

01204211 Discrete Mathematics

Lecture 11a: Gaussian Elimination and LU Decomposition

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Review: A Linear System

Consider the following system of linear equations:

$$\begin{array}{rrcrcl} x_1 & + & x_2 & + & x_3 & = & 5 \\ 2x_1 & + & x_2 & + & 2x_3 & = & 10 \\ 3x_1 & + & x_2 & + & 2x_3 & = & 4 \end{array}$$

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Again we can view it as a vector equation:

$$\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} x_1 + \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} x_2 + \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix} x_3 = \begin{bmatrix} 5 \\ 10 \\ 4 \end{bmatrix}$$

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Solving this system is equivalent to testing if

$$[5, 10, 4] \in \text{Span} \{[1, 2, 3], [1, 1, 1], [1, 2, 2]\}.$$

Review: Testing spans

Problem

Given a set of n -vectors $S = \{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\}$ over \mathbb{F} and an n -vector \mathbf{v} , can we check if $\mathbf{v} \in \text{Span } S$?

Example: Consider 3-vectors over \mathbb{R} . Let

$$\mathbf{u}_1 = [1, 2, 3], \mathbf{u}_2 = [1, 1, 1], \mathbf{u}_3 = [1, 2, 2].$$

We would like to check if

$$\mathbf{v} = [10, 13, 29] \in \text{Span } \{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}.$$

Let us define variables $\alpha_1, \alpha_2, \alpha_3$ such that $\mathbf{v} = \alpha_1 \mathbf{u}_1 + \alpha_2 \mathbf{u}_2 + \alpha_3 \mathbf{u}_3$; i.e., we want $\alpha_1, \alpha_2, \alpha_3$ to be such that

$$\alpha_1 \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} + \alpha_2 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + \alpha_3 \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix} = \begin{bmatrix} 10 \\ 13 \\ 29 \end{bmatrix}$$

Matrix form

We can write these constraints down as the following linear equations.

$$1\alpha_1 + 1\alpha_2 + 1\alpha_3 = 10$$

$$2\alpha_1 + 1\alpha_2 + 2\alpha_3 = 13$$

$$3\alpha_1 + 1\alpha_2 + 2\alpha_3 = 29$$

We also can, equivalently, write them in matrix form.

$$\begin{bmatrix} 1 & 1 & 1 \\ 2 & 1 & 2 \\ 3 & 1 & 2 \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{bmatrix} = \begin{bmatrix} 10 \\ 13 \\ 29 \end{bmatrix}$$

Review: Properties of matrix multiplications

1+2+5+7

Let A, B, C be matrices.

- ▶ (Associative) $(AB)C = A(BC)$
- ▶ (Distributive) $A(B + C) = AB + AC$
- ▶ In general not commutative: Usually $AB \neq BA$

Identity Matrix

Definition

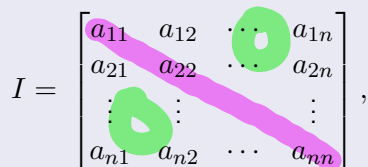
An n -by- n matrix I is an **identity matrix** if

$$I = \begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 \\ \vdots & \vdots & & \vdots \\ 0 & 0 & \cdots & 1 \end{bmatrix}$$

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An n -by- n matrix I is an **identity matrix** if

$$I = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix},$$
A diagram of an identity matrix. The matrix is represented as a square array of elements a_{ij} . A thick pink diagonal line runs from the top-left element a_{11} to the bottom-right element a_{nn} . Three green circles are drawn around the elements a_{11} , a_{22} , and a_{nn} , which are the ones on the diagonal.

such that $a_{ii} = 1$ for $1 \leq i \leq n$ and $a_{ij} = 0$ for all $i \neq j$.

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For any n -by- m matrix A ,

$$\underline{IA} = A,$$

and for any m -by- n matrix B ,

$$\underline{BI} = B.$$

Inverses

$$\frac{1}{2} = 2^{-1}$$

Definition

For an n -by- n matrix A , the **inverse of A** , denoted by A^{-1} , is an n -by- n matrix such that

$$\underline{AA^{-1}} = \underline{A^{-1}A} = I.$$

Remark 1: You can think of an inverse as a matrix that let you “get back” anything after multiplying with A , i.e.,

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$$R = IR = (LA)R = LAR = L(AR) = LI = L.$$

Remark 3: A might not have an inverse. If A has an inverse, we say that A is **invertible**.

Lemma 1

If A and B are invertible, we have that

$$(AB)^{-1} = B^{-1}A^{-1}.$$

Proof.

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Transpose

- ▶ $(AB)^T = B^T A^T$.
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This is because

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Definition

Matrix A is symmetric if

$$A = A^T.$$

$$\begin{bmatrix} 1 & 3 & 0 \\ 3 & 2 & 7 \\ 0 & 7 & 1 \end{bmatrix}$$

Solving a system of linear equations

For an $n \times n$ matrix A and a system of linear equations

$$Ax = b,$$

with n variables $x = [x_1, x_2, \dots, x_n]$, if A^{-1} is an inverse of A , we can use it to solve for x .

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For an $n \times n$ matrix A and a system of linear equations

$$A\mathbf{x} = \mathbf{b},$$

with n variables $\mathbf{x} = [x_1, x_2, \dots, x_n]$, if A^{-1} is an inverse of A , we can use it to solve for \mathbf{x} .

Note that we can multiply on the left of both sides with A^{-1} to obtain

$$\underline{A^{-1}A}\mathbf{x} = A^{-1}\mathbf{b}.$$

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Note that we can multiply on the left of both sides with A^{-1} to obtain

$$x = A^{-1}Ax = A^{-1}b.$$

Thus

$$x = \underbrace{A^{-1}b},$$

is the solution of the system.

$$\begin{bmatrix} 1 & 1 & 1 \\ 2 & 1 & 2 \\ 3 & 1 & 2 \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{bmatrix} = \begin{bmatrix} 10 \\ 13 \\ 29 \end{bmatrix}$$

Let's perform Gaussian elimination.

$$\begin{bmatrix} 1 & 1 & 1 \\ 2 & 1 & 2 \\ 3 & 1 & 2 \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{bmatrix} = \begin{bmatrix} 10 \\ 13 \\ 29 \end{bmatrix}$$

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$$\begin{aligned} & \text{Red: } R_2 \leftarrow R_2 + (-2)R_1 \rightarrow \\ & \text{Blue: } R_3 \leftarrow R_3 + (-3)R_1 \rightarrow \end{aligned} \begin{bmatrix} 1 & 1 & 1 \\ 0 & -1 & 0 \\ 0 & -2 & -1 \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{bmatrix} = \begin{bmatrix} 10 \\ -7 \\ -1 \end{bmatrix}$$

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$$R_3 \leftarrow R_3 - 2R_2 \rightarrow \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{bmatrix} = \begin{bmatrix} 10 \\ 7 \\ 13 \end{bmatrix}$$

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We can perform backward substitution to find that $\alpha_1 = 16$, $\alpha_2 = 7$, and $\alpha_3 = -13$.

Gaussian elimination and matrix operations

We will look closer to see how we could “describe” the steps from Gaussian elimination using matrix multiplications. This would be very useful later. We start with

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 2 & 1 & 2 \\ 3 & 1 & 2 \end{bmatrix}.$$

The first row operation we did is: $R_2 \leftarrow R_2 - 2R_1$
Can we explain this step with a matrix multiplication?

Gaussian elimination and matrix operations

We will look closer to see how we could “describe” the steps from Gaussian elimination using matrix multiplications. This would be very useful later. We start with

$$M = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad A = \begin{bmatrix} 1 & 1 & 1 \\ 2 & 1 & 2 \\ 3 & 1 & 2 \end{bmatrix}.$$

The first row operation we did is: $R_2 \leftarrow R_2 - 2R_1$

Can we explain this step with a matrix multiplication? I.e., can we find M such that

$$MA = \begin{bmatrix} 1 & 1 & 1 \\ 0 & -1 & 0 \\ 3 & 1 & 2 \end{bmatrix} \quad \div R_2 + (-2)R_1$$

We currently have

$$MA = \begin{bmatrix} 1 & 1 & 1 \\ 0 & -1 & 0 \\ 3 & 1 & 2 \end{bmatrix}.$$

The next row operation we did is: $R_3 \leftarrow R_3 - 3R_1$

Can we explain this step with a matrix multiplication?

We currently have

$$M' = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -3 & 0 & 1 \end{bmatrix} \quad MA = \begin{bmatrix} 1 & 1 & 1 \\ 0 & -1 & 0 \\ 3 & 1 & 2 \end{bmatrix}.$$

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Elementary matrices

Operations	Result	Elementary matrix	Remarks
$R_2 \leftarrow R_2 - 2R_1$	$\begin{bmatrix} 1 & 1 & 1 \\ 0 & -1 & 0 \\ 3 & 1 & 2 \end{bmatrix}$	$\underline{E_{12}} = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$	<i>inverse.</i> $E_{12}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$
$R_3 \leftarrow R_3 - 3R_1$	$\begin{bmatrix} 1 & 1 & 1 \\ 0 & -1 & 0 \\ 0 & -2 & -1 \end{bmatrix}$ ✓	$\underline{E_{13}} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -3 & 0 & 1 \end{bmatrix}$	
$R_3 \leftarrow R_3 - 2R_2$	$\begin{bmatrix} 1 & 1 & 1 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$ ✓	$\underline{E_{23}} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -2 & 1 \end{bmatrix}$ ✓	

Recall that we have

$$E_{\underline{23}} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -2 & 1 \end{bmatrix}, \quad E_{13} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -3 & 0 & 1 \end{bmatrix}, \quad E_{\underline{23}} = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

Let $E_{12}^{-1}, E_{13}^{-1}, E_{23}^{-1}$ be inverses of E_{12}, E_{13}, E_{23} , respectively.

It is not hard to see that

$$E_{12}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

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Therefore, we can write

$$\underbrace{E_{12}^{-1} E_{13}^{-1} E_{23}^{-1} E_{23} E_{13} E_{12}}_{\text{red arcs}} A = \underbrace{A}_{\text{red circle}} = E_{12}^{-1} E_{13}^{-1} E_{23}^{-1} B,$$

After working out the multiplication

$$E_{12}^{-1} E_{13}^{-1} E_{23}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 2 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 3 & 2 & 1 \end{bmatrix}$$

we see that

$$\begin{bmatrix} 1 & 1 & 1 \\ 2 & 1 & 2 \\ 3 & 1 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 3 & 2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}.$$

The matrix A is “factored” into two matrices. We denote the first matrix L (for lower triangular) and the second one U (for upper triangular).

This is called an **LU decomposition** of A .

Why is an LU decomposition useful? (1)

$$Ax = b$$

$A \rightarrow LU$

$$L(Ux) = b$$

$$\begin{bmatrix} \text{Lower triangular} \end{bmatrix} \begin{bmatrix} \text{Upper triangular} \end{bmatrix} \begin{bmatrix} x \end{bmatrix} = \begin{bmatrix} b \end{bmatrix}$$

$$\begin{array}{l} Ux = b \\ Lx = b \end{array}$$

Solve in

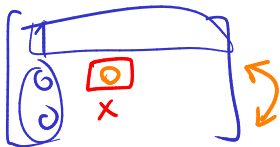
iii $Ly = b$ or y

iii $Ux = y$ or x

Why is an LU decomposition useful? (2)

$$A = LU, \quad A^{-1} = (LU)^{-1} = U^{-1}L^{-1}$$

LU decomposition - pivots



$$\begin{bmatrix} 1 & & & 0 \\ & 1 & & \\ 0 & & 1 & 1 \\ & 0 & & 1 \end{bmatrix}$$

permutation matrix.

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{bmatrix}$$

$$= \begin{bmatrix} r_1 \\ r_4 \\ r_2 \\ r_3 \end{bmatrix}$$