# Notes of "Invariant Subspace and Eigenvectors"

#### Jinxin Wang

#### 1 Overview

- Invariant subspace
  - Def: An invariant subspace for a linear operator
    - \* Rmk: Two trivial invariant subspaces for a linear operator
  - Def: The restriction of a linear operator over an invariant space
  - Rmk: Connection between an invariant subspace for a linear operator and a matrix of the operator
  - Thm: A necessary and sufficient condition for the matrix of a linear operator under a basis has the form of block-wise diagonal matrix
  - Rmk: Generalization of the above theorem to multiple invariant subspaces for a linear operator
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- Eigenvectors and characteristic polynomial
  - Def: Eigenvector and eigenvalue of a linear operator
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  - Rmk:
  - Def: Eigenspace and geometric multiplicity
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- $\bullet\,$  The criterion of diagonalizable linear operators
  - Def: Diagonalizable linear operator
  - Rmk: A equivalent condition for a linear operator to be diagonalizable in terms of eigenvectors
- The existence of invariant subspaces

## 2 Invariant subspace

**Definition 1** (An invariant subspace for a linear operator). Let  $\mathcal{A}$  be a linear operator on a space V. A subspace U of V is called an invariant subspace for  $\mathcal{A}$  if  $\mathcal{A}U \subset U$ , where  $\mathcal{A}U = \{\mathcal{A}x \mid x \in U\}$ .

**Definition 2** (The restriction of a linear operator over an invariant space).

Remark 1 (Connection between an invariant subspace for a linear operator and a matrix of the operator). Let U be an invariant subspace for a linear operator A on a space V. Choose a basis of U and expand it into a basis of V as  $\{e_1, e_2, \ldots, e_n\}$ . Suppose among them  $e_{i+1}, e_{i+2}, \ldots, e_j (i < j)$  are the basis of U and  $A_U$  is the matrix of the restriction  $A_U$  under the basis  $e_{i+1}, e_{i+2}, \ldots, e_j$ . Then the matrix of A under this basis is that

$$A = \begin{pmatrix} A_{11} & 0 & A_{13} \\ A_{21} & A_{U} & A_{23} \\ A_{31} & 0 & A_{33} \end{pmatrix}$$

in which  $A_{11}$  is a square matrix of order i, and  $A_{33}$  is a square matrix of order n-j.

Proof: Since U is an invariant subspace of A, for any of  $e_{i+1}, e_{i+2}, \ldots, e_j$ ,  $Ae_k \in U$   $(k = i + 1, i + 2, \ldots, j)$ , and thus a linear combination of  $e_{i+1}, e_{i+2}, \ldots, e_j$ . Hence the nonzero elements in columns  $i + 1, i + 2, \ldots, j$  can only appear in rows  $i + 1, i + 2, \ldots, j$ . More specifically,  $A(e_{i+1}, e_{i+2}, \cdots, e_j) = A_U(e_{i+1}, e_{i+2}, \cdots, e_j) = (e_{i+1}, e_{i+2}, \cdots, e_j)A_U$ , hence the block consisting of columns  $i + 1, i + 2, \ldots, j$  in

$$A \ is \begin{pmatrix} 0 \\ A_U \\ 0 \end{pmatrix}$$
 which satisfies

$$\mathcal{A}(e_{i+1}, e_{i+2}, \cdots, e_j) = (e_1, e_2, \cdots, e_{i+1}, e_{i+2}, \cdots, e_j, e_{j+1}, \cdots, e_n) \begin{pmatrix} 0 \\ A_U \\ 0 \end{pmatrix}$$

Conversely, if the matrix of A under a basis  $\{e_1, e_2, \ldots, e_n\}$  has the above form, i.e., then the linear span  $\langle e_{i+1}, e_{i+2}, \ldots, e_j \rangle$  is an invariant subspace for A.

**Remark 2** (Specialization of the above remark to invariant subspaces of dimension 1). If the space V is a direct sum of n invariant subspaces  $V_1, V_2, \ldots, V_n$  of dimension 1, then with a basis that is compatible with these subspaces, the matrix of the linear operator under this basis has the form as

$$\begin{pmatrix} a_1 & 0 & 0 & \cdots & 0 \\ 0 & a_2 & 0 & \cdots & 0 \\ 0 & 0 & a_3 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & a_n \end{pmatrix}$$

which is a diagonal matrix.

Conversely, if the matrix of the linear operator under a basis is a diagonal matrix, then the space can be expressed as a direct sum of n invariant subspaces of dimension 1 for the operator.

## 3 Eigenvectors and characteristic polynomial

**Definition 3** (Eigenvector and eigenvalue of a linear operator).

**Remark 3** (Connection between eigenvectors and invariant subspaces). Every non-zero vector in an invariant subspace of dimension 1 for a linear operator is an eigenvector of the operator. Conversely, the linear span of an eigenvector of a linear operator is an invariant subspace for the operator.

Proof: Let U be an invariant subspace of dimension 1 for a linear operator A of the space V.

- **P1** For each non-zero vector  $v \in U$ , according to the definition of an invariant subspace, we have  $Av \in U$ . Since dim V = 1, v is also a basis of V, and hence  $Av = \lambda v$ . Therefore v is an eigenvector of A.
- **P2** Given an eigenvector v of  $\mathcal{A}$  with corresponding eigenvalue  $\lambda$ , the linear span  $\langle v \rangle = \{\mu v \mid \mu \in K\}$ , then  $\mathcal{A} \langle v \rangle = \{\mathcal{A}\mu v \mid \mu \in K\} = \{\mu \mathcal{A}v \mid \mu \in K\} = \{\mu \lambda v \mid \mu \in K\} \in \langle v \rangle$ . Therefore,  $\langle v \rangle$  is an invariant subspace for  $\mathcal{A}$ .

### 4 The criterion of diagonalizable linear operators

**Definition 4** (Diagonalizable linear operator). A linear operator is diagonalizable if the matrix of it under a basis is a diagonal matrix.

**Remark 4** (A equivalent condition for a linear operator to be diagonalizable in terms of eigenvectors). A linear operator  $\mathcal{A}$  on a space V is diagonalizable if and only if V has a basis consists of eigenvectors of  $\mathcal{A}$ .

Proof: (TODO)

### 5 The existence of invariant subspaces