

$$A = L \cdot U$$

01204211 Discrete Mathematics
Lecture 11a: Gaussian Elimination and LU Decomposition

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$$12 = 3 \cdot 2 \cdot 2$$

Review: A Linear System

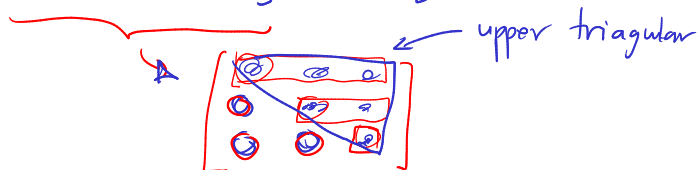
Consider the following system of linear equations:

$$x_1 + x_2 + x_3 = 5$$

$$2x_1 + x_2 + 2x_3 = 10$$

$$3x_1 + x_2 + 2x_3 = 4$$

$$\begin{bmatrix} 1 & 1 & 1 \\ 2 & 1 & 2 \\ 3 & 1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 5 \\ 10 \\ 4 \end{bmatrix}$$



Review: A Linear System

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$$\begin{array}{rrcrcl} x_1 & + & x_2 & + & x_3 & = & 5 \\ 2x_1 & + & x_2 & + & 2x_3 & = & 10 \\ 3x_1 & + & x_2 & + & 2x_3 & = & 4 \end{array}$$

Again we can view it as a vector equation:

$$\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} x_1 + \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} x_2 + \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix} x_3 = \begin{bmatrix} 5 \\ 10 \\ 4 \end{bmatrix}$$

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Solving this system is equivalent to testing if

$$[5, 10, 4] \in \text{Span} \{[1, 2, 3], [1, 1, 1], [1, 2, 2]\}.$$

Review: Testing spans

Problem

Given a set of n -vectors $S = \{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\}$ over \mathbb{F} and an n -vector \mathbf{v} , can we check if $\mathbf{v} \in \text{Span } S$?

Example: Consider 3-vectors over \mathbb{R} . Let

$$\mathbf{u}_1 = [1, 2, 3], \mathbf{u}_2 = [1, 1, 1], \mathbf{u}_3 = [1, 2, 2].$$

We would like to check if

$$\mathbf{v} = [10, 13, 29] \in \text{Span } \{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}.$$

Let us define variables $\alpha_1, \alpha_2, \alpha_3$ such that $\mathbf{v} = \alpha_1 \mathbf{u}_1 + \alpha_2 \mathbf{u}_2 + \alpha_3 \mathbf{u}_3$; i.e., we want $\alpha_1, \alpha_2, \alpha_3$ to be such that

$$\alpha_1 \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} + \alpha_2 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + \alpha_3 \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix} = \begin{bmatrix} 10 \\ 13 \\ 29 \end{bmatrix}$$

Matrix form

We can write these constraints down as the following linear equations.

$$\begin{array}{rcrcrcrcrcl} 1\alpha_1 & + & 1\alpha_2 & + & 1\alpha_3 & = & 10 \\ 2\alpha_1 & + & 1\alpha_2 & + & 2\alpha_3 & = & 13 \\ 3\alpha_1 & + & 1\alpha_2 & + & 2\alpha_3 & = & 29 \end{array}$$

We also can, equivalently, write them in matrix form.

$$\begin{bmatrix} 1 & 1 & 1 \\ 2 & 1 & 2 \\ 3 & 1 & 2 \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{bmatrix} = \begin{bmatrix} 10 \\ 13 \\ 29 \end{bmatrix}$$

Review: Properties of matrix multiplications

Let A, B, C be matrices.

- ▶ (Associative) $(AB)C = A(BC)$
- ▶ (Distributive) $A(B + C) = AB + AC$
- ▶ In general not commutative: Usually $AB \neq BA$

Identity Matrix

Definition

An n -by- n matrix I is an **identity matrix** if

$$I = \begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 \\ \vdots & \vdots & & \vdots \\ 0 & 0 & \cdots & 1 \end{bmatrix}$$

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An n -by- n matrix I is an **identity matrix** if

$$I = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix},$$

such that $a_{ii} = 1$ for $1 \leq i \leq n$ and $a_{ij} = 0$ for all $i \neq j$.

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For any n -by- m matrix A ,

$$IA = A,$$

and for any m -by- n matrix B ,

$$BI = B.$$

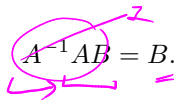
Inverses

Definition

For an n -by- n matrix A , the **inverse of A** , denoted by A^{-1} , is an n -by- n matrix such that

$$AA^{-1} = A^{-1}A = I.$$

Remark 1: You can think of an inverse as a matrix that let you “get back” anything after multiplying with A , i.e.,


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Remark 3: A might not have an inverse. If A has an inverse, we say that A is **invertible**.

Lemma 1

If A and B are invertible, we have that

$$(AB)^{-1} = B^{-1}A^{-1}.$$

Proof.

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Transpose

- ▶ $(AB)^T = B^T A^T$.
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Definition

Matrix A is **symmetric** if

$$A = A^T.$$

Solving a system of linear equations

For an $n \times n$ matrix A and a system of linear equations

$$A\mathbf{x} = \mathbf{b},$$

with n variables $\mathbf{x} = [x_1, x_2, \dots, x_n]$, if A^{-1} is an inverse of A , we can use it to solve for \mathbf{x} .

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Note that we can multiply on the left of both sides with A^{-1} to obtain

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Thus

$$\mathbf{x} = A^{-1}\mathbf{b},$$

is the solution of the system.

$$\begin{bmatrix} 3 & 3 & 3 \\ 2 & 1 & 2 \\ 3 & 1 & 2 \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{bmatrix} = \begin{bmatrix} 30 \\ 13 \\ 29 \end{bmatrix}$$

Let's perform Gaussian elimination.

$$\begin{bmatrix} 3 & 3 & 3 \\ 2 & 1 & 2 \\ 3 & 1 & 2 \end{bmatrix} \xrightarrow{R_1 \leftarrow R_1/3} \begin{bmatrix} 1 & 1 & 1 \\ 2 & 1 & 2 \\ 3 & 1 & 2 \end{bmatrix} \xrightarrow{\begin{matrix} R_2 \leftarrow R_2 - 2R_1 \\ R_3 \leftarrow R_3 - 3R_1 \end{matrix}} \begin{bmatrix} 1 & 1 & 1 \\ 0 & -1 & 0 \\ 0 & -2 & -1 \end{bmatrix} \xrightarrow{R_2 \leftarrow -R_2} \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 0 \\ 0 & -2 & -1 \end{bmatrix} \xrightarrow{R_3 \leftarrow R_3 + 2R_2} \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \xrightarrow{R_3 \leftarrow -R_3} \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{R_1 \leftarrow R_1 - R_2} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{R_1 \leftarrow R_1 - R_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} \textcircled{1} & 1 & 1 \\ \textcircled{2} & 1 & 2 \\ 3 & 1 & 2 \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{bmatrix} = \begin{bmatrix} 10 \\ 13 \\ 29 \end{bmatrix}$$

Let's perform Gaussian elimination.

$$\begin{aligned} R_2 &\leftarrow R_2 - R_1 \\ R_3 &\leftarrow R_3 - 3R_1 \end{aligned}$$

$$\begin{bmatrix} 1 & 1 & 1 \\ 2 & 1 & 2 \\ 3 & 1 & 2 \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{bmatrix} = \begin{bmatrix} 10 \\ 13 \\ 29 \end{bmatrix}$$

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$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & -1 & 0 \\ 0 & -2 & -1 \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{bmatrix} = \begin{bmatrix} 10 \\ -7 \\ -1 \end{bmatrix}$$

$$R_3 \leftarrow R_3 - 2R_2$$

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We can perform backward substitution to find that $\alpha_1 = 16$, $\alpha_2 = 7$, and $\alpha_3 = -13$.

Gaussian elimination and matrix operations

We will look closer to see how we could “describe” the steps from Gaussian elimination using matrix multiplications. This would be very useful later. We start with

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 2 & 1 & 2 \\ 3 & 1 & 2 \end{bmatrix}.$$

The first row operation we did is: $R_2 \leftarrow R_2 - 2R_1$
Can we explain this step with a matrix multiplication?

The image shows a handwritten equation representing the row operation $R_2 \leftarrow R_2 - 2R_1$ as a matrix multiplication. On the left, a blue-outlined matrix M is shown, representing an elementary matrix that subtracts 2 times the first row from the second row. It has a horizontal line between the first and second rows, and another between the second and third rows. The first row is $[1, 0, 0]$, the second row is $[-2, 1, 0]$, and the third row is $[0, 0, 1]$. The -2 is written in pink. Below the matrix is the label M . In the middle, a red-outlined matrix A is shown, representing the original matrix. It has a horizontal line between the first and second rows. The first row is $[1, 1, 1]$, the second row is $[2, 1, 2]$, and the third row is $[3, 1, 2]$. The third row is circled in blue. Below the matrix is the label A . To the right of matrix A is an equals sign, followed by a red-outlined matrix representing the result of the operation. This matrix has a horizontal line between the first and second rows. The first row is $[1, 1, 1]$, the second row is $[0, -1, 0]$, and the third row is $[3, 1, 2]$. The third row is underlined in blue.

$$\begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 2 & 1 & 2 \\ 3 & 1 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 0 & -1 & 0 \\ 3 & 1 & 2 \end{bmatrix}$$

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Can we explain this step with a matrix multiplication? I.e., can we find M such that

$$MA = \begin{bmatrix} 1 & 1 & 1 \\ 0 & -1 & 0 \\ 3 & 1 & 2 \end{bmatrix}.$$

We currently have

$$MA = \begin{bmatrix} 1 & 1 & 1 \\ 0 & -1 & 0 \\ 3 & 1 & 2 \end{bmatrix}.$$

The next row operation we did is: $R_3 \leftarrow R_3 - 3R_1$

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$$M'MA = \begin{bmatrix} 1 & 1 & 1 \\ 0 & -1 & 0 \\ 0 & -2 & -1 \end{bmatrix}.$$

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Elementary matrices

$[A]$

$E_{12} A$

Operations	Result	Elementary matrix	Remarks
$R_2 \leftarrow R_2 - 2R_1$	$\begin{bmatrix} 1 & 1 & 1 \\ 0 & -1 & 0 \\ 3 & 1 & 2 \end{bmatrix}$	$E_{12} = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$	
$R_3 \leftarrow R_3 - 3R_1$	$\begin{bmatrix} 1 & 1 & 1 \\ 0 & -1 & 0 \\ 0 & -2 & -1 \end{bmatrix}$	$E_{13} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -3 & 0 & 1 \end{bmatrix}$	
$R_3 \leftarrow R_3 - 2R_2$	$\begin{bmatrix} 1 & 1 & 1 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$	$E_{23} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -2 & 1 \end{bmatrix}$	

$E_{13}(E_{12} A)$

$U = E_{23} E_{13} E_{12} A$

$$4 \left(\frac{1}{5} \right) \left(\frac{1}{4} \right) \cancel{4.5} - 6 \cdot x = 0$$
$$x = \frac{4 \left(\frac{1}{5} \right) \left(\frac{1}{4} \right)}{6}$$

Recall that we have $R_3 \leftarrow R_3 - 2R_2$

$$E_{32} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -2 & 1 \end{bmatrix}, \quad E_{13} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -3 & 0 & 1 \end{bmatrix}, \quad E_{12} = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

Let $E_{12}^{-1}, E_{13}^{-1}, E_{23}^{-1}$ be inverses of E_{12}, E_{13}, E_{23} , respectively.

It is not hard to see that

$$E_{12}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 2 & 1 \end{bmatrix}, \quad E_{13}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & 0 & 1 \end{bmatrix}, \quad E_{23}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$R_3 \leftarrow R_3 + 2R_2$$

Recall that we have

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Therefore, we can write

$$E_{12}^{-1} E_{13}^{-1} E_{23}^{-1} E_{23} E_{13} E_{12} A = A = E_{12}^{-1} E_{13}^{-1} E_{23}^{-1} B,$$

After working out the multiplication

$$E_{12}^{-1}E_{13}^{-1}E_{23}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 2 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 3 & 2 & 1 \end{bmatrix}$$

we see that

$$\overset{A}{\begin{bmatrix} 1 & 1 & 1 \\ 2 & 1 & 2 \\ 3 & 1 & 2 \end{bmatrix}} = \overset{L}{\begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 3 & 2 & 1 \end{bmatrix}} \overset{U}{\begin{bmatrix} 1 & 1 & 1 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}}.$$

The matrix A is “factored” into two matrices. We denote the first matrix L (for lower triangular) and the second one U (for upper triangular).

This is called an **LU decomposition** of A .

Why is an LU decomposition useful? (1)

Why is an LU decomposition useful? (2)

LU decomposition - pivots