

```

'''
'''
#Hello My name is binary_code_form;
#Hello My Name Is binary_form_code:
#{2}
#[3]
#{Li}
#[Si] | |
'''
'''
#$help_print[{2[si]}]
#sig_bliss_exit
#Mother_of_codes
#new_gen_22nd_21st_cent
#$help_print[{$new_gen_22nd_21st_cent}] | |
#$professor_ig_bliss_exit
#$help_data_chess_exec_form_binary_code_form
#sexec_help_print[$help_data_chess_exec_form_binary_code_form}] ||
'''
'''
$0x=1y
$0x=-1y

```

\$1=1, 1=-1, 1=0 because os a matter and atoms shifting on a graph in the universe.

\$what does 1 equal a multiple solution can have one question

```

$e=mc^3 red
$e-m=c^2 blue
$e-m=c^3 green
$e-m=c^4 Purple
$e-m=c^5 orange
$e-m=c^7 grey

$ee=mc^3 red
$e-m=c^2 blue
$e-m=c^3 green
$e-m=c^4 Purple
$e-m=c^5 orange
$e-m=c^7 grey

$e^(2)=mc^(3 ) Red

$e^( )=mc^(3 ) Blue

$e^(2)=mc^( ) green

$Jevon.Jamel.James

$12/19/2020

$12.19.2020

$e^(2)=mc^(3 ) Red

$e^(2)=mc^(3 ) Blue

$e^(2)=mc^(3 ) green

$e=mc^(2) red

```

$e^{(9m)} = c^{(9)}$ blue

$e^{(2m)} = c^{(7)}$ green

$e^{(3m)} = c^{(5)}$ purple

$e^{(4m)} = c^{(3)}$ yellow

$m = c^{(3+e^{(2)})}$ grew

$m = c^{(7-e^{(3)})}$ light blue

\$Jevon Jamel James

\$12.19.2020

\$12/19/2020

$E^9M = C^9$ ' Einstein Relativity theory' the ball drops and roll.

$E^2M = C^7$

$E^3M = C^5$

$E^4M = C^3$

\$1.66 and its square-root $8.13^2 = 66.0969$ or $8.126^2 = 66.031876$; 2 decimal places or 3 decimal places behind zero. SIGMA

\$2.

$E = A^2 + B^3 - C^5$

\$2a.

$E - A^2 - B^3 + C^5 = A^2 + B^3 - C^5$

$E = 66$ and its square-root $8.13^2 = 66.0969$ or $8.126^2 = 66.031876$; 2 decimal places or 3 decimal places behind zero.

\$3.

\$A.

$E + A^2 + B^3 + C^5 = A^2 + B^3 + C^5 + E$

\$Newton's law = $(S * I * G * M * A) / T$

$((\text{Speed})(\text{Inertia})(\text{Gravity})(\text{Mass})(\text{Acceleration})) / \text{Time}$

\$Newton's Law

""The three laws proposed by Sir Isaac Newton concerning relations between force, motion, acceleration, mass, and inertia. ... Newton's first law states that a body at rest will remain at rest, and a body in motion will remain in motion with a constant velocity, unless acted upon by a force.'

\$Author: Jevon Jamel James

\$Title: Equation For Motion Of Vehicular Object

\$Date: 08.29.2019

\$James Corporation 2019

\$Math Equation, Chemical Formula

\$1. $E + 2MC = MC^2 + E^2$

$2E + 0MC = 0MC^2 + E^2$

\$Compounds

\$2. $E + MC^2 = MC^2 + E^2$

$2E + MC^2 = MC^2 + E^2$

\$Infinite Solutions

\$1.MATH EQUATION

$E = MC^2$

$E = MC^2$

$E = MC^2 \text{NAT}$

$E = MC^2 \text{NAT}$

\$E2=MC^2NAT

\$E2=MC2NAT

\$E2=MC^2

\$E2=MC2

\$"" 'Inertia=Mass(Accelation) I=MA'

\$Power=Inertia(mass)/enegy P=IM/E

\$Energy=Mass(Change in Charge)^2Force(acceleration)(time) E=MC^2NAT

\$1. GT^26 T HO^34 V^54 HC^45 QR^75

\$ 2. E=MC^2NAT

\$ "" "Manmade forces that defy forces of collision that collide by friction, when forces ACT on positive and negative scope of existence; when forces push against and repel from motion push against to de magnify collective negative straights to equalize a positive result.

\$Friction: to grasp the asphalt It opposes motion

\$Momentum: to coast of drive

\$Center of gravity: thermodynamics and fluid rigedy; to be at equilibrium to be centered on an axis N, S, E, W,; NE, NS, NW, SE, SW, EW.

\$ U X N=Friction

\$"" variables: s = displacement, u = initial velocity, v = final velocity, a = acceleration, t = time.

\$((V0^25a+V0t+V0^4+at^27)^27/V02+2a(S-S0))x(S0+Vt(a))^91(U x N)

\$((Cybrary-:(sybrary-circuits))' = MS^230t 29. Geosphere equation: to be continued 30. Geospatial

\$ (Microsoft Cat Intelligence)

\$"" ^ (Windows 10)(Microsoft; Catalyst â€¢Intel Core#, GS^230) Core ^ ((Cybrary-'8'(Sybrary-Circuits))' GS^230 Mcat=MCI-+computer

\$Paragraph: MCat-MCI= Compressor(V6-V7,V8 Engine)

\$Cars ^^^ Bumble(Transformers) Hawk(Presidential) ^^ (Business Cars) DanDum(Gundam Knight)

\$1. Anti Fog Lights A. L- Light adjuster Sensor 2. Timing Belt 3. + 0-240 MPH= KMH 4. + Synthetic Oil 5. Tire Rotation on all four wheels 3 Notches on Rim. 6. Ballpoint Joints on Rims all four tires- Four wheel all weather Drive.

\$B.= Cruise Circuit Control. C.= Traction Control

\$- Fiberglass Aluminum Body - Undercarriage

\$+ Compressor V6-V8

\$(25e+26m+25c)log

\$"" Celog(x)

\$mc+(600Ã·13)(e)=1.697905113Ã-10^1

\$F(x)=eÃ·48e

\$G(x)=eÃ-48e

\$X= 0.0208, 354.67

\$F(x)=elog^(x)

\$G(x)=elog^(x)

\$x:1,2,3,4,5,6,7,8,9,cont

\$X= 2.7179, 2.7169,2.7152,2.7129,2.7099, thus cont d decimal places behind zero

\$F(x)=23Ã·log23^(x)

\$G(x)=12Ã-log12(x)

\$X=2,3,4,5,6,7,8,9, cont

\$e^(tan(xmc)^1,2,3,4,5,6,7,8,9,cont)

\$e^(cos(xmc)^,1,2,3 4,5,6,7,8,9,cont)

\$e^(sin(xmc)^1,2,3,4,5,6,7,8,9,cont)

\$e^(cos(xmc)^,1,2,3 4,5,6,7,8,9,cont)

```
$e^(tan(xmc)^1,2,3,4,5,6,7,8,9)
$e^(cos(xmc)^,1,2,3 4,5,6,7,8,9)
```

```
$e^(sin(xmc)^1,2,3,4,5,6,7,8,9)
```

```
$V8-V22
$""vsin(14)=-vsin(17)
```

```
$vsin(8)
```

```
$-vsin(22)
```

```
$vsin(8)=-vsin(22)
```

```
$vtan(13)
$-vtan13
$vtan(13)=-vtan(13)
```

```
$vsin(8)=-vsin(12)
$Exoskeleton
$x-s=1/XS*1
$1x-1s=1/((XS)*1)
```

```
$Genome
$x+s=1*ds/1
$1x+1s=(1*(ds))/1
$1d+1s=(1*(ds))/1
```

```
$Two strands of RNA
```

```
$sin(1)*log(x)-cos(1)*log(s)=sin(1)/log(ds)*cos(1)
```

```
$sin(1)*log(x)-cos(1)*log(s)=sin(1)/log(XS)*cos(1)
```

```
$DNA
$sin(1)*log(d)+cos(1)*log(s)=sin(1)*log(ds)/cos(1)
```

```
$Conclusion
$Exoskeleton;Genome+Genome;RNA+RNADNA
```

```
$latin mode calculus
$i=9001*sin(cm)*50-90c*sin(xc)*100
$print(Intelligence)
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#$exec_help_print[$help_data_chess_exec_form_binary_code_form}] ||
```

```
#$1.Xray= x(pie(y))= x(pie(y))^3
#$2.x(pie(y))=x^{2}(pie(y))^3 #3.cos(xyz)=tan(xyzzy)sin(xyz)log(xy)z
#24f(x)(m * g * h)=(-(dN/dt))+(m/(s2)) +( m * g * h)
```

```
#24x(PE)=A+(siu)+(PE)
#P= A+siu/(e(24x-1))
#P= A+siu/(e(24x-1))
'''

#$main.py
'''

'''
```