01204211 Discrete Mathematics Lecture 10a: Nondeterministic automata¹

Jittat Fakcharoenphol

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¹Based on lecture notes of *Models of Computation* course by Jeff Erickson.□ → ← ② → ← ② → ← ② → ◆ ○ ◆

Review: DFA (Formal definitions)

A finite-state machine or a deterministic finite-state automaton (DFA) has five components:

- ightharpoonup the input alphabet Σ ,
- ightharpoonup a finite set of states Q,
- ightharpoonup a transition function $\delta: Q \times \Sigma \longrightarrow Q$
- ightharpoonup a start state $s \in Q$, and
- ▶ a subset $A \subseteq Q$ of accepting states.

Review: Acceptance

One step move: from state q with input symbol a, the machine changes its state to $\delta(q,a)$.

Extension: from state q with input string w, the machine changes its state to $\delta^*(q,w)$ defined as

$$\delta^*(q,w) = \left\{ \begin{array}{ll} q & \text{if } w = \varepsilon, \\ \delta^*(\delta(q,a),x) & \text{if } w = ax. \end{array} \right.$$

The signature of δ^* is $Q \times \Sigma^* \longrightarrow Q$.

$\mathsf{accepting}\ w$

For a finite-state machine with starting state s and accepting states A, it accepts string w iff

$$\delta^*(s, w) \in A$$
.

Language of a DFA

L(M)

For a DFA M , let L(M) be the set of all strings that M accepts. More formally, for $M=(\Sigma,Q,\delta,s,A)$,

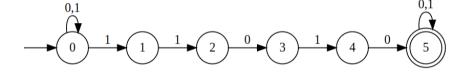
$$L(M) = \{ w \in \Sigma^* \mid \delta^*(s, w) \in A \}.$$

We refer to L(M) as the language of M.

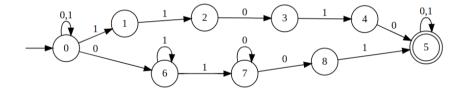
Acceptance

We also says M accepts L(M).

New example 1



New example 2



What's going on here?

More relaxed transitions

From state $q \in Q$, for input a, the machine can "possibly" change its state to many states.

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New transition function δ :

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From state $q \in Q$, for input a, the machine can "possibly" change its state to many states.

New transition function $\delta: Q \times \Sigma \longrightarrow 2^Q$.

We refer to this new kind of automaton as a **nondeterministic finite-state automaton** or **NFA**.

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Remark: δ can return the empty set \emptyset .

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What else do we need to define to "properly" talk about NFAs?

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Thus, instead of thinking of a machine that maintains **one** state, we can think of an NFA as a machine that maintains a **set** of states.

If the current set of states is $C\subseteq Q$ and the input is $a\in \Sigma$ what would the new set of states be?

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$$\delta^*(q, w) = \begin{cases} \{q\} & \text{if } w = \varepsilon, \\ \bigcup_{r \in \delta(q, a)} \delta^*(r, x) & \text{if } w = ax. \end{cases}$$

The signature of δ^* is $Q \times \Sigma^* \longrightarrow 2^Q$.



Acceptance

accepting w

For a nondeterministic finite-state machine with starting state s and accepting states A, it accepts string w iff

$$\delta^*(s, w) \cap A \neq \emptyset.$$

► Clairvoyance.

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- ► Parallel threads.

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- ► Parallel threads.
- ► Proofs/oracles.

ε -transition

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An NFA accepts string w iff there is a sequence of transitions

$$s \xrightarrow{a_1} q_1 \xrightarrow{a_2} q_2 \xrightarrow{a_3} q_3 \xrightarrow{a_4} \cdots \xrightarrow{a_{k-1}} q_{k-1} \xrightarrow{a_k} q_k,$$

where $q_k \in A$ and $w = a_1 a_2 \cdots a_k$ where $a_i \in \Sigma \cup \{\varepsilon\}$ for $1 \le i \le k$.

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where $q_k \in A$ and $w = a_1 a_2 \cdots a_k$ where $a_i \in \Sigma \cup \{\varepsilon\}$ for $1 \le i \le k$. The transition function also changes its domain to $Q \times (\Sigma \cup \{\varepsilon\})$.

ε -transition: examples

ε -reach

The ε -reach of state $q \in Q$ (denoted by ε -reach(q)) consists of all states r that satisfy one of the following conditions:

- ightharpoonup r = q, or
- $ightharpoonup r \in \delta(q', \varepsilon)$ for some state q' in the ε -reach of q.

Extended transition function: δ^*

We define $\delta^*:Q\times\Sigma^*\longrightarrow 2^Q$ as follows:

$$\delta^*(q,w) = \left\{ \begin{array}{ll} \varepsilon\text{-reach}(p) & \text{if } w = \varepsilon \\ \displaystyle \bigcup_{r \in \varepsilon\text{-reach}(p)} \; \bigcup_{q \in \delta(r,q)} \delta^*(q,x) & \text{if } w = ax. \end{array} \right.$$

Notation abuse

We sometimes also write, for subset $S \subseteq Q$,

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and

$$\varepsilon\text{-reach}(S) = \bigcup_{q \in S} \varepsilon\text{-reach}(q).$$

Extended transition function: δ^* (with shorter notation)

We define $\delta^*: Q \times \Sigma^* \longrightarrow 2^Q$ as follows:

$$\delta^*(q,w) = \left\{ \begin{array}{ll} \varepsilon\text{-reach}(p) & \text{if } w = \varepsilon \\ \\ \delta^*(\delta(\varepsilon\text{-reach}(p),a),x) & \text{if } w = ax. \end{array} \right.$$

Removing ε -transitions: idea

Lemma 1

For any NFA $M=(\Sigma,Q,\delta,s,A)$ with ε -transitions, there is an NFA $M'=(\Sigma,Q',\delta',s',A')$ without ε -transitions such that L(M)=L(M').

Proof.

Main question

- \blacktriangleright We see that ε -transitions does not add any "power" to the machine.
- Does nondeterminism add any power to NFA (over typical DFA)?

Simulating parallel machines

Subset construction: idea

NFA to DFA: subset construction

Given an NFA $M=(\Sigma,Q,\delta,s,A)$, we can construct an equivalent DFA $M'=(\Sigma,Q',\delta',s',A')$ as follows:

- $\blacktriangleright \ \ \mathsf{Let} \ Q' = 2^Q,$
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- ▶ and let $\delta': Q' \times \Sigma \longrightarrow Q'$ be such that

$$\delta'(q', a) = \bigcup_{p \in q'} \delta(p, a),$$

for all $q' \subseteq Q$ and $a \in \Sigma$.

Example

Every language L can be described by a regular expression if and only if L is the language accepted by a DFA.

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- Every NFA can be transformed into an equivalent DFA. (done)
- Every regular expression can be transformed into an equivalent NFA.

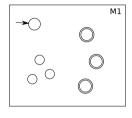
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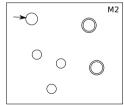
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- ▶ Every regular expression can be transformed into an equivalent NFA. (TODO)

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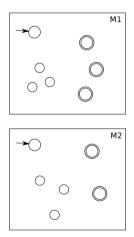
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- Every NFA can be transformed into an equivalent DFA. (done)
- Every regular expression can be transformed into an equivalent NFA. (TODO)
- ▶ Every NFA can be transformed into an equivalent regular expression. (only idea)

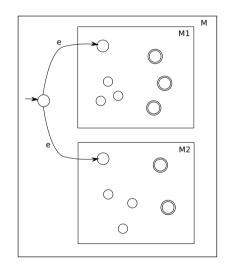
Warm-up: union of DFA \Longrightarrow NFA



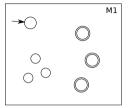


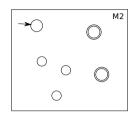
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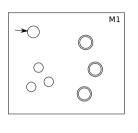


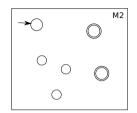
Concatenation: idea

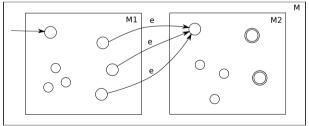




Concatenation: idea







Stronger claim

Our goal is to prove:

Lemma 2

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Every regular language is accepted by a nondeterministic finite-state automaton.

But we will prove a "stronger" claim.

Lemma 3 (Thompson's algorithm)

Every regular language is accepted by a nondeterministic finite-state automaton with exactly one accepting state, which is different from its start state.

Consider any regular expression R over alphaget Σ . We prove that there is an NFA N that accepts the language described by R by induction.

Induction hypothesis: for any subexpression S of R, there is an NFA that accepts the language described by S.

We denote an NFA with this notation:

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- $ightharpoonup R = \emptyset$:
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- $ightharpoonup R = \emptyset$:
- $ightharpoonup R = \varepsilon$:
- ightharpoonup R=a for some $a\in\Sigma$:
- ightharpoonup R = ST for some regular expression S and T:

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- $ightharpoonup R = \emptyset$:
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- $ightharpoonup R = a ext{ for some } a \in \Sigma$:
- ightharpoonup R = ST for some regular expression S and T:
- ightharpoonup R = S + T for some regular expression S and T:

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- $ightharpoonup R = S^*$ for some regular expression S:

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Induction hypothesis: for any subexpression S of R, there is an NFA that accepts the language described by S.

We denote an NFA with this notation:

There are 6 cases:

- $ightharpoonup R = \emptyset$:
- $ightharpoonup R = \varepsilon$:
- ightharpoonup R = a for some $a \in \Sigma$:
- ightharpoonup R = ST for some regular expression S and T:
- ightharpoonup R = S + T for some regular expression S and T:
- $ightharpoonup R = S^*$ for some regular expression S:

In all cases, the language L(R) is accepted by an NFA with exactly one accepting state which is different from its start state, as required.

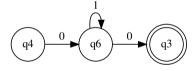
Example: 1 + 00

Example: $(1 + 00)^*$

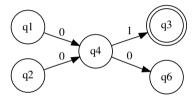
Example: $(1+00)^* + 1^*0$

NFA to Regular expressions

State elimination: example 1



State elimination: example 2



State elimination: example 3

