# 01204211 Discrete Mathematics Lecture 10a: Nondeterministic automata<sup>1</sup>

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<sup>&</sup>lt;sup>1</sup>Based on lecture notes of *Models of Computation* course by Jeff Erickson.

### Review: DFA (Formal definitions)

A finite-state machine or a deterministic finite-state automaton (DFA) has five components:

- ightharpoonup the input alphabet  $\Sigma$ ,
- ightharpoonup a finite set of states Q,
- ightharpoonup a transition function  $\delta: Q \times \Sigma \longrightarrow Q$
- ightharpoonup a start state  $s \in Q$ , and
- ▶ a subset  $A \subseteq Q$  of accepting states.

#### Review: Acceptance

One step move: from state q with input symbol a, the machine changes its state to  $\delta(q,a).$ 

**Extension:** from state q with input string w, the machine changes its state to  $\delta^*(q,w)$  defined as

$$\delta^*(q,w) = \left\{ \begin{array}{ll} q & \text{if } w = \varepsilon, \\ \delta^*(\delta(q,a),x) & \text{if } w = ax. \end{array} \right.$$

The signature of  $\delta^*$  is  $Q \times \Sigma^* \longrightarrow Q$ .

#### accepting w

For a finite-state machine with starting state  $\boldsymbol{s}$  and accepting states A, it accepts string  $\boldsymbol{w}$  iff

$$\delta^*(s, w) \in A$$
.

### Language of a DFA

#### L(M)

For a DFA M, let L(M) be the set of all strings that M accepts. More formally, for  $M=(\Sigma,Q,\delta,s,A)$ ,

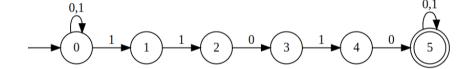
$$L(M) = \{ w \in \Sigma^* \mid \delta^*(s, w) \in A \}.$$

We refer to L(M) as the language of M.

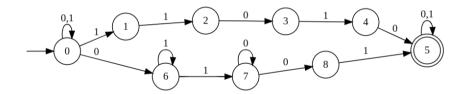
#### Acceptance

We also says M accepts L(M).

### New example 1



# New example 2





### More relaxed transitions

From state  $q \in Q$ , for input a, the machine can "possibly" change its state to many states.

New transition function  $\delta: Q \times \Sigma \longrightarrow 2^Q$ .

We refer to this new kind of automaton as a **nondeterministic finite-state automaton** or **NFA**.

### NFA (Formal definitions)

A nondeterministic finite-state automaton (NFA) has five components:

- $\blacktriangleright$  the input alphabet  $\Sigma$ ,
- ightharpoonup a finite set of states Q,
- ightharpoonup a transition function  $\delta: Q \times \Sigma \longrightarrow 2^Q$
- ightharpoonup a start state  $s \in Q$ , and
- ightharpoonup a subset  $A \subseteq Q$  of accepting states.

Remark:  $\delta$  can return the empty set  $\emptyset$ .

What else do we need to define to "properly" talk about NFAs?

#### **Transition**

One step move: from state q with input symbol a, the machine changes its state to one of  $\delta(q,a)$ .

Thus, instead of thinking of a machine that maintains **one** state, we can think of an NFA as a machine that maintains a **set** of states.

If the current set of states is  $C\subseteq Q$  and the input is  $a\in \Sigma$  what would the new set of states be?

**Extension:** from state q with input string w, the machine changes its set of states  $\delta^*(q,w)$  defined as

$$\delta^*(q,w) = \left\{ \begin{array}{ll} \{q\} & \text{if } w = \varepsilon, \\ \\ \bigcup_{r \in \delta(q,a)} \delta^*(r,x) & \text{if } w = ax. \end{array} \right.$$

The signature of  $\delta^*$  is  $Q \times \Sigma^* \longrightarrow 2^Q$ .

### Acceptance

#### accepting w

For a nondeterministic finite-state machine with starting state s and accepting states A, it accepts string w iff

$$\delta^*(s, w) \cap A \neq \emptyset.$$

### Interpretation

- Clairvoyance.
- Parallel threads.
- ► Proofs/oracles.

#### $\varepsilon$ -transition

An NFA accepts string  $\boldsymbol{w}$  iff there is a sequence of transitions

$$s \xrightarrow{a_1} q_1 \xrightarrow{a_2} q_2 \xrightarrow{a_3} q_3 \xrightarrow{a_4} \cdots \xrightarrow{a_{k-1}} q_{k-1} \xrightarrow{a_k} q_k$$

where  $q_k \in A$  and  $w = a_1 a_2 \cdots a_k$  where  $a_i \in \Sigma \cup \{\varepsilon\}$  for  $1 \le i \le k$ . The transition function also changes its domain to  $O \times (\Sigma \cup \{\varepsilon\})$ 

The transition function also changes its domain to  $Q \times (\Sigma \cup \{\varepsilon\})$ .



#### $\varepsilon$ -reach

The  $\varepsilon$ -reach of state  $q \in Q$  (denoted by  $\varepsilon$ -reach(q)) consists of all states r that satisfy one of the following conditions:

- ightharpoonup r = q, or
- $ightharpoonup r \in \delta(q', \varepsilon)$  for some state q' in the  $\varepsilon$ -reach of q.

### Extended transition function: $\delta^*$

We define  $\delta^*: Q \times \Sigma^* \longrightarrow 2^Q$  as follows:

$$\delta^*(q,w) = \left\{ \begin{array}{ll} \varepsilon\text{-reach}(p) & \text{if } w = \varepsilon \\ \displaystyle \bigcup_{r \in \varepsilon\text{-reach}(p)} \displaystyle \bigcup_{q \in \delta(r,q)} \delta^*(q,x) & \text{if } w = ax. \end{array} \right.$$

### Notation abuse

We sometimes also write, for subset  $S\subseteq Q$ ,

$$\delta(S,a) = \bigcup_{q \in S} \delta(q,a),$$

$$\delta^*(S, a) = \bigcup_{q \in S} \delta^*(q, a),$$

and

$$arepsilon$$
-reach $(S)=igcup arepsilon$ -reach $(q).$ 

### Extended transition function: $\delta^*$ (with shorter notation)

We define  $\delta^*: Q \times \Sigma^* \longrightarrow 2^Q$  as follows:

$$\delta^*(q,w) = \left\{ \begin{array}{ll} \varepsilon\text{-reach}(p) & \text{if } w = \varepsilon \\ \\ \delta^*(\delta(\varepsilon\text{-reach}(p),a),x) & \text{if } w = ax. \end{array} \right.$$

Removing  $\varepsilon$ -transitions: idea

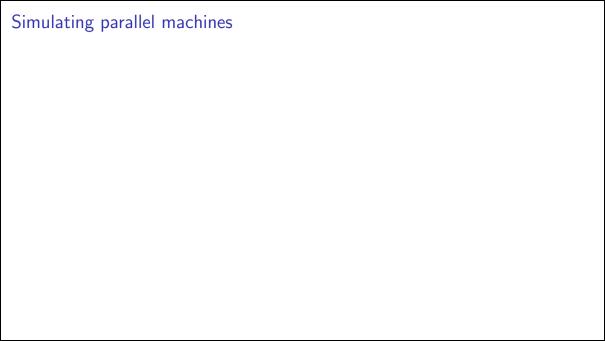
#### Lemma 1

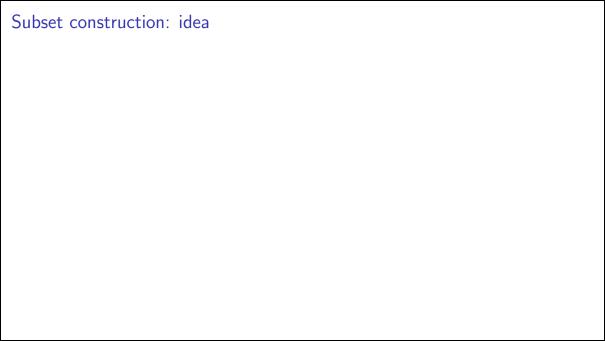
For any NFA  $M=(\Sigma,Q,\delta,s,A)$  with  $\varepsilon$ -transitions, there is an NFA  $M'=(\Sigma,Q',\delta',s',A')$  without  $\varepsilon$ -transitions such that L(M)=L(M').

#### Proof.

### Main question

- $\blacktriangleright$  We see that  $\varepsilon$ -transitions does not add any "power" to the machine.
- ▶ Does nondeterminism add any power to NFA (over typical DFA)?





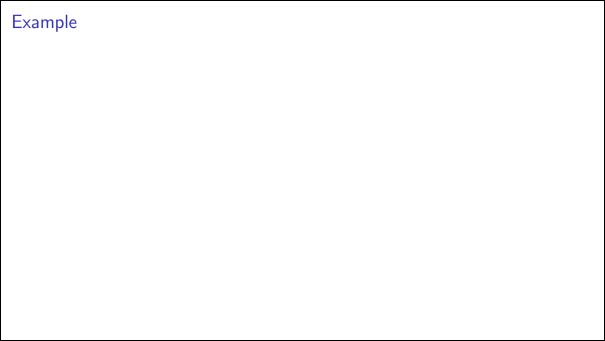
#### NFA to DFA: subset construction

Given an NFA  $M=(\Sigma,Q,\delta,s,A)$ , we can construct an equivalent DFA  $M'=(\Sigma,Q',\delta',s',A')$  as follows:

- $\blacktriangleright \text{ Let } Q' = 2^Q,$
- $ightharpoonup s' = \{s\},$
- $\blacktriangleright \ A' = \{S \subseteq Q \mid S \cap A \neq \emptyset\},\$
- ▶ and let  $\delta': Q' \times \Sigma \longrightarrow Q'$  be such that

$$\delta'(q', a) = \bigcup_{p \in q'} \delta(p, a),$$

for all  $q' \subseteq Q$  and  $a \in \Sigma$ .



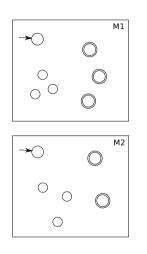
#### Kleene's Theorem

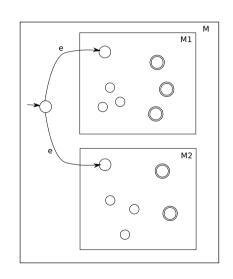
Every language L can be described by a regular expression if and only if L is the language accepted by a DFA.

#### Steps:

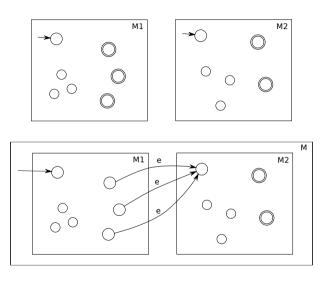
- Every DFA can be transformed into an equivalent NFA. (trivial)
- Every NFA can be transformed into an equivalent DFA. (done)
- Every regular expression can be transformed into an equivalent NFA. (TODO)
- Every NFA can be transformed into an equivalent regular expression. (only idea)

# Warm-up: union of DFA $\Longrightarrow$ NFA





### Concatenation: idea



### Stronger claim

Our goal is to prove:

#### Lemma 2

Every regular language is accepted by a nondeterministic finite-state automaton.

But we will prove a "stronger" claim.

#### Lemma 3 (Thompson's algorithm)

Every regular language is accepted by a nondeterministic finite-state automaton with exactly one accepting state, which is different from its start state.

### Proof (Thompson's algorithm).

Consider any regular expression R over alphaget  $\Sigma$ . We prove that there is an NFA N that accepts the language described by R by induction.

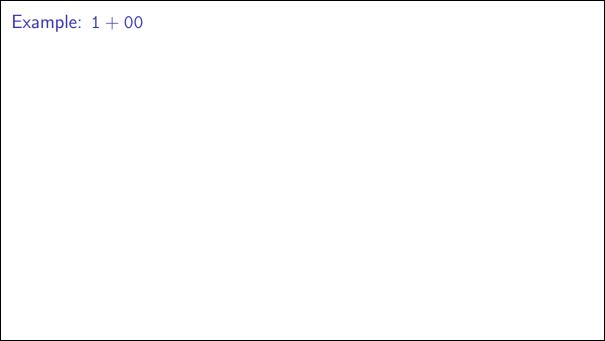
**Induction hypothesis:** for any subexpression S of R, there is an NFA that accepts the language described by S.

We denote an NFA with this notation:

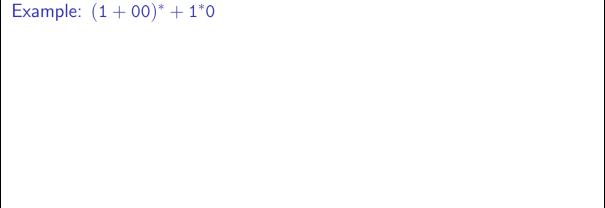
There are 6 cases:

- $ightharpoonup R = \emptyset$ :
  - $ightharpoonup R = \varepsilon$ :
  - ightharpoonup R = a for some  $a \in \Sigma$ :
- ightharpoonup R = ST for some regular expression S and T:
- ightharpoonup R = S + T for some regular expression S and T:
- $ightharpoonup R = S^*$  for some regular expression S:

In all cases, the language L(R) is accepted by an NFA with exactly one accepting state which is different from its start state, as required.

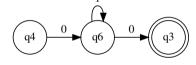




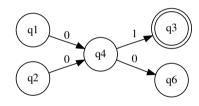




# State elimination: example 1



# State elimination: example 2



## State elimination: example 3

