# 01204211 Discrete Mathematics Lecture 10a: Nondeterministic automata<sup>1</sup>

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September 17, 2024

<sup>&</sup>lt;sup>1</sup>Based on lecture notes of *Models of Computation* course by Jeff Erickson.□ → ← ② → ← ② → ← ② → ◆ ○ ◆

# Review: DFA (Formal definitions)

A finite-state machine or a deterministic finite-state automaton (DFA) has five components:

- ightharpoonup the input alphabet  $\Sigma$ ,
- ightharpoonup a finite set of states Q,
- ightharpoonup a transition function  $\delta: Q \times \Sigma \longrightarrow Q$
- ightharpoonup a start state  $s \in Q$ , and
- ▶ a subset  $A \subseteq Q$  of accepting states.

### Review: Acceptance

One step move: from state q with input symbol a, the machine changes its state to  $\delta(q,a)$ .

**Extension:** from state q with input string w, the machine changes its state to  $\delta^*(q,w)$  defined as

$$\delta^*(q, w) = \begin{cases} q & \text{if } w = \varepsilon, \\ \delta^*(\delta(q, a), x) & \text{if } w = ax. \end{cases}$$

The signature of  $\delta^*$  is  $Q \times \Sigma^* \longrightarrow Q$ .

### $\mathsf{accepting}\ w$

For a finite-state machine with starting state s and accepting states A, it accepts string w iff

$$\delta^*(s, w) \in A$$
.

### Language of a DFA

### L(M)

For a DFA M , let L(M) be the set of all strings that M accepts. More formally, for  $M=(\Sigma,Q,\delta,s,A)$  ,

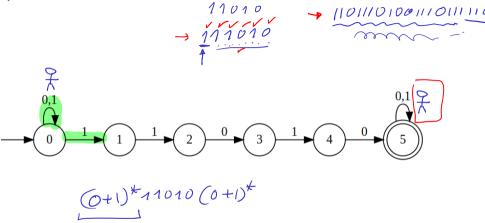
$$L(M) = \{ w \in \Sigma^* \mid \delta^*(s, w) \in A \}.$$

We refer to L(M) as the language of M.

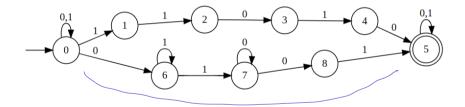
### Acceptance

We also says M accepts L(M).

# New example 1



nondeterministic



What's going on here?

### More relaxed transitions

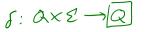
From state  $q \in Q$ , for input a, the machine can "possibly" change its state to many states.

#### More relaxed transitions

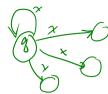
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New transition function  $\delta$ :

### More relaxed transitions







From state  $q \in Q$ , for input a, the machine can "possibly" change its state to many states.

New transition function  $\delta: Q \times \Sigma \longrightarrow 2^{Q}$ .

We refer to this new kind of automaton as a nondeterministic finite-state automaton or NFA.

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What else do we need to define to "properly" talk about NFAs?

One step move: from state q with input symbol a, the machine changes its state to one of  $\delta(q,a)$ .  $\longrightarrow$   $\varphi$ . accepts  $\omega$   $\Longrightarrow$   $\Im mov$   $\Im m$  state  $\Longrightarrow$  accepting states



One step move: from state q with input symbol a, the machine changes its state to one of  $\delta(q,a)$   $\leq \mathcal{Q}$ 

Thus, instead of thinking of a machine that maintains **one** state, we can think of an NFA as a machine that maintains a **set** of states.

If the current set of states is  $C\subseteq Q$  and the input is  $a\in \Sigma$  what would the new set of

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**Extension:** from state  $\widehat{q}$  with input string w, the machine changes its set of states  $\delta^*(q,w)$  defined as

$$\delta^*(q,w) = \begin{cases} \{q\} & \text{if } w = \varepsilon, \\ \\ & \omega > \alpha \cdot \chi \end{cases}$$

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The signature of  $\delta^*$  is  $Q \times \Sigma^* \longrightarrow 2^Q$ .



### Acceptance

### accepting w

For a nondeterministic finite-state machine with starting state s and accepting states A, it accepts string w iff

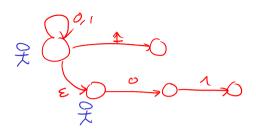
$$\delta^*(s,w) \cap A \neq \emptyset.$$

► Clairvoyance. (あつなみ)

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- ► Parallel threads. (भार्गाम:)

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- ► Parallel threads.
- ► Proofs/oracles.

### $\varepsilon\text{-transition}$

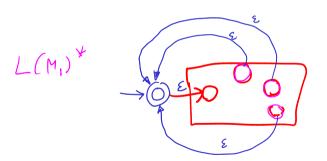


DPA M2  $\varepsilon$ -transition L(M) L(M2)

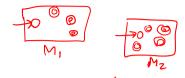


### $\varepsilon$ -transition

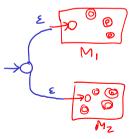




### $\varepsilon$ -transition







An NFA accepts string w iff there is a sequence of transitions

$$\underbrace{3} \xrightarrow{a_1} q_1 \xrightarrow{a_2} q_2 \xrightarrow{a_3} q_3 \xrightarrow{a_4} \cdots \xrightarrow{a_{k-1}} q_{k-1} \xrightarrow{a_k} \underbrace{q_k} ,$$

where  $\underline{q_k} \in \underline{A}$  and  $\underline{w} = a_1 a_2 \cdots a_k$  where  $\underline{a_i} \in \Sigma \cup \{\varepsilon\}$  for  $1 \leq i \leq k$ .

#### $\varepsilon$ -transition

$$\delta(q, r) = \{-\}$$

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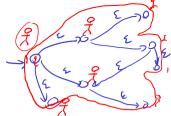
$$s \xrightarrow{a_1} q_1 \xrightarrow{a_2} q_2 \xrightarrow{a_3} q_3 \xrightarrow{a_4} \cdots \xrightarrow{a_{k-1}} q_{k-1} \xrightarrow{a_k} q_k,$$

where  $q_k \in A$  and  $w = a_1 a_2 \cdots a_k$  where  $a_i \in \Sigma \cup \{\varepsilon\}$  for  $1 \le i \le k$ . The transition function also changes its domain to  $Q \times (\Sigma \cup \{\varepsilon\})$ .



# $\varepsilon$ -transition: examples

# $\widehat{\varepsilon}$ reach



The  $\varepsilon$ -reach of state  $q \in Q$  (denoted by  $\varepsilon$ -reach(q)) consists of all states r that satisfy one of the following conditions:

$$\rightarrow$$
  $r = q$ , or  $*$ 

$$ightharpoonup r \in \delta(q', \varepsilon)$$
 for some state  $q'$  in the  $\varepsilon$ -reach of  $q$ .

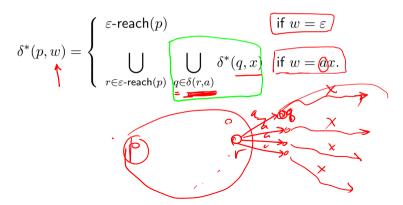








We define  $\delta^*: Q \times \Sigma^* \longrightarrow 2^Q$  as follows:

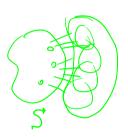


### Notation abuse



We sometimes also write, for subset  $S \subseteq Q$ ,

$$\delta(S,a) = \bigcup_{q \in S} \delta(q,a),$$



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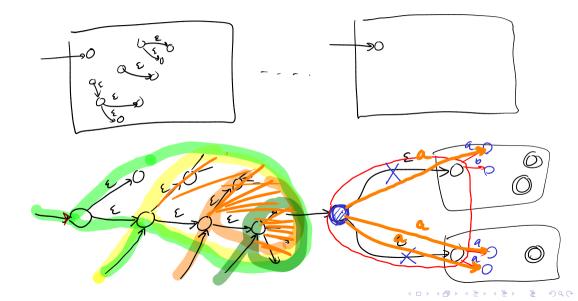
and

$$\varepsilon\text{-reach}(S) = \bigcup_{q \in S} \varepsilon\text{-reach}(q).$$

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$$\delta^*(p,w) = \left\{ \begin{array}{ll} \varepsilon\text{-reach}(p) & \text{if } w = \varepsilon \\ \\ \delta^*(\delta(\varepsilon\text{-reach}(p),a),x) & \text{if } w = ax. \end{array} \right.$$

# Removing $\varepsilon$ -transitions: idea



#### Lemma 1

For any NFA 
$$M=(\Sigma,Q,\delta,s,A)$$
 with  $\varepsilon$ -transitions, there is an NFA  $M'=(\Sigma,Q',\underline{\delta'},s',A')$  without  $\varepsilon$ -transitions such that  $L(M)=L(M')$ .

#### Proof.

In 
$$G'=Q$$
,  $G'=S$ ,

that items  $S'$  now,  $\forall g \in G'$ ,  $\forall a \in E$ 

$$S'(g,a) = S(\varepsilon - reach(g), a), \overline{S'(g,\varepsilon)} = \emptyset$$

that in  $A'=\{g \in G' \mid \varepsilon - reach(g) \cap A \neq \emptyset\} \subseteq \emptyset$ 

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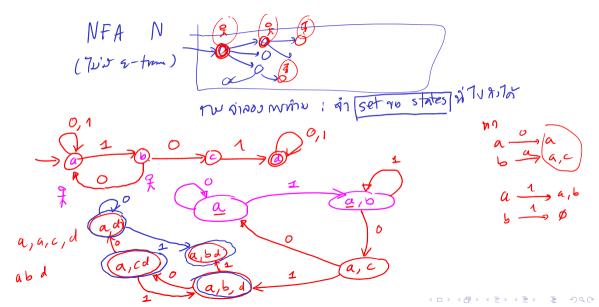
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$$(g,w) = S'(g,w) = S'(g$$

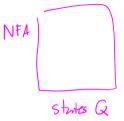
## Main question

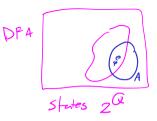
- $\blacktriangleright$  We see that  $\varepsilon$ -transitions does not add any "power" to the machine.
- Does nondeterminism add any power to NFA (over typical DFA)?

# Simulating parallel machines



## Subset construction: idea





### NFA to DFA: subset construction

$$S': Q' \times \Sigma \to Q'$$
  $S: Q \times \Sigma \to 2^Q$ 

Given an NFA  $M=(\Sigma,Q,\delta,s,A)$ , we can construct an equivalent DFA  $M'=(\Sigma,Q',\delta',s',A')$  as follows:

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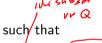
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- $A' = \{ S \subseteq Q \mid S \cap A \neq \emptyset \},$
- ▶ and let  $\delta': Q' \times \Sigma \longrightarrow Q'$  be such that



$$\delta'(\underline{q'},\underline{a}) = \bigcup_{p \in q'} \underline{\delta(p,a)},$$

for all  $q' \subseteq Q$  and  $a \in \Sigma$ .



# Example



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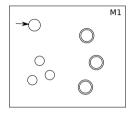
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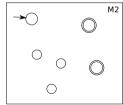
- Every regular expression can be transformed into an equivalent NFA. (TODO)
- Every NFA can be transformed into an equivalent regular expression. (only idea)



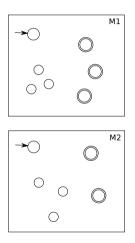


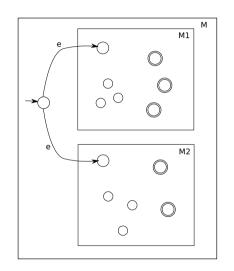
## Warm-up: union of DFA $\Longrightarrow$ NFA



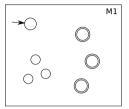


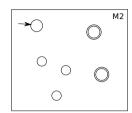
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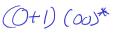


### Concatenation: idea

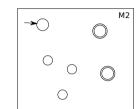




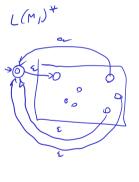
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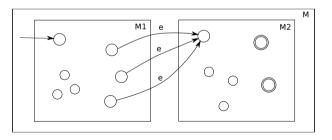


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## Stronger claim

Our goal is to prove:

#### Lemma 2

Every regular language is accepted by a nondeterministic finite-state automaton.

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But we will prove a "stronger" claim.

### Lemma 3 (Thompson's algorithm)

Every regular language is accepted by a nondeterministic finite-state automaton with exactly one accepting state, which is different from its start state.

Consider any regular expression R over alphaget  $\Sigma$ . We prove that there is an NFA N that accepts the language described by R by induction.

**Induction hypothesis:** for any subexpression S of R, there is an NFA that accepts the language described by S.

We denote an NFA with this notation:

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- $ightharpoonup R = \emptyset$ :
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- ightharpoonup R = ST for some regular expression S and T:

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- $ightharpoonup R = S^*$  for some regular expression S:

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We denote an NFA with this notation:

There are 6 cases:

- $ightharpoonup R = \emptyset$ :
- $ightharpoonup R = \varepsilon$ :
- ightharpoonup R = a for some  $a \in \Sigma$ :
- ightharpoonup R = ST for some regular expression S and T:
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In all cases, the language L(R) is accepted by an NFA with exactly one accepting state which is different from its start state, as required.

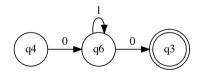
Example: 1 + 00

Example:  $(1 + 00)^*$ 

Example:  $(1+00)^* + 1^*0$ 

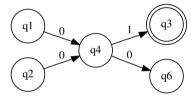
## NFA to Regular expressions

# State elimination: example 1





## State elimination: example 2



## State elimination: example 3

