Chapter \_

# Vector Spaces

# 1.1 $\mathbb{R}^n$ and $\mathbb{C}^n$

Linear algebra is the study of linear maps on finite dimensional vector spaces. In linear algebra, complex numbers are necessary for classifying the basic types of linear transformations in terms of their eigenvalues. Eigenvalues arise as solutions to certain polynomial equations.

# Complex Numbers

A **complex number** is an ordered pair (a, b) of real numbers. Complex numbers are often written as a + bi. The set of all complex numbers is denoted  $\mathbb{C}$ .

$$\mathbb{C} = \{a + bi \mid a, b \in \mathbb{R}\}\$$

**Addition** and **multiplication** on  $\mathbb{C}$  are defined by

$$(a+bi) + (c+di) = (a+c) + (b+d)i$$
  
 $(a+bi)(c+di) = (ac-bd) + (ad+bc)i$ 

The complex numbers a + 0i can be identified with the real numbers  $\mathbb{R}$ . Using multiplication as defined above, it is easy to see that  $i^2 = -1$ . The complex numbers inherit almost all the properties from the real numbers.

Commutativity  $\alpha + \beta = \beta + \alpha$  and  $\alpha\beta = \beta\alpha$  for all  $\alpha, \beta \in \mathbb{C}$ 

**Associativity**  $(\alpha + \beta) + \gamma = \alpha + (\beta + \gamma)$  and  $(\alpha\beta)\gamma = \alpha(\beta\gamma)$  for all  $\alpha, \beta, \gamma \in \mathbb{C}$ 

**Identities**  $\alpha + 0 = \alpha$  and  $\alpha 1 = \alpha$  for all  $\alpha \in \mathbb{C}$ 

**Additive Inverse** for every  $\alpha \in \mathbb{C}$ , there is a unique  $-\alpha \in \mathbb{C}$  such that  $\alpha + (-\alpha) = 0$ 

**Multiplicative Inverse** for every  $\alpha \in \mathbb{C}$ , there is a unique  $\alpha^{-1} \in \mathbb{C}$  such that  $\alpha \alpha^{-1} = 1$ 

**Distributive Property**  $\gamma(\alpha + \beta) = \gamma \alpha + \gamma \beta$  for all  $\alpha, \beta, \gamma \in \mathbb{C}$ 

These properties for addition and multiplication on the complex numbers define a field. Both  $\mathbb{C}$  and  $\mathbb{R}$  are fields. Most theorems in linear algebra hold for fields, so all further statements will use the terminology  $\mathbb{F}$  to refer to either  $\mathbb{C}$  or  $\mathbb{R}$ .

# n-tuples and $\mathbb{F}^n$

Let n be a nonnegative integer. An n-tuple is an ordered list of n elements.

$$(x_1, x_2, \ldots, x_n)$$

Two lists are equal if and only if they have the same length and the same elements in the same order. The set of all n-tuples with elements in  $\mathbb{F}$  is denoted  $\mathbb{F}^n$ .

$$\mathbb{F}^n = \{(x_1, x_2, \dots, x_n) \mid x_i \in \mathbb{F} \text{ for } i = 1, 2, \dots, n\}$$

In the case of n = 0,  $\mathbb{F}^n$  consists of a single element 0. This trivial space is defined to make the theorems consistent for all natural numbers. For  $n \geq 1$ ,  $0 \in \mathbb{F}^n$  is the *n*-tuple with all entries 0.

$$0 := (0, \ldots, 0)$$

By convention, n-tuples in  $\mathbb{F}^n$  will be represented by single variables and the components will use the same variable name along with a subscript to indicate position within the n-tuple.

$$x = (x_1, x_2, \dots, x_n)$$

Geometrically, a n-tuple is represented by an arrow. n-tuples represent quantities that have direction and magnitude.

#### Addition on $\mathbb{F}^n$

**Addition** on  $\mathbb{F}^n$  can be defined componentwise.

$$x + y = (x_1 + y_1, x_2 + y_2, \dots, x_n + y_n)$$

Since addition is defined componentwise with respect to the base field  $\mathbb{F}$ , addition on  $\mathbb{F}^n$  inherits many of the properties of addition on  $\mathbb{F}$ .

**Associativity** (x + y) + z = x + (y + z) for all  $x, y, z \in \mathbb{F}^n$ 

Commutativity x + y = y + x for all  $x, y \in \mathbb{F}^n$ 

**Additive Identity** x + 0 = x for all  $x \in \mathbb{F}$ 

**Additive Inverse** for each  $x \in \mathbb{F}^n$  there exists  $-x \in \mathbb{F}^n$  such that x + (-x) = 0. The additive inverse is given explicitly by  $-x := (-x_1, -x_2, \dots, -x_n)$ 

# Scalar Multiplication on $\mathbb{F}^n$

Similarly, scalar multiplication with respect to the field  $\mathbb{F}$  is defined componentwise.

$$\lambda x = (\lambda x_1, \lambda x_2, \dots, \lambda x_n)$$

Elements of the field  $\mathbb{F}$  are also called scalars, since scalar multiplication scales the length of n-tuples. Scalar multiplication also inherits many properties of multiplication of the base field  $\mathbb{F}$ .

**Associativity**  $(\alpha\beta)x = \alpha(\beta x)$  for all  $\alpha, \beta \in \mathbb{F}$  and all  $x \in \mathbb{F}^n$ 

Multiplicative Identity 1x = x for all  $x \in \mathbb{F}^n$ 

**Distributive Property**  $\alpha(x+y) = \alpha x + \alpha y$  and  $(\alpha + \beta)x = \alpha x + \beta x$  for all  $\alpha, \beta \in \mathbb{F}$  and all  $x, y \in \mathbb{F}^n$ 

Suppose  $a = bi \neq 0$ . Find a complex number c + di such that

$$(a+bi)^{-1} = c+di$$

**Solution.** By the definition of an inverse,

$$(a+bi)(c+di) = 1+0i$$

Applying the multiplication formula for complex numbers and equating real and imaginary parts,

$$ac - bd = 1$$
$$bc + ad = 0$$

Solving this system of equations yields

$$c = \frac{a}{a^2 + b^2}, \quad d = \frac{-b}{a^2 + b^2}$$

## Problem 1.2

Let  $a + bi \in \mathbb{C}$  with b > 0. Find two square roots of a + bi. What happens if b < 0?

**Solution.** Any square root x + yi of a + bi satisfies the equation

$$(c+di)^2 = a+bi$$

Using the rules of complex multiplication and equating real and imaginary parts leads to the system of equations

$$c^2 - d^2 = a$$
$$2cd = b$$

Notice that these equations imply  $c^2 + d^2 = \sqrt{a^2 + b^2}$ . Therefore, the solution to the system of equations must satisfy

$$c^{2} = \frac{\sqrt{a^{2} + b^{2}} + a}{2}$$
$$d^{2} = \frac{\sqrt{a^{2} + b^{2}} - a}{2}$$

The condition that b > 0 implies that cd > 0. Therefore, c and d must have the same sign. Thus, the two square roots of a + bi are given by the formula

$$\pm \left(\sqrt{\frac{\sqrt{a^2+b^2}+a}{2}}+i\sqrt{\frac{\sqrt{a^2+b^2}-a}{2}}\right)$$

In the case that b < 0, the argument above implies that c and d must have opposite signs. Therefore, the two square roots are given by

$$\pm \left(\sqrt{\frac{\sqrt{a^2+b^2}+a}{2}}-i\sqrt{\frac{\sqrt{a^2+b^2}-a}{2}}\right)$$

# 1.2 Definition of Vector Spaces

It turns out that many different types of mathematical objects share the same properties as  $\mathbb{F}^n$ . The notion of a vector space is meant to capture the essential properties of  $\mathbb{F}^n$  without being restricted to the specific details of the mathematical object.

## Vector Space

A vector space over the field  $\mathbb{F}$  is a set V along with an addition  $+: V \times V \to V$  and a scalar multiplication  $\cdot: \mathbb{F} \times V \to V$  that satisfy the following properties:

- (a) Commutativity of Addition
- (b) Associativity of Addition and Scalar Multiplication
- (c) Additive and Multiplicative Identities
- (d) Additive Inverses
- (e) Distributive Property

An element of a vector space is called a **vector**.

**Example.**  $\mathbb{F}^{\infty}$  is defined to be the set of all sequences of elements in  $\mathbb{F}$ :

$$\mathbb{F}^{\infty} := \{(x_1, x_2, \dots) \mid x_i \in \mathbb{F} \text{ for } j = 1, 2, \dots \}$$

Addition and scalar multiplication on  $\mathbb{F}^{\infty}$  are defined as

$$(x_1, x_2,...) + (y_1, y_2...) = (x_1 + y_1, x_2 + y_2,...)$$
  
 $\lambda(x_1, y_1,...) = (\lambda x_1, \lambda x_2,...)$ 

**Example.**  $\mathbb{R}^{[a,b]}$  is the set of all functions  $f:[a,b]\to\mathbb{R}$  where addition and scalar multiplication are defined pointwise:

$$(f+g)(x) = f(x) + g(x)(\lambda f)(x) = \lambda f(x)$$

where  $f, g \in \mathbb{R}^{[a,b]}$  and  $\lambda \in \mathbb{R}$ .

**Example.** W[a,b] is the set of all differentiable functions  $f:[a,b]\to\mathbb{C}$  where addition and scalar multiplication are defined pointwise. This is a vector space since the sum of two differentiable functions is differentiable and the a constant multiple of a differentiable functions is still differentiable.

# Theorem 1.1: Properties of Vector Spaces

- (a) A vector space has a unique additive identity 0.
- (b) Every element v in a vector space has a unique additive inverse -v.
- (c) For every  $v \in V$ , 0v = 0
- (d) For every  $\lambda \in \mathbb{F}$ ,  $\lambda 0 = 0$
- (e) For every  $v \in V$ , (-1)v = -v

Prove that -(-v) = v for every  $v \in V$ .

**Solution.** Using the associativity of scalar multiplication and property (e) from Theorem 1.1:

$$-(-v) = -1(-v) = -1(-1v) = [(-1)(-1)]v = 1v = v$$

## Problem 1.4

The empty set is not a vector space. The empty set only fails one of the requirements in the definition of a vector space. Which one?

**Solution.** Commutativity, associativity, additive inverse, multiplicative identity, and the distributive properties are vacuously true since there are no elements of the empty set. However, the existence of an additive identity can not be statisfied by the empty set since it contains no elements.

## Problem 1.5

Show that in the definition of a vector space, the additive inverse condition can be replaced by the condition

$$0v = 0$$
 for all  $v \in V$ 

**Solution.** A condition can be replaced by another condition if the two statements are logically equivalent. Property (c) of Theorem 1.1, proves one direction of the logical equivalence. To prove the other direction, suppose 0v = v for all  $v \in V$ . Then,

$$0 = 0v = (-1+1)v = -1v + 1v = -1v + v$$

Thus, for each vector  $v \in V$  there is an additive inverse -1v. This completes the proof.

## Problem 1.6

Considered the extended real line  $\mathbb{R} \cup \{-\infty\} \cup \{\infty\}$ . For  $x, y \in \mathbb{R}$  the usual definitions for addition and multiplication of real numbers apply. For x > 0 define

$$(\pm x)\infty = \pm \infty, \qquad (\pm x)(-\infty) = \mp \infty$$

For x = 0 define  $(0)\infty = (0)(-\infty) = 0$ . For  $x \in \mathbb{R}$ ,

$$x + \infty = \infty + x = \infty,$$
  $x + (-\infty) = (-\infty) + x = -\infty$   
 $\infty + \infty = \infty,$   $(-\infty) + (-\infty) = -\infty,$   $\infty + (-\infty) = 0$ 

Is the extended real line a vector space over  $\mathbb{R}$ ?

**Solution.** The extended real line is not a vector space over  $\mathbb{R}$  since addition is not associative. For example,

$$-\infty + (\infty + 1) = (-\infty + \infty) = 0$$

whereas

$$(-\infty + \infty) + 1 = 0 + 1 = 1$$

# 1.3 Subspaces

# Subspaces

A subset U of a vector space V is called a **subspace** of V is U is also a vector space using the same addition and scalar multiplication as on V.

# Theorem 1.2: Conditions for a Subspace

A set u of V is a subspace of V if and only if U satisfie the following three conditions:

additive identity  $0 \in U$ 

**closed under addition**  $u, v \in U$  implies  $u + v \in U$ 

closed under scalar multiplication  $a \in \mathbb{F}$  and  $u \in U$  implies  $au \in U$ .

*Proof.* If U is a subspace of V, then U satisfies the three conditions above by the definition of a vector space. Conversely, suppose U satisfies the three conditions above. The first condition ensures that the additive identity is in U. The second condition ensures addition is well defined. The third condition ensures that scalar multiplication is well defined.

Moreover, associativity, commutativity, multiplicative identities, and distributive properties are automatically satisfied by U since they hold in V. Lastly, closure of scalar multiplication ensures the additive inverse -v = -1v is contained in U. Thus, U is a subspace.

**Example.** The set of continuous real-values functions on the interval [a,b] is a subspace of  $\mathbb{R}^{[a,b]}$ 

**Example.** The set of all sequences of complex numbers with limit 0 is a subspace of  $\mathbb{C}^{\infty}$ 

# Sum of Subsets

Suppose  $U_1, U_2, \ldots, U_m$  are subsets of V. The **sum** of  $U_1, \ldots, U_m$ , denoted  $U_1 + \cdots + U_m$ , is the set of all possible sums of elements of  $U_1, U_2, \ldots, U_m$ . More precisely,

$$U_1 + \dots + U_m = \{u_1 + \dots + u_m \mid u_1 \in U_1, \dots, u_m \in U_m\}$$

**Example.** Let  $U, V \in \mathbb{F}^3$  where  $U = \{(x, 0, 0) \mid x \in \mathbb{F}\}$  and  $W = \{(0, y, 0) \mid y \in \mathbb{F}\}$ . Then,

$$U + W = \{(x, y, 0) \mid x, y \in \mathbb{F}\}\$$

**Example.** Suppose that  $U = \{(x, x, y, y) \in \mathbb{F}^4 \mid x, y \in \mathbb{F}\}$  and  $W = \{(x, x, x, y) \in \mathbb{F}^4 \mid x, y \in \mathbb{F}\}$ . Then

$$U + W = \{(x, x, y, z) \in \mathbb{F}^4 \mid x, y, z \in \mathbb{F}\}\$$

# Theorem 1.3: Sum of Subspaces is the Smallest Containing Subspace

Suppose  $U_1, \ldots, U_m$  are subspaces of V. Then,  $U_1 + \cdots + U_m$  is the smallest subspace of V containing  $U_1, \ldots, U_m$ .

Proof.  $0 = 0 + \cdots + 0 \in U_1, \ldots, U_m$ . Since  $U_1, \ldots, U_m$  are closed under addition and scalar multiplication, it follows that their subset sum is also closed under addition and multiplication. Thus,  $U_1 + \cdots + U_m$  is a subspace of V by Theorem 1.2. Clearly,  $U_i \in U_1 + \cdots + U_m$  for each  $i = 1, \ldots, m$ . Conversely, ansy subspace U of V containing  $U_1, \ldots, U_m$  must contain  $U_1 + \cdots + U_m$  since subspaces must contain all finite sums of their elements. Therefore,  $U_1, \ldots, U_m \subset U_1 + \cdots + U_m \subset U$ .

## Direct Sum

Suppose  $U_1, \ldots, U_m$  are subspaces of V. The sum  $U_1 + \cdots + U_m$  is called a **direct sum** if each element of  $U_1 + \cdots + U_m$  can be written uniquely as a sum

$$u_1 + \cdots + u_m$$
,  $u_i \in U_i$  for  $i = 1, \dots, m$ 

A direct sum will be denoted by  $U_1 \oplus \cdots \oplus U_m$ .

**Example.** Suppose  $U_j$  is the subspace of  $\mathbb{F}^n$  of vectors whose coordinates are all 0 except for the jth coordinate.

$$U_i = \{(0, \dots, x_i, \dots, 0) \mid x_i \in \mathbb{F}\}\$$

Then,  $\mathbb{F}^n = U_1 \oplus \cdots \oplus U_n$ 

**Example.** Let  $U_1 = \{(x, y, 0) \in \mathbb{F}^3 \mid x, y \in \mathbb{F}\}$ ,  $U_2 = \{(0, 0, z) \in \mathbb{F}^3 \mid z \in \mathbb{F}\}$ ,  $U_3 = \{(0, y, y) \in \mathbb{F}^3 \mid y \in \mathbb{F}\}$ . Note that  $U_1 + U_2 + U_3 = \mathbb{F}3$ , because every vector in  $\mathbb{F}^3$  can be written as

$$(x, y, z) = (x, y, 0) + (0, 0, z) + (0, 0, 0)$$

However, (0,0,0) can be written in many different ways as the sum  $u_1 + u_2 + u_3$ . For example,

$$(0,0,0) = (0,a,0) + (0,0,a) + (0,-a,-a)$$

for any  $a \in \mathbb{F}$ . Therefore,  $\mathbb{F}^3 \neq U_1 \oplus U_2 \oplus U_3$ . However,  $\mathbb{F}^3 = U_1 \oplus U_2$ .

# Theorem 1.4: Condition for Direct Sum

Suppose  $U_1, \ldots, U_m$  are subspaces of V. Then,  $U_1 + \cdots + U_m$  is a direct sum if and only if the only way to write 0 as a sum  $u_1 + \cdots + u_m$ , where each  $u_j \in U_j$ , is by taking each  $u_j = 0$ .

*Proof.* Suppose  $U_1 + \cdots + U_m$  is a direct sum. Then the definition of a direct sum implies that the only way to write 0 as a sum  $u_1 + \cdots + u_m$ , where each  $u_i \in U_i$ , is by taking each  $u_i = 0$ .

Now suppose that the only way to write 0 as a sum  $u_1 + \cdots + u_m$ , where each  $u_j \in U_j$ , is by taking each  $u_j = 0$ . Let  $v \in U_1 + \cdots + U_m$ . We can write

$$v = u_1 + \cdots + u_m$$

for some  $u_i \in U_i$ . Suppose that v had another representation

$$v = v_1 + \dots + v_m$$

for some  $v_i \in U_i$ . Then,

$$0 = (u_1 - v_1) + \dots + (u_m - v_m)$$

Since,  $u_j - v_j \in U_j$  by the subspace property of each  $U_j$ , it follows from the assumption that  $u_j - v_j = 0$ . Thus,  $u_1 = v_1, \ldots, u_1 = v_1$ . The representation for v is unique, so  $U_1 \oplus \cdots \oplus U_m$  is a direct sum.

# Theorem 1.5: Direct Sum of Two Subspaces

Suppose U and W are subspaces of V. Then, U+W is a direct sum if and only if  $U\cap W=\{0\}$ .

*Proof.* Suppose that U+W is a direct sum. If  $v \in U \cap W$ , then 0 = v + (-v), where  $v \in U$  and  $-v \in W$ . By the unique representation of 0, we have v = 0. Thus,  $U \cap W = \{0\}$ .

Now suppose,  $U \cap W = \{0\}$ . Let  $u \in U$  and  $w \in W$  such that 0 = u + w. This equation implies u = -w. By closure of additive inverses,  $u \in U \cap W$ . Hence, u = 0 from the assumption. This also implies w = 0. Theorem 1.4 implies U + W is a direct sum.

Show that the set U of differentiable functions  $f:(-1,1)\to\mathbb{R}$  such that f'(0)=f(0) is a subspace of  $\mathbb{R}^{(-1,1)}$ .

**Solution.** 0 is a differentiable function whose derivative is equal to its value at 0, so  $0 \in U$ . Suppose that  $f, g \in U$ . Then, f + g is differentiable and

$$(f+g)'(0) = f'(0) + g'(0) = f(0) + g(0) = (f+g)(0)$$

Therefore,  $f + g \in U$ . Moreover, for any  $c \in \mathbb{R}$ 

$$(cf)'(0) = cf'(0) = cf(0) = (cf)(0)$$

Thus,  $cf \in U$ . By Theorem 1.2, it follows that U is a subspace.

## Problem 1.8

Is  $\mathbb{R}^2$  a subspace of the complex vector space  $\mathbb{C}^2$ ?

**Solution.** The underlying field of  $\mathbb{C}^2$  is  $\mathbb{C}$ . The set  $\mathbb{R}^2$  is not closed with respect to scalar multiplication on  $\mathbb{C}$ . For example,  $i(1,1)=(i,i)\notin\mathbb{R}$ . Therefore,  $\mathbb{R}^2$  is not a subspace of  $\mathbb{C}^2$ .

#### Problem 1.9

Let  $U_1 = \{(a, b) \in \mathbb{R}^2 \mid a^3 = b^3\}$  and  $U_2 = \{(a, b) \in \mathbb{C}^2 \mid a^3 = b^3\}$ . Is  $U_1$  a subspace of  $\mathbb{R}^2$ ? Is  $U_2$  a subspace of  $\mathbb{C}$ ?

**Solution.** Over  $\mathbb{R}$ , the condition  $a^3 = b^3$  is equivalent to a = b. Thus,  $U_1 = \{(a, a) \in \mathbb{R}^2 \mid a \in \mathbb{R}\}$  is clearly a subspace of  $\mathbb{R}^2$ . In the complex numbers, the 3rd root of unity  $\omega \in \mathbb{C}$  satisfies the property  $\omega^3 = 1$ . Therefore,  $(1, 1), (1, \omega) \in U_2$ . However, their sum,  $(2, \omega + 1)$ , is not contained in  $U_2$ . Thus,  $U_2$  is not a subspace of  $\mathbb{C}^2$ .

## Problem 1.10

Give an example of a nonempty subset  $U \in \mathbb{R}^2$  that is closed under addition and under taking inverses, but U is not a subspace of  $\mathbb{R}^2$ .

**Solution.** Consider the integer lattice  $\mathbb{Z}^2 := \{(a,b) \mid a,b \in \mathbb{Z}\}$ . This subset of  $\mathbb{R}^2$  is closed under addition and taking additive inverses, but is not closed under scalar multiplication (e.g.  $\frac{1}{2}(a,b) \notin \mathbb{Z}^2$  for a or b odd).

# Problem 1.11

Give an example of a nonempty subset U of  $\mathbb{R}^2$  such that U is closed under scalar multiplication, but U is not a subspace of  $\mathbb{R}^2$ .

**Solution.** Consider the set  $U = \{(a,b) \in \mathbb{R}^2 \mid ab = 0\}$ . This is the set of points in the cartesian plane where at least one coordinate is 0. This set contains 0 = (0,0) and is closed under scalar multiplication. However, (1,0) and (0,1) are in U, but their sum (1,1) is not.

Prove that the intersection of any collection of subspaces of V is a subspace.

**Solution.** Suppose  $U_a$  is a subspace of V for all a in some indexing set  $\Gamma$ .  $0 \in U_a$  for all  $a \in \Gamma$ , so  $0 \in \bigcap_{a \in \Gamma} U_a$ . Furthermore, for any  $x, y \in \bigcap_{a \in \Gamma} U_a$ ,  $x, y \in U_a$  for each  $a \in \Gamma$ . Therefore,  $x + y \in U_a$  for each  $a \in \Gamma$  since each  $U_a$  is a subspace. Thus,  $x + y \in \bigcap_{a \in \Gamma} U_a$ . Let  $\lambda \in \mathbb{F}$ . For any  $x \in \bigcap_{a \in \Gamma} U_a$ ,  $x \in U_a$  for each  $a \in \Gamma$ . Therefore,  $\lambda x \in U_a$  for each  $a \in \Gamma$  since each  $U_a$  is a subspace. Thus,  $\lambda x \in \bigcap_{a \in \Gamma} U_a$ . By Theorem 1.2,  $\bigcap_{a \in \Gamma} U_a$  is a subspace of V.

# Problem 1.13

Prove that the union of two subspaces of V is a subspace of V if and only if one subspace is contained in the other subspace.

**Solution.** Let U, W be subspaces of V. Suppose,  $U \cup W$  is a subspace of V. For the sake of contradiction, assume neither U or W is contained in the other subspace. Then, there exists elements  $x \in U - W$  and  $y \in W - U$ . By the closure of addition,  $x + y \in U \cup W$ , so x + y is contained in either U, W, or both. If  $x + y \in U$ , then closure under addition implies  $y = (x + y) + (-x) \in U$ . This contradicts the definition of y. Similarly, if  $x + y \in W$ , then closure under addition implies  $x = (x + y) + (-y) \in W$ . This contradicts the definition of x. Therefore, the initial assumption that neither U or W is contained in the other subspace is false. This proves the forward direction. The proof in the other direction is trivial.

#### Problem 1.14

Prove that the union of three subspaces of V is a subspace of V if and only if one subspace contains two other subspaces.

**Solution.** Let  $U_1, U_2, U_3 \subset V$  be subspaces. Suppose  $U_1 \cup U_2 \cup U_3$  is a subspace of V.

If one of the subspaces contained another subspace, say  $U_3 \subset U_2$ , then  $U_1 \cup U_2 \cup U_3 = U_1 \cup U_2$ . Using the result from Problem 1.13, it follows that  $U_1 \subset U_2$  or  $U_2 \subset U_1$ . In either case, one subspace would contain two other subspaces.

If no subspace is contained within any other subspace, then there exists nonzero vectors  $u_1 \in U_1 - (U_2 \cup U_3)$  and  $u_2 \in U_2 - (U_1 \cup U_3)$ . Observe that  $u_1 + u_2, u_1 - u_2 \in U_3 - (U_1 \cup U_2)$ . Closure under addition implies  $u_1, u_2 \in U_3$ , a contradiction. Thus, one subspace must contain the other two subspaces. The proof in the other direction is trivial.

# Problem 1.15

Give an example of a vector space over a field other than  $\mathbb{R}$  or  $\mathbb{C}$  where Problem 1.14 fails.

**Solution.** Consider the vector space  $\mathbb{F}_2^2$  over the field  $\mathbb{F}_2$ . Consider the subspaces

$$U_1 = \{(0,0), (1,0)\}, \quad U_2 = \{(0,0), (0,1)\}, \quad U_3 = \{(0,0), (1,1)\}$$

None of these subspaces are proper subsets of each other yet  $\mathbb{F}_2^2 = U_1 \cup U_2 \cup U_3$ .

Chapter 2

# Finite Dimensional Vector Spaces

# 2.1 Span and Linear Independence

#### Linear Combinations and Span

A linear combination of a list  $v_1, \ldots, v_m$  of vectors in V is a vector of the form  $a_1v_1 + \cdots + a_mv_m$  with  $a_1, \ldots, a_m \in \mathbb{F}$ . The set of all linear combinations of a list  $v_1, \ldots, v_m$  of vectors in V is called the **span**. The span is denoted by

$$Span(v_1,...,v_m) = \{a_1v_1 + \cdots + a_mv_m \mid a_1,...,a_m \in \mathbb{F}\}\$$

The span of an empty list is defined to be the trivial subspace  $\{0\}$ .

# Theorem 2.1: Span is Smallest Containing Subspace

The span of a list of vectors in V is the smallest subspace of V containing all the vectors in the list.

Proof. Suppose  $v_1, \ldots, v_m$  is a list of vectors in V. Span $(v_1, \ldots, v_m)$  contains the additive identity, is closed under addition, and is closed under scalar multiplication. By theorem 1.2,  $\operatorname{Span}(v_1, \ldots, v_2)$  is a subspace of V. Obviously,  $v_i \in \operatorname{Span}(v_1, \ldots, v_m)$  for each  $i = 1, \ldots, m$ . Conversely, any subspace containing each  $v_i$  must contain  $\operatorname{Span}(v_1, \ldots, v_m)$  since subspaces are closed under addition and scalar multiplication. This completes the proof.

## Finite-Dimensional and Infinite-Dimensional

If  $\operatorname{Span}(v_1, \ldots, v_n) = V$ , we say that  $v_1, \ldots, v_n$  spans V. A vector space is called **finite-dimensional** if some finite list of vectors in it spans the space. If the vector space is not finite-dimensional, then it is called **infinite-dimensional**.

**Example.** Suppose n is a positive integer. Let  $e_i$  be a vector in  $\mathbb{F}^n$  whose ith component is 1 and the rest of the components are zero. Then for any  $x = (x_1, \dots, x_n) \in \mathbb{F}^n$ ,

$$x = x_1 e_1 + \dots + x_n e_n$$

Therefore, the Span $(e_1, \ldots, e_n) = \mathbb{F}^n$ . The collection  $\{e_i\}$  of vectors is called the **standard basis** vectors of  $\mathbb{F}^n$ . This result shows that  $\mathbb{F}^n$  is a finite dimensional vector space.

**Example.** Let  $\mathcal{P}$  denote the vector space of polynomials. The subspace  $\mathcal{P}_m$  is spanned by  $1, z, \ldots, z^m$  since any polynomial  $p(z) \in \mathcal{P}_m$  can be written as

$$p(z) = a_0 + a_1 z + \dots + a_m z^m$$

where  $a_0, \ldots, a_m \in \mathbb{F}$ . Therefore,  $\mathcal{P}_m$  is a finite-dimensional vector space. However, there is no finite list of polynomials that can span  $\mathcal{P}$  since  $\mathcal{P}$  contains polynomials unbounded in degree. Thus,  $\mathcal{P}$  is an infinite-dimensional vector space.

# Linear Independence and Linear Dependence

A list  $v_1, \ldots, v_m$  of vectors in V is called **linearly dependent** if the equation

$$a_1v_1 + \cdots + a_mv_m = 0$$

has a nontrivial solution. A list  $v_1, \ldots, v_m$  of vectors is called **linearly independent** if it is not linearly dependent. The empty list is defined to be linearly independent.

Linear independence/dependence arises naturally in the discussion of representation of vectors via linear combinations. Suppose  $v \in \text{Span}(v_1, \dots, v_m)$ . If v has two representations then

$$v = a_1 v_m + \dots + a_m v_m$$
$$v = b_1 v_m + \dots + b_m v_m$$

Subtracting two equations yields

$$0 = (a_1 - b_1)v_1 + \dots + (a_m - b_m)v_m$$

If the vectors are linearly independent, this equation only has the trivial solution where  $a_i - b_i = 0$  for all i = 1, ..., m. This means that the two representations were in fact the same. Therefore, any representation of a vector by a linear combination of linearly independent list of vectors must be unique. Had the list of vectors been linearly dependent, then the multiple representations of the vector as a linear combination of the same list of vectors would be possible. In this sense, linearly dependent lists of vectors contain redundant information. The following lemma demonstrates that removing the redundant information from a list of vectors does not change the span of the list.

#### Theorem 2.2: Linear Dependence Lemma

Suppose  $v_1, \ldots, v_m$  is a linearly dependent list in V. Then, there exists an index  $j \in \{1, \ldots, m\}$  such that

- (a)  $v_i \in \operatorname{Span}(v_1, v_{i-1})$
- (b)  $\operatorname{Span}(v_1, \dots, v_{j-1}, v_{j+1}, \dots, v_m) = \operatorname{Span}(v_1, \dots, v_m)$

*Proof.* For part (a), linear dependence implies that there exists a nontrivial solution to the equation

$$c_1v_1 + \dots + c_mv_m = 0$$

Thus there exists a largest index  $j \in \{1, ..., m\}$  such that  $c_j \neq 0$ . The equation can be rearranged as

$$v_j = \frac{c_1}{c_j}v_1 + \dots + \frac{c_{j-1}}{c_j}v_{j-1}$$

Thus,  $v_j \in \text{Span}(v_1, \dots, v_{j-1})$ , proving (a). Part (b) follows immediately by replacing  $v_j$  in the liner combination  $a_1v_1 + \dots + a_mv_m$  by the equation above. The resulting linear combination will include all of the vectors in the list except for  $v_j$ .