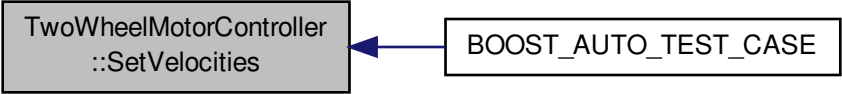


TwoWheelMotorController
::SetVelocities



```
graph LR; A[BOOST_AUTO_TEST_CASE] --> B[TwoWheelMotorController::SetVelocities]
```

The diagram consists of two rectangular boxes. The box on the left is light gray with a black border and contains the text 'TwoWheelMotorController' on the top line and '::SetVelocities' on the bottom line. The box on the right is white with a black border and contains the text 'BOOST_AUTO_TEST_CASE'. A dark blue arrow points from the right side of the white box to the left side of the gray box.

BOOST_AUTO_TEST_CASE