# 01204211 Discrete Mathematics Lecture 9b: Affine Spaces

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## Review: Linear combinations

#### Definition

For any scalars

$$\alpha_1, \alpha_2, \ldots, \alpha_m$$

and vectors

$$\boldsymbol{u}_1, \boldsymbol{u}_2, \ldots, \boldsymbol{u}_m,$$

we say that

$$\alpha_1 \boldsymbol{u}_1 + \alpha_2 \boldsymbol{u}_2 + \cdots + \alpha_m \boldsymbol{u}_m$$

is a linear combination of  $u_1, \ldots, u_m$ .

# Review: Span

#### Definition

A set of all linear combination of vectors  $u_1, u_2, \dots, u_m$  is called the **span** of that set of vectors.

It is denoted by  $\mathrm{Span}\{\boldsymbol{u}_1,\boldsymbol{u}_2,\ldots,\boldsymbol{u}_m\}.$ 

# Review: Vector spaces

#### Definition

A set  $\mathcal V$  of vectors over  $\mathbb F$  is a **vector space** iff

- ightharpoonup (V1)  $\mathbf{0} \in \mathcal{V}$ ,
- ightharpoonup (V2) for any  $u\in\mathcal{V}$ ,

$$\alpha \cdot \boldsymbol{u} \in \mathcal{V}$$

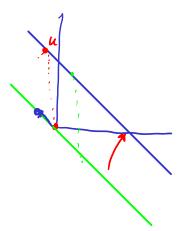
for any  $\alpha \in \mathbb{F}$ , and

ightharpoonup (V3) for any  $oldsymbol{u},oldsymbol{v}\in\mathcal{V}$ ,

$$u + v \in \mathcal{V}$$
.

#### Examples of vector spaces:

- A span of vectors is a vector space.
- A solution set to homogeneous linear equations is a vector space.



If we have a line or a plane passing through a vector a, but not through the origin, how can we represent it?

► Translate the object so that it passes through the origin.

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- ightharpoonup We obtain a vector space  $\mathcal V$ .

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- We get the set

$$A = a + u : u \in V$$

If we have a line or a plane passing through a vector  $\boldsymbol{a}$ , but not through the origin, how can we represent it?

- Translate the object so that it passes through the origin.
- ightharpoonup We obtain a vector space  $\mathcal{V}$ .
- ightharpoonup Then we translate it back so that it passes through a.
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$$\mathcal{A} = \{ \boldsymbol{a} + \boldsymbol{u} : \boldsymbol{u} \in \mathcal{V} \}$$

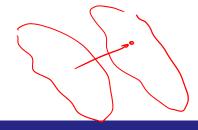
▶ Question: Is A a vector space?

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- ► Question: Is A a vector space?
- ightharpoonup We also write it as a + V.

# Affine spaces



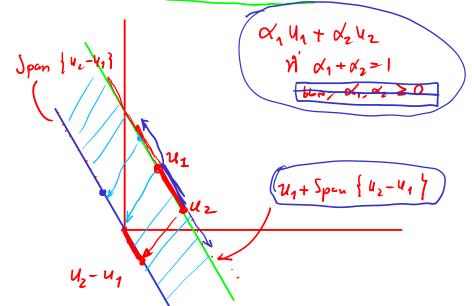
## Definition

If a is a vector and  $\mathcal V$  is a vector space, then

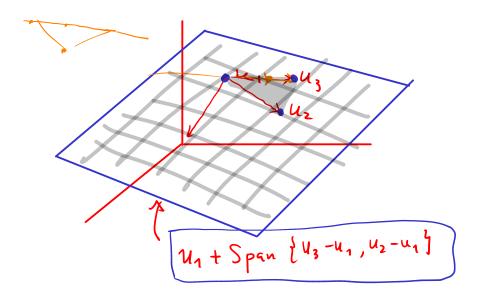
$$a + V$$

is an affine space.

# An affine space and convex combination: 2 dimensions



# An affine space and convex combination: 3 dimensions



### Affine combination

#### Definition

For any scalars  $\alpha_1, \alpha_2, \ldots, \alpha_m$  such that

$$\alpha_1 + \alpha_2 + \ldots + \alpha_m = 1$$

and vectors  $oldsymbol{u}_1, oldsymbol{u}_2, \dots, oldsymbol{u}_m$ , we say that a linear combination

$$\alpha_1 \boldsymbol{u}_1 + \alpha_2 \boldsymbol{u}_2 + \dots + \alpha_m \boldsymbol{u}_m$$

is an **affine combination** of  $u_1, \ldots, u_m$ .

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### **Definition**

The set of all affine combinations of vectors  $u_1, u_2, \ldots, u_m$  is called the affine hull of  $u_1, u_2, \ldots, u_m$ .



## Convex combination: review



#### Definition

For any scalars  $\alpha_1, \alpha_2, \dots, \alpha_m \geq 0$  such that

$$\alpha_1 + \alpha_2 + \ldots + \alpha_m = 1$$

and vectors  $oldsymbol{u}_1, oldsymbol{u}_2, \dots, oldsymbol{u}_m$ , we say that a linear combination

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is a **convex combination** of  $u_1, \ldots, u_m$ .

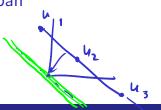
#### Definition

The set of all convex combinations of vectors  $u_1, u_2, \dots, u_m$  is called the **convex hull** of  $u_1, u_2, \dots, u_m$ .



# Writing an affine space using a span

Writing an affine space using a span



# An affine space

An affine space passing through  $oldsymbol{u}_1, oldsymbol{u}_2, \dots, oldsymbol{u}_n$  is

$$(u_1)$$
+ Span  $\{u_2 - u_1, u_3 - u_1, \dots, u_n - u_1\}.$ 

$$= \begin{bmatrix} 1 - \alpha_2 - \alpha_3 + \dots - \alpha_n \end{bmatrix} u_1 + \alpha_2 u_2 + \alpha_3 u_3 + \dots + \alpha_n u_n$$

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Non-homogeneous linear system  $\chi = [x_1, x_2, y_3, \dots, x_n]$ 

Two linear systems:

What can you say about the solution sets of these two related linear systems?

$$Q_{11} \times_{1} + Q_{12} \times + - \cdots + Q_{1n} \times_{n} = b_{1}$$
  
 $Q_{11} \times_{1} + Q_{12} \cdot \times_{2} + \cdots + Q_{1n} \cdot \times_{n} = b_{1}$   
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Non-homogeneous linear system

geneous linear system

$$u_1 \otimes u_2 = b_1 \otimes b_1 \otimes b_2 \otimes b_2 \otimes b_1 \otimes b_2 \otimes$$

Two linear systems:

$$\mathbf{a_1} \cdot \mathbf{x} = b_1$$
  $\mathbf{a_1} \cdot \mathbf{x} = 0$   
 $\mathbf{a_2} \cdot \mathbf{x} = b_2$   $\mathbf{a_2} \cdot \mathbf{x} = 0$   
 $\vdots$   $\vdots$   $\vdots$   $\vdots$   $\mathbf{a_m} \cdot \mathbf{x} = b_m$   $\mathbf{a_m} \cdot \mathbf{x} = 0$ 

What can you say about the solution sets of these two related linear systems?

**0** is always a solution to the linear system on the right.

Note: A linear equation whose right-hand-side is zero is called a homogeneous linear equation. A system of linear homogeneous equations is called a **homogeneous linear system**.

# Solutions of the two systems

Recall that if  $\underline{u}_1$  and  $\underline{u}_2$  are both solutions to the non-homogeneous linear system, we have that for any i

$$a_i u_1 - a_i u_2 = b_i - b_i \neq 0 \neq \underline{a_i(u_1 - u_2)}.$$

# Solutions of the two systems

Recall that if  ${m u}_1$  and  ${m u}_2$  are both solutions to the non-homogeneous linear system, we have that for any i

$$a_i u_1 - a_i u_2 = b_i - b_i = 0 = a_i (u_1 - u_2).$$

This implies that  $\underline{u_1-u_2}$  is a solution to the homogeneous linear system.

Suppose that  ${\mathcal W}$  is the set of all solution to the non-homogeneous linear system, i.e.,

$$\mathcal{W} \neq \{ \boldsymbol{x} : \boldsymbol{a}_i \boldsymbol{x} = b_i, \text{ for } 1 \leq i \leq m \},$$

and let  $u \in \mathcal{W}$  be one of the solutions, we have that

$$\{\boldsymbol{v}-\boldsymbol{u}:\boldsymbol{v}\in\mathcal{W}\}$$

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is a vector space, because 
$$\{\pmb{v}-\pmb{u}:\pmb{v}\in\mathcal{W}\}=\{\pmb{x}:\underline{\pmb{a}_i\pmb{x}}=0, \text{ for } 1\leq i\leq m\}$$

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$$\{\boldsymbol{v} - \boldsymbol{u} : \boldsymbol{v} \in \mathcal{W}\} = \{\boldsymbol{x} : \boldsymbol{a}_i \boldsymbol{x} = 0, \text{ for } 1 \leq i \leq m\}$$

In other words,

$$\mathcal{W} = \mathbf{u} + \{\mathbf{v} - \mathbf{u} : \mathbf{v} \in \mathcal{W}\}$$

$$= \mathbf{u} + \{\mathbf{x} : \mathbf{a}_i \mathbf{x} = 0, \text{ for } 1 \le i \le m\},$$

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and let  $u \in \mathcal{W}$  be one of the solutions, we have that

$$\{v - u : v \in \mathcal{W}\}$$

is a vector space, because

$$\{v - u : v \in W\} = \{x : a_i x = 0, \text{ for } 1 \le i \le m\}$$

In other words,

$$\mathcal{W} = \mathbf{u} + \{\mathbf{v} - \mathbf{u} : \mathbf{v} \in \mathcal{W}\}$$
  
=  $\mathbf{u} + \{\mathbf{x} : \mathbf{a}_i \mathbf{x} = 0, \text{ for } 1 \le i \le m\},$ 

i.e.,  ${\cal W}$  is an affine space.

# Solutions to a non-homogeneous linear system

#### Lemma 1

If the solution set of a linear system is not empty, it is an affine space.