Notes of ”Invariant Subspace and Eigenvectors”

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1 Overview

- Invariant subspace
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    * Rmk: Two trivial invariant subspaces for a linear operator
  - Rmk: Connection between an invariant subspace for a linear operator and a matrix of the operator
  - Thm: A necessary and sufficient condition for the matrix of a linear operator under a basis has the form of block-wise diagonal matrix
  - Rmk: Generalization of the above theorem to multiple invariant subspaces for a linear operator
  - Rmk: Specialization of the above remark to invariant subspaces of dimension 1
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- Eigenvectors and characteristic polynomial
  - Def: Eigenvector and eigenvalue of a linear operator
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  - Rmk:
  - Def: Eigenspace and geometric multiplicity
  - Def: Algebraic multiplicity of a eigenvalue
- The criterion of diagonalizable linear operators
  - Def: Diagonalizable linear operator
  - Rmk: A equivalent condition for a linear operator to be diagonalizable in terms of eigenvectors
- The existence of invariant subspaces

2 Invariant subspace

Definition 1 (An invariant subspace for a linear operator)**.** *Let $\mathcal{A}$ be a linear operator on a space V. A subspace U of V is called an invariant subspace for $\mathcal{A}$ if $\mathcal{A}U \subset U$, where $\mathcal{A}U = \{\mathcal{A}x \mid x \in U\}$.*

Remark 1 (Connection between an invariant subspace for a linear operator and a matrix of the operator)**.** *Let U be an invariant subspace for a linear operator $\mathcal{A}$ on a space V. Choose a basis of U and expand it into a basis of V as $\{e_1, e_2, \ldots, e_n\}$. Suppose among them $e_{i+1}, e_{i+2}, \ldots, e_j (i < j)$ are the basis of U and A_U is the matrix of the restriction $\mathcal{A}_U$ under the basis $e_{i+1}, e_{i+2}, \ldots, e_j$. Then the matrix of $\mathcal{A}$ under this basis is that*

$$\begin{pmatrix} A_{11} & 0 & A_{13} \\ A_{21} & A_U & A_{23} \\ A_{31} & 0 & A_{33} \end{pmatrix}$$

in which A_{11} is a square matrix of order i, and A_{33} is a square matrix of order $n - j$.

Conversely, if the matrix of $\mathcal{A}$ under a basis $\{e_1, e_2, \ldots, e_n\}$ has the above form, i.e. , then the linear span $\langle e_{i+1}, e_{i+2}, \ldots, e_j \rangle$ is an invariant subspace for $\mathcal{A}$.

Remark 2 (Specialization of the above remark to invariant subspaces of dimension 1)**.** *If the space V is a direct sum of n invariant subspaces $V_1, V_2, \ldots, V_n$ of dimension 1, then with a basis that is compatible with these subspaces, the matrix of the linear operator under this basis has the form as*

$$\begin{pmatrix} a_1 & 0 & 0 & \cdots & 0 \\ 0 & a_2 & 0 & \cdots & 0 \\ 0 & 0 & a_3 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & a_n \end{pmatrix}$$

which is a diagonal matrix.

Conversely, if the matrix of the linear operator under a basis is a diagonal matrix, then the space can be expressed as a direct sum of n invariant subspaces of dimension 1 for the operator.

3 Eigenvectors and characteristic polynomial

Definition 2 (Eigenvector and eigenvalue of a linear operator)**.**

Remark 3 (Connection between eigenvectors and invariant subspaces)**.** *Every non-zero vector in an invariant subspace of dimension 1 for a linear operator is an eigenvector of the operator. Conversely, the linear span of an eigenvector of a linear operator is an invariant subspace for the operator.*

Proof: Let U be an invariant subspace of dimension 1 for a linear operator $\mathcal{A}$ of the space V.

P1 *For each non-zero vector $v \in U$, according to the definition of an invariant subspace, we have $\mathcal{A}v \in U$. Since $\dim V = 1$, v is also a basis of V, and hence $\mathcal{A}v = \lambda v$. Therefore v is an eigenvector of $\mathcal{A}$.*

P2 *Given an eigenvector v of $\mathcal{A}$ with corresponding eigenvalue λ, the linear span $\langle v \rangle = \{\mu v \mid \mu \in K\}$, then $\mathcal{A} \langle v \rangle = \{\mathcal{A}\mu v \mid \mu \in K\} = \{\mu \mathcal{A} v \mid \mu \in K\} = \{\mu\lambda v \mid \mu \in K\} \in \langle v \rangle$. Therefore, $\langle v \rangle$ is an invariant subspace for $\mathcal{A}$.*

4 The criterion of diagonalizable linear operators

Definition 3 (Diagonalizable linear operator)**.** *A linear operator is diagonalizable if the matrix of it under a basis is a diagonal matrix.*

Remark 4 (A equivalent condition for a linear operator to be diagonalizable in terms of eigenvectors)**.** *A linear operator $\mathcal{A}$ on a space V is diagonalizable if and only if V has a basis consists of eigenvectors of $\mathcal{A}$.*

Proof: (TODO)

5 The existence of invariant subspaces