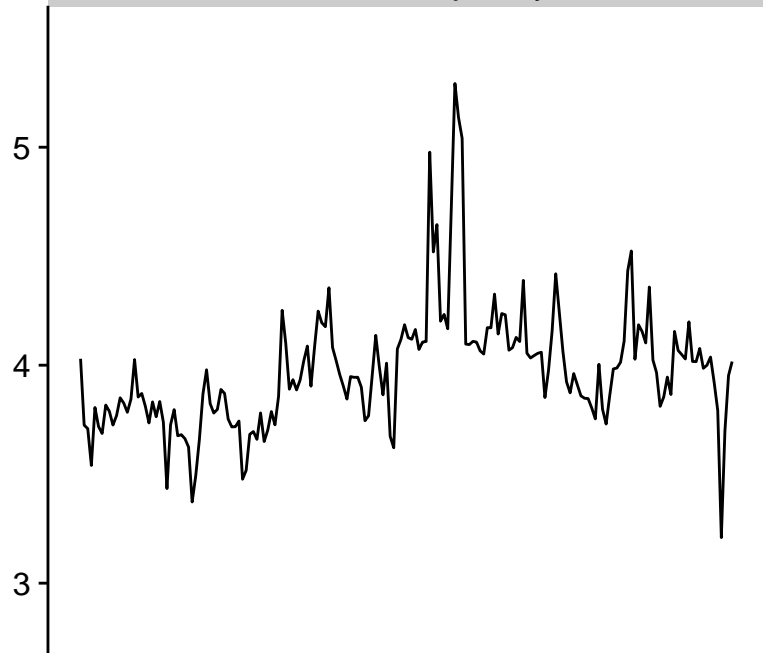
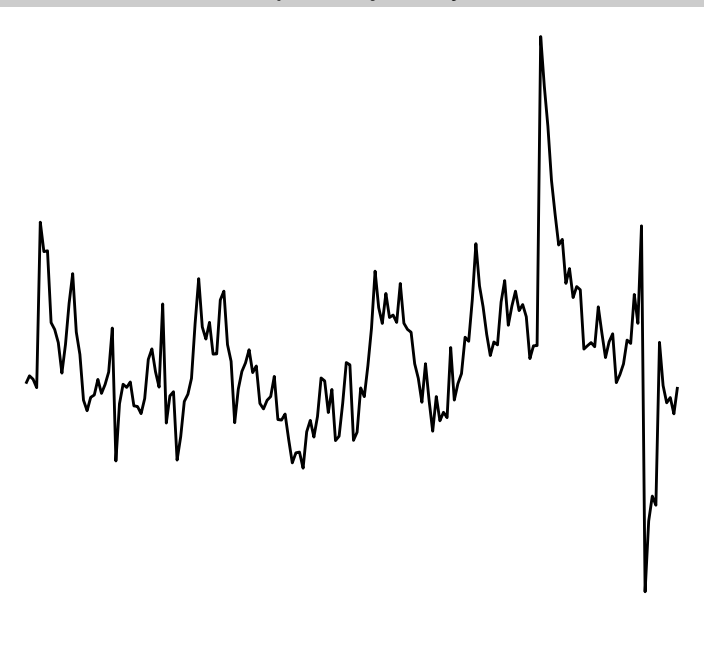


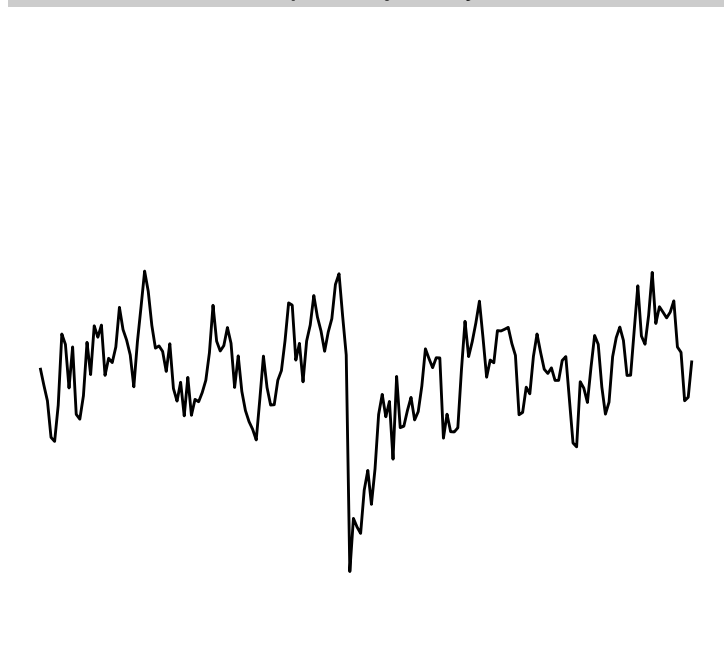
Observed Trajectory



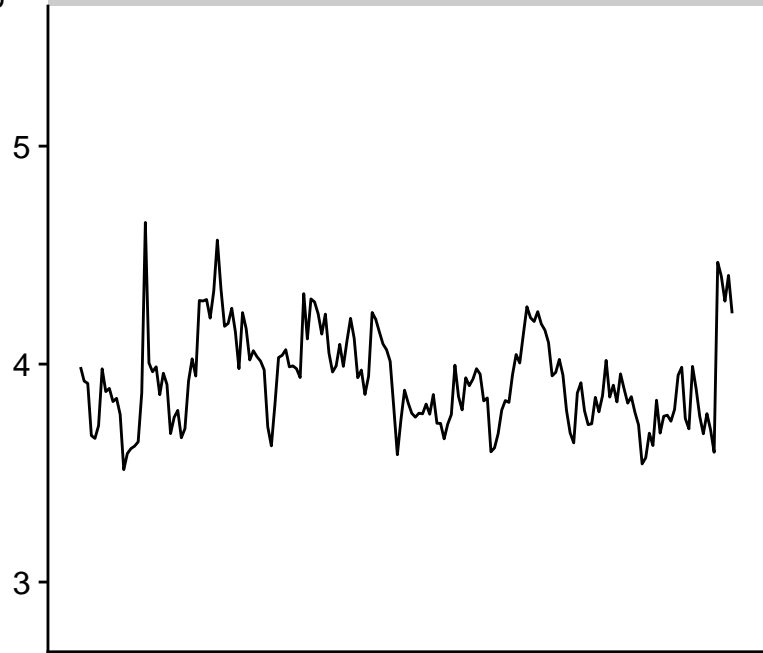
Sample Trajectory 1



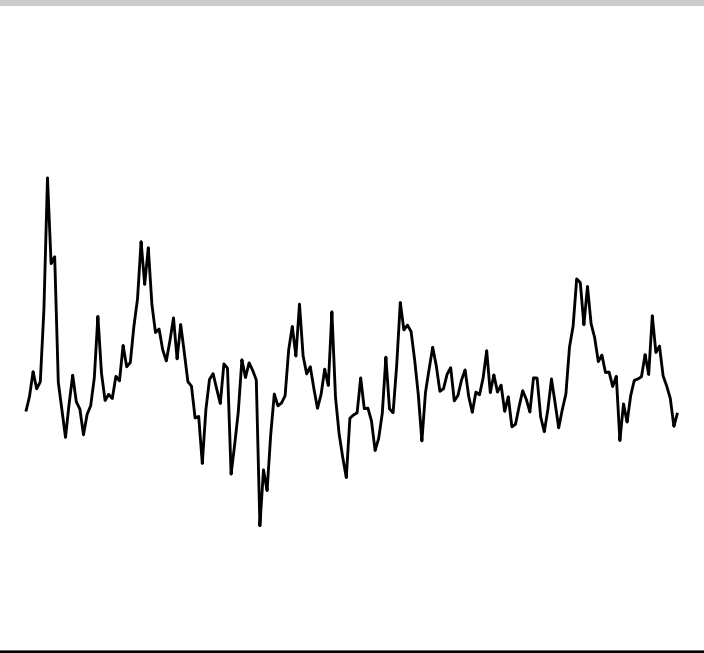
Sample Trajectory 2



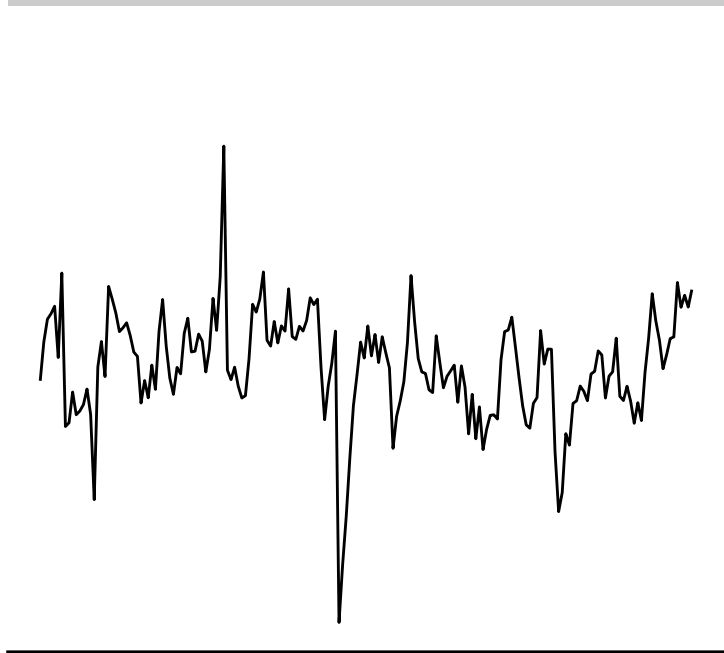
Sample Trajectory 3



Sample Trajectory 4



Sample Trajectory 5



Day