.

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#### **Protocol Parameters**

Symbol	Description	Range	Default
BAUD	Baud Rate	300 -115200	19200
DEVID	Device ID	0 – 32767	0
T1	Inter-character Timeout	0.1 - 10 sec	1 sec
T2	Protocol Timeout	0.2 - 25 sec	3 sec
T3	Reply Timeout	1 – 120 sec	30 sec
T4	Inter-block Timeout	1 – 120 sec	10 sec
RTY	(Retry Limit	1 – 31	3

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These parameters can be adjusted on the Eagle Xtreme through the SECS/GEM Configuration page found in the [Configuration] [Factory Automation][SECS/GEM Communication] menu. The changes become effective when the operator exits the Configuration page. Please note that the timing parameters are in ms.

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# 13. GEM Compliance Statement

AB339E GEM Compliance Statement (as at 28 Aug. 00)

GEM COMPLIANCE STATEMENT		
FUNDAMENTAL GEM REQUIREMENTS	IMPLEMENTED	GEM-COMPLIANT
State Models	☑ Yes ☐ No	☑ Yes
Equipment Processing States	☑ Yes □ No	□ No
Host-Initiated S1=F13/F14 Scenario	☑ Yes □ No	
Event Notification	☑ Yes □ No	
On-Line Identification	☑ Yes □ No	
Error Messages	☑ Yes □ No	
Documentation	☑ Yes □ No	
Control (Operator Initiated)	☑ Yes □ No	
ADDITIONAL CAPABILITIES	IMPLEMENTED	GEM-COMPLIANT
Establish Communications	☑ Yes ☐ No	☑ Yes ☐ No
Dynamic Event Report Configuration	☑ Yes □ No	☑ Yes □ No
Variable Data Collection	☑ Yes ☐ No	☑ Yes □ No
Trace Data Collection	☐ Yes ☑ No	☐ Yes ☑ No
Status Data Collection	☑ Yes ☐ No	☑ Yes □ No
Alarm Management	☑ Yes □ No	☐ Yes ☑ No (1)
Remote Control	☑ Yes □ No	☑ Yes □ No
Equipment Constants	☑ Yes □ No	☑ Yes □ No
Process Program Management	☑ Yes □ No	☑ Yes □ No
Material Movement	☐ Yes ☑ No	☐ Yes ☑ No
Equipment Terminal Services	☑ Yes ☐ No	☐ Yes ☑ No (2)
Clock	☑ Yes ☐ No	☑ Yes □ No
Limits Monitoring	☐ Yes ☑ No	☐ Yes ☑ No
Spooling	☐ Yes ☑ No	☐ Yes ☑ No
Control (Host-Initiated)	☑ Yes ☐ No	☑ Yes □ No

#### Note:

- (1) Events indicating an Alarm Set and Alarm Clear are shared among all alarms. GEM requires a separate event for every alarm.
- (2) Only the Single Line terminal service is supported.

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## **Application Notes**

Following are some simple tips on configuring the Host software to communicate with the Eagle Xtreme.

Earlier versions of the ASMGEM library (pre June – 2000) did not correctly support the System Bytes. For these versions the Host had to have an option to Ignore System Bytes enabled.

The ASMGEM library used by ASM equipment does not support Message Interleaving or Multiple Open Transactions.

ASMGEM has an internal receive buffer size of 32K. Any multi-block message larger than this will be rejected with S9, F11 Data Too Long (DLN) message. The exception to the rule is during Process Program Upload / Dnload, where a special buffer will be dynamically created to handle the long message (if permission to send has been granted).

If the machine is bonding and receives a request for upload or download, there may be a few seconds pause to the bonding process while the file is compresses / decompressed. The delay will be seen as an inter-wire delay and does NOT affect the bonding quality. If possible, do not perform upload / download operations when the Processing state is EXECUTING.

Note that all the message descriptions are using the SML Notation. This makes it easier to find the data type of the variables in the message and removes the need for a Data Dictionary section in the document.

SML Format

SML Format	
Item Format	SML Item Format Mnemonic
LIST	L[Length]
Binary	В
Boolean	BOOLEAN
ASCII	A[Length]
JIS-8	J[Length]
8-byte integer (signed)	I8
1-byte integer (signed)	I1
2-byte integer (signed)	I2
4-byte integer (signed)	I4
8-byte floating point	F8
4-byte floating point	F4
8-byte integer (unsigned)	U8
1-byte integer (unsigned)	U1
2-byte integer (unsigned)	U2
4-byte integer (unsigned)	U4
* Any Type (Variant)	V

<sup>\* (</sup>V=variant) is not a "true" SML Item Format, but is added to inform that the format for an item is not fixed until the moment the message is sent (eg. Host Command Parameters S2, F41).

For factory floor implementation, linking to a network of Terminal Servers will extend the distance between the Host and the Equipment in a simple and efficient manner. This also removes the WinSECS RS-232 implementation limit of a max baud of 19200. This is because the data is sent over a network to the Terminal Server which can be configured to communicate at speeds up to 115200 baud.

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Many Terminal Servers have a Type-Ahead buffer. Ensure this is set to a large value (1024) if communication faults are detected during large messages (especially process program upload / download).

#### An Example:

VinSECS Settings (Direct Conn	ection)
General Tab	
AutoDevice	$\overline{\checkmark}$
MonitorEnable	
MultipleOpen	
SimulateMode	
PortType	RS-232
DefaultDeviceID	0
RS-232 Tab	
SerialPort	COM1/COM2
AcceptDuplicateBlocks	
AutoBaud	$\overline{\checkmark}$
IgnoreSystemBytes	
Interleave	
SecsHost	$\overline{\checkmark}$
Baud	19200
RetryLimit	3
T1	1
T2	1
T3	45
T4	10

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#### 14. IDEALine Feature – Wire bonder with Cell Controller

#### 14.1. Introduction

In IDEALINE one or more ASM AB339E wire bonder(s) connected and controlled by a Cell Controller. Here Cell Controller is a remote intelligent computer, controlling all the wire bonders. In IDEALINE most of the wire bonder features are automatically controlled by cell controller which include recipe management, statistic management, Alarm management , Lot management , strip management, etc.

Wire bonder can communicate with cell controller either by using RS-232 communication or HSMS (TCP\IP) communication. As soon as the communication enabled with cell controller, the following information will be sent from bonder to cell controller.

- MDLN: Model No of the equipment. For Eagle Xtreme wire bonder this string will be "Eg XT"
- 2) SoftRev: Software version of the wire bonder (eg: 090592)
- 3) Equip ID: The Equipment ID for identification of individual wire bonder
- 4) Last PM Date: Last Preventive Maintenance Date
- 5) Installation Date:
- 6) Operator ID: This is to identify which operator is in-charge of production side.

### 14.2. Recipe Management

If the wire bonder is working as IDEALINE mode operator can not load the bond program manually using the bonder menu item "Load Bond Program". Because this menu item will be dim as protection. Here Cell Controller will give the recipe name (PPID) to the wire bonder and wire bonder will automatically load that particular recipe from the bonder hard disk to memory. Cell controller can see which are the bond programs (PPIDs) available in the bonder hard disk by directly search. Also it can delete the bond program (PPID) from bonder hard disk.

## 14.3. Alarm Management

All the errors and warnings happened in wire bonder during different state will be automatically sent to cell controller. During the bonding if any error happens that error should be registered to Cell controller according to that error type.

## 14.4. Statistic Management

Cell controller can monitor all the statistical from the wire bonder. Statistical data contain the information of UPH, Productive time, Non Scheduled Time, Scheduled Time, Idle Time, Number of good bonded unit, number of rejected unit, etc

Every time wire bonder's state will be reflected to cell controller dynamically. The different states of wire bonder are as follows

- 1) PRODUCTION
  - a) Production (Wire Bonder tower Light is GREEN)
  - b) StandBy (Wire Bonder tower Light is YELLOW)
  - c) Unscheduled Down (Wire Bonder tower Light is RED)
- 2) ENGINEERING (Wire Bonder tower Light is YELLOW)
- 3) SCHEDULED DOWN (Wire Bonder tower Light is YELLOW)

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### 14.5. Stripmap Management

In IDEALINE mode each strip require a strip defect map (PRE-BOND-STRIPMAP) from Cell controller , so that bonder will handle (bond or skip) each subunit according to strip defect code of PRE-BOND-STRIPMAP. Before start bonding of each strip , bonder will verify whether the correct PRE-BOND-STRIPMAP has reached from cell controller for that particular strip. If strip map has not reached from the cell controller, bonder will display a message "Waiting for Strip map from Host" before start bonding and only after receiving the PRE-BOND-STRIPMAP from cell controller boner will start bonding.

The PRE-BOND-STRIPMAP from cell controller contains information of X-coordinate, Y-coordinate and the Error Code for every sub unit of that strip. According to Error Code bonder will take the appropriate action on a particular sub unit.

After completion of the strip bonding , strip map result, i.e POST-BOND-STRIPMAP, will send to the cell controller.

In strip map management boder has mainly 3 types of strip index array

- Host Strip Index: This is the PRE-BOND-STRIPMAP, new strip map received from Cell Controller. This will receive during strip indexing into leadframe track. Just before bonding start, PRE-BOND-STRIPMAP will transfer to "Bond Strip Index"
- 2) Bond Strip Index: This contains the stripmap data of currently bonding strip. Once start bonding wirebonder will process each subunit according to PRE-BOND-STRIPMAP data and will update it upon completion of each sub unit. After finish the bonding of a particular strip all information, say POST-BOND-STRIPMAP will be transferred to "Output Strip Index". Also the same information will be transferred to Cell Controller during leadframe index out.
- 3) Output Strip Index: After bonding a strip, all the strip map information (POST-BOND-STRIPMAP) will be passed from Bond Strip Index to Output Strip Index. And POST-BOND-STRIPMAP will be stored here up to the arrival of POST-BOND-STRIPMAP from Bond Strip Index. As the new POST-BOND-STRIPMAP comes from the Bond Strip Index the new one will be stored after erasing old one.

There are two types of strip map format available in ASM Eagle/Eagle60/Eagle Xtreme wire bonder called

- a) SEMI G84 stripmap format and
- b) ASM stripmap format

This classification is mainly based on the content of stripmap data and method of stripmap data download/upload

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### 14.5.1. SEMI G84 Stripmap Standard

In this method wir bonder will request for PRE-BOND-STRIPMAP data to Cell controller using S14F1 (GAR) during strip indexing into track and Cell Controller will download PRE-BOND-STRIPMAP data using S14F2 (GAD) . This is a single transaction and more faster

Here PRE-BOND-STRIPMAP data contains

- > Strip ID
- Strip status (First strip, Intermediate strip, last strip, Test strip, etc)
- > Number of Rows and Columns in strip
- > Origin Location of first subunit
- > Cell status of strip
- > Error Code of each subunit
- > Whether the Block is last block

The uploading of POST-BOND-STRIPMAP is done by S6F11/S6F12 and it is equipment initiated transaction.

The POST-BOND-STRIPMAP data contains

- ➤ Strip ID
- > Strip Process status (whether fully bonded or partially bonded)
- > Number of Rows and Columns in strip
- > Error code for each subunit after process
- ➤ Whether the Block is last block

#### S14, F1 GetAttr Request (GAR)

S, H ⇔ E, reply

#### Description

: This message is used to request a set of specified attributes for one or more objects. It consists of an "object specifier" for the owner of the target objects (the objects of interest), the target object type, a list of identifiers of the target objects, a filter (a list of qualifying relationships) that limits the target objects of interest to those that meet all of the qualifications in and the specific attributes whose values are requested.

```
Structure : L, 5
```

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3. <ATTRRELNq> a = # attributes requested 5. L, a 1. <ATTRID1> a. <ATTRIDa>

#### Exception

If OBJSPEC is a zero-length item, no object specifier is provided. If i = 0, only the filter is to be applied. If q = 0, no filter is specified. If both i and q = 0, information for all instances of the objects are requested. If a = 0, all attributes are requested.

#### S14, F2 GetAttr Data (GAD)

S, H ⇔ E, reply

: This message is used to transfer the set of requested attributes of the specified object(s). The order of attributes is retained from the primary message.

Structure

```
L, 2
  1. L, n
                        n = number of objects
      1. L, 2
           1. <OBJID1>
                        a = number of attributes
           2. L, a
                1. L, 2
                    1. <ATTRID1>
                    2. <ATTRDATA1>
                a. L, 2
                    1. <ATTRIDa>
                    2. <ATTRDATAa>
       n. L, 2
            1. <OBJIDn>
            2. L, b
                         b = number of attributes
                1. L, 2
                     1. <ATTRID1>
                     2. <ATTRDATA1>
                b. L, 2
                     1. <ATTRIDb>
                     2. <ATTRDATAb>
  2. L, 2
       1. <OBJACK>
       2. L, p
                       p = number of errors reports
            1. L, 2
                1. <ERRCODE1>
                 2. <ERRTEXT1>
```

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p.L, 2 1. <ERRCODEp> 2. <ERRTEXTp>

#### Exception

If OBJSPEC is a zero-length item, no object specifier is provided. If n=0, no objects matched the specified filter. If p=0, no errors were detected.

If n = 0, no objects matched the specified filter. In this case, equipment will automatically create the default stripmap. If p = 0, no errors were detected.

### 14.5.2. ASM Stripmap Standard

In this method Cell controller will initiate the PRE-BOND-STRIPMAP download with S2F15/S6F16 during strip indexing process and here S2F15/S6F16 is a multi-block transaction. Each block can contain information up to 20 subunits.

The PRE-BOND-STRIPMAP data contains

- Strip ID
- > Strip status (First strip, Intermediate strip, last strip, Test strip, etc)
- > X-coordinate and Y-coordinate of each subunit
- > Error code for each subunit
- ➤ Whether the Block is last block

The uploading of POST-BOND-STRIPMAP is done by S6F11/S6F12 and it is equipment initiated transaction.

The POST-BOND-STRIPMAP data contains

- > Strip ID
- > Strip Process status (whether fully bonded or partially bonded)
- > X-coordinate and Y-coordinate of each subunit
- > Error code for each subunit after process
- ➤ Whether the Block is last block(since data is sending block by block)

## 14.5.3. Create Default Stripmap

For some customers' requirement, our software supports create default map in WB from Revision 11 Reference 47 onwards. If user enables the flag of "Create default strip map" in menu page [10A12], machine will auto create default map instead of sending S14F1 event to request strip map. The default stripmap data contains:

- > Strip ID: Read from 2D camera
- > Strip Process status: 0 (fully bonded)
- Original location: 3
- > G84 strip map number of row: set same as row number in bond program
- > G84 strip map number of column: set same as column number in bond program
- > Cell Status: 0
- Defect code: 200

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### 14.6. Lot Management

### 14.6.1. Lot Management with Cell Controller

Before starting the production of a new lot, Cell controller will send the Lot Information to the wire bonder. This lot information contains

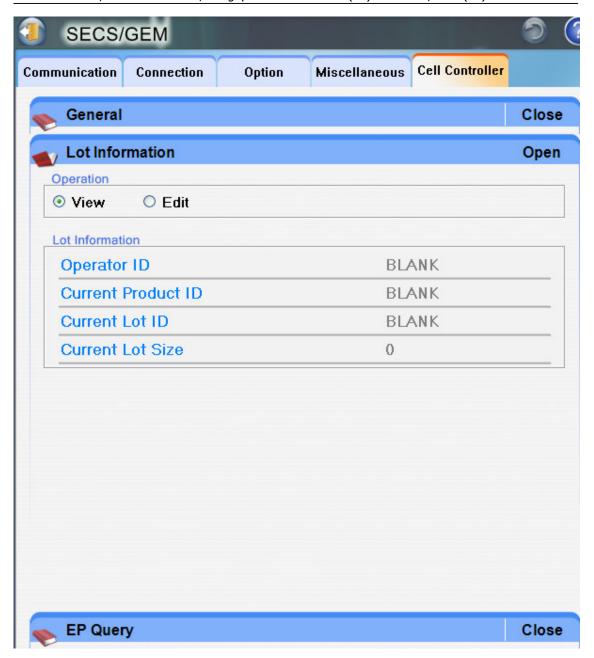
- 1) Lot ID
- 2) Product Id
- 3) Lot quantity
- 4) Unit per strip
- 5) Process Program ID
- 6) Gold Wire Type
- 7) Capillary Type
- 8) Window Clamp Type
- 9) Top Plate Type
- 10) Number of rows in Strip
- 11) Number of Columns in Strip

All these lot information will be stored in Wire bonder. Since cell controller can sent the new lot at any time Wire bonder has the capability to store 2 lot arrays, Current lot information and New Lot Information. Current Lot information contains all the information about the current running lot. And New Lot Information contains the information of the latest Lot sent by cell controller. Once a lot starts all the lot information from "New Lot Information" array will be passed to "Current Lot Information" array.

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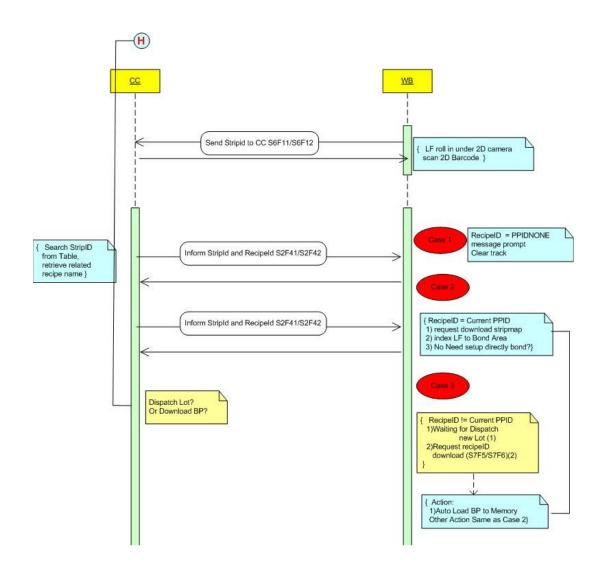
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### 14.6.2. Multi Lot sequence

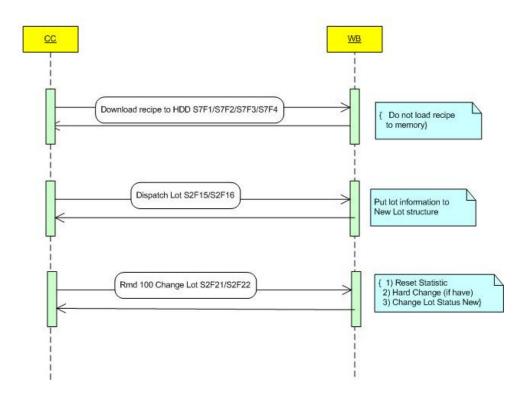


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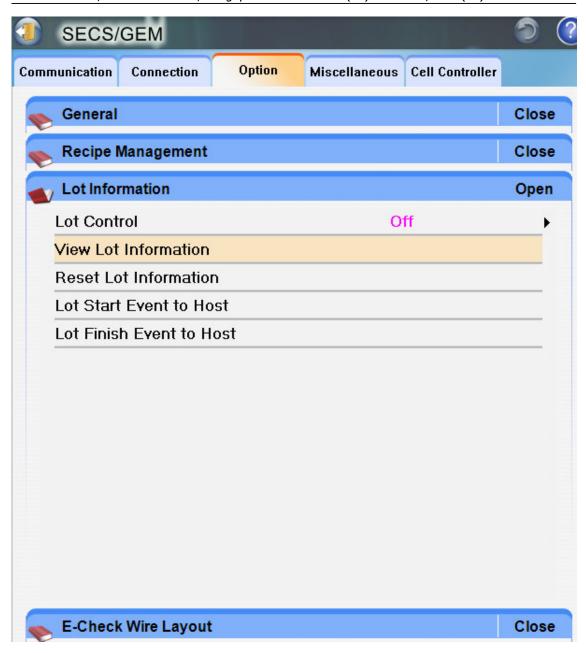
## 14.6.3. Advanced Lot Management

As customer required, our software support advanced lot management in Eagle Xtreme. The Lot Management feature is independent from strip mapping, tracking and validation feature. Equipment does not need to enable strip mapping option, to have lot management features functional. The related menu items locate in menu page [Configuration]->[ Factory Automation]->[ SECS/GEM]->[Option]->[ Lot Information]

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#### A. Item "Lot Control"

- -Disabled, machine will be able to operate as per normal.
- -Enabled, machine will be able to autobond and single bond **ONLY** when lot information is received.

#### **B. Item "View Lot Information"**

- -This menu item is used to view current lot information machine is using. The lot information contains:
  - 12) Lot ID
  - 13) PPID
  - 14) Operator ID
  - 15) LF Count

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- 16) Magazine Count
- 17) Total Unit
- 18) Processed Unit
- 19) Num of LF Bonded
- 20) Num of Magazine Bonded
- 21) Lot Status

#### C. Item "Reset Lot Information"

This menu item is used to reset current lot information to default value.

**Note:** To allow user to reset current processing lot.

If user enables this feature for advanced lot management, machine will auto report the related events to host during bonding. The related events for lot management is define as followed:

If user enables lot management feature, machine will auto report lot status event to host during bonding cycle. The major activity events are defined per below:

#### A. Lot Start Event:

```
CEID = 45

RPTID = 45

SVID = 265 (Operator ID)

SVID = 560 (Current Lot ID)

SVID = 562 (Current Lot Size, No of Unit in Lot)

SVID = 564 (Current Lot PPID)

SVID = 582 (Current Lot LF Count)

SVID = 583 (Current Lot Magazine Count)
```

**Note:** This equipment will report to host during the  $1^{st}$  Lead Frame of current lot index into the work holder.

#### **B. Lot End Event:**

```
CEID = 46

RPTID = 46

SVID = 265 (Operator ID)

SVID = 560 (Current Lot ID)

SVID = 562 (Current Lot Size, No of Unit in Lot)

SVID = 564 (Current Lot PPID)

SVID = 582 (Current Lot LF Count)

SVID = 583 (Current Lot Magazine Count)

SVID = 984 (Processed Unit Num in Current Lot)

SVID = 985 (Processed yield in Current Lot)
```

**Note**: This event will report to host during the last LF of current lot index out to the output magazine. After sending this event, machine will stop bonding until next lot information is received.

#### C. LF Index-In Event:

```
CEID = 41

RPTID = 41

SVID = 470 (Strip ID. Without turning on 2D code feature, this SVID should be default value "BLANK")

SVID = 981 (Index of Bonding LF)

SVID = 982 (Index of Bonding Magazine)
```

**Note:** This event will report to host during at every LF index into work holder.

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#### **D. LF Index-Out Event:**

CEID = 42 RPTID = 42

SVID = 470 (Strip ID. Without turning on 2D code feature, this SVID should be default value "BLANK")

SVID = 981 (Index of Bonded LF) SVID = 982 (Index of Bonded Magazine)

**Note:** This event will report to host at every LF index out to output magazine.

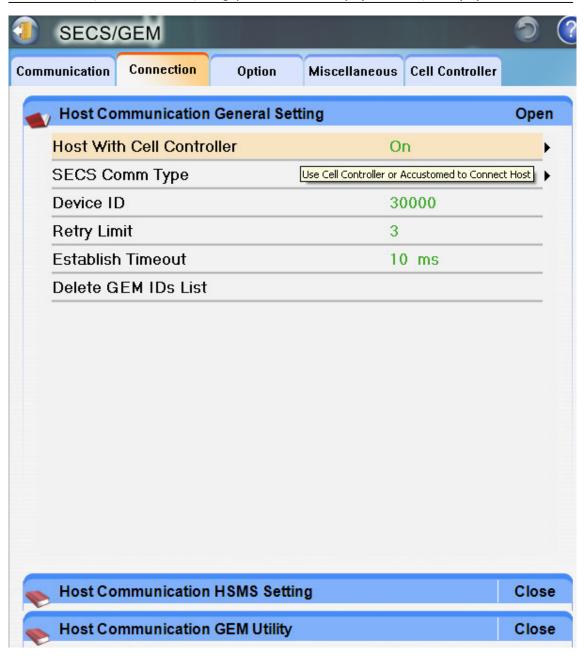
## 14.7. Wire Bonder S/W settings for Cell Controller

For a proper communication with cell controller the wire bonder menu settings should be correct.

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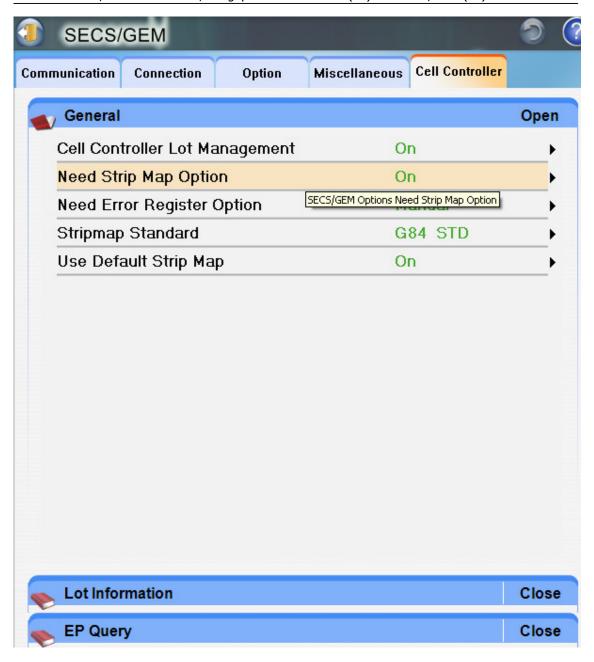


0. **Host With Cell Controller:** This menu item should be On for IDEALINE setup.

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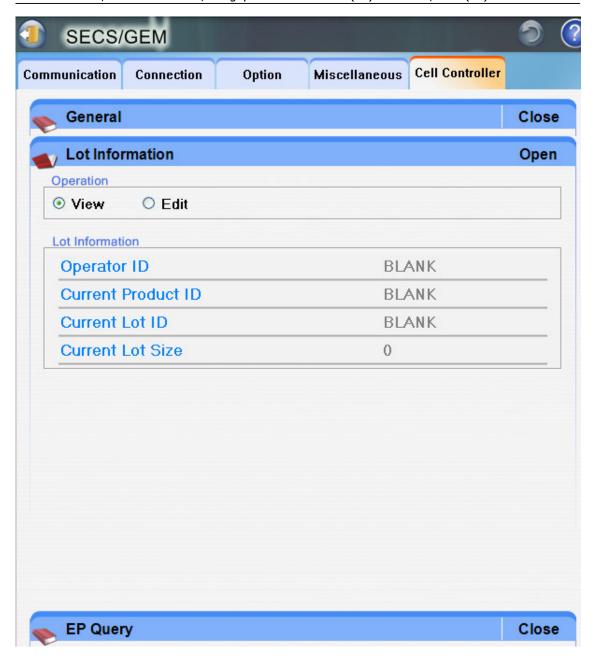


- 1. **Cell Controller Lot Mgt:** This menu item should be YES for IDEALINE setup.
- 2. **Need Strip Map Option?:** In IDEALINE mode production can be done with or without Strip Map feature. If the customer is using Strip map management in IDEALINE mode, this menu item should be YES, otherwise NO.
- 3. **Lot Information :** Lot information menu page contains "Current Lot Information" and "New Lot Information" This menu page is just for getting information about the Current Lot and New Lot information sent from cell controller

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## 15. HSMS (TCP\IP) Communication

#### 15.1.Introduction

High Speed SECS Message Services (HSMS) defines a communication interface suitable for exchange of messages or information between computers using TCP\IP environment which provides reliable two way simultaneous transmission of streams of contiguous bytes. In the semiconductor industry HSMS communication is useful for the exchange of information between remote computer and the semiconductor equipment using TCP\IP. Where TCP\IP (Transmission Control Protocol \ Internet protocol) is a method of communication which provides reliable, connection oriented message exchange between computers within a Network.

HSMS is an alternative to SEMI E4 (SECS-1) for applications where higher speed communication is needed, instead of simple point-to-point topology. It is also an alternative to SEMI E13 (SECS Message Services) for application where TCP\IP is preferred over OSI.

## 15.2. Comparison between SECS-1 and HSMS

Feature	e SECS-1 HSMS		
Communication Protocol Base	RS-232	RS-232 TCP\IP	
Physical Layer	25 pin connector and 4 wire serial cable	Physical Layer not defined. HSMS allow any TCP\IP supported medium.	
Communication speed	Typically about 1000bytes/seconds (assuming 9600 baud).  Max Baud is 115200	Typically 10Mbits/second (assuming typical Ethernet)	
Connections	One physical RS-232 cable per SECS-1 connection	One physical network can support many HSMS connections	
Message Format	Message text is SECS-II Data items Transmits a SECS-II message as a series of transmittal blocks each approximately 256 bytes in size. Each block has a one byte block length, a ten byte block header, text, and a two bytes checksum	Message text is SECS-II Data items Transmits a SECS-II message as a TCP\IP byte stream. The message has a four bytes message length, ten bytes message header, and text. The TCP\IP layer may impose blocking limits which depends on the physical layer used. But this blocking is transparent to the TCP\IP API and is outside the scope of HSMS.	
Header	Ten byte header on each block of the message. Header bytes 4-5 contains Ebit and block number	One ten byte header for entire message. Header byte 4-5 contain P Type and S Type. Header byte 2-3 are W-Bit, stream, and functions when Stype=0 (Data message). For S Type not equal to 0(Control message), bytes 2-3 have other uses. No R-bit	
Maximum Message size	Limited to approximately 7.9 million bytes (32767 blocks times 244 text byte per block)	Message size is limited by 4 bytes message length. (approximately 4Gbytes). Local implementation of TCP\IP and HSMS may further limit	

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		this in practice.
Protocol parameter (common)	T3 Reply Timeout Device ID	T3 Reply Timeout Session ID (analogous to Device ID)
Protocol parameter (SECS-I only)	Baud Rate T1 Inter Character timeout T2 Block Protocol Timeout T4 Inter Block Timeout Retry Limit	Not used in HSMS (corresponding issues addressed by TCP\IP layers)
Protocol parameter (HSMS only)	Not need for SECS-I	IP address and Port of PASSIVE entity T5 Connect separation Timeout T6 Control Transact Timeout T7 NOT SELECTED Timeout T8 Network Inter Character Timeout

## 15.3. Hardware Settings for HSMS Communication

For HSMS communication ASM Eagle Xtreme wire bonder must have a Network Interface Card (NIC). Please use the PCI Ethernet card in PCI Slot 1 for Eagle Xtreme wire bonder. For more details about NIC installation and HSMS setup please refer the NIC installation document for Eagle Xtreme wire bonder.

## 15.4. Software Settings for HSMS Communication

"HSMS Configuration" menu page can see under "SECS\GEM configuration" menu page. This menu page will be bright only for the customers those who are using HSMS communication features. Customer should setup these menu items according to their network and host computer settings.

- 0. **HSMS communication mode**: According to SECS\GEM standard, 2 types of communication modes can set in the bonder ( PASSIVE or ACTIVE) . Normally in equipment side this mode is PASSIVE and host side this mode is ACTIVE.
- Hsms Remote (HOST) IP: This one is IP address of the Host computer. Here user has
  to give a valid HOST IP address. Otherwise bonder will prompt an error message "Invalid
  IP address". The standard format of IP is four gorup of numbers separated by dot. But
  here in ASM AB339E wire bonder instead of dot user has to give a blank space as the
  separator or delimit (eg: 100 10 25 8)
- 2. **Remote (Host) IP Port**: Here user has to enter the IP port value of the host computer.
- 3. HSMS Local (Equip) IP: This number is the equipment's IP address. This menu item will be dim, so that user can not give any value manually. Because during the bonder initialization, bonder will get this value from the IP configuration file. This IP configuration file is existing in the bonder hard disk. If user changes any network configuration settings this file also will be updated dynamically. The Equipment IP address value is in standard format. Four group of numbers separated by dot.(eg: 100.10.25.8)

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Host Communication General Setting		Clo
Host Communication HSMS Setting		Оре
HSMS Comm Mode	Passive	
HSMS Host IP Address	10.8.113.6	
Remote (Host) IP Port	5000	
Equipment IP Address	10.8.112.24	
Network Mask	255.255.0.0	
Gateway	10.8.8.1	
Local (Equipment) IP Port	5001	
Reply Timeout(T3)	45 Sec	
Connect Step Timeout(T5)	50 Sec	
Control Tran Timeout(T6)	50 Sec	
Not Selected Timeout(T7)	50 Sec	
Network Interch Timeout(T8)	50 Sec	
Link Test Timeout	60 Sec	
Delete Net Cor HSMS Link Test Timeout		

- 4. **Reply Timeout (T3):** Reply Timeout in HSMS protocol is a limit on the length of time that the HSMS message protocol is willing to wait for a reply message. Value range is 1 to 120 seconds
- 5. **Connect Separate Timeout (T5)**: This timeout is used to prevent excessive TCP\IP connect activity by providing a minimum time between the breaking, by an application program, of a TCP\IP connection or a failed attempt to establish one, and the attempt, by the same application program to initiate a new TCP\IP connection. Value range is 1 to 240 seconds

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- 6. Control Transact Timeout (T6): This defines the maximum time an HSMS control transaction can remain open before a communication failure is considered to have occurred. A transaction is considered open from the time the initiator sends the required request message until the response message is received. Value range is 1 to 240 seconds
- 7. **Not Selected Timeout (T7):** This defines the time which a TCP\IP connection can remain in the NOT SELECTED state (i.e., no HSMS activity) before it is considered a communication failure. This property sets or returns the T7 "not selected" timeout value (in seconds) for the HSMS protocol. Value range is 1 to 240 seconds
- 8. **Network InterCh Timeout (T8)**: This is the maximum amount of time which may transpire between the receipt of any two successive bytes of a complete HSMS message before a communication failure is considered to have occurred. Value range is 1 to 120 seconds
- Link Test Timeout: This value determines the amount of time between the link test
  control message issued by application software control. Such message are useful to
  determine whether or not the HSMS connection is intact, even in the absence of SECS
  message activity.

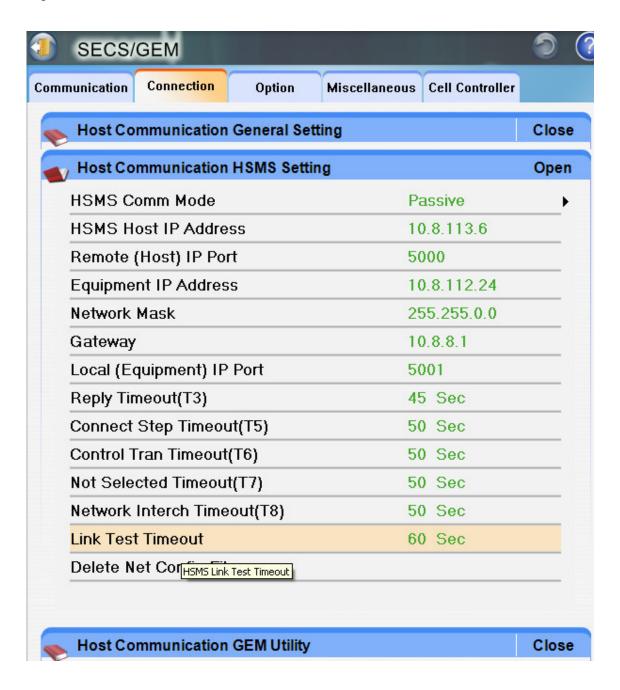
Please note that the unit of all HSMS timeout parameter values in ASM AB339E wire bonder menu is in seconds (s).

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**HSMS Network Configuration settings:** This settings only one time required to do in the ASM Eagle Xtreme wire bonder..



**0. Equipment IP Addr:** This should be an unique IP address (Internet Protocol) for individual equipment. Here user has to give a valid IP address. Otherwise bonder will prompt an error message "Invalid IP address". The standard format of IP is four gorup of numbers separated by dot. But here in ASM AB339E wire bonder instead of dot user has to give a blank space as the separator or delimit (eq: 100 10 25 8)

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- 1. Netmask: This value is according to the customer's LAN settings(Local Area Networking). Here user has to give a valid Netmask address. Otherwise bonder will prompt an error message "Invalid IP address". The standard format of Netmaks is four gorup of numbers separated by dot. But here in ASM AB339E wire bonder instead of dot user has to give a blank space as the separator or delimit (eg: 255 255 0 0)
- **2. Gateway :** This value is also according to the customer's LAN settings(Local Area Networking). Here user has to give a valid Gateway address. Otherwise bonder will prompt an error message "Invalid IP address". The standard format of Gateway is four groups of numbers separated by dot. But here in ASM AB339E wire bonder instead of dot user has to give a blank space as the separator or delimit (eq: 100 172 18 123)
- 3. **Local (Equip) IP Port :** This is a part of TCP/IP communication. The complete network address is specified by IP address and IP port number. By default in ASM EAGLE wire bonder this value is 5000. Customer can change this value according to their Host settings.

Please give the above values from the bonder menu (HSMS configuration\Network configuration) with the help of network administrator. After modifying any of these three values bonder will prompt the message "Restart the bonder for new Setting". The new values will be activated only after restarting the bonder. If any of these values modify, bonder will generate a dynamic IP configuration file inside the bonder hard disk

**Note:** Out of HSMS and RS-232 communications only one type communication user can configure in ASM Eagle Xtreme wire bonder. If wire bonder software is for HSMS communication, then all the RS-232 related setting parameters in bonder menu will be hided and vice versa.

#### 15.5. HSMS Demo Version Protection

HSMS demo version is an evaluation software for customers who want to use HSMS communication feature for a particular time period for their production evaluation. In the demo version software HSMS communication feature will expire after that particular time period and so that customer can not use that feature after that time period. During the HSMS setting and Network configuration customer can identify whether the software is a demo version or the original version. In the demo version during the Network configuration settings, bonder will display the message "HSMS Demo Ver Protection". Also every time when the operator try to access the "HSMS configuration" menu page or "SECS\Gem Option" menu page the same message will be repeated.

Later if customer satisfied in the demo version and they want to use HSMS feature permanently , then ASM will provide a dynamic password to make demo version into the original version ,so that they can use the same software in future also.

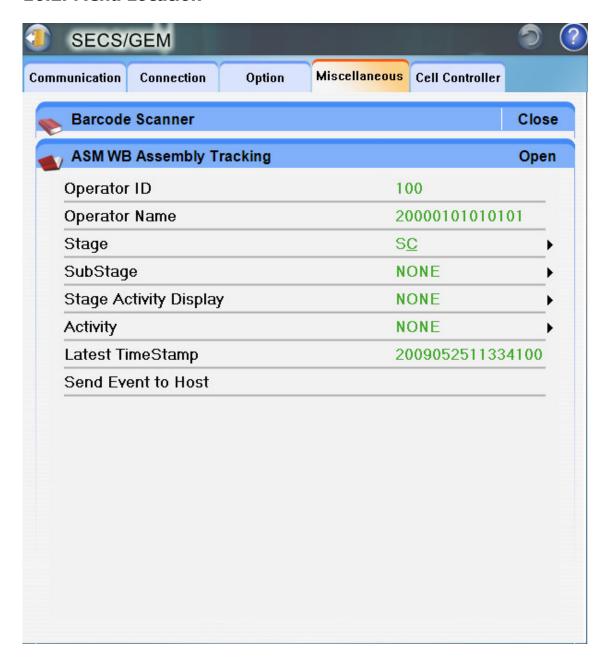
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## 16. Wirebonder Assembly Tracking System

#### 16.1. Introduction

The purpose of this feature is to monitor and control from Cell Controller different pre-shipment assembly stage/sub stage activities of wire bonder. This feature is available only for ASM in-house usage only for Quality assurance.

#### 16.2. Menu Location



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## 16.3. Assembly Stage Notification

Assembly Stage Notification (**ASN**) is to notify Cell Controller when there is any change of activity in stage/sub stage. When user changes the activity of a stage or sub stage, Wire Bonder Equipment shall report **ASN** to Cell Controller through event report (**S6F11/S6F12**) and to request ASN through event report request (**S6F15/16**).

Assembly	Element	Data Type	Elaboration
Stage Notification, ASN	UserName	ASCII	<b>D</b> escribes the user name of the user id that is currently attending to the equipment.
			Describes the user id of the user that is currently attending to the equipment
	UserID	ASCII	Enforcement Rule: Equipment has to prompt user to enter user id before allowing user to successfully start/end a stage/substage.
			<b>D</b> escribes the stage that the equipment
	Stage	ASCII	Definition of stages: "SETUP & CALIBRATION" "IN-HOUSE QUAD" "FINAL TEST & QUAD" "PRE-SHIPMENT"
			Describes the substages of the equipment
	SubStage		Definition of substages in <b>Stage 3</b> : "FORCE CALIBRATION" "MOTION DECOUPLING CALIBRATION" "FFC TUNING" "E-TORCH BURN IN" "INDEXING ACCURACY TEST"
			Describes whether the equipment is starting/ending the stage
	Activity	ASCII	Definition of Activity: "PENDING" "STARTED" "ENDED" "SUBMISSION-1" "SUBMISSION-2" "SUBMISSION-3" "SUBMISSION-4" "SUBMISSION-5"
	TimeStamp	ASCII	Start/End time for each stage/substage, as yyyymmddhhmmsscc.

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Cell Controller can send Host command "ASN" with following element which helps to update the assembly Stage from remote Cell Controller without any user prompt on the equipment side.

Update	Element	Data Type	Elaboration
Assembly Stage ("ASN")	"Stage"	ASCII	Describes the stage that the equipment  Definition of stages: "SETUP & CALIBRATION" "IN-HOUSE QUAD" "FINAL TEST & QUAD" "PRE-SHIPMENT"
	"SubStage"	ASCII	Describes the substages of the equipment  Definition of substages in Stage 3:  "FORCE CALIBRATION"  "MOTION DECOUPLING CALIBRATION"  "FFC TUNING"  "E-TORCH BURN IN"  "INDEXING ACCURACY TEST"
	"Activity"	ASCII	Describes whether the equipment is starting/ending the stage  Definition of Activity: "PENDING" "STARTED" "ENDED" "SUBMISSION-1" "SUBMISSION-2" "SUBMISSION-3" "SUBMISSION-3" "SUBMISSION-4" "SUBMISSION-5"
	"TimeStamp"	ASCII	Start/End time for each stage/substage, as yyyymmddhhmmsscc.

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## 17. eCheck – Wire Layout comparison

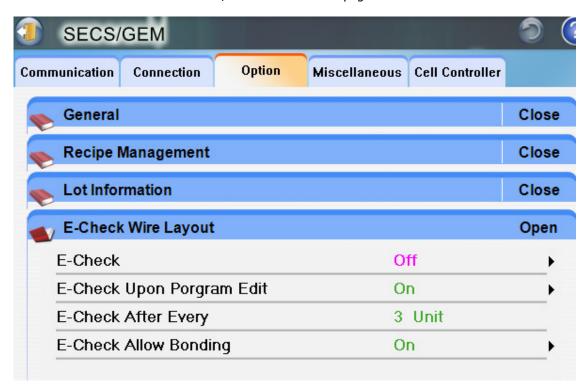
#### 17.1. Introduction

This feature helps to compare the wire layout loaded at wire bonder with base program (or master program) stored at host, after teaching or prior to auto-bonding. Wire bonder will generate "LAYOUT.DAT" file and will upload to host and host will do the comparison between this newly generated .DAT file and Master program's .DAT file. The comparison will PASS or FAIL based on the predefined parameter tolerance limit setting on host side.

For more details about generating Master program and verification program refer "Manual of ASM Offline Verification Program (OLVP) or eCheck.

#### 17.2. Menu location

The menu item is located under SECS/GEM communication page



- 0: **"eCheck"** :- This is the master flag to support all eCheck related features. If it is disabled, none of the eCheck features will work out.
- 1: "eCheck upon pgm Edit" :- If this flag is YES , upon user edits or teaches the bond program, wirebonder will trigger for eCheck.
- 2: **"eCheck after every n units"**:- During autobond after every n units finish, wire bonder will trigger for eCheck. If this set as 0, then feature will disable. The value of n varies from 0 to 30000.

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3: "eCheck Allow Bonding": This flag shows the status of eCheck PASS or FAILURE, based on the result from host. There are three possible values (YES (PASS), NO(FAIL), and Compare).

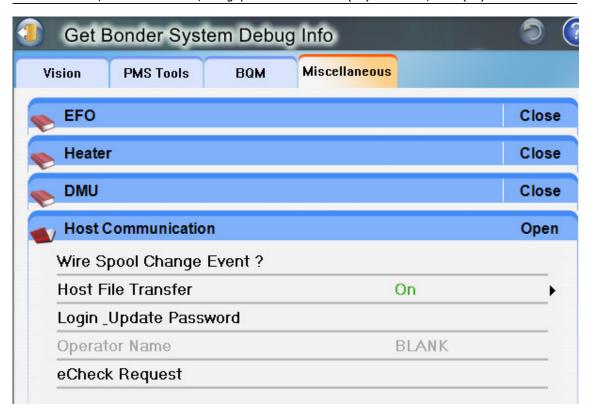
Besides these menu items, there is another menu item called **"eCheck Request"** inside "Utilities"  $\rightarrow$  "Host Misc Operations" page. By this item user can manually trigger an eCheck request to host at any time.



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## 17.3. eCheck Functionality

Different eCheck triggering methods are

#### 1) Host initiated eCheck:-

When host wants to do eCheck wire layout

- > Host sends a remote command (RMT CMD 134) to wirebonder
- > Wirebonder will upload the file "LAYOUT.DAT" to host using S7F1, S7F2, S7F3 & S7F4
- Host will do the eCheck (wire layor comparison) while wirebonder waits for eCheck result.
- > Host will send the eCheck result to wirebonder , also it will allow/reject wirebonder to do bonding based on the eCheck result.

#### 2) Wirebonder initiated eCheck, upon teaching/modification of bond program:-

If Operator Edits/Teaches the bond program, upon quitting the Teach menu page, wirebonder will trigger eCheck request event (CEID 86) to host.

- 3) **Wirebonder initiated eCheck, during autobond:** Wirebonder will trigger eCheck request event (CEID 86) to host, just before start the bonding of first unit; Also after every n number of units (user can key in this 'n' from menu).
- 4) **User can manually request eCheck:**By this user can manually trigger an eCheck request to host at any time

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