

Comparison of Random Walk based techniques for estimating network averages

Jithin K. Sreedharan

INRIA, France

Konstantin Avrachenkov

INRIA, France

Vivek S. Borkar

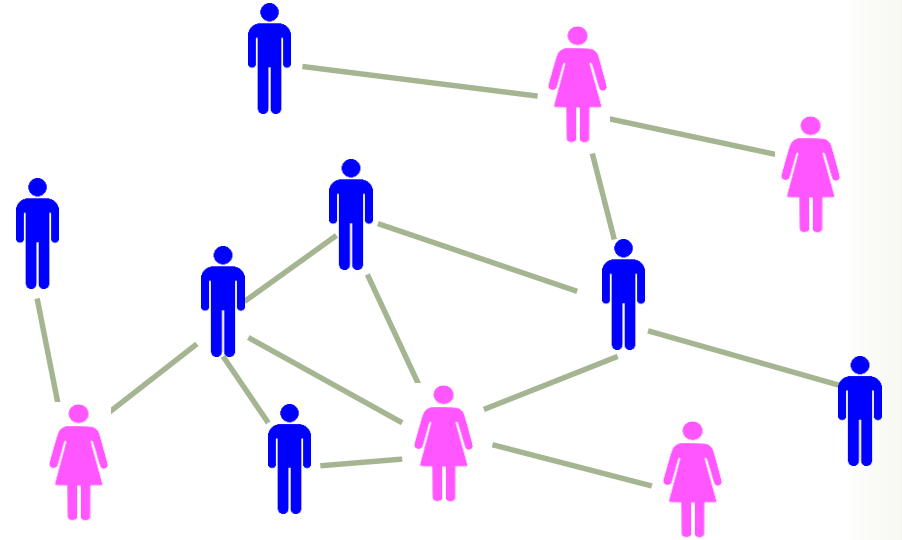
IIT Bombay, India

Arun Kadavankandy

INRIA, France

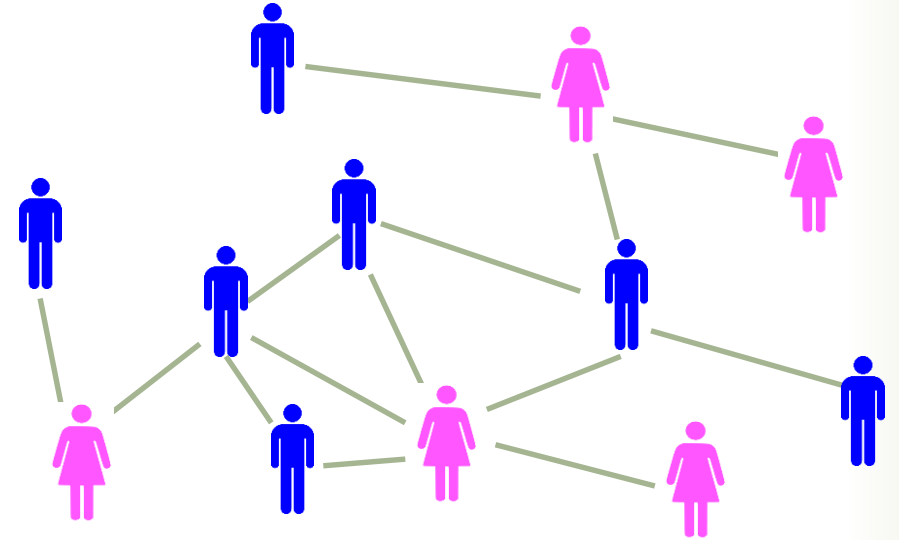
Motivation

- Estimation in Online Social Network (OSN)
- **Example:**
What proportion of a population supports a given political party?
How young a given social network is?



Motivation

- Estimation in Online Social Network (OSN)
- **Example:**
What proportion of a population supports a given political party?
How young a given social network is?



Easy to answer if the graph is fully known beforehand

What if the network is not known?

- Can only crawl network
- Few queries

Problem definition

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Let $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

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- Undirected graph

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Estimate $\mu(\mathcal{G}) = \frac{1}{|\mathcal{V}|} \sum_{u \in \mathcal{V}} f(u)$

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- Graph is unknown

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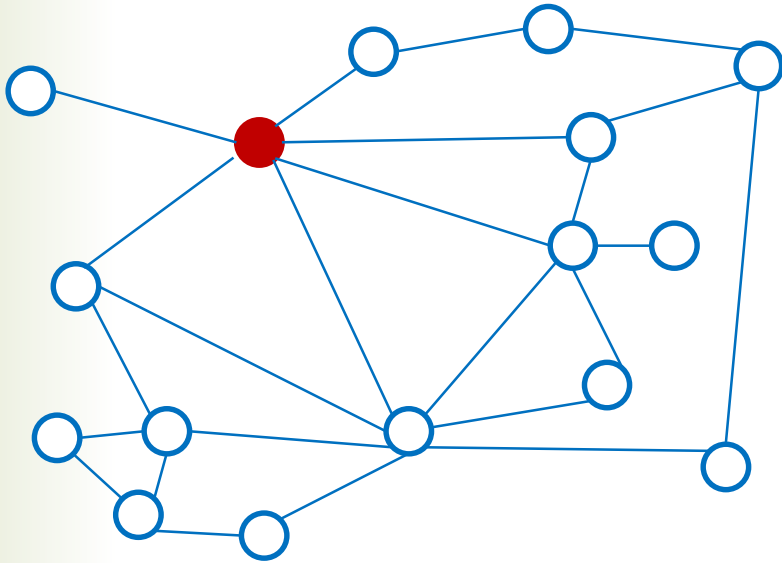
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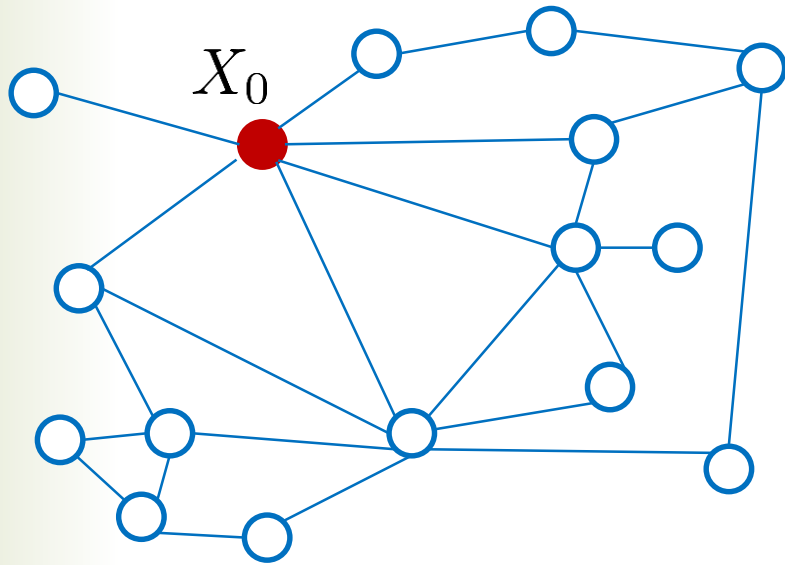
- Graph is unknown
 - Only local information available
- | | | |
|--|---|--------------------------------------|
| | { | Seed nodes and their neighbor IDs |
| | | Query (visit) a neighbor |
| | | Visited nodes and their neighbor IDs |

Random Walk based estimation

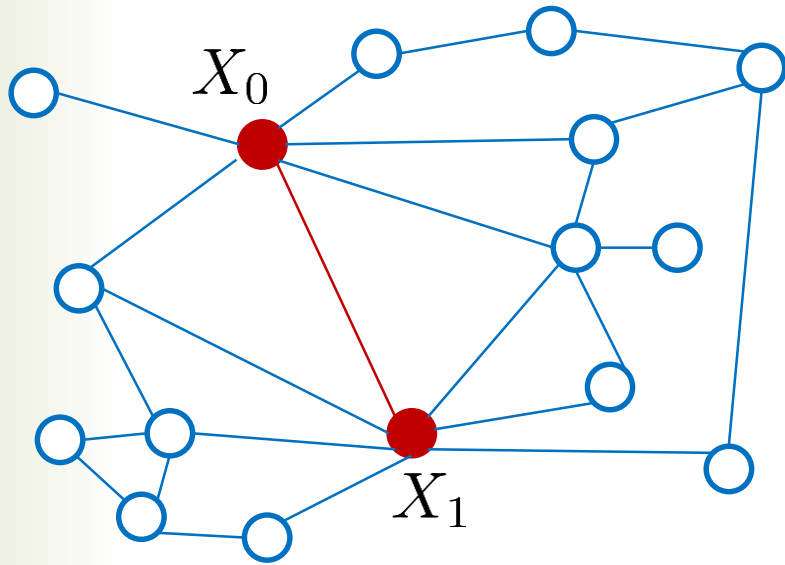
Random Walk based estimation



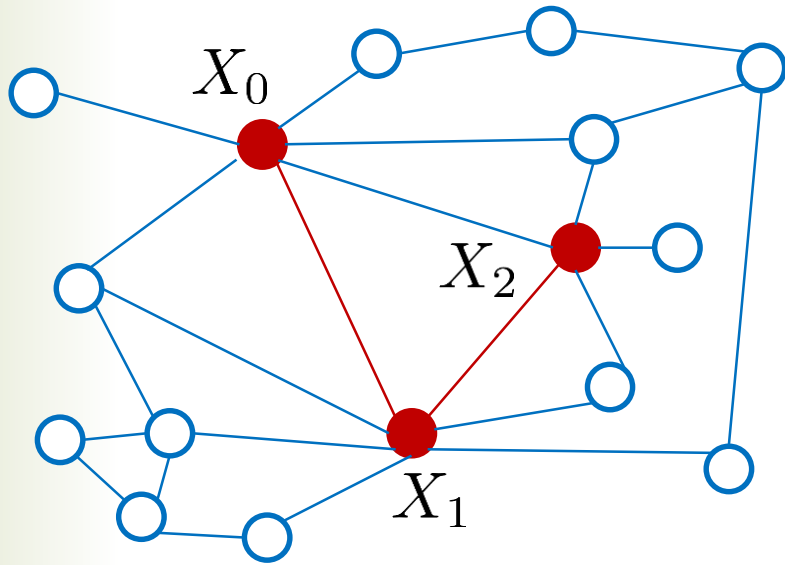
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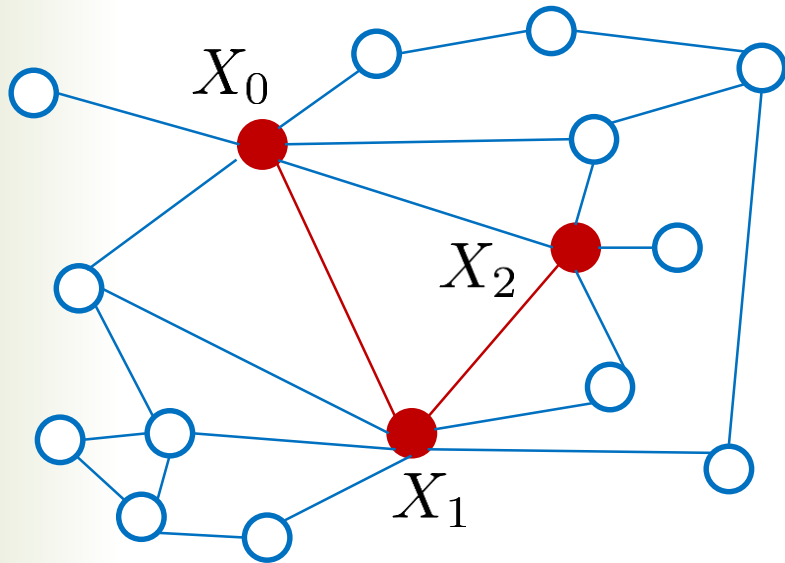


Random Walk based estimation



Random Walk based estimation

Random walk $\{X_k\}_{k \geq 0}$ has unique stationary distribution $\{\pi_i\}_{i=1}^n$ if graph G is connected and non-bipartite

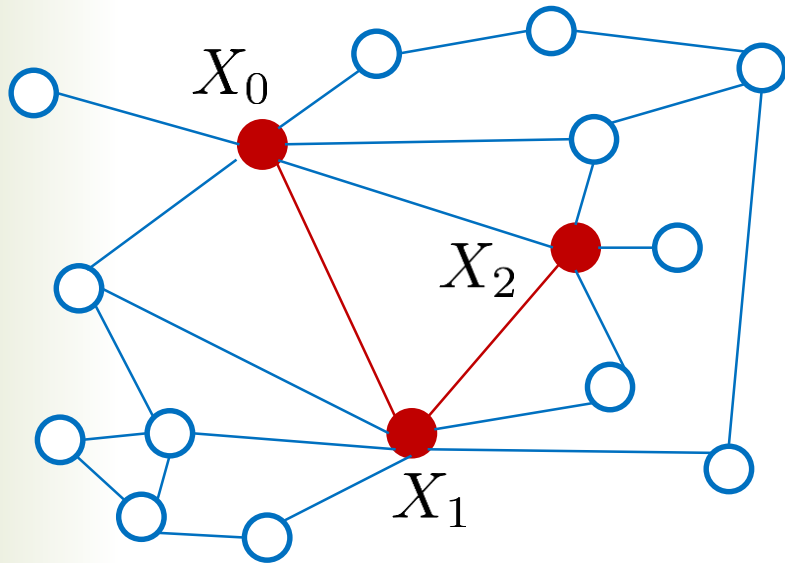


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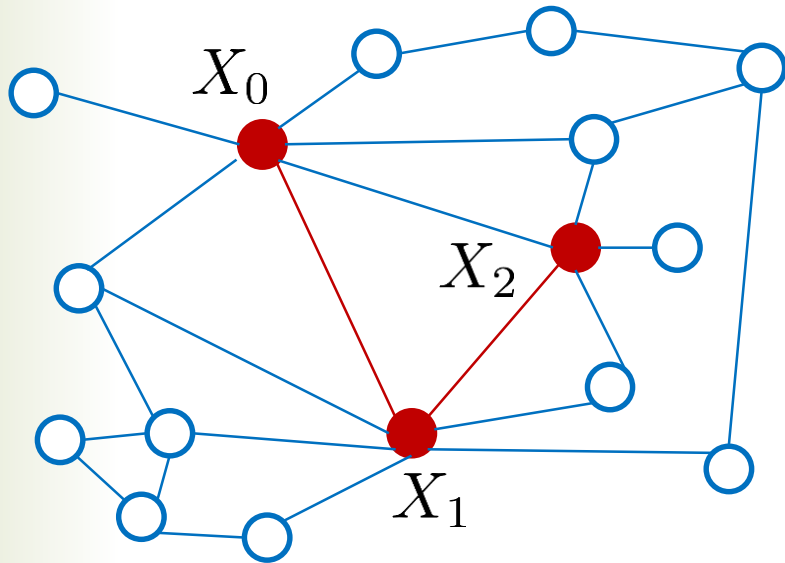
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$$\text{Estimate } \mu(\mathcal{G}) = \frac{1}{|\mathcal{V}|} \sum_{u \in \mathcal{V}} f(u)$$



Random Walk based estimation

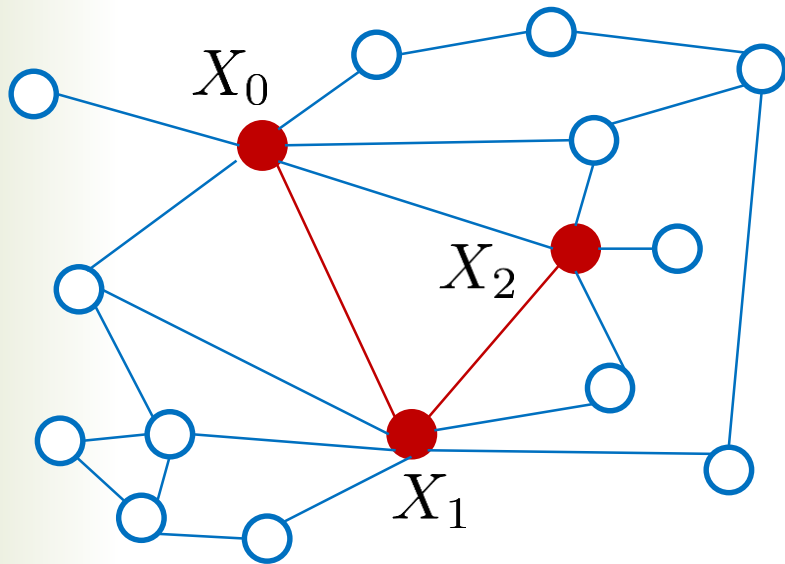
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- How: Ergodic theorem

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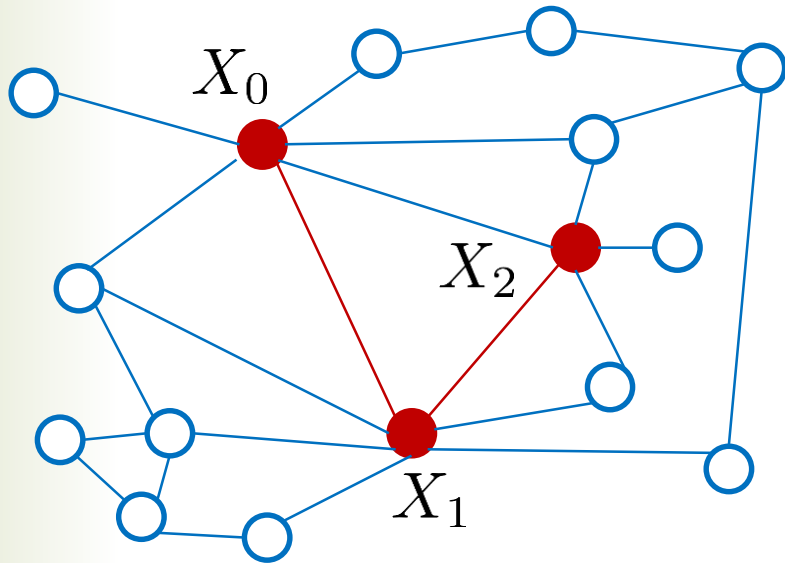
- How: Ergodic theorem

For any initial distribution,

$$\frac{1}{n} \sum_{k=0}^n f(X_k) \rightarrow \sum_{u \in \mathcal{V}} \pi_u f(u) \quad \text{a.s.}$$

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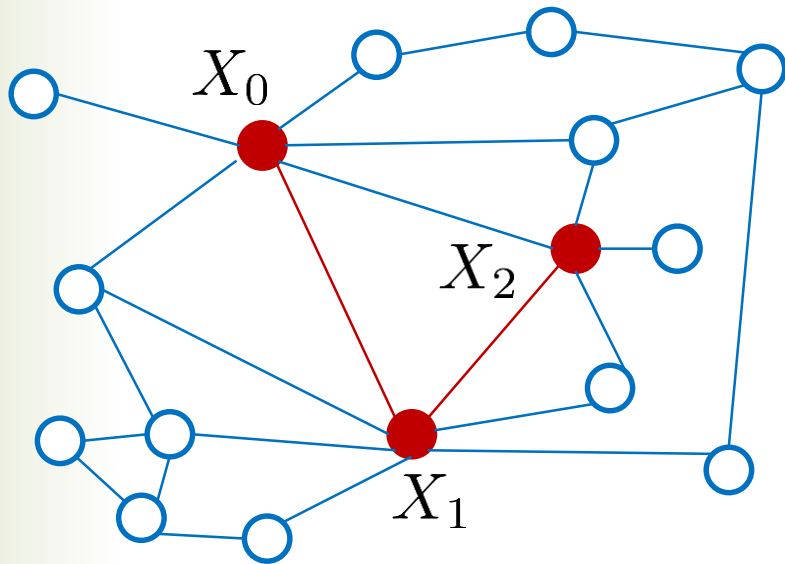
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How to make $\pi_u = \frac{1}{|\mathcal{V}|}$?

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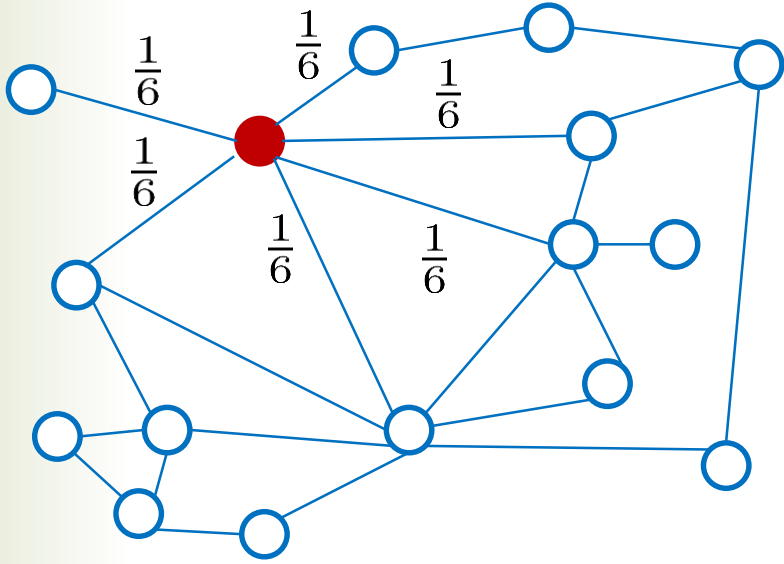
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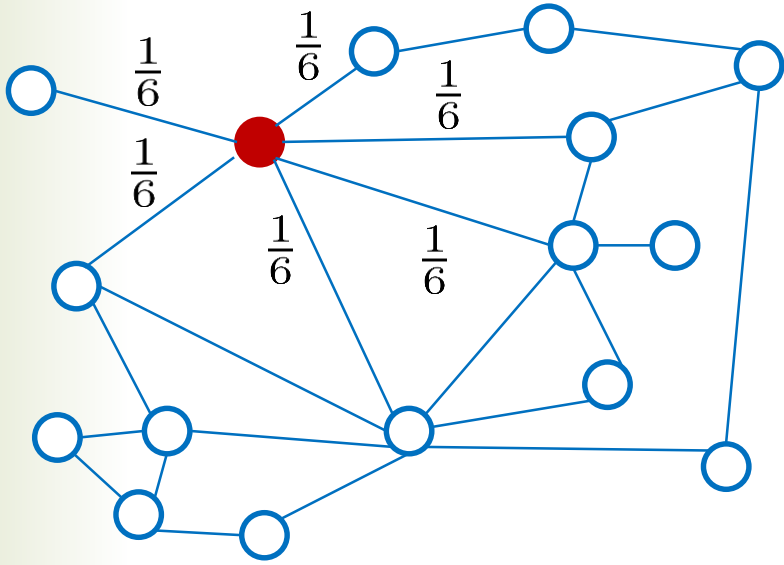
How to compare different random walks?

Respondent Driven Sampling

Respondent Driven Sampling



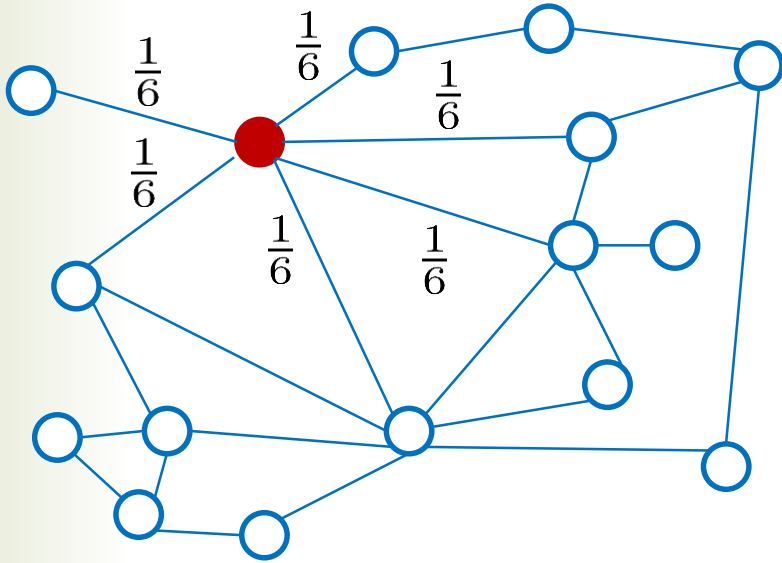
Respondent Driven Sampling



- With re-weighting the function f

$$f'(u) = \frac{f(u)}{|\mathcal{V}| \pi_u}$$

Respondent Driven Sampling

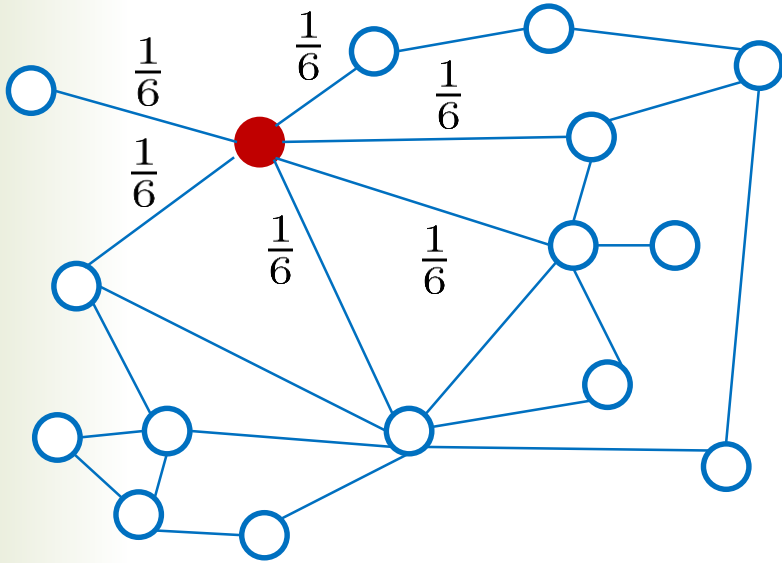


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Requires knowledge of no. of nodes and no. of edges

Respondent Driven Sampling



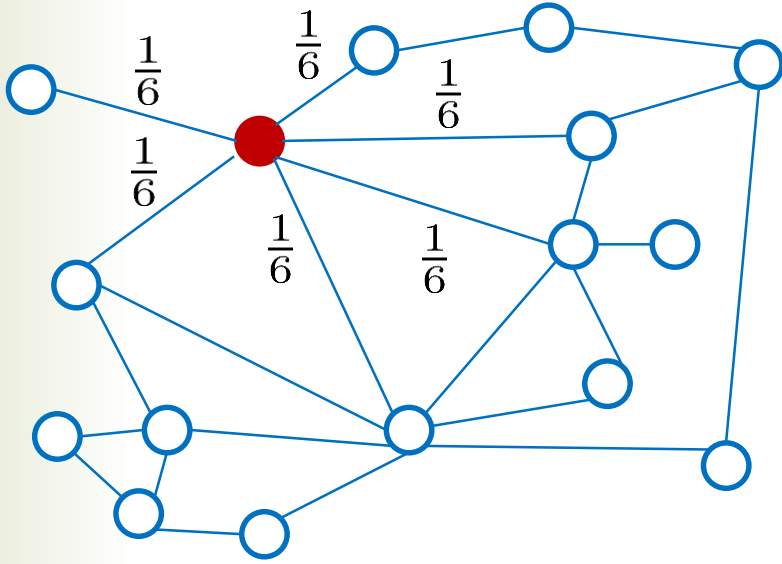
- With re-weighting the function f

$$f'(u) = \frac{f(u)}{|\mathcal{V}| \pi_u}$$

Requires knowledge of no. of nodes and no. of edges

Estimator:
$$\frac{1}{\sum_{k=1}^n \frac{1}{\deg(X_k)}} \sum_{k=1}^n \frac{f(X_k)}{\deg(X_k)}$$

Respondent Driven Sampling



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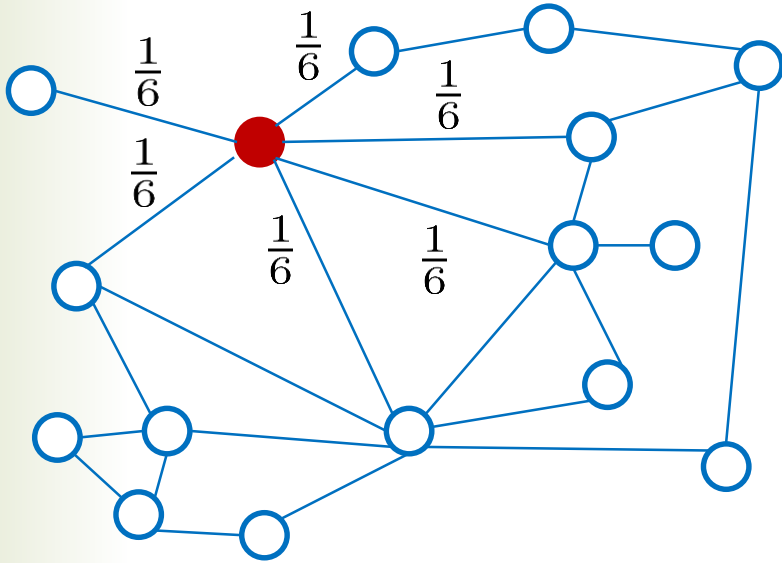
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\searrow

$\frac{|\mathcal{V}|}{2|\mathcal{E}|}$

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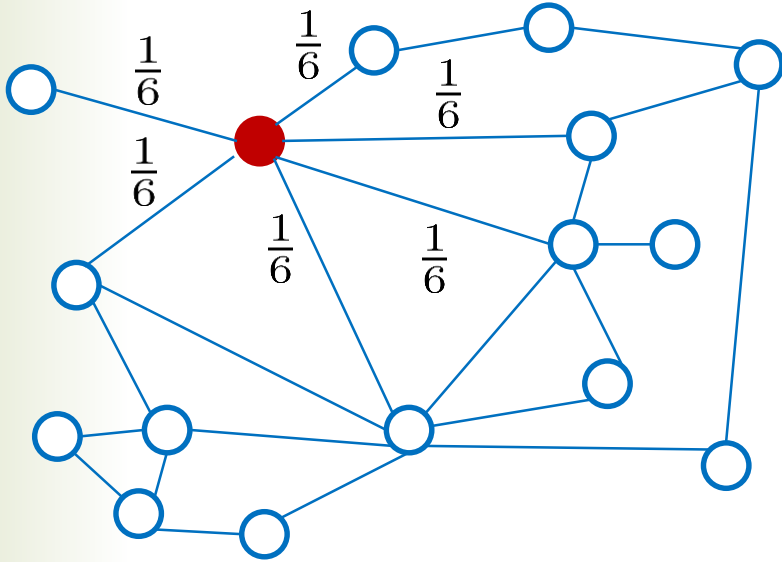
Estimator:

$$\frac{1}{\sum_{k=1}^n \frac{1}{\deg(X_k)}} \sum_{k=1}^n \frac{f(X_k)}{\deg(X_k)}$$

↗ $\frac{1}{2|\mathcal{E}|} \sum_{u \in \mathcal{V}} f(u)$

↘ $\frac{|\mathcal{V}|}{2|\mathcal{E}|}$

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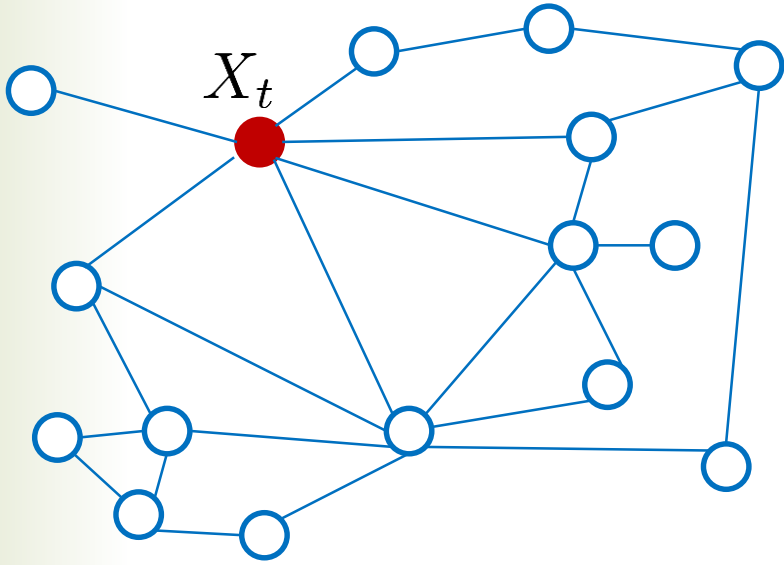
Estimator:

$$\frac{1}{\sum_{k=1}^n \frac{1}{\deg(X_k)}} \sum_{k=1}^n \frac{f(X_k)}{\deg(X_k)} \rightarrow \frac{1}{|\mathcal{V}|} \sum_{u \in \mathcal{V}} f(u) \text{ a.s.}$$

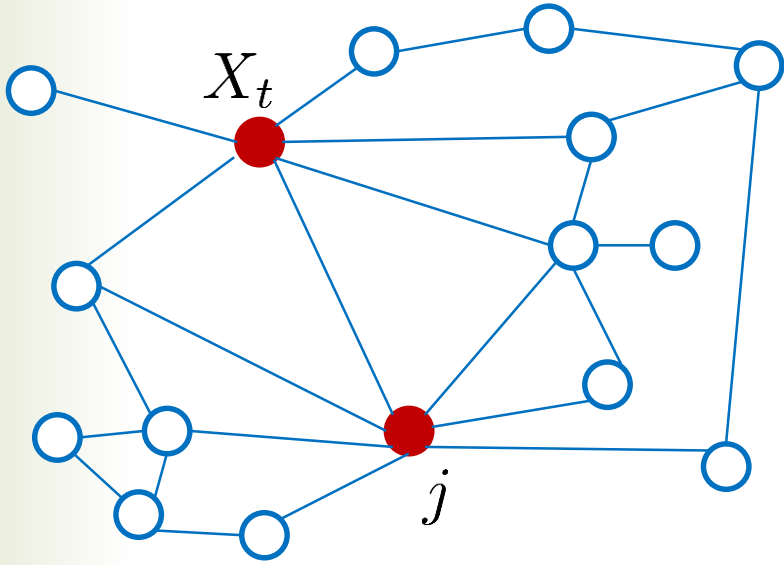
Annotations:

- A blue arrow points from the denominator $\sum_{k=1}^n \frac{1}{\deg(X_k)}$ to the expression $\frac{1}{2|\mathcal{E}|} \sum_{u \in \mathcal{V}} f(u)$.
- A blue arrow points from the fraction $\frac{1}{2|\mathcal{E}|}$ to the expression $\frac{|\mathcal{V}|}{2|\mathcal{E}|}$.

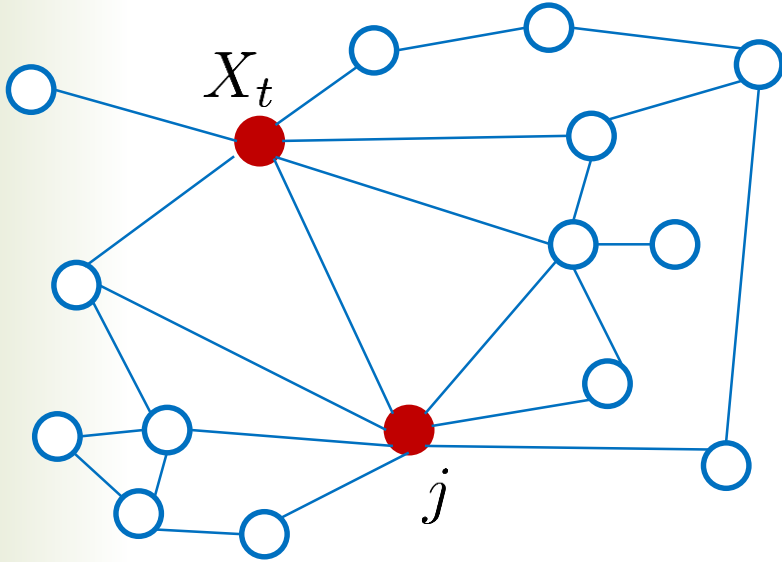
Metropolis Hastings Sampling



Metropolis Hastings Sampling

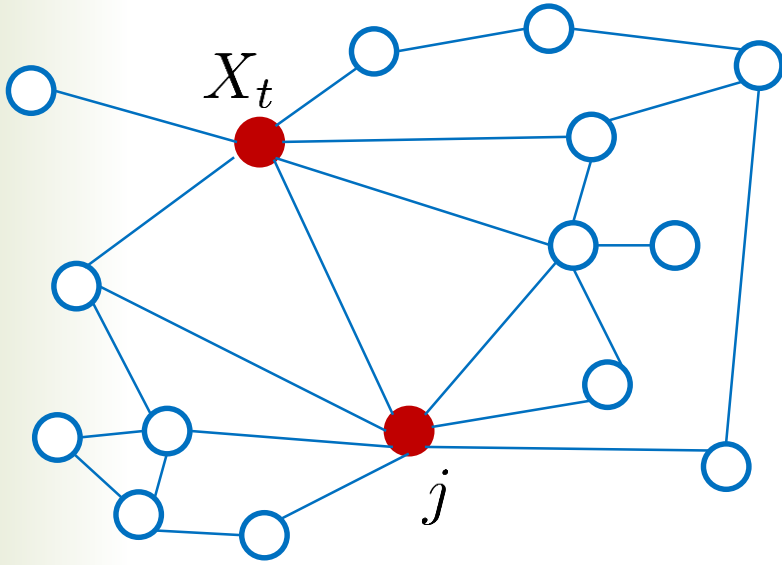


Metropolis Hastings Sampling



$$\Pr(\text{head}) := \min \left\{ 1, \frac{\deg(X_t)}{\deg(j)} \right\}$$

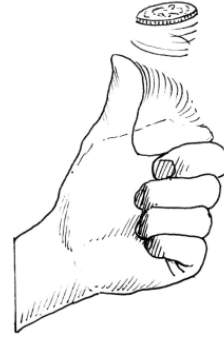
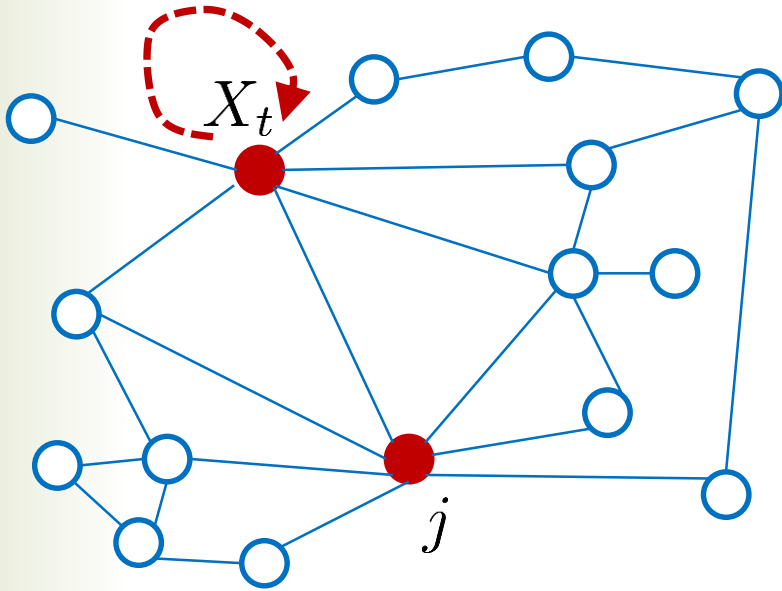
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If head appears: move to j

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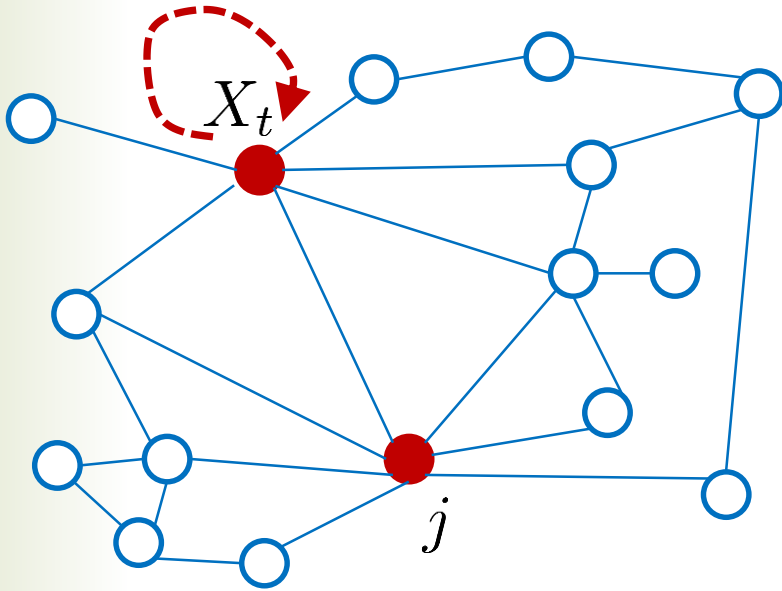


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If head appears: move to j

If tail appears: stays at X_t

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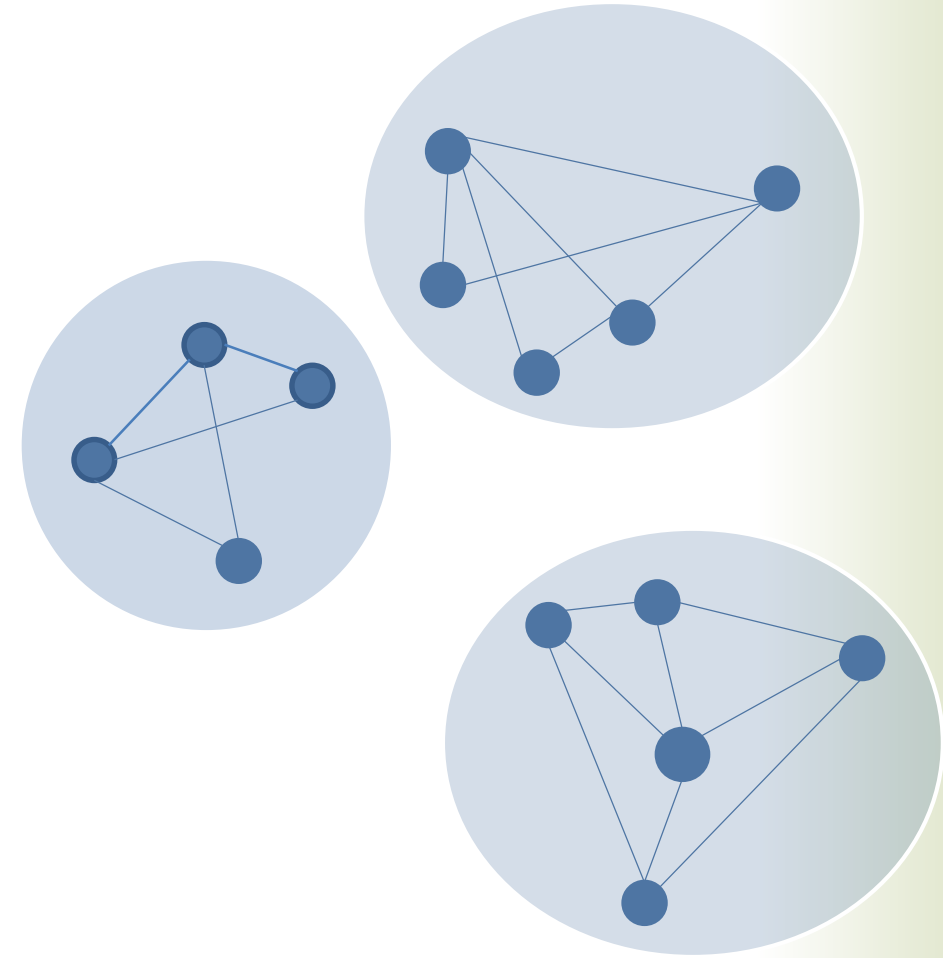
For any initial distribution,

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Reinforcement Learning technique

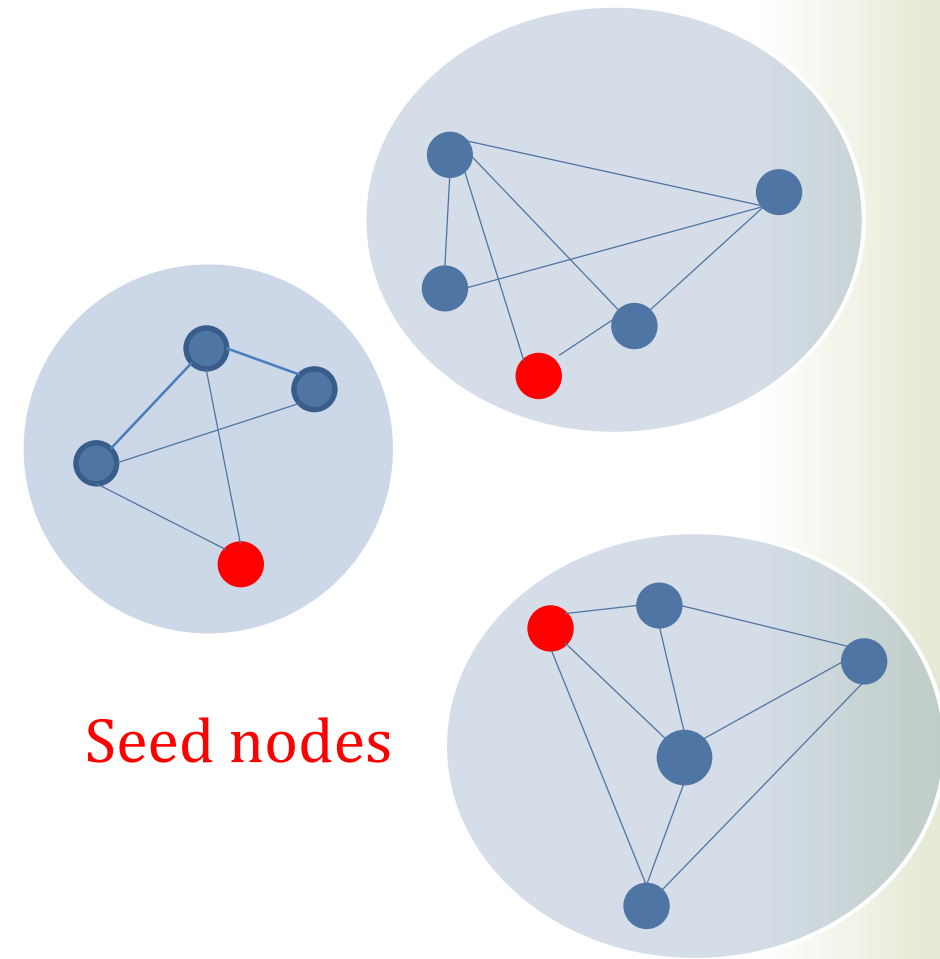
Reinforcement Learning technique

- Graph not necessarily connected or has included connected components of interest



Reinforcement Learning technique

- Graph not necessarily connected or has included connected components of interest
- Few seed nodes

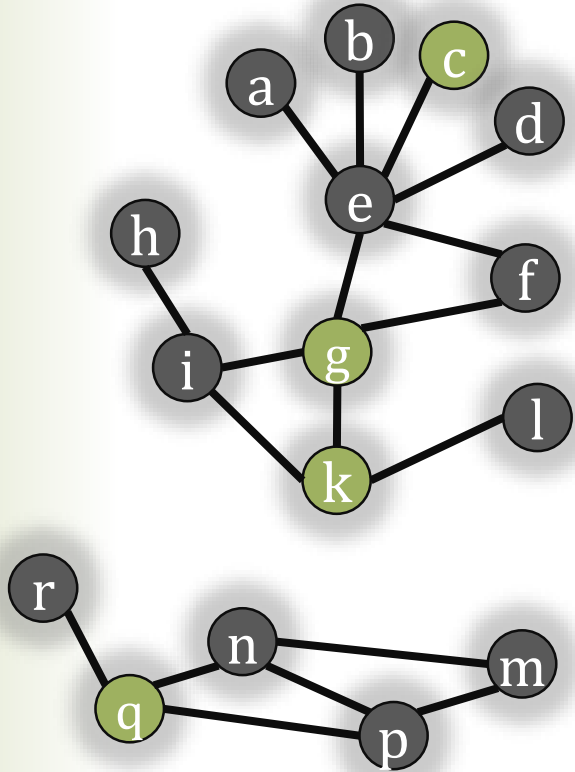


Idea of tours

γ_0

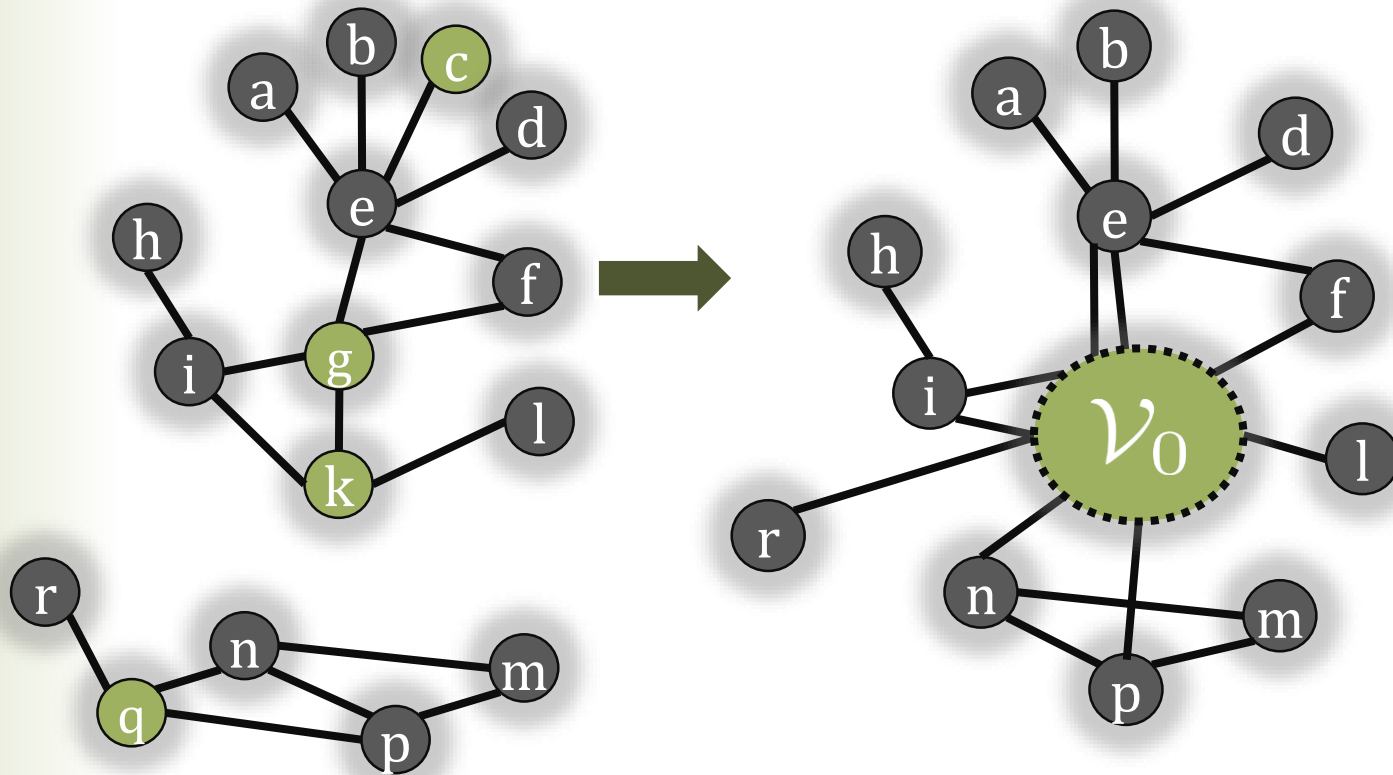
Idea of tours

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$



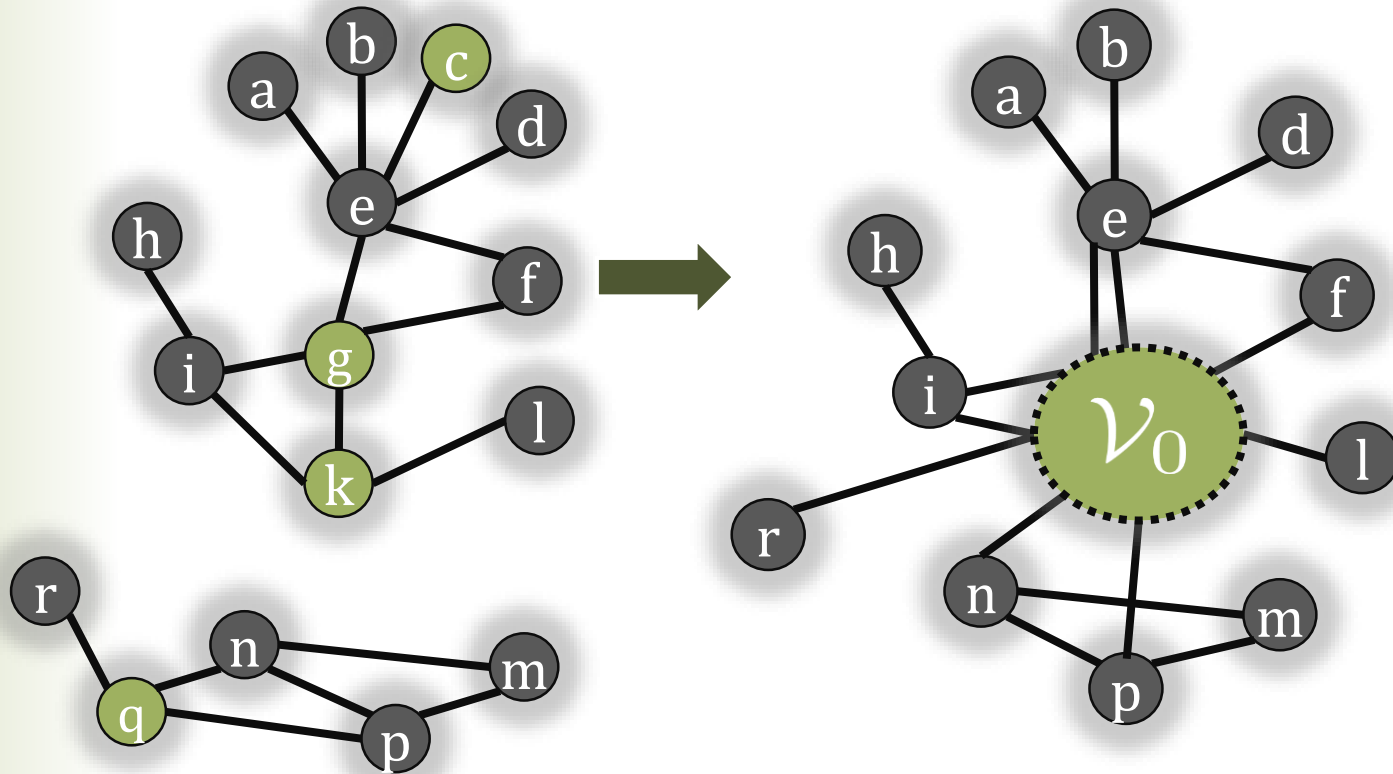
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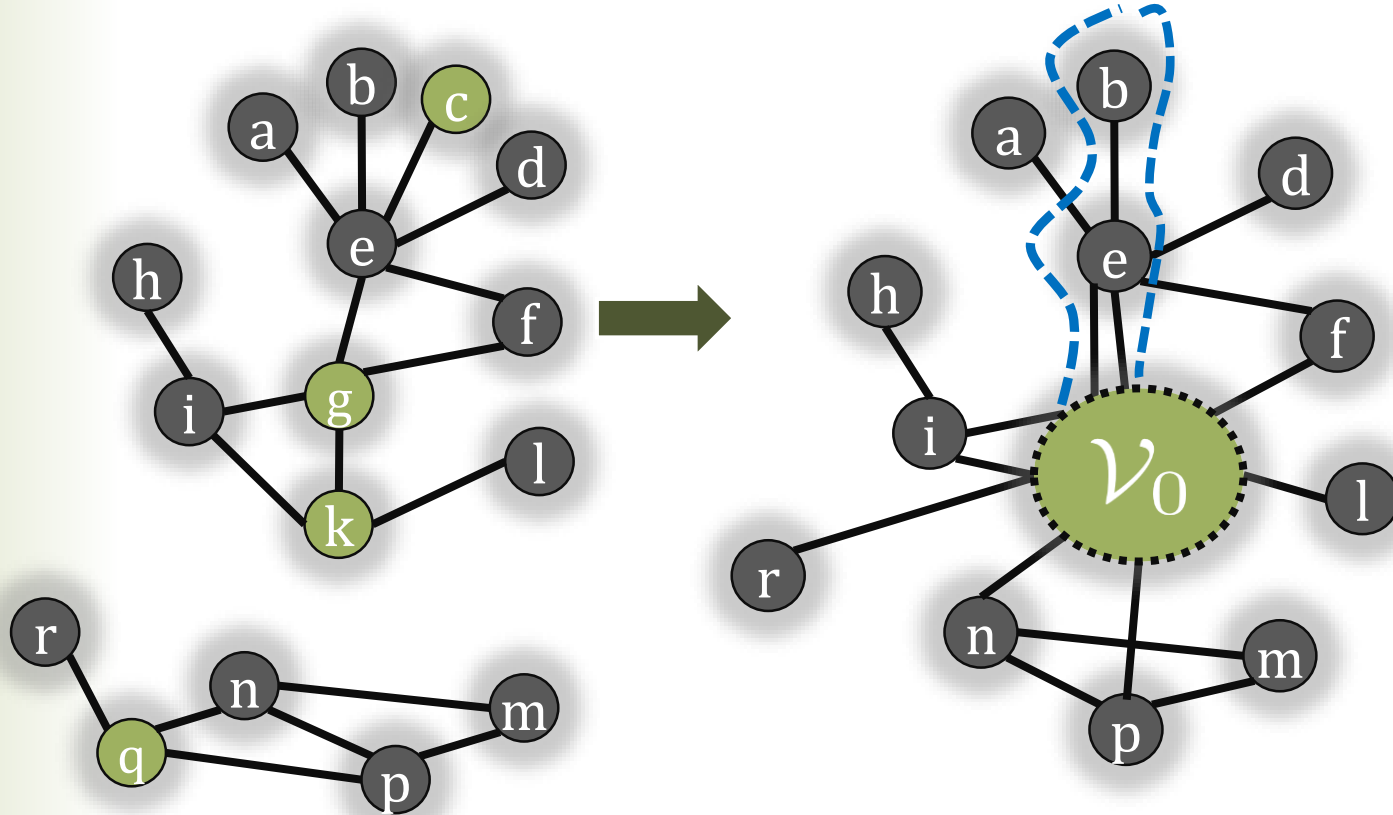
$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$



Sample
 $z \sim \text{Uniform}(\mathcal{V}_0)$

Idea of tours

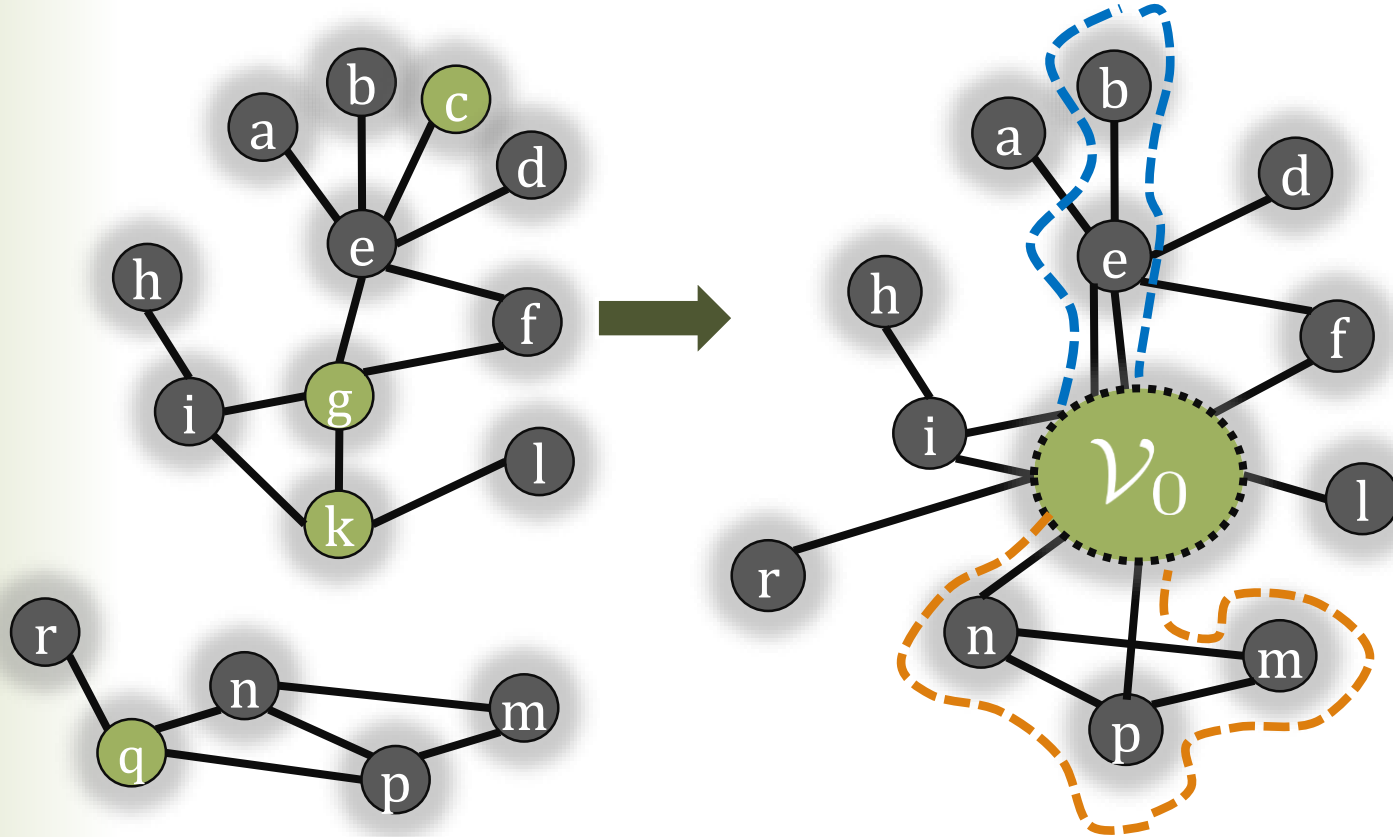
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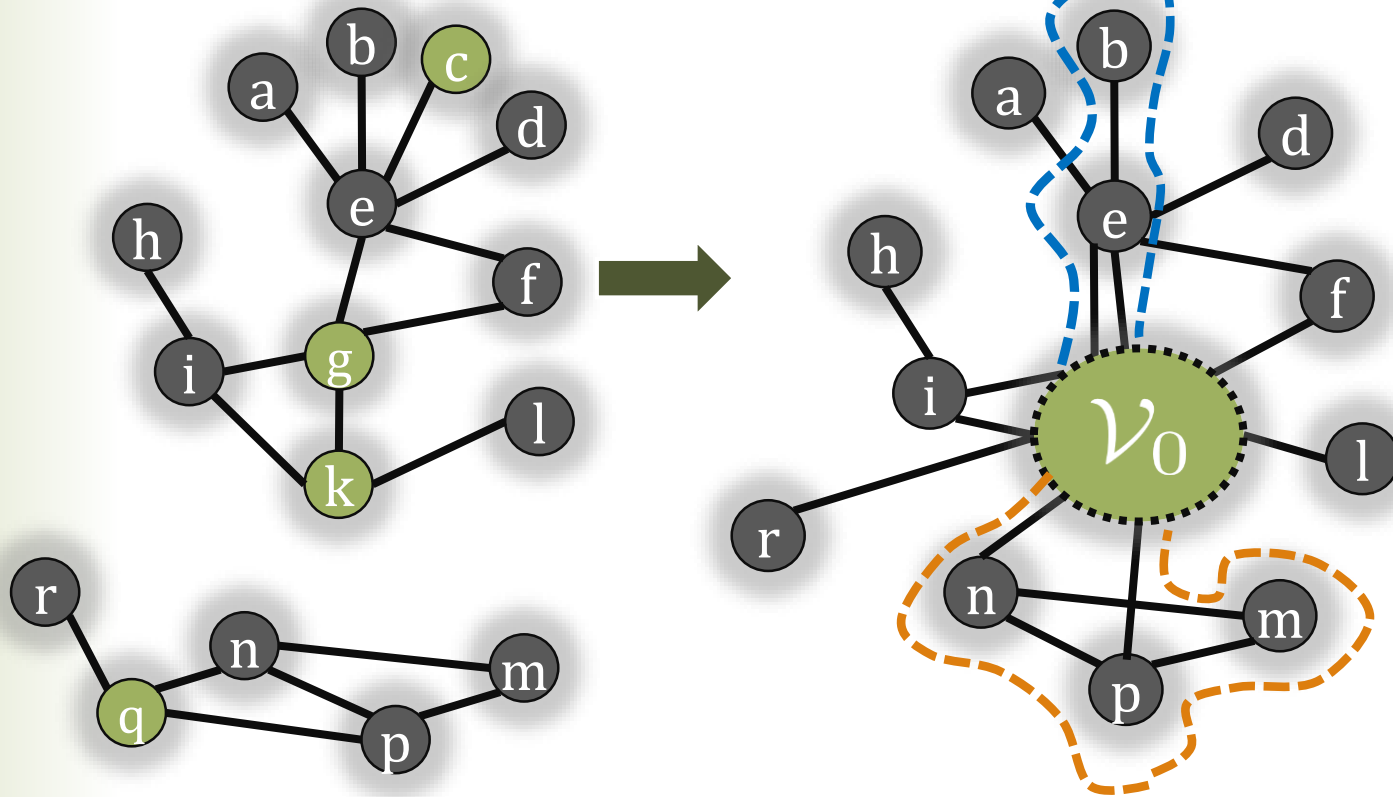
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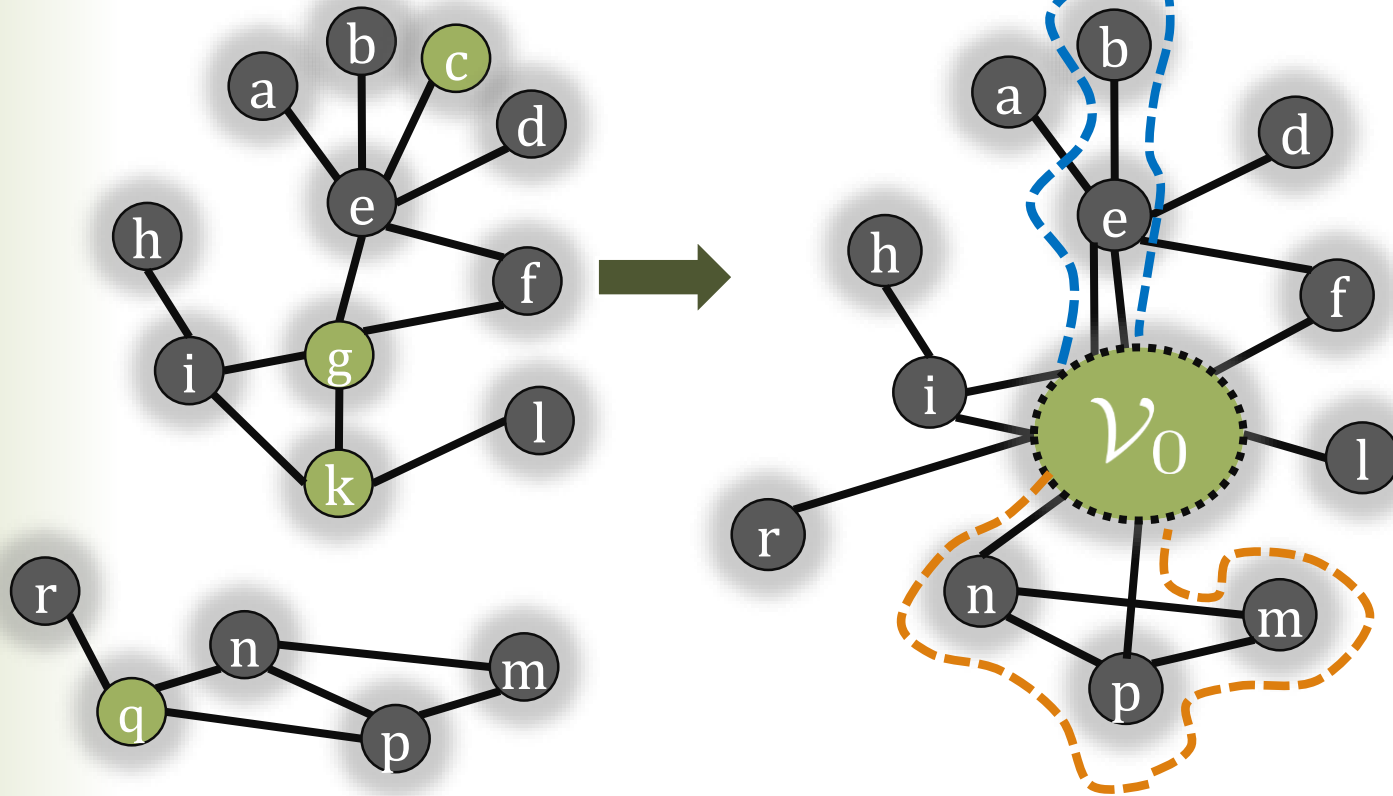


Properties of tours:

Sample
 $z \sim \text{Uniform}(\mathcal{V}_0)$

Idea of tours

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$



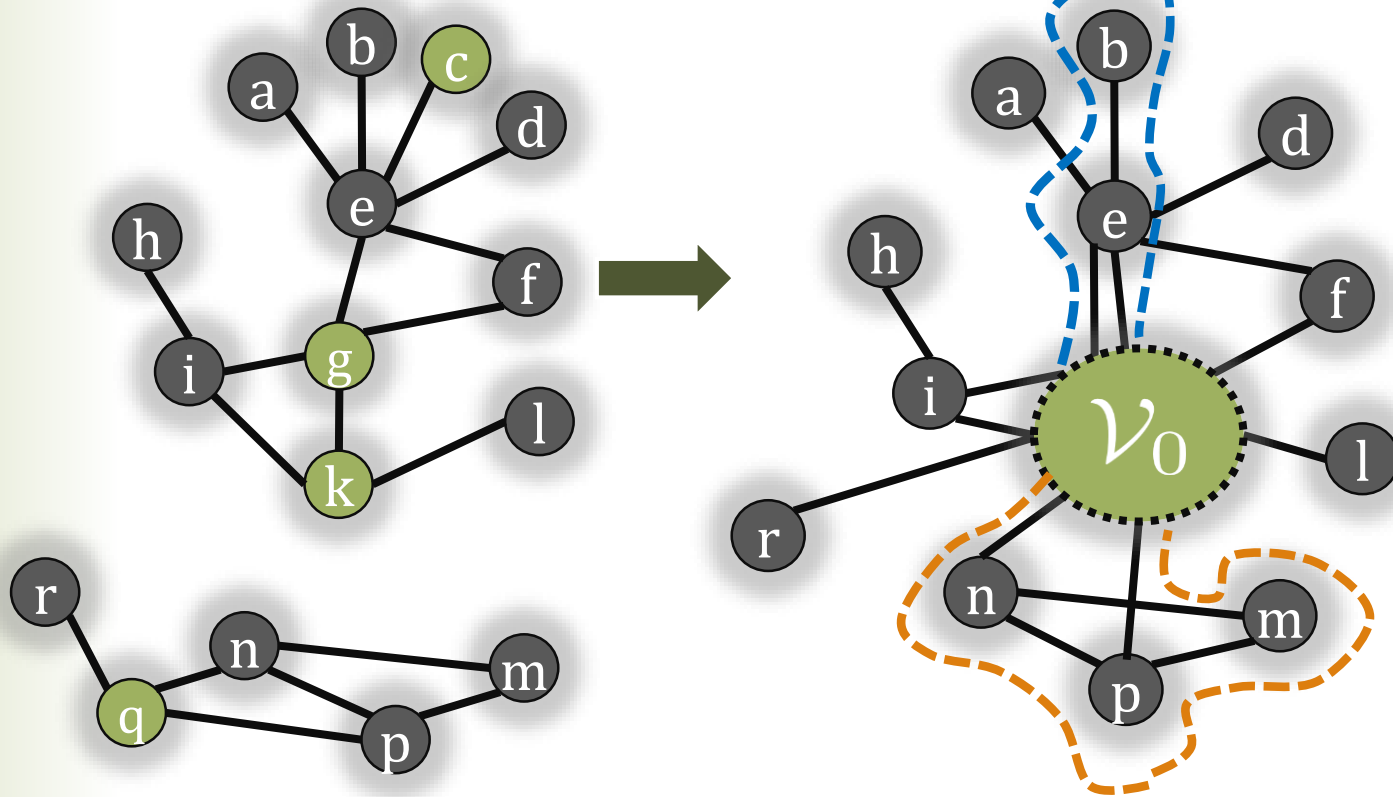
Properties of tours:

- Tours are independent

Sample
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Idea of tours

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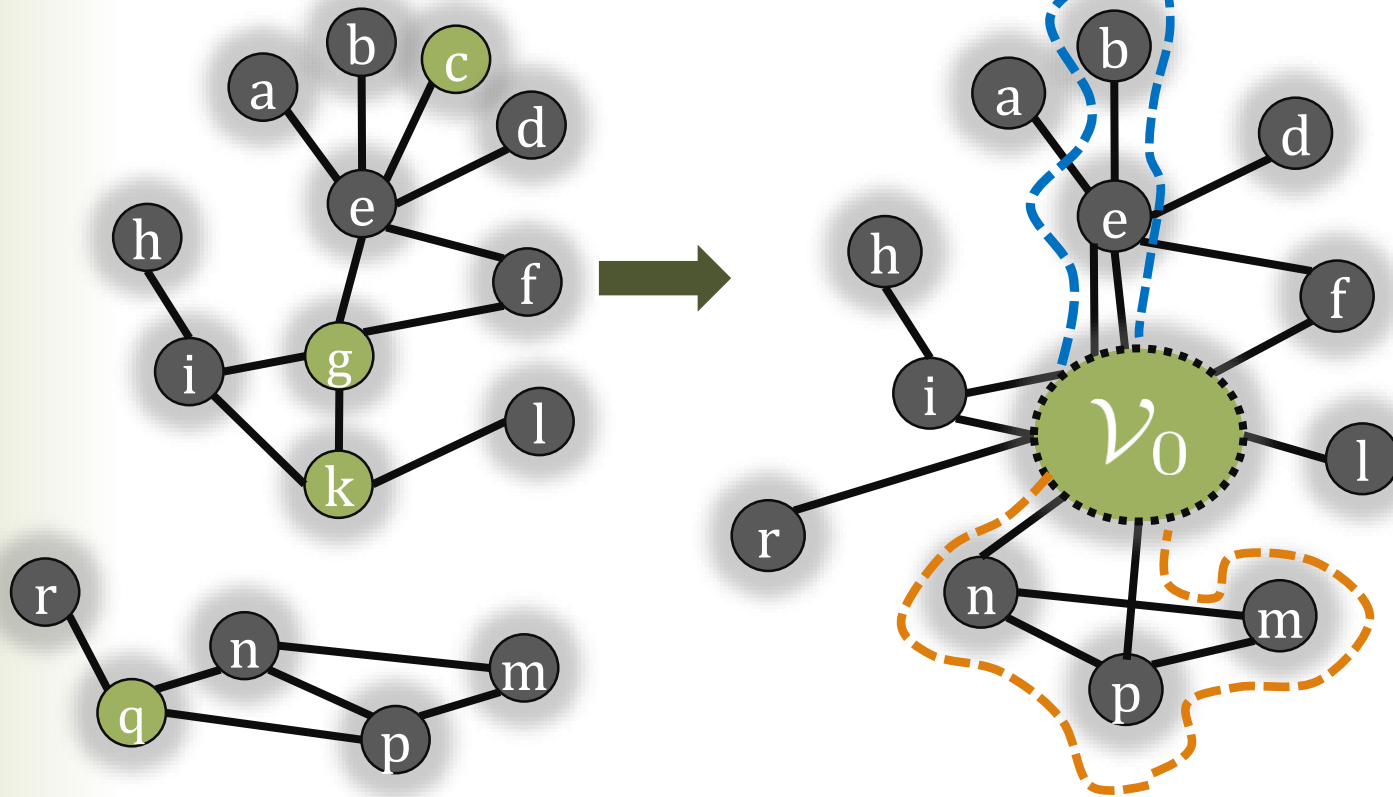
Properties of tours:

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- Fully distributed crawler

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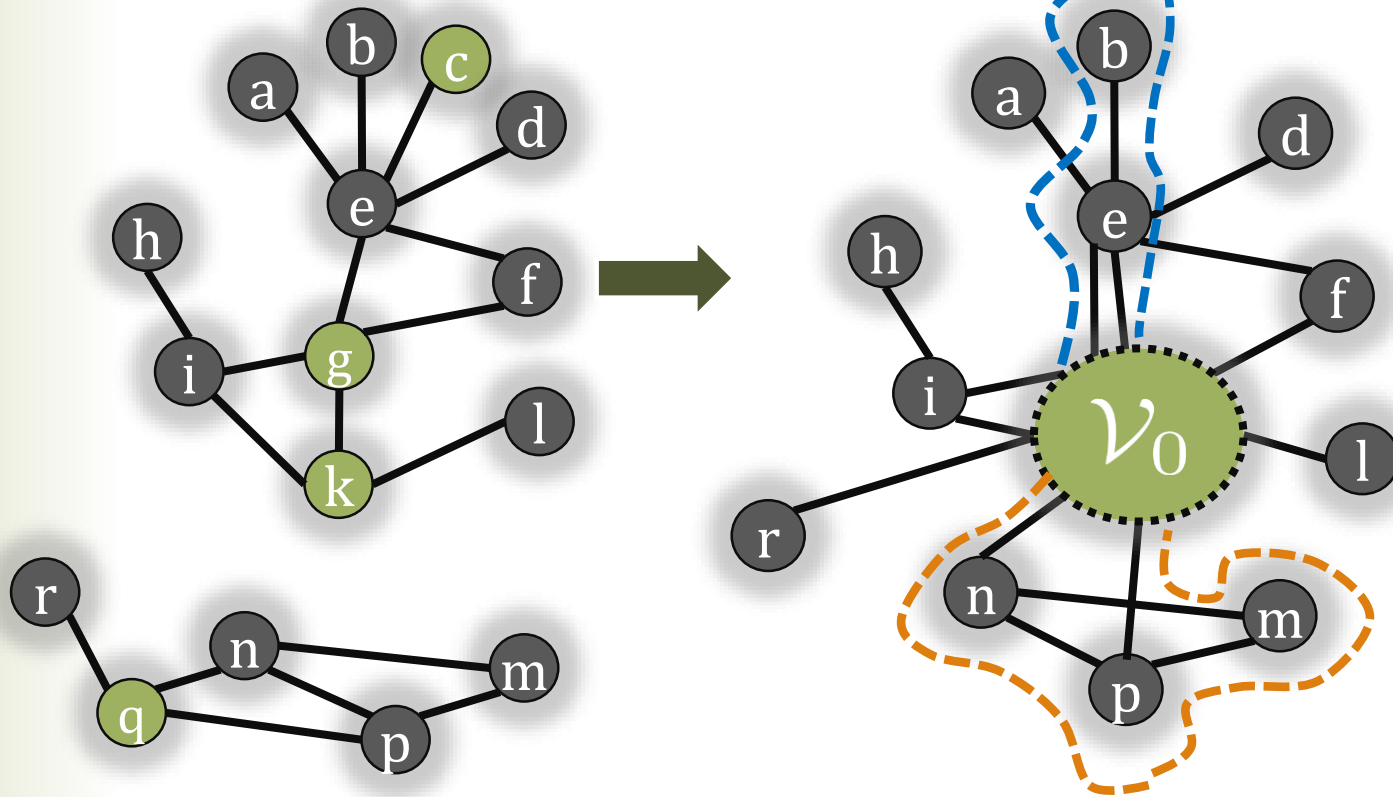
Properties of tours:

- Tours are independent
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Sample
 $z \sim \text{Uniform}(\mathcal{V}_0)$

Idea of tours

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$



Properties of tours:

- Tours are independent
- Fully distributed crawler implementation
- Larger super node size, shorter the tours

Sample
 $z \sim \text{Uniform}(\mathcal{V}_0)$

Reinforcement Learning technique (contd.)

Stochastic Approximation Algorithm

Reinforcement Learning technique (contd.)

For each node i in \mathcal{V}_0  Seed set

Stochastic Approximation
Algorithm

Reinforcement Learning technique (contd.)

Stochastic Approximation Algorithm

For each node i in \mathcal{V}_0 ← Seed set

Function sum
inside a tour

$$V_{n+1}(i) = V_n(i) + a(n)\mathbb{I}\{z = i\} \left[\left(\sum_{m=1}^{\xi(n)} f(X_m^n) \right) - \frac{\xi(n)}{|\mathcal{V}_0|} \sum_{j \in \mathcal{V}_0} V_n(j) + V_n(X_{\xi(n)}^n) - V_n(i) \right]$$

↑
Cost function

Reinforcement Learning technique (contd.)

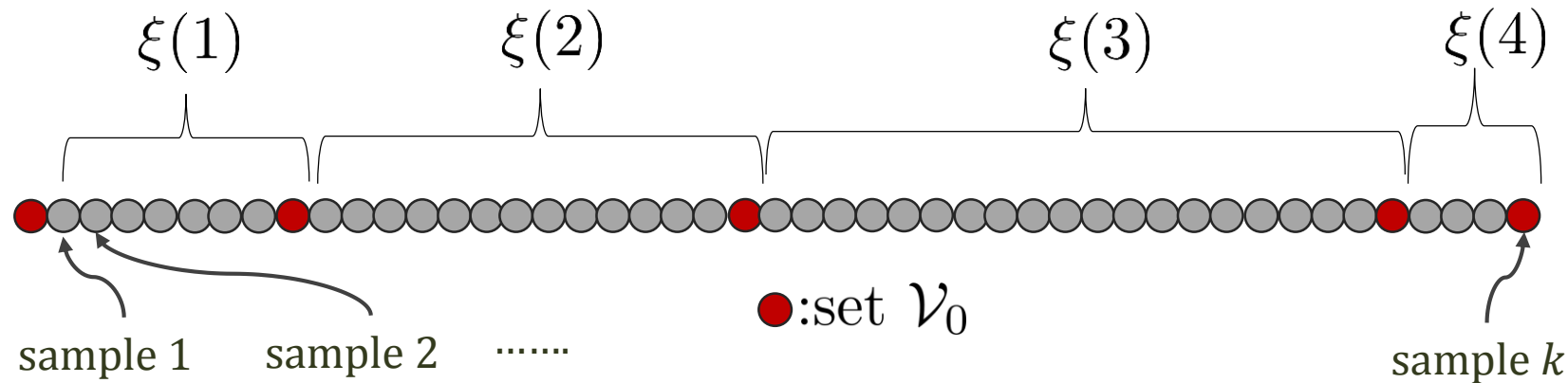
Stochastic Approximation Algorithm

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Function sum
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Cost function



Reinforcement Learning technique (contd.)

Stochastic Approximation Algorithm

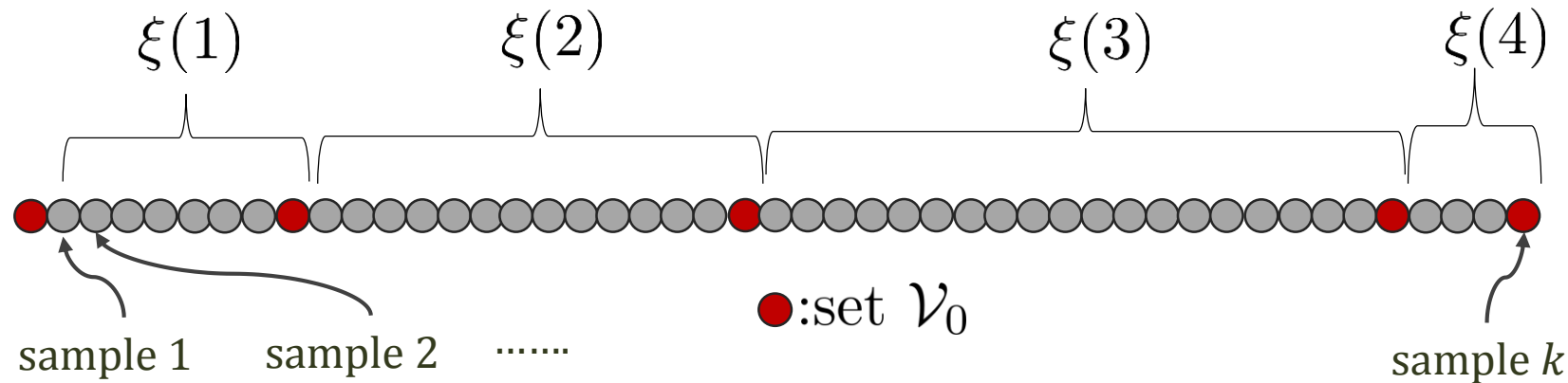
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↑
Cost function

$a(n) > 0$ are stepsizes satisfying $\sum_n a(n) = \infty$, $\sum_n a(n)^2 < \infty$.



Reinforcement Learning technique (contd.)

Stochastic Approximation Algorithm

For each node i in \mathcal{V}_0 ← Seed set

Function sum
inside a tour

$$V_{n+1}(i) = V_n(i) + a(n)\mathbb{I}\{z = i\} \left[\overbrace{\left(\sum_{m=1}^{\xi(n)} f(X_m^n) \right)}^{\text{Function sum inside a tour}} - \frac{\xi(n)}{|\mathcal{V}_0|} \sum_{j \in \mathcal{V}_0} V_n(j) + V_n(X_{\xi(n)}^n) - V_n(i) \right]$$

↑
Cost function

$a(n) > 0$ are stepsizes satisfying $\sum_n a(n) = \infty$, $\sum_n a(n)^2 < \infty$.

$$\frac{1}{|\mathcal{V}_0|} \sum_{j \in \mathcal{V}_0} V_n(j) \rightarrow \sum_{u \in \mathcal{V}} \pi_u f(u)$$

Which Random Walk method to select ?

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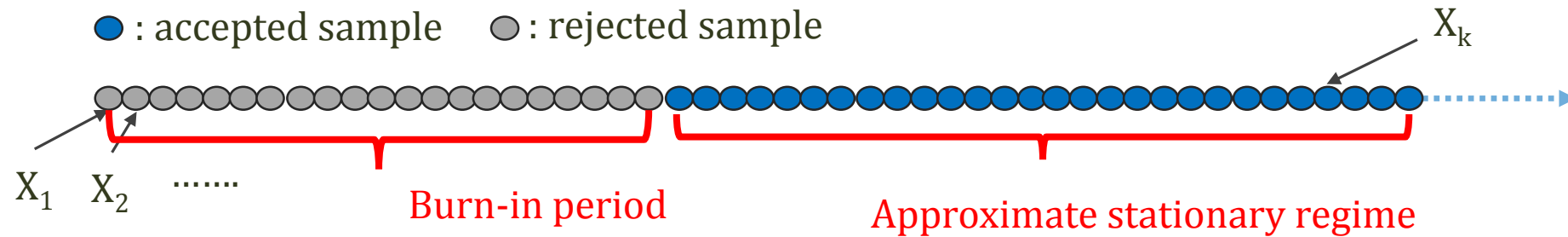
- Mixing time

Not a good criterion here due to burn-in period.

Which Random Walk method to select ?

- Mixing time

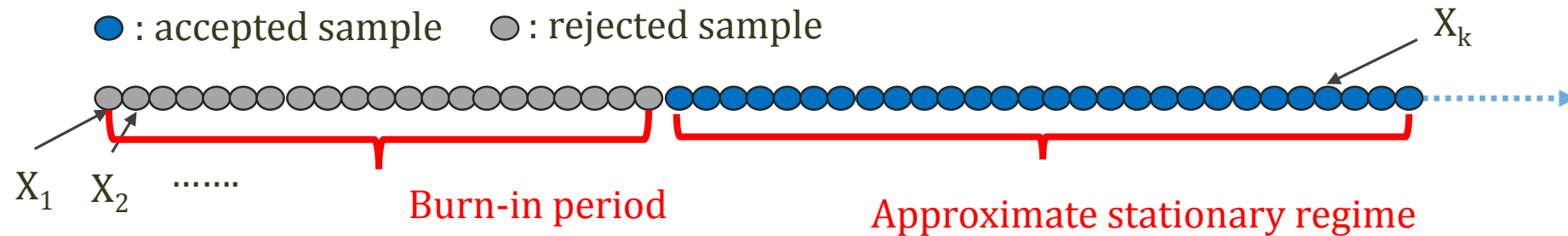
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Which Random Walk method to select ?

- Mixing time

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Reinforcement Learning technique does not require burn-in period

Which Random Walk method to select ?

- Mixing time

Not a good criterion here due to burn-in period.

- Efficiency of the estimator:

How many samples are needed to achieve certain accuracy

Asymptotic Variance

Asymptotic Variance

Asymptotic variance of the estimator

$$\sigma^2 \triangleq \lim_{n \rightarrow \infty} n \operatorname{Var} (\mu^{(n)}(\mathcal{G}))$$

Asymptotic Variance

Asymptotic variance of the estimator

$$\sigma^2 \triangleq \lim_{n \rightarrow \infty} n \operatorname{Var} (\mu^{(n)}(\mathcal{G}))$$

Also from Central Limit Theorem equivalent

$$\sqrt{n} \left(\hat{\mu}^{(n)}(\mathcal{G}) - \mu(\mathcal{G}) \right) \xrightarrow{\mathcal{D}} \mathcal{N}(0, \sigma^2)$$

Asymptotic Variance (contd.)

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- For Metropolis-Hastings Sampling,

$$\sqrt{n} \left(\hat{\mu}_{\text{MH}}^{(n)}(\mathcal{G}) - \mu(\mathcal{G}) \right) \xrightarrow{\mathcal{D}} \mathcal{N}(0, \sigma_{\text{MH}}^2)$$

$$\text{where } \sigma_{\text{MH}}^2 = \frac{2}{n} \mathbf{f}^T \mathbf{Z} \mathbf{f} - \frac{1}{n} \mathbf{f}^T \mathbf{f} - \left(\frac{1}{n} \mathbf{f}^T \mathbf{1} \right)^2$$

Fundamental matrix of Markov chain

Asymptotic Variance (contd.)

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$$\sqrt{n} \left(\hat{\mu}_{\text{MH}}^{(n)}(\mathcal{G}) - \mu(\mathcal{G}) \right) \xrightarrow{\mathcal{D}} \mathcal{N}(0, \sigma_{\text{MH}}^2)$$

$$\text{where } \sigma_{\text{MH}}^2 = \frac{2}{n} \mathbf{f}^T \mathbf{Z} \mathbf{f} - \frac{1}{n} \mathbf{f}^T \mathbf{f} - \left(\frac{1}{n} \mathbf{f}^T \mathbf{1} \right)^2$$

Fundamental matrix of Markov chain

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$$\sqrt{n} (\hat{\mu}_{\text{RDS}}^{(n)}(\mathcal{G}) - \mu(\mathcal{G})) \xrightarrow{\mathcal{D}} \mathcal{N}(0, \sigma_{\text{RDS}}^2) \quad , \quad \sigma_{\text{RDS}}^2 = \text{function}(\text{deg}, \mathbf{Z}, \mathbf{f})$$

Asymptotic Variance (contd.)

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- For Reinforcement Learning based sampling,

$$\mathbb{E} \left[|\hat{\mu}_{\text{RL}}^{(n)}(\mathcal{G}) - \mu(\mathcal{G})|^2 \right] = \mathcal{O} \left(\frac{1}{n} \right)$$

Numerical Studies

Normalized Root Mean Square Error (NRMSE) vs Budget B

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Budget B: number of allowed samples

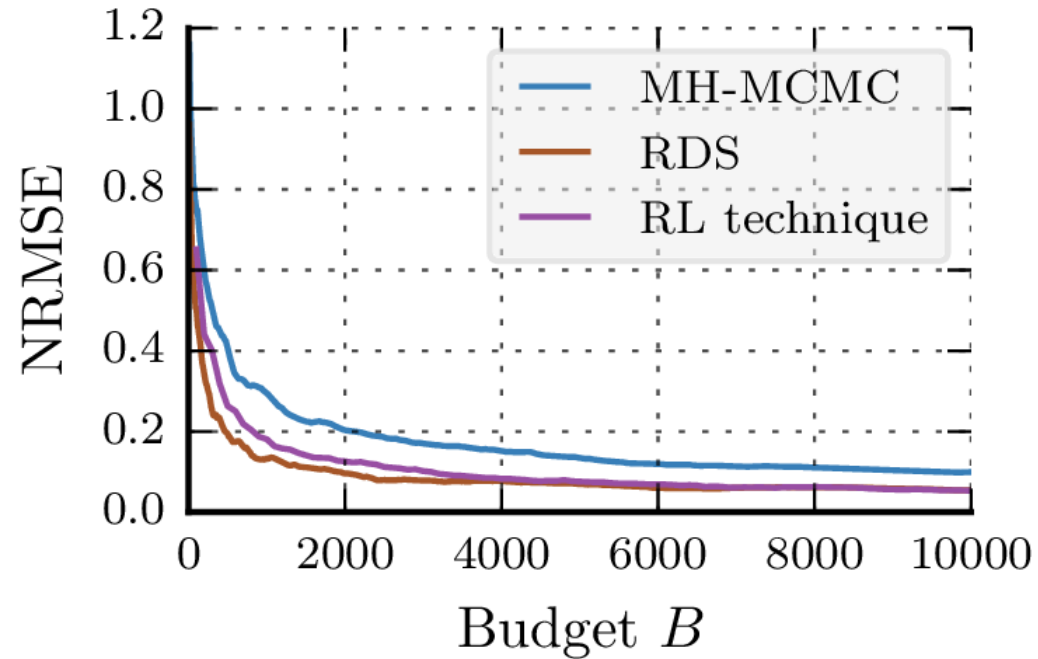
Les Misérables network

Les Misérables network

Number of nodes: 77, number of edges: 254.

Les Misérables network

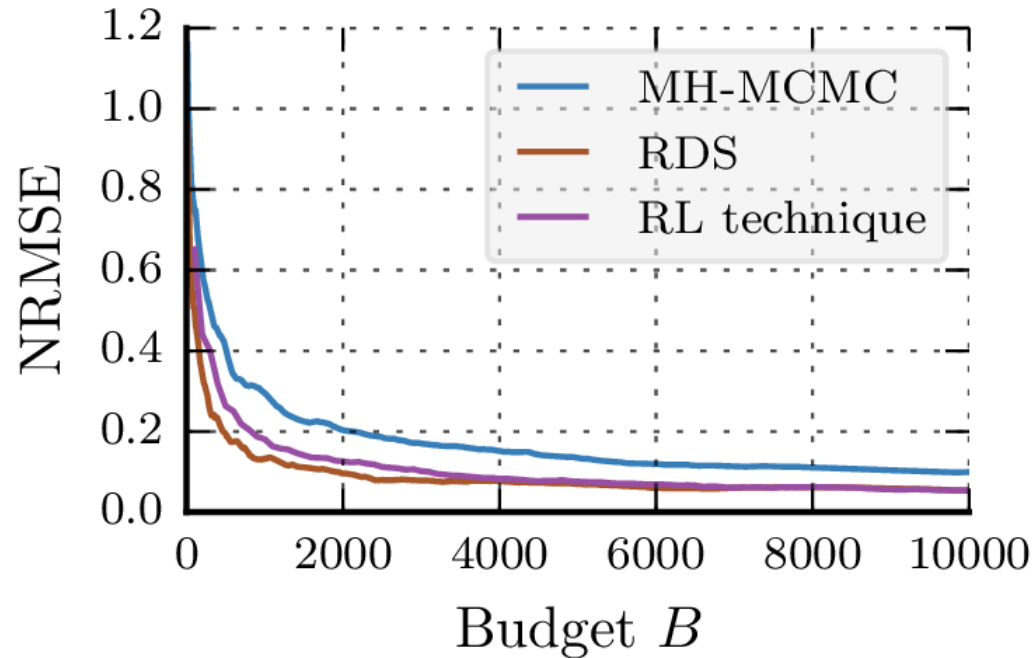
Number of nodes: 77, number of edges: 254.



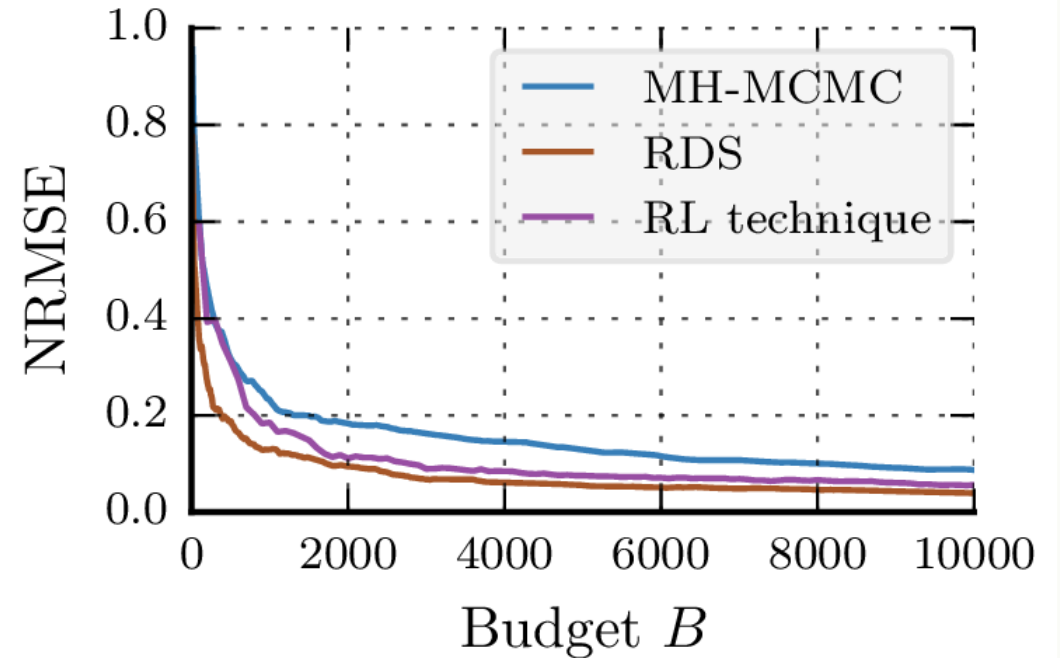
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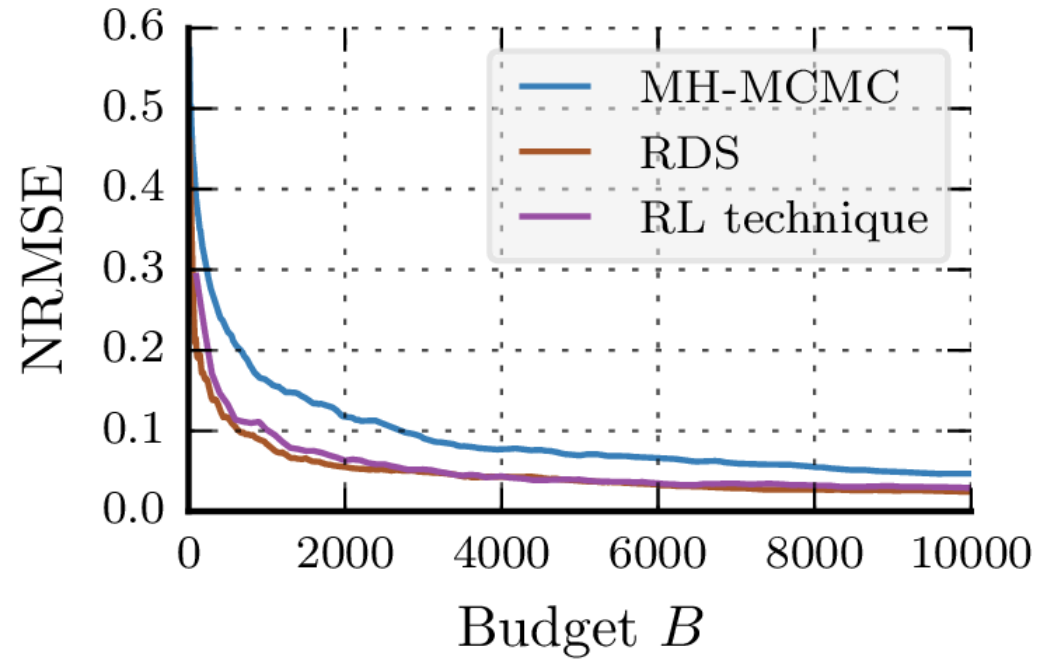
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$$\mu(\mathcal{G}) = \frac{1}{|\mathcal{V}|} \sum_{u \in \mathcal{V}} \mathbb{I}\{\deg(u) < 4\}$$

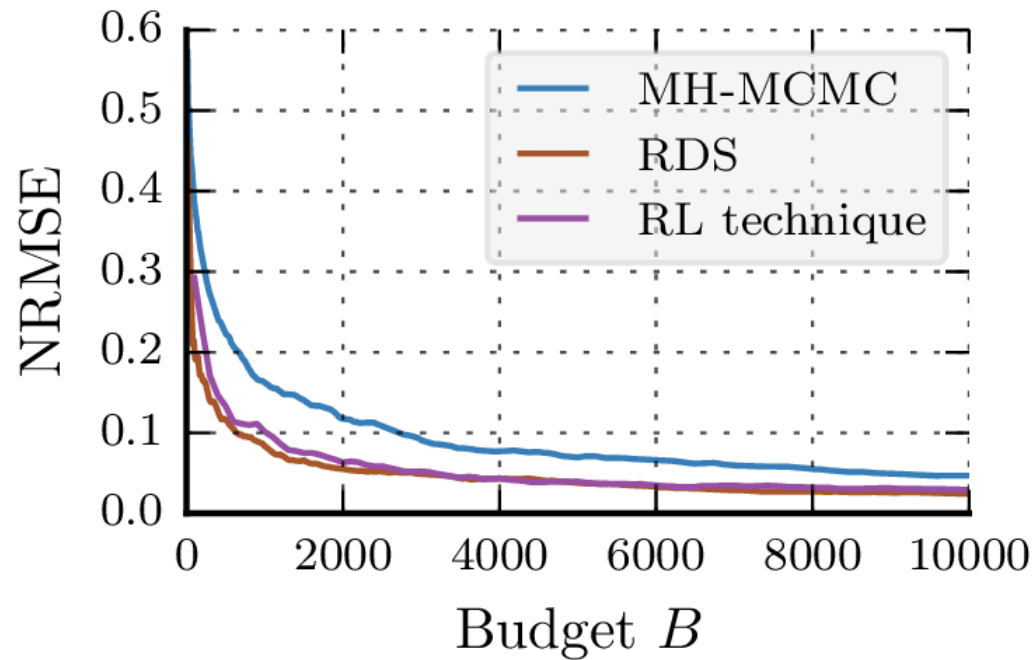
Les Misérables network contd.

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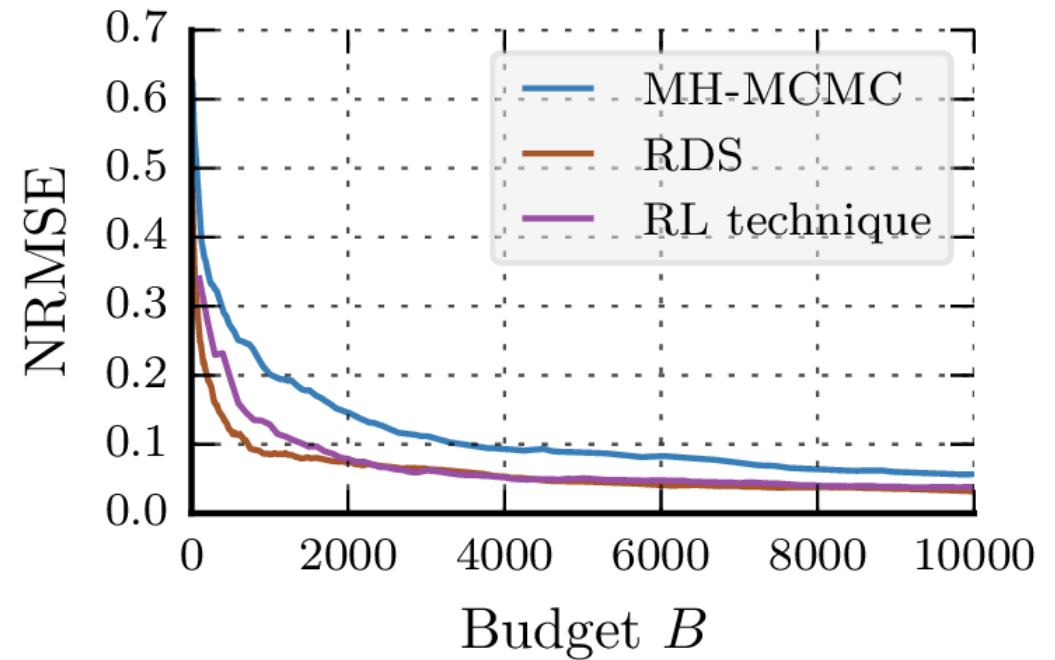


$\mu(\mathcal{G}) = \text{Average degree}$

Les Misérables network contd.



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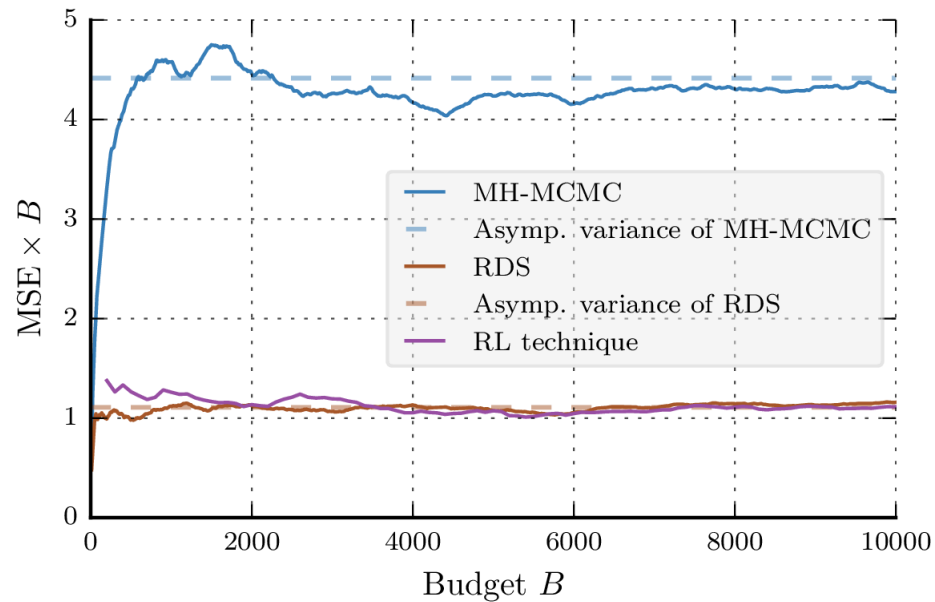
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Les Misérables network contd.

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Study of asymptotic variance

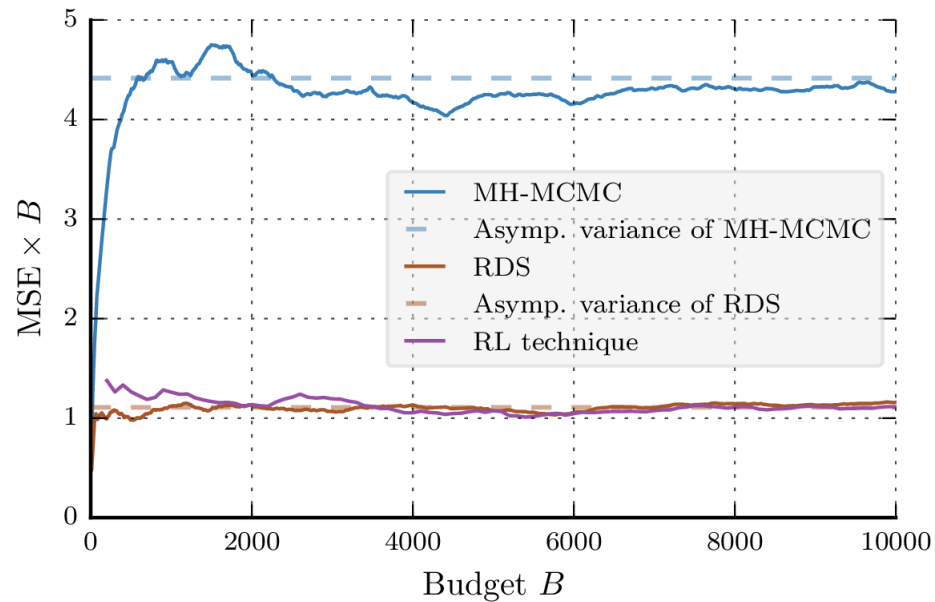
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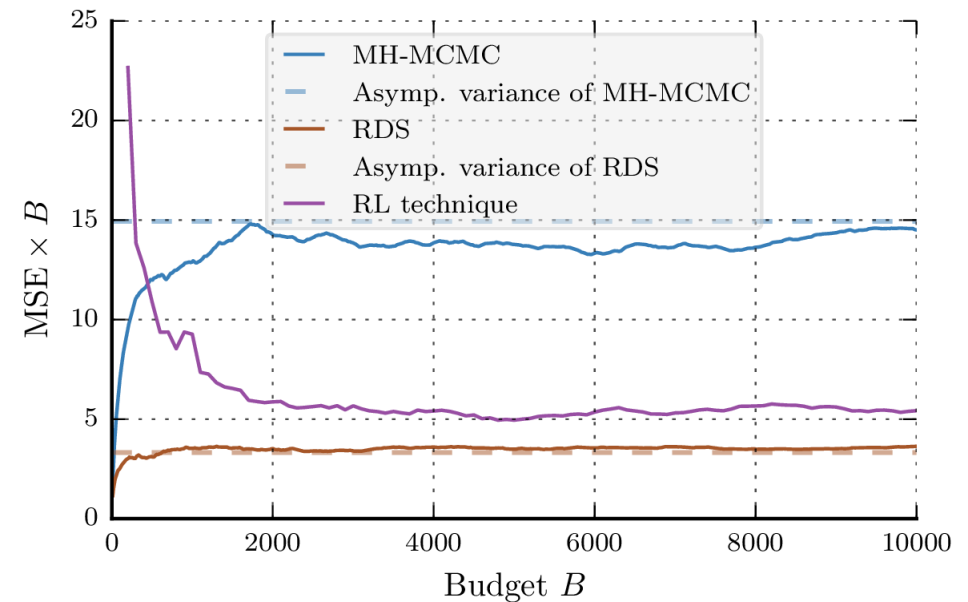
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Les Misérables network contd.

Study of asymptotic variance



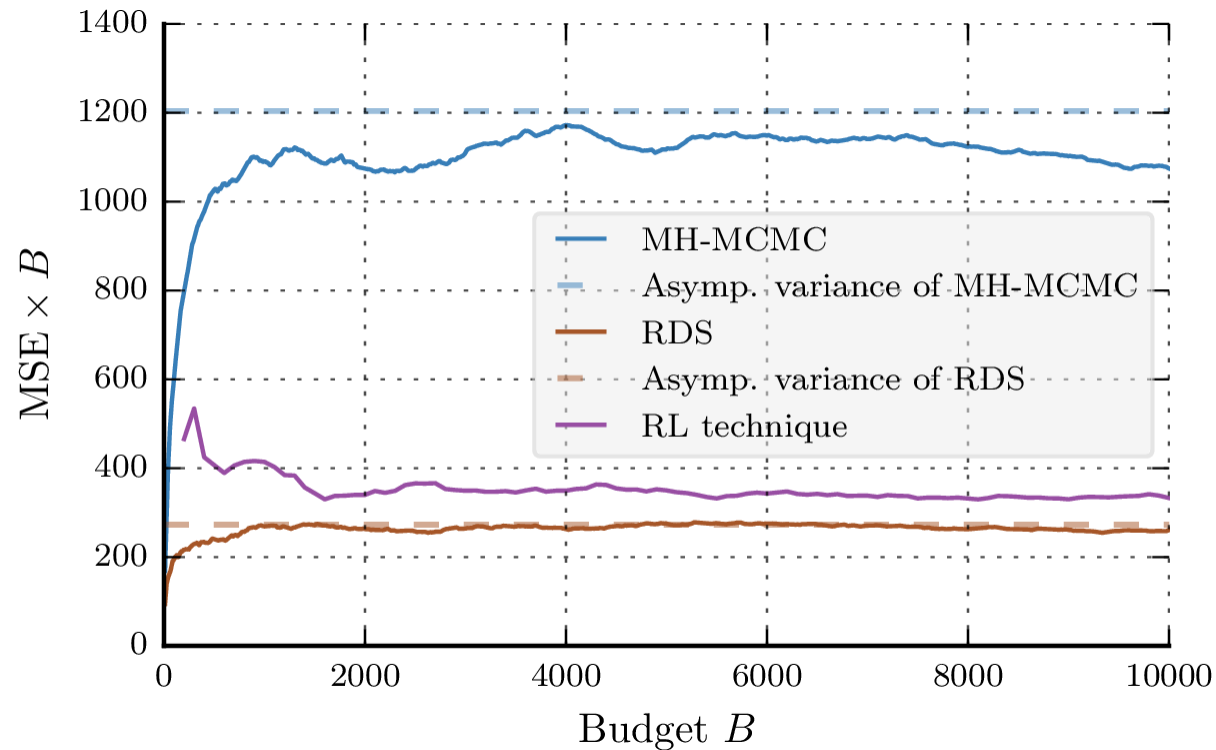
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Les Misérables network contd.

Study of asymptotic variance



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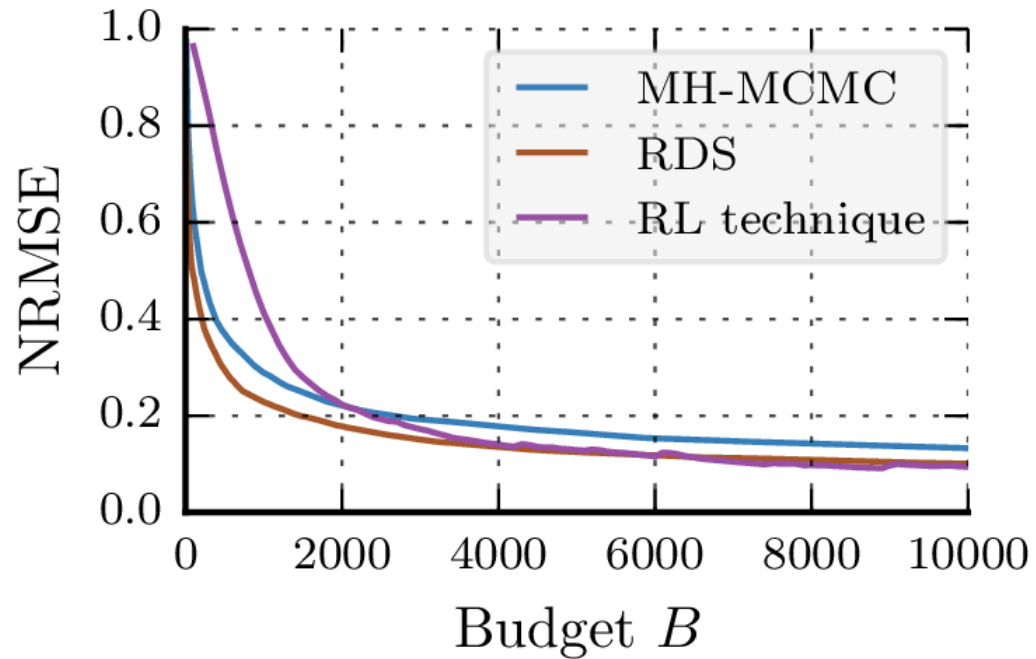
Friendster network

Friendster network

Number of nodes $\sim 65K$ number of edges $\sim 1.25M$

Friendster network

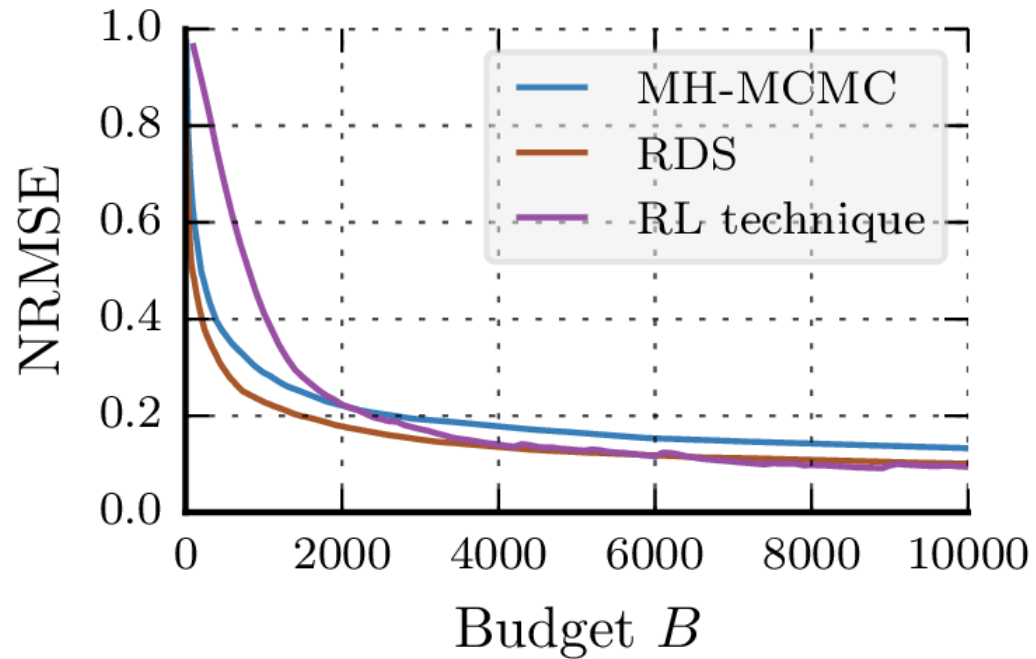
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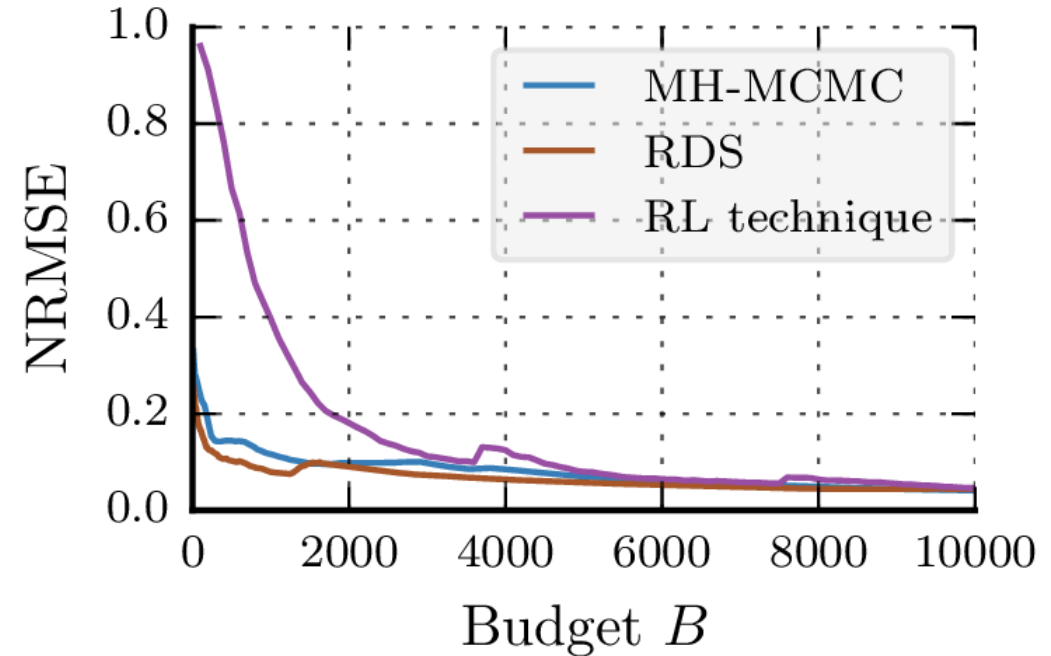
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Friendster network

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$$\mu(\mathcal{G}) = \frac{1}{|\mathcal{V}|} \sum_{u \in \mathcal{V}} \mathbb{I}\{\deg(u) > 50\}$$



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Friendster network contd.

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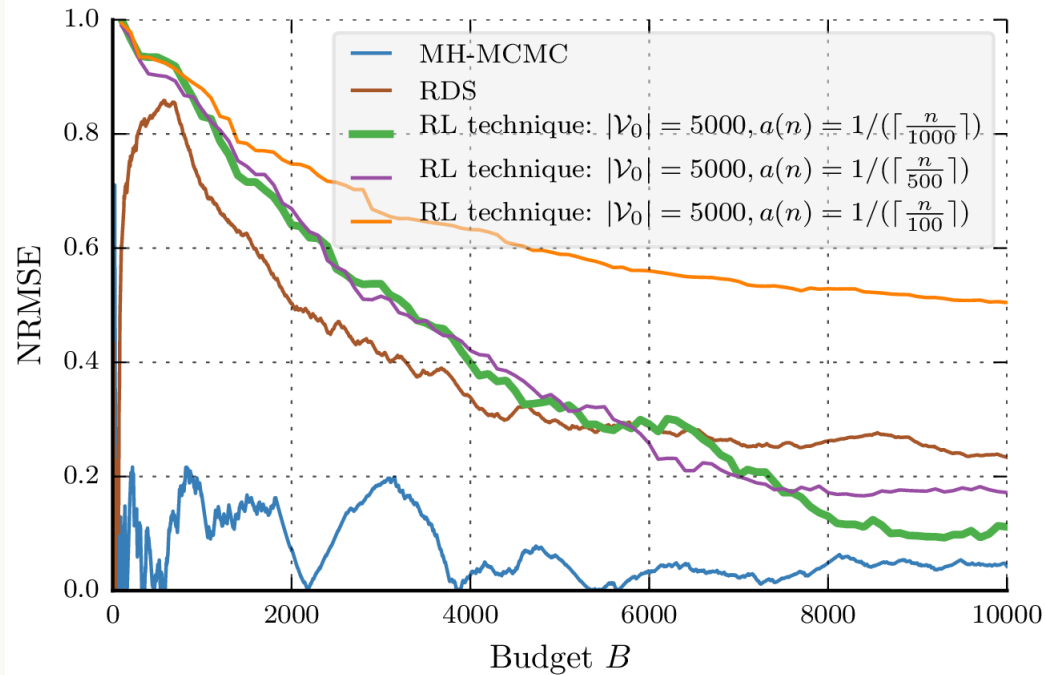
Stability of sample paths:

Friendster network contd.

Stability of sample paths: **single path example**

Friendster network contd.

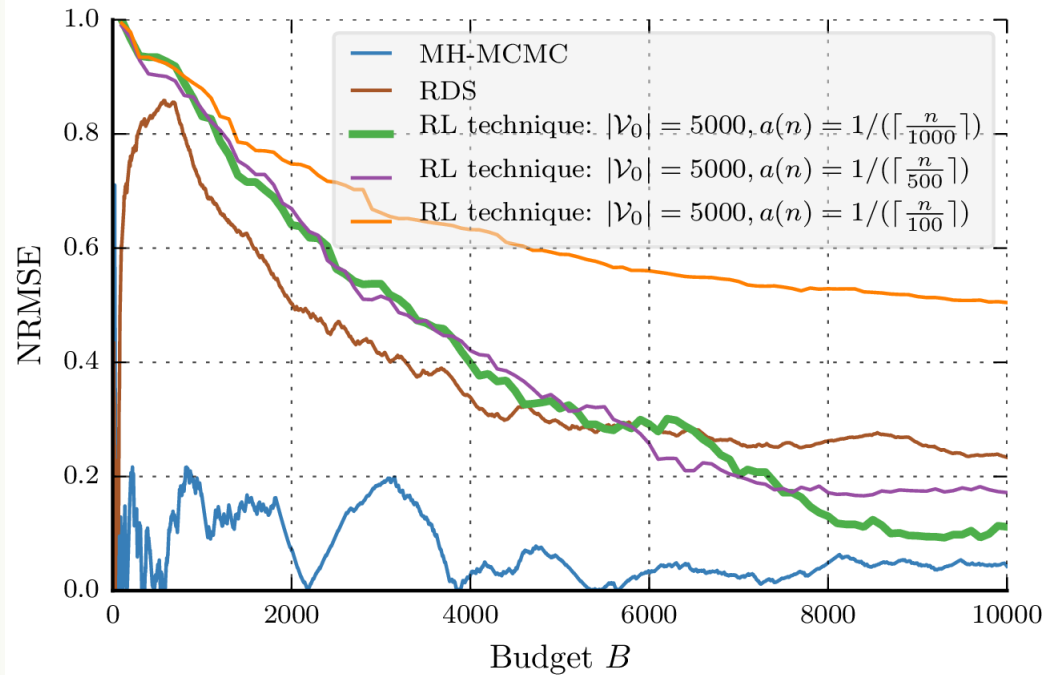
Stability of sample paths: **single path example**



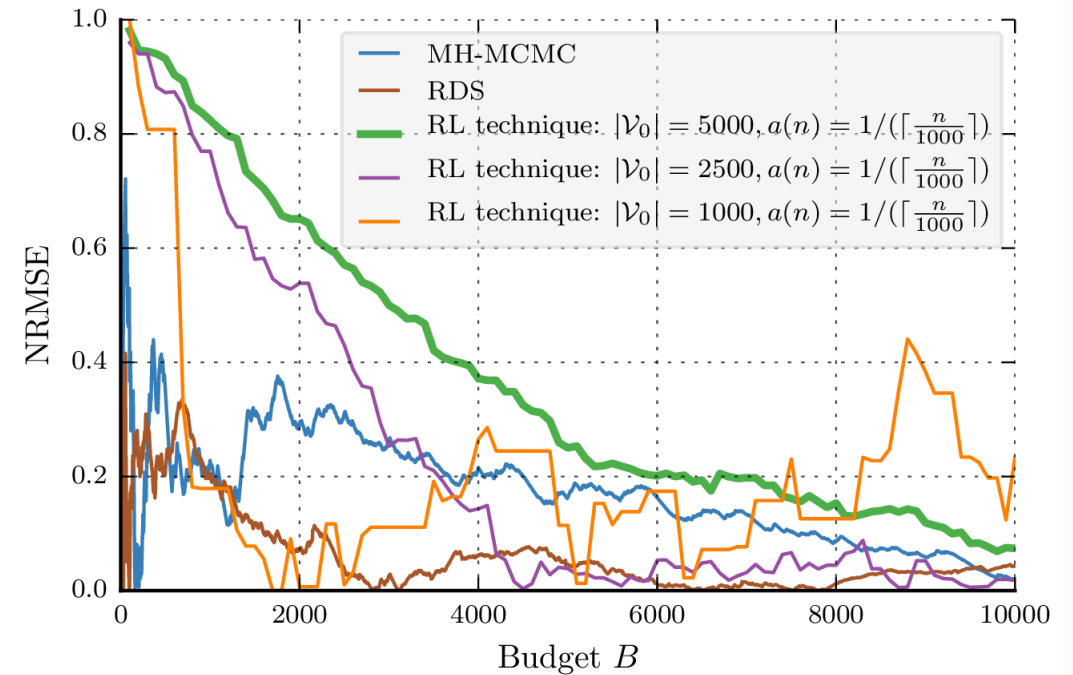
Varying super-node size

Friendster network contd.

Stability of sample paths: **single path example**



Varying super-node size



Varying step size

Conclusions

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- RDS works better. RL technique comparable, yet more stable and no burn-in !

Thank you!
<http://bit.do/Jithin>