

CSCI 599: Digital Geometry Processing

9.1 Remeshing



Hao Li

<http://cs599.hao-li.com>

Outline

- *What* is remeshing?
- *Why* remeshing?
- *How* to do remeshing?

Outline

- *What is remeshing?*
- *Why remeshing?*
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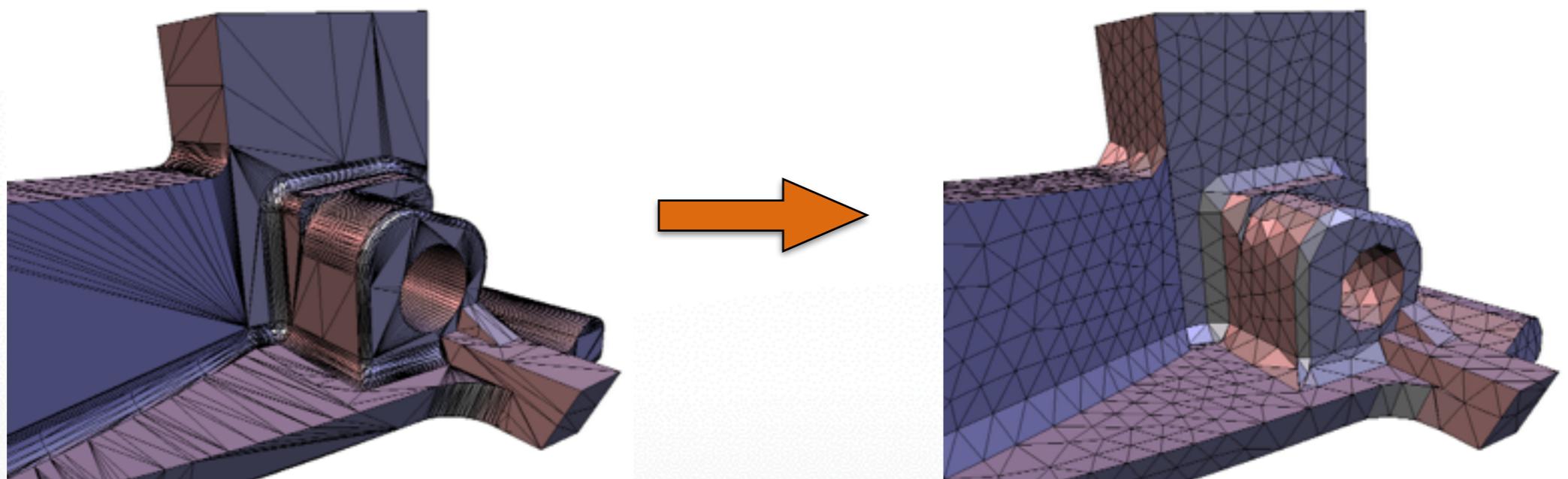
Definition

Given a 3D mesh

- Already a manifold mesh

Compute another mesh

- Satisfy some quality requirements
- Approximate well the input mesh



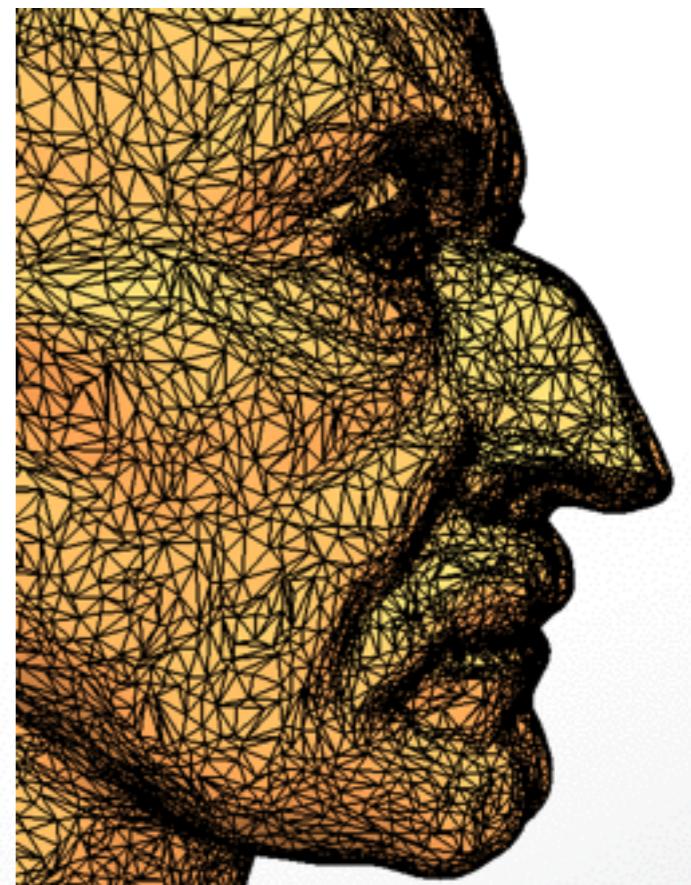
Outline

- *What* is remeshing?
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- *How* to do remeshing?

Motivation

Unsatisfactory “raw” mesh

- By scanning or implicit representations

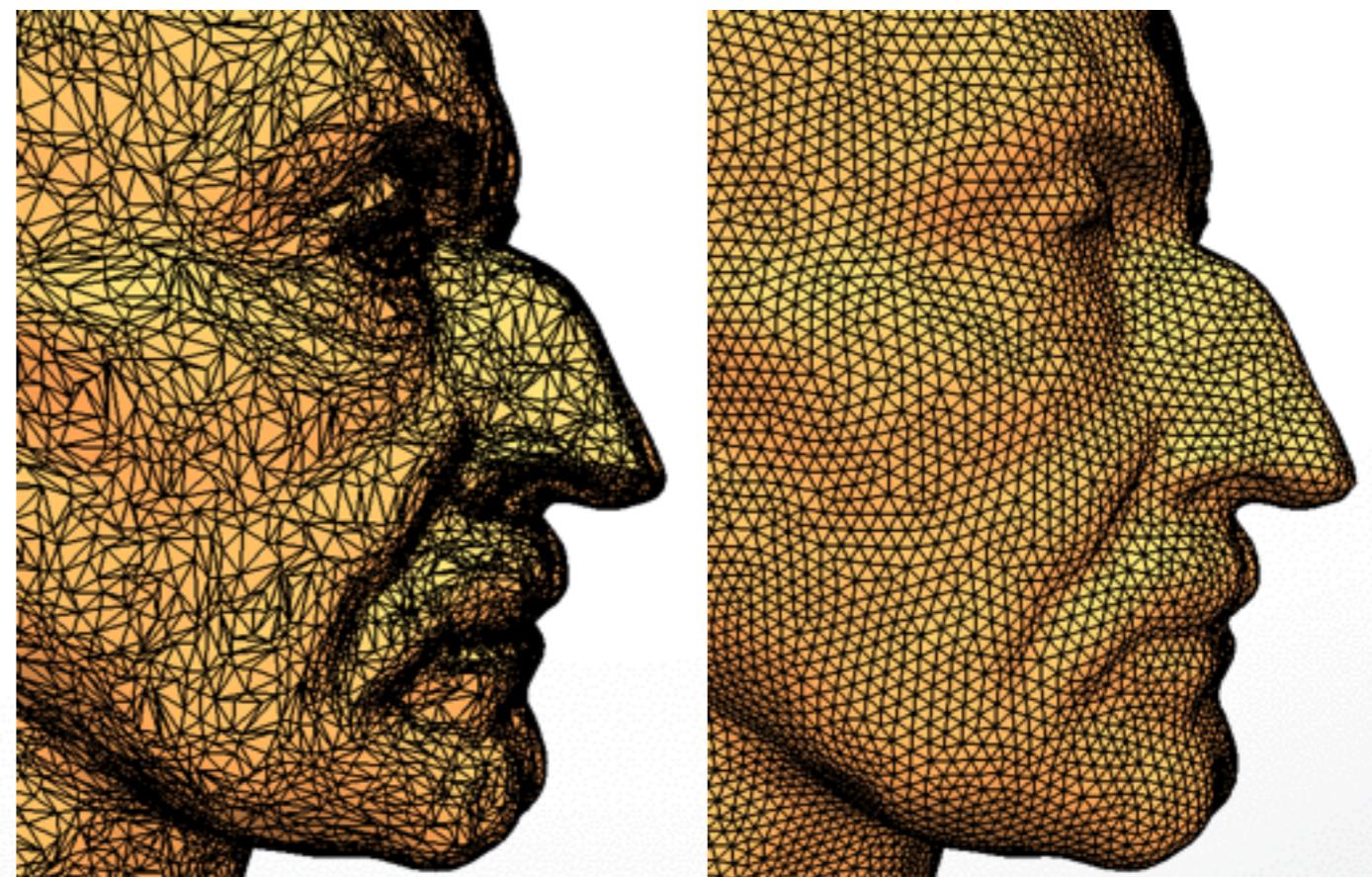


Motivation

Unsatisfactory “raw” mesh

- By scanning or implicit representations

Improve mesh quality for further use



Motivation

Unsatisfactory “raw” mesh

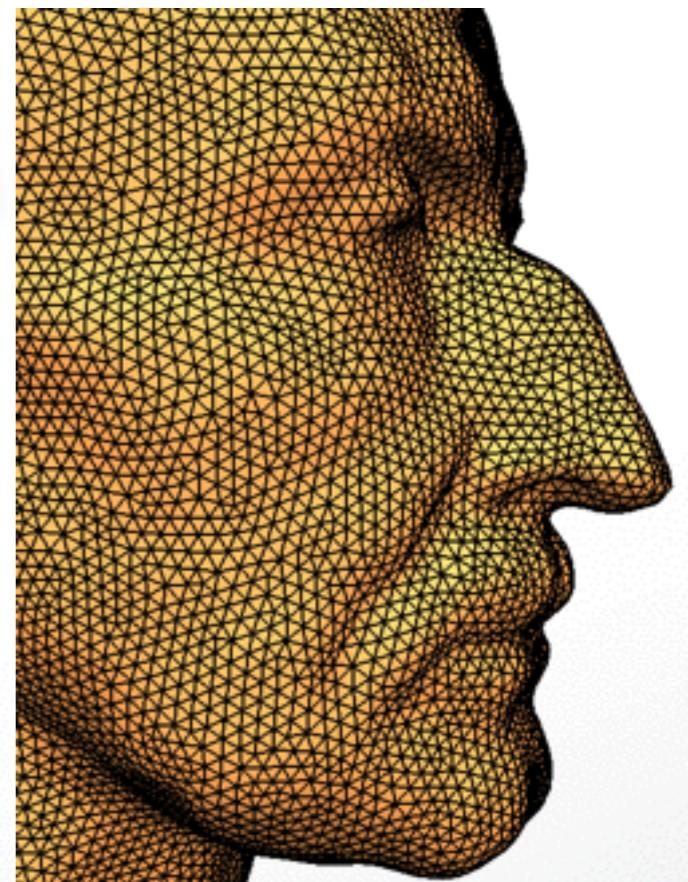
- By scanning or implicit representations

Improve mesh quality for further use

- Modeling: easy processing
- Simulation: numerical robustness
-

Quality requirements

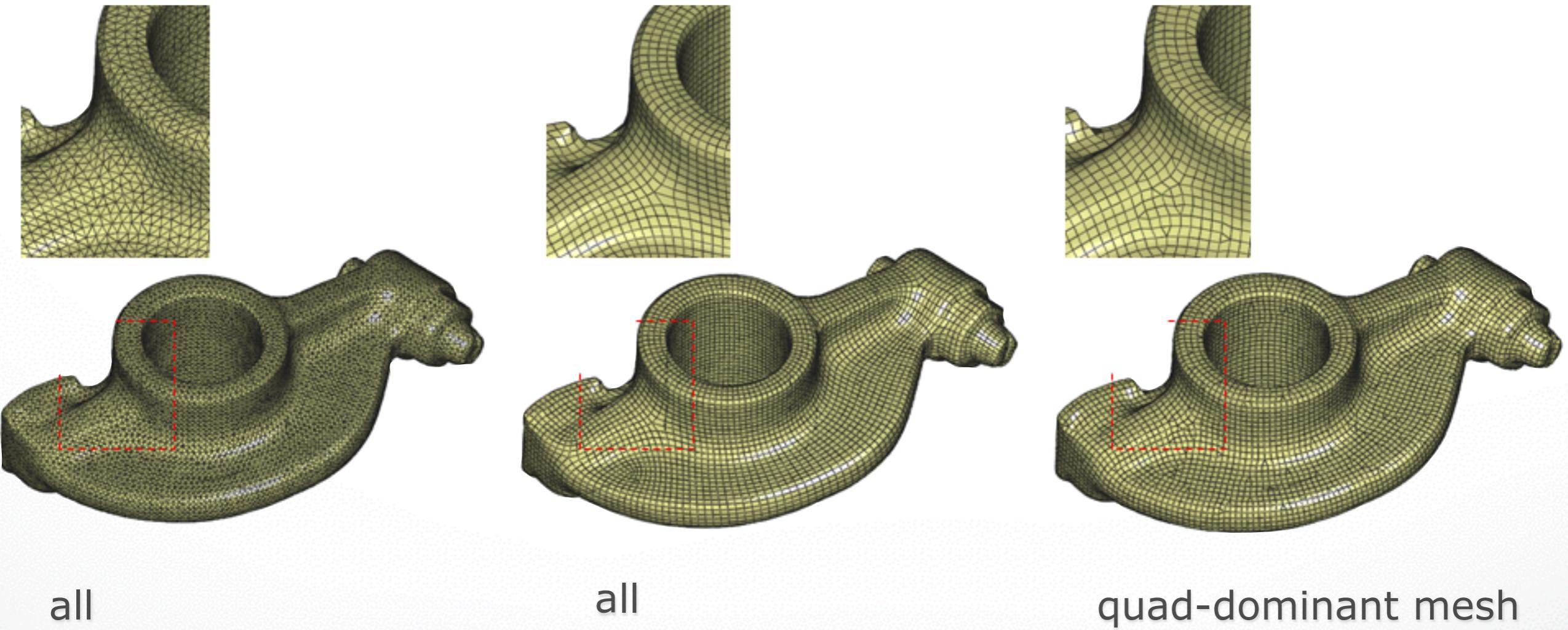
- Local structure
- Global structure



Local structure

Element type

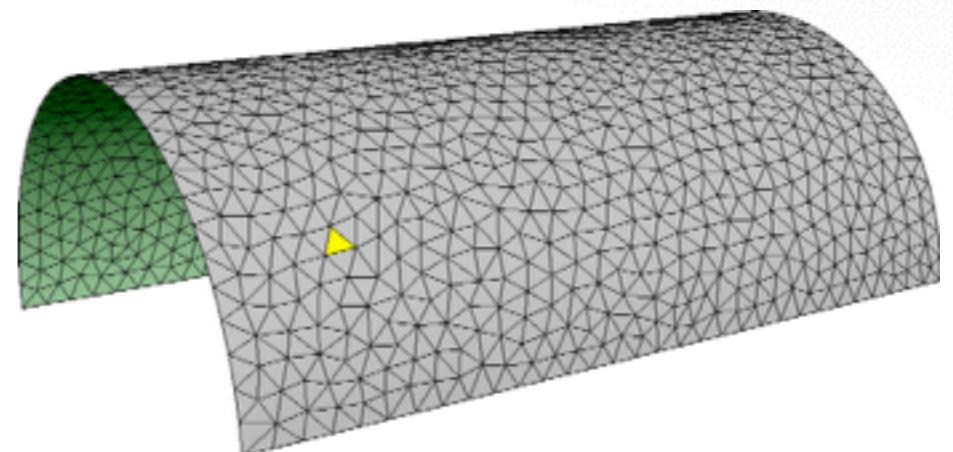
- Triangles vs. quadrangles



Local structure

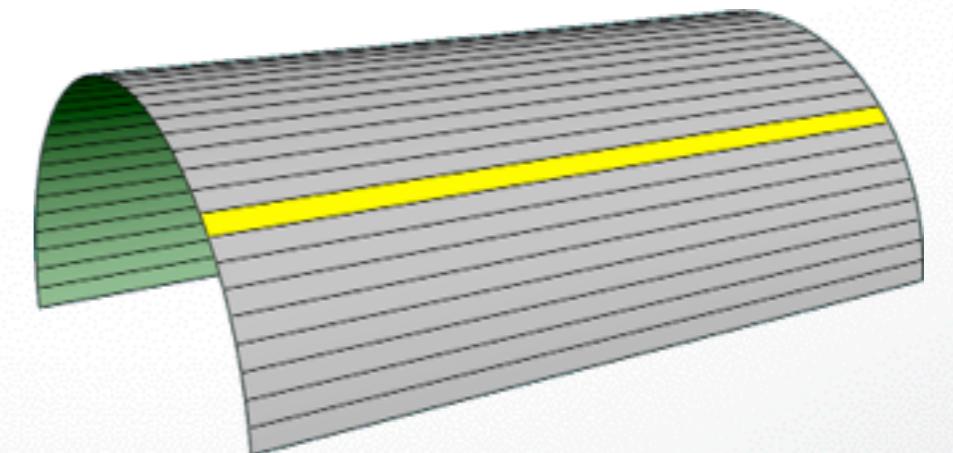
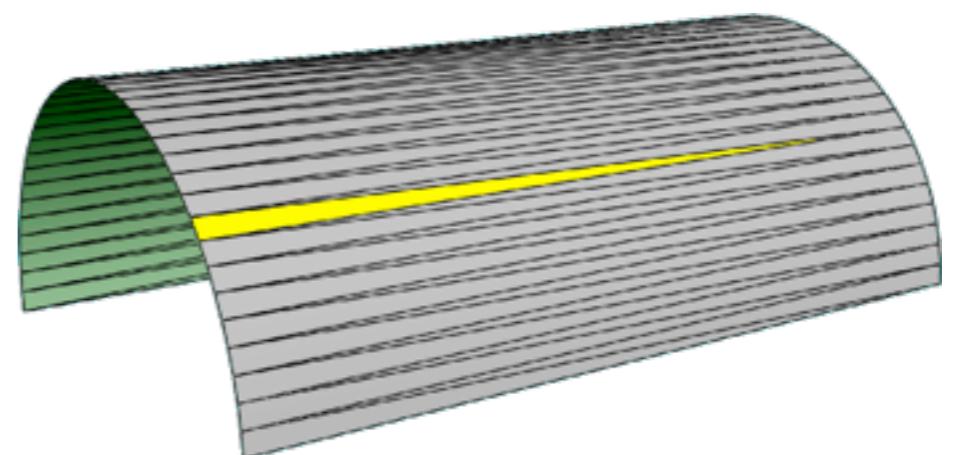
Element type

- Triangles vs. quadrangles



Element shape

- Isotropic vs. anisotropic



Local structure

Element type

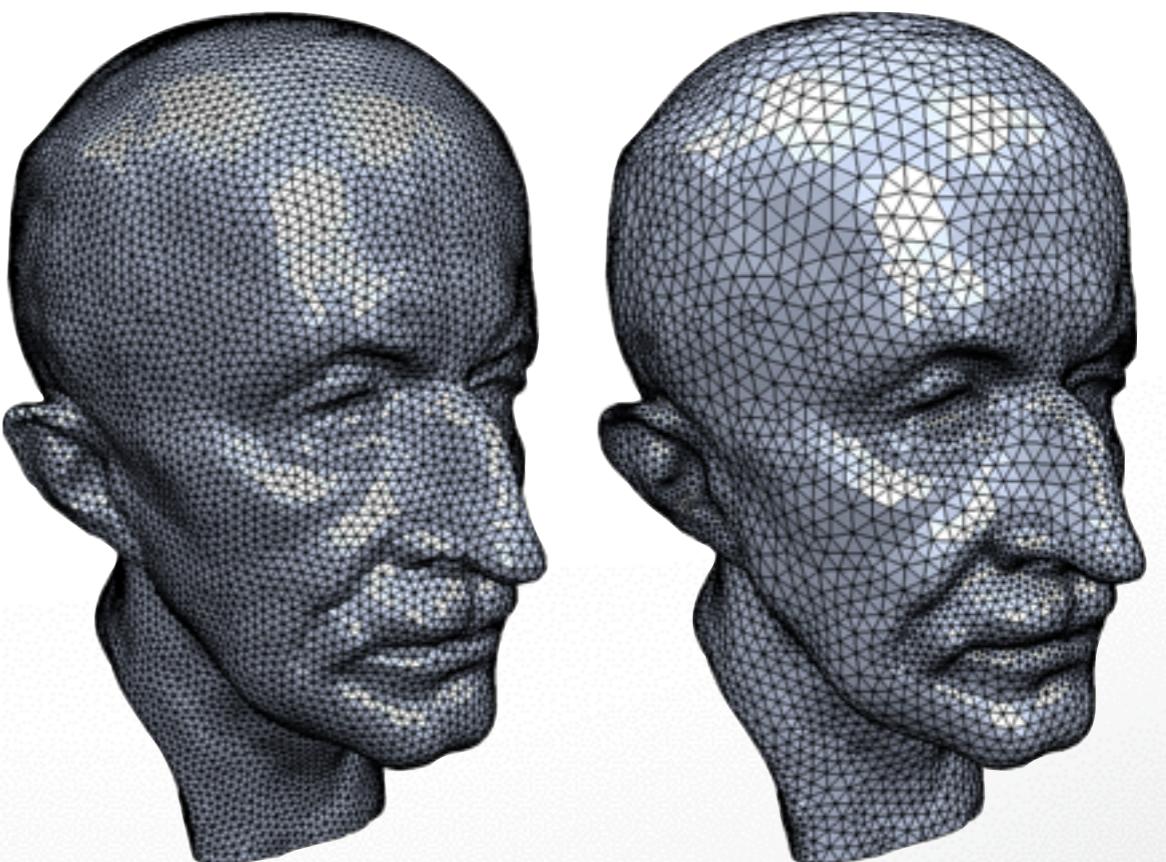
- Triangles vs. quadrangles

Element shape

- Isotropic vs. anisotropic

Element distribution

- Uniform vs. adaptive



Local structure

Element type

- Triangles vs. quadrangles

Element shape

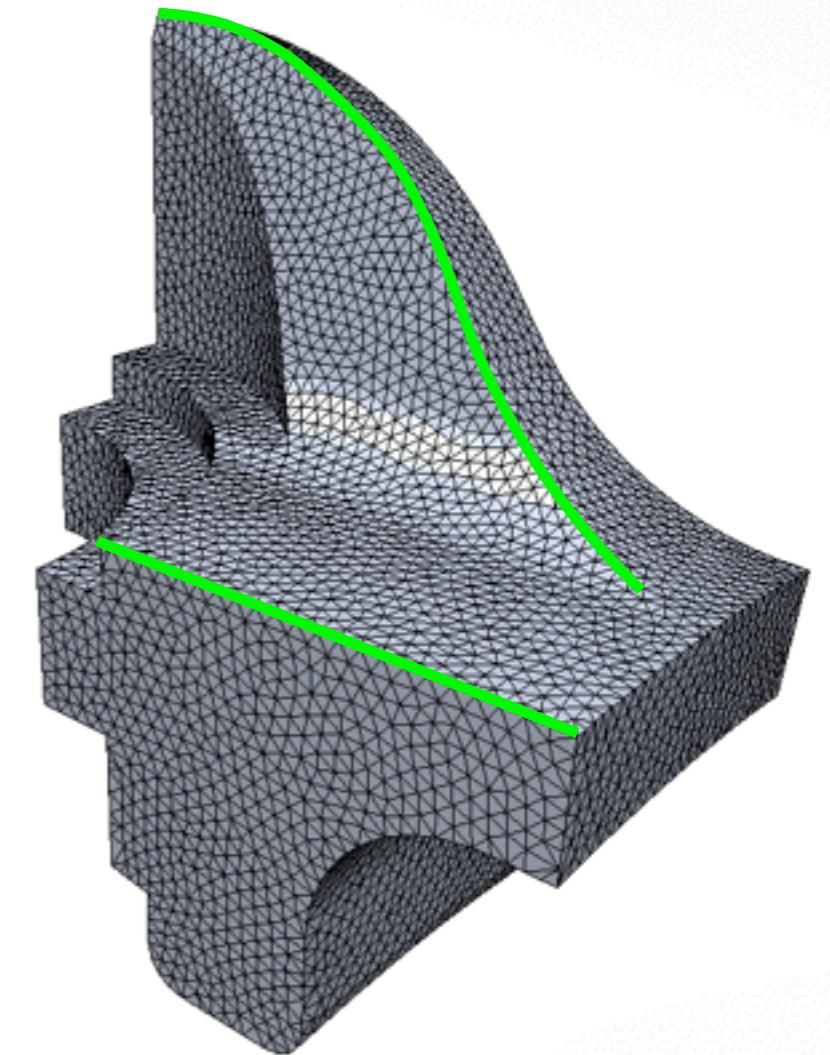
- Isotropic vs. anisotropic

Element distribution

- Uniform vs. adaptive

Element alignment

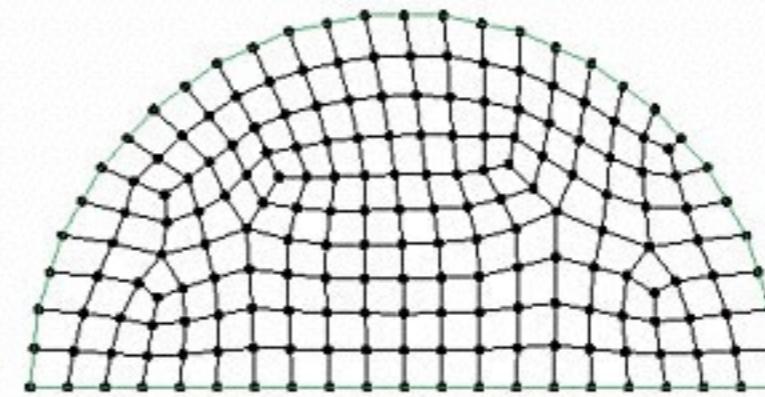
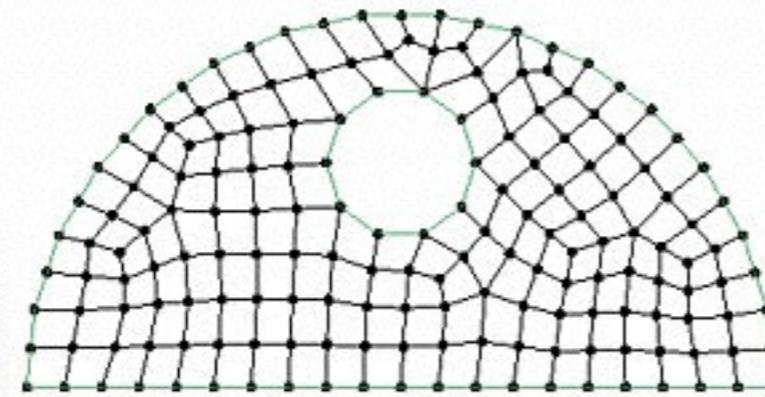
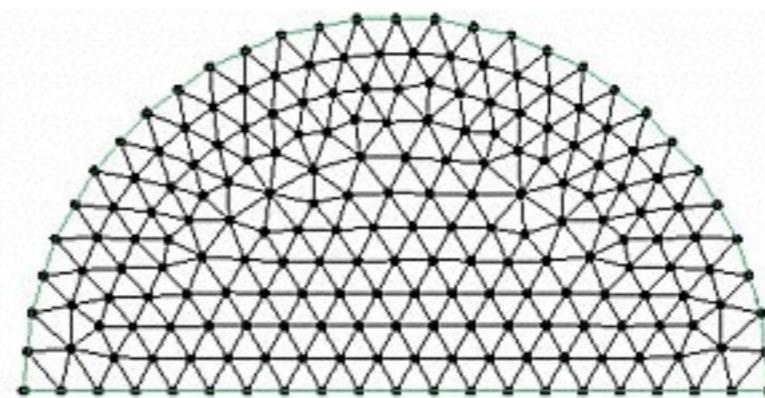
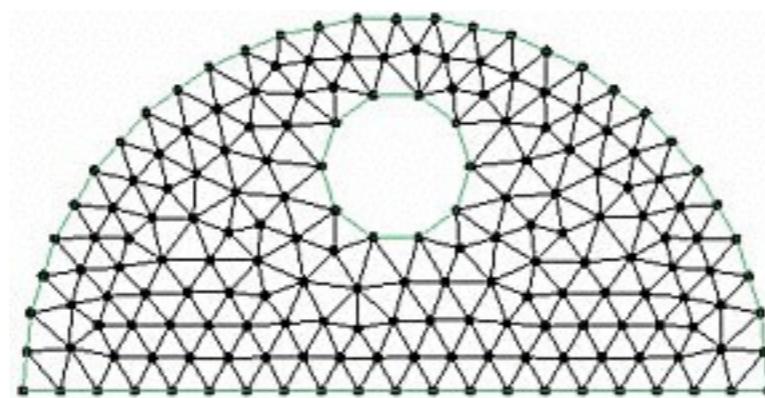
- Preserve sharp features and curvature lines



Global structure

Valence of a *regular* vertex

	Interior vertex	Boundary vertex
Triangle mesh	6	4
Quadrangle mesh	4	3



Global structure

Valence of a *regular* vertex

	Interior vertex	Boundary vertex
Triangle mesh	6	4
Quadrangle mesh	4	3

Different types of mesh structure

- Irregular
- Semi-regular: multi-resolution analysis / modeling
- Highly regular: numerical simulation
- Regular: only possible for special models

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 - **Isotropic remeshing**
 - Anisotropic remeshing

Isotropic remeshing

Incremental remeshing

- Simple to implement and robust
- Not need parameterization
- Efficient for high-resolution input

Variational remeshing

- Energy minimization
- Parameterization-based → expensive
- Works for coarse input mesh

Greedy remeshing

Isotropic remeshing

Incremental remeshing

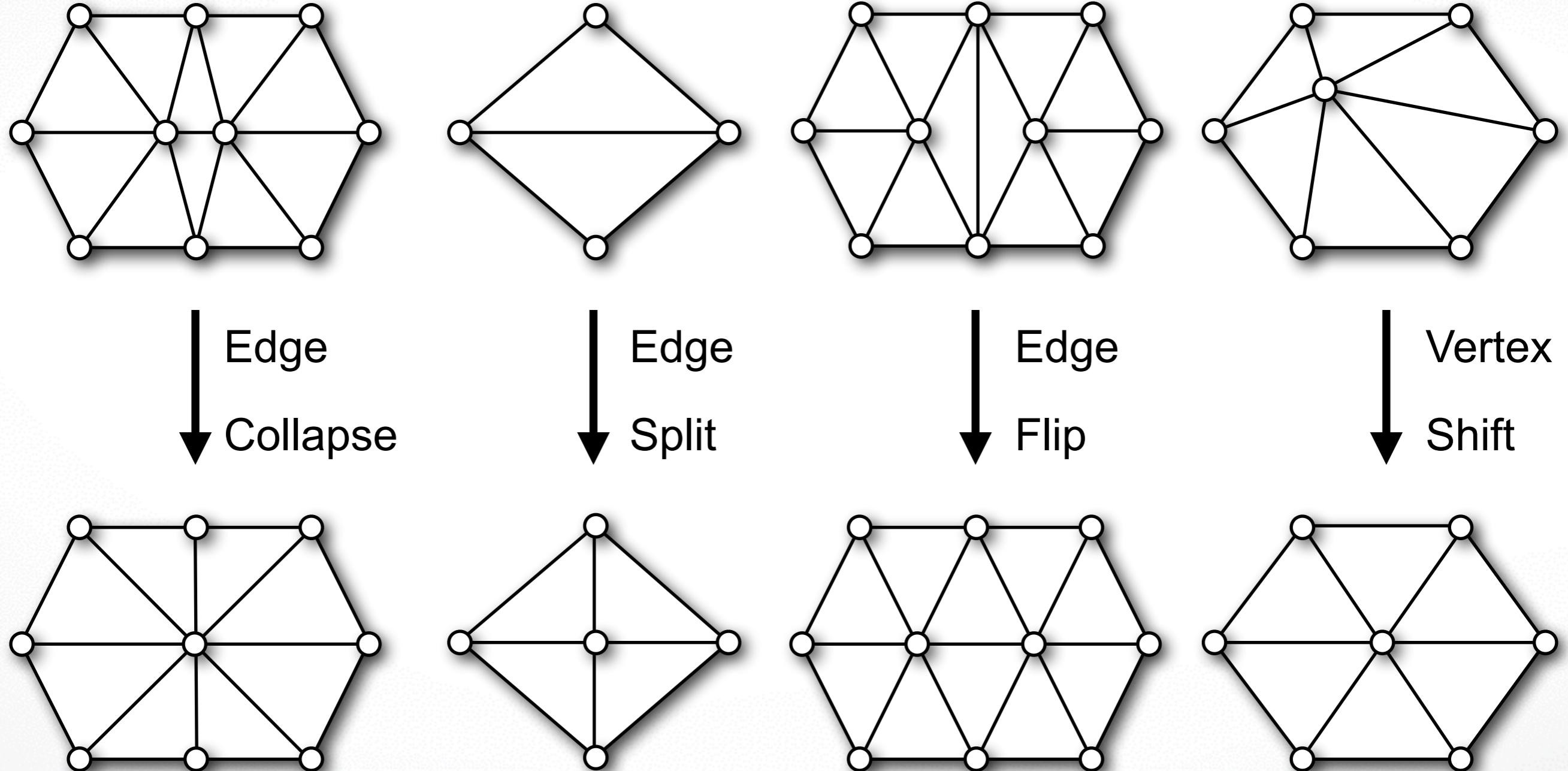
- Simple to implement and robust
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Greedy remeshing

Local remeshing operators



Incremental remeshing

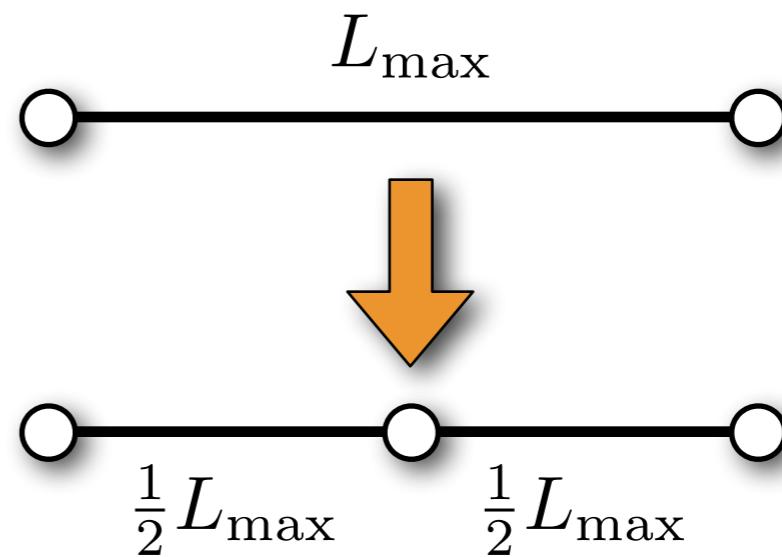
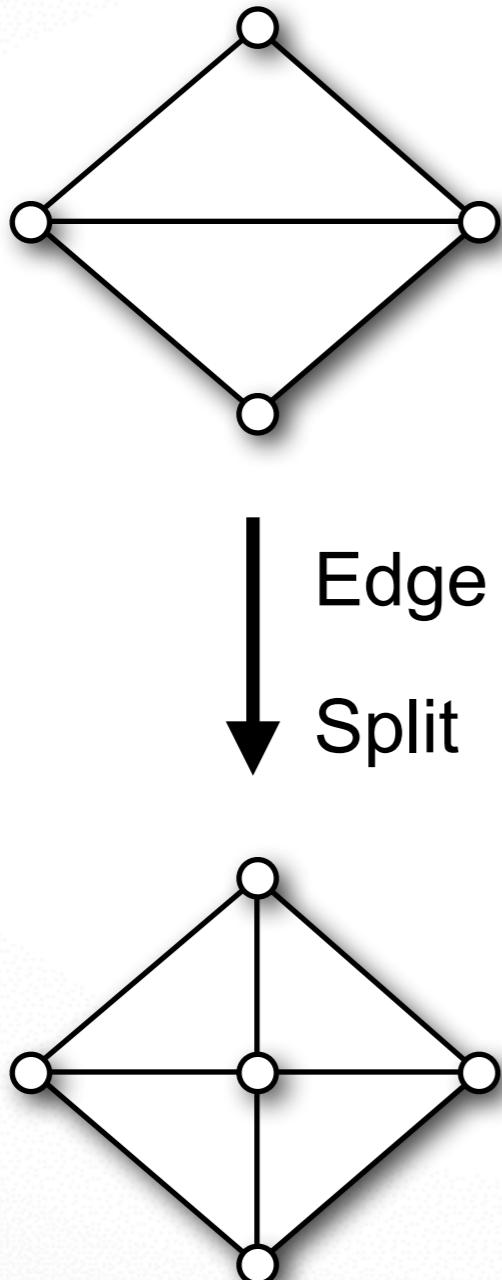
Specify target edge length L

$$L_{\max} = 4/3 * L; L_{\min} = 4/5 * L;$$

Iterate:

1. Split edges longer than L_{\max}
2. Collapse edges shorter than L_{\min}
3. Flip edges to get closer to optimal valence
4. Vertex shift by tangential relaxation
5. Project vertices onto reference mesh

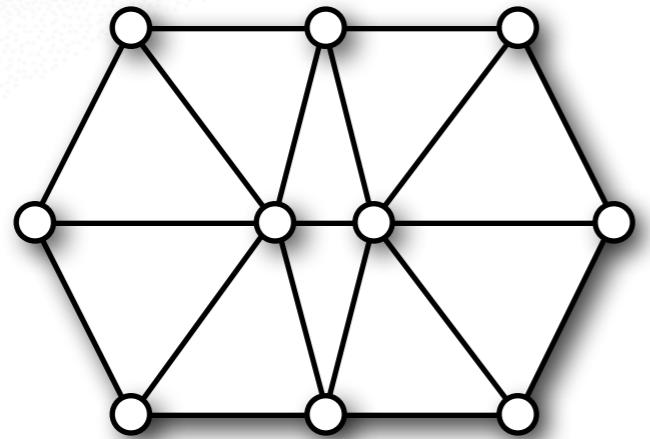
Edge split



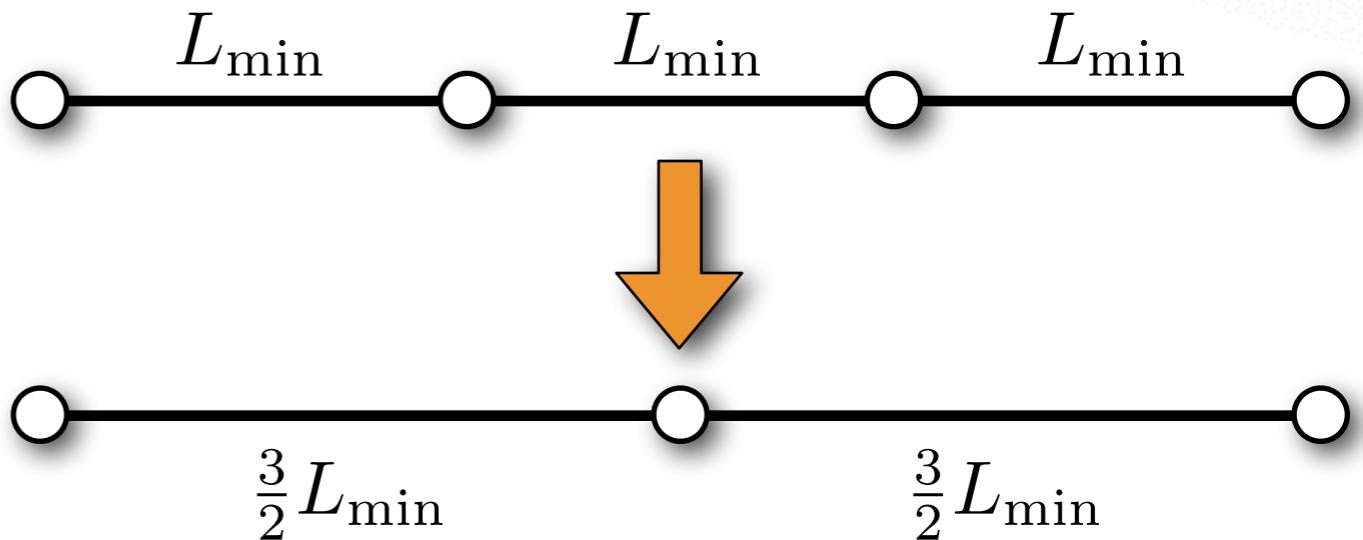
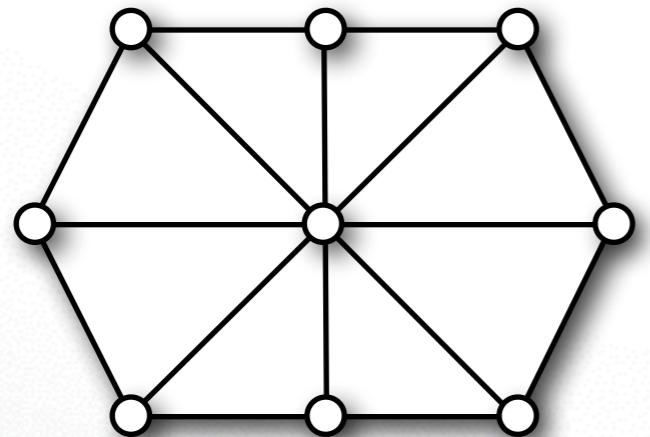
$$\begin{aligned}|L_{\max} - L| &= \left| \frac{1}{2}L_{\max} - L \right| \\ \Rightarrow L_{\max} &= \frac{4}{3}L\end{aligned}$$

Split edges longer than L_{\max}

Edge collapse



↓
Edge
Collapse



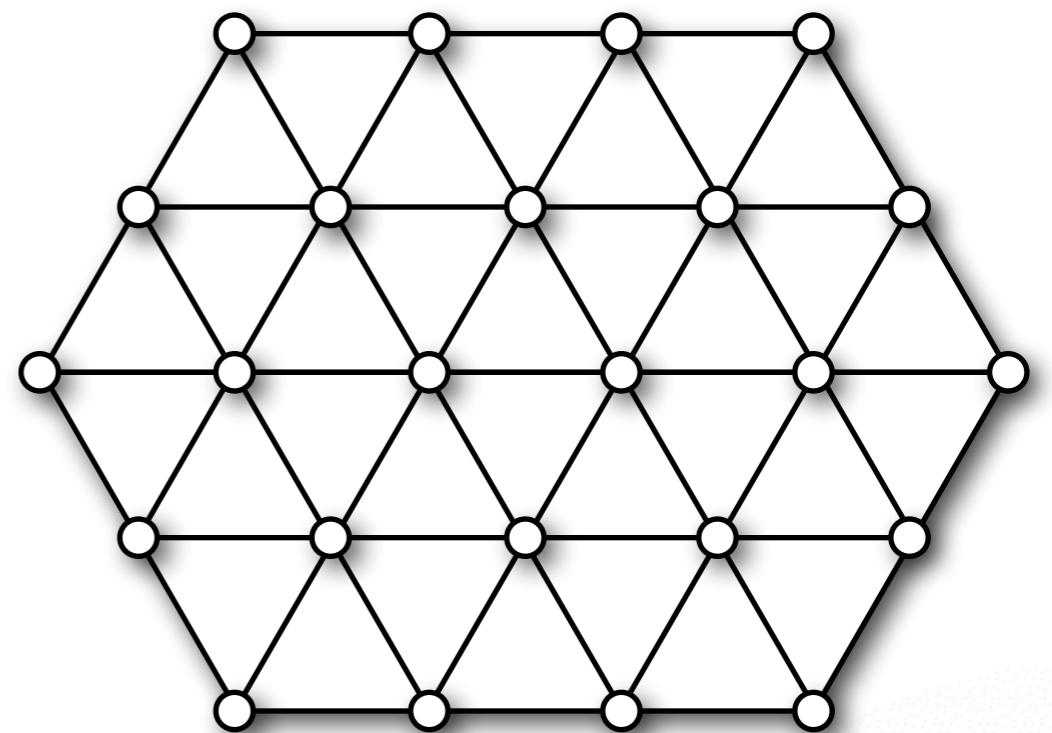
$$\begin{aligned}|L_{\min} - L| &= \left| \frac{3}{2}L_{\min} - L \right| \\ \Rightarrow L_{\min} &= \frac{4}{5}L\end{aligned}$$

Collapse edges shorter than L_{\min}

Edge flip

Optimal valence

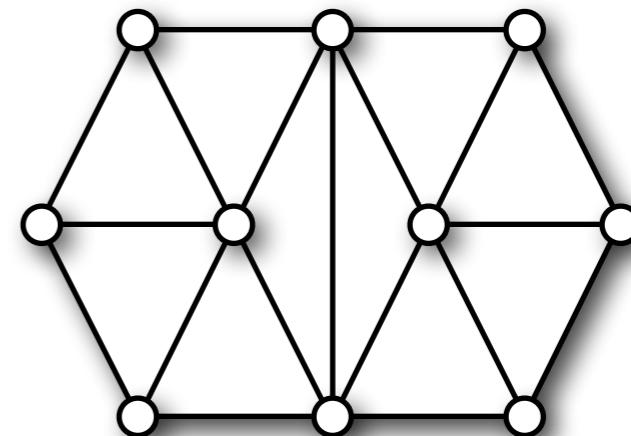
- 6 for interior vertices
- 4 for boundary vertices



Edge flip

Optimal valence

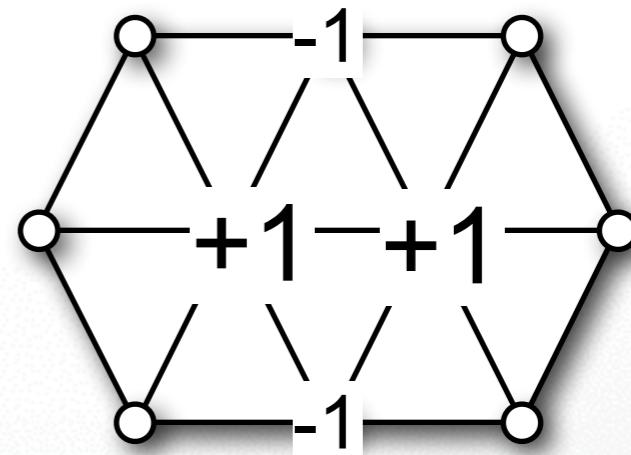
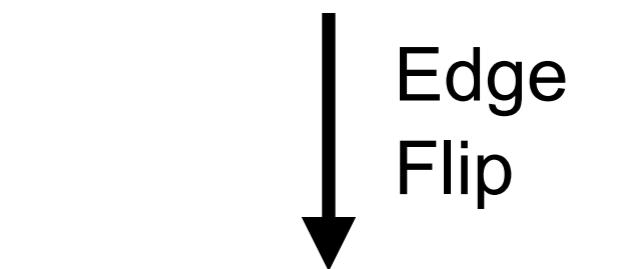
- 6 for interior vertices
- 4 for boundary vertices



Improve valences

- Minimize valence excess

$$\sum_{i=1}^4 (\text{valence}(v_i) - \text{opt_valence}(v_i))^2$$

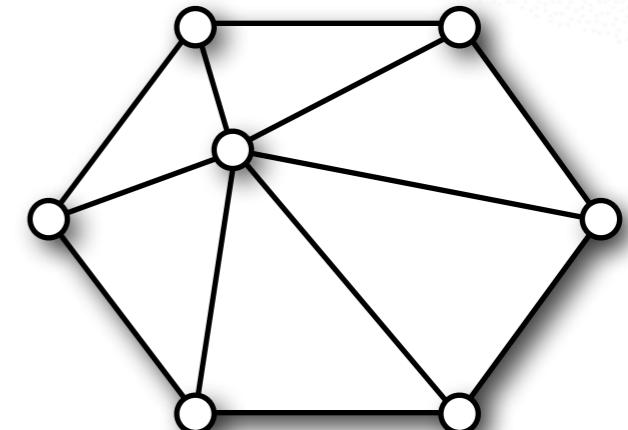


Vertex shift

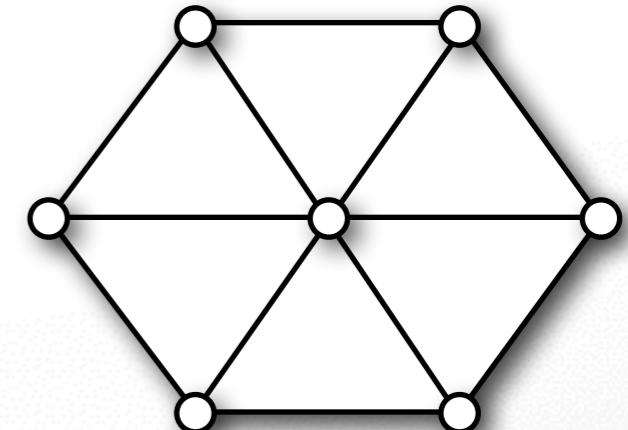
Local “spring” relaxation

- Uniform Laplacian smoothing
- Barycenter of one-ring neighborhood

$$\mathbf{c}_i = \frac{1}{\text{valence}(v_i)} \sum_{j \in N(v_i)} \mathbf{p}_j$$



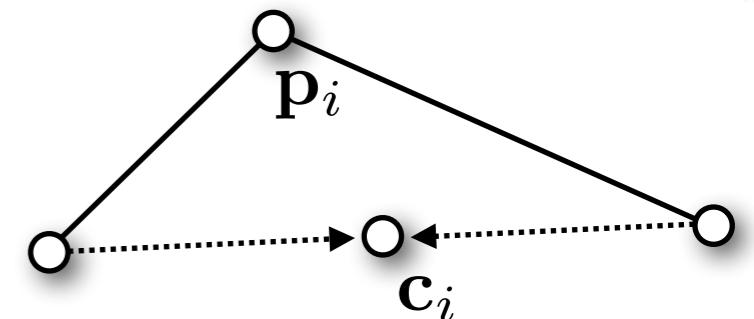
Vertex
Shift



Vertex shift

Local “spring” relaxation

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Vertex shift

Local “spring” relaxation

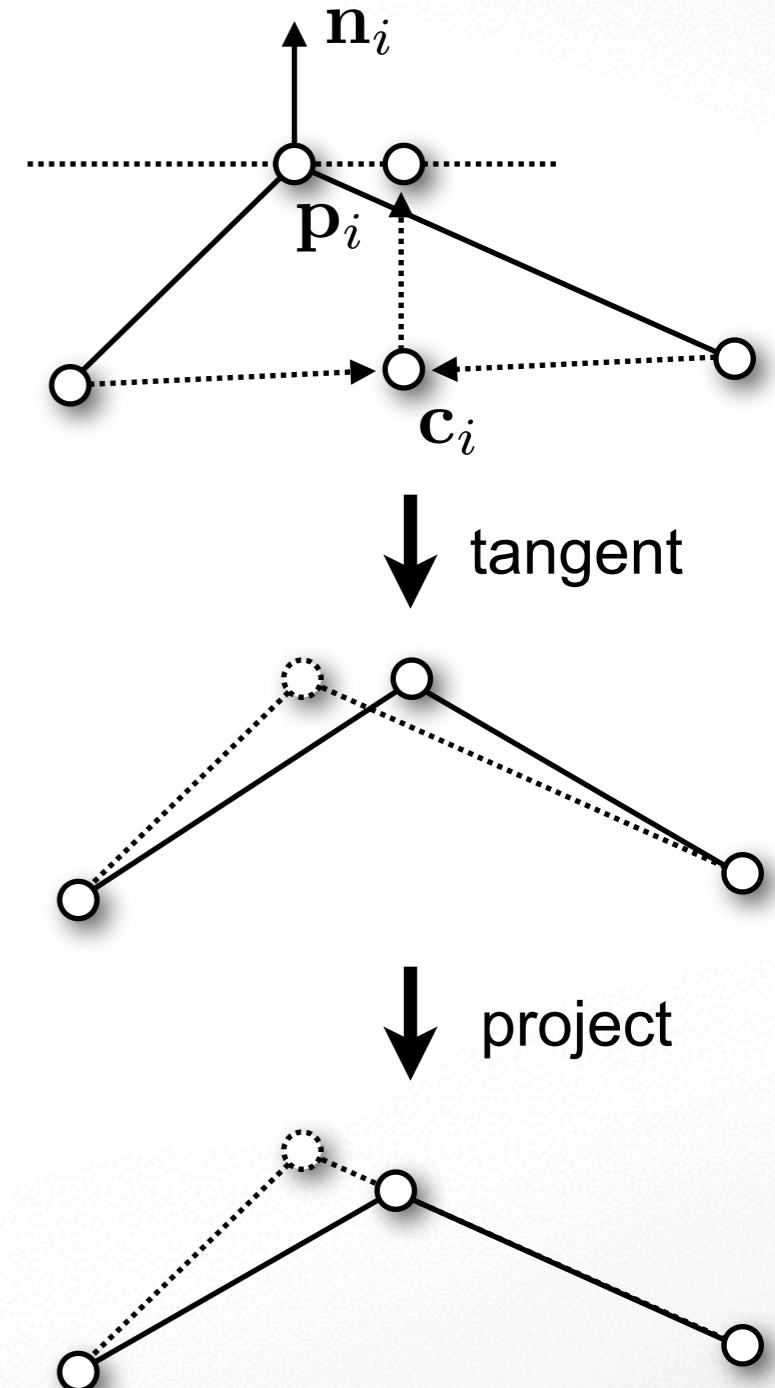
- Uniform Laplacian smoothing
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$$\mathbf{c}_i = \frac{1}{\text{valence}(v_i)} \sum_{j \in N(v_i)} \mathbf{p}_j$$

Keep vertex (approx.) on surface

- Restrict movement to tangent plane

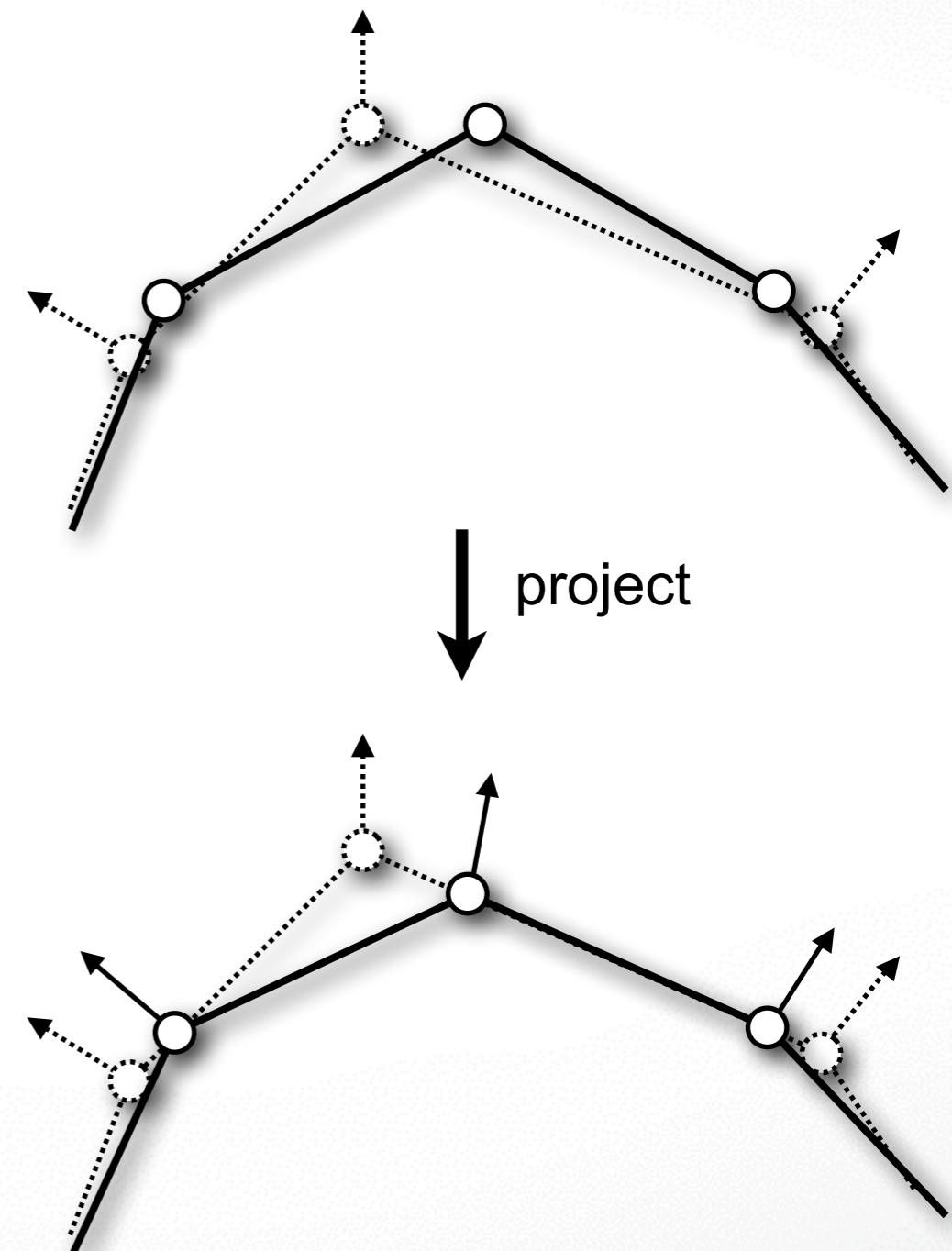
$$\mathbf{p}_i \leftarrow \mathbf{p}_i + \lambda (\mathbf{I} - \mathbf{n}_i \mathbf{n}_i^T) (\mathbf{c}_i - \mathbf{p}_i)$$



Vertex projection

Onto original reference mesh

- Find closest triangle
- Use BSP to accelerate $\rightarrow O(\log n)$
- Barycentric interpolation to compute position & normal



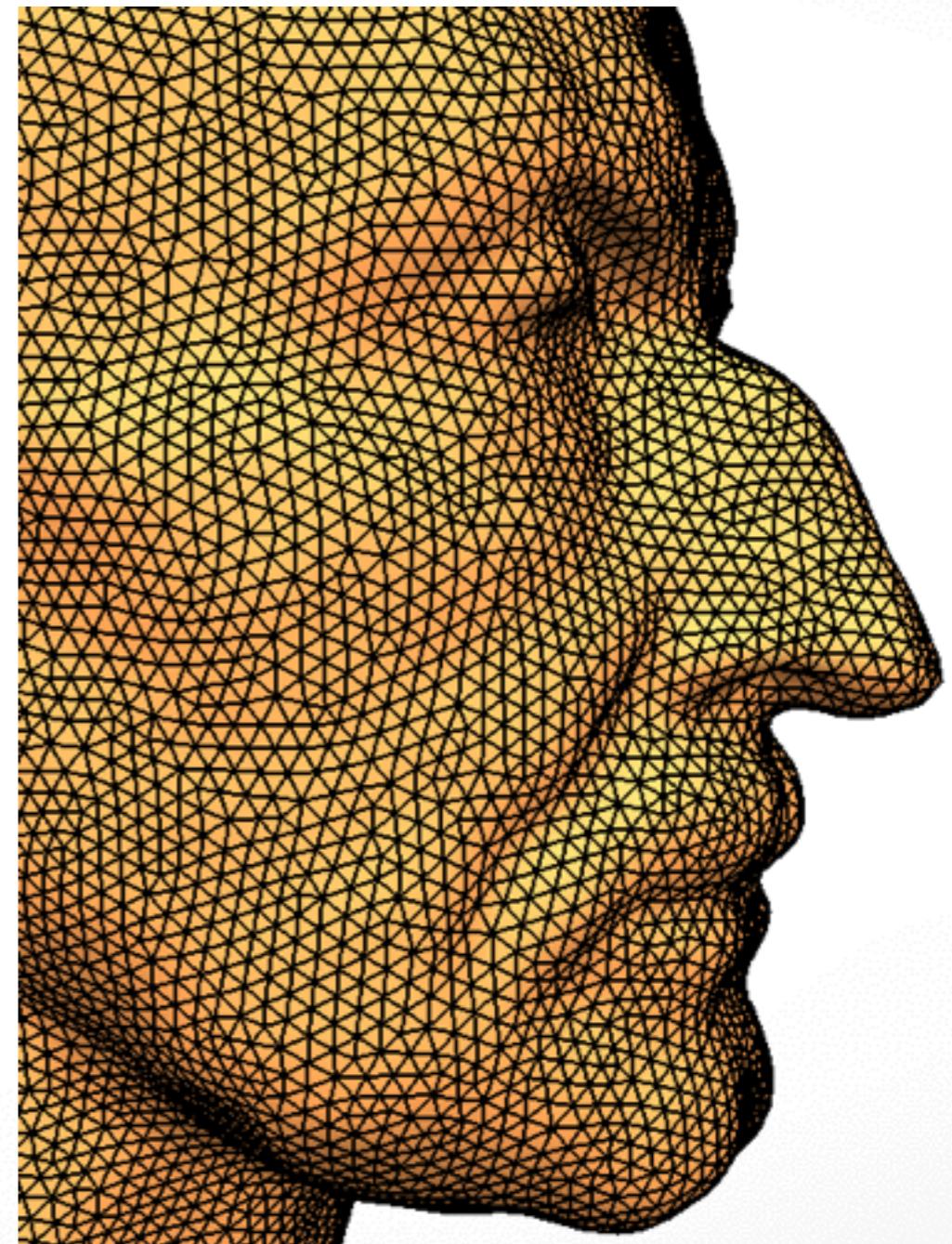
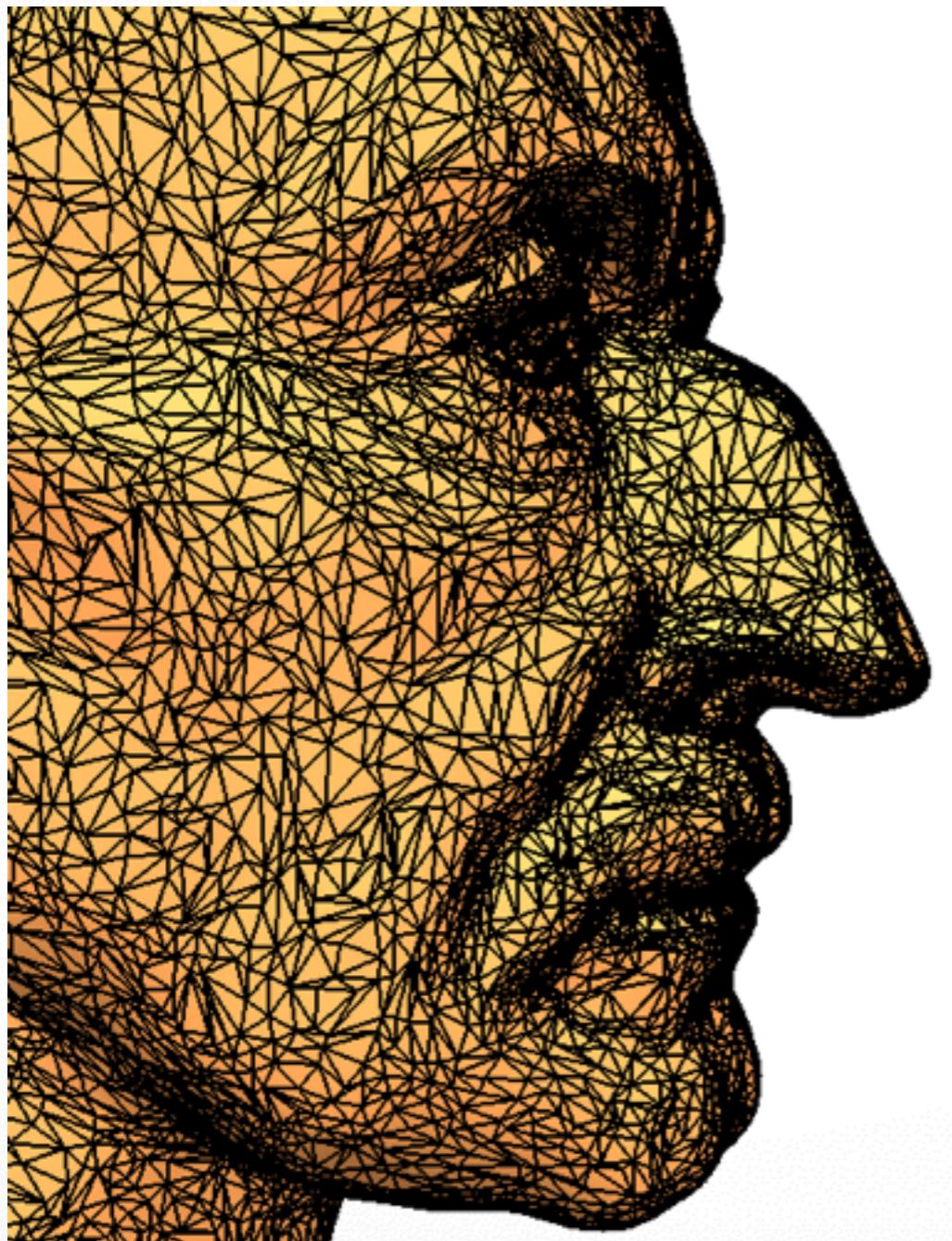
Incremental remeshing

Specify target edge length L

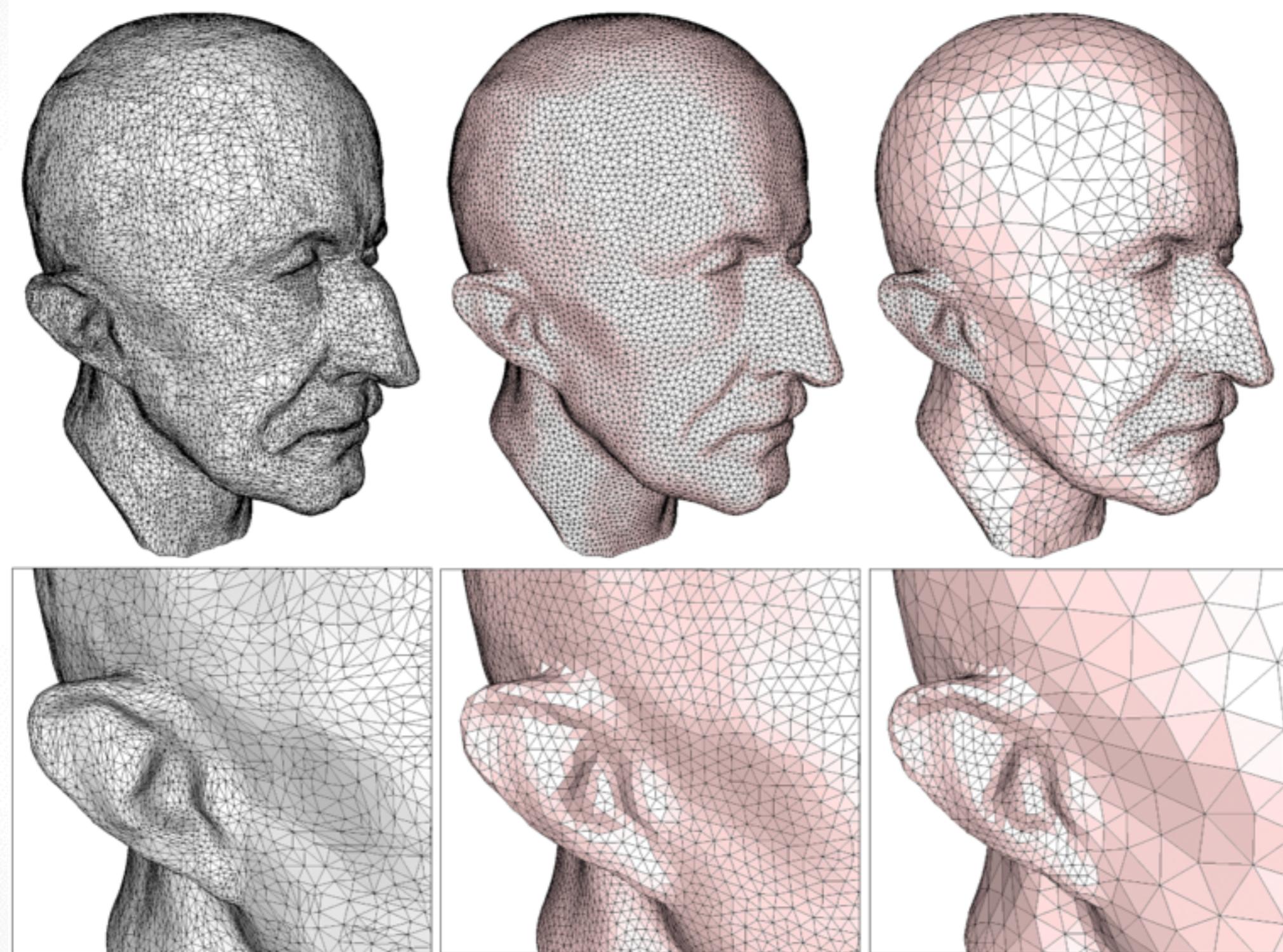
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Remeshing result

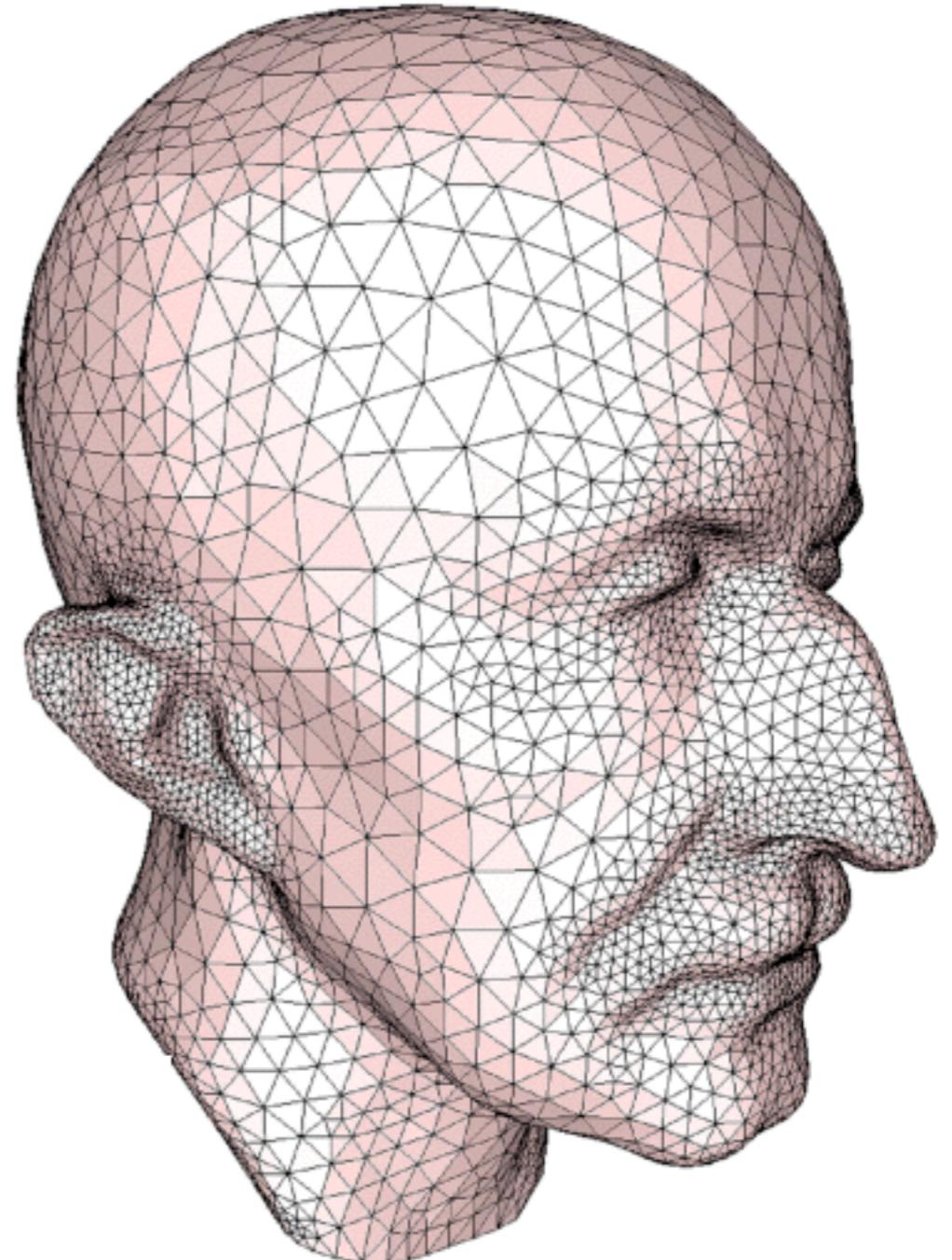


Adaptive remeshing

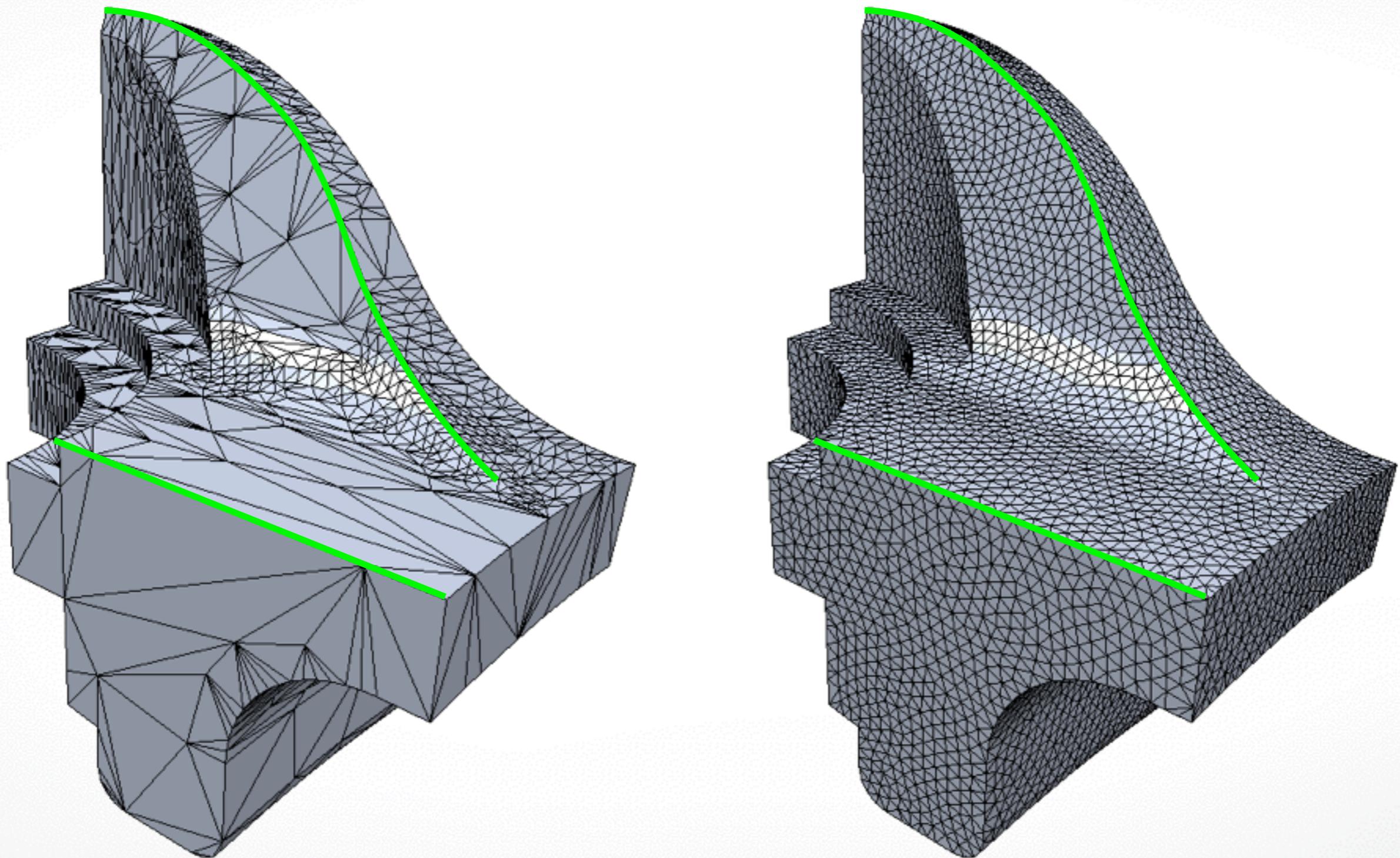


Adaptive remeshing

- Compute maximum principle curvature on reference mesh
- Determine local target edge length from max-curvature
- Adjust edge split / collapse criteria accordingly



Feature preservation



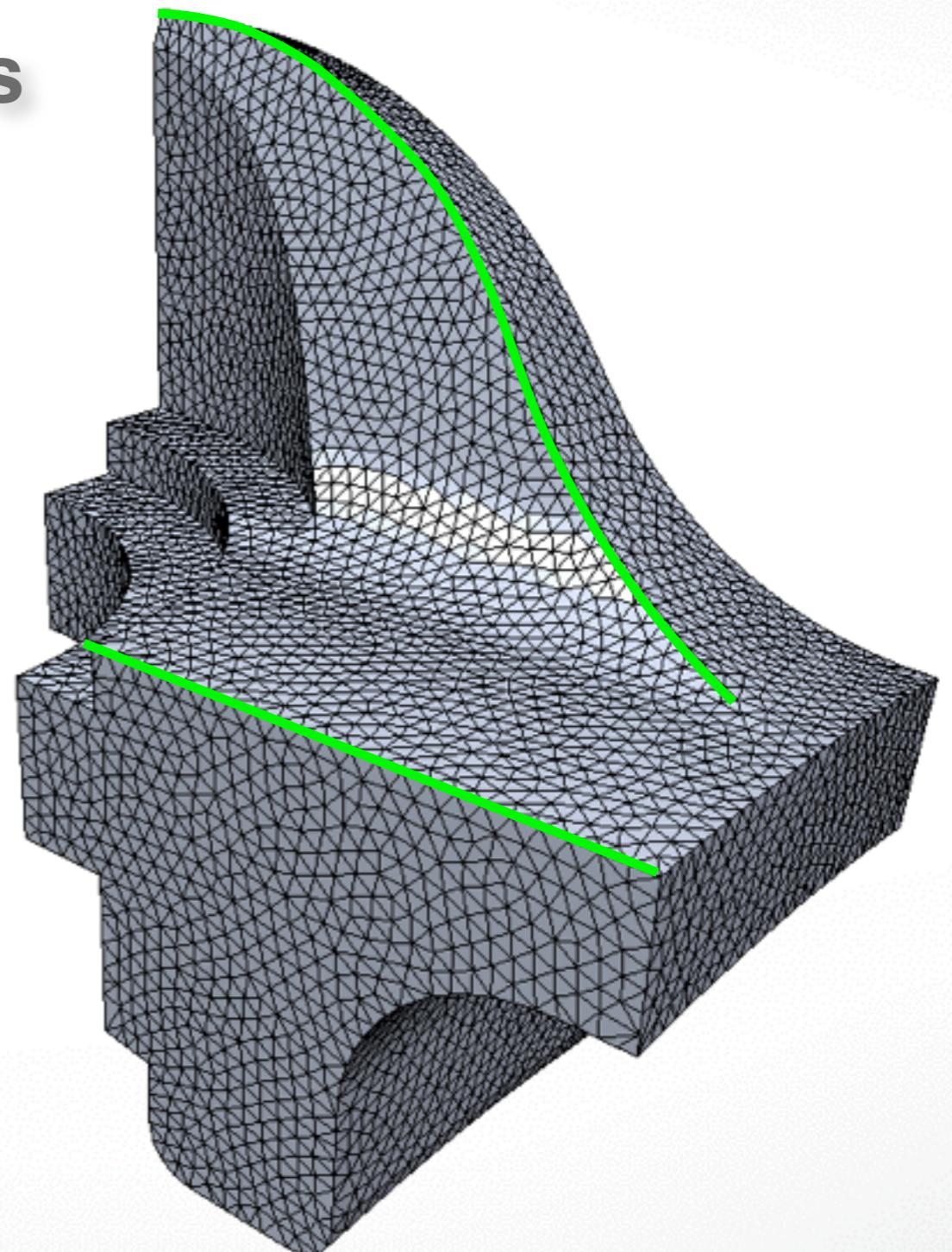
Feature preservation

Define feature edges / vertices

- Large dihedral angles
- Material boundaries

Adjust local operators

- Do not touch corner vertices
- Do not flip feature edges
- Collapse along features
- Univariate smoothing
- Project to feature curves



Isotropic remeshing

Incremental remeshing

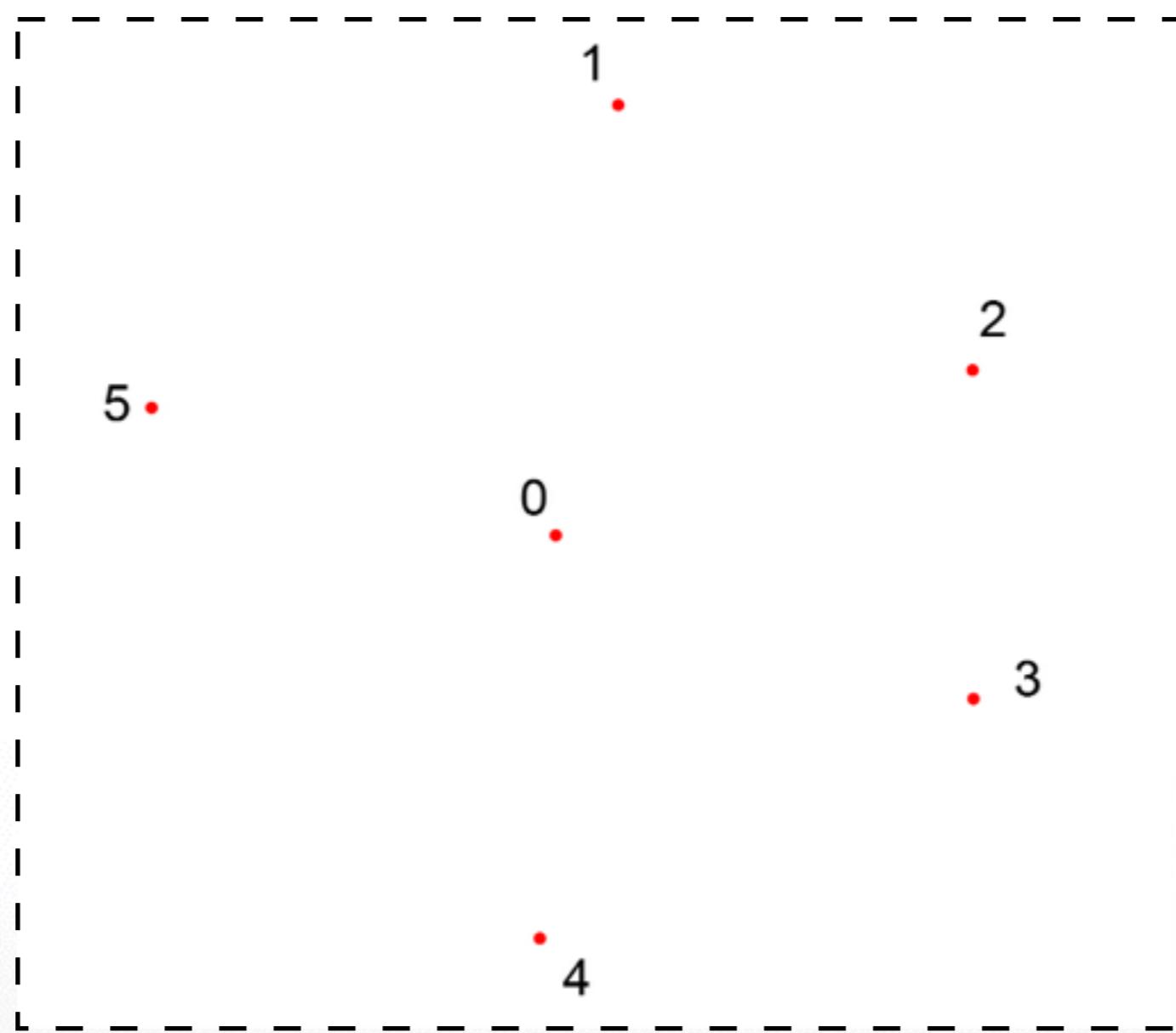
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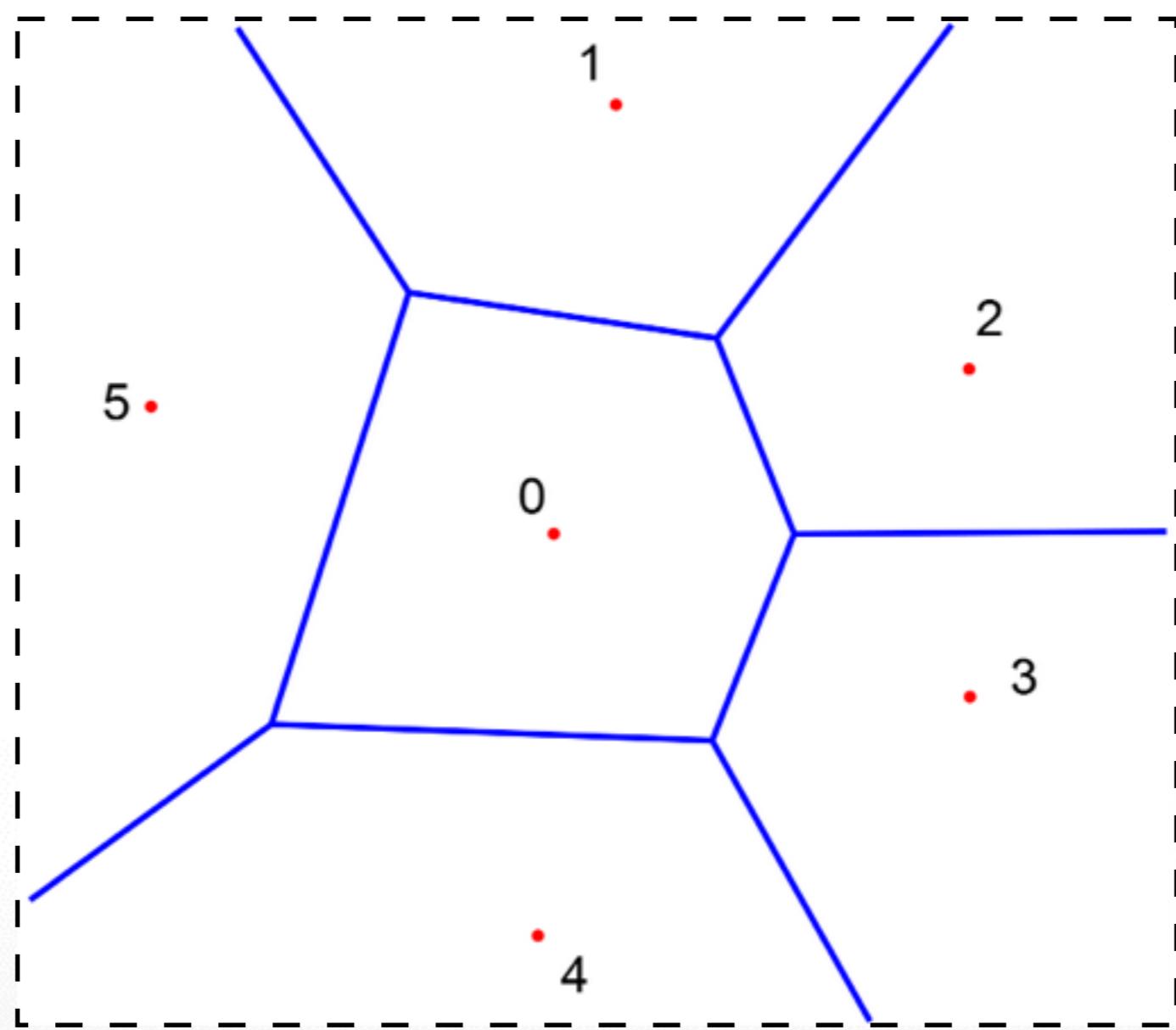
Greedy remeshing

Voronoi Diagram



Voronoi Diagram

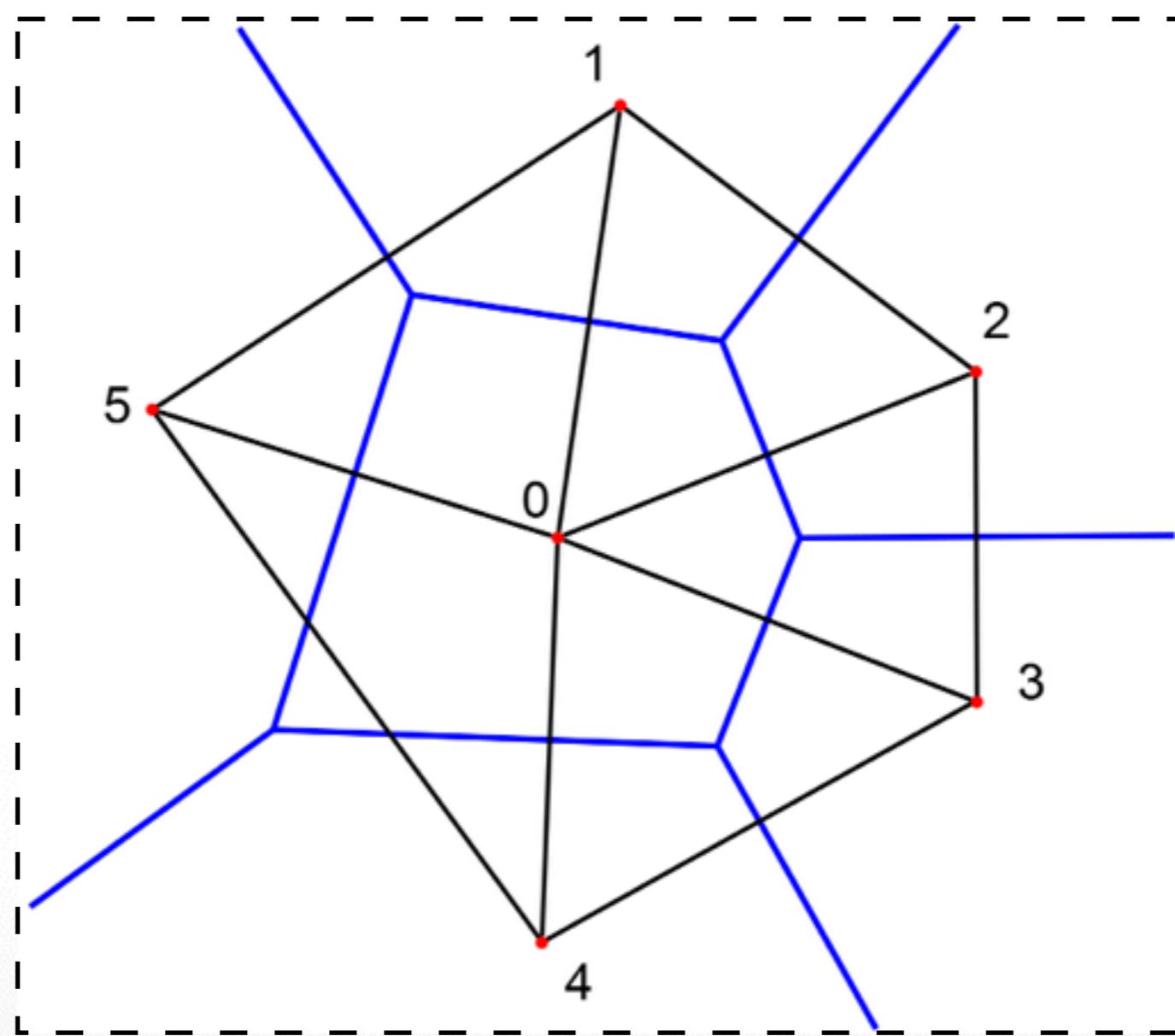
Divide space into a number of cells



Voronoi Diagram

Divide space into a number of cells

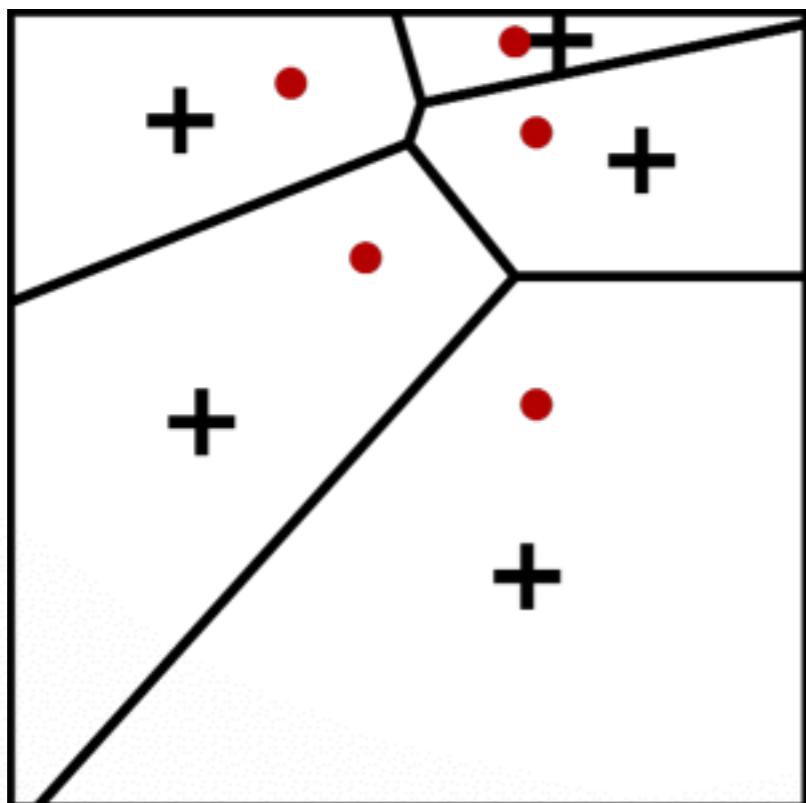
Dual graph: Delaunay triangulation



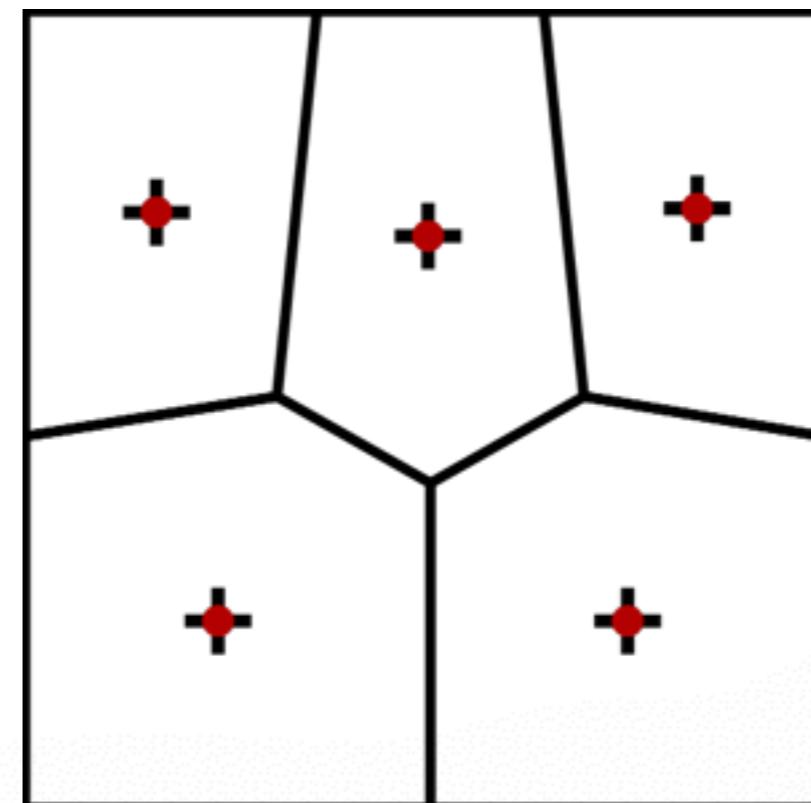
Centroidal Voronoi Diagram

For each cell

The generating point ● = mass of center +



non CVD



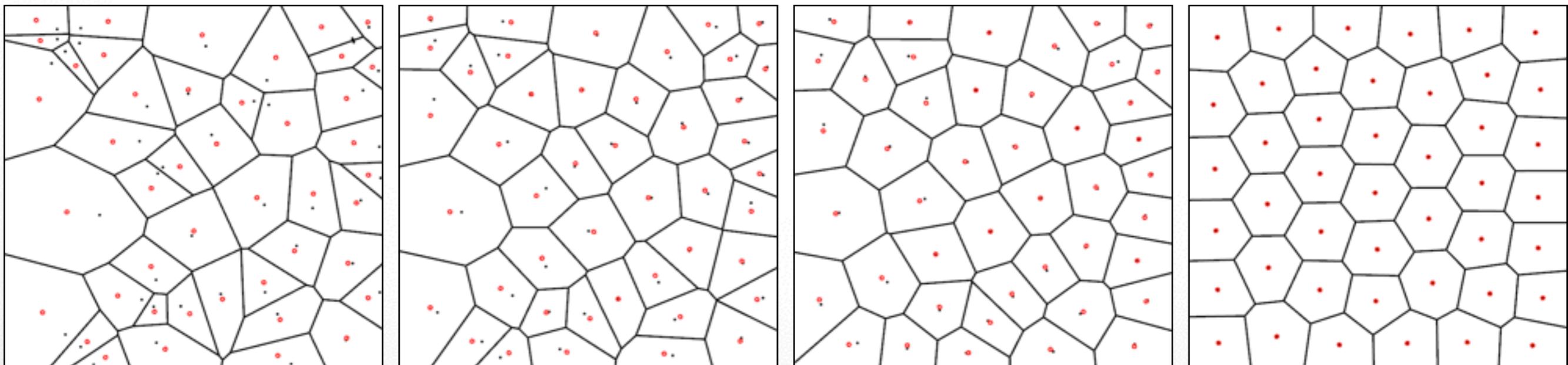
CVD

Centroidal Voronoi Diagram

Compute CVD by Lloyd relaxation

1. Compute Voronoi diagram of given points \mathbf{p}_i
2. Move points \mathbf{p}_i to centroids \mathbf{c}_i of their Voronoi cells V_i
3. Repeat steps 1 and 2 until satisfactory convergence

$$\mathbf{p}_i \leftarrow \mathbf{c}_i = \frac{\int_{V_i} \mathbf{x} \cdot \rho(\mathbf{x}) \, d\mathbf{x}}{\int_{V_i} \rho(\mathbf{x}) \, d\mathbf{x}}$$



Centroidal Voronoi Diagram

Compute CVD by Lloyd relaxation

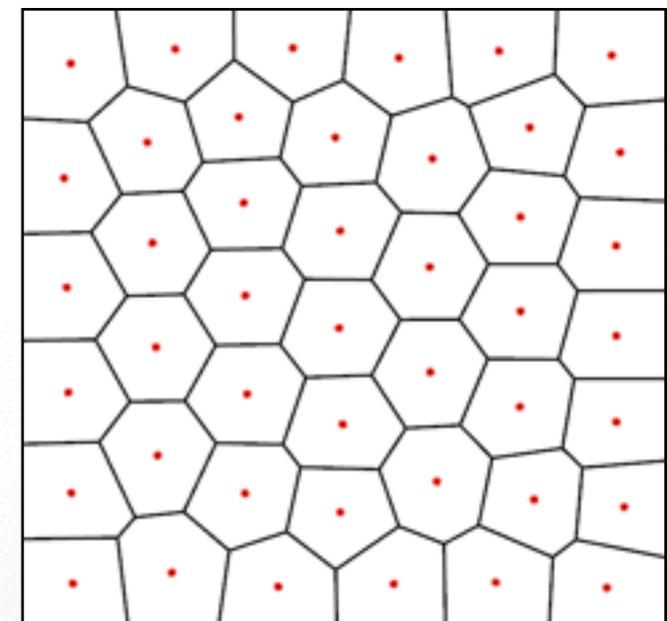
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CVD maximizes compactness

- Minimize the energy:

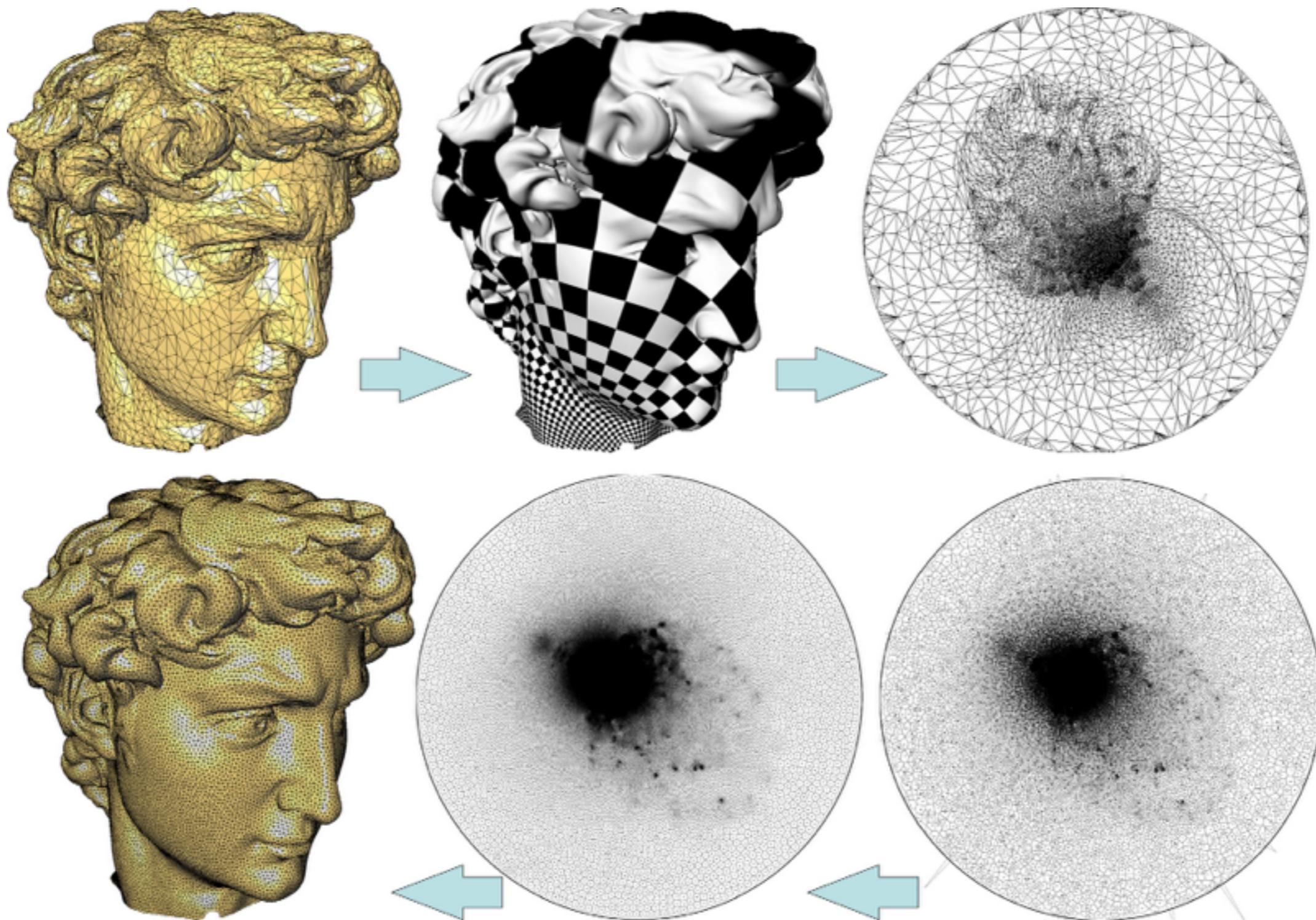
$$\sum_i \int_{V_i} \rho(\mathbf{x}) \|\mathbf{x} - \mathbf{p}_i\|^2 \, d\mathbf{x} \rightarrow \min$$



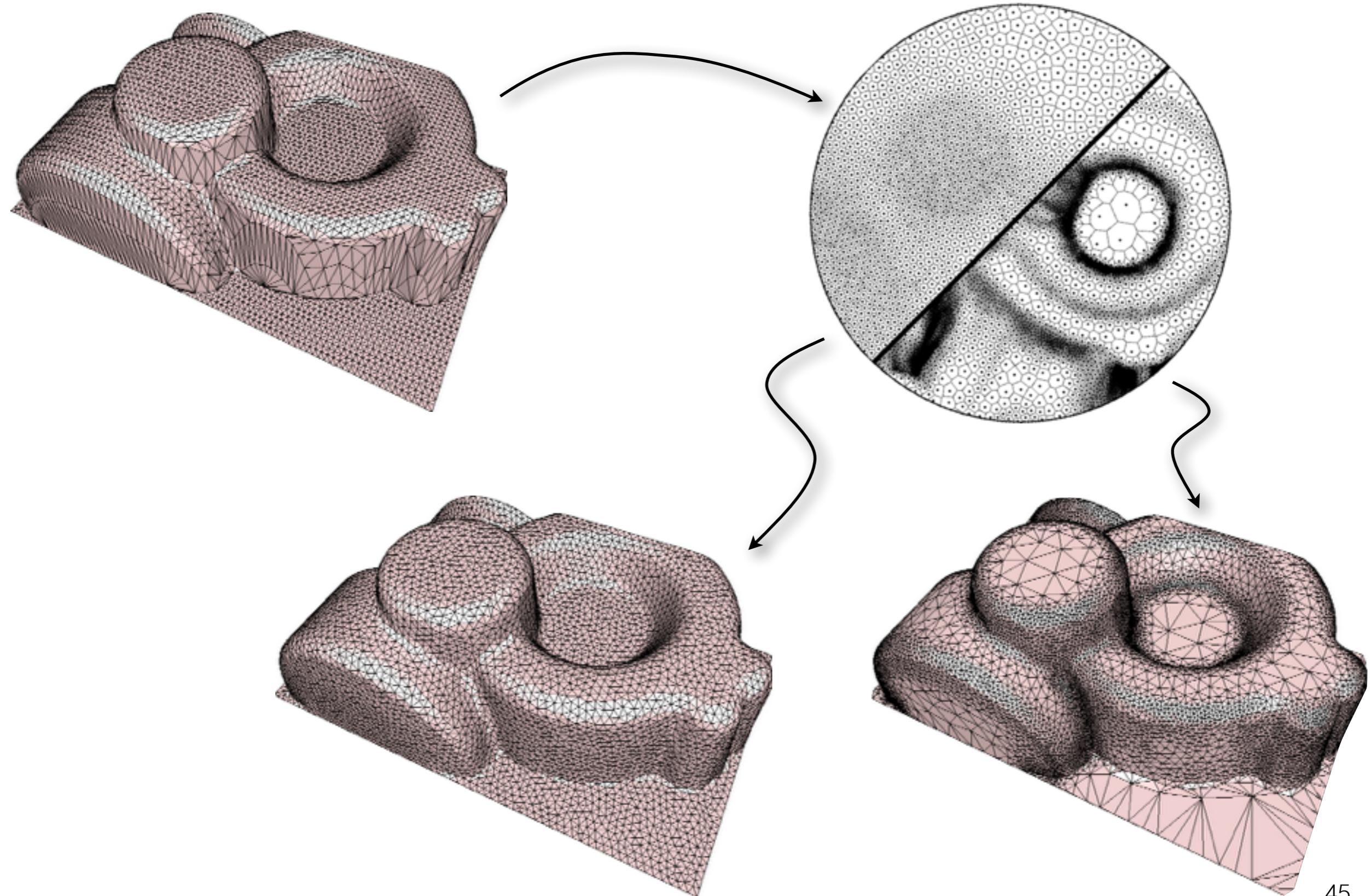
Variational remeshing

- 1. Conformal parameterization of input mesh**
- 2. Compute local density**
- 3. Perform in 2D parameter space**
 - A. Randomly sample according to local density
 - B. Compute CVD by Lloyd relaxation
- 4. Lift 2D Delaunay triangulation to 3D**

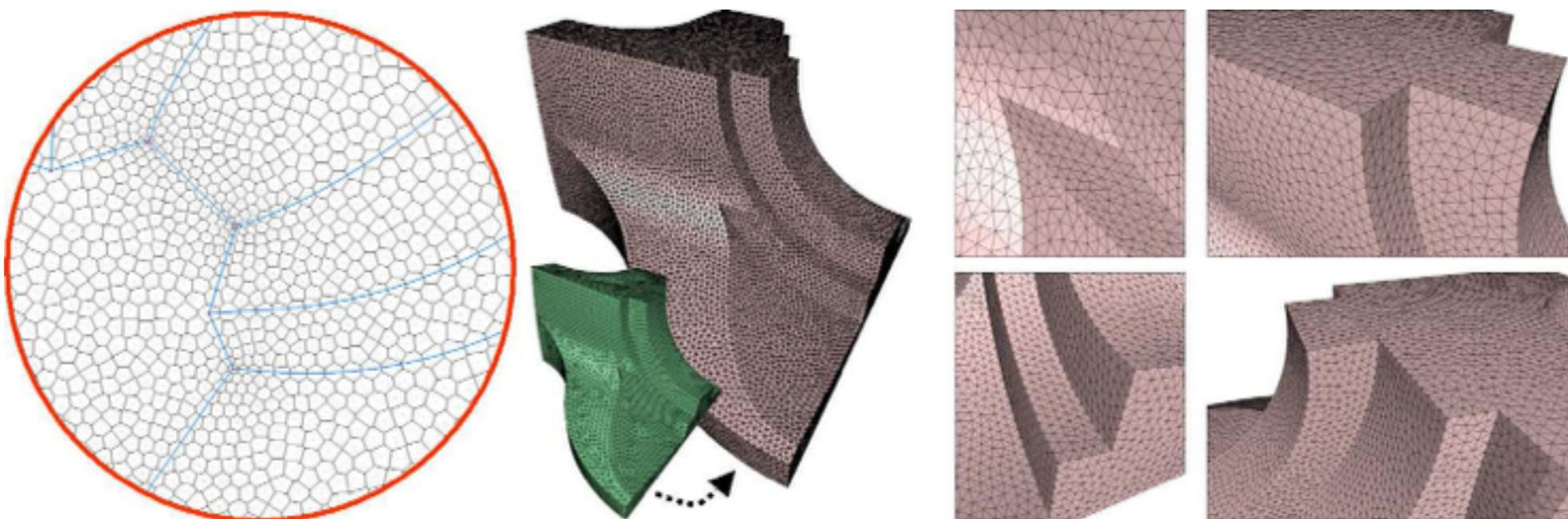
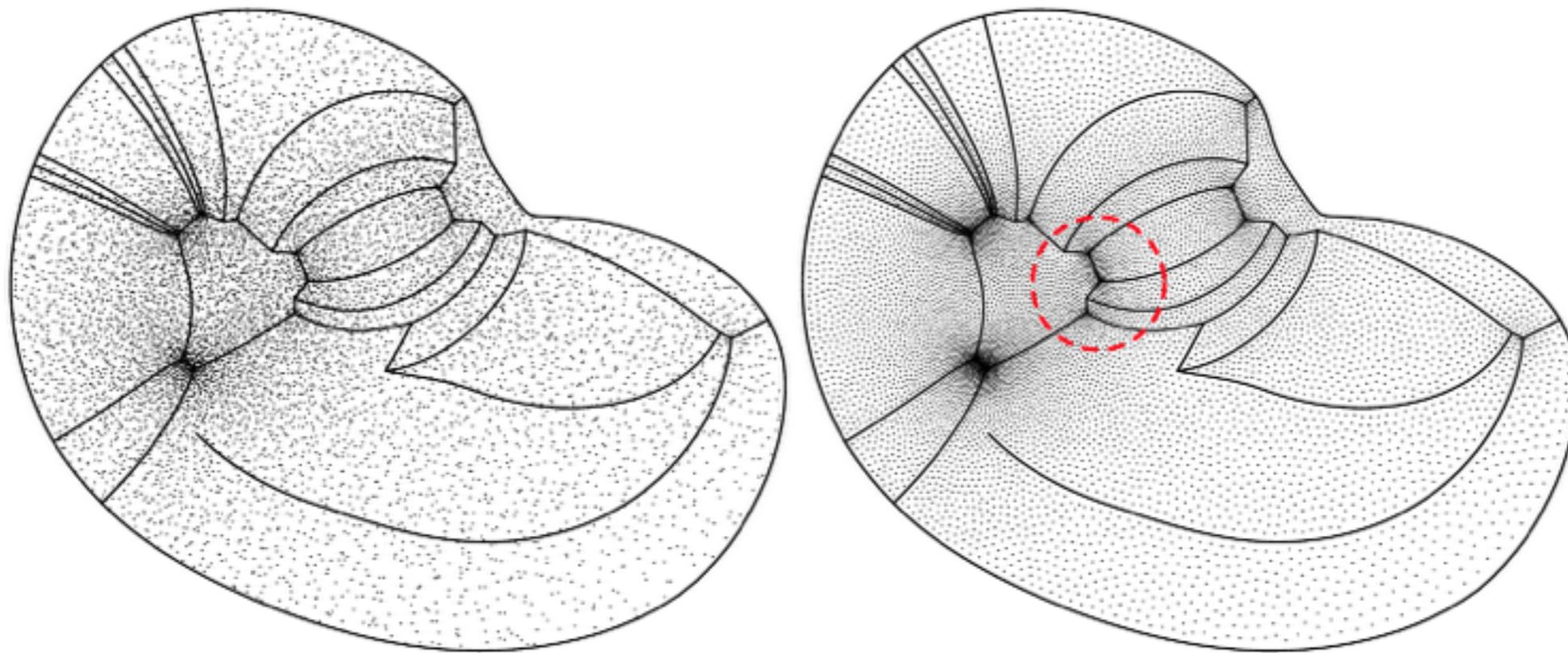
Variational remeshing



Adaptive remeshing



Feature preservation



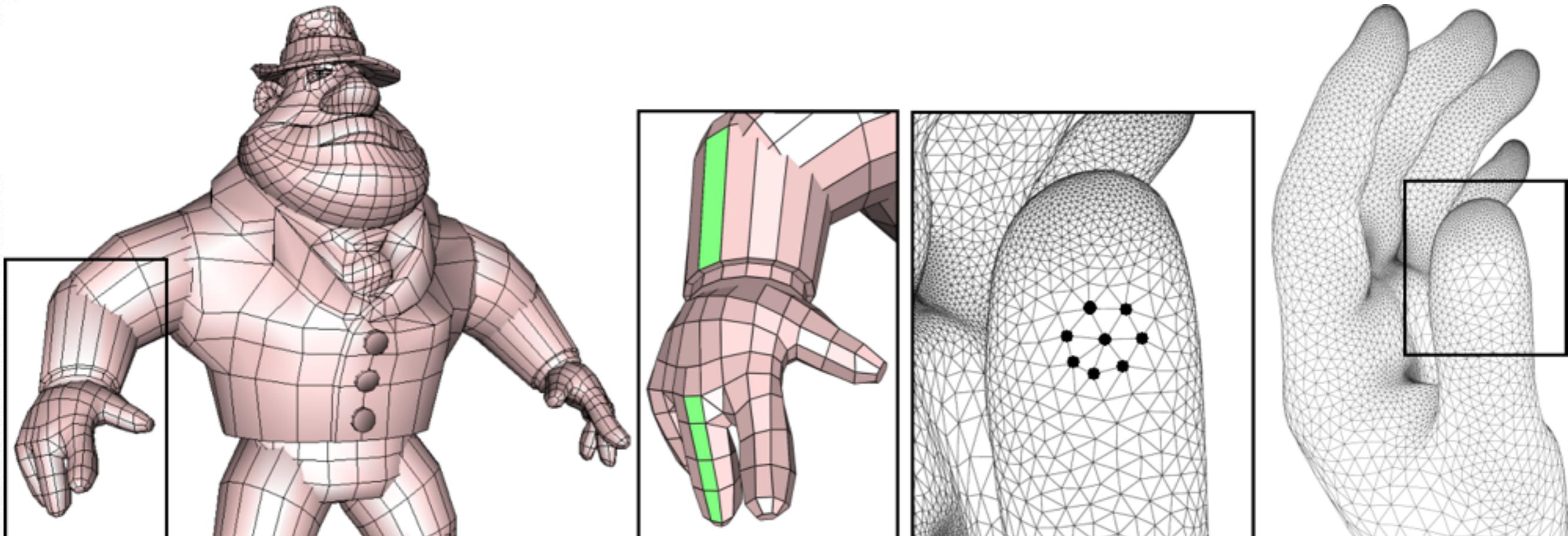
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 - Isotropic remeshing
 - **Anisotropic remeshing**

Anisotropic remeshing

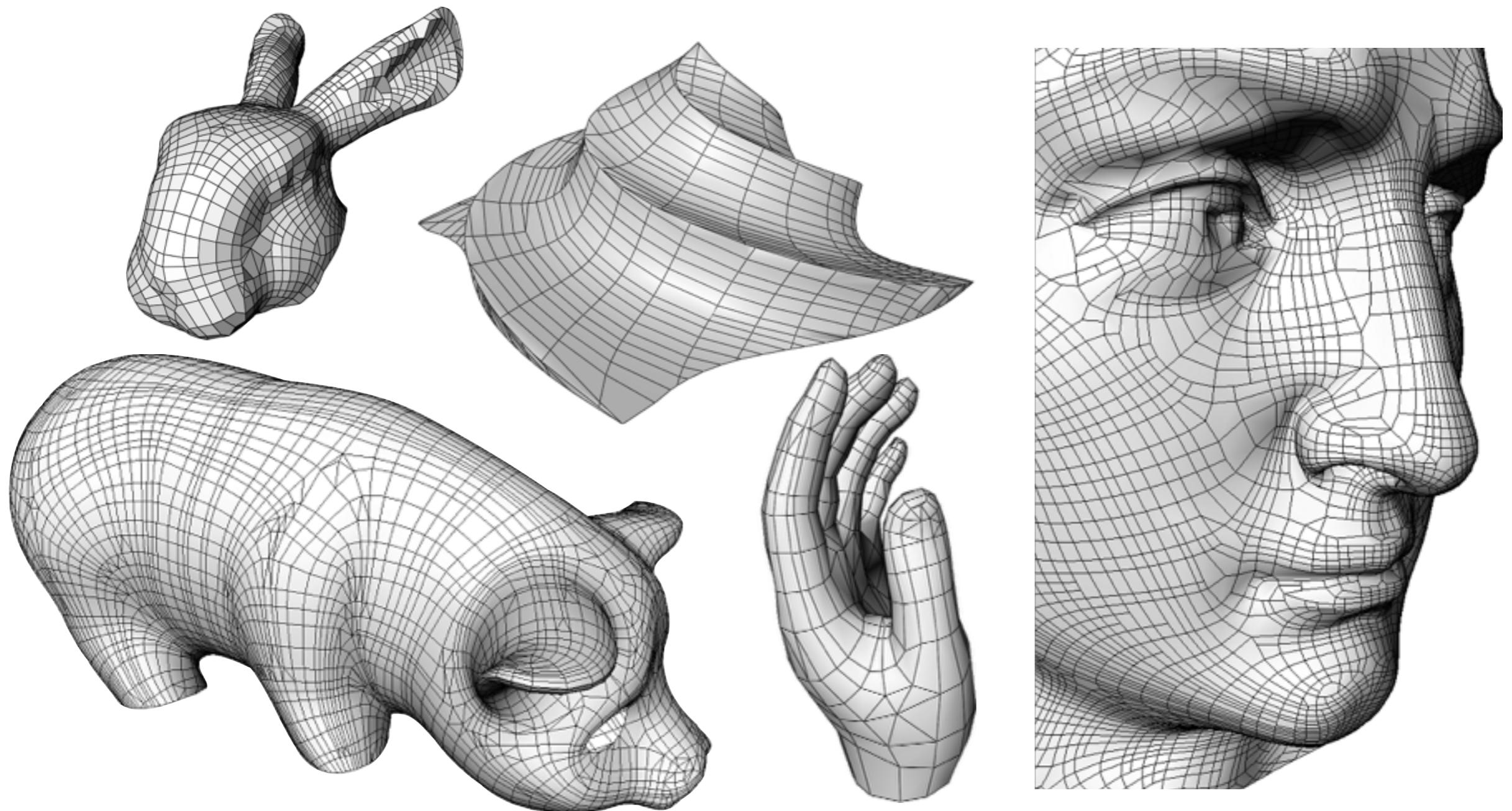
Artist-designed models

- Conform to the anisotropy of a surface



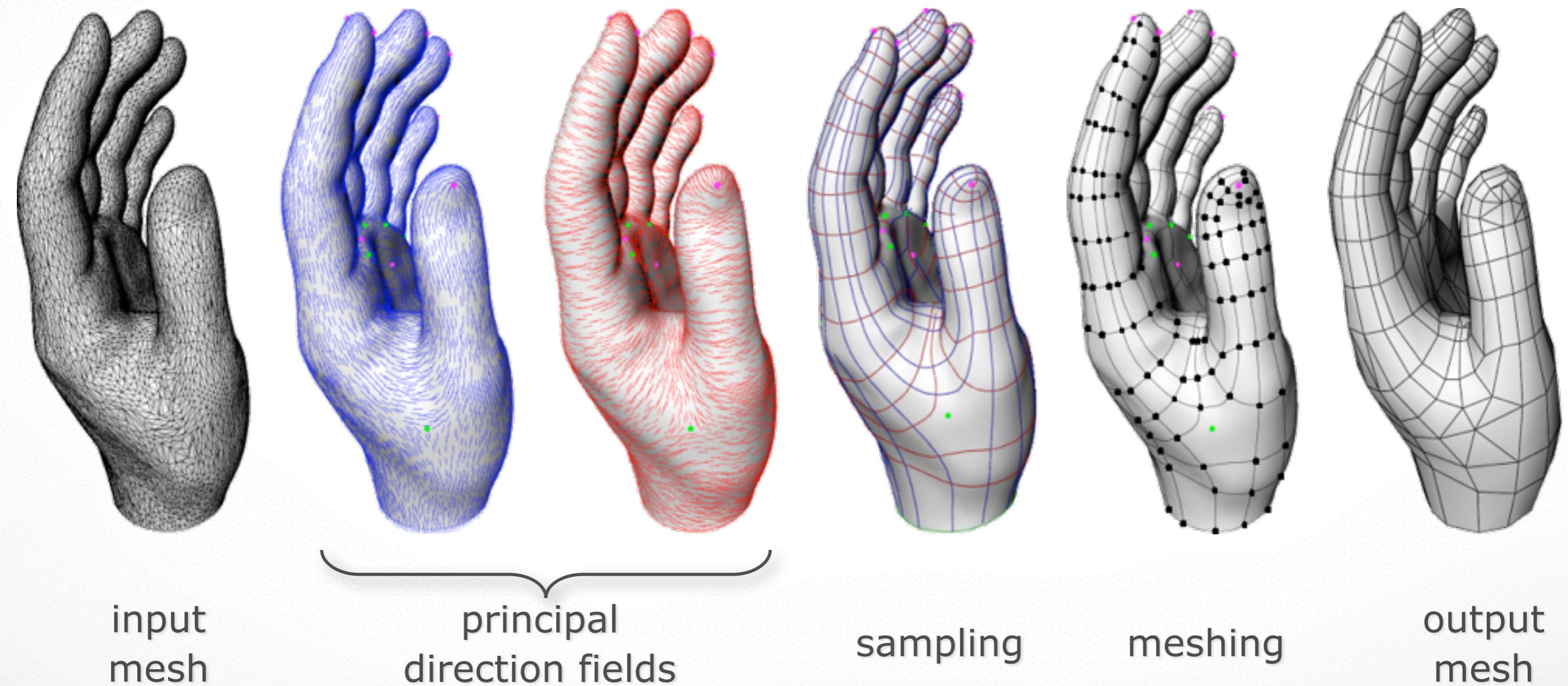
Anisotropic remeshing

[Alliez et al. 2003] *Anisotropic Polygonal Remeshing.*



Anisotropic remeshing

[Alliez et al. 2003] *Anisotropic Polygonal Remeshing.*



input
mesh

principal
direction fields

sampling

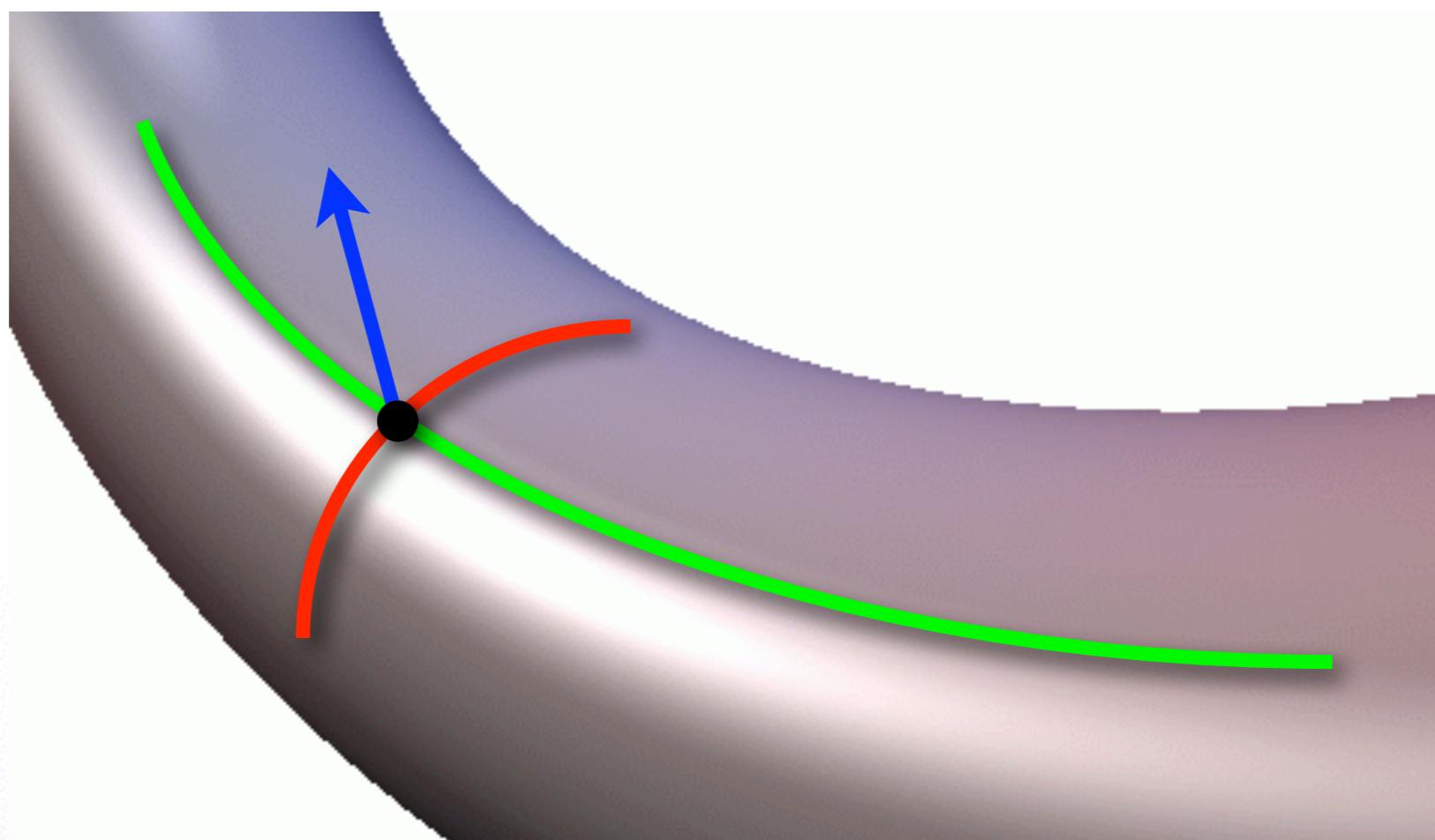
meshing

output
mesh

Anisotropy

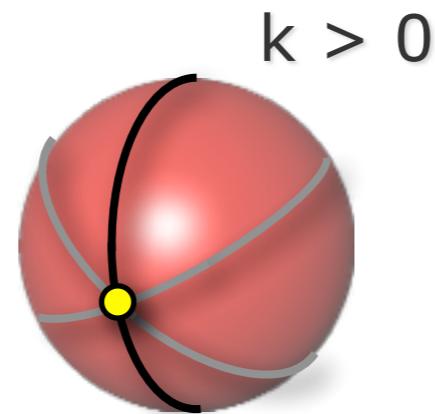
Differential geometry

- A local *orthogonal* frame: min/max curvature directions and normal

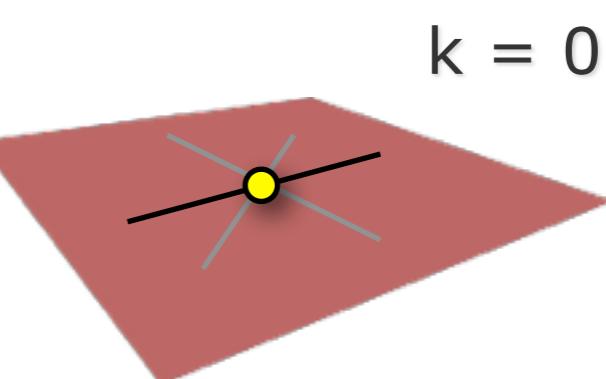


3D curvature tensor

Isotropic



$$k > 0$$

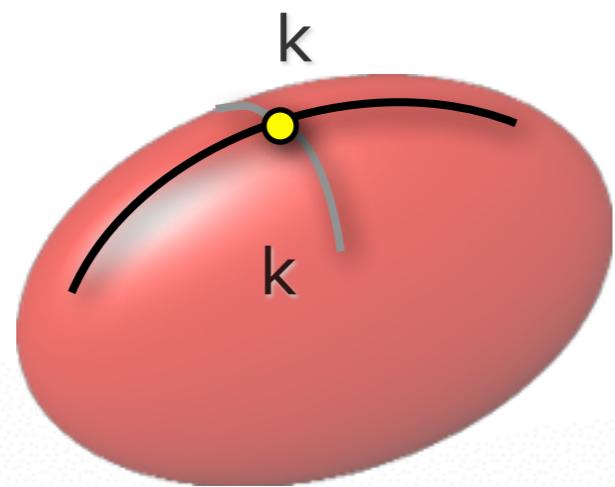


$$k = 0$$

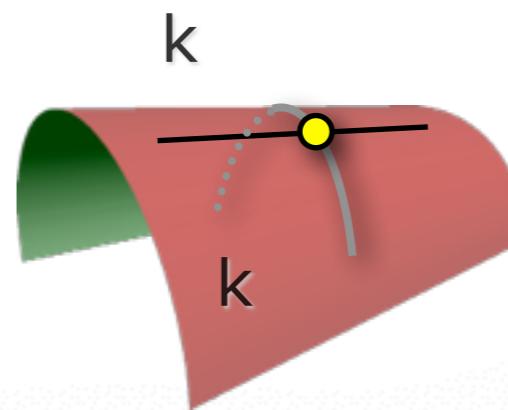
spherical

Anisotropic

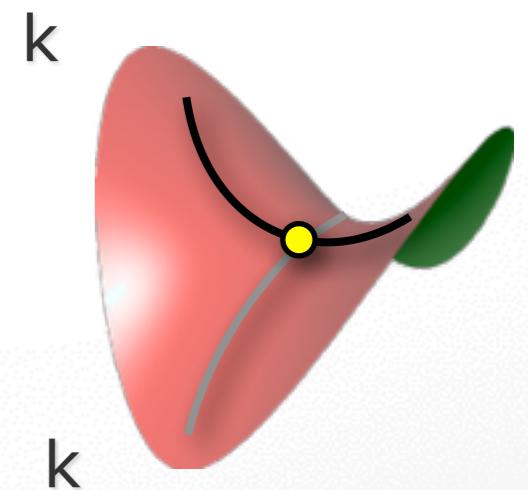
2 principal directions



elliptic

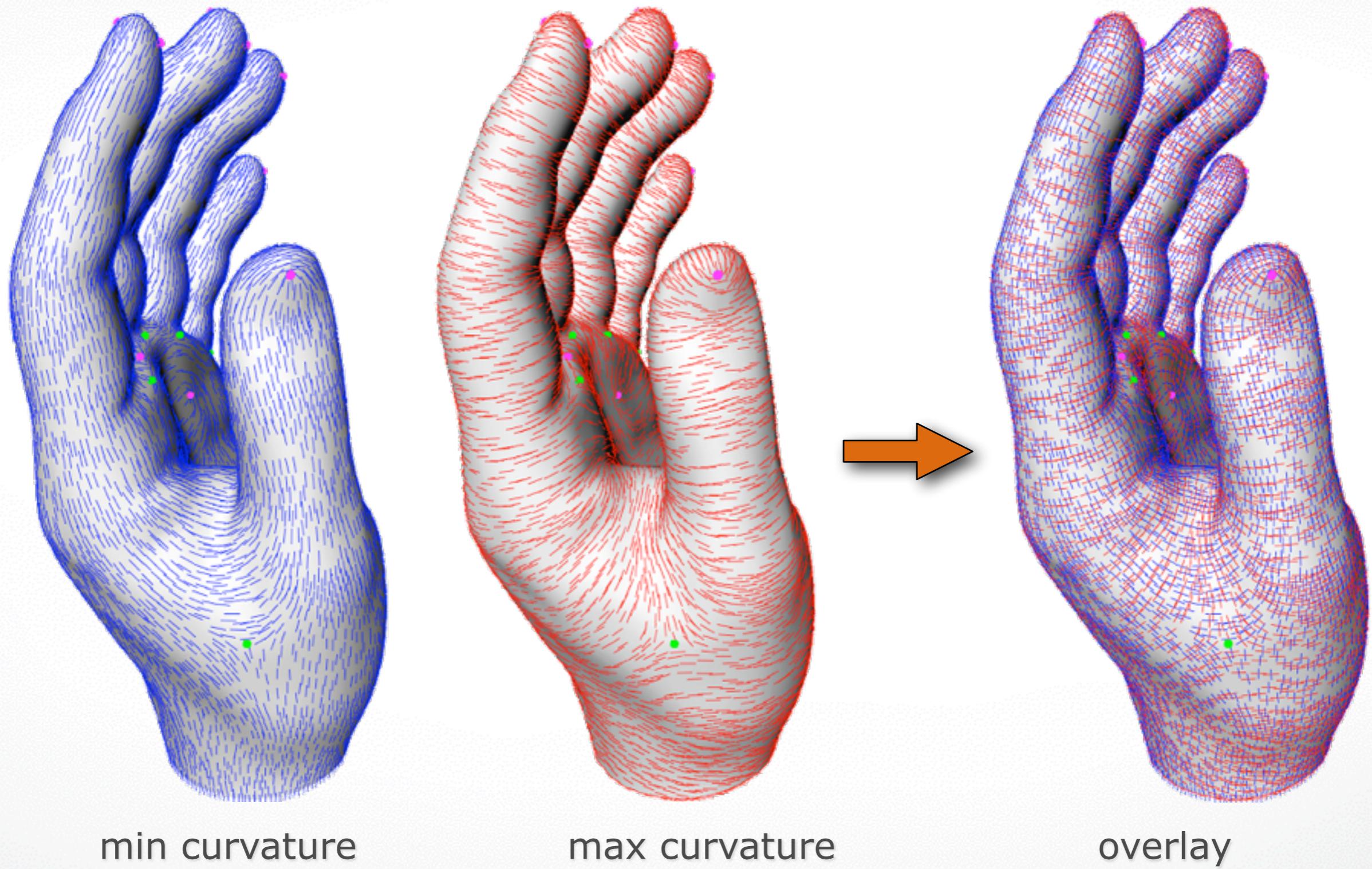


hyperbolic

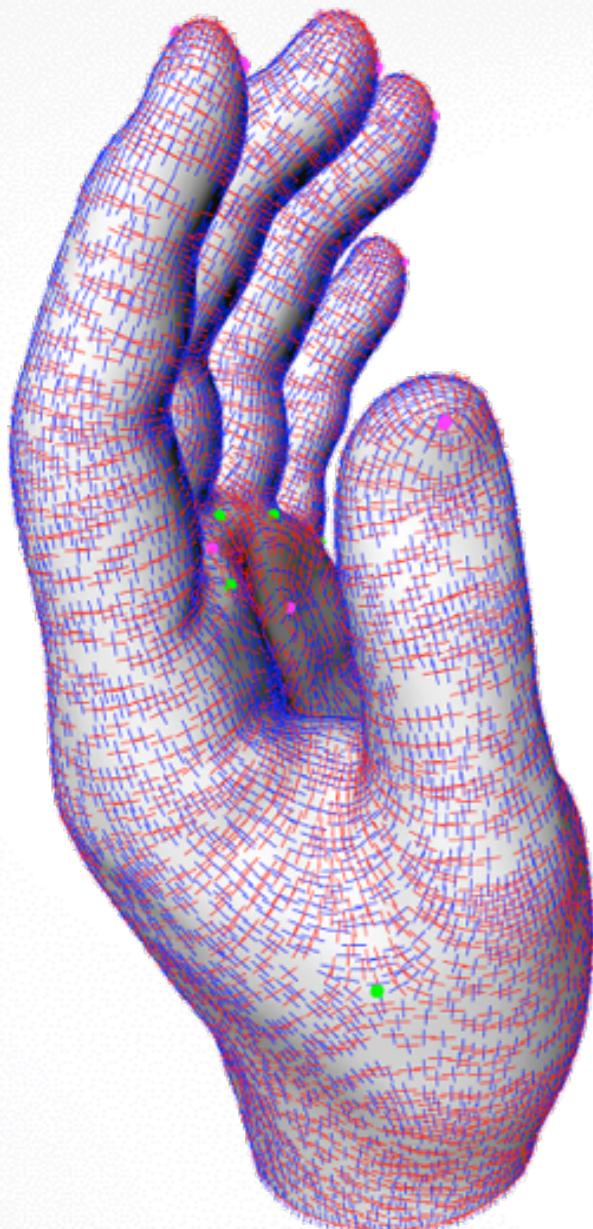


parabolic

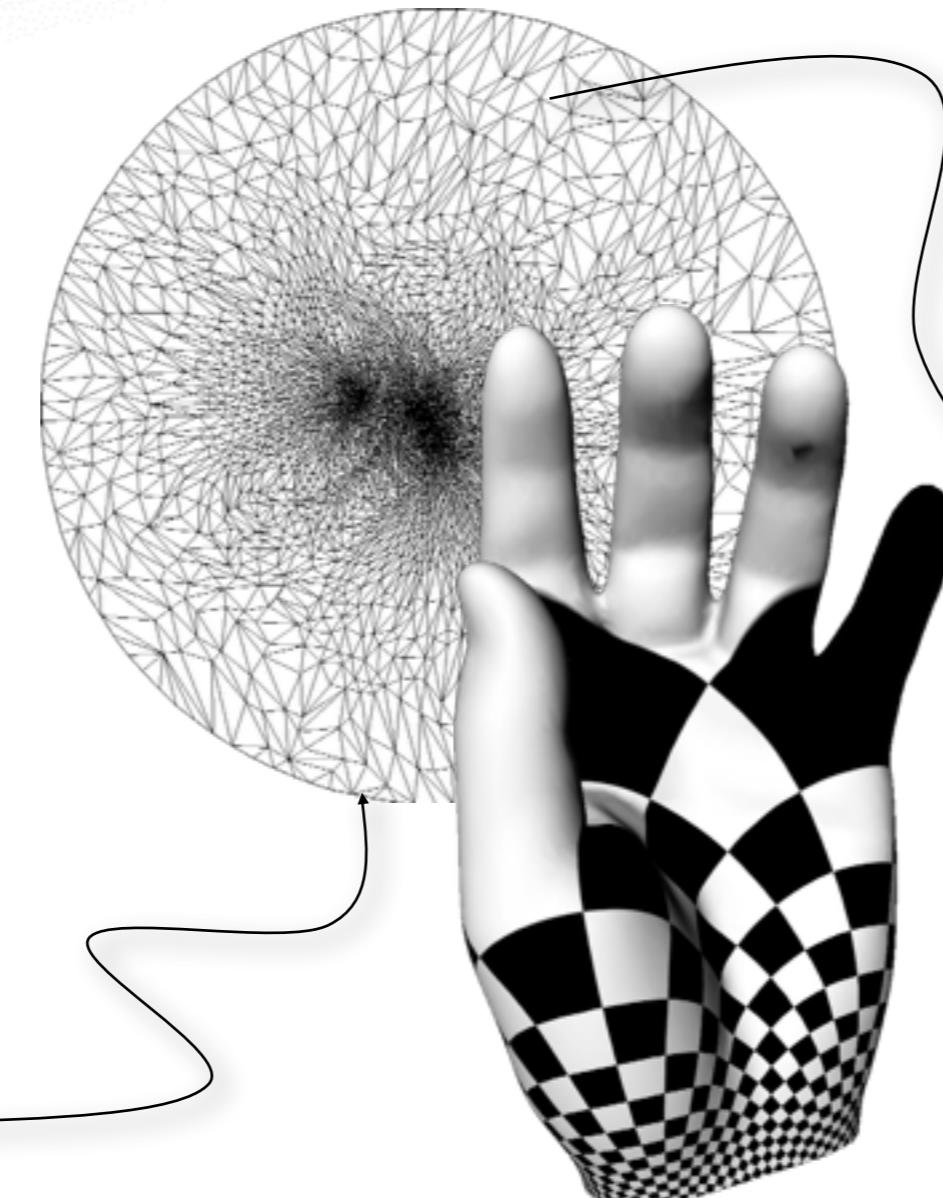
Principal direction fields



Flattening to 2D

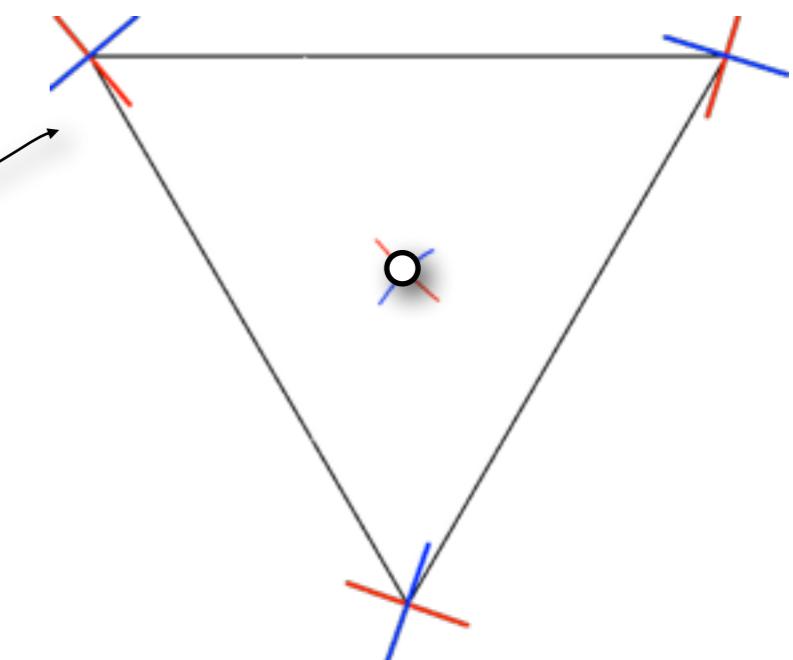


one 3D tensor
per vertex



discrete conformal
parameterization

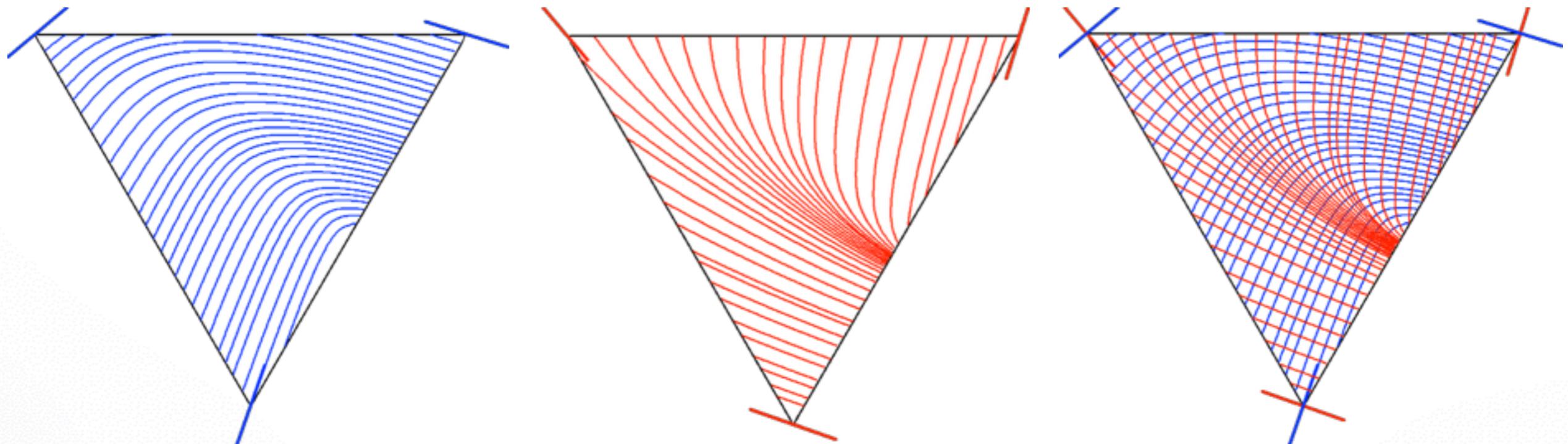
piecewise linear
interpolation of
2D tensors



2D tensor
using barycentric
coordinates

2D direction fields

- Regular case



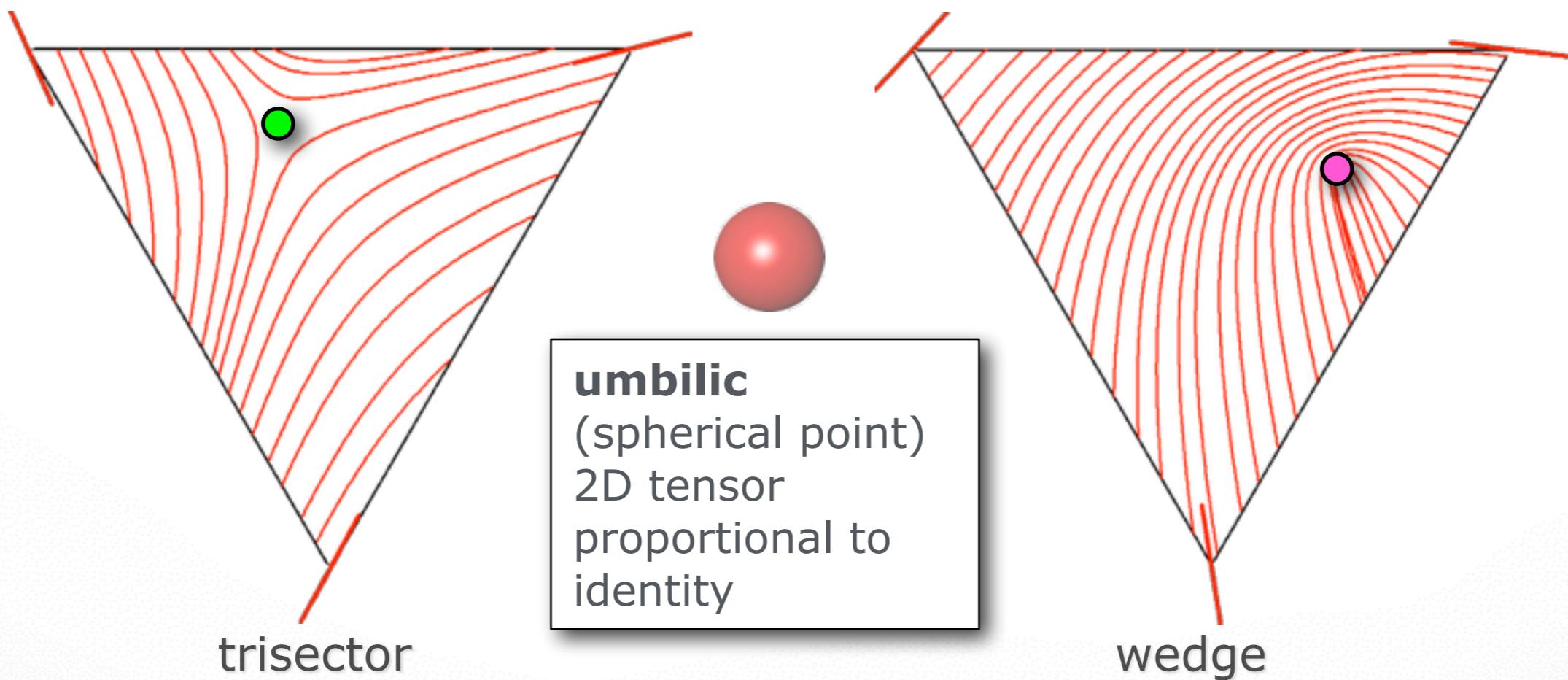
minor foliation

major foliation

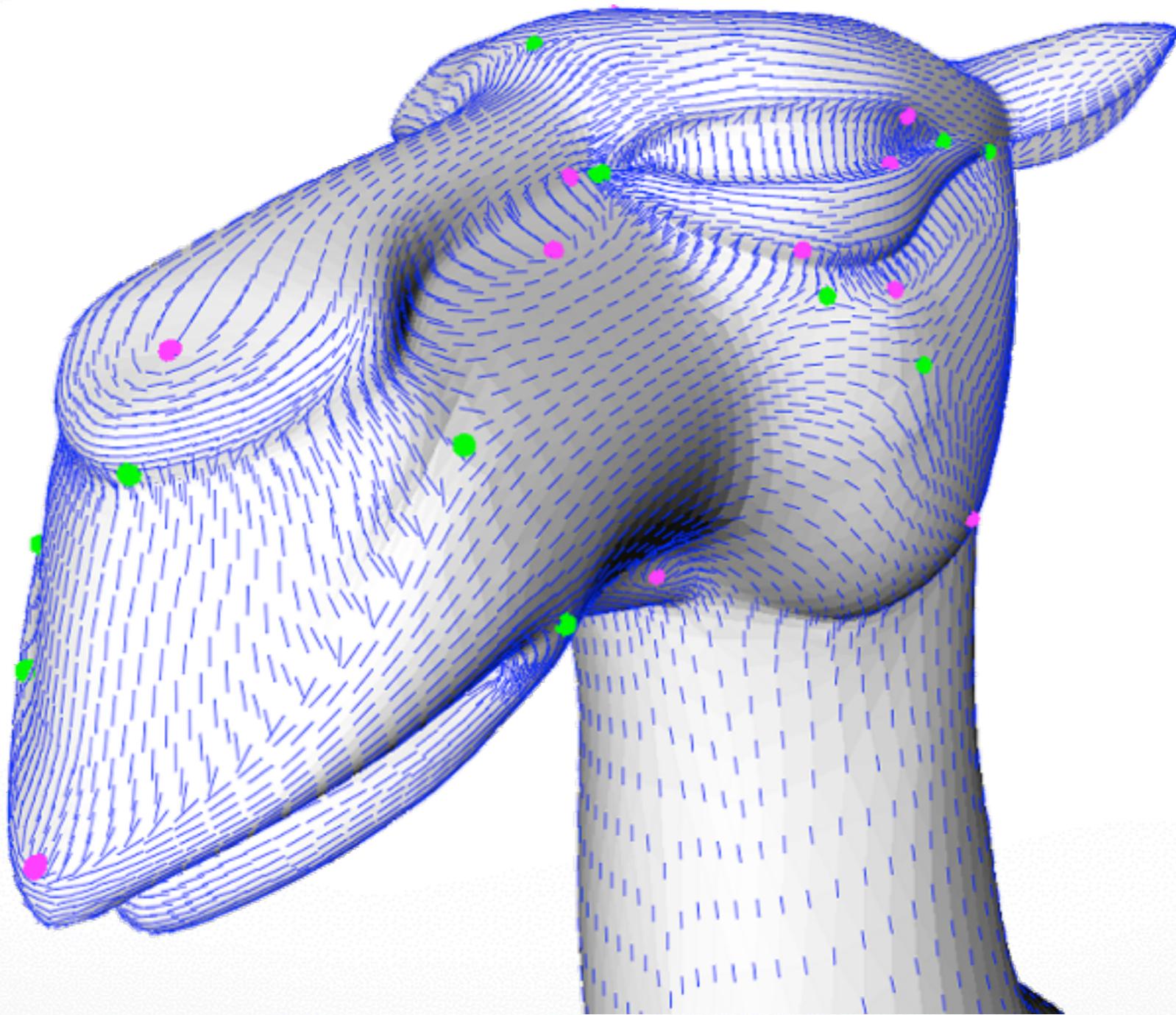
principal foliations

2D direction fields

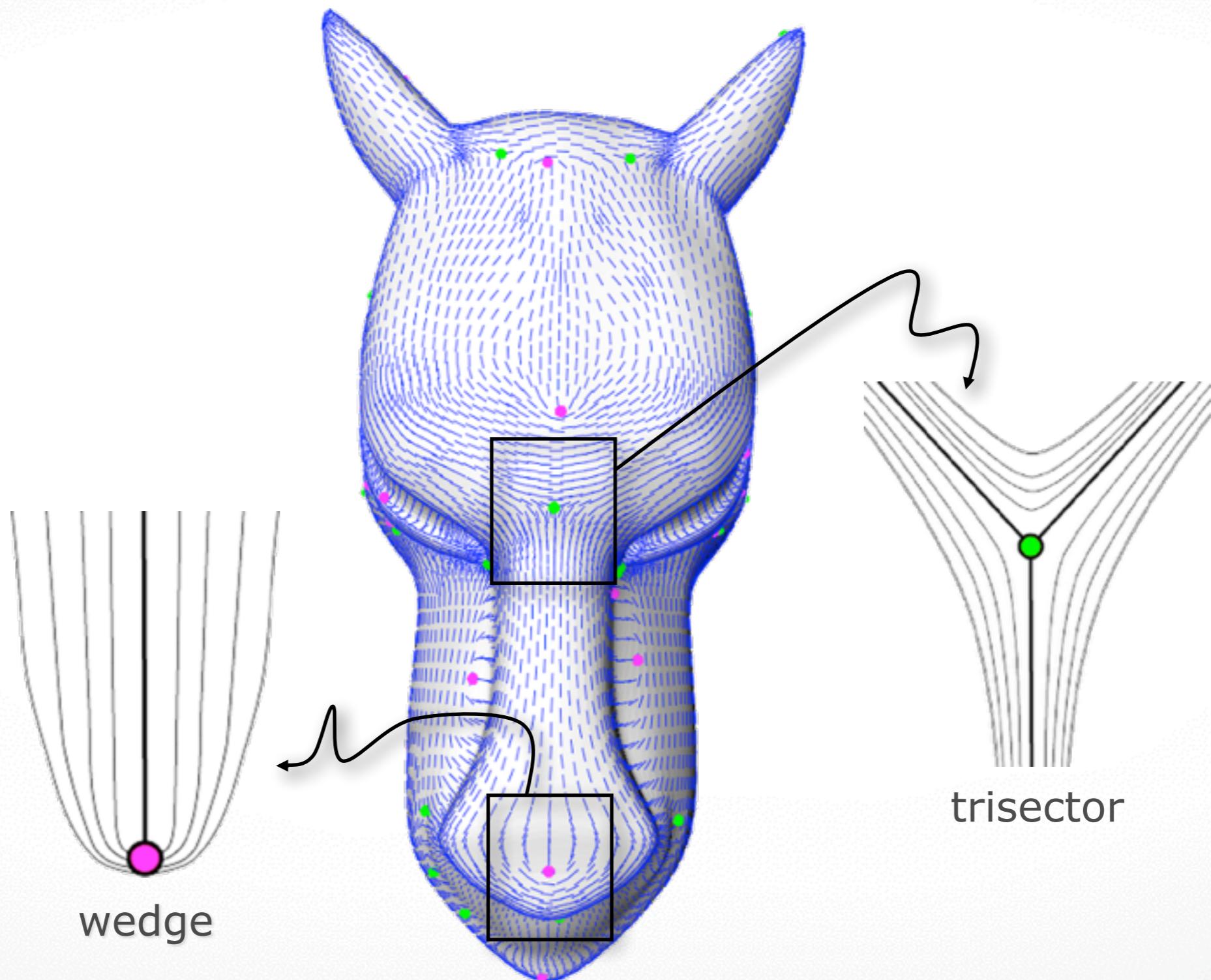
- Singularities



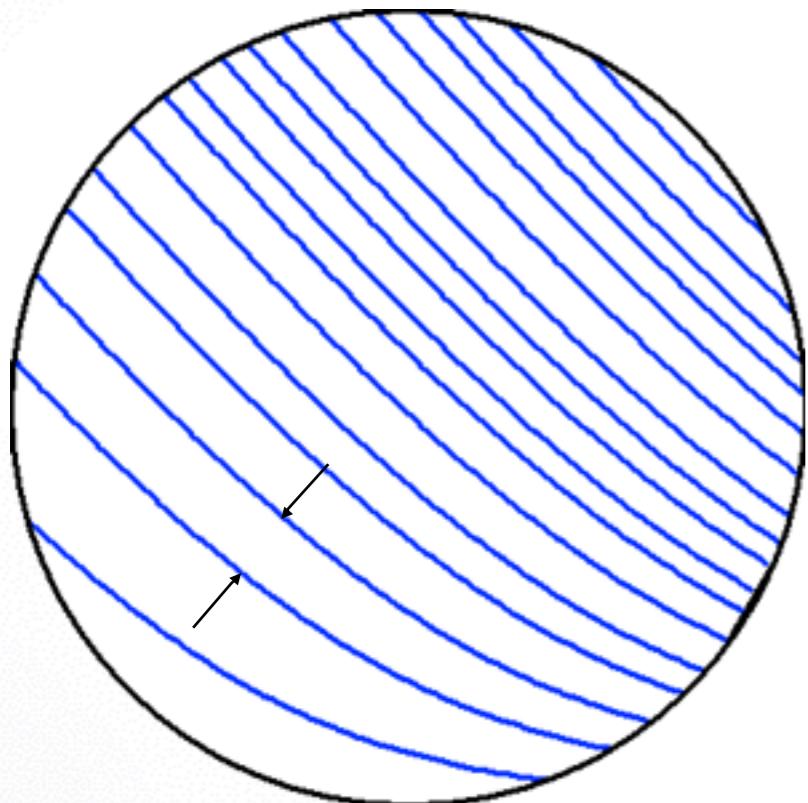
Umbilics



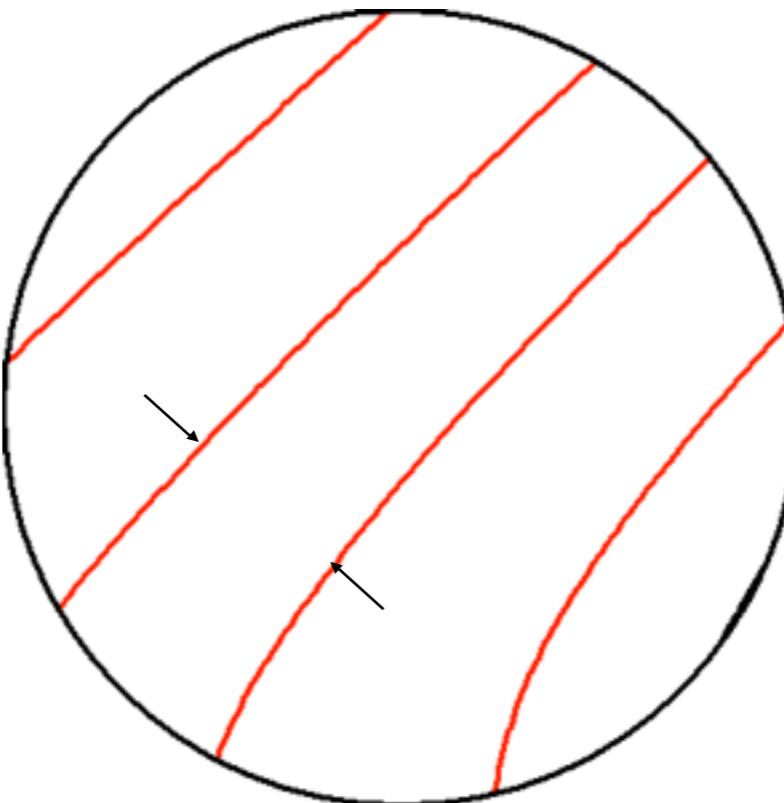
Umbilics



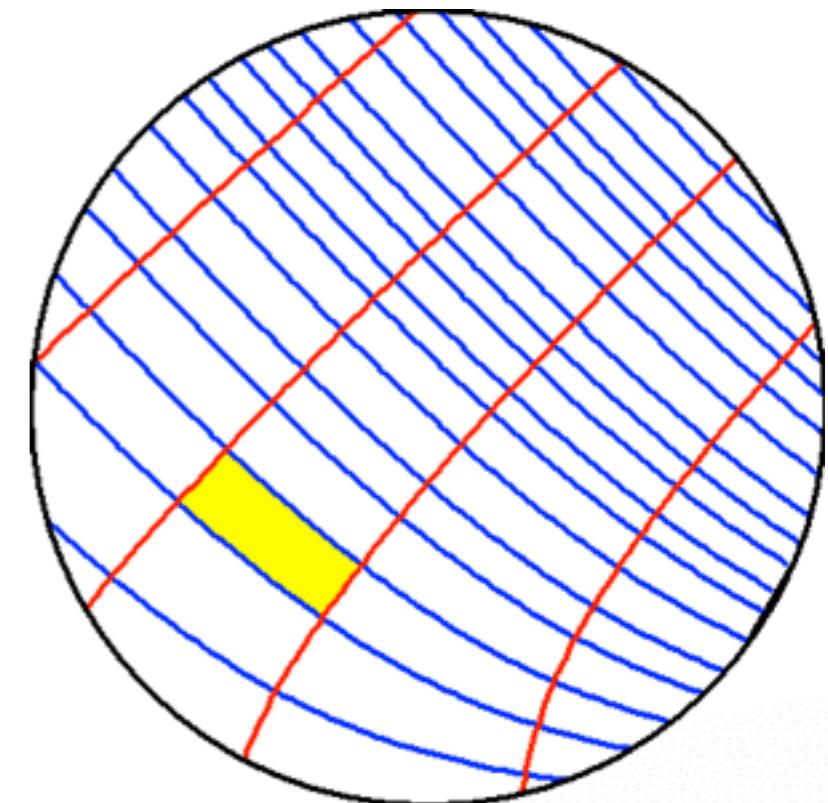
Lines of curvature



minor net

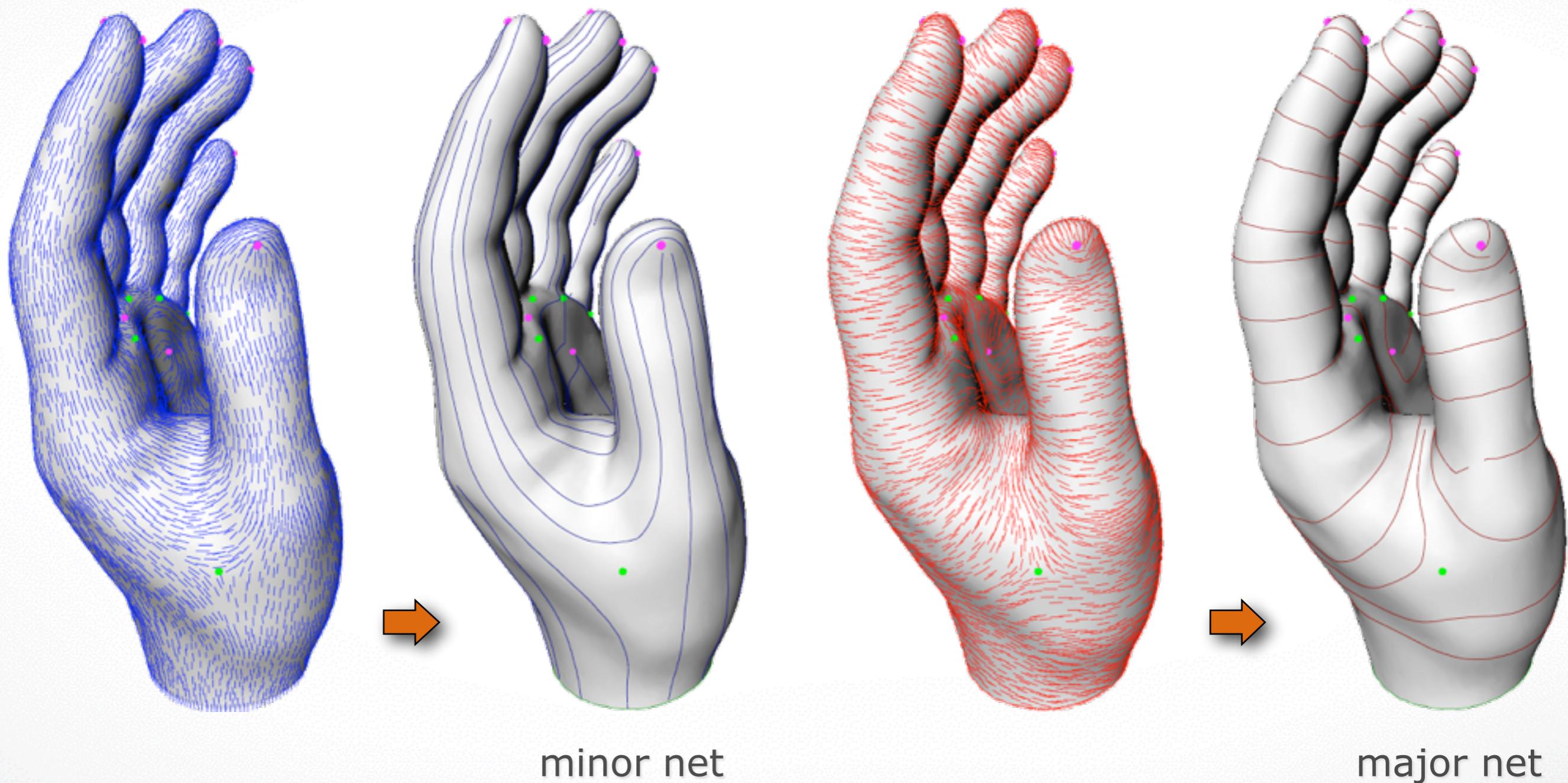


major net



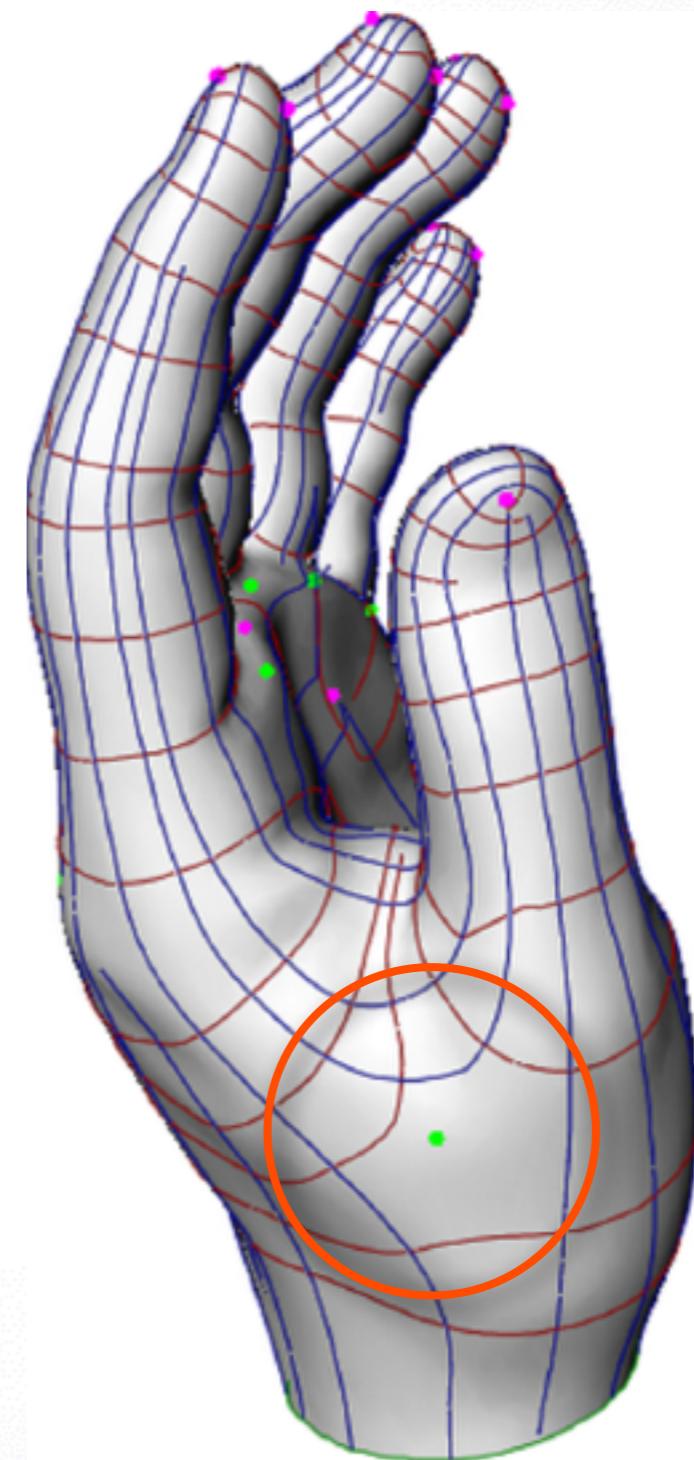
overlay

Lines of curvature

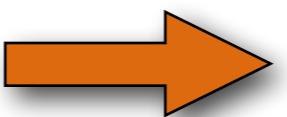
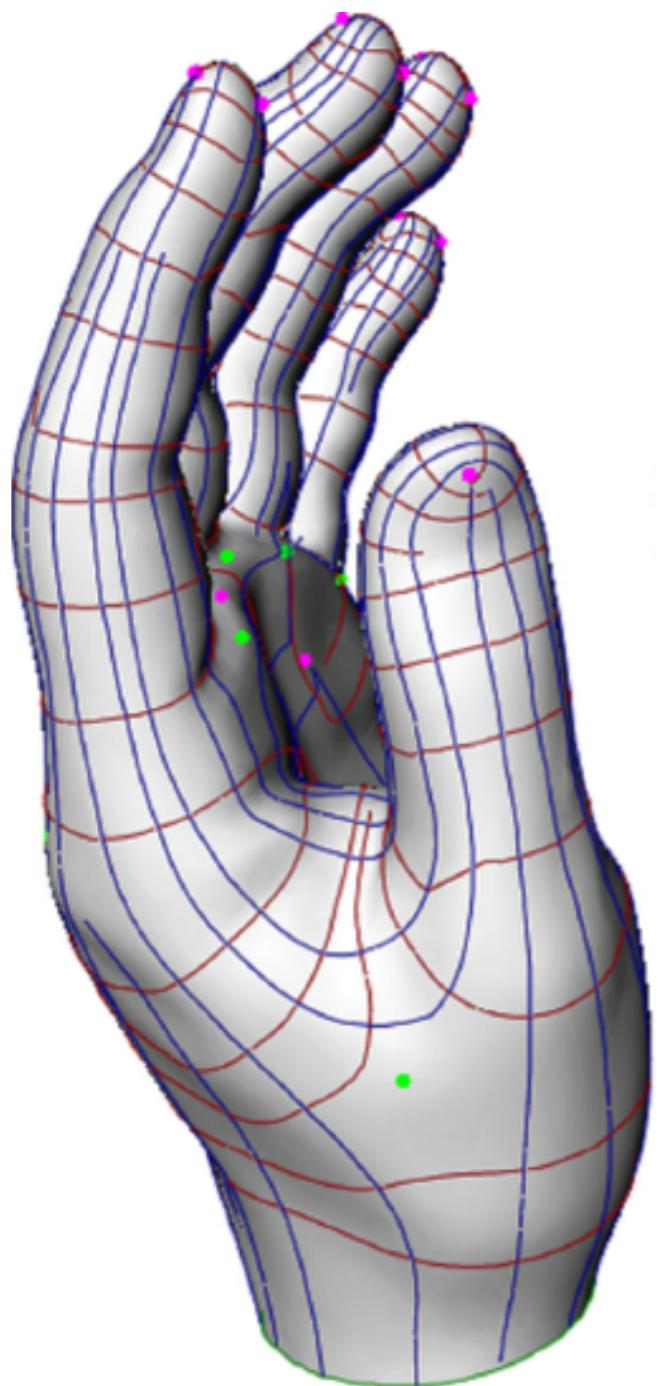


Overlay

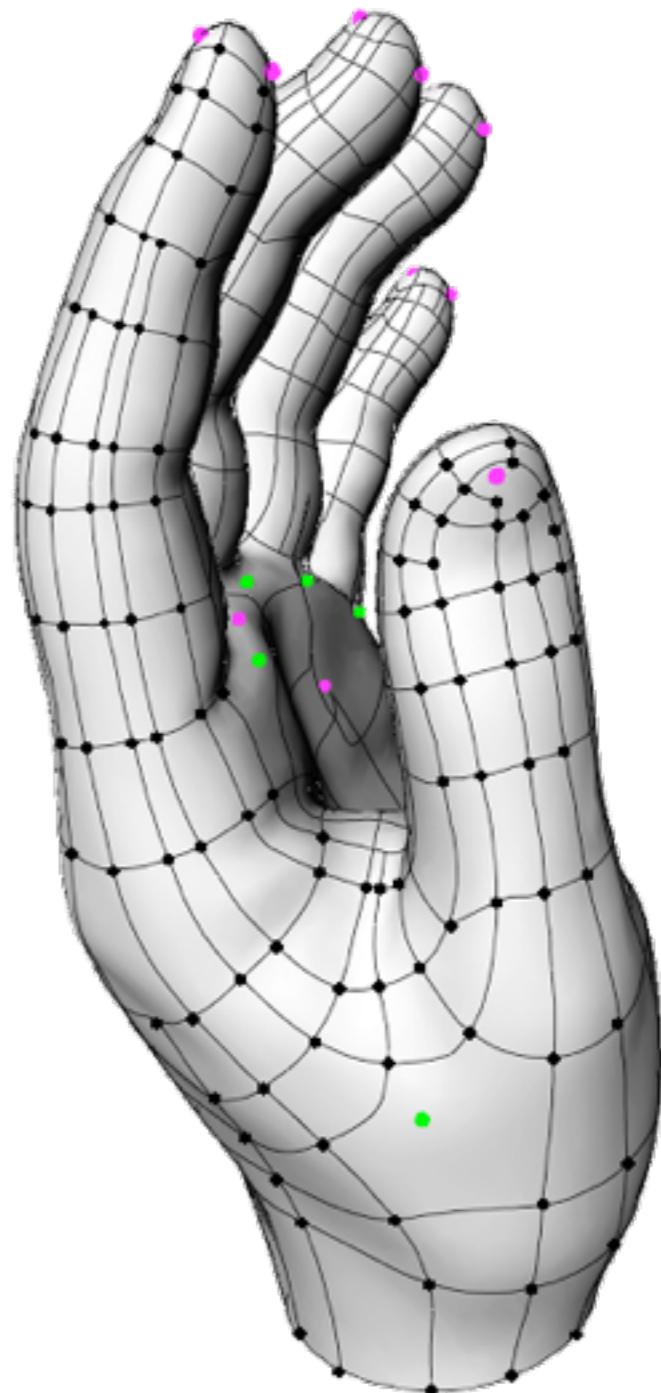
- Overlay curvature lines in anisotropic regions
- Add umbilical points in isotropic regions



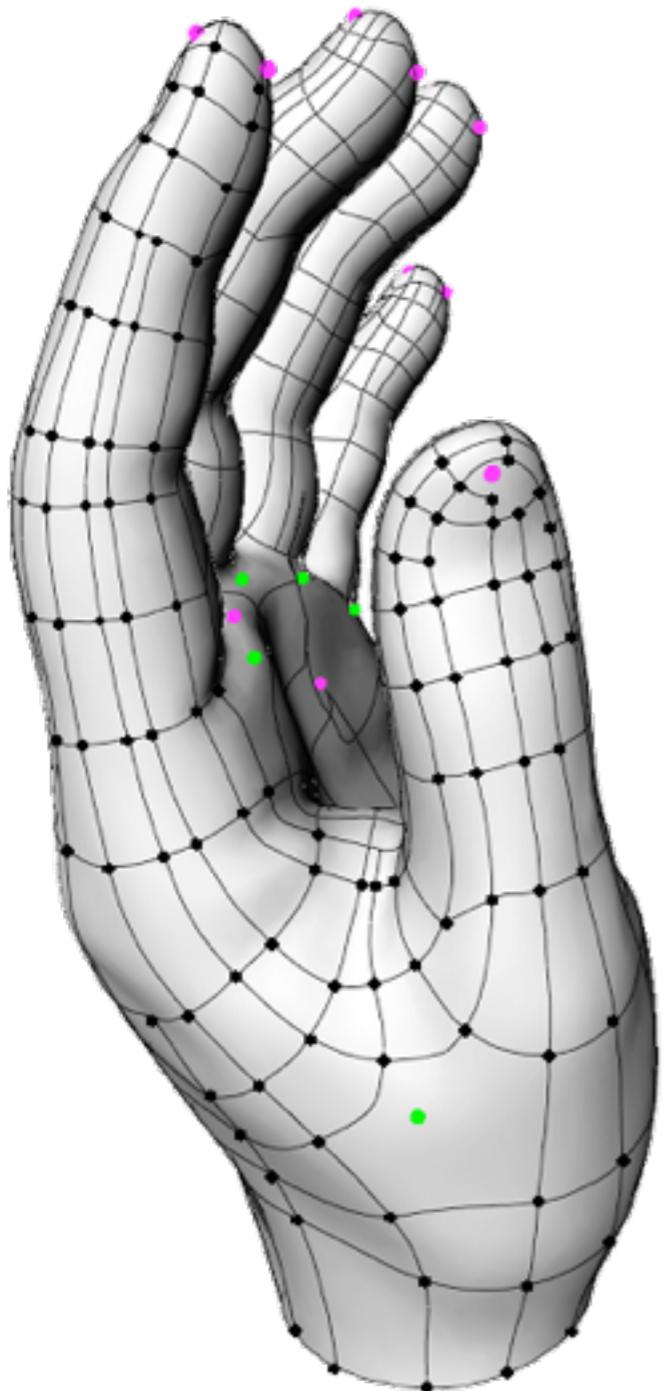
Vertices



intersect lines of
curvatures



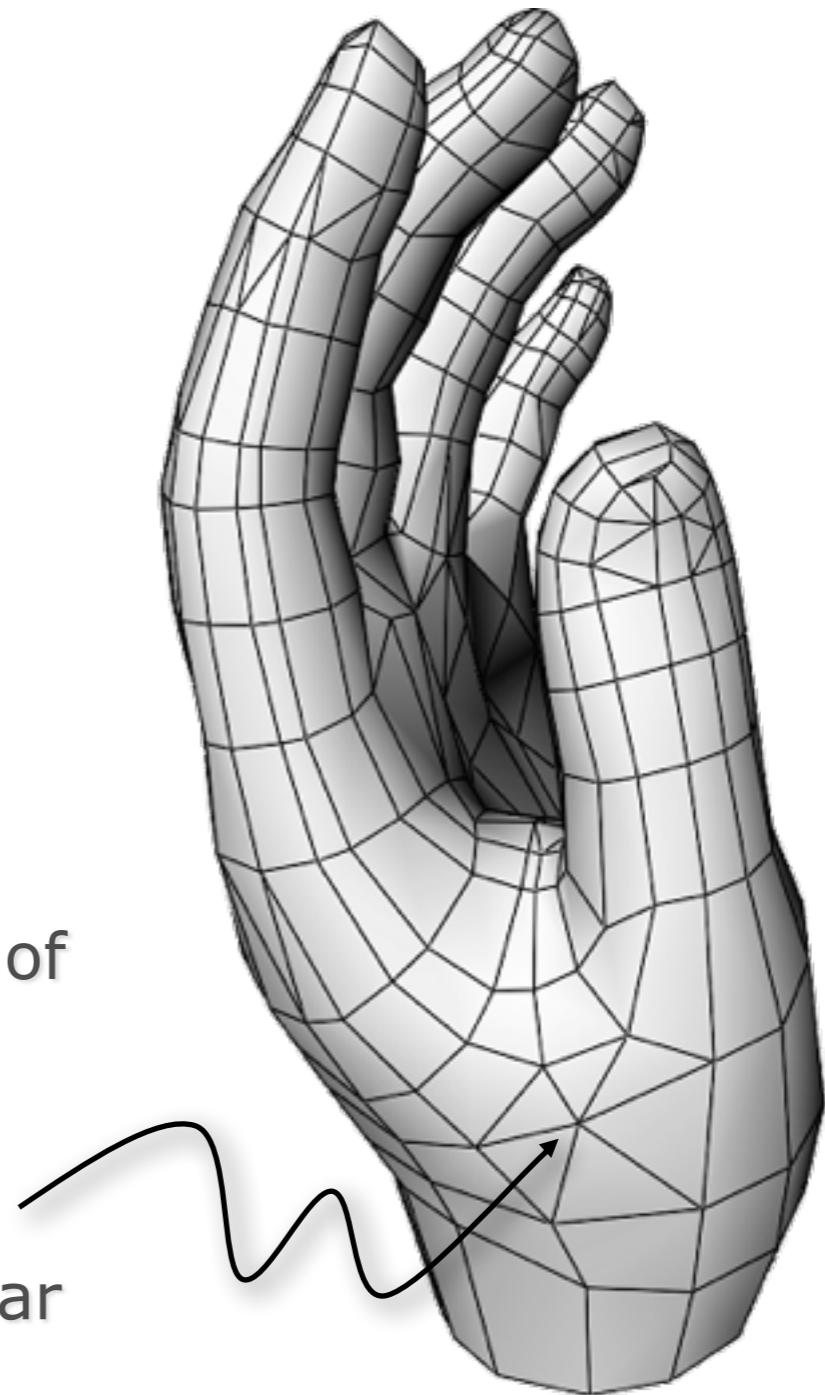
Edges



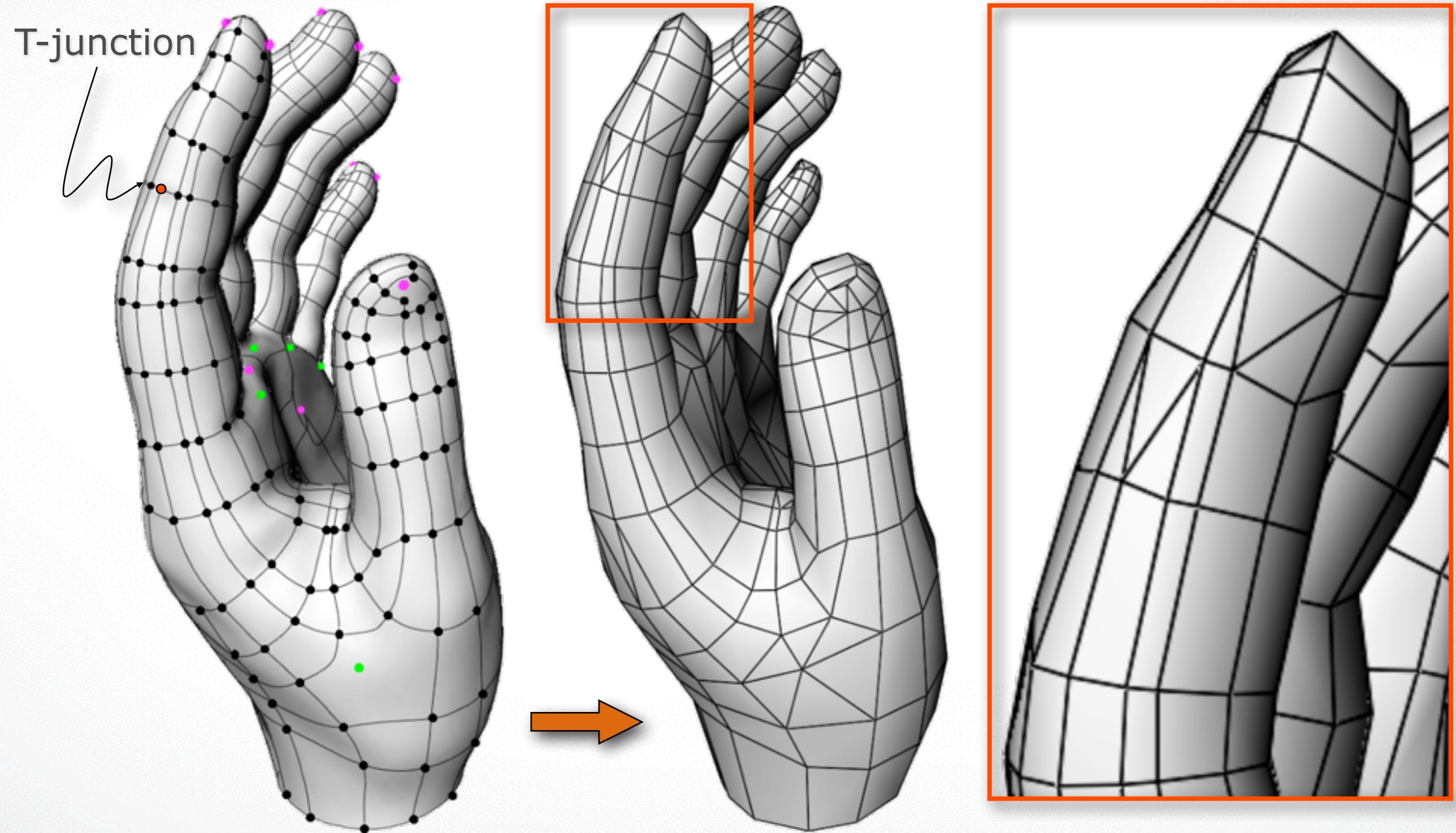
straighten lines of
curvatures

+

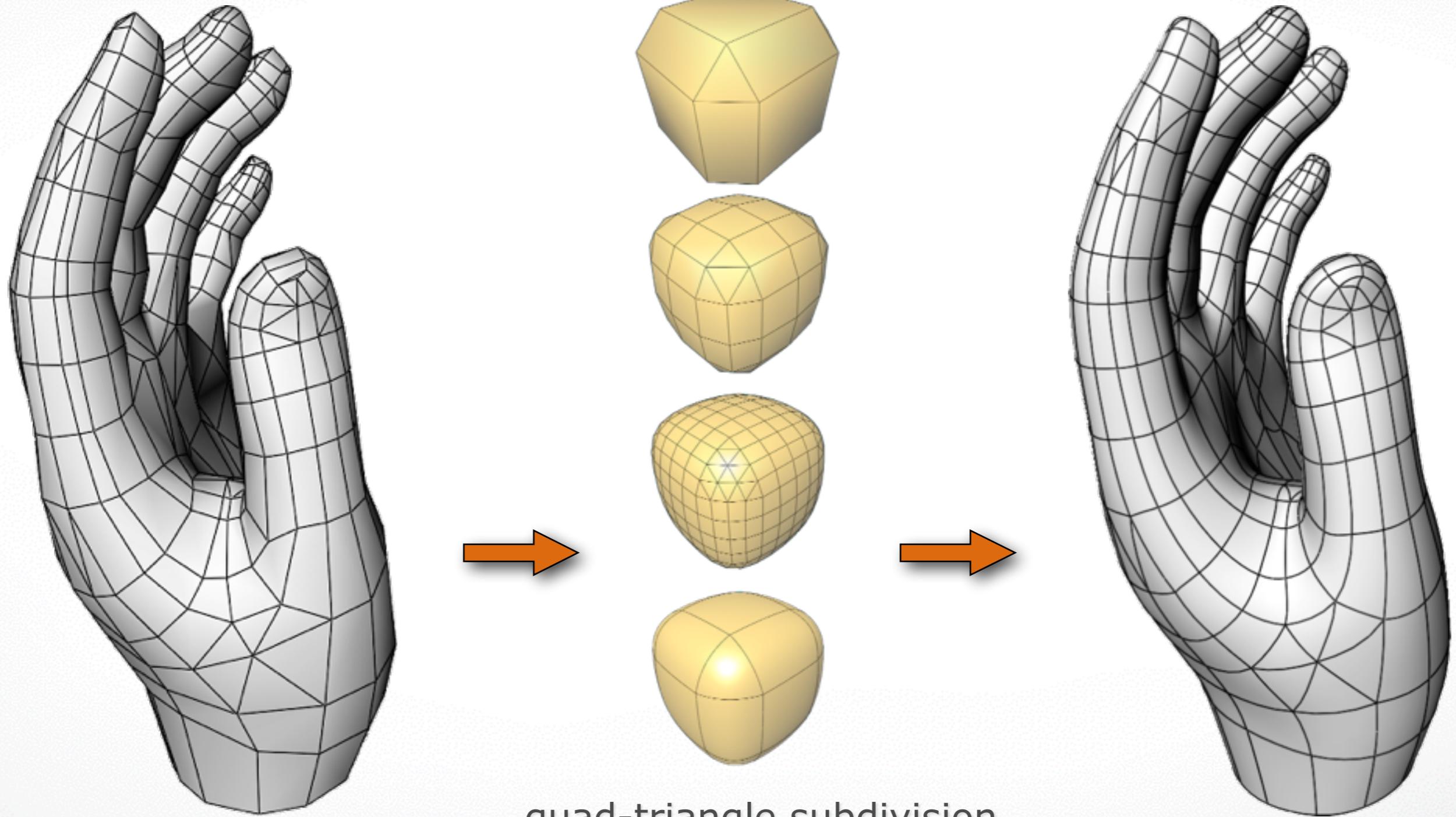
Delaunay
triangulation near
umbilics



Resolve T-junctions

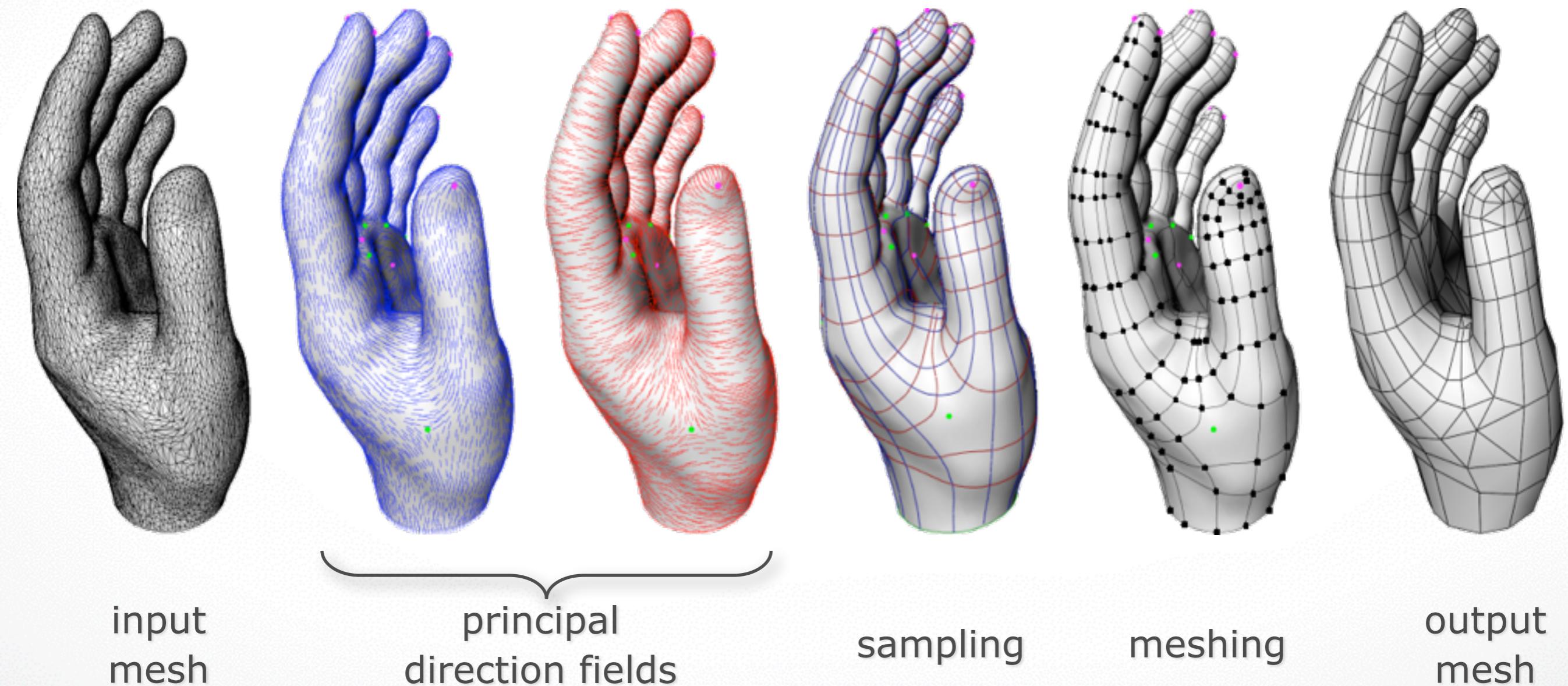


Smoothing



Anisotropic remeshing

[Alliez et al. 2003] *Anisotropic Polygonal Remeshing.*



input
mesh

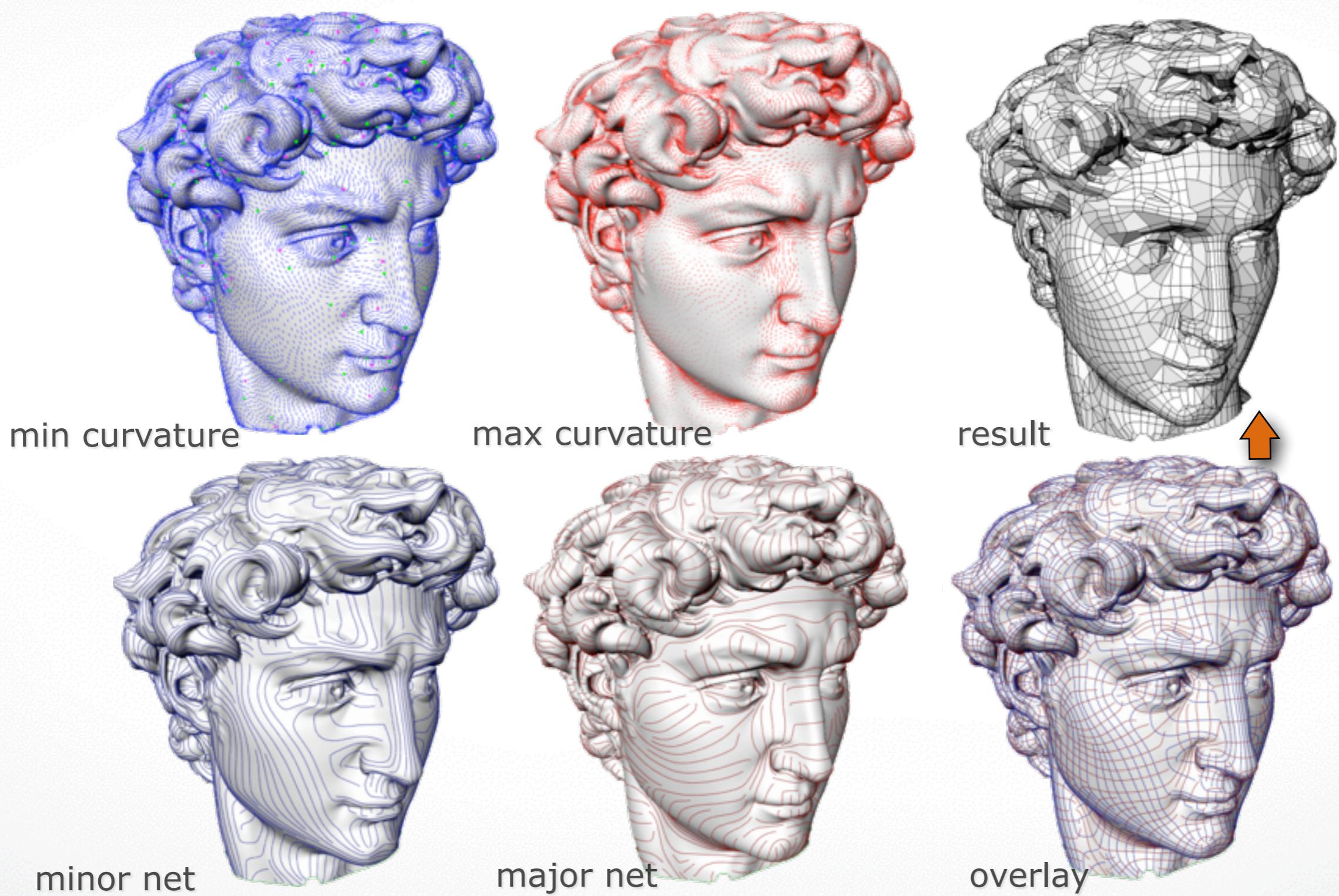
principal
direction fields

sampling

meshing

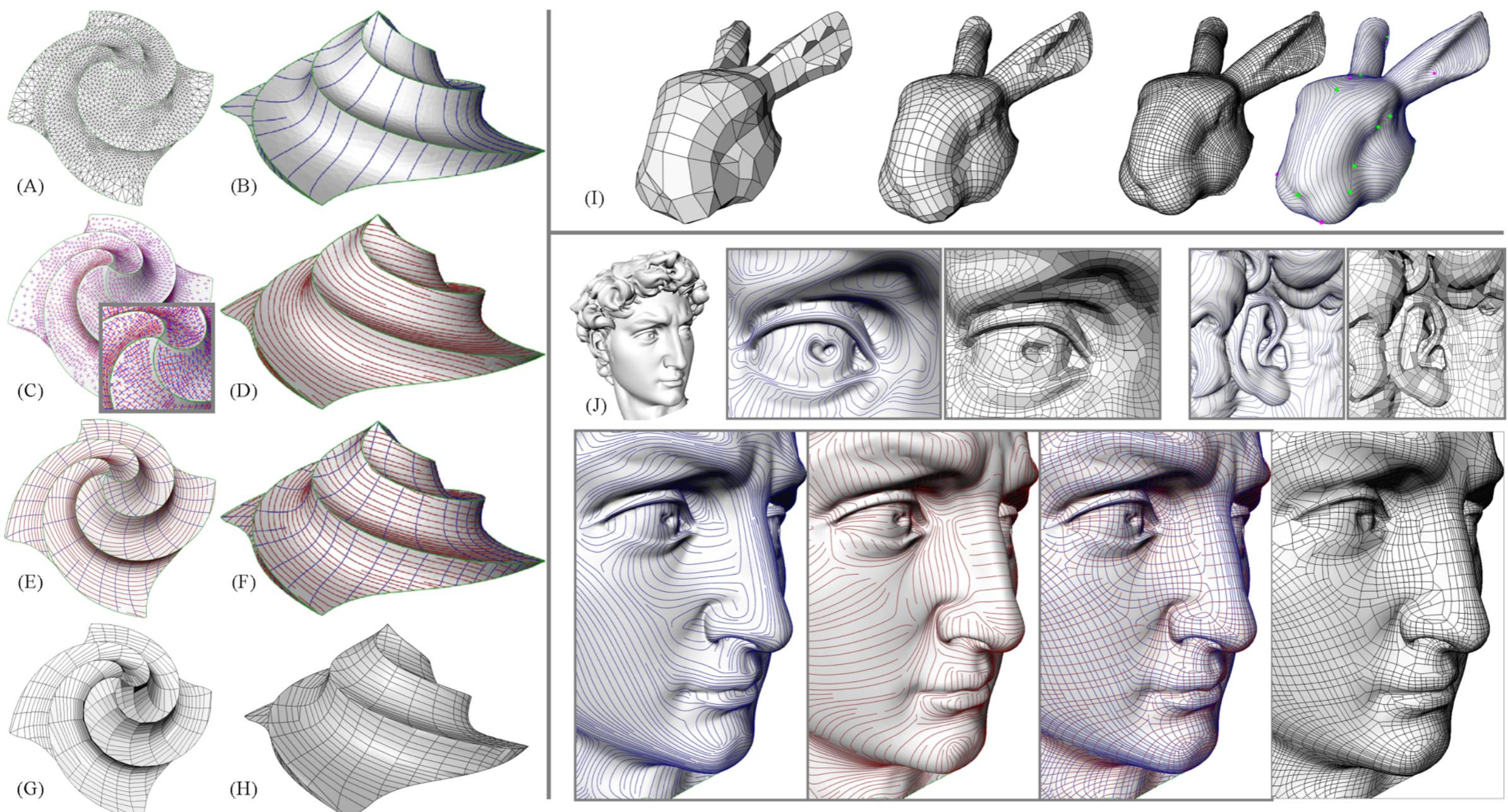
output
mesh

Remeshing results



Remeshing results

[Alliez et al. 2003] *Anisotropic Polygonal Remeshing.*



Tools

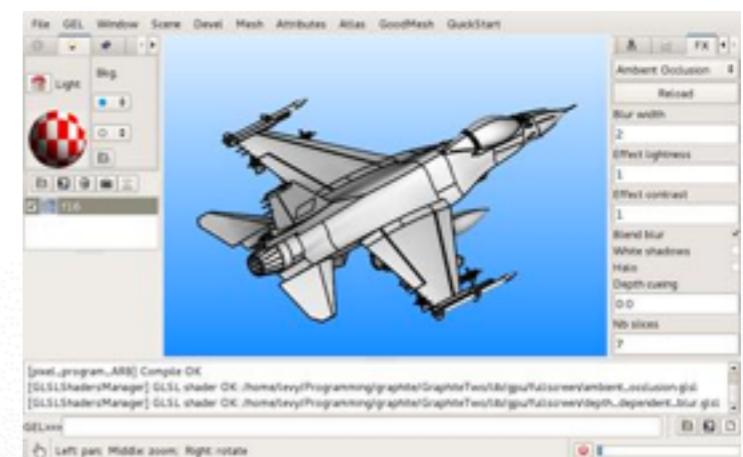
MeshLab

- meshlab.sourceforge.net
- open source
- available for Windows, MacOSX, and Linux



Graphite

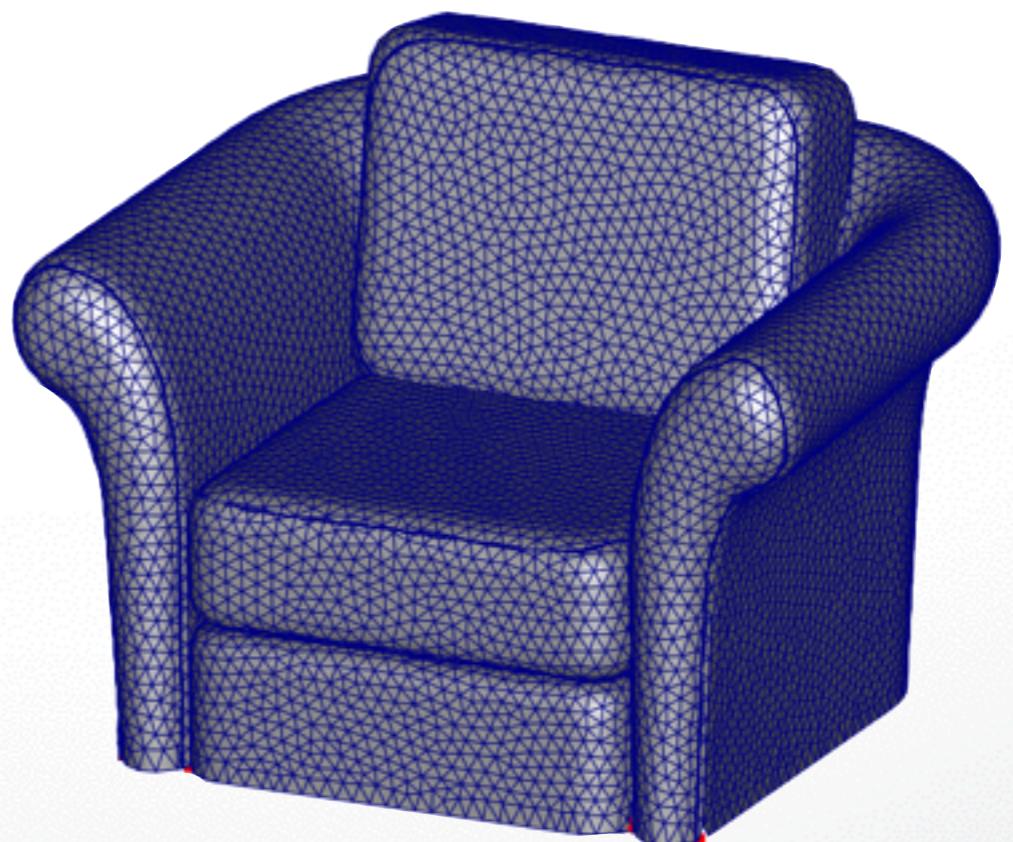
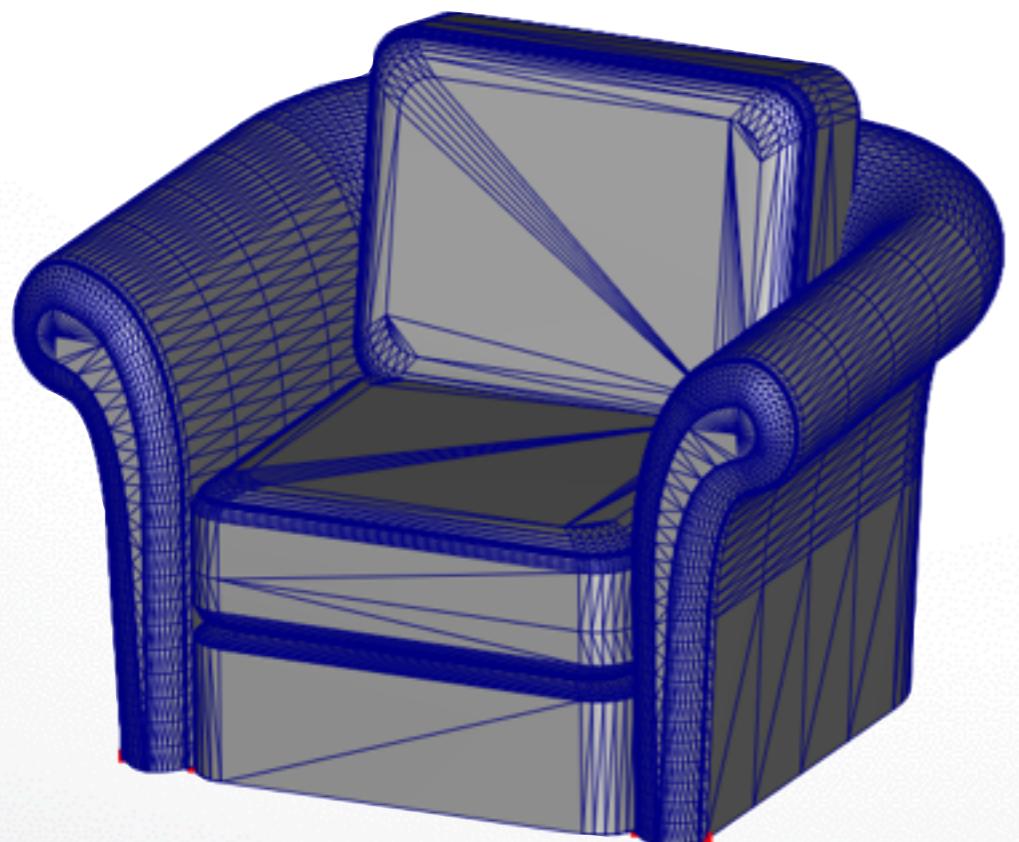
- <http://alice.loria.fr/index.php/software/3-platform/22-graphite.html>
- available for Windows
- MacOSX or Linux?



Remeshing via Graphite

“Mesh” → “remesh” → “pliant” →

- [Optional] flag border as feature
- [Optional] flag sharp edges as feature (dihedral angle)
- [Optional] estimate edge size (bounding box divisions)
- remesh (target edge length)



Literature

- Textbook: Chapter 6
- Alliez et al, “*Interactive geometry remeshing*”, SIGGRAPH 2002
- Alliez et al, “*Isotropic surface remeshing*”, SMI 2003
- Alliez et al, “*Anisotropic polygonal remeshing*”, SIGGRAPH 2003
- Vorsatz et al, “*Dynamic remeshing and applications*”, Solid Modeling 2003
- Botsch & Kobbelt, “*A remeshing approach to multiresolution modeling*”, Symp. on Geometry Processing 2004
- Marinov et al, “*Direct anisotropic quad-dominant remeshing*”, Pacific Graphics 2004
- Alliez et al, “*Recent advances in remeshing of surfaces*”, AIM@Shape state of the art report, 2006

<http://cs599.hao-li.com>

Thanks!

