MIT App Inventor Codi Bot: Complete



Level: advanced

This tutorial combines all the previous tutorials together. Here, you can interact with all Codi Bot functions, including LEDs, wings and sounds.

• source .ino / source .aia



Function description

This project will show you how to control all Codi Bot functions with App Inventor through a BLE connection

Hardware

Please follow this building guide to assemble your Codi Bot.

App Inventor

Now log in to your App Inventor account and create a new project or directly import this aia file.

Since this app is the combination of the previous three, this tutorial will not go into very much detail. But you are certainly can follow this tutorial to build the app step by step.

This app is composed of **four** different sections:

- 1. Connection (<u>Designer/Blocks</u>)
- 2. Wing (Designer/Blocks)
- 3. LED (<u>Designer/Blocks</u>)
- 4. Buzzer (Designer/Blocks)

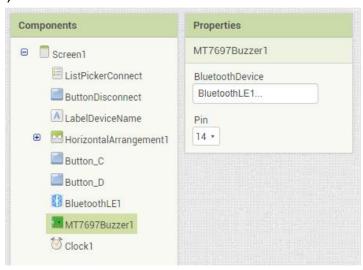
Designer

- 1. We need to import two extensions from this URL:
 - Bluetooth low energy: http://iot.appinventor.mit.edu/assets/resources/edu.mit.ap pinventor.ble.aix
 - MT7697pin:
 http://iot.appinventor.mit.edu/assets/resources/edu.mit.ap
 pinventor.iot.mt7697.aix
- 2. Add a **BluetoothLE** component to your project, we will use it to send commands to Codi Bot through Bluetooth connection.

3. Add seven MT7697Pin components to your project. Set their BluetoothDevice properties to BluetoothLE1 and rename them as table below:

Rename as	Mode	Pin
MT7697_LeftWingServo	servo	2
MT7697_RightWingServo	servo	7
MT7697_LeftWingLED	analog output	3
MT7697_RightWingLED	analog output	9
MT7697_LED_R	analog output	15
MT7697_LED_G	analog output	16
MT7697_LED_B	analog output	11

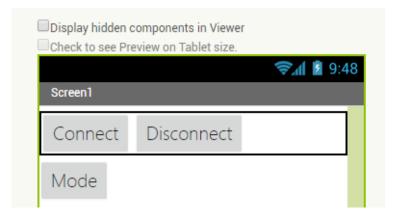
- 4. Add an **MT7697Buzzer** component to your project, we use this to control the #14 pin of Linklt 7697, which is connected with Robot Shield onboard buzzer.
 - Set its BluetoothDevice property to BluetoothLE1 (Step 2.) and set Pin to 14.



Connection

- 5. Add a ListPicker to select available Bluetooth devices nearby.

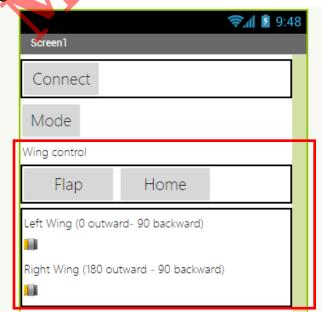
 Rename it to "ListPicker_Connect", set Text to "Connect" and FontSize to 20.
- 6. Add a button to close Bluetooth connection between your Android phone and Linklt 7697. Rename it to "Button_Disconnect" and set Text to "Disconnect".
- 7. Add a Label to show messages of connection. Rename it to "Label Device" and clear Text to "".
- 8. Add a Horizontal Arrangement component, set Width to **Fill parent**, then add components from Step 4 to 6 into it.
- Add another ListPicker to select one of the three control mode: Wing, LED and Sound. Rename it to "ListPicker_Connect", Text to "Mode" and FontSize to 20.



Wing (Designer)

- 10. Add a Label to show message, rename it to "Label_Wing" and set Text to "Wing control".
- 11. Add two Buttons for wing actions. Rename them to "Button_WingFlap" and "Button_Home". Set FontSize to 20 and Text to "Flap" and "Home".
- 12. Add a HorizontalArrangement component, set **Width** to **Fill parent**, then put components of Step 11 into it.

- 13. Add two labels to show messages. Rename them to
 "Label_LeftWing" and "Label_RightWing". Set their Text to
 "Left Wing (0 outward- 90 backward) " and "Right Wing (180 outward 90 backward) ".
- 14. Add a slider to control left wing position. Rename it to "Label_LeftWing". Set MinValue to 0, MaxValue to 90, Width to Fill parent and ColorLeft to Green.
- 15. Add a slider to control right wing position. Rename it to "Label_RightWing". Set MinValue to 90, MaxValue to 180, Width to Fill parent and ColorLeft to Purple.
- 16. Add a Vertical Arrangement component, set **Width** to **Fill parent**, then add components from Step 13 to 15 into it.
- 17. Wing section finishes as below:



LED (Designer)

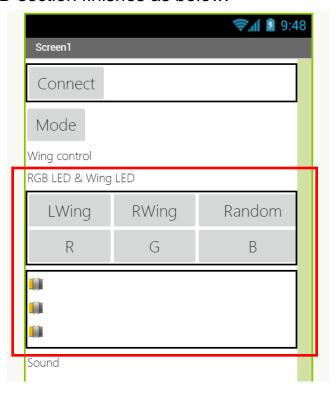
- 18. Add a Label to show message, rename it to "Label_LED" and set Text to "RGB LED & Wing LED".
- 19. Add four buttons for RGB LED actions. Rename them to "Button_LED_R", "Button_LED_G", "Button_LED_B" and "Button_RGB_Random". Set Text to "R", "G", "B", and "Random"; Width to 30 percent; and FontSize to 20.

- 20. Add two more buttons for wing LEDs actions. Rename them as "Button_LED_LeftWing" and "Button_LED_RightWing". Set Text to "L" and "R", Width to 30 percent and FontSize to 20.
- 21. Add a TableArrangement component, set Width to Fill parent, Columns to 3 and Rows to 2. Then add the components from Step 19 to 20 into it.
- of RGB LED. Rename them to "Slider_LED_R",

 "Slider_LED_G" and "Slider_LED_B". Set ColorLeft to Red,

 Green and Blue; Set MinValue to 0, MaxValue to 255 and

 Width to Fill parent.
- 23. Add a Vertical Arrangement component, set **Width** to **Fill parent**, then add components of Step 22 into it.
- 24. LED section finishes as below:



Sound (Designer)

- 25. Add a Label to show message, rename it to "Label_Sound" and set Text to "Sound".
- 26. Add eight buttons to make sounds, Rename them to "Button_C", "Button_D", "Button_E", "Button_F", "Button_G", "Button_A", "Button_B" and "Button_C2". Text to "C", "D", "E", "F", "G", "A", "B" and "C' ". Set Width to 25 percent and FontSize to 20.
- 27. Add a TableArrangement component, set **Width** to **Fill** parent, **Columns** to **4** and **Rows** to **2**. Then add the components of Step 26 into it.
- 28. Sound section finishes as below:



Not all the functions of previous tutorials are included here, for instance specifying sound frequency and time duration. However, you can always tinker with this app and add as many App Inventor components as you like.

Blocks

Let's take a look at our blocks step by step. Notice this time we have a different connection approach than with previous projects. We use ListPicker to select available BluetoothLE device instead of a specified device.

Similar to Designer, we use the same structure to guide you to finish the blocks needed for this project.

Connection (Blocks)

1. Initialize app and scan for nearby Bluetooth devices
In Screen1.Initialize event, we ask BluetoothLE component to
scan for BLE devices nearby (BluetoothLE1.StartScanning).

If any devices are found (**BluetoothLE1.DeviceFound** event), we put these devices into ListPicker.

```
when Screen1 · Initialize
do call BluetoothLE1 · StartScanning

when BluetoothLE1 · DeviceFound
do set ListPicker_Connect · ElementsFromString · to BluetoothLE1 · DeviceList ·
```

2. Choose device with ListPicker

We choose device to connect in a ListPicker. In the **ListPicker.AfterPicking** event, we use the BluetoothLE.Connect method to connect with the device selected.

3. BLE Connected

When connected successfully (BluetoothLE.Connected event),

we will see related messages on several components, hide the ListPicker and show other components. This is because if we send Bluetooth commands without connecting to something first, it may cause error.

```
when BluetoothLE1 v. Connected

do set Screen1 v. Title to f Connected

set ListPicker_Connect visible v to false

set ListPicker_Mode v. Enabled v to true v

set Slider_LeftWing v. ThumbEnabled v to true v

set Slider_LED_R v. ThumbEnabled v to true v

set Slider_LED_G v. ThumbEnabled v to true v

set Slider_LED_B v. ThumbEnabled v to true v

set Slider_LED_B v. ThumbEnabled v to true v

set Button_Disconnect v. Visible v to true v

set Label_Device v. Text v to v join ( Connected to: "

BluetoothLE1 v. ConnectedDeviceName v

call home v
```

4. Another ListPicker to choose one of the modes

To simplify the interface, we separate related components into three groups: Wing, LED and Sound. In the

ListPicker.BeforePicking event, we set the ListPicker elements to a list (Wing, LED, Sound).

Next, in **ListPicker.AfterPicking** event, we set related components to be visible or not according to the selection result.

```
when ListPicker_Mode v .BeforePicking
do set ListPicker_Mode v . Elements v to make a list " Wing "
" LED "
" Sound "
```

5. Button to disconnect

When **Button_Disconnect** is pressed, we close the Bluetooth connection and hide all Layout components.

And when we disconnect successfully

(BluetoothLE.Disconnected event), we reset all components to their initial status and wait for the next connection.

```
when Button_Disconnect v .Click

do call BluetoothLE1 v .Disconnect

set HorizontalArrangement_Wing v . Visible v to false v

set VerticalArrangement_Wing v . Visible v to false v

set TableArrangement_LED v . Visible v to false v

set VerticalArrangement_LED v . Visible v to false v

set TableArrangement_Buzzer v . Visible v to false v
```

```
when BluetoothLE1 . Disconnected

do set Screen1 . Title to wait for connection set ListPicker_Connect . Visible to false set ListPicker_Mode . Enabled to false set Slider_LeftWing . ThumbEnabled to false set Slider_LeftWing . ThumbEnabled to false set Slider_LED_R . ThumbEnabled to false set Slider_LED_R . ThumbEnabled to false set Slider_LED_B . StartScanning
```

Wings (Blocks)

Here we will control the wings by buttons and sliders, as we did in the Codi Bot wing tutorial.

6. Button to move wings to home position

We create a procedure (**home**) to move the wings and sliders back to their home positions, which is **45** for left wing and **135** for right wing.

7. Button to flap wings

This section is exactly the same with <u>Codi Bot wing tutorial</u>. We use **Button_WingFlap** to control the clock timer, which in turn makes the wings flapping.

For simplicity, we create two procedures (**forward**, **backward**) to control the servo motor positions.

```
initialize global flap to false v
when Button_WingFlap .Click
                        TimerEnabled •
            ■Clock1 ▼
                        TimerEnabled •
          set Clock1 ▼
          set Button Winc Flap ▼ . Text ▼
                                               " Flap "
              Clock TimerEnabled •
                   n_WingFlap 🔻
                                 Text ▼
   when Clock1 ▼ .Timer
        📮 if
                    get global flap 🔻
                                              true 🔻
              call forward *
              set global flap v to ( false v
              call backward •
              set global flap ▼ to 📜 true ▼
             to forward

  call MT7697_LeftWingServo ▼

                                            .Write
                                             value |
              call MT7697_RightWingServo ▼ .Write
                                              value
                                                     180
          🔯 to (backward)
              .Write
                                            value
                                                   90

  call MT7697_RightWingServo ▼ .Write

                                              value
```

8. Sliders to move each wing

When you drag a slider, the corresponding servo motor will move to the selected position.

```
when Slider_LeftWing .PositionChanged
 thumbPosition
    set Label_LeftWing . Text to
                                          round get thumbPosition
    ? call MT7697 LeftWii
                               .Write
                                   value
                                                         get thumbPosition
when Slider RightWing PositionChanged
 thumbPosition
    set Label_RightWing •
                                           270
                                           round 🔻 🛴 get (thumbPosition 🔻
    ? call MT7697 RightWingServo .Write
                                                270
                                                round 🔻
                                                        get (thumbPosition
```

LED (Blocks)

Here we are going to control the LEDs with buttons and sliders, as we did in the **Codi Bot LED tutorial**.

9. Button to control RGB LED

These three buttons are used to control the red, green and blue colors of the RGB LED. For the red light, we use

MT7697_LED_R.Write method. Value 255 turns on the red light; and value 0 turns it off. Please finish the other two button events in a same manner.

```
when Button_LED_G ▼ .Click
    🔯 if
                Button_LED_G
                                   Write
    then (2) call MT7697_LED G
                       597 LED G
                                   value
                                    to
                                            " G
  en_Button_LED_B v .Click
do 👩 if
                Button_LED_B
                               . Text ▼
          2 call MT7697_LED_B v .Write
                                   value
                                          255
           set Button LED B *
                              Text ▼ to
              call MT7697_LED_B .Write
                                          0
                                   value

    Button_LED_B ▼
```

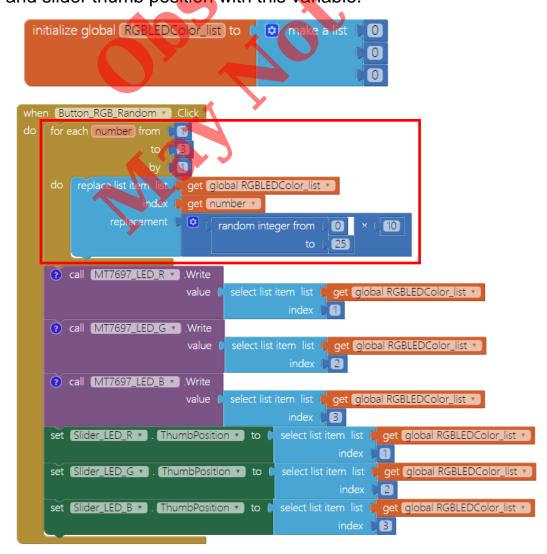
10. Button to control the green and purple wing LEDs

These two buttons are used to control the LEDs of both wings. The idea is the same as in the previous step.

```
when Button_LED_LeftWing . Click
               Button_LED_LeftWing •
                                      Text ▼
                                                       L_Wing
          7 call MT7697_LeftWingLED •
                                       .Write
                                              255
                                        value
          set Button_LED_LeftWing •
                                    Text ▼ to
          call (MT7697_LeftWingLED *)
                                       .Write
          set Button LED LeftWing V
                                    Text ▼ to
when Button_LED_RightWing ▼ .Click
               Button_LED_RightWing •
                                       Text ▼
                                                       " R_Wing
    then ? call MT7697_RightWingLED . Write
                                                255
                                         value
          set Button_LED_RightWing *
          call MT7697_RightWingLED .Write
                                         value 📗
                                                255
          set Button_LED_RightWing •
                                     Text ▼ to
```

11. Button to randomize the RGB LED color

We can also randomize the RGB LED color. When **Button_RGB_Random** is pressed, we use a loop (for each) to replace the **RGBLEDColor_list** variable content with a random number from **0** to **250**. Then we control the corresponding color and slider thumb position with this variable.



12. Sliders to fine tune the RGB LED color

When the slider is dragged, we control the corresponding color by slider thumb position.

```
when Slider_LED_R .PositionChange
 thumbPosition
    (2) call MT7697_LED_R
                             Write
                             value
                                     round
                                               get (thumbPosition
when Slider LED G PositionChanged
thumbPosition
   ? call MT7697_LED_G v .Write
                              value 🔏
                                     round *
                                                get thumbPosition *
when Slider LED B . PositionChanged
thumbPosition
   2 call MTV697 LED_B V .Write
                                                get thumbPosition
                             value (
                                    round *
```

Sound (Blocks)

Here we can play different notes with buttons, which are exactly the same with the **Codi Bot Sound tutorial**.

13. Buttons to make sounds of different notes

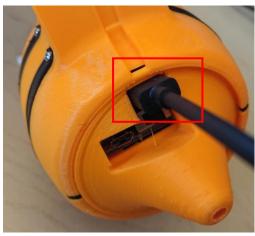
We have eight buttons here. Each of them will tell the buzzer inside the Codi Bot to make a different note. For example, when **Button_C** is pressed (**Button_C.Click** event), we use a **MT7697Buzzer.Buzz** method to make a sound of Note C by specifying the **frequency** as 262 and the **duration** as 200 (milliseconds). Please finish the other seven button events in the same manner.



Arduino IDE and sketch

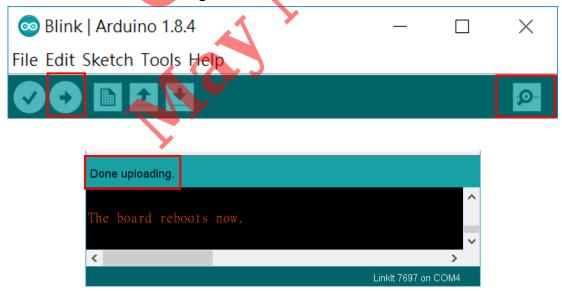
Make sure your computer has Arduino IDE installed and LinkIt 7697 SDK and driver are ready. If not, please check out this <u>Codi Bot</u> Standalone tutorial.

Connect your computer and LinkIt 7697 with a microUSB cable.

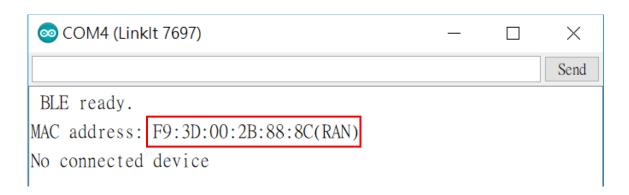


Please download the Arduino sketch from here and open it in your Arduino IDE. This sketch can be used for all following Codi Bot projects, to allow you to focus on building App Inventor projects you will enjoy.

Press the "**Upload**" right-arrow button of Arduino IDE. This will compile and upload the Arduino sketch to your LinkIt 7697. Please make sure you can see the "**done uploading**" message in the console before continuing.

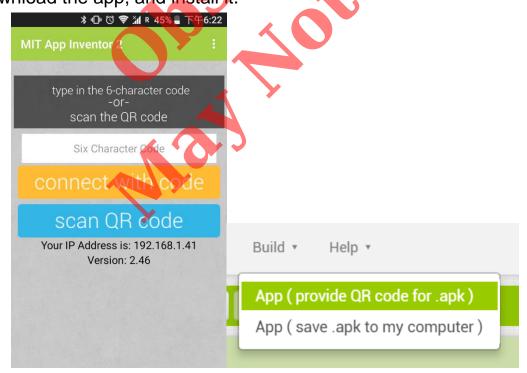


Click the magnifier icon at the up-right corner of Arduino IDE. You should see a message in the pop-up window. The [XX:XX:XX:XX:XX] 12-digit string is the Bluetooth address of your Linklt 7697. We will choose the device of this address in our app.



Tips

Make sure your LinkIt 7697 is running correctly. And install App Inventor project on your Android phone by clicking Build / App (provide QR code for .apk), this will show a QR code for the .apk file of this project. Use MIT AI2 Companion to scan this QR code, download the app, and install it.



Open Codi Bot app (Fig 1.) and click **Connect** ListPicker. You'll see a list of available Bluetooth devices (Fig 2). In general, the first item is the Codi Bot where "**F9:3D:00:2B:88:8C**" is the Bluetooth address of my Codi Bot. Click it and your phone will try to connect with the Codi Bot, If it connects successfully, you will see your app like in Fig 3.

Click **Mode** ListPicker to choose which mode you want to play with: **Wing**, **LED** or **Sound** (Fig. 4). Choose one to interact with your Codi Bot (Fig 5 to Fig 7). Remember to click the **Disconnect** button when you finish with this project.

