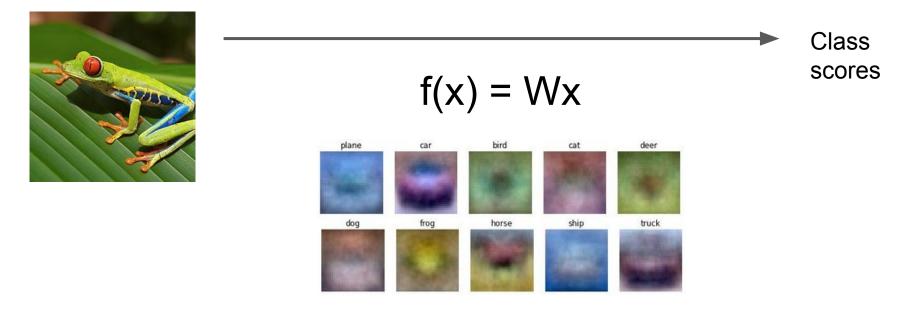
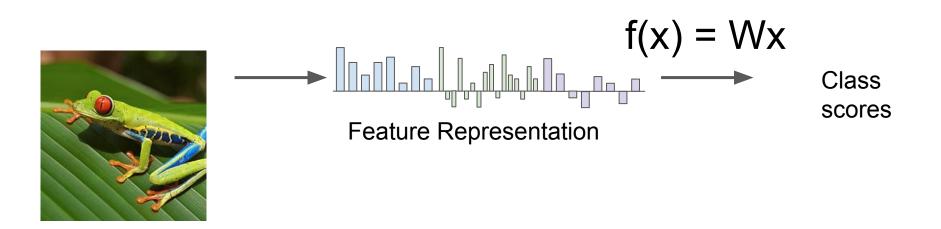
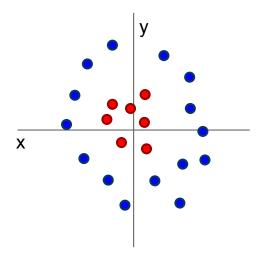
## Aside: Image Features



### Aside: Image Features

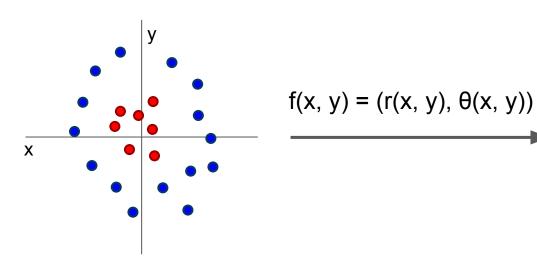


## Image Features: Motivation

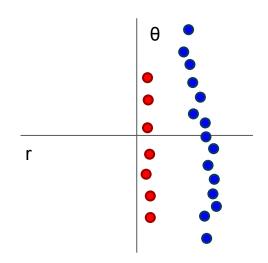


Cannot separate red and blue points with linear classifier

#### Image Features: Motivation

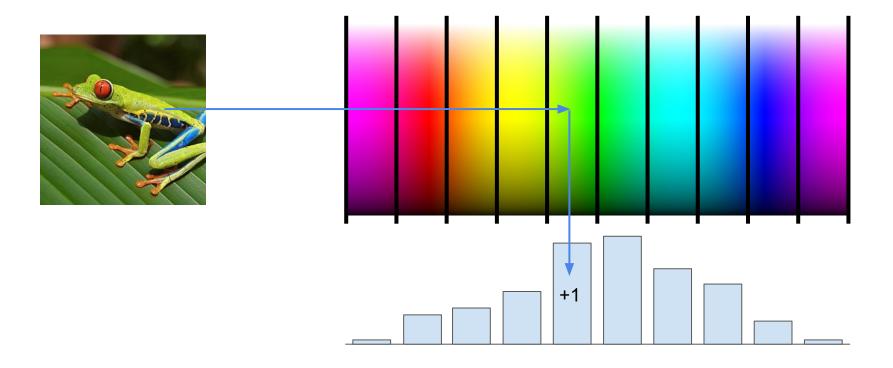


Cannot separate red and blue points with linear classifier

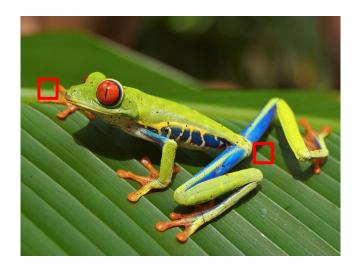


After applying feature transform, points can be separated by linear classifier

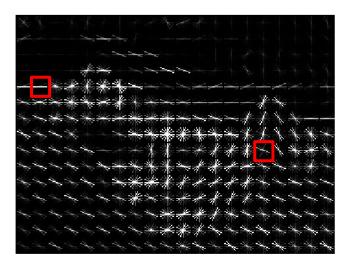
# Example: Color Histogram



### Example: Histogram of Oriented Gradients (HoG)



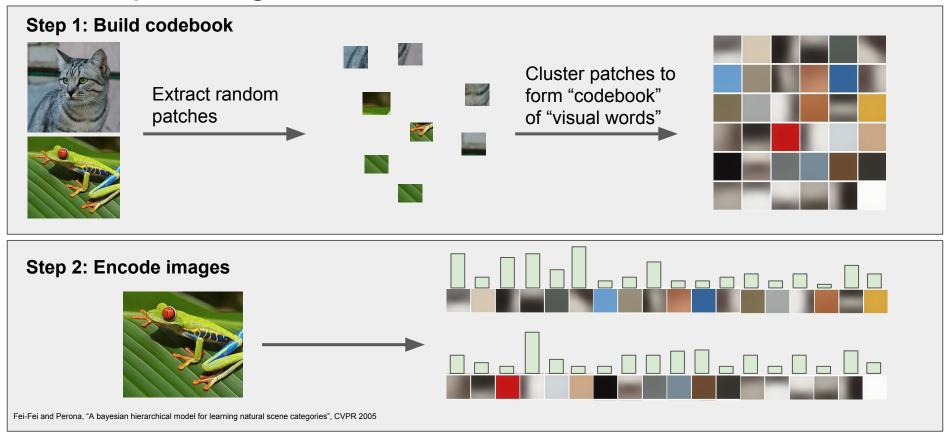
Divide image into 8x8 pixel regions Within each region quantize edge direction into 9 bins



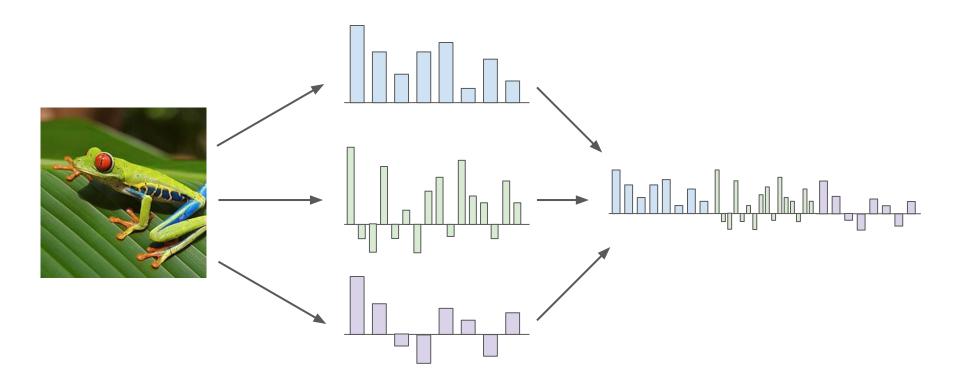
Example: 320x240 image gets divided into 40x30 bins; in each bin there are 9 numbers so feature vector has 30\*40\*9 = 10.800 numbers

Lowe, "Object recognition from local scale-invariant features", ICCV 1999
Dalal and Triggs, "Histograms of oriented gradients for human detection," CVPR 2005

### Example: Bag of Words



### Aside: Image Features



## Image features vs ConvNets

