Y86

- The Y86 is
- A simple subset of the IA32(Intel) architecture.
 - The IA32 has
 - · Too many instructions with an overly complicated encodeing
 - Too many addressing modes
 - Efficiency over simplicity
 - So we use a simplified version
- It has
 - 8 general-purpose 32-bit registers.
 - 1 program counter(PC)
 - 3 single-bit condition codes: ZF, SF, OF
 - 12 types of instruction

Y86 Instructions

- register/memory transfers:
 - rmmovl rA, D[rB] $M_{\Delta}[D + R[rB]] \leftarrow R[rA]$
 - Example: rmmovl %edx, \$0x20(%esi)
 - mrmovl D(rB), rA R[rA] ← M_4 [D + R[rB]]
 - Example: mrmovl \$0x10(%edx), %esi
- Other data transfer instructions
 - rrmovl rA, rB R[rB] ← R[rA]
 - irmovl V, rB R[rB] ← V
- Arithmetic instructions(operate on registers only)
 - addl rA, rB $R[rB] \leftarrow R[rB] + R[rA]$
 - subl rA, rB R[rB] ← R[rB]-R[rA]
 - and rA, rB $R[rB] \leftarrow R[rB] \& R[rA]$
 - xorl rA, rB R[rB] ← R[rB]^R[rA]
 - mull rA, rB R[rB] \leftarrow R[rB]*R[rA]
 - divl rA, rB R[rB] ← R[rB]/R[rA]
 - divl rA, rB R[rB] ← R[rB]%R[rA]

Y86 Instructions cont'

- Unconditional
 - jmp Dest PC <- Dest</p>
- Conditional jumps

jle Dest	$PC \leftarrow Dest if last result <=0$
– jl Dest	$PC \leftarrow Dest if last result \leq 0$
– je Dest	PC ← Dest if last result < 0
jne Dest	$PC \leftarrow Dest if last result \neq 0$
jge Dest	PC ← Dest if last result ≥ 0
– jg Dest	$PC \leftarrow Dest if last result > 0$

Conditional

_	cmovle rA, rB	$R[rB] \leftarrow R[rA]$ if last result ≤ 0
_	cmovl rA, rB	$R[rB] \leftarrow R[rA]$ if last result < 0
_	cmove rA, rB	$R[rB] \leftarrow R[rA]$ if last result = 0
_	cmovne rA, rB	$R[rB] \leftarrow R[rA]$ if last result $\neq 0$
_	cmovge rA, rB	$R[rB] \leftarrow R[rA]$ if last result ≥ 0
_	cmovg rA, rB	$R[rB] \leftarrow R[rA]$ if last result > 0

Example

```
C Example
                                                                      Y86:
                                IA32 Assembly:
Int start[] = { 4,7,8,9,12,11};
                                                                       .pos 0x100
                                sum_function:
                                movl $start, %edx
                                                      # int *str = start
int sum_function () {
                                                                      sum_function:
           int sum = 0;
                                                                      irmovl $start, %edx
                                                      # int sum = 0
                                xorl %eax, %eax
                                                                      xorl %eax %eax
           int count = 6;
                                .L2:
                                                                      L2:
           int *str=start;
                                addl (%rdx), %eax
                                                      #sum += *str
                                                                      mrmovl (%edx), %ebx
                                addq $4, %rdx
                                                      #str++, count--
                                                                      addl %ebx %eax
           while (count) {
                                cmpq $start+24, %rdx
                                                      #if count != 0
                                                                      irmovl $4, %ebx
           sum += *str;
                                                                      addl %ebx, %edx
                                jne .L2
                                                      #loop
           str++;
                                                                      irmovl $end, %ebx
           count--;
                                rep
                                                                      subl %edx, %ebx
                                ret
           }
                                                                      jne L2
           return sum;
                                                                      ret
}
                                                                       .pos 0x200
                                                                      start:
                                                                       . . .
                                                                      end:
```

Y86 instruction set encoding

Byte	()	1	l	2	3	4	5
halt	0	0						
nop	1	0						
rrmovl rA, rB	2	0	rA	rB				
$\mathtt{irmovl}\ V,\ rB$	3	0	F	rB		7	7	
$\mathtt{rmmovl}\ rA,D(rB)$	4	0	rA	rB		I)	
$\mathtt{mrmovl}\ D(rB),\ rA$	5	0	rA	rB		I)	
OP1 rA, rB	6	fn	rA	rB				_
jxx Dest	7	fn			Dest			
cmovXX rA, rB	2	fn	rA	rB				
call Dest	8	0			Dest			
ret	9	0						
pushl $\mathbf{r}\mathbf{A}$	Α	0	rA	F				
popl rA	В	0	rA	F				

Number	Register Name
_	-
0	%eax
1	%ecx
2	%edx
3	%ebx
4	%esp
5	%ebp
6	%esi
7	%edi
F	No register

	0	jmp
	1	jle
	2	jl
	თ	je
	4	jne
	5	jge
	6	jg
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fn jump

7 jump functions

fn	operation			
0	addl			
1	subl			
2	andl			
3	xorl			

Program register identifiers

Operations supported

Branches Moves **Operations** 4 addl 0 0 0 rrmovl cmovne jmp jne cmovle jle subl 7 1 5 1 5 6 1 cmovge jge cmovl andl 2 jΙ 2 6 2 cmovg 6 jg cmove 2 3 je 3 3 xorl