中山大学计算机学院2023 年春季超级计算原理与实践 MPI 编程作业本科生实验报告

课程名称: 超级计算机原理与操作

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一、实验题目

Pthread编程

二、实验内容

1.欧拉公式

并非所有和π有关的研究都旨在提高计算它的准确度。1735年,欧拉解决了巴塞尔问题,建立了所有平方数的倒数ηπ的关系:

\$\$ П/6=\sum_{i=1}^{∞} 1/i^2 \$\$ 请使用pthread中的semaphore计算的值。

可以参考课件中的方法,在参考代码中提供了运行所需的主函数,也提供了串行代码供同学们参考;请同学们将并行的代码补充完整,需要补充的部分见注释PLEASE ADD THE RIGHTCODES部分。实验报告中请展示相应的运算结果,并分析加速比随n变化的关系。

2。生产者消费者问题

有一个生产者在生产产品,这些产品将提供给若干个消费者去消费,为了使生产者和消费者能并发执行,在两者之间设置一个有多个缓冲区的缓冲池,生产者将它生产的产品放入一个缓冲区中,消费者可以从缓冲区中取走产品进行消费,所有生产者和消费者都是异步方式运行的,但它们必须保持同步,即不允许消费者到一个空的缓冲区中取产品,也不允许生产者向一个已经装满产品且尚未被取走的缓冲区中投放产品。在本题中,我们只考虑一个生产者一个消费者的情况,具体流程如图:

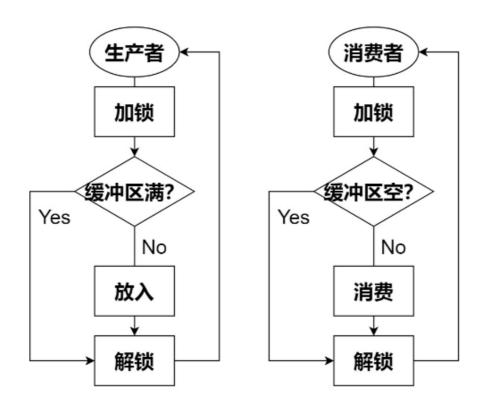


Figure 1:一把锁实现的生产者消费者队列

- 1.在参考代码中提供了运行所需要的主函数,请同学们将代码补充完整。
- 2.参考代码只使用了一把锁来实现生产者消费者队列,但是这存在一个问题,极端情况下,生产者每次都加锁成功,那缓冲区会满,产品无法放入缓冲区。消费者会饥饿,因为他一直无法获得锁,请考虑如何解决饥饿问题。实验报告中请展示相应的实验过程和运算结果。

3.线程池

线程池(thread pool): 是一种线程的使用模式。在实际系统中,频繁的创建销毁线程会带来过多的调度开销,从而影响整体性能。线程池维护着多个线程,等待着监督管理者分配可并发执行的任务。这避免了在处理短时间任务时创建与销毁线程的代价。线程池不仅能够保证内核的充分利用,还能防止过分调度。

在本习题中,我们采用任务队列的模式来实现一个线程池:主线程负责将相应的任务放入任务队列中,工作线程负责从任务队列中取出相应的任务进行处理,如果任务队列为空,则取不到任务的工作线程将进入挂起状态。具体代码见

github:https://github.com/Monaco12138/Threadpool-2023-DCS244-homework4

请根据要求填充完成空缺的部分,实现一个简单的线程池。

三、代码实现以及结果分析

1.实验一 ex1_pi_mutex

(1)代码实现

```
/* File: ex1_pi_mutex.c
 * Purpose: Estimate (pi^2)/6 using series
                (pi^2)/6 = [1/(1^2) + 1/(2^2) + 1/(3^2) + 1/(4^2) . . . ]
            It uses a semaphore to protect the critical section.
 * Compile: gcc -g -Wall -o ex1_pi_mutex ex1_pi_mutex.c -lpthread
           timer.h needs to be available
           ./ex1 pi mutex <number of threads> <n>
 * Run:
 * or
            ./ex1_pi_mutex (using defalut)
            n is the number of terms of the Maclaurin series to use
            n should be evenly divisible by the number of threads
 * Input:
            none
 * Output: The estimate of pi using multiple threads, one thread, and the
            value computed by the math library arctan function
           Also elapsed times for the multithreaded and singlethreaded
            computations.
 * Notes:
 * 1. The radius of convergence for the series is only 1. So the
         series converges quite slowly.
 */
#include <stdio.h>
#include <stdlib.h>
#include <math.h>
#include <pthread.h>
#include <semaphore.h>
#include <sys/time.h>
#define GET TIME(now) { \
  struct timeval t; \
   gettimeofday(&t, NULL); \
  now = t.tv sec + t.tv usec/1000000.0; \
const int MAX THREADS = 1024;
long thread_count;
long long n;
long double sum;
sem_t sem;
void* Thread_sum(void* rank);
/* Only executed by main thread */
void Get_args(int argc, char* argv[]);
void Usage(char* prog_name);
```

```
double Serial_pi(long long n);
int main(int argc, char* argv[]) {
            thread; /* Use long in case of a 64-bit system */
  pthread t* thread handles;
  double start, finish, elapsed;
  /* please choose terms 'n', and the threads 'thread count' here. */
  n = 1000000000;
  thread_count = 4;
  /* You can also get number of threads from command line */
  //Get_args(argc, argv);
  thread_handles = (pthread_t*) malloc (thread_count*sizeof(pthread_t));
  sem_init(&sem, 0, 1);
  sum = 0.0;
  GET TIME(start);
   for (thread = 0; thread < thread_count; thread++)</pre>
      pthread_create(&thread_handles[thread], NULL,
          Thread_sum, (void*)thread);
   for (thread = 0; thread < thread_count; thread++)</pre>
      pthread_join(thread_handles[thread], NULL);
   GET_TIME(finish);
   elapsed = finish - start;
   // sum = 4.0*sum;
      printf("With n = %lld terms,\n", n);
      printf(" Our estimate of pi = %.15Lf\n", sum);
      printf("The elapsed time is %e seconds\n", elapsed);
      GET TIME(start);
      sum = Serial pi(n);
      GET_TIME(finish);
      elapsed = finish - start;
      printf(" Single thread est = %.15Lf\n", sum);
      printf("The elapsed time is %e seconds\n", elapsed);
      printf("
                               pi = %.15lf\n", (4.0*atan(1.0))*
(4.0*atan(1.0))/6);
       sem_destroy(&sem);
         free(thread_handles);
         return 0;
} /* main */
void* Thread sum(void* rank) {
   long long my_rank = (long long) rank;//获取自己的线程号
   long double my_sum = 0.0;//线程计算的和
   long long local n=n/thread count;//此线程计算的个数
   long long start=1+(my_rank)*local_n;//此线程计算范围的开始
   long long end=(my rank+1)*local n;//此线程计算范围的结束
```

```
//对本线程计算的范围求和
   for(long long i=start;i<=end;i++){</pre>
   my_sum += 1.0 / (i*i);
   }
  sem_wait(&sem);//sem_wait可以用来阻塞当前线程,直到信号量的值大于0,解除阻塞,解除阻
塞后, sem的值-1, 表示公共资源被执行减少了
  sum += my_sum; //全局变量sum加上本线程计算的和
  sem_post(&sem);//当有线程阻塞在这个信号量上时,调用这个函数会使其中的一个线程不再阻塞
  return NULL;
} /* Thread_sum */
double Serial_pi(long long n) {
            long double sum = 0.0;
            long long i;
            for (i = 1; i <= n; i++) {
              sum += 1.0 / (i*i);
            }
            return sum;
} /* Serial */
void Get_args(int argc, char* argv[]) {
              if (argc != 3) Usage(argv[0]);
              thread count = strtol(argv[1], NULL, 10);
              if (thread_count <= 0 || thread_count > MAX_THREADS)
Usage(argv[0]);
              n = strtoll(argv[2], NULL, 10);
              if (n <= 0) Usage(argv[0]);</pre>
            } /* Get_args */
void Usage(char* prog_name) {
                 fprintf(stderr, "usage: %s <number of threads> <n>\n",
prog name);
                 >= 1\n");
                 number of threads\n");
                exit(0);
} /* Usage */
```

实验原理

本实验利用\$\$ П/6=\sum {i=1}^{∞} 1/i^2 \$\$计算П/6

(1)首先初始化信号量,同一时间只能由一个线程加入互斥区

```
sem_init(&sem, 0, 1);
```

(2)接着调用pthread create创造thread count多个线程,每个线程执行Thread sum

```
for (thread = 0; thread < thread_count; thread++)
    pthread_create(&thread_handles[thread], NULL,Thread_sum, (void*)thread);</pre>
```

(3)在Thread_sum也就是我们编写的函数中,我们获取每个线程的线程号,根据线程号分好计算的范围,每个线程计算该线程负责范围的和,通过sem_wait(&sem)和sem_post(&sem)一个时刻只能一个线程加入互斥区域,并执行全局变量sum加上本线程计算的和。

```
void* Thread_sum(void* rank) {
   long long my_rank = (long long) rank; //获取自己的线程号
   long double my_sum = 0.0;//线程计算的和
   long long local n=n/thread count;//此线程计算的个数
   long long start=1+(my_rank)*local_n;//此线程计算范围的开始
   long long end=(my_rank+1)*local_n;//此线程计算范围的结束
   //对本线程计算的范围求和
   for(long long i=start;i<=end;i++){</pre>
  my sum += 1.0 / (i*i);
  sem wait(&sem);//sem wait可以用来阻塞当前线程,直到信号量的值大于0,解除阻塞,解除阻
塞后, sem的值-1, 表示公共资源被执行减少了
  sum += my sum; //全局变量sum加上本线程计算的和
  sem_post(&sem);//当有线程阻塞在这个信号量上时,调用这个函数会使其中的一个线程不再阻塞
  return NULL;
} /* Thread_sum */
```

(4)输出多线程计算的时间和估计值

(5)再串行计算sum

(6)输出串行计算的时间和估计值

运行结果

n = 10000, thread_count = 4

n = 1000000, thread_count = 4

```
====== ERROR =======

With n = 1000000 terms,

Our estimate of pi = 1.644933066848726
The elapsed time is 1.900911e-03 seconds
Single thread est = 1.644933066848727
The elapsed time is 6.484985e-03 seconds
pi = 1.644934066848226

======= REPORT =======
```

 $n = 100000000, thread_count = 4$

====== OUTPUT ======

With n = 1000000000 terms,

Our estimate of pi = 1.644934056848227

The elapsed time is 1.616180e-01 seconds

Single thread est = 1.644934056848227

The elapsed time is 6.575110e-01 seconds

pi = 1.644934066848226

====== REPORT ======

实验结果分析

加速比=Ts/Tp

thread_count	n	并行计算时间	串行计算时间	加速比
4	10000	3.299713e-04s	6.413460e-05s	19.44%
4	1000000	1.900911e-03s	6.484985e-03s	341.16%
4	100000000	1.616180e-01s	6.575110e-01s	406.83%

由表格数据可以看出,随着n的增大加速比也增大,在n=10000时并行计算时间慢于串行计算时间, n=100000000时并行计算时间是串行计算时间的1/4

2.实验二 ex2_producer

代码实现

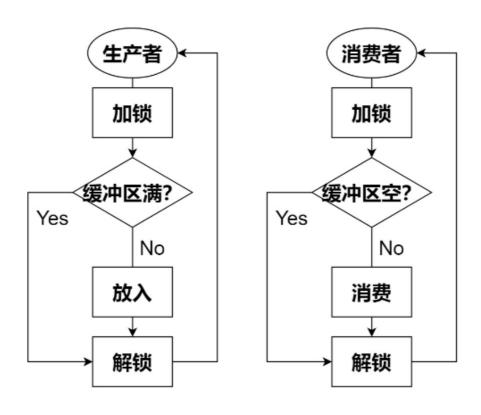
#include <stdio.h>
#include <stdlib.h>

```
#include <string.h>
#include <pthread.h>
#define NUMS 100 //表示生产, 消费的次数
#define CAPACITY 5 //定义缓冲区最大值
int capacity = 0; //当前缓冲区的产品个数
pthread_mutex_t mylock = PTHREAD_MUTEX_INITIALIZER; //互斥量
void *produce(void *args)//生产者函数
{
   int produce_times=3;//固定生产的次数上限
   while(produce_times>0){//当未达到固定生产的次数上限,继续生产、
   if(capacity>=CAPACITY)continue;//防止对锁的竞争造成的饥饿问题
   pthread_mutex_lock(&mylock);//上锁
   if(capacity<CAPACITY)produce_times--;//若未达到缓冲区最大值,则可以生产
   while(capacity<CAPACITY){//生产直到不能再生产
      printf("Producer:capacity=%d\n",++capacity);//输出缓冲区产品个数
   printf("Producer:The buffer is full!\n");
   pthread_mutex_unlock(&mylock);//解锁
   }
   return NULL;
  /**********************
void * consume(void *args)//消费者函数
{
   int consume times=3;//固定消费的次数上限
   while(consume_times>0){//当未达到固定消费的次数上限,继续消费
   if(capacity<=0)continue;//防止对锁的竞争造成的无法生产问题
   pthread_mutex_lock(&mylock);//上锁
   if(capacity>0)consume_times--;//若缓冲区非空,则可以消费
   while(capacity>0){//消费直到缓冲区空
      printf("Consumer:capacity=%d\n",--capacity);//输出缓冲区产品个数
   printf("Consumer:The buffer is empty!\n");
   pthread_mutex_unlock(&mylock);//解锁
   return NULL;
  }
int main(int argc, char** argv) {
  int err;
   pthread_t produce_tid, consume_tid;
   void *ret;
   err = pthread_create(&produce_tid, NULL, produce, NULL);//创建线程
   if (err != 0) {
```

```
printf("线程创建失败:%s\n", strerror(err));
       exit(-1);
   }
   err = pthread_create(&consume_tid, NULL, consume, NULL);
   if (err != 0) {
       printf("线程创建失败:%s\n", strerror(err));
       exit(-1);
   }
   err = pthread_join(produce_tid, &ret);//主线程等到子线程退出
   if (err != 0) {
       printf("生产着线程分解失败:%s\n", strerror(err));
       exit(-1);
   err = pthread_join(consume_tid, &ret);
   if (err != 0) {
       printf("消费者线程分解失败:%s\n", strerror(err));
       exit(-1);
   }
   return (EXIT_SUCCESS);
}
```

实验原理

本程序是一个消费者、生产者问题(生产者函数),具体流程如图:



实验重点:

(1)问题:所有生产者和消费者都是异步方式运行的,但它们必须保持同步,即不允许消费者到一个空的缓冲区中取产品,也不允许生产者向一个已经装满产品且尚未被取走的缓冲区中投放产品

解决方法:

利用锁,每次对缓冲区操作前上锁、结束操作解锁,能避免生产者和消费者同时对互斥区进行操作造成冲突问题

(2)问题:参考代码只使用了一把锁来实现生产者消费者队列,但是这存在一个问题,极端情况下,生产者每次都加锁成功,那缓冲区会满,产品无法放入缓冲区。消费者会饥饿,因为他一直无法获得锁,产生饥饿问题

解决方法:

产生饥饿问题的原因是对生产者和消费者对锁也有竞争问题,参考代码规定只使用了一把锁,我们可以通过对 capacity即缓冲区产品的数目的条件判断规定生产者和消费者对锁的使用:

若capacity>=CAPACITY,则说明缓冲区已满,不需要生产者上锁,所以使生产者忙等,直到capacity < CAPACITY,满足生产者生产条件可以上锁

若capacity < = 0,则说明缓冲区空,不需要消费者上锁,所以使消费者忙等,直到capacity > 0,满足消费者消费条件可以上锁

```
pthread_mutex_lock(&mylock);//上锁 if(capacity>0)consume_times--;//若缓冲区非空,则可以消费 while(capacity>0){//消费直到缓冲区空 printf("Consumer:capacity=%d\n",--capacity);//输出缓冲区产品个数 } printf("Consumer:The buffer is empty!\n"); pthread_mutex_unlock(&mylock);//解锁 } return NULL;
```

运行结果

为避免不断生产和消费造成死循环,我们设置生产和消费的上限次数=3

```
====== OUTPUT ======
Producer:capacity=1
Producer:capacity=2
Producer:capacity=3
Producer:capacity=4
Producer:capacity=5
Producer:The buffer is full!
Consumer:capacity=4
Consumer:capacity=3
Consumer:capacity=2
Consumer:capacity=1
Consumer:capacity=0
Consumer:The buffer is empty!
Producer:capacity=1
Producer:capacity=2
Producer:capacity=3
Producer:capacity=4
Producer:capacity=5
Producer:The buffer is full!
```

Consumer:capacity=3
Consumer:capacity=2
Consumer:capacity=1
Consumer:capacity=0
Consumer:The buffer is empty!
Producer:capacity=1
Producer:capacity=2
Producer:capacity=3
Producer:capacity=4
Producer:capacity=5

Producer:The buffer is full!

Consumer:capacity=4

Consumer:capacity=3

Consumer:capacity=2

Consumer:capacity=1

Consumer:capacity=0

Consumer:The buffer is empty!

3.实验三 thread_pool

代码实现(这里展示thread_pool.c中代码,其他代码未改动,每个函数细节在注释中)

(1)每个线程执行的函数,若线程池未回收则一直等待任务执行

```
void Job_running(threadpool* pool)// 线程池中的每个线程执行此函数 {
    while(pool->flag==1){//pool未回收则一直循环执行任务
    while(pool->jobnum==0);//无任务时忙等
    Jobnode job = Pop(pool); // pop函数里面会进行互斥和等待非空
```

```
if(job.pf!=NULL){
    job.pf(job.arg); // 执行任务函数
    }
    }
    pthread_exit(∅);
}
```

(2)线程池的初始化操作

```
threadpool* Pool_init(int Maxthread)//构造函数
{
   threadpool* pool;
   pool = (threadpool*)malloc(sizeof(threadpool));
   pool->flag = 1;//flag=0时表示被回收
   pool->threads=(pthread_t*)malloc(sizeof(pthread_t)*Maxthread);
      //PLEASE ADD YOURS CODES
   if(pool->threads==NULL){//分配空间失败
      printf("malloc threads fail\n");
      return NULL;
   }
   //初始化
   pool->poolhead=(threadjob*)malloc(sizeof(threadjob));
   pool->Maxthread=Maxthread;
   for(int i=0;i<pool->Maxthread;i++)pthread_create(&pool->threads[i],NULL,
(void*)Job running,pool);//从线程池取出线程执行任务函数
   pool->poolhead->next=NULL;
   pool->poolhead->data.pf=NULL;
   pool->jobnum=0;
   sem_init(&pool->sem, 0, 1);//每次只能一个线程加入线程池操作
   return pool;
}
```

(3)将任务节点添加到线程池中

(4)push相应的任务节点

```
int Push(threadpool* pool , Jobnode data )//push相应的任务节点
{
   sem_wait(&pool->sem);
   //添加仟务
   threadjob *head =pool->poolhead;
   while(head->next!=NULL){
      head=head->next;
   }
   head->data.pf=data.pf;
   head->data.arg=data.arg;
   pool->jobnum++;
   threadjob*new_node=(threadjob*)malloc(sizeof(threadjob));
   head->next=new_node;
   new node->next=NULL;
   sem_post(&pool->sem);
      //PLEASE ADD YOURS CODES
   return 1;
                  *************************************
}
```

(5)删除线程池

(6)pop任务节点

```
Jobnode Pop(threadpool* pool)//pop相应的任务节点
{
  sem_wait(&pool->sem);//上锁
  if(pool->jobnum==0){//任务为0,做特殊处理,线程不需要执行任务
  sem_post(&pool->sem);
  return pool->poolhead->data;//data为NULL
  pool->jobnum--;
  threadjob*head=pool->poolhead;
  pool->poolhead=head->next;
  head->next=NULL;
  sem_post(&pool->sem);//解锁
  return head->data;
     //PLEASE ADD YOURS CODES
  }
```

运行结果

```
ljj@ljj-virtual-machine:~/Desktop/parallel_programming$ gcc threadpool1.c
ljj@ljj-virtual-machine:~/Desktop/parallel_programming$ ./a.out
this is the task1 running in <101938>, the answer = 1037037832
this is the task2 running in <101939>, the answer = 1800079522
this is the task1 running in <101938>, the answer = 964052537
this is the task1 running in <101940>, the answer = 66661969
this is the task2 running in <101947>, the answer = 824997573
this is the task2 running in <101942>, the answer = 756257002
this is the task1 running in <101940>, the answer = 1996567275
this is the task2 running in <101938>, the answer = 1567893058
this is the task2 running in <101938>, the answer = 868043668
this is the task1 running in <101938>, the answer = 1081605874
this is the task2 running in <101938>, the answer = 873924261
this is the task1 running in <101938>, the answer = 2114379532
this is the task1 running in <101940>, the answer = 1288012791
this is the task1 running in <101942>, the answer = 1201757409
this is the task1 running in <101939>, the answer = 194722833
this is the task2 running in <101938>, the answer = 1856605521
this is the task2 running in <101938>, the answer = 1587120109
this is the task1 running in <101938>, the answer = 710177488
this is the task2 running in <101945>, the answer = 102977869
this is the task2 running in <101938>, the answer = 1701126374
this is the task2 running in <101938>, the answer = 911251867
this is the task2 running in <101942>, the answer = 1178593342
this is the task2 running in <101942>, the answer = 852621555
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可以看到执行任务的线程的id号为101938到101948十个数字,说明执行任务的线程是不断地从线程池中的十个 线程中取出来的,200个任务都是这十个不断执行操作的结果。

这样就能避免你创造太多个线程执行,每个线程都是执行一个时间很短的任务就结束了,频繁创建线程就会大大降低系统的效率

四、心得体会

- (2) 通过实验一, 学会了使用多线程并行执行, 用并行程序进行加速。
- (3) 通过实验三,对线程池有了更深的了解,同时学会了编写简单的线程池重复使用线程。