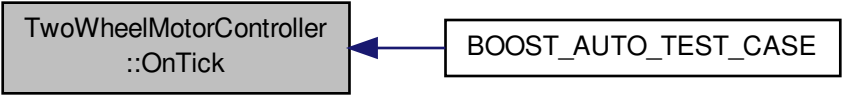


TwoWheelMotorController
::OnTick



```
graph LR; A[BOOST_AUTO_TEST_CASE] --> B[TwoWheelMotorController::OnTick];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The box on the left is light gray with a black border and contains the text 'TwoWheelMotorController' on the top line and '::OnTick' on the bottom line. The box on the right is white with a black border and contains the text 'BOOST_AUTO_TEST_CASE'. A blue arrow points from the right side of the white box to the left side of the gray box.

BOOST_AUTO_TEST_CASE