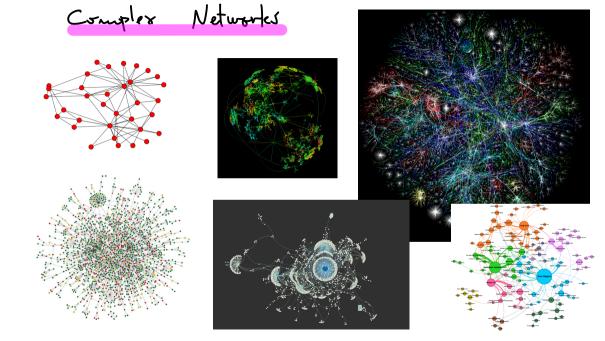
Geometria diferencial discreta Fa MAT - UNC Mayo 2023

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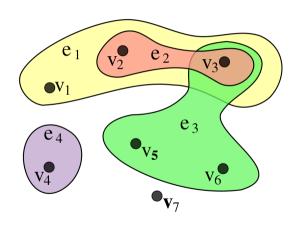
- Outline
- · Redis complijes
- · Hipergrafos (higher order networks) · Grupos de Renormalización
- · Repart de alpetra lineal



Complex Networks

$$N \sim L^{d}$$
 $M \sim L^{d}$ 
 $M \sim L^{d}$ 

#### Hyperprofos



No tiene la estructura de un espació topologico.

repularizadores campr (Fourier) [d] = Tdø(k)  $Z(\mu) = \int [d\tilde{\phi}]^{\frac{1}{2}} e^{-\frac{S}{S}} [\tilde{\phi}]$ 

Acción de teoria etectiva (mesoscopica) a escala E1max  $e^{-\tilde{S}} [\tilde{\phi}]$   $= \int [d\tilde{\phi}]^{\frac{-\tilde{S}}{\text{Aud}}} e^{-\tilde{S}} [\tilde{\phi}]$   $= \int [d\tilde{\phi}]^{\frac{-\tilde{S}}{\text{Aud}}} e^{-\tilde{S}} = 0 \approx 241$ 

Con alphos casos (GR)  $\tilde{S}_{\epsilon\mu} [\tilde{\phi}] \approx \tilde{S} [\tilde{\phi}_{\epsilon}] \qquad \begin{array}{c} \tilde{\phi}_{\epsilon} \\ \tilde{\phi}_{\epsilon} \end{array} \qquad \begin{array}{c} \tilde{\phi}_{\epsilon}$ 

$$S(\gamma) = \int_{\Omega} \left( \frac{1}{2} (\nabla \gamma)^2 - f \gamma \right) dn \qquad \gamma, f, g \in (\Omega \rightarrow \mathbb{R})$$

 $\phi = arguin S(\gamma)$   $\gamma = g \text{ in } \Omega$ Poisson  $-\Delta \phi = f$  en  $\Omega$ (M) ≈ myoridad de Y ≈ repularigador Dy = 0 so y es func. arménica.

Repart Algebra Lineal

$$V + cV' \in V$$

$$C \in \mathbb{R}$$

$$V = [V \rightarrow \mathbb{R}]$$

$$V = [V \rightarrow \mathbb{R}]$$

Bare

$$U = U'b_i = U'b_i$$

Netroise

Linstein

r1,..., rn & R

Base duel

Duble dual

$$V \simeq V^{**} \qquad \text{natural}$$

$$V \Rightarrow v \leftarrow v \quad \hat{v}(f) := f(v)$$

is mortismo

 $\bigvee^{**} := \left(\bigvee^{*}\right)^{*} = \left[\bigvee^{*} \longrightarrow \mathbb{R}\right]$ 

No son naturalmente ya que bi depende de bj b; 4> b

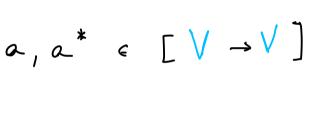
#### Producto interno

Terrema de Riesz e Isom. Musicales

Un prod. interno indua isomortismos

$$\bigvee \ni \bigvee \qquad \stackrel{b}{=} \qquad f \in \bigvee \qquad \# = b^{-1}$$

f(v') := v.v'



 $a^*(v).v' = v.a(v')$ 

an resumen V E V V\* > f

prod.

interno no hacen falta geom. b y # isom. Music. V ≃ V \*

Free Vector Space

$$X \text{ conjunt} \sigma$$

$$e_{x} \in (X \rightarrow \mathbb{R})$$

$$e_{x}(x') = \begin{cases} 1 & x = x' \\ 0 & \text{c.c.} \end{cases}$$

$$B_{X} = \{e_{x}: x \in X\}$$
 is base in espacis vectorial
$$F_{X} = span(B_{X})$$

Geometria Diferencial Confina

buses directional espació e; a; e Tp tang. M (A) ei es ei e To cotano. € (3;) = 5; R" ~ Tp m = 2,.2; Mes Rismm. métrian

Teorena de Stokes Generalizads

calculó 
$$\int dw = \int w$$

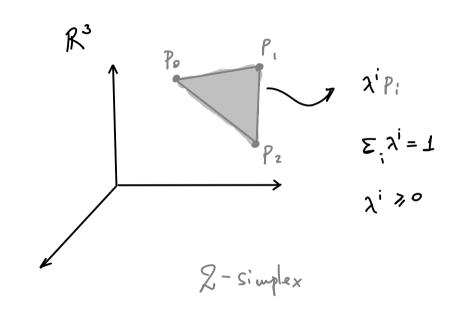
Apelva

Apelva

permetría?

Geometria Diferencial Discreta

Compley as Simpliciales 1-9mplx K1 Z-simplex 3-simplex0 - ringlex triango. de rep: on en Rn K := KU ... UK,



# Intervales y Formas

$$\int_{M} \omega \approx \Xi \omega_{i} \left(V_{i4}, ..., V_{iN}\right)$$

\* 
$$\omega$$
 multilineal  $\Rightarrow \omega$  alternante  $\omega = \omega$ 

## Orientación

$$\omega(\ldots,-v_{i},\ldots)=-\omega(\ldots,v_{i},\ldots)$$
 orient.  

$$\omega(\ldots,v_{i},\ldots,v_{i},\ldots)=-\omega(\ldots,v_{i},\ldots,v_{i},\ldots)$$
 permut.

W multilinerel es ventajess, peux introduce:

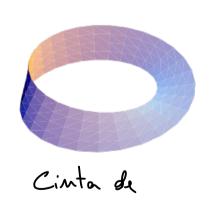
```
* volumenes nepativos

* orientación
```

Iqual, consiene multilinealided y lidiar con los signos  $\omega$  or  $-\omega$ a usar

100

### Orientabilidad



Möbius

Una manifold M es en entable ri existe una torma W sobre M que nunca se anula.

## Chains (tayent multirectors)

Ck := FK aspacis mect.

de k-chains

ei...ik e Ck is c... cik

c = c<sup>s</sup> e<sub>s</sub> c<sup>s</sup> eR, sek

Boundary Operator
$$\partial_k \in [C \to C] \quad C = C_0 \oplus \cdots \oplus C_n$$

2 (ei...ig) = Sqk = (-1) ei...ir.ir.ir.ir

 $\partial := \partial_1 \oplus \dots \oplus \partial_n$ ∂ુ:= ૦

DKE[CK → CK-1]

$$\partial := \partial_1 \oplus \dots \oplus \partial_n \qquad \partial_k$$

$$\partial_k(C) = \partial_1 (C_k) \subseteq C_{k-1} \qquad \partial_k$$

$$f \in C^* = [C \rightarrow R]$$
 analysis discretify de las formas

$$C^* := C^* \oplus \cdots \oplus C^*_n$$

Cobsundary Operator (exterior duris.)

d<sub>k</sub> 
$$\in [C^* \rightarrow C^*]$$

f c c c ×  $(q^{k}(t))(c) := f(g^{k+1}(c))$ 

d := d₀ + ... + dn dn:= 0

dre[cx -> Ck+1]

 $d_{k}(C^{*}) = d(C^{*}_{k}) \subseteq C^{*}_{k+1}$ 

Teorema de Stokes Generalizado

discrets 
$$(d(w))(c) = w(d(c))$$
 topologic  
Continus  $\int dw = \int w$  Sin métrica!  
 $M = \int M$ 

Dual coloundary operator (codifferential) adjunto 
$$d^* \in [C^* \to C^*]$$

requiere 
$$d'(F) \cdot g := f \cdot d(g)$$
  $\forall f, g \in C^*$  métrico!!

 $m_{rs} := e_{s} \cdot e_{r} \qquad d^{*} = d^{*} \oplus ... \oplus d^{*}_{n} \qquad d^{*}_{k}(f) \cdot g = f \cdot d_{k}(g)$   $0 \quad \text{son at} \qquad d^{*}_{k}(C^{*}) = d^{*}(C^{*}_{k+1}) \subseteq C^{*}_{k} \qquad d^{*}_{k} \in [C^{*}_{k+1} \to C^{*}_{k}]$   $d_{1} \circ f \cdot d_{1} \circ m \cdot d_{1} \qquad d_{2} \circ f \cdot d_{3} \circ f \cdot d_{4} \circ f$ 

 $\Delta(C_k^*) = \Delta_k(C_k^*) \leq C_k^*$ 

AKE [CK→CK]

A := dd\* + d\* d  $\triangle = \triangle_{\circ} \oplus \dots \oplus \triangle_{n}$ 

 $=: \Delta_k^{lown} + \Delta_k^{up}$ 

$$\Delta_{K} = J_{K-1}J_{K-1}^{*} + J_{K}^{*}J_{K}$$

$$\partial_{k} \circ \partial_{k+1} = 0$$
 $\Rightarrow \partial^{z} = 0$ 
 $d_{k+1} \circ d_{k} = 0$ 
 $\Rightarrow d^{z} = 0$ 
 $d_{k} \circ d_{k+1} = 0$ 
 $\Rightarrow (d^{*})^{z} = 0$ 
 $d_{k} \circ d_{k+1} = 0$ 
 $\Rightarrow (d^{*})^{z} = 0$ 
 $\Rightarrow (d^{*})^{z} = 0$ 

Physics is about  $Z^{nd}$ 
 $A = (d^{*} + d)^{z}$ 

order diffs. eqs. |||

Otrac operat.

$$0 = C_{n+1} \xrightarrow{\partial_{n+1}} ( \underset{n}{\xrightarrow{\partial_{n}}} C_{n-1} \xrightarrow{\partial_{n+1}} \cdots \xrightarrow{\partial_{2}} C_{1} \xrightarrow{\partial_{3}} ( \underset{n}{\xrightarrow{\partial_{3}}} ) \xrightarrow{\partial_{n}} ( \underset{n}{\xrightarrow{\partial_{n}}} ) \xrightarrow{\partial_{n+1}} ( \underset{n}{\xrightarrow{\partial_{n}}} ) \xrightarrow{\partial_{n}} ( \underset{n}{\xrightarrow{\partial_{n}}} ) \xrightarrow{\partial_{n$$

$$= C_{n+1} \xrightarrow{\partial_{n}} ( \bigcap_{n} C_{n-1} \xrightarrow{\partial_{n-1}} \cdots \xrightarrow{\partial_{2}} C_{1} \xrightarrow{\partial_{1}} ( \bigcap_{n} C_{n-1} \xrightarrow{\partial_{1}} \cdots \xrightarrow{\partial_{1}} C_{1} \xrightarrow{\partial_{1}} \cdots \xrightarrow{\partial_{1}} C_{1} \xrightarrow{\partial_{1}} ( \bigcap_{n} C_{n-1} \xrightarrow{\partial_{1}} \cdots \xrightarrow{\partial_{1}} C_{1} \cdots$$

2 T T DT DT DT incidence matrices

$$\partial_{n+1}^{T}$$
  $\partial_{n}^{T}$   $\partial_{n-1}^{T}$   $\partial_{2}^{T}$   $\partial_{3}^{T}$   $\partial_{3}^{T}$   $\partial_{n}^{T}$   $\partial_{n}^{T}$ 

$$0 = C_{n+1}^{*} \xrightarrow{d_{n+2}} C_{n}^{*} \xrightarrow{d_{n-2}} \cdots \xrightarrow{d_{n-2}} \cdots \xrightarrow{d_{n-2}} C_{n}^{*} \xrightarrow{d_{n}^{*}} C_{n}^{*} \xrightarrow{d_{n}^{*}} C_{n}^{*} \xrightarrow{d_{n-2}} C_{n}^{*} \xrightarrow{d_{n}^{*}} C_{n}^{*} C_{n}^{*} C_{n}^{*} \xrightarrow{d_{n}^{*$$

 ∈ ker ∂<sub>k</sub> ⇒ C ;s called k-cycle CE rug 2 k+1 => C is called k-boundary fekerdk = f is called K-cocycle (closed form) f & rag dk-1 => f is called k-coboundary (exact form)  $f = dg = -g_8 + g_q$ g€ C.\* t'4 & C\*

hourlopy 
$$H_{K} := \ker \partial_{k} / \operatorname{rng} \partial_{k+1} \qquad \beta_{k} := \operatorname{rnk} H_{K}$$

$$k - th Bellin''.$$

cohowology Hk:= ker dk+1/mg dk quotient spaces

Helmholtz-Hodge decomposition

HK = ker dk+1 / rng dk = rng dk+1 @ ker (dkudk+1 dkdk) @ rng dk

ker dk+1

 $f \in C_k^*$   $g \in C_{k-1}^*$   $g \in C_{k-1}^*$   $g \in C_{k+1}^*$   $g \in C_{k$ 

Gracius!