Mitigating Bias in Computer Vision

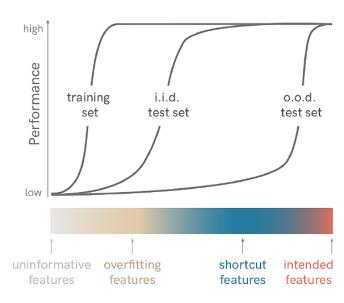
Ji-Ze G. Jang

Note: this presentation outlines the AI fairness project **ideas** I proposed, **motivations** of my work, and experimental **designs**. Due to time and resource constraints, this project was left open-ended before I transitioned to the University of Maryland Vision and Learning Lab.



Al Fairness / Bias

- How can we bypass shortcut features and ensure that the relevant statistics are learned from a computer vision model?
- How can we reduce or even eliminate the network's reliance on spurious correlations in the data to achieve high accuracy?
 - correlation ≠ causation !!

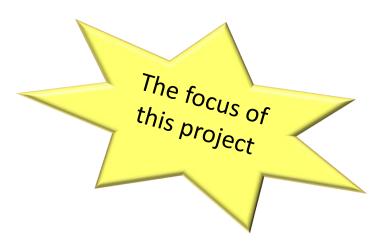


Types of Bias Mitigation Methods

- Pre-processing: debias the training data
- In-processing: debias the model architecture / objective function
 - E.g., Resampling and Reweighting
 - E.g., Adversarial training (fairness through blindness)
 - E.g., Domain discriminative training (fairness through awareness)
- Post-processing: debias the prediction

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Label Noise Detection and Bias Mitigation in Supervised NNs

Fall 2021

Problem Statement

- Protected attributes in a dataset may lead to fairness or robustness problems
 - They are often associated with social bias (e.g., race, gender, age)
- **Goal**: to predict an output variable Y given an input variable X, while remaining unbiased with respect to the protected variable A
- However, existing bias identification and mitigation methods overly rely on labels of protected attributes

Problem Statement

• Existing bias identification and mitigation methods *overly rely on labels* of protected attributes

• But what happens if the *labels* themselves are *biased*?

<u>Step 1</u>:

Detect label error (if they exist at all) in various existing bias mitigation methods

<u>Step 2</u>:

Devise a novel method to debias the neural network

Preliminary idea: reduce reliance on labels using few-shot learning?

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Bias mitigation method

 \times

Type of noise with which to flip the labels

Bias Mitigation Methods

1. Domain-independent training [1]

- Independently train an object classification model on each of two domains
- At test time, apply *prior shift* to adjust output probabilities toward a uniform distribution

2. Group DRO with increased regularization [2]

- ullet Train with strong regularization methods, including strong l_2 penalty and early stopping
- Compute worst-case accuracy for pre-defined groups

3. Invariant Risk Minimization (IRM) [3]

Obtain a data representation such that the optimal classifier is invariant (i.e., the same for all training environments)

^[1] Wang et al. Towards Fairness in Visual Recognition: Effective Strategies for Bias Mitigation. In CVPR, 2020.

^[2] Sagawa et al. Distributionally Robust Neural Networks for Group Shifts: On the Importance of Regularization for Worst-case Generalization. In ICLR, 2020.

^[3] Arjovsky et al. Invariant Risk Minimization. arXiv:1907.02893, 2020.

Types of Noise and Noise Levels

- 1. No noise
- 2. Flip label with *random* probability $p \in \{0.001, 0.01, 0.02, 0.05\}$
- 3. Flip label with probability that is *correlated* with the target attribute

Adding / Amplifying Noise in the Dataset

 Goal: amplify bias in the dataset and assess how well the bias mitigation methods perform

```
Algorithm 1 Noise Injection
 1: Let A and B be two distinct attributes in a labeled dataset.
 2: Hyperparameter: noise level p
 3: for each label in A do
      if A = 1 and B = 1 then
         flip the label of B with P(B=0|A=1) < p
      else if A = 1 and B = 0 then
         flip the label of B with P(B=1|A=1) > p
      else if A = 0 and B = 1 then
         flip the label of B with P(B=0|A=0) > p
      else if A=0 and B=0 then
10:
         flip the label of B with P(B=1|A=0) < p
11:
      end if
13: end for
```

where A is the protected attribute, B is the target attribute, and p is the probability with which to flip the binary label

<u>Step 1</u>:

Detect label error (if they exist at all) in various existing bias mitigation methods

Bias mitigation method

Type of noise with which to flip the labels

Ablation studies

Conditions for Ablation Studies

1. Domain-independent training [1]

Dataset: CelebA

Metrics: directional bias amplification, KL, DEO, accuracy

2. Group DRO with *increased regularization* [2]

Dataset: Waterbirds

Metric: worst group accuracy

3. Invariant Risk Minimization (IRM) [3]

Dataset: Color MNIST

Metric: classification accuracy

× 52 runs
for
3 noise types
4 noise levels

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Results for Group DRO trained on Waterbirds

- The lines indicate average worst-group accuracies across 52 trials for each unique (noise type, noise level) condition
- The largely overlapping error bars indicate 1 standard deviation from the mean

Worst Group Accuracy Showing first 20 runs - noise_type: Random, noise_level: 0.3 - noise_type: Random, noise_level: 0.2 - noise_type: Random, noise_level: 0.3 - noise_type: Random, noise_level: 0.05 - noise_type: Correlated, noise_level: 0.2 - noise_type: Correlated, noise_level: 0.1 - noise_type: Correlated, noise_level: 0.05 - noise_type: None, noise_level: 0.1 - noise_type: Correlated, noise_level: 0.05 - noise_type: None, noise_level: 0.1 - noise_type: Correlated, noise_level: 0.05 - noise_type: None, noise_level: 0.1 - noise_type: Correlated, noise_level: 0.05 - noise_type: None, noise_level: 0.1 - noise_type: Correlated, noise_level: 0.05 - noise_type: None, noise_level: 0.1 - noise_type: Correlated, noise_level: 0.05 - noise_type: None, noise_level: 0.1 - noise_type: Correlated, noise_level: 0.05 - noise_type: None, noise_level: 0.1 - noise_type: Correlated, noise_level: 0.05 - noise_type: None, noise_level: 0.1 - noise_type: Correlated, noise_level: 0.05 - noise_type: None, noise_level: 0.1 - noise_type: Correlated, noise_level: 0.05 - noise_type: None, noise_level: 0.1 - noise_type: Correlated, noise_level: 0.05 - noise_type: None, noise_level: 0.1 - noise_type: Correlated, noise_level: 0.05 - noise_type: None, noise_level: 0.1 - noise_type: Correlated, noise_level: 0.05 - noise_type: None, noise_type: Correlated, noise_typ

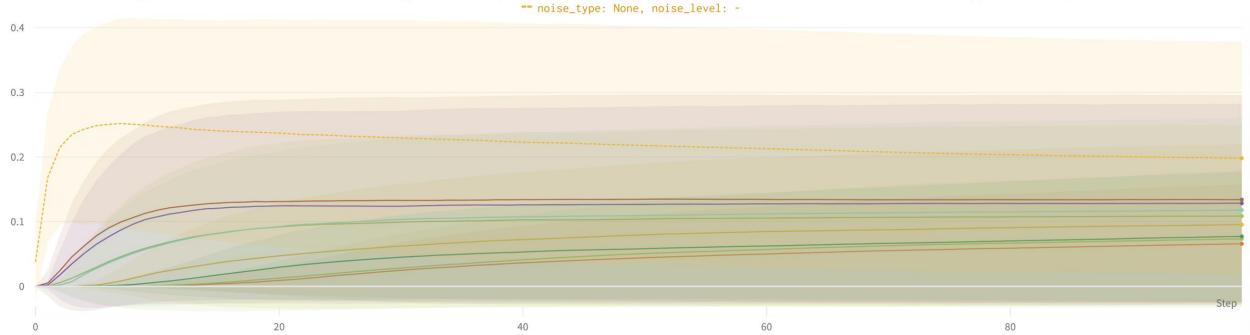


Results for Group DRO trained on Waterbirds

 Overall, the experimental results show no significant difference between the baseline (no noise), random noise, and correlation conditions

Showing first 20 runs — noise_type: Random, noise_level: 0.3 — noise_type: Random, noise_level: 0.2 — noise_type: Random, noise_level: 0.1 — noise_type: Correlated, noise_level: 0.3 — noise_type: Random, noise_level: 0.05 — noise_type: Correlated, noise_level: 0.1 — noise_type: Correlated, noise_level: 0.05 — noise_type: None, noise_level: -

Worst Group Accuracy



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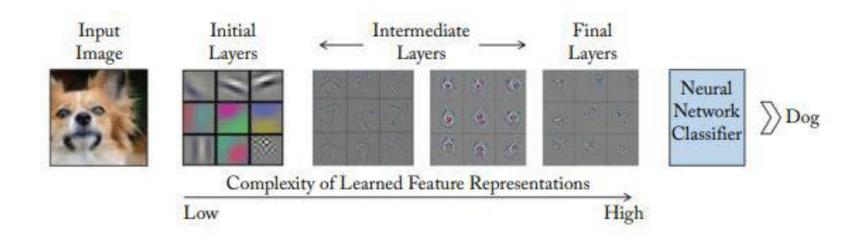
Not applicable, since no significant label error was detected in existing bias mitigation methods

Texture Bias in Generative NNs

Spring 2022

How CNNs "See" an Image

> CNNs combine low-level features (e.g., edges) to form increasingly complex shapes until an object can be classified by the network



How CNNs "See" an Image

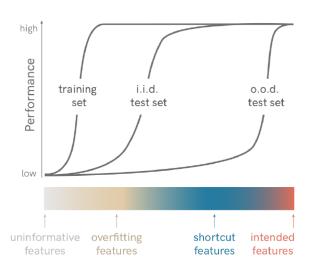
- ➤ CNNs are currently the most predictive models for human object recognition (Cadieu et al., 2014)
- However, several findings found that CNNs can classify objects solely based on texture (local) information!

How CNNs "See" an Image

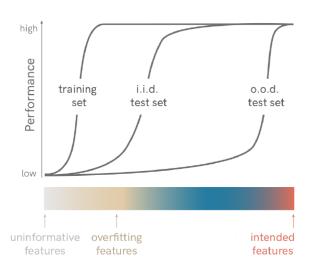
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"Texture bias"

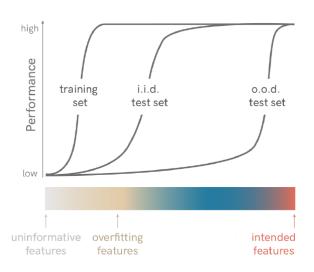
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- Learned representations are not based on intended features
- May suggest an *inductive bias* in CNNs that is different from that of humans



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 - Problematic for CNNs to generalize to O.O.D. data



- Learned representations are not based on intended features
- May suggest an inductive bias in CNNs that is different from that of humans
 - o Problematic for CNNs to generalize to O.O.D. data
 - Difficult for models to learn human-relevant vision tasks in small-data regimes

Previous Research Directions

- Direction 1:
 - Understanding texture bias in CNNs via comparison with behavioral data
- Direction 2:
 - Debiasing CNNs using shape + texture information
- Direction 3:
 - Texture bias in ViTs

Original Plan for Research Project

- **Motivation**: *semantic image synthesis* networks (e.g., SPADE) may contain texture bias, synthesizing outputs with high-quality "stuff" but poor-quality objects
- **Hypothesis**: stuff classes have simpler textures than complex objects, which allows them to be synthesized more easily with higher quality

• Steps:

- 1. Detect texture bias (if any) in semantic image synthesis networks
- 2. Devise a novel method to debias image synthesis (generative) networks

Progress paused...

... due to time and resource constraints at the University of Rochester