## 18.02 EXERCISES

# Problem Set 3: Parametric Equations for Curves

#### Part I

#### Unit 1E Equations of Lines and Planes

4. Where does the line through (0,1,2) and (2,0,3) intersect the plane x+4y+z=4?

Solution:

A vector along the line is < 2, -1, 1 >. Hence, the parametric equation of the line is

$$\begin{cases} x = x(t) = 0 + 2t = 2t \\ y = y(t) = 1 - t \\ z = z(t) = 2 + t \end{cases}$$

For the intersection point of the line and the plane, it satisfies

$$x(t) + 4y(t) + z(t) = 4$$
$$2t + 4(1 - t) + 2 + t = 4$$
$$-t = -2$$
$$t = 2$$

Therefore, the coordinates of the intersection point is (x(2), y(2), z(2)), which is (4, -1, 4).

7. Formulate a general method for finding the distance between two skew (i.e., non-intersecting) lines in space, and carry it out for two non-intersecting lines lying along the diagonals of two adjacent faces of the unit cube (place it in the first octant, with one vertex at the origin).

Solution:

7-1. Formulate a general method for finding the distance between two parallel planes in space:

Suppose that the equations of two parallel planes are respectively

$$n_1x + n_2y + n_3z = c_1$$
  
 $n_1x + n_2y + n_3z = c_2$ 

Then the vector  $\vec{n} = \langle n_1, n_2, n_3 \rangle$  is one of the normal vectors of the two planes. Therefore, we can construct the parametric equation of a line perpendicular to the two planes as

$$\begin{cases} x(t) = n_1 t \\ y(t) = n_2 t \\ z(t) = n_3 t \end{cases}$$

Therefore, the two intersection points the line has with the two planes respectively satisfy

$$\begin{split} n_1x(t_1) + n_2y(t_1) + n_3z(t_1) &= c_1 \\ n_1^2t_1 + n_2^2t_1 + n_3^2t_1 &= c_1 \\ t_1 &= \frac{c_1}{n_1^2 + n_2^2 + n_3^2} \\ n_1x(t_2) + n_2y(t_2) + n_3z(t_2) &= c_2 \\ n_1^2t_2 + n_2^2t_2 + n_3^2t_2 &= c_1 \\ t_2 &= \frac{c_2}{n_1^2 + n_2^2 + n_3^2} \end{split}$$

The distance between two points in the line can be calculated as

$$d = \sqrt{(x(t_1) - x(t_2))^2 + (y(t_1) - y(t_2))^2 + (z(t_1) - z(t_2))^2}$$

$$= \sqrt{(n_1^2 + n_2^2 + n_3^2)(t_1 - t_2)^2}$$

$$= \sqrt{(n_1^2 + n_2^2 + n_3^2)(\frac{c_1 - c_2}{n_1^2 + n_2^2 + n_3^2})^2}$$

$$= \frac{|c_1 - c_2|}{\sqrt{n_1^2 + n_2^2 + n_3^2}}$$

$$= \frac{|c_1 - c_2|}{|\vec{n}|}$$

7-2. Formulate a general method for finding the distance between two non-parallel lines in space:

Suppose that there are two non-parallel lines in space named  $l_a$  and  $l_b$ . Their normal vectors are respectively  $\vec{n_a} = \langle n_{ax}, n_{ay}, n_{az} \rangle$  and  $\vec{n_b} = \langle n_{bx}, n_{by}, n_{bz} \rangle$ ,

and their parametric equations are respectively:

$$\begin{cases} x_a(t) = x_{a0} + n_{ax}t \\ y_a(t) = y_{a0} + n_{ay}t \\ z_a(t) = z_{a0} + n_{az}t \end{cases}$$
$$\begin{cases} x_b(t) = x_{b0} + n_{bx}t \\ y_b(t) = y_{b0} + n_{by}t \\ z_b(t) = z_{b0} + n_{bz}t \end{cases}$$

Then we can find the vector  $\vec{n}$  which is perpendicular to both  $l_a$  and  $l_b$  by

$$\vec{n} = \vec{n_a} \times \vec{n_b}$$
$$= \langle n_x, n_y, n_z \rangle$$

Then the distance between  $l_a$  and  $l_b$  is equal to the distance between the two planes  $P_a$  and  $P_b$  with  $\vec{n}$  as their normal vectors where  $l_a$  and  $l_b$  lie within respectively.

The equation of  $P_a$  is

$$n_x x + n_y y + n_z z = n_x x_{a0} + n_y y_{a0} + n_z z_{a0}$$

The equation of  $P_b$  is

$$n_x x + n_y y + n_z z = n_x x_{b0} + n_y y_{b0} + n_z z_{b0}$$

According to the previous part, the distance between  $P_a$  and  $P_b$  is

$$d = \frac{|(n_x x_{a0} + n_y y_{a0} + n_z z_{a0}) - (n_x x_{b0} + n_y y_{b0} + n_z z_{b0})|}{|\vec{n}|}$$

$$= \frac{|\vec{n} \cdot \langle (x_{a0} - x_{b0}), (y_{a0} - y_{b0}), (z_{a0} - z_{b0}) \rangle|}{|\vec{n}|}$$

$$= \frac{|\vec{n} \cdot \vec{A_0 B_0}|}{|\vec{n}|}$$

$$= \frac{|(\vec{n_a} \times \vec{n_b}) \cdot \vec{A_0 B_0}|}{|\vec{n_a} \times \vec{n_b}|}$$

Therefore, the distance between  $l_a$  and  $l_b$  is

$$d = \frac{|(\vec{n_a} \times \vec{n_b}) \cdot \vec{A_0 B_0}|}{|\vec{n_a} \times \vec{n_b}|}$$

7-3 Apply the above method to find the distance between two non-intersecting lines lying along the diagonals of two adjacent faces of the unit cube (place it in the first octant, with one vertex at the origin).

The two non-intersecting diagonals of two adjacent faces of the unit cube I choose are the diagonal between (0,0,0) and (1,0,1), and the diagonal between (0,1,0) and (0,0,1). Therefore, the parametric equations of these two lines along the described diagonals are respectively:

$$\begin{cases} x_a(t) = t \\ y_a(t) = 0 \\ z_a(t) = t \end{cases}$$
$$\begin{cases} x_b(t) = 0 \\ y_b(t) = 1 - t \\ z_b(t) = t \end{cases}$$

Therefore,

$$\vec{n_a} = \langle 1, 0, 1 \rangle$$
  
 $\vec{n_b} = \langle 0, -1, 1 \rangle$   
 $A_0 = (0, 0, 0)$   
 $B_0 = (0, 1, 0)$   
 $\vec{A_0 B_0} = \langle 0, 1, 0 \rangle$ 

Therefore, the distance between the two non-intersecting diagonals is

$$d = \frac{|(\vec{n_a} \times \vec{n_b}) \cdot \vec{A_0 B_0}|}{|\vec{n_a} \times \vec{n_b}|}$$

$$= \frac{|\langle 1, -1, -1 \rangle \cdot \langle 0, 1, 0 \rangle|}{|\langle 1, -1, -1 \rangle|}$$

$$= \frac{\sqrt{3}}{3}$$

Therefore, the distance between the two non-intersecting diagonals of two adjacent faces of the unit cube is  $\frac{\sqrt{3}}{3}$ .

#### Unit 1I Vector Functions and Parametric Equations

1. The point P moves with constant speed v in the direction of the constant vector  $\vec{ai} + b\vec{j}$ . If at time t = 0 it is at  $(x_0, y_0)$ , what is its position vector function  $\vec{r}(t)$ ?

Solution:

The direction of the constant vector  $\vec{ai} + \vec{bj}$  is

$$dir(A) = \frac{a}{\sqrt{a^2 + b^2}}\vec{i} + \frac{b}{\sqrt{a^2 + b^2}}\vec{j}$$

Hence in a period of time t, the point P moves in a distance of vt in the direction  $\langle \frac{a}{\sqrt{a^2+b^2}}, \frac{b}{\sqrt{a^2+b^2}} \rangle$ . Hence along the x-axis it moves in a distance of  $\frac{a}{\sqrt{a^2+b^2}}vt$ , and along the y-axis it moves in a distance of  $\frac{b}{\sqrt{a^2+b^2}}vt$ . Therefore, the position vector function of the point P is

$$\vec{r}(t) = \langle x_0 + \frac{a}{\sqrt{a^2 + b^2}} vt, y_0 + \frac{b}{\sqrt{a^2 + b^2}} vt \rangle$$

3. Describe the motions given by each of the following position vector functions, as t goes from  $-\infty$  to  $\infty$ . In each case, give the xy-equation of the curve along which P travels, and tell what part of the curve is actually traced out by P.

- a)  $\vec{r} = 2\cos^2 t\vec{i} + \sin^2 t\vec{j}$
- b)  $\vec{r} = \cos 2t\vec{i} + \sin t\vec{j}$ c)  $\vec{r} = (t^2 + 1)\vec{i} + t^3\vec{j}$ d)  $\vec{r} = \tan t\vec{i} + \sec t\vec{j}$

Solution:

a)

- 5. A string is wound clockwise around the circle of radius a centered at the origin O; the initial position of the end P of the string is (a,0). Unwind the string, always pulling it taut (so it stays tangent to the circle). Write parametric equations for the motion of P.
- 7. The cycloid is the curve traced out by a fix point P on a circle of radius a which rolls along the x-axis in the positive direction, starting when P is at the origin O. Find the vector function OP; use as variable the angle  $\theta$  through which the circle has rolled.

### Part II

- 1. A circular disk of radius 2 has a dot marked at a point half-way between the center and the circumference. Denote this point by P. Suppose that the disk is tangent to the x-axis with the center initially at (0,2) and P initially at (0,1)and that it starts to roll to the right on the x-axis at unit speed. Let C be the curve traced out by the point P.
- a) Make a sketch of what you think the curve C will look like.
- b) Use vectors to find the parametric equations for  $\vec{OP}$  as a function of time t.
- c) Open the 'Mathlet' Wheel (with link on course webpage) and set the parameters to view an animation of this particular motion problem. Then activate the 'Trace' function to see a graph of the curve C. If this graph is substantially different from your hand sketch, sketch it also and then describe what led you to produce your first idea of the graph.