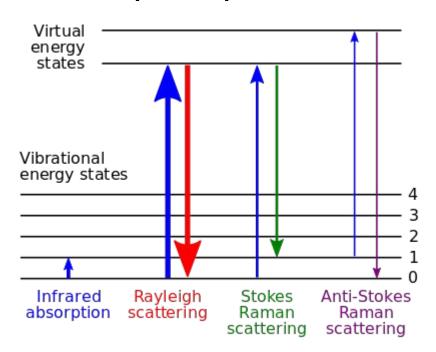
# RAMAN Spectroscopy of liver tissue samples

A pilot study

#### Raman principle



https://en.wikipedia.org/wiki/Raman\_spectroscopy

#### **Advantages**

- Optical, non contact, non invasive, non destructive technique
- Vibrational spectroscopy technique specific to chemical bonds
- Provides a fingerprint to identify molecules (Label-free technique)
- Mapping possibilities through XYZ scanning
- Can provide reference spectra to CARS and SRS imaging for increased spatial resolution

#### Instrumentation

Horiba LabRAM HR

Located at IESL

Optimizations:

- i) +785 nm laser source
- ii) +9 high refl. mirrors
- iii) obj lens 60X NA:1.2 W
- iv) Trans illumination
- v) temp stabilization



### The study...

#### Samples:

1 normal liver slice (8um thickness on CaF2 substrate)

1 malignant liver slice (8um thickness on CaF2 substrate)

#### Questions:

Can Raman spectroscopy differentiate them?

What more can we learn from it?

# Measurement settings

Laser source: 532nm, 100mW

Objective lens: x50, NA 0.50, air

Spot size: 1.3um spatial, 1.6um axial

Energy on the sample: 13mW

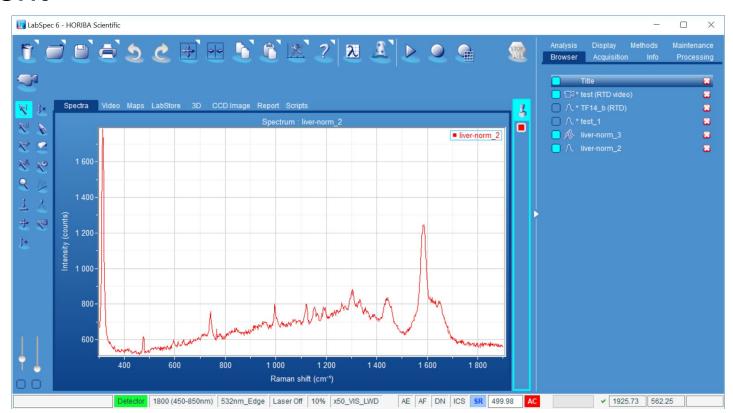
Exposure time: 30 sec/point, 9 accumulations

Spatial resolution: 3X9, 5um step

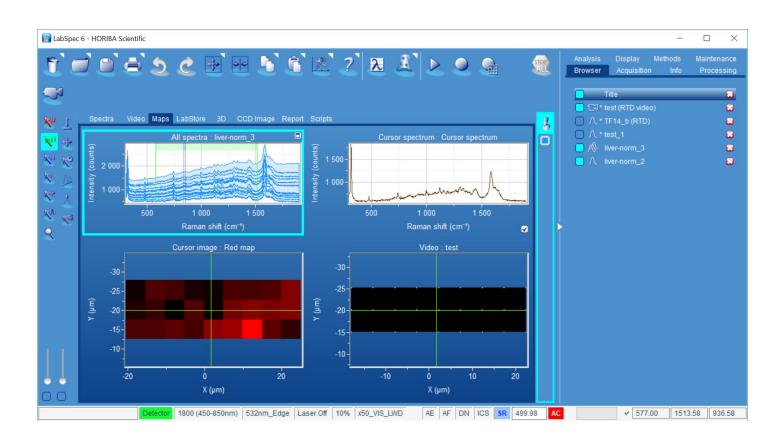
Measurement time: 2 hours

#### Measurement

Raman spectrum from normal liver tissue

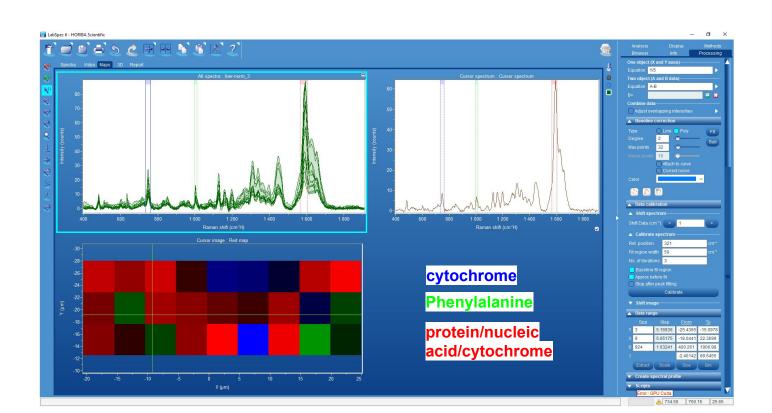


## Mapping



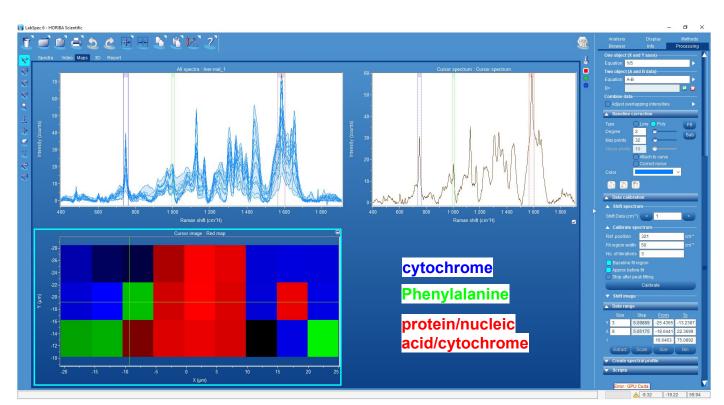
#### Pseudocolor imaging on individual tissue samples

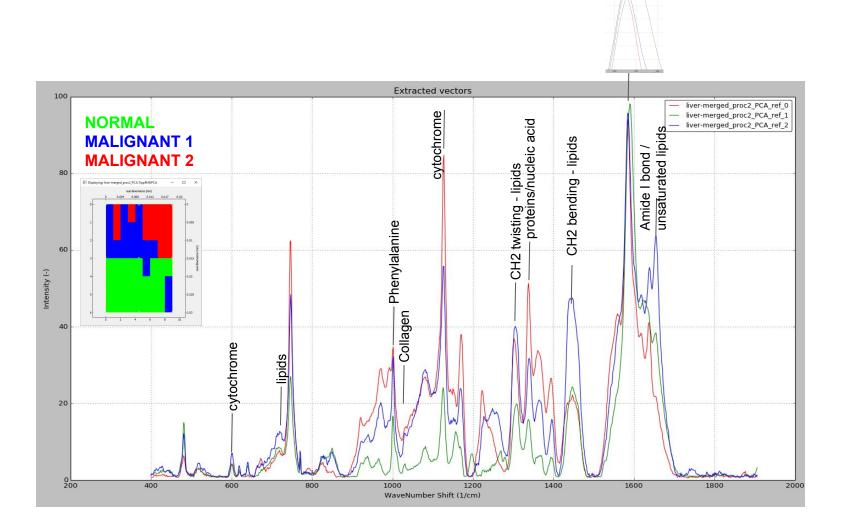
Normal



### Pseudocolor imaging on individual tissue samples

Malignant





#### Solutions

- Laser line at 785 nm (minimize autofluorescence <70%) to be tested soon
- Water immersion objective lens (increase signal by 3.5 times) under testing
- Surface tracing algorithms in progress
- Develop advanced machine learning algorithms under testing
- Develop the calibration methodology in progress
- Develop the reference spectra database in progress

### Problems, problems, problems...

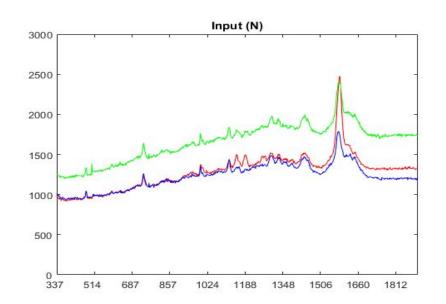
- 1. Raman is 10E-6 of the emitted signal so everything matters
- 2. Focal distance affects signal intensity
- 3. Background is different on every point due to AF
- 4. There is no calibration process to secure quantitative measurements
- 5. There is no specific reference database
- 6. Classification is currently performed on peaks comparison, manually

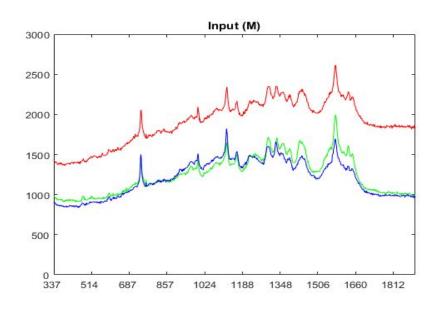
# Preliminary results from machine learning algorithms

Work on progress...

# Robust PCA (advanced signal processing)

Machine learning algorithms to extract repetitive information from large datasets.

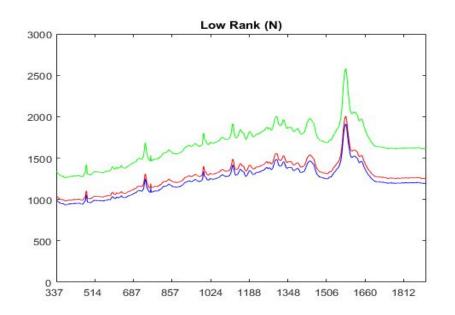


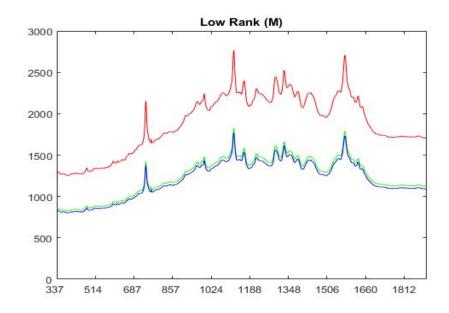


Each color line represents a random point on the image map

# Robust PCA (advanced signal processing)

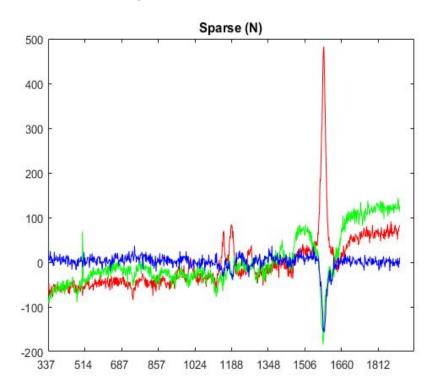
Identification of common Raman signal within the 27 spatial points of the map

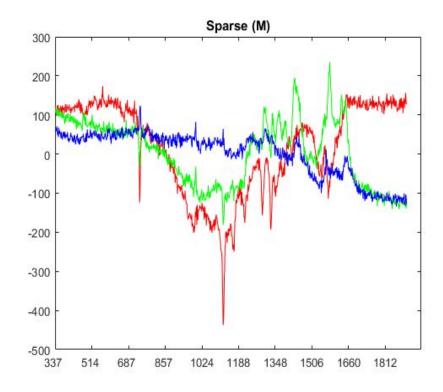




# Robust PCA (advanced signal processing)

Raman signal differences between the 27 spatial points of the map





Thank you for your attention!