

Assume 
$$K_0 = \frac{A_0 E}{L}$$
  
 $K_1 = 5K_0$   $K_2 = 3K_0$ .  
Gonvert stiffness (spering)  
 $\frac{3k_0}{2}$   $\frac{3k_0}{3}$ 

. Matrix Foundin

$$\begin{bmatrix} R_1 \\ R_2 \end{bmatrix} = \begin{bmatrix} 5k_0 & 5k_0 & 6 \\ -5k_0 & 5k_0 + 3k_0 & -3k_0 \\ 0 & -3k_0 & 3k_0 \end{bmatrix} \begin{bmatrix} U_1 \\ U_2 \\ U_3 \end{bmatrix}$$

Boundary Condition 0,=0, R=R, D2=0, R3=P

$$\begin{bmatrix} R_{1} \\ O \end{bmatrix} = \begin{bmatrix} SK_{6} & -SK_{6} & 0 \\ -SK_{6} & 8K_{6} & -3K_{6} \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ -SK_{6} & 8K_{6} & -3K_{6} \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ -SK_{6} & 8K_{6} & -3K_{6} \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ -SK_{6} & 0 \\ 0 \end{bmatrix} = \begin{bmatrix} SK_{6} & 0 \\ 0 \\ -SK_{6} & 0 \\ 0 \end{bmatrix} = \begin{bmatrix} SK_{6} & 0 \\ 0 \\ -SK_{6} & 0 \\ 0 \end{bmatrix} = \begin{bmatrix} SK_{6} & 0 \\ 0 \\ -SK_{6} & 0 \\ 0 \end{bmatrix} = \begin{bmatrix} SK_{6} & 0 \\ 0 \\ -SK_{6} & 0 \\ 0 \end{bmatrix} = \begin{bmatrix} SK_{6} & 0 \\ 0 \\ -SK_{6} & 0 \\ 0 \end{bmatrix} = \begin{bmatrix} SK_{6} & 0 \\ 0 \\ -SK_{6} & -SK_{6} \\ -SK_{6} & -SK_{6$$

$$\begin{bmatrix} R_1 \\ R_2 \\ R_3 \end{bmatrix} = \begin{bmatrix} 11k_0 & -11k_0 & 0 & 0 & 0 \\ -11k_0 & 11k_0 + 3k_0 & -3k_0 & 0 & 0 \\ 0 & -3k_0 & 9k_0 + 7k_0 & -7k_0 & 0 \\ 0 & -7k_0 & 7k_0 + 7k_0 & -7k_0 \\ 0 & 0 & -5k_0 & 5k_0 \end{bmatrix} \begin{bmatrix} U_1 \\ U_2 \\ U_3 \\ U_4 \\ U_5 \end{bmatrix}$$

- for 2 Element

Mone Element system is more accurate.

## Input for C, D & E:-

```
Young's Modulus of bar material: 5000000
Length of bar: 500
Cross section Area at the free end: 10
Value of force applied at end: 1000
Input array of no. of Quadratic elements to discretize: [2 4 6 8 10]
% Linear elements - Displacement of bar due to load at free end, fixed at
another
clc,clearvars,format compact,close all
E = input("Young's Modulus of bar material: ");
1 = input("Length of bar: ");
A l = input("cross section Area at the free end: ");
P = input("Value of force applied at end: ");
n = input("Input array of no. of linear elements to discretize: ");
disp_end_lin = [];
for i = 1:length(n)
 e_n = zeros(n(i),2); %element node connectivity relation
 for j = 1:n(i)
 e_n(j,:) = [j j+1]; %i th row gives i th element's node connectivity
 end
 l_e = 1/n(i); %Length of each element
 no_nodes = max(e_n,[],'all'); %no. of nodes
 force = zeros(no nodes,1);
 stiffness = zeros(no_nodes);
 displacement = zeros(no nodes,1);
 g = 1;
 h = setdiff(1:no_nodes,g);
 r = no_nodes;
 force(r,1) = P;
 reduced_force = force(h, :);
 %Creating Stiffness matrix
```

```
for j = 1:n(i)
 t = 3 - (((2*j)-1)/n(i));
 T = (E*A l*t)/l e;
 r = e_n(j,1); % left node no. of element j
 s = e_n(j,2); % right node no. of element j
 stiffness(r,r) = stiffness(r,r) + T;
 stiffness(s,s) = stiffness(s,s) + T;
 stiffness(r,s) = stiffness(r,s) - T;
 stiffness(s,r) = stiffness(s,r) - T;
 end
 zero_disp_nodes = g;
 active_nodes = setdiff(1:no_nodes,zero_disp_nodes); % nodes with unknown
displacement
 reduced stiffness = stiffness;
 reduced stiffness = reduced_stiffness(:,active_nodes); %A([3,9],:) = [];
Deletes rows
 reduced_stiffness = reduced_stiffness(active_nodes,:); %keeps rows and
columns of active nodes in stifness matrix in order to solve for unknown
displacements.
 unknown disp = inv(reduced stiffness)*reduced force;
 for j = 1:length(active_nodes)
 displacement(active_nodes(j)) = unknown_disp(j);
 end
 fprintf("\n%d linear elements", n(i))
 fprintf("\nDisplacement at end = %d", displacement(no_nodes))
 disp_end_lin(end+1) = displacement(no_nodes);
end
%Plotting
X = n;
Y = disp end lin;
plot(X,Y);
hold on
plot(X,Y,'bv','MarkerFaceColor','b');
title('Displacement at End vs. No. of Elements')
ylabel('Displacement')
xlabel('No. of Elements')
```

```
grid on
analy_soln = (P*l*log(3))/(2*E*A_l);
yline(analy_soln,'m','LineWidth',1.5)
legend('','FEM Solution(Linear)','Exact
Solution','Location','Northwest','Orientation','vertical');
```

#### Output: -

```
2 linear elements
Displacement at end = 5.333333e-03
4 linear elements
Displacement at end = 5.448773e-03
6 linear elements
Displacement at end = 5.472906e-03
8 linear elements
Displacement at end = 5.481624e-03
10 linear elements
Displacement at end = 5.485710e-03
```

### D.

```
% Quadratic elements
clc,clearvars,format compact,close all
E = input("Young's Modulus of bar material: ");
l = input("Length of bar: ");
A_l = input("cross section Area at the free end: ");
P = input("Value of force applied at end: ");
n = input("Input array of no. of Quadratic elements to discretize: ");
disp_end_quad = [];
for i = 1:length(n)
e_n = zeros(n(i),3); %element node connectivity relation

v = 1;
```

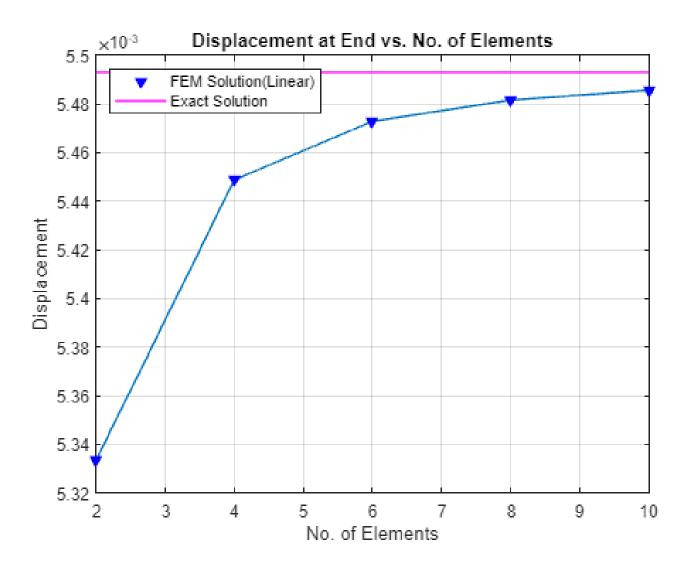
```
for j = 1:n(i)
e_n(j,:) = [v v+1 v+2]; %i th row gives i th element's node
connectivity
v = v+2;
end
1 e = 1/n(i); %Length of each element
no nodes = max(e n,[],'all'); %no. of nodes
force = zeros(no nodes,1);
stiffness = zeros(no nodes);
displacement = zeros(no nodes,1);
g = 1;
h = setdiff(1:no_nodes,g);
r = no_nodes;
force(r,1) = P;
reduced force = force(h, :);
%Creating Stiffness matrix
for j = 1:n(i)
t = 3 - (((2*j)-1)/n(i));
T = (E*A_1*t)/(3*1_e);
q = e_n(j,1); % left node no. of element j
 r = e n(j,2); % middle node no. of element j
s = e_n(j,3); % right node no. of element j
%Diagonal elements
stiffness(q,q) = stiffness(q,q) + (7*T);
stiffness(r,r) = stiffness(r,r) + (16*T);
 stiffness(s,s) = stiffness(s,s) + (7*T);
%Upper diagonal elements
 stiffness(q,r) = stiffness(r,s) - (8*T);
stiffness(q,s) = stiffness(s,r) + T;
 stiffness(r,s) = stiffness(r,s) - (8*T);
%Lower diagonal elements
```

```
stiffness(r,q) = stiffness(q,r);
 stiffness(s,q) = stiffness(q,s);
stiffness(s,r) = stiffness(r,s);
end
 zero disp nodes = g;
 active nodes = setdiff(1:no nodes, zero disp nodes); % nodes with
unknown displacement
 reduced stiffness = stiffness;
 reduced stiffness = reduced_stiffness(:,active_nodes);
A([3,9],:) = []; Deletes rows
 reduced stiffness = reduced stiffness(active nodes,:); %keeps
rows and columns of active nodes in stifness matrix in order to
solve for unknown displacements.
 unknown disp = inv(reduced stiffness)*reduced force;
for j = 1:length(active nodes)
displacement(active nodes(j)) = unknown disp(j);
end
fprintf("\n%d Quadratic elements", n(i))
fprintf("\nDisplacement at end = %d", displacement(no nodes))
disp end quad(end+1) = displacement(no nodes);
end
%Plotting
X = n;
Y = disp end quad;
plot(X,Y);
hold on
plot(X,Y,'bv','MarkerFaceColor','b');
title('Displacement at End vs. No. of Elements')
ylabel('Displacement')
xlabel('No. of Elements')
grid on
analy soln = (P*1*log(3))/(2*E*A 1);
yline(analy_soln, 'm', 'LineWidth', 1.5)
legend('','FEM Solution','Exact
Solution','Location','Northwest','Orientation','vertical');
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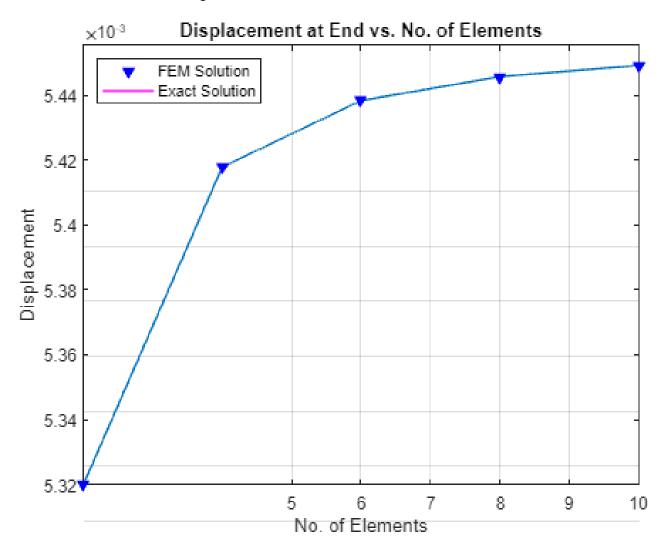
#### Output: -

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```

## Linear elements



# **Quadratic** elements



#### F. Conclusions:-

- ✓ As number of elements increase, the rate of convergence to exact solution decreases, for both the linear and quadratic elements.
- ✓ So, for infinite number of elements, FEM model gives approximate exact solution.
- ✓ Even with finite number of elements, the error in FEM solution is very small, so can be used up to good approximation.
- ✓ According to the application of problem and computation power available, one can decide the extent of discretization of model, which comes with the penalty of errors.