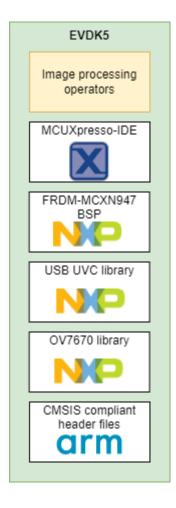
Embedded Vision Design

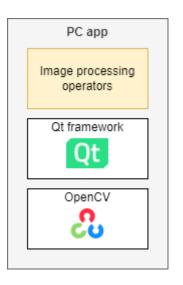
EVD1 Development basics

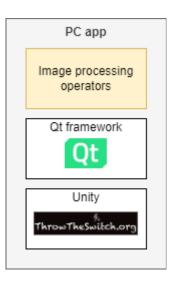
By Hugo Arends



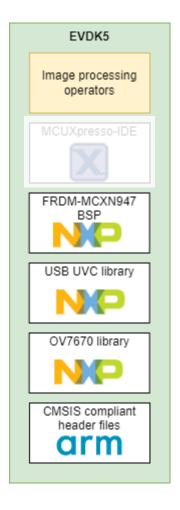
EVD1 – Tools and software

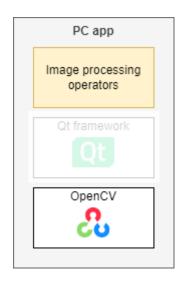






EVD1 – Tools and software







Tools vs software packages

- evdk5
 - evdk_images
 - evdk_operators
 - evdk_sheets
 - evdk_workspace_mcuxpresso
 - evdk_workspace_qt

Top level folder structure

- evdk5
 - evdk_images
 - evdk_operators
 - coding_and_compression.c
 - coding_and_compression.h
 - graphics_algorithms.c
 - graphics_algorithms.h
 - evdk_sheets
 - evdk_workspace_mcuxpresso
 - evdk_workspace_qt

Image processing source files, a file per class

- evdk5
 - evdk_images
 - evdk operators
 - evdk_sheets
 - evdk_workspace_mcuxpresso
 - frdmmcxn947_evdk5_0
 - .settings
 - board
 - CMSIS
 - ...
 - usb usb
 - utilities
 - video
 - cproject ...
 - .project
 - frdmmcxn947_evdk5_0.mex
 - evdk_workspace_qt

MCUXpresso-IDE resource files and drivers



evdk5 evdk_images evdk_operators evdk_sheets evdk_workspace_mcuxpresso frdmmcxn947_evdk5_0 .settings board CMSIS s usb utilities video .cproject .project frdmmcxn947_evdk5_0.mex evdk workspace qt

MCUXpresso-IDE resource files and drivers

- evdk5
 - evdk_images
 - evdk operators
 - evdk_sheets
 - evdk_workspace_mcuxpresso
 - evdk_workspace_qt
 - evdk5_histogram_file
 - evdk5_histogram_webcam
 - evdk5_unit_test
 - evdk5_webcam
 - evdk5_webcam.pro
 - main.cpp
 - utils

Qt example projects

- evdk5
 - evdk_images
 - **→ =** evdk_operators
 - evdk_sheets
 - evdk_workspace_mcuxpresso
 - evdk_workspace_qt
 - evdk5_histogram_file
 - evdk5_histogram_webcam
 - evdk5_unit_test
 - evdk5_webcam
 - evdk5_webcam.pro
 - main.cpp
 - utils

Qt example projects

- evdk5
 - evdk_images
 - evdk operators
 - evdk_sheets
 - evdk_workspace_mcuxpresso
 - evdk_workspace_qt
 - evdk5_histogram_file
 - evdk5_histogram_webcam
 - evdk5_unit_test
 - Unity
 - evdk5_test.pro
 - main.c
 - test_coding_and_compression.c
 - test_coding_and_compression.h
 - evdk5_webcam
 - utils

Qt unit test project



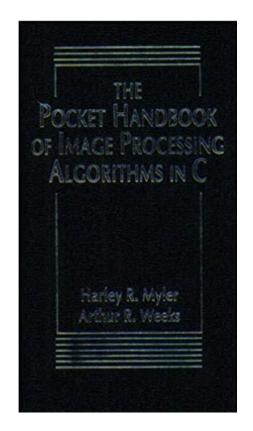
evdk5 evdk_images evdk_operators evdk_sheets evdk_workspace_mcuxpresso evdk_workspace_qt evdk5_histogram_file evdk5 histogram webcam evdk5_unit_test Unity evdk5_test.pro main.c test_coding_and_compression.c test_coding_and_compression.h evdk5_webcam utils

Qt unit test project

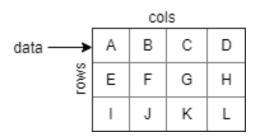
HAN_UNIVERSITY
OF APPLIED SCIENCES

```
/// Defines the type of images
typedef enum
{
    IMGTYPE_UINT8 = 1, ///< Pixels of type ::uint8_pixel_t.
    IMGTYPE_INT16 = 2, ///< Pixels of type ::int16_pixel_t.
    IMGTYPE_INT32 = 4, ///< Pixels of type ::int32_pixel_t.
    IMGTYPE_FLOAT = 8, ///< Pixels of type ::float_pixel_t.
    IMGTYPE_UYVY = 16, ///< Pixels of type ::uyvy_pixel_t.
    IMGTYPE_BGR888 = 32, ///< Pixels of type ::bgr888_pixel_t.
}eImageType;</pre>
```

Myler, H. R., & Weeks, A. R. (2009). *The pocket handbook of image processing algorithms in C.*Prentice Hall Press.



```
/// Defines the type of images
typedef enum
{
    IMGTYPE_UINT8 = 1, ///< Pixels of type ::uint8_pixel_t.
    IMGTYPE_INT16 = 2, ///< Pixels of type ::int16_pixel_t.
    IMGTYPE_INT32 = 4, ///< Pixels of type ::int32_pixel_t.
    IMGTYPE_FLOAT = 8, ///< Pixels of type ::float_pixel_t.
    IMGTYPE_UYVY = 16, ///< Pixels of type ::uyvy_pixel_t.
    IMGTYPE_BGR888 = 32, ///< Pixels of type ::bgr888_pixel_t.
}eImageType;</pre>
```



```
/// Defines the type of images
typedef enum
{
    IMGTYPE_UINT8 = 1, ///< Pixels of type ::uint8_pixel_t.
    IMGTYPE_INT16 = 2, ///< Pixels of type ::int16_pixel_t.
    IMGTYPE_INT32 = 4, ///< Pixels of type ::int32_pixel_t.
    IMGTYPE_FLOAT = 8, ///< Pixels of type ::float_pixel_t.
    IMGTYPE_UYVY = 16, ///< Pixels of type ::uyvy_pixel_t.
    IMGTYPE_BGR888 = 32, ///< Pixels of type ::bgr888_pixel_t.
}eImageType;</pre>
```

```
cols

data → A B C D

E F G H

I J K L
```

```
/// \brief Type definition of a uint8 pixel
///
/// 8 bits per pixel
typedef uint8_t uint8_pixel_t;
```

Memory allocation: 12×1 byte = 12 bytes



```
/// Defines the type of images
typedef enum
{
    IMGTYPE_UINT8 = 1, ///< Pixels of type ::uint8_pixel_t.
    IMGTYPE_INT16 = 2, ///< Pixels of type ::int16_pixel_t.
    IMGTYPE_INT32 = 4, ///< Pixels of type ::int32_pixel_t.
    IMGTYPE_FLOAT = 8, ///< Pixels of type ::float_pixel_t.
    IMGTYPE_UYVY = 16, ///< Pixels of type ::uyvy_pixel_t.
    IMGTYPE_BGR888 = 32, ///< Pixels of type ::bgr888_pixel_t.
}eImageType;</pre>
```

```
cols

data → A B C D

E F G H

I J K L
```

```
/// \brief Type definition of an int16 pixel
///
/// 16 bits per pixel
typedef int16_t int16_pixel_t;
```

Memory allocation: 12×2 bytes = 24 bytes



```
/// Defines the type of images
typedef enum
{
    IMGTYPE_UINT8 = 1, ///< Pixels of type ::uint8_pixel_t.
    IMGTYPE_INT16 = 2, ///< Pixels of type ::int16_pixel_t.
    IMGTYPE_INT32 = 4, ///< Pixels of type ::int32_pixel_t.
    IMGTYPE_FLOAT = 8, ///< Pixels of type ::float_pixel_t.
    IMGTYPE_UYVY = 16, ///< Pixels of type ::uyvy_pixel_t.
    IMGTYPE_BGR888 = 32, ///< Pixels of type ::bgr888_pixel_t.
}eImageType;</pre>
```

```
cols

data A B C D

E F G H

I J K L
```

```
/// \brief Type definition of an int32 pixel
///
/// 32 bits per pixel
typedef int32_t int32_pixel_t;
```

Memory allocation: $12 \times 4 \ bytes = 48 \ bytes$



```
/// Defines the type of images
typedef enum
{
    IMGTYPE_UINT8 = 1, ///< Pixels of type ::uint8_pixel_t.
    IMGTYPE_INT16 = 2, ///< Pixels of type ::int16_pixel_t.
    IMGTYPE_INT32 = 4, ///< Pixels of type ::int32_pixel_t.
    IMGTYPE_FLOAT = 8, ///< Pixels of type ::float_pixel_t.
    IMGTYPE_UYVY = 16, ///< Pixels of type ::uyvy_pixel_t.
    IMGTYPE_BGR888 = 32, ///< Pixels of type ::bgr888_pixel_t.
}eImageType;</pre>
```

```
cols

data → A B C D

E F G H

I J K L
```

```
/// \brief Type definition of a float pixel
///
/// 32 bits per pixel
typedef float float_pixel_t;
```

Memory allocation: $12 \times 4 \ bytes = 48 \ bytes$

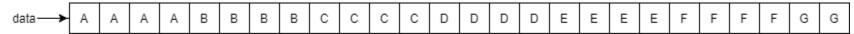


Image basics – Creating images

```
// Create an image
image_t *src = newUint8Image(4, 3);

// Use src in an image processing pipeline
// ...

// Cleanup
deleteUint8Image(src);
```

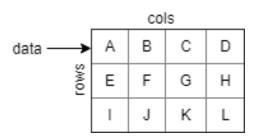
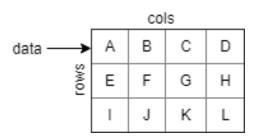


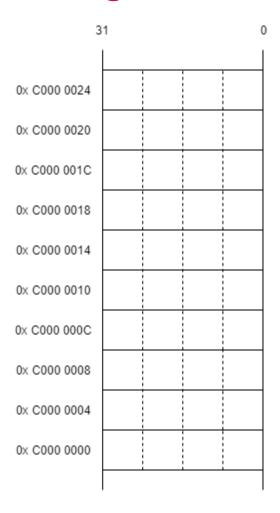
Image basics – Creating images

```
// Create an image
image_t *src = newFloatImage(4, 3);

// Use src in an image processing pipeline
// ...

// Cleanup
deleteFloatImage(src);
```





int a = 0;

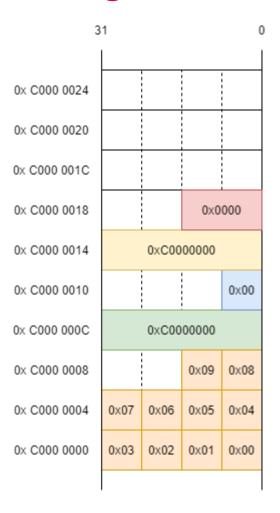
- 'a' is a variable, but what is a variable?
 name of a storage area
- What does the type of a variable tell?
 size and layout in memory
- How can we get the memory address of a variable?
 by using the reference operator: &

```
int *p1 = &a;
```

Why is this incorrect?

```
char *p2 = &a;
```

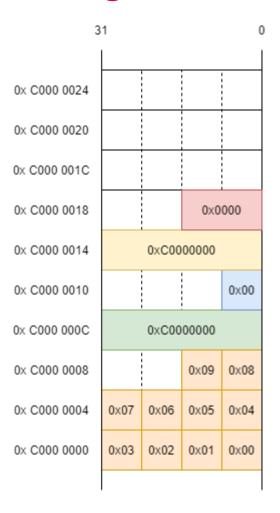
The base-type of the pointer is different from the base-type of the variable



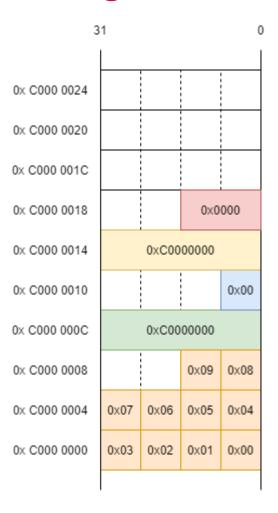
```
uint8_t data[10] = {0,1,2,3,4,5,6,7,8,9};
uint8_t *p = data; // alternative: &data[0]
uint8_t a = 0;
uint16_t *q = (uint16_t *)data;
uint16_t b = 0;
```

```
// Reading one element from the data array
a = data[3];  // a = 0x03
a = *(data+3); // a = 0x03
a = *(p+3);  // a = 0x03

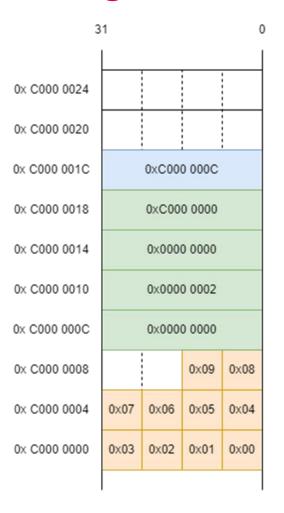
// Reading two elements from the data array
b = *(q+3);  // b = 0x0706
```



```
uint8_t data[10] = {0,1,2,3,4,5,6,7,8,9};
uint8_t *p = data; // alternative: &data[0]
uint8_t a = 0;
uint16_t *q = (uint16_t *)data;
uint16_t b = 0;
```



```
uint8_t data[10] = {0,1,2,3,4,5,6,7,8,9};
uint8_t *p = data; // alternative: &data[0]
uint8_t a = 0;
uint16_t *q = (uint16_t *)data;
uint16_t b = 0;
```



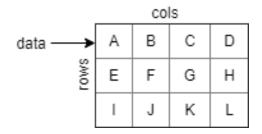
```
uint8_t data[10] = {0,1,2,3,4,5,6,7,8,9};
image_t image = {0,2,IMGTYPE_UINT8,data};
image_t *src = ℑ
```

```
// Image manipulation
image.cols = 5; // image = {5,2,0,0xC000 0000}
src->cols = 5; // image = {5,2,0,0xC000 0000}

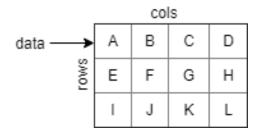
*((uint8_t *)src->data + 3) = 0; // data={0,1,2,0,4,5,6,7,8,9}

*((uint16_t *)src->data + 3) = 0;// data={0,1,2,3,4,5,0,0,8,9}
```

Use convenience functions for accessing pixels



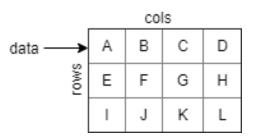
Use convenience functions for accessing pixels



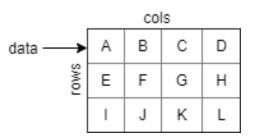
```
inline void setFloatPixel(const image_t *img, const int32_t c, const int32_t r, const float_pixel_t value)
{
    *((float_pixel_t *)(img->data) + (r * img->cols + c)) = value;
}

Explicit type cast to
    pixel type
    the offset
```

```
// Create a new image
image t *src = newUint8Image(4, 3);
// Clear the image
clearImage(src);
// Get the value of pixel B (1,0)
if(getUint8Pixel(src, 1, 0) == 0)
   // Set pixel G (2,1) to the value 100
    setUint8Pixel(src, 2, 1, 100);
// Cleanup
deleteUint8Image(src);
```

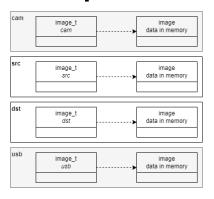


```
// Create a new image
image t *src = newFloatImage(4, 3);
// Clear the image
clearImage(src);
// Get the value of pixel B (1,0)
if(getFloatPixel(src, 1, 0) == 0)
   // Set pixel G (2,1) to the value 100
    setFloatPixel(src, 2, 1, 100);
// Cleanup
deleteFloatImage(src);
```



Anatomy of a project

MCUXpresso-IDE project



For running the image processing pipeline on the microcontroller

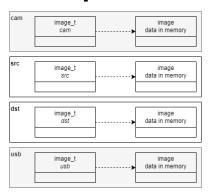
Qt & Unity unit test project



For unit testing the individual image processing operators

Anatomy of a project

MCUXpresso-IDE project



For running the image processing pipeline on the microcontroller

No hardware?

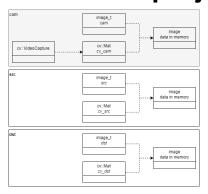
Qt & Unity unit test project



For unit testing the individual image processing operators

Anatomy of a project

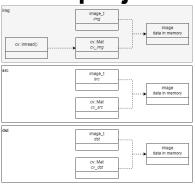
Qt webcam project



For running the image processing pipeline on your laptop with a webcam

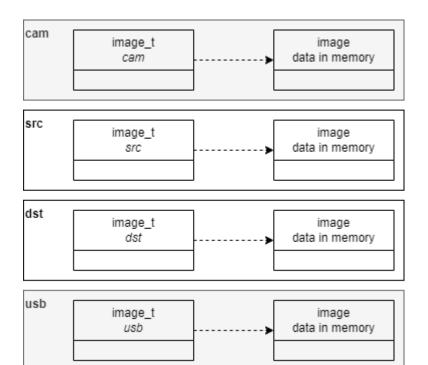
No hardware? No problem!

Qt file project



For running the image processing pipeline on your laptop with a file

Mandatory



Mandatory



```
void exampleThreshold(void)
  // -----
  // Local image memory allocation
  // -----
  image t *src = newUint8Image(EVDK5 WIDTH, EVDK5 HEIGHT);
  image t *dst = newUint8Image(EVDK5 WIDTH, EVDK5 HEIGHT);
  while(1U)
    // ----
    // Wait for camera image complete
    // -----
    while(smartdma camera image complete == 0)
    smartdma camera image complete = 0;
```

```
// ----
// Image processing pipeline
// -----
// Convert uyvy_pixel_t camera image to uint8_pixel_t image
convertToUint8(cam, src);

threshold(src, dst, 0, 64);

// Convert uint8_pixel_t image to bgr888_pixel_t image for USB
convertToBgr888(dst, usb);
}
```

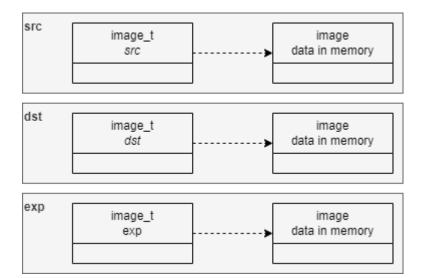
Demo



Mandatory

Mandatory

Mandatory





```
int main(void)
{
    UNITY_BEGIN();

RUN_TEST(test_threshold);

return UNITY_END();
}
```

```
void test_threshold(void)
{
    // Prepare image data
    uint8_pixel_t src_data[4] = {0, 32,128,255}
    uint8_pixel_t dst_data[4] = {0, 0, 0, 0}
    uint8_pixel_t exp_data[4] = {1, 1, 0, 0}

    // Prepare images: src, dst and exp
    image_t src = {2, 2, IMGTYPE_UINT8, src_data};
    image_t dst = {2, 2, IMGTYPE_UINT8, dst_data};
    image_t exp = {2, 2, IMGTYPE_UINT8, exp_data};
```

```
// Execute test
  threshold(&src, &dst, 0, 64);

#if 0
    // Print image data for debugging
    prettyprint(&src, "src");
    prettyprint(&exp, "exp");
    prettyprint(&dst, "dst");

#endif

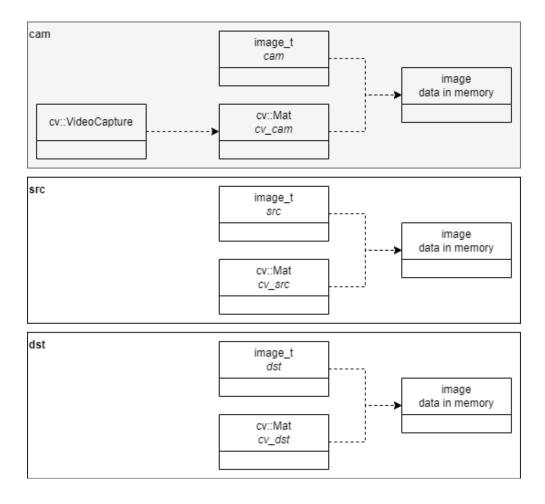
// Verify the destination to expected result
    TEST_ASSERT_EQUAL(exp,dst);
}
```

Demo



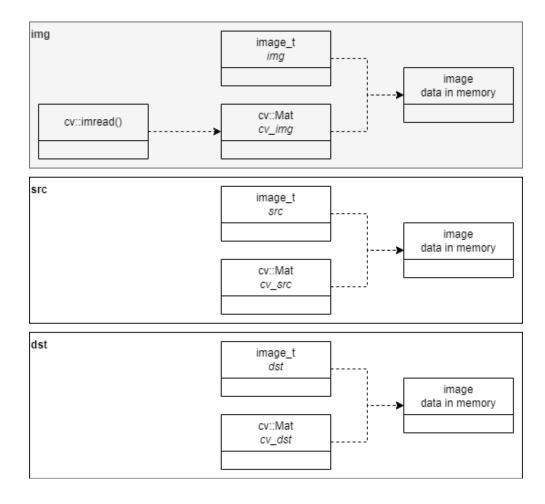
Anatomy of a Qt webcam project

Mandatory



Anatomy of a Qt file project

Mandatory



EVD1 – Assignment



Study guide Week 1

4 Change and run the MCUXpresso-IDE example project5 Run Qt Webcam project6 Run Qt and Unity unit test project