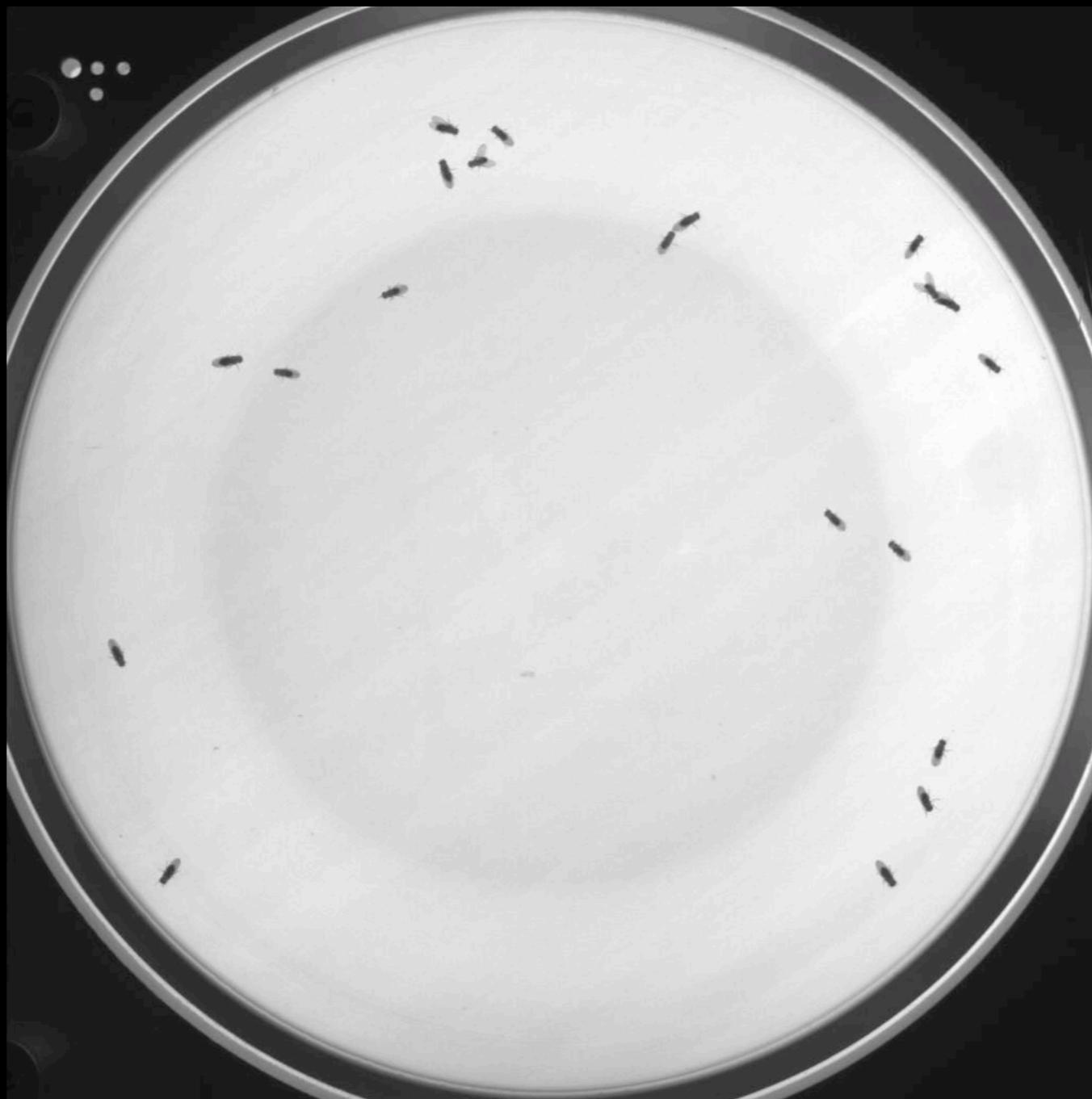


# Imitation learning to understand behaviour

Daniel Jiwoong Im  
Branson Lab

# Motivation

**fly behaviour are diverse and complex**



# Goals

- To gain insight into the structure and rules governing fly behaviour.
- To identify the important components for deciding fly actions.

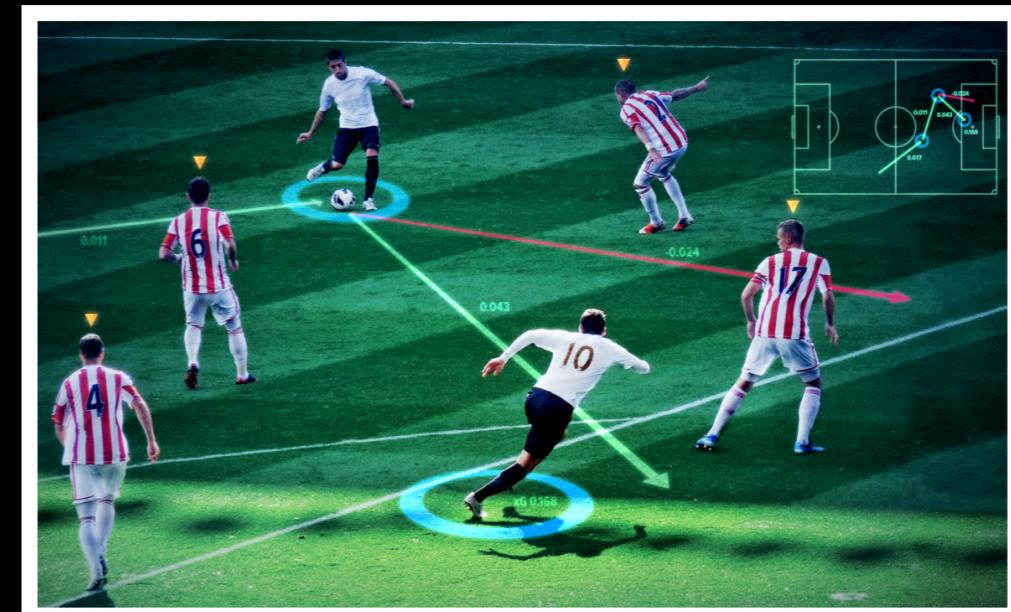
# Predicting behaviour



Pedestrian prediction for self-driving cars



Stock market forecast



Sports Analytics

## Our Approach (Outline)

1. Simulate an artificial fly that behaves like a fly.

- Using machine learning (ML), we build a black box model that produce fly behaviours without explicit rules, instead by pattern recognition and inference from the data

2. Interpret and understand the behaviour of artificial fly

- Do controlled experiments: psychophysics studies and look into how black box model functions

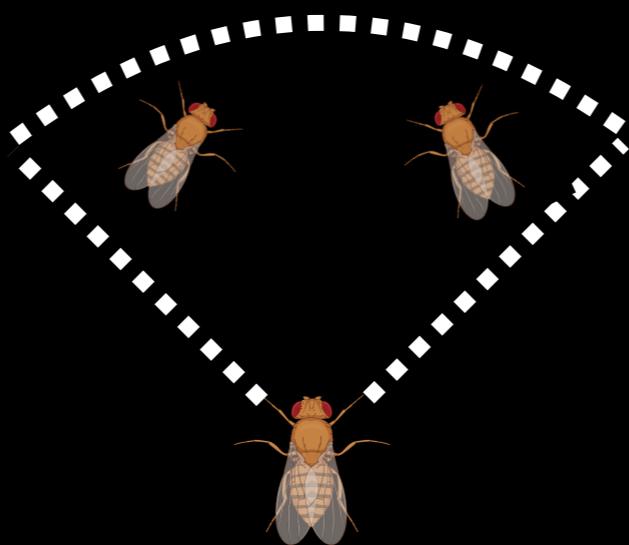
# Quantifying behaviour



Approximate ...



what fly is **doing**

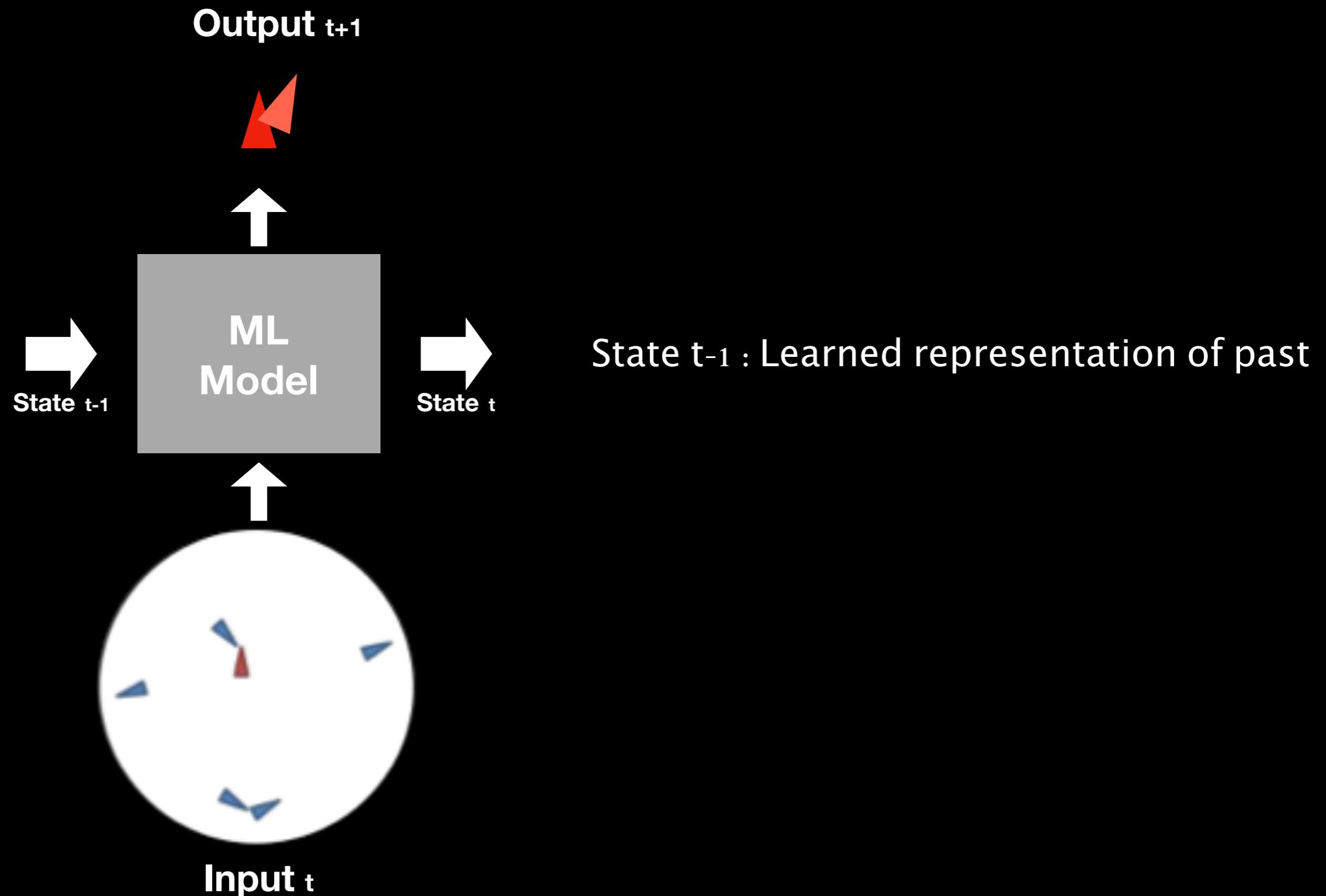


what fly is **seeing**



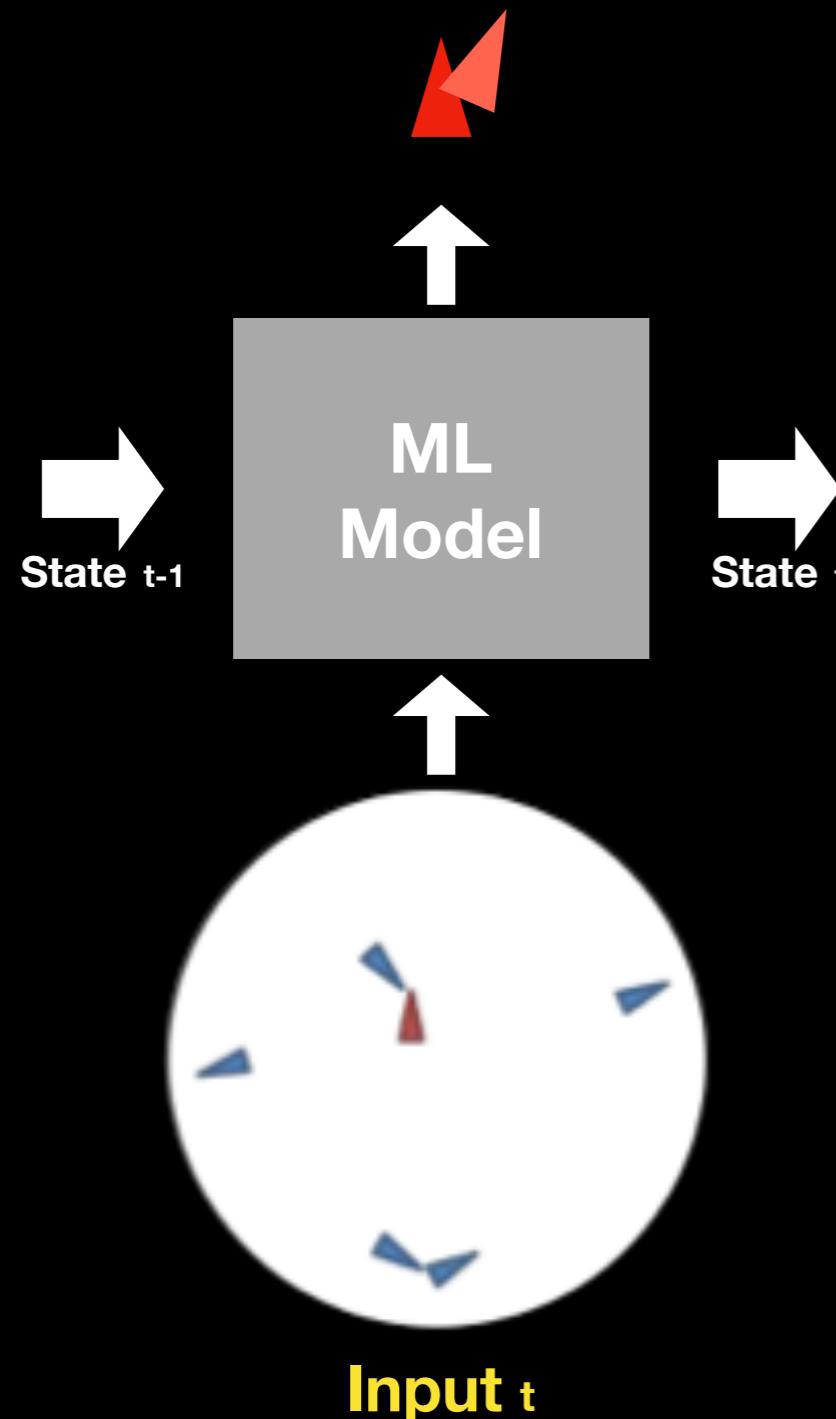
its relative position to the **chamber**

# Predicting the next movement



# Predicting the next movement

Position  $t+1$



**Predicts 8 motion features:**

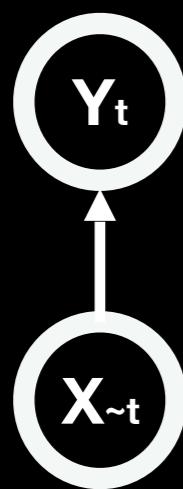
- Forward velocity
- Side velocity
- angular velocity
- Left & right wing length
- Left & right wing angle
- Body length

# **Model Architectures**

X<sub>t</sub> - Output  
X<sub>t</sub> - Input  
U<sub>t</sub>, L<sub>t</sub> - Intermediate layers

# Model Architectures

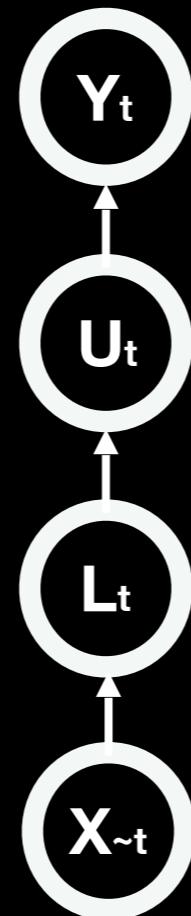
## LINEAR



Simple model:

Linear Regression

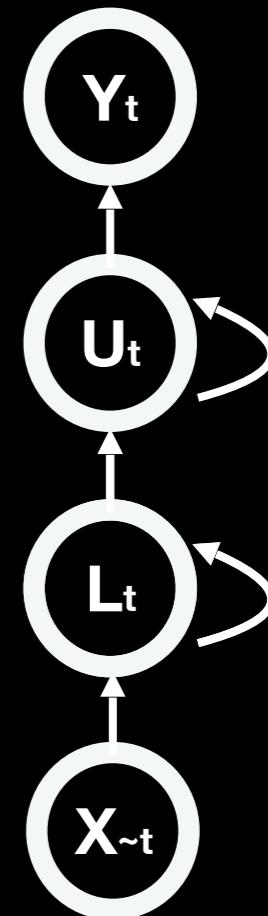
## CNN



Feedforward model:

Convolutional neural network

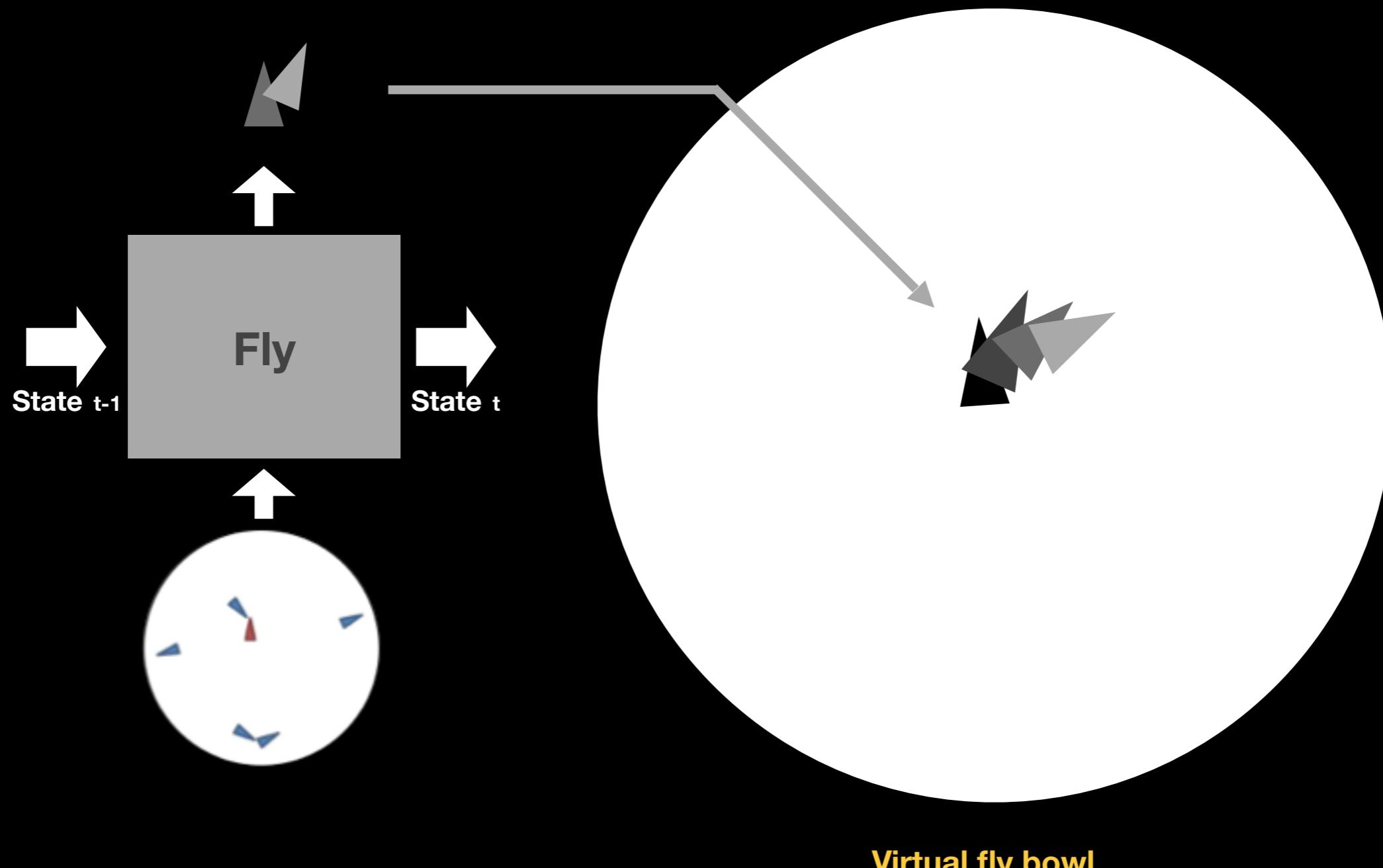
## RNN



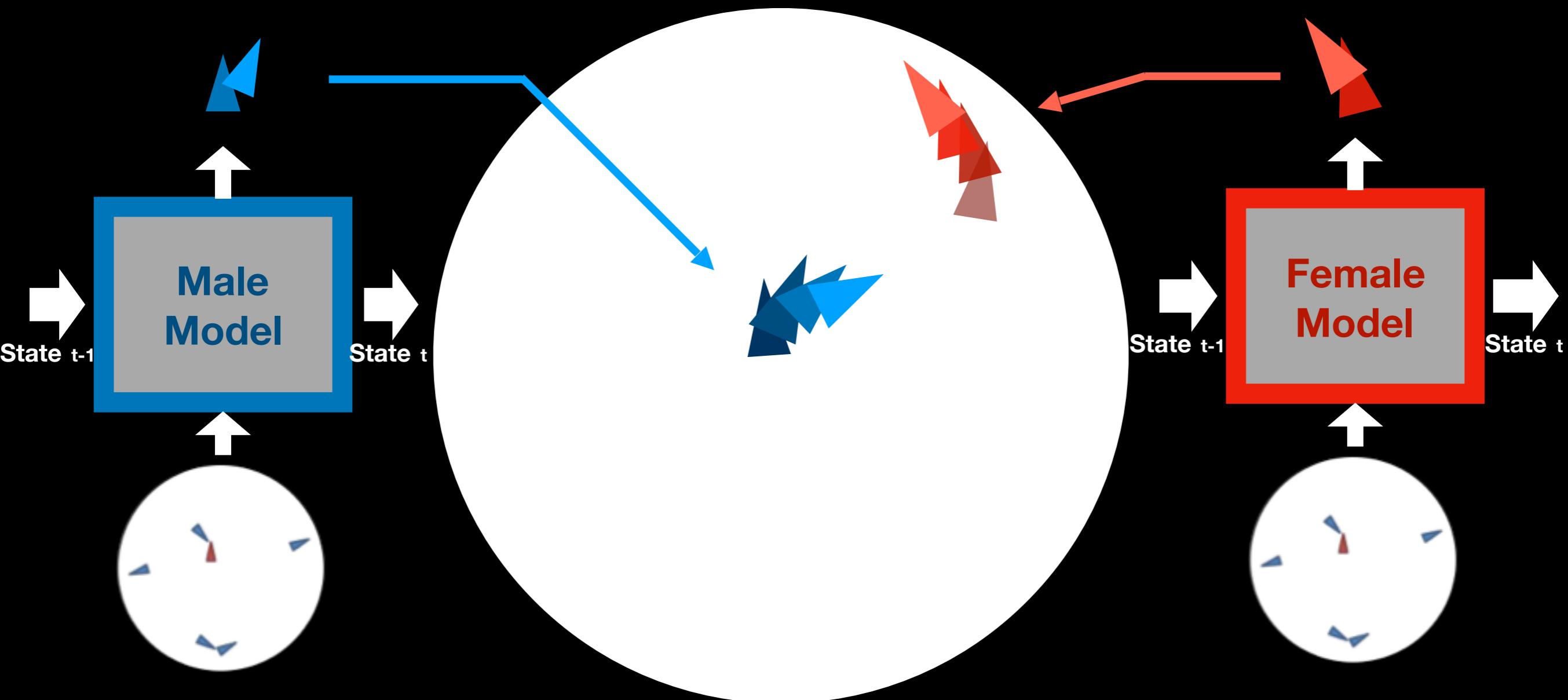
Model with memory:

Recurrent neural network

# Artificial fly is an agent



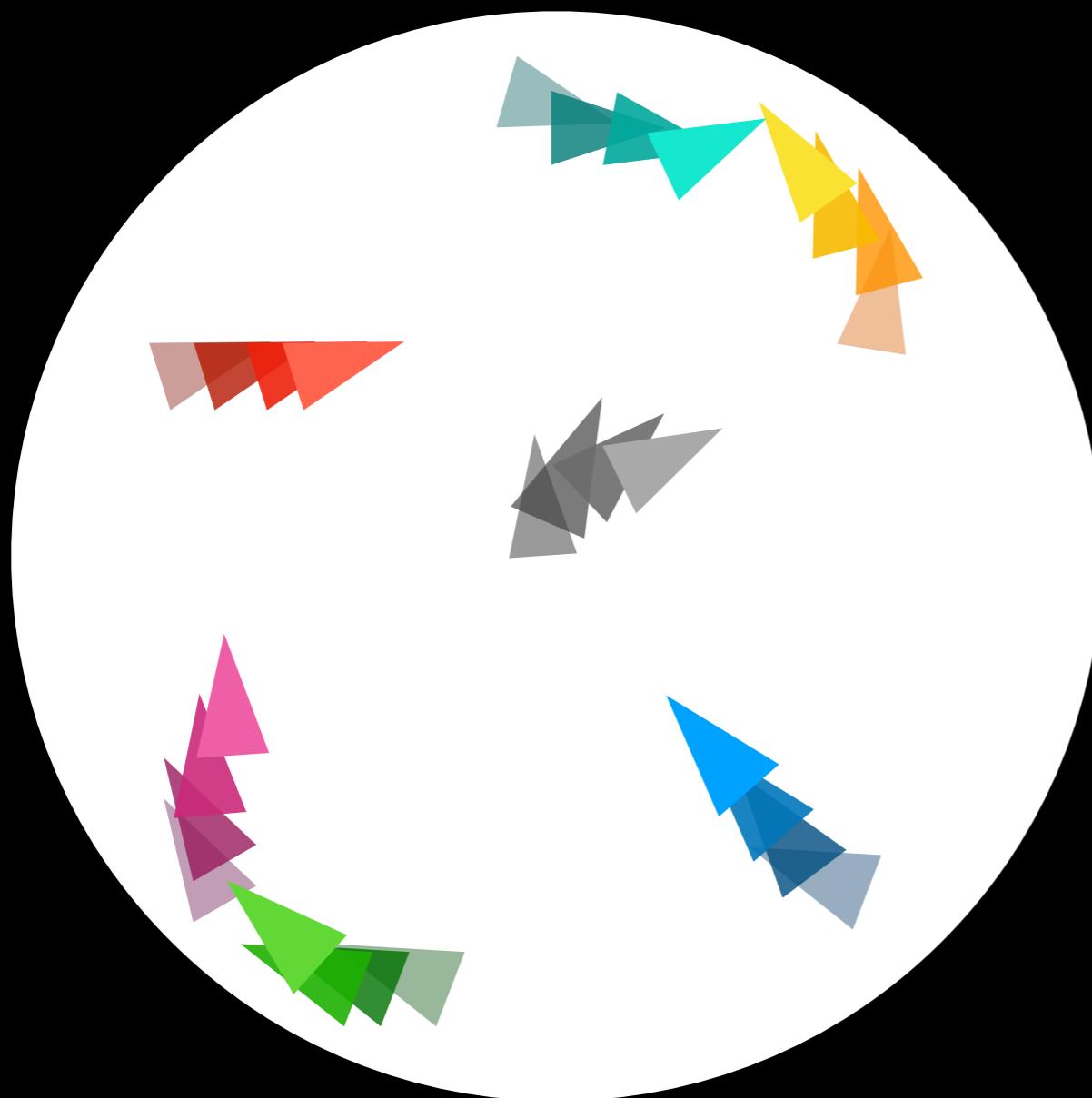
# Artificial male & female fly



# Multi-agent system



# Social interaction system



The behaviours that we consider to differentiate between real versus simulated flies:

- Movement patterns
- Avoiding obstacles
- Exploring the edge of the arena
- Social interactions

# **Simulations**

Real Data

RNN

# Simulations

Videos

LINEAR

CNN

# Artificial Fly Evaluation

Goal: Simulated fly to use mechanisms that real fly is using.  
How to measure how true this is?

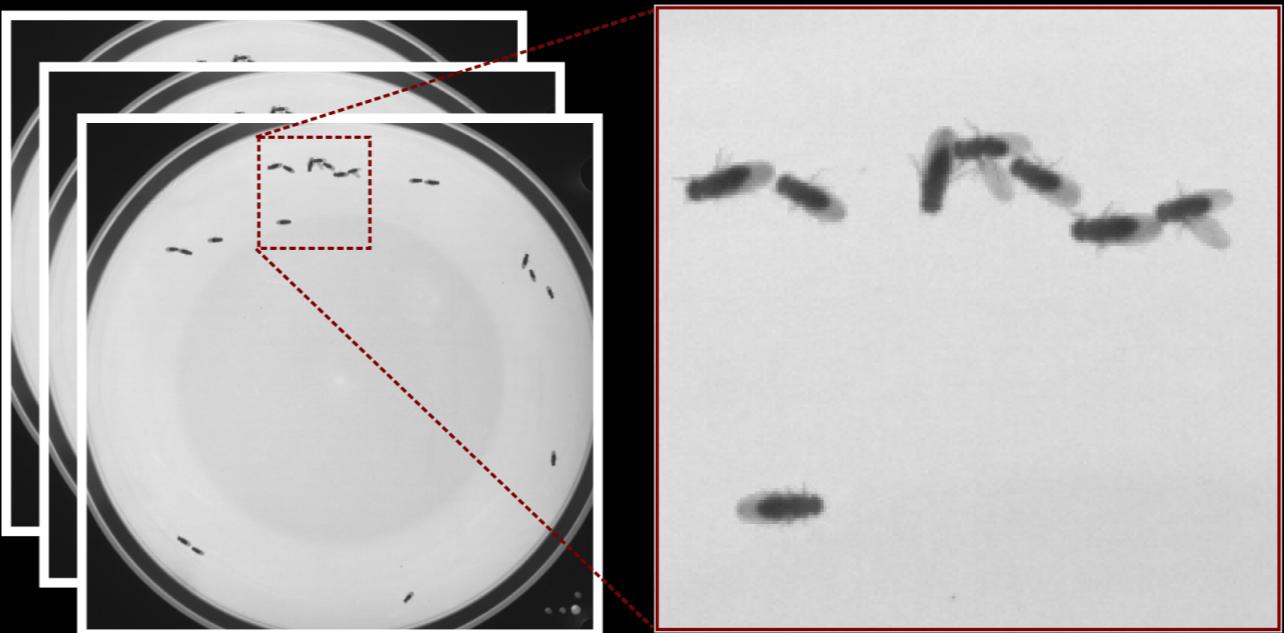
# Artificial Fly Evaluation

Self-driving car



VS

Fruit fly



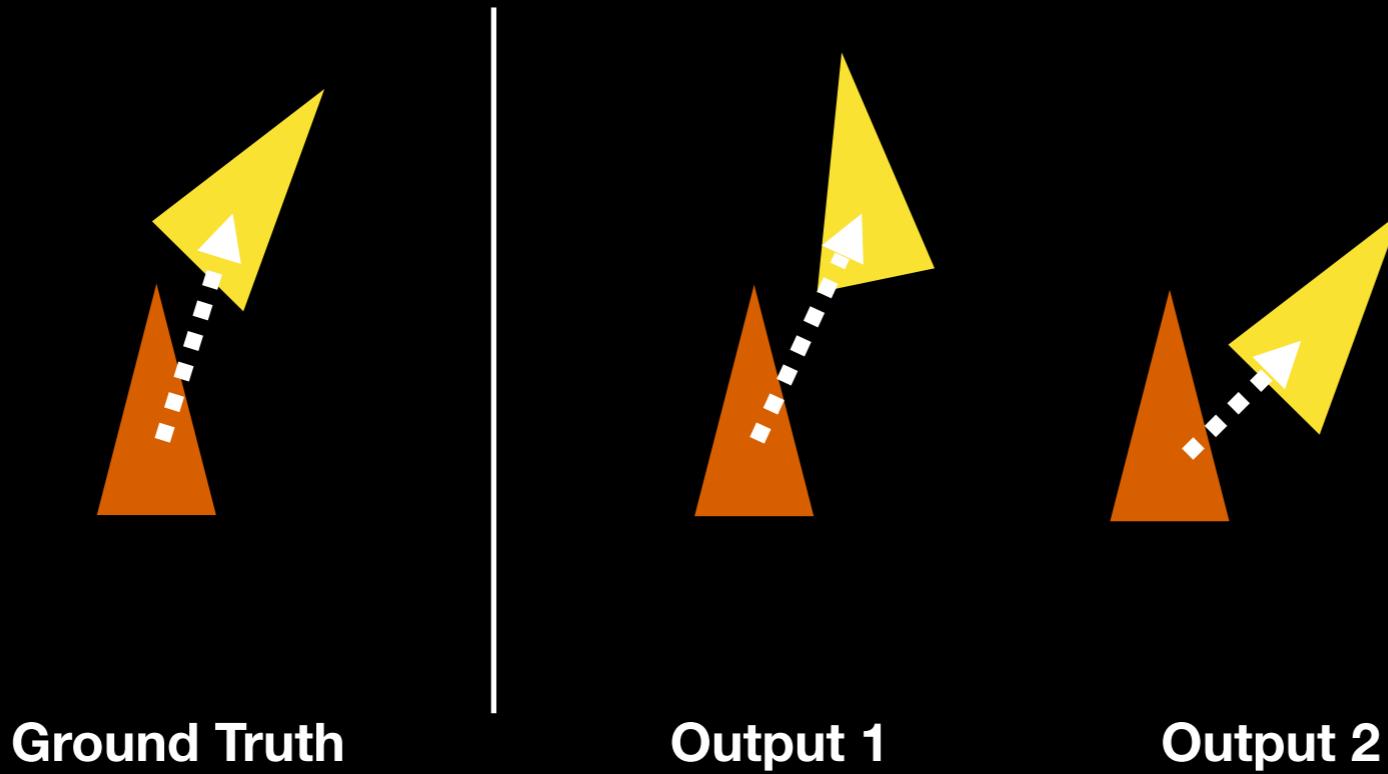
Performance Metrics:

Is it hitting the pedestrians?

What metric is meaningful for predicting behaviour?

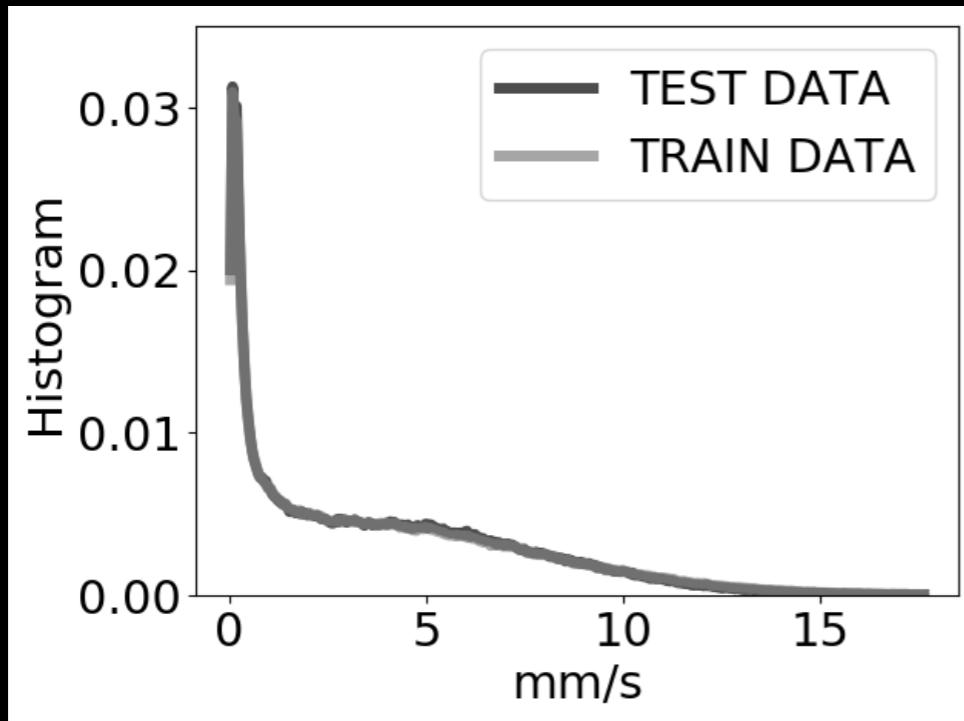
# Artificial Fly Evaluation

What type of difference matters more?

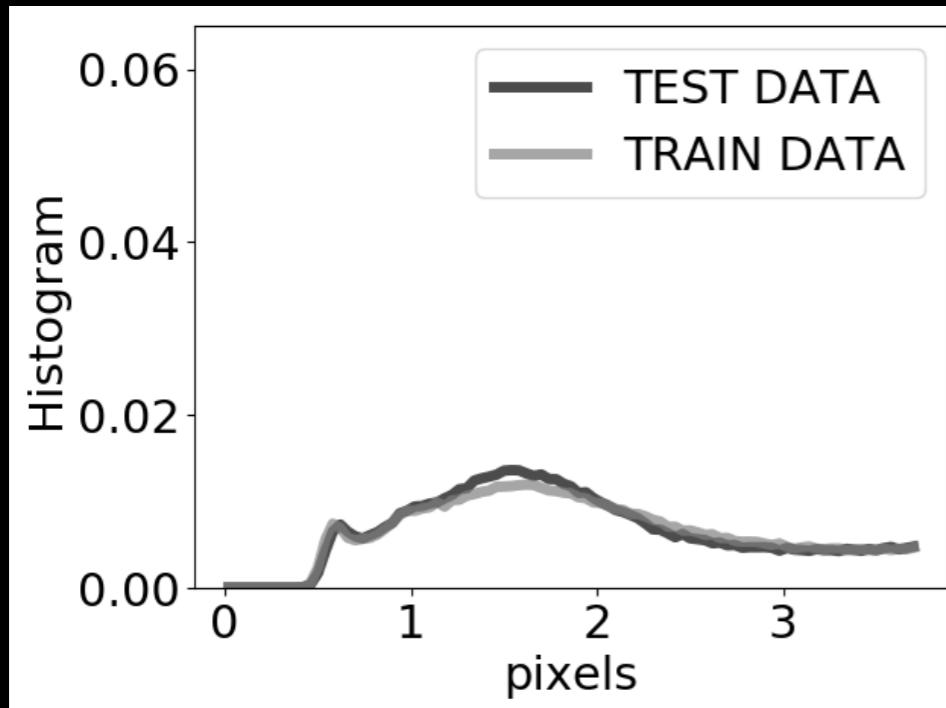


# Evaluation : Distribution Distance

Velocity

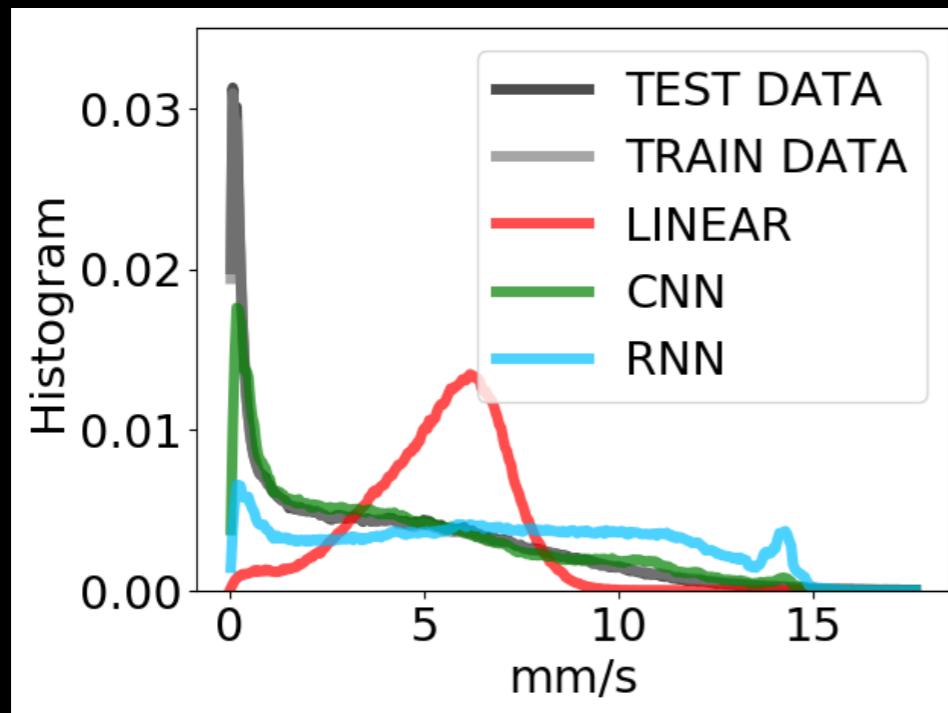


Closest distance between flies

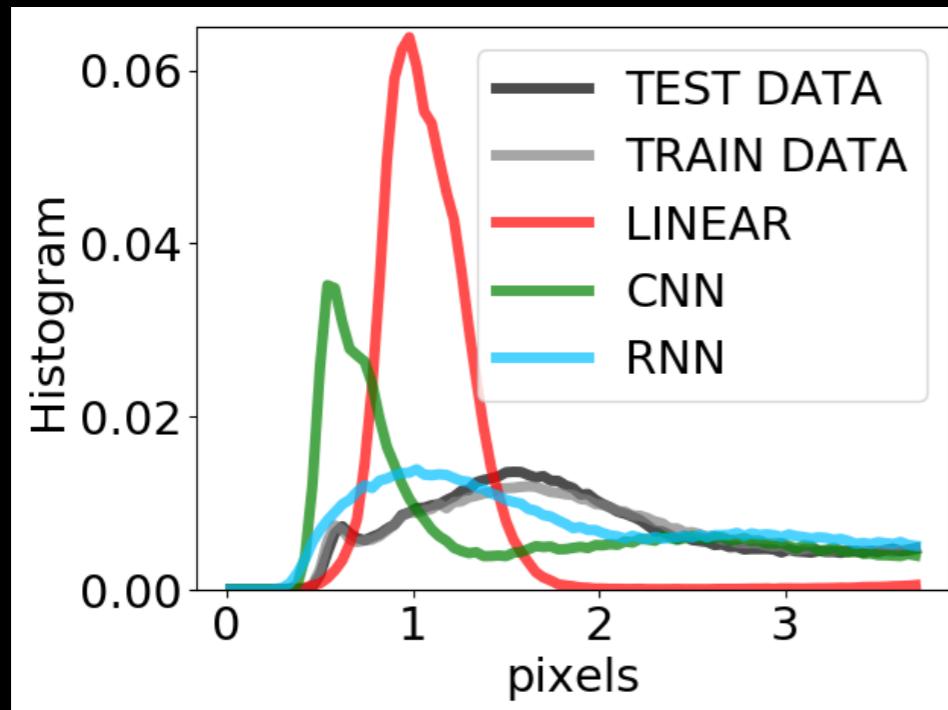


# Evaluation : Distribution Distance

Velocity

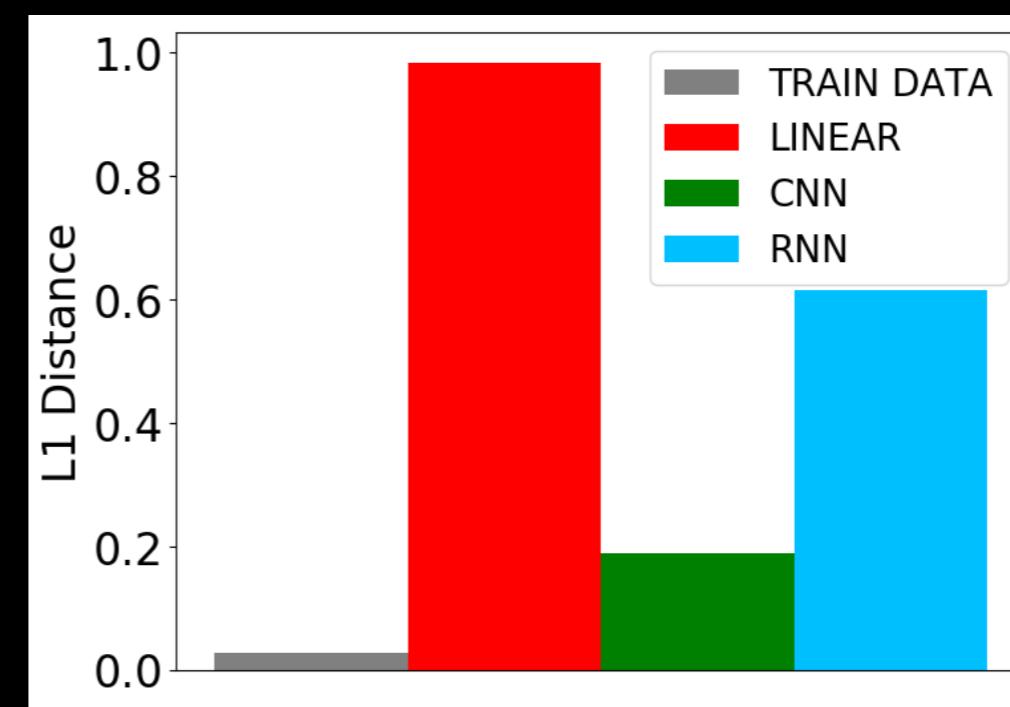
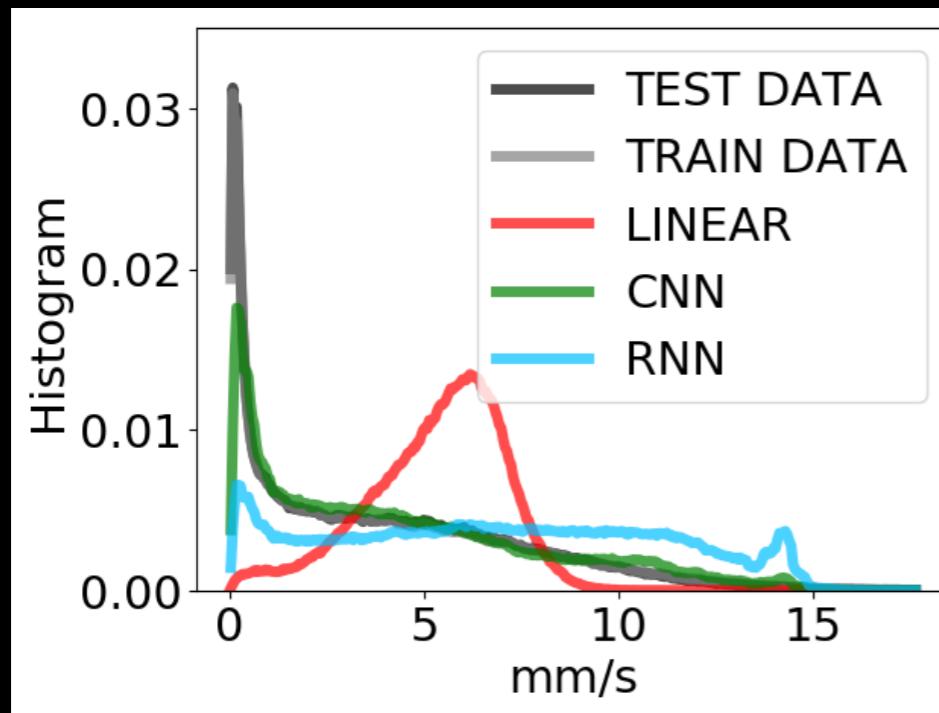


Closest distance between flies



# Evaluation : Distribution Distance

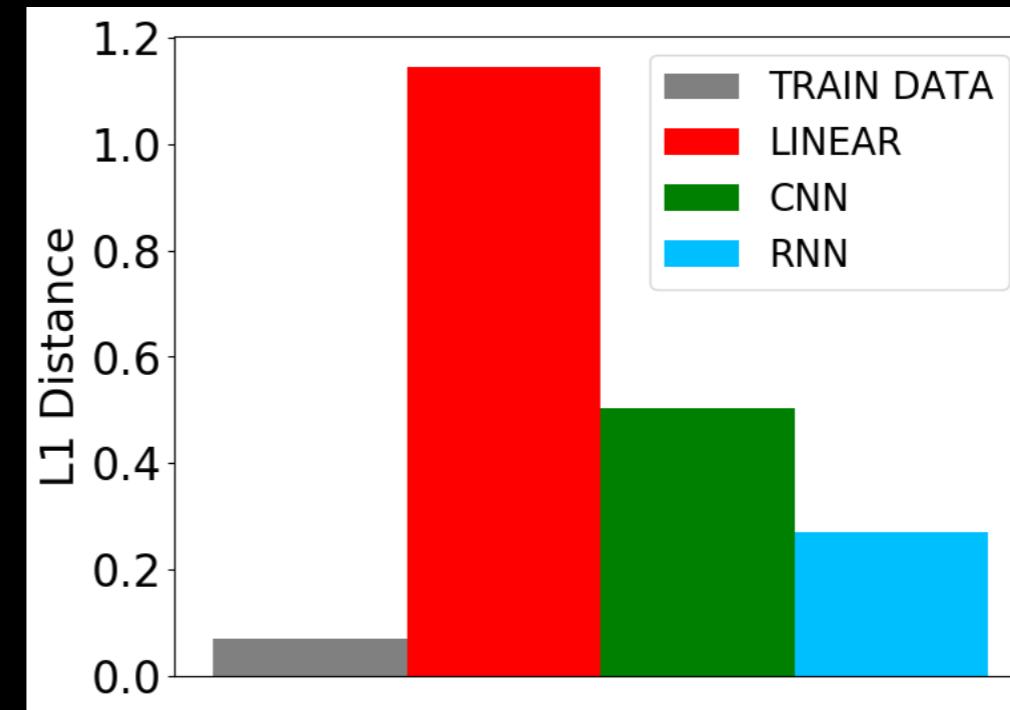
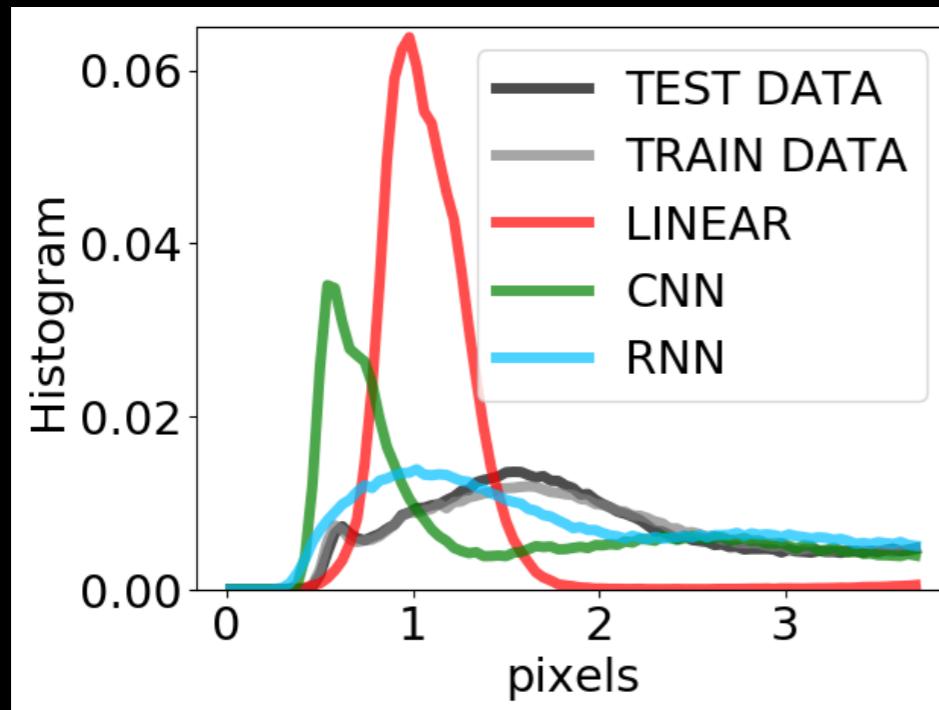
Velocity



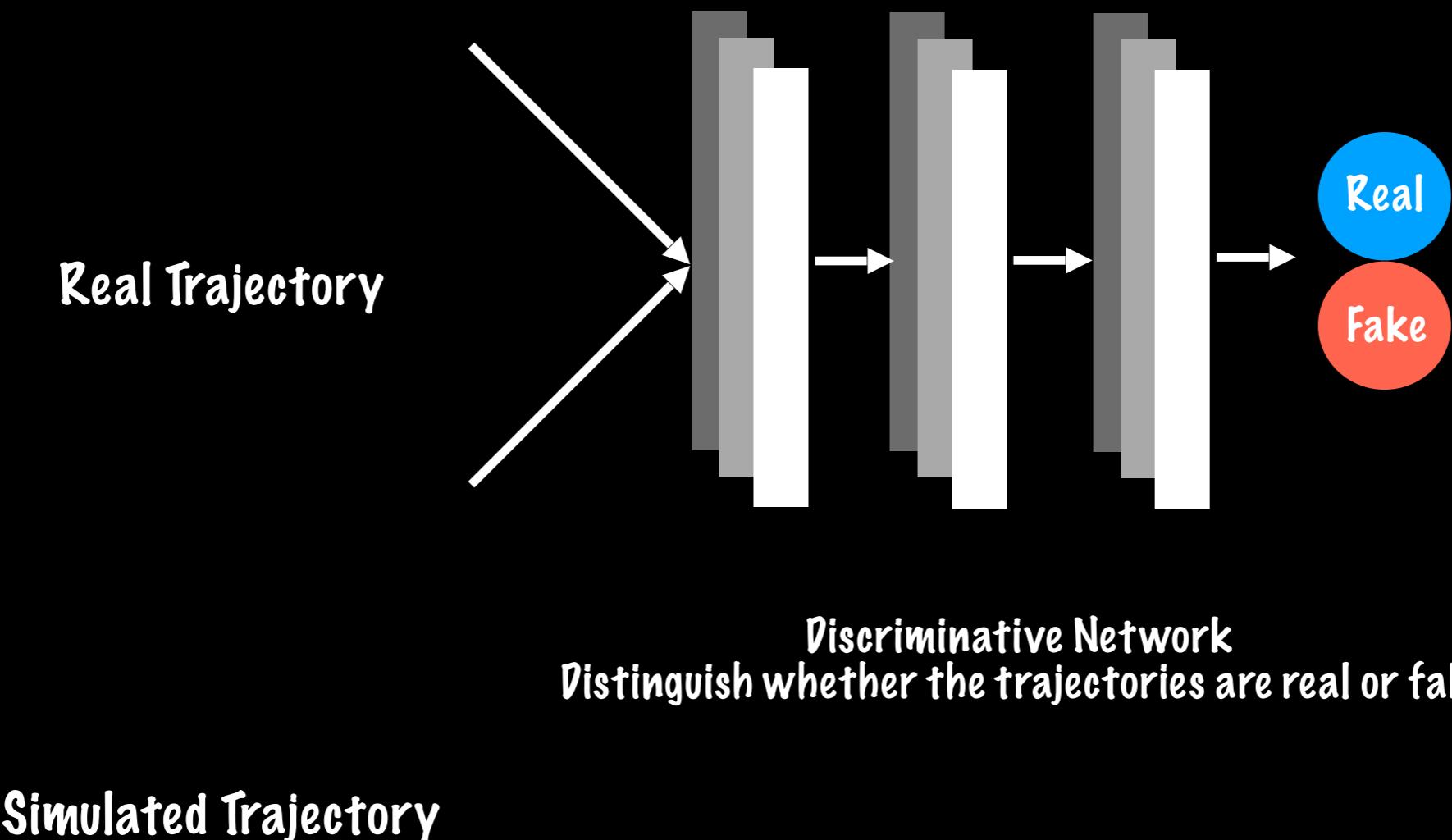
Other Features:

- Distance to wall
- Angular velocities
- Wing angles

Closest distance between flies

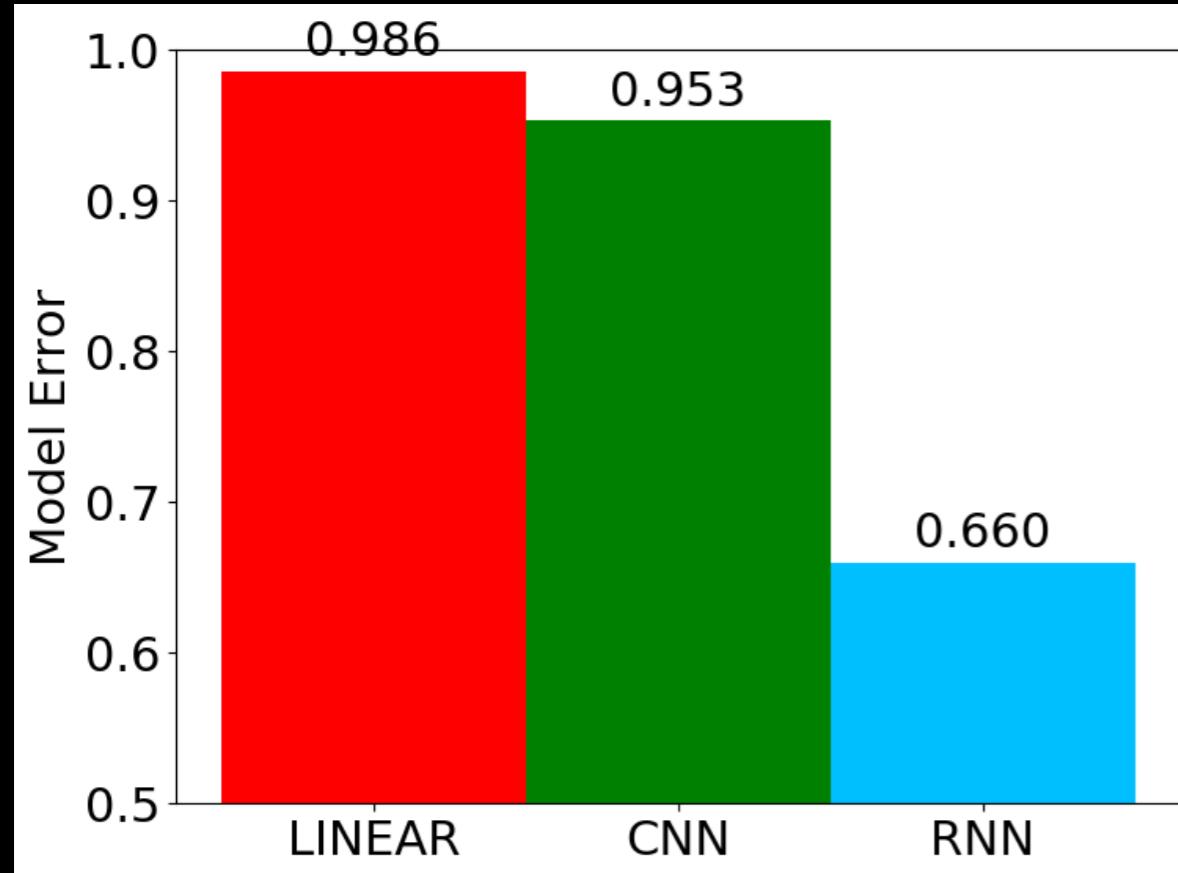


# Evaluation : Real / Fake Discrimination

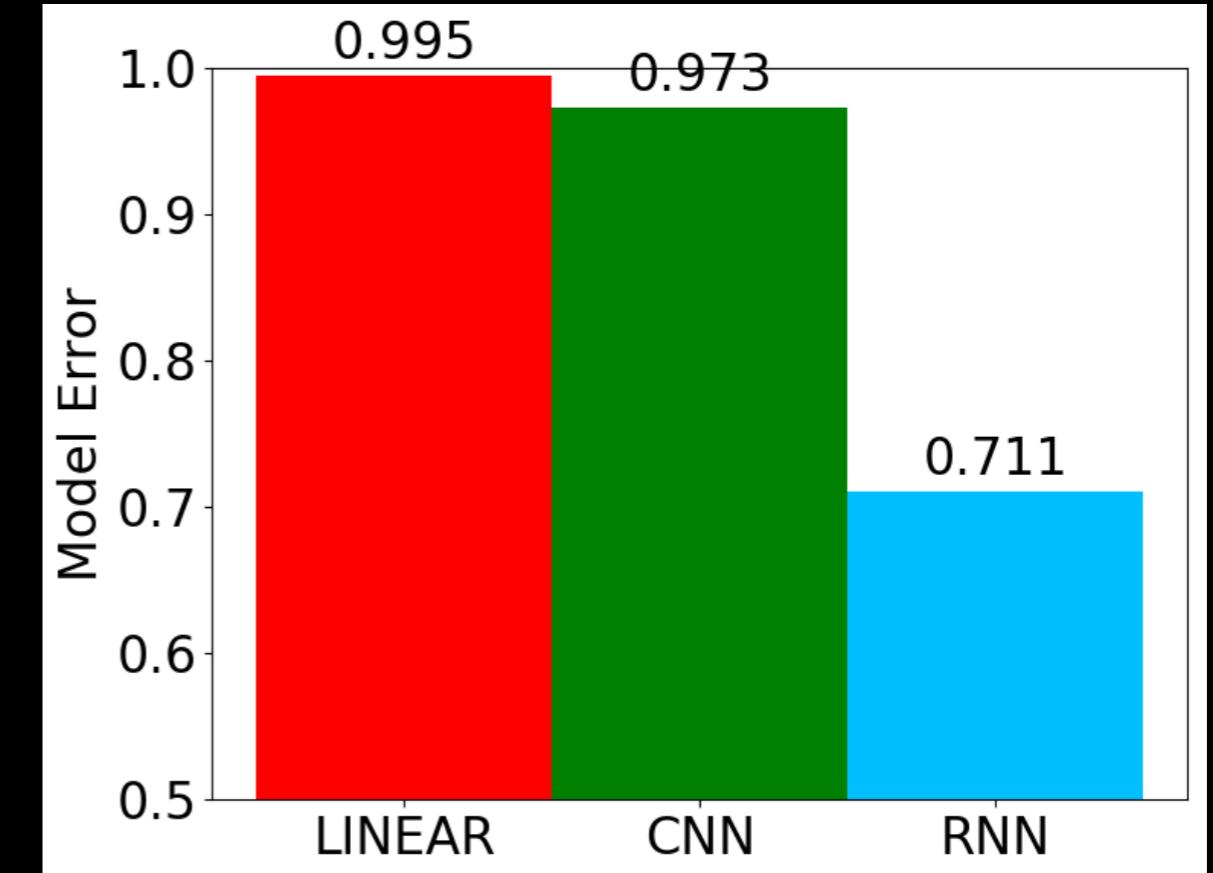


# Evaluation : Real / Fake Discrimination

Male



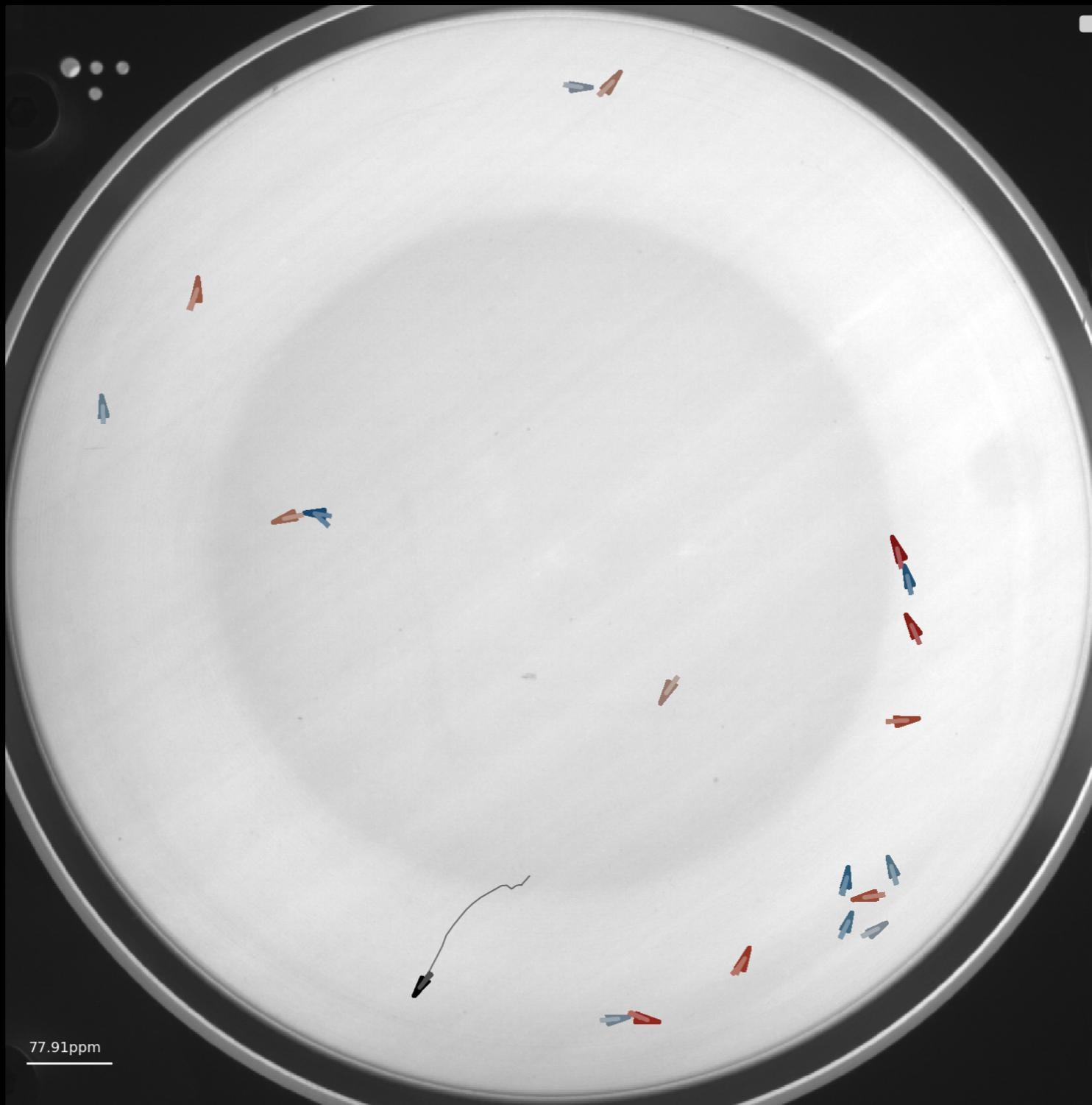
Female



## Our Approach (Outline)

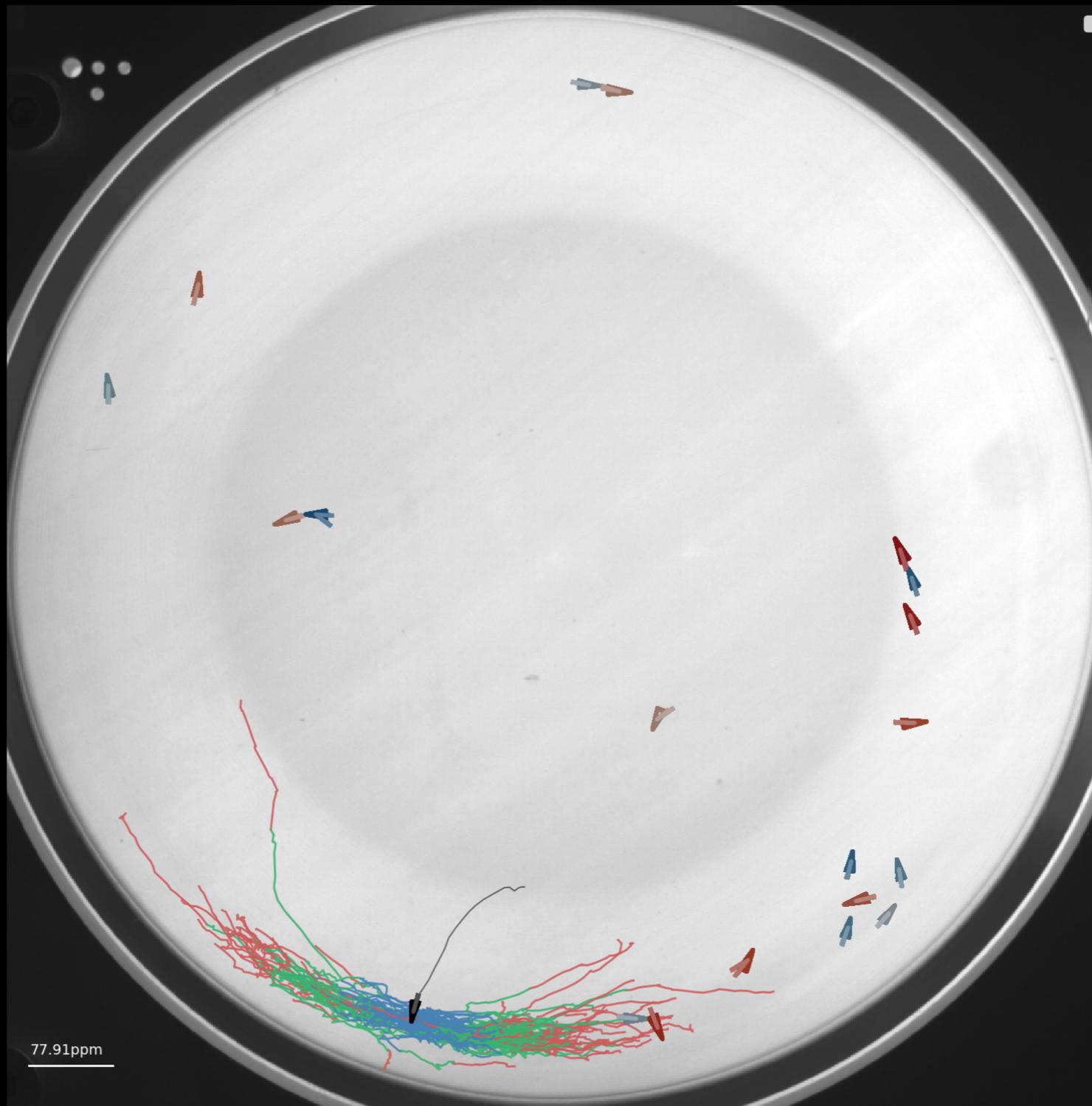
1. Simulate an artificial fly that behaves like a fly.
2. Interpret and understand the behaviour of artificial fly

# Behaviour Analysis: Look at predictions into the future



# Behaviour Analysis: Look at predictions into the future

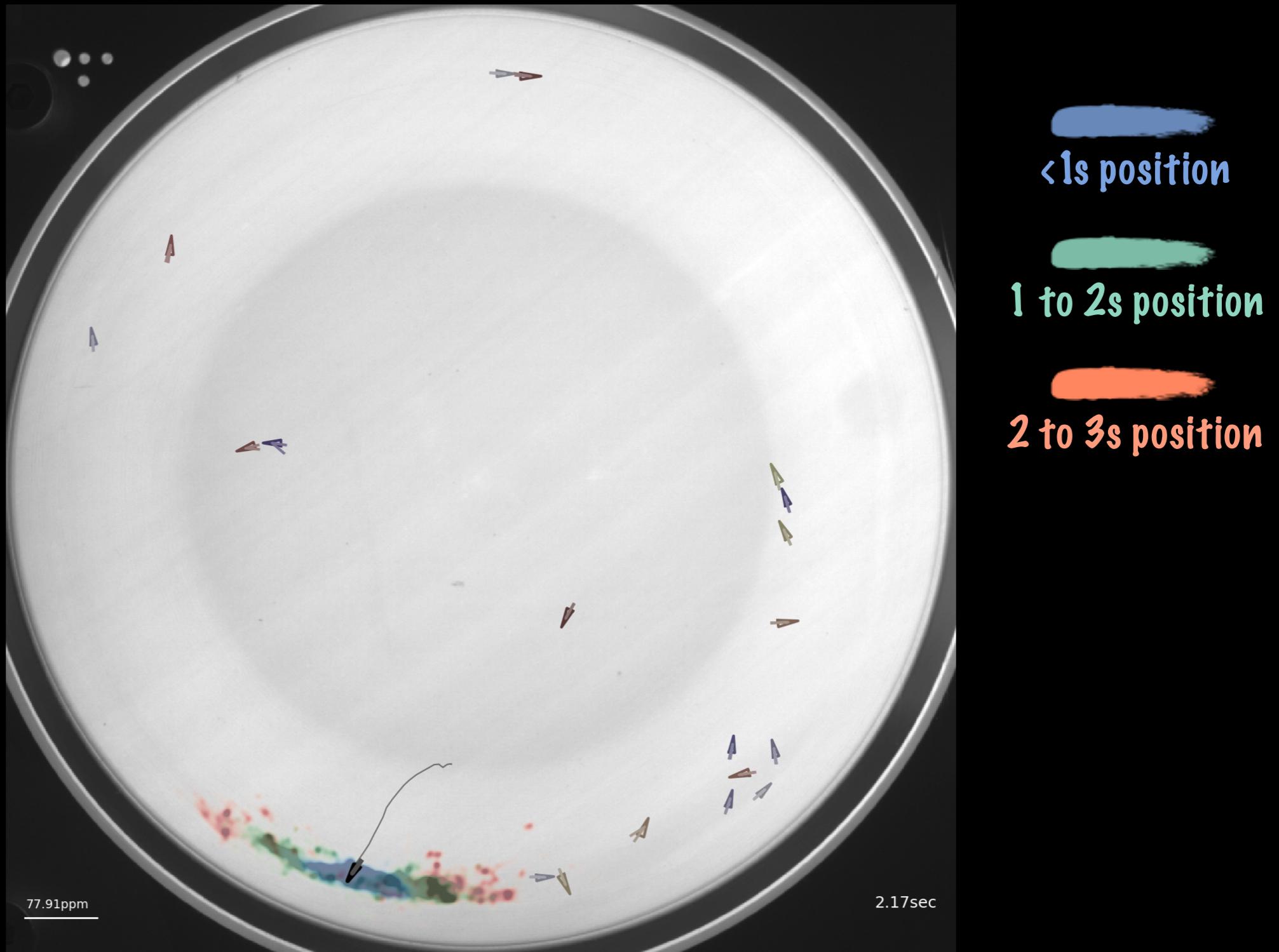
Predicted trajectories of next 3 seconds



- <1s position
- 1 to 2s position
- 2 to 3s position

# Behaviour Analysis: Look at predictions into the future

Histogram over fly trajectories of next 3 seconds



# Behaviour Analysis: Look at predictions into the future

Fly simulation movie

video



< 1s position



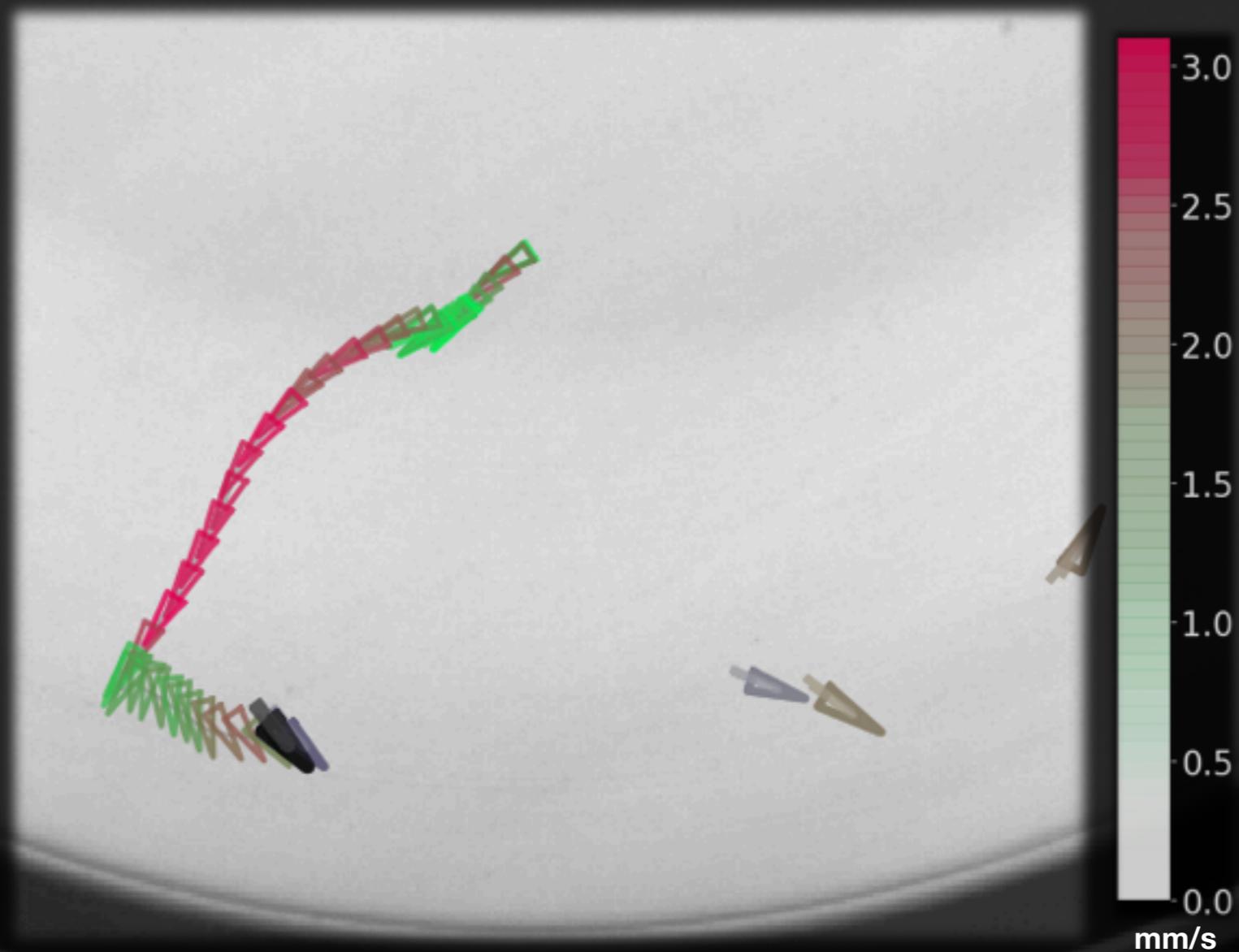
1 to 2s position



2 to 3s position

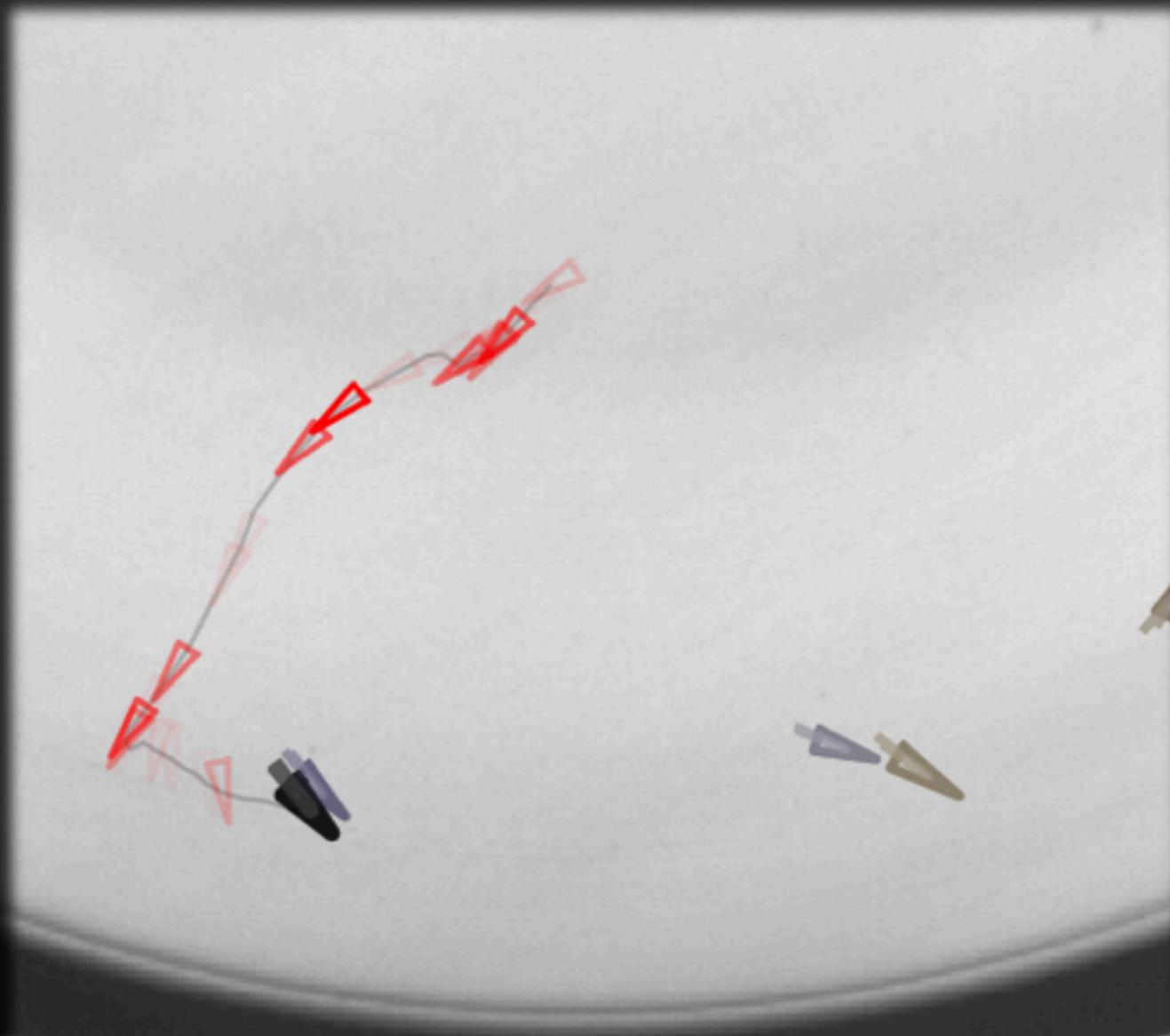
# Behaviour Analysis: influential input

Last 50 frames of forward velocity data



# Behaviour Analysis: influential input

Contributed forward motions among last 50 motions data



# Behaviour Analysis: influential input

Movie of fly simulation with contributed forward motions

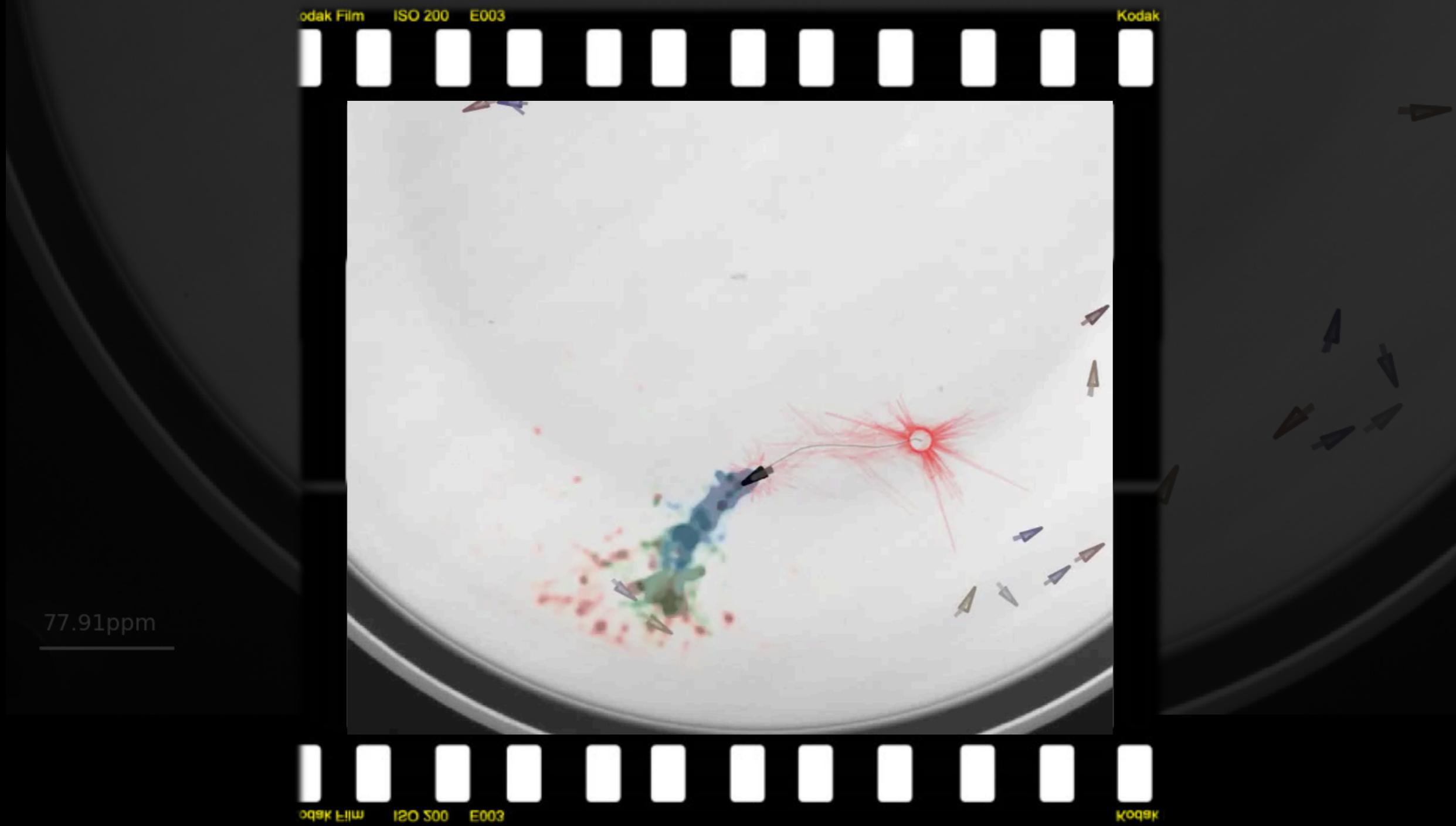


77.91 ppm



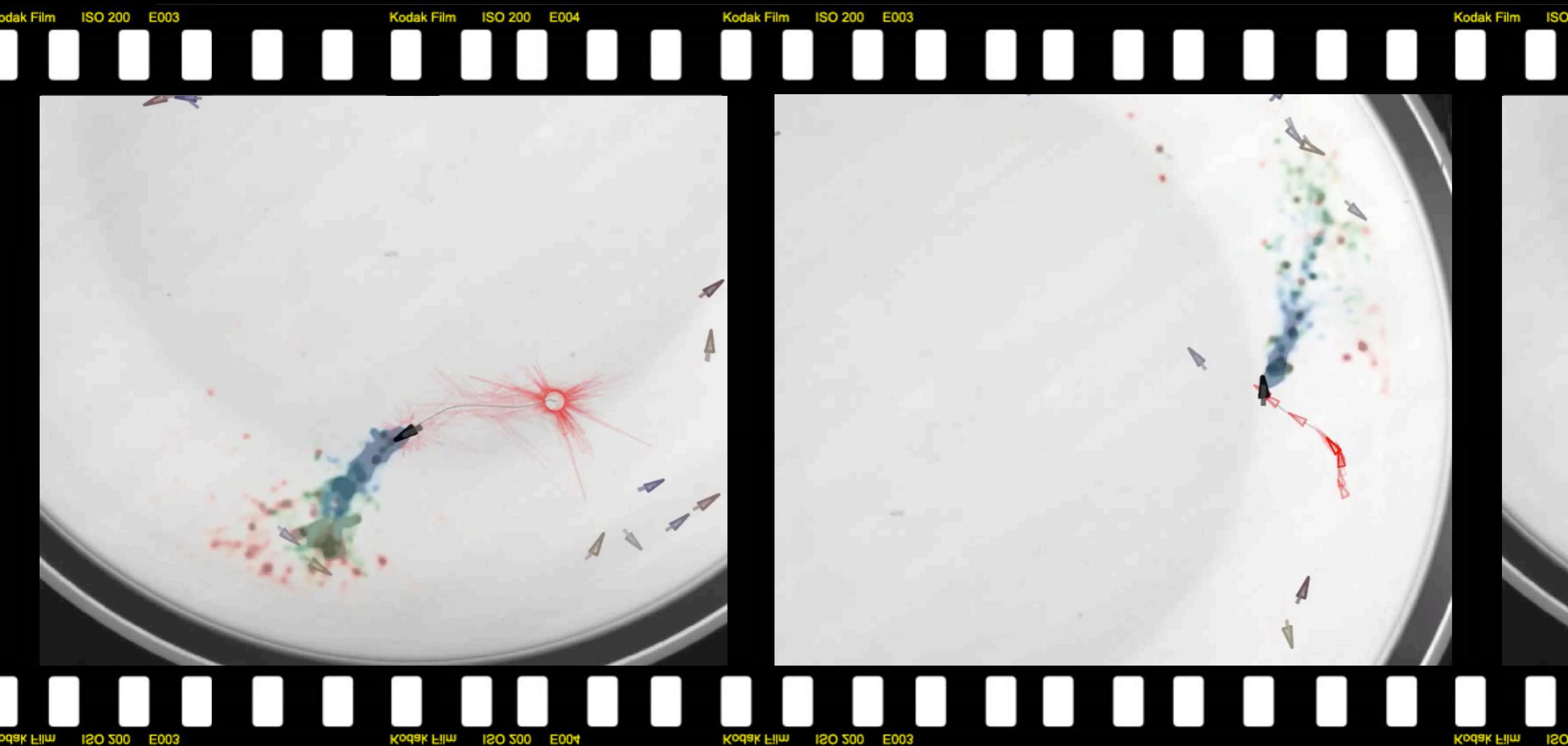
# Behaviour Analysis: influential input

Movie of fly simulation with contributed forward motions



# Behaviour Analysis: Searching for hypothesis

1. Apply the analysis to different situations
2. Look for interesting scenarios
3. Narrow down the set of hypothesis



# Summary

- **Observed** that simulated flies behave like real flies
- **Learned** that RNN produces behaviours that are closer to real flies based on our metrics
- **Introduced** visualization tools that help analyze artificial fly predictions

# Future work

- **Analyze** internal representations of artificial fly to understand the key components
- **Apply** on different genotypes of flies to look for difference in behaviours

# Acknowledgements



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Lee**



**Elizabeth  
Gillette**



**Heejun  
Choi**



**Paola  
Correa**

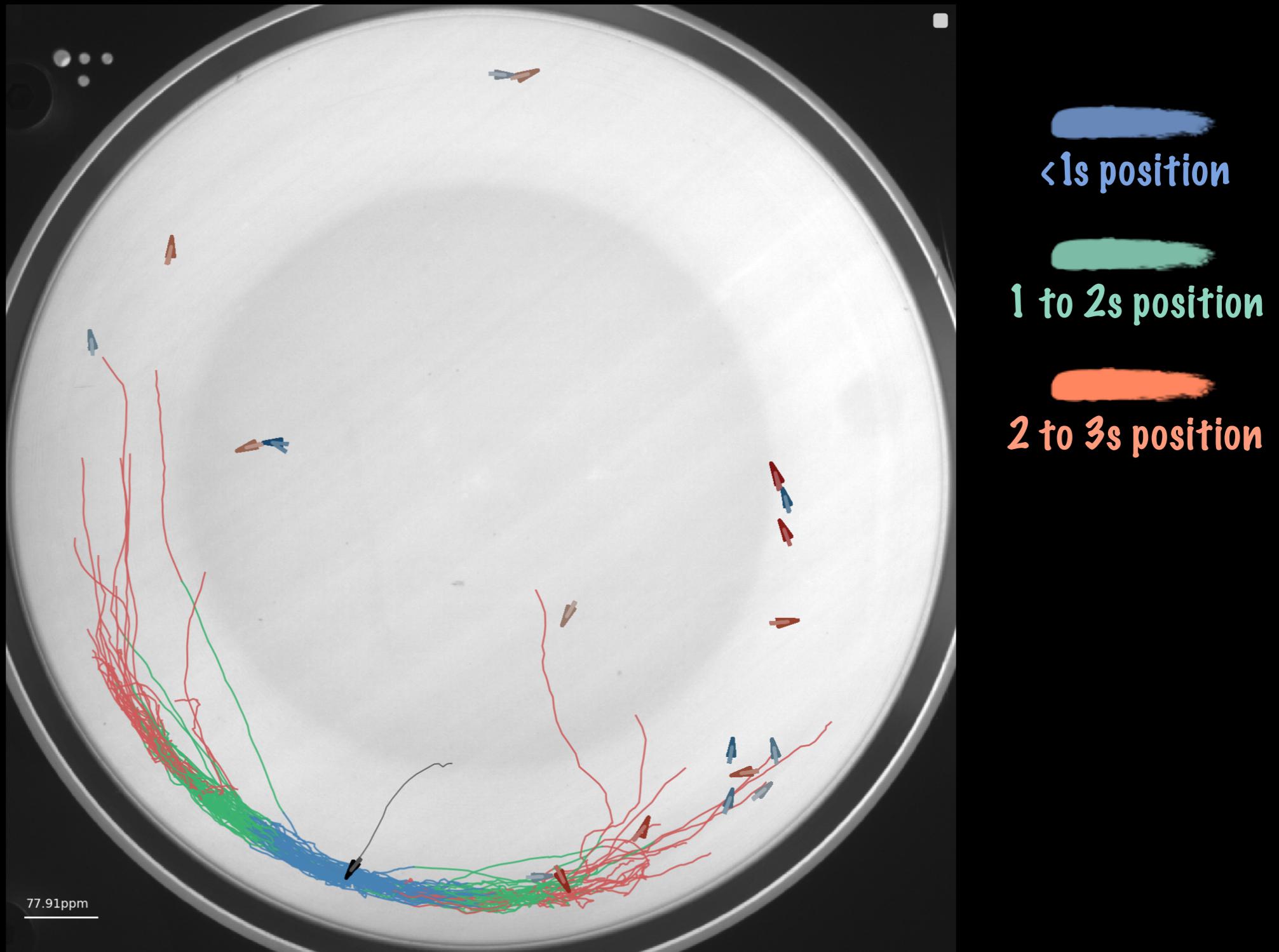


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**Scientific Computing**  
**IT**  
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**Nakul Verma**  
**Rinat Mohar**  
**Natalie Falco**  
**Monet Weldon**  
**Najla Masoodpanah**  
**Andrew Evans**

# Behaviour Analysis: Look at predictions into the future

Predicted trajectories of next 3 seconds

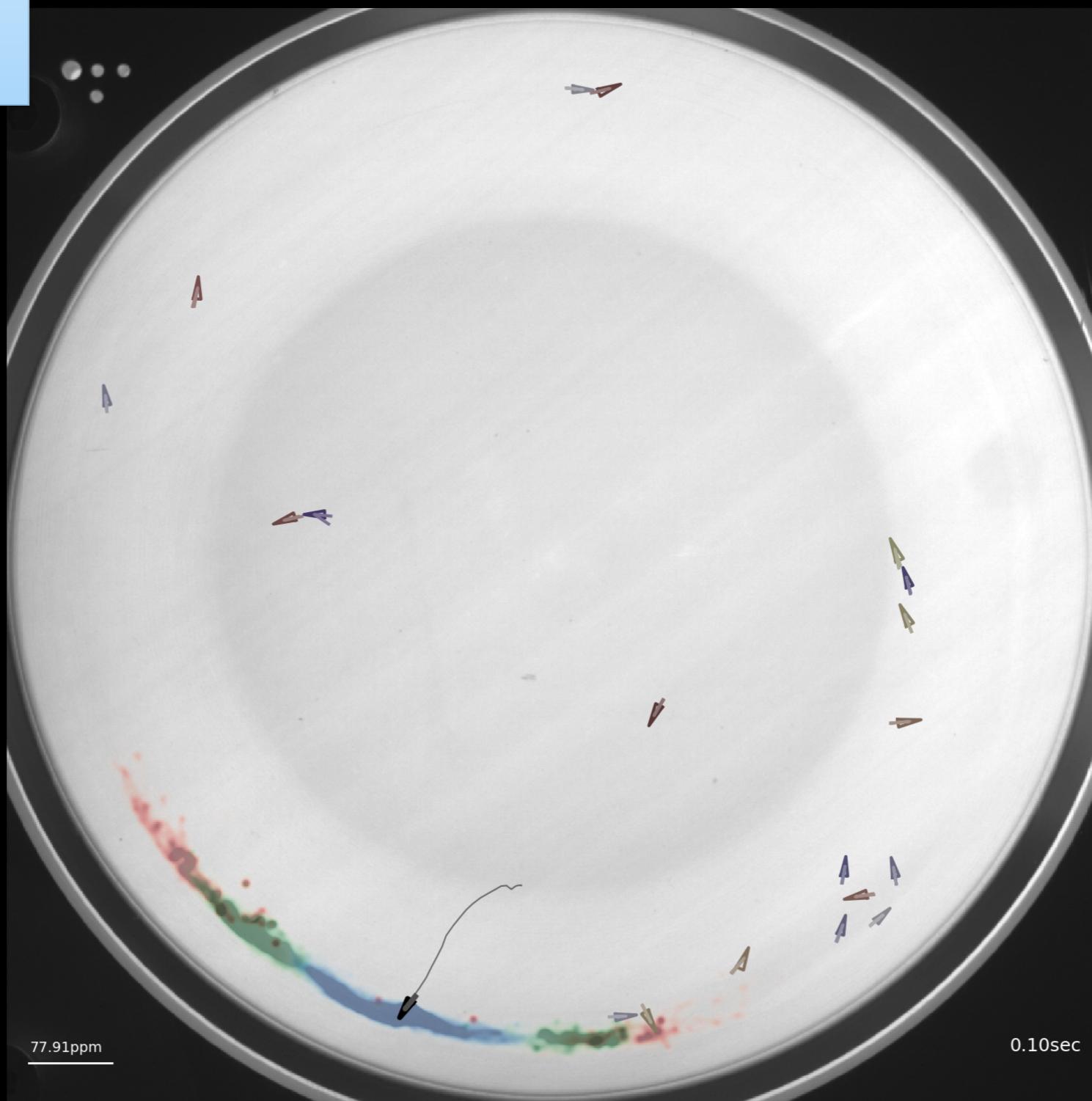


# Behaviour Analysis: Look at predictions into the future

Ref Tie back to real goals.

Identify prediction change dramatically

Histogram over fly trajectories of next 3 seconds



# Behaviour Analysis: Look at predictions into the future

Still frame of lines and then heatmap

Now we show movies of next 3 seconds

Fly simulation movie



< 1s position



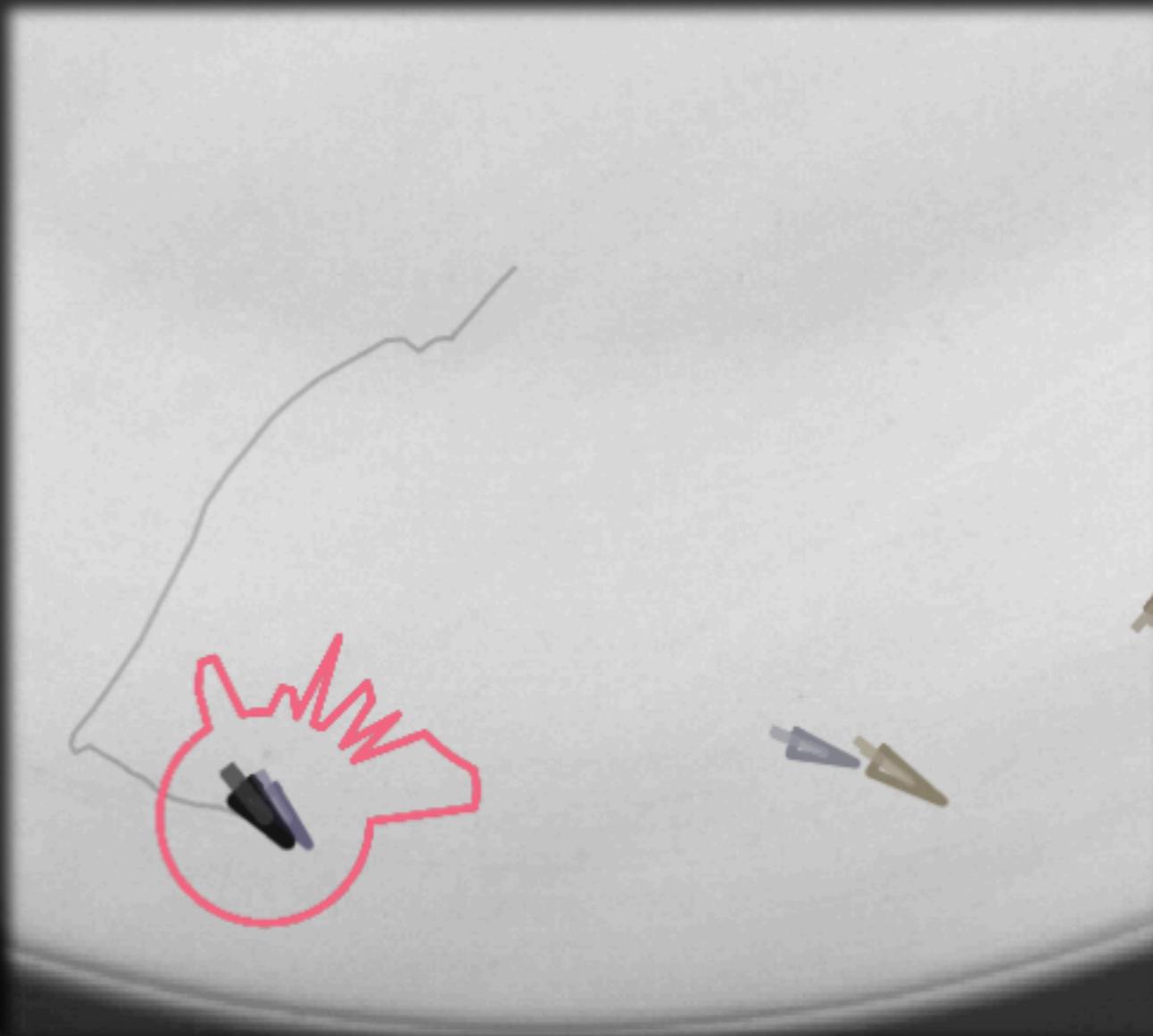
1 to 2s position



2 to 3s position

# Behaviour Analysis: input contribution analysis

Vision features - approximation of what fly sees (pink)



# Behaviour Analysis: input contribution analysis

Last 50 frames of vision features (pink)



# Behaviour Analysis: input contribution analysis

Contributed visions among last 50 vision features

