RECURSIVE BEST-FIRST SEARCH

# PROGRAM:

class Node:

def \_\_init\_\_(self, state, parent=None, cost=0, heuristic=0):

self.state = state

self.parent = parent

self.cost = cost

self.heuristic = heuristic

self.f\_cost = cost + heuristic

def \_\_lt\_\_(self, other):

return self.f\_cost < other.f\_cost

def \_\_repr\_\_(self):

return f"Node({self.state}, f\_cost={self.f\_cost})"

def rbfs(problem, node, f\_limit):

print(f"RBFS called with node: {node}, f\_limit: {f\_limit}")

if problem.is\_goal(node.state):

return node, 0

successors = []

for successor in problem.get\_successors(node.state):

s = Node(successor['state'], node, node.cost + successor['cost'], successor['heuristic'])

successors.append(s)

if not successors:

return None, float('inf')

successors.sort()

while successors:

best = successors[0]

if best.f\_cost > f\_limit:

return None, best.f\_cost

alternative = successors[1].f\_cost if len(successors) > 1 else float('inf')

result, best.f\_cost = rbfs(problem, best, min(f\_limit, alternative))

if result is not None:

return result, best.f\_cost

successors.remove(best)

return None, float('inf')

class Problem:

def \_\_init\_\_(self, initial\_state, goal\_state, successors):

self.initial\_state = initial\_state

self.goal\_state = goal\_state

self.successors = successors

def is\_goal(self, state):

return state == self.goal\_state

def get\_successors(self, state):

return self.successors.get(state, [])

def recursive\_best\_first\_search(problem):

initial\_state = problem.initial\_state

start\_node = Node(initial\_state, None, 0, problem.get\_successors(initial\_state)[0]['heuristic'])

result, \_ = rbfs(problem, start\_node, float('inf'))

return result

initial\_state = 'A'

goal\_state = 'G'

successors = {

'A': [{'state': 'B', 'cost': 1, 'heuristic': 5}, {'state': 'C', 'cost': 4, 'heuristic': 2}],

'B': [{'state': 'D', 'cost': 2, 'heuristic': 2}, {'state': 'E', 'cost': 5, 'heuristic': 1}],

'C': [{'state': 'F', 'cost': 1, 'heuristic': 4}],

'D': [{'state': 'G', 'cost': 3, 'heuristic': 0}],

'E': [],

'F': [{'state': 'G', 'cost': 1, 'heuristic': 0}],

'G': []

}

problem = Problem(initial\_state, goal\_state, successors)

solution = recursive\_best\_first\_search(problem)

path = []

node = solution

while node:

path.append(node.state)

node = node.parent

path.reverse()

print("Path to goal:", path)

OUTPUT:

RBFS called with node: Node(A, f\_cost=5), f\_limit: inf

RBFS called with node: Node(B, f\_cost=6), f\_limit: 6

RBFS called with node: Node(D, f\_cost=5), f\_limit: 6

RBFS called with node: Node(G, f\_cost=6), f\_limit: 6

Path to goal: ['A', 'B', 'D', 'G']

=== Code Execution Successful ===