Neural Network Under the Hood

Handwritten digit recognition is a good first-lesson on image recognition for beginners.

The MNIST dataset consists 60000 training examples and 10000 test examples, of digits 0-9, can be downloaded from <u>Yann Lecun's</u> <u>website</u>.

In this project we will:

- Implement a 2-layer neural network.
- · Compute the forward pass and backward pass with softmax loss.
- · Use the normlizaiton to help network converge.
- Use a stochastic gradient descent to optimize the loss function.

Fully connected layer design

In this section, we define functions that are used to calculate forward propagationa and backward propagation in fully connected layer. Complete following unfinished functions.

In [26]:

```
import numpy as np
def affine forward(x, w, b):
   Computes the forward pass for an affine (fully-connected) layer.
   The input x has shape (N, d_1, \ldots, d_k) and contains a minibatch of N
   examples, where each example x[i] has shape (d 1, ..., d k). We will
   reshape each input into a vector of dimension D = d_1 * \dots * d_k, and
   then transform it to an output vector of dimension \overline{\mathbf{M}}.
   - x: A numpy array containing input data, of shape (N, d 1, ..., d k)
   - w: A numpy array of weights, of shape (D, M)
   - b: A numpy array of biases, of shape (M,)
   Returns a tuple of:
   - out: output, of shape (N, M)
   - cache: (x, w, b)
   out = None
   ********************************
   # TODO: Implement the affine forward pass. Store the result in out. You
   # will need to reshape the input into rows.
   N = x.shape[0] #the number of rows
   D = np.prod(x.shape[1:]) #D = d 1 * ... * d k
   x ND = np.reshape(x, (N, D))
   out = np.dot(x ND, w) + b
   ************
                               END OF YOUR CODE
   cache = (x, w, b)
   return out, cache
def affine_backward(dout, cache):
   Computes the backward pass for an affine layer.
   Inputs:
   - dout: Upstream derivative, of shape (N, M)
   - cache: Tuple of:
      - x: Input data, of shape (N, d 1, ... d k)
     - w: Weights, of shape (D, M)
   Returns a tuple of:
```

```
- \alpha x: Gradient with respect to x, of snape (N, \alpha 1, ..., \alpha K)
  - dw: Gradient with respect to w, of shape (D, M)
  - db: Gradient with respect to b, of shape (M,)
  x, w, b = cache
  dx, dw, db = None, None, None
  N = x.shape[0]
  D = np.prod(x.shape[1:])
  x_ND = np.reshape(x, (N, D))
  dx ND = np.dot(dout, w.T)
  dx = dx ND.reshape(x.shape)
  ************
  # TODO: Implement the affine backward pass. Calculate dw and db.
  # About two lines of code.
  ******************************
  dw = np.dot(x.reshape(N,D).T, dout)
  db = np.sum(dout, axis=0)
  ***********
                       END OF YOUR CODE
  ******************************
  return dx, dw, db
def relu forward(x):
  Computes the forward pass for a layer of rectified linear units (ReLUs).
  Input:
  - x: Inputs, of any shape
  Returns a tuple of:
  - out: Output, of the same shape as x
  - cache: x
  11 11 11
  out = None
  # TODO: Implement the ReLU forward pass. About One line of code.
  out = np.maximum(0,x)
  END OF YOUR CODE
  cache = x
  return out, cache
def relu backward(dout, cache):
  Computes the backward pass for a layer of rectified linear units (ReLUs).
  Input:
  - dout: Upstream derivatives, of any shape
  - cache: Input x, of same shape as dout
  Returns:
  - dx: Gradient with respect to x
  dx, x = None, cache
  **
  # TODO: Implement the ReLU backward pass. About one line of code.
  dx = np.array(dout, copy=True)
  ***********
                       END OF YOUR CODE
  *****************************
  return dx
def affine relu forward(x, w, b):
  Convenience layer that perorms an affine transform followed by a ReLU
  Inputs:
```

```
- x: Input to the affine layer
   - w, b: Weights for the affine layer
   Returns a tuple of:
   - out: Output from the ReLU
    - cache: Object to give to the backward pass
   a, fc_cache = affine_forward(x, w, b)
   out, relu cache = relu forward(a)
   cache = (fc cache, relu cache)
   return out, cache
def affine relu backward(dout, cache):
   Backward pass for the affine-relu convenience layer
   fc cache, relu cache = cache
   da = relu backward(dout, relu cache)
   dx, dw, db = affine backward(da, fc cache)
   return dx, dw, db
def softmax loss(x, y):
   Computes the loss and gradient for softmax classification.
   Inputs:
   - x: Input data, of shape (N, C) where x[i, j] is the score for the jth
     class for the ith input.
   - y: Vector of labels, of shape (N,) where y[i] is the label for x[i] and
     0 <= y[i] < C
   Returns a tuple of:
   - loss: Scalar giving the loss
    - dx: Gradient of the loss with respect to x
   shifted logits = x - np.max(x, axis=1, keepdims=True)
   Z = np.sum(np.exp(shifted_logits), axis=1, keepdims=True)
   log probs = shifted logits - np.log(Z)
   probs = np.exp(log_probs)
   N = x.shape[0]
   loss = -np.sum(log probs[np.arange(N), y]) / N
   dx = probs.copy()
   dx[np.arange(N), y] -= 1
   dx /= N
   return loss, dx
```

Two layer neural network model

In this section, we will use above functions to assemble our two layer fully connected neural network model, and define model methods such as loss, train, and predict. Complete following unfinished functions.

In [2]:

```
class TwoLayerNet(object):
    """
    A two-layer fully-connected neural network. The net has an input dimension of
    N, a hidden layer dimension of H, and performs classification over C classes.
    We train the network with a softmax loss function and L2 regularization on the
    weight matrices. The network uses a ReLU nonlinearity after the first fully
    connected layer.

In other words, the network has the following architecture:
    input - fully connected layer - ReLU - fully connected layer - softmax

The outputs of the second fully-connected layer are the scores for each class.
    """

def __init__(self, input_size, hidden_size, output_size, std=le-4):
    """
    Initialize the model. Weights are initialized to small random values and
    biases are initialized to zero. Weights and biases are stored in the
    variable self.params, which is a dictionary with the following keys:
```

```
W1: First layer weights; has shape (D, H)
   b1: First layer biases; has shape (H,)
   W2: Second layer weights; has shape (H, C)
   b2: Second layer biases; has shape (C,)
   - input size: The dimension D of the input data.
   - hidden_size: The number of neurons H in the hidden layer.
   - output size: The number of classes C.
   self.params = {}
   self.params['W1'] = std * np.random.randn(input size, hidden size)
   self.params['b1'] = np.zeros(hidden_size)
   self.params['W2'] = std * np.random.randn(hidden size, output size)
   self.params['b2'] = np.zeros(output size)
def loss(self, X, y=None, reg=0.0):
   Compute the loss and gradients for a two layer fully connected neural
   Inputs:
   - X: Input data of shape (N, D). Each X[i] is a training sample.
   - y: Vector of training labels. y[i] is the label for X[i], and each y[i] is
     an integer in the range 0 \le y[i] \le C. This parameter is optional; if it
     is not passed then we only return scores, and if it is passed then we
     instead return the loss and gradients.
   - reg: Regularization strength.
   Returns:
   If y is None, return a matrix scores of shape (N, C) where scores[i, c] is
   the score for class c on input X[i].
   If y is not None, instead return a tuple of:
   - loss: Loss (data loss and regularization loss) for this batch of training
   - grads: Dictionary mapping parameter names to gradients of those parameters
     with respect to the loss function; has the same keys as self.params.
   # Unpack variables from the params dictionary
   W1, b1 = self.params['W1'], self.params['b1']
   W2, b2 = self.params['W2'], self.params['b2']
   N, D = X.shape
   scores = None
   *************************
   # TODO: Perform the forward pass, computing the class scores for the input. #
   # Store the result in the scores variable, which should be an array of
   # shape (N, C). About 4 lines of codes.
   layer1_out, cache1 = affine_forward(X, W1, b1)
   layer1 out relu, cache1 relu = affine relu forward(X, W1, b1)
   layer2_out, cache2 = affine_forward(layer1_out_relu, W2, b2)
   scores = layer2 out
   END OF YOUR CODE
   # If the targets are not given then jump out, we're done
   if y is None:
       return scores
   # Compute the loss
   loss = None
   data_loss, dout = softmax_loss(scores, y)
   reg_loss = 0.5 * reg * (np.sum(W2*W2) + np.sum(W1*W1))
   loss = data loss + reg loss
   # Backward pass: compute gradients
   grads = \{\}
   dlayer1 out relu, dW2, db2 = affine backward(dout, cache2)
   dlayer1 out = relu backward(dlayer1 out relu, cache1 relu)
```

```
dx, dW1, db1 = affine backward(dlayer1 out, cache1)
   grads['bl'] = db1
   grads['W1'] = dW1 + 1 * reg * W1
   grads['b2'] = db2
   grads['W2'] = dW2 + 1 * reg * W2
   return loss, grads
def train(self, X, y, X_val, y_val,
        learning_rate=1e-3, learning_rate_decay=0.95,
        reg=5e-6, num iters=100,
        batch size=200, verbose=False):
   Train this neural network using stochastic gradient descent.
   - X: A numpy array of shape (N, D) giving training data.
   - y: A numpy array f shape (N,) giving training labels; y[i] = c means that
    X[i] has label c, where 0 \le c < C.
   - X val: A numpy array of shape (N val, D) giving validation data.
   - y_val: A numpy array of shape (N_val,) giving validation labels.
   - learning rate: Scalar giving learning rate for optimization.
   - learning rate decay: Scalar giving factor used to decay the learning rate
    after each epoch.
   - reg: Scalar giving regularization strength.
   - num iters: Number of steps to take when optimizing.
   - batch size: Number of training examples to use per step.
   - verbose: boolean; if true print progress during optimization.
   num train = X.shape[0]
   iterations per epoch = max(num train / batch size, 1)
   # Use SGD to optimize the parameters in self.model
   loss history = []
   train acc history = []
   val_acc_history = []
   for it in range(num_iters):
      X batch = None
      y batch = None
      # TODO: Create a random minibatch of training data and labels, storing #
      # them in X batch and y batch respectively.
      indices = np.random.choice(num_train, batch_size, replace=True)
      X batch = X[indices,:]
      y batch = y[indices]
      END OF YOUR CODE
      ****************
      # Compute loss and gradients using the current minibatch
      loss, grads = self.loss(X batch, y=y batch, reg=reg)
      loss history.append(loss)
      # TODO: Use the gradients in the grads dictionary to update the
      # parameters of the network (stored in the dictionary self.params)
      # using stochastic gradient descent. You'll need to use the gradients
      # stored in the grads dictionary defined above. About 4 lines of codes. #
      self.params['W1'] -= learning_rate*grads['W1']
      self.params['W2'] -= learning rate*grads['W2']
      self.params['b1'] -= learning_rate*grads['b1']
      self.params['b2'] -= learning_rate*grads['b2']
      END OF YOUR CODE
      if verbose and it % 100 == 0:
         print('iteration %d / %d: loss %f val acc %f' % (it,
```

```
num iters, loss, (self.predict(X val) == y val).mean()))
       # Every epoch, check train and val accuracy and decay learning rate.
       if it % iterations_per_epoch == 0:
          # Check accuracy
          train acc = (self.predict(X batch) == y batch).mean()
          val_acc = (self.predict(X_val) == y_val).mean()
          train acc history.append(train acc)
          val_acc_history.append(val_acc)
          # Decay learning rate
          learning_rate *= learning_rate_decay
   return {
       'loss_history': loss_history,
       'train acc history': train acc history,
       'val acc history': val acc history,
def predict(self, X):
   Use the trained weights of this two-layer network to predict labels for
   data points. For each data point we predict scores for each of the {\it C}
   classes, and assign each data point to the class with the highest score.
   - X: A numpy array of shape (N,\ D) giving N D-dimensional data points to
     classify.
   Returns:
   - y pred: A numpy array of shape (N,) giving predicted labels for each of
     the elements of X. For all i, y\_pred[i] = c means that X[i] is predicted
     to have class c, where 0 \le c < C.
   y_pred = None
   W1, b1 = self.params['W1'], self.params['b1']
   W2, b2 = self.params['W2'], self.params['b2']
   scores = None
   # TODO: Perform the forward pass, computing the class scores for the input. #
   # Store the result in the scores variable, which should be an array of
   # shape (N, C). About 4 lines of codes.
   *************************
   layer1_out, _ = affine_relu_forward(X, W1, b1)
   layer2 out, = affine relu forward(X, W2, b2)
   scores = layer2 out
   y pred = np.argmax(scores, axis=1)
   END OF YOUR CODE
   return y_pred
```

In [3]:

```
from keras.datasets import mnist
from __future__ import print_function

import matplotlib.pyplot as plt
import numpy as np
%matplotlib inline
plt.rcParams['figure.figsize'] = (8.0, 6.0) # set default size of plots
plt.rcParams['image.interpolation'] = 'nearest'
plt.rcParams['image.cmap'] = 'gray'

# Some more magic so that the notebook will reload external python modules;
# see http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-ipython
%load_ext autoreload
%autoreload 2
Using TensorFlow backend.
```

Load the data

From now on, you will see how the model you just built performs on MINIST handwritten digit dataset.

```
In [18]:
```

```
(X_train, y_train), (X_test, y_test) = mnist.load_data()
```

In [19]:

```
print("Loaded training images of shape:", X_train.shape)
print("Loaded training labels of shape:", y_train.shape)
print("Loaded test images of shape", X_test.shape)
print("Loaded test labels of shape", y_test.shape)
```

```
Loaded training images of shape: (60000, 28, 28)
Loaded training labels of shape: (60000,)
Loaded test images of shape (10000, 28, 28)
Loaded test labels of shape (10000,)
```

Show some random images

Show some random images to get a gut feeling of how the data looks like. Make sure row * col is less than the size of training set example number. To adjust the size of plot size, just modify: plt.rcParams['figure.figsize'] on the first code block.

In [20]:

```
row, col = 5, 10
idx = np.random.choice(X_train.shape[0], row*col, replace=False)
for i in range(row):
    for j in range(col):
        plt_idx = idx[i*col+j]
        plt.subplot(row, col, i*col+j+1)
        plt.title(y_train[plt_idx])
        plt.imshow(X_train[plt_idx,:,:])
        plt.axis('off')
```

```
2 7 8 0 3 6 3 5 8 3
2 7 8 0 3 6 5 5 8 3
2 3 6 7 8 5 8 8 8 7 8
2 8 6 7 8 5 8 8 8 7 8
2 8 6 1 1 9 3 3 8 8
2 8 6 1 7 8 1 9 3 3 8 8
2 8 6 1 7 8 1 9 3 3 8 8
4 6 1 7 8 1 9 3 3 8 8
4 6 1 7 8 1 6 1 9 5
4 6 1 7 8 1 6 1 9 5
4 6 8 8 8
```

Preprocess the data

Preprocess Part.1

in and part, we proprocess the data by.

- · Split training set data to train and validation.
- · Normalize the data

In [21]:

```
# Split the data into train, val, and test sets.
num training = 50000
num_validation = 10000
num test = 10000
# Our validation set will be num_validation points from the original
# training set.
mask = range(num_training, num_training + num_validation)
X_val = X_train[mask]
y_val = y_train[mask]
# Our training set will be the first num train points from the original
# training set.
mask = range(num training)
X train = X train[mask]
y train = y train[mask]
# We use the first num test points of the original test set as our
# test set.
mask = range(num_test)
X \text{ test} = X \text{ test[mask]}
y_test = y_test[mask]
# Normalize the data: subtract the mean image
mean image = np.mean(X train, axis=0, dtype=X train.dtype)
X train -= mean image
X val -= mean image
X test -= mean image
print('Train data shape: ', X train.shape)
print('Train labels shape: ', y_train.shape)
print('Validation data shape: ', X_val.shape)
print('Validation labels shape: ', y val.shape)
print('Test data shape: ', X_test.shape)
print('Test labels shape: ', y test.shape)
Train data shape: (50000, 28, 28)
Train labels shape: (50000,)
Validation data shape: (10000, 28, 28)
Validation labels shape: (10000,)
Test data shape: (10000, 28, 28)
Test labels shape: (10000,)
```

Preprocess Part.2

Reshape the 3 dimension data to a [N * (row * col)] 2 dimension matrix. N is the number of examples, (row, col) is the shape of an example image.

```
In [22]:
```

```
# Preprocessing: reshape the image data into rows
X_train = np.reshape(X_train, (X_train.shape[0], -1))
X_val = np.reshape(X_val, (X_val.shape[0], -1))
X_test = np.reshape(X_test, (X_test.shape[0], -1))

# As a sanity check, print out the shapes of the data
print('Training data shape: ', X_train.shape)
print('Validation data shape: ', X_val.shape)
print('Test data shape: ', X_test.shape)
```

Training data shape: (50000, 784) Validation data shape: (10000, 784) Test data shape: (10000, 784)

Overfit Small Dataset

Training with a small dataset, i.e. a training set with 1000 example images, we should see an overfitting model.

```
In [23]:
```

```
# Preprocessing: reshape the image data into rows
X_train_small = X_train[:1000, :]
y_train_small = y_train[:1000]
# As a sanity check, print out the shapes of the data
print('Training data shape: ', X train small.shape)
print('Validation data shape: ', X val.shape)
print('Test data shape: ', X_test.shape)
Training data shape: (1000, 784)
Validation data shape: (10000, 784)
Test data shape: (10000, 784)
In [27]:
input size = 28 * 28
hidden size = 50
num classes = 10
net = TwoLayerNet(input size, hidden size, num classes)
# Train the network
stats = net.train(X train small, y train small, X val, y val,
            num iters=1000, batch size=50,
            learning rate=1e-3, learning rate decay=0.99,
            reg=0.5, verbose=True)
# Predict on the validation set
val acc = (net.predict(X val) == y val).mean()
train acc = (net.predict(X train small) == y train small).mean()
print('Validation accuracy: ', val_acc)
print('Train accuracy: ', train acc)
iteration 0 / 1000: loss 2.302685 val acc 0.152800
iteration 100 / 1000: loss 0.613273 val acc 0.789800
iteration 200 / 1000: loss 0.264332 val acc 0.839000
iteration 300 / 1000: loss 0.335980 val_acc 0.862600
iteration 400 / 1000: loss 0.253564 val_acc 0.867700
iteration 500 / 1000: loss 0.126698 val acc 0.872800
iteration 600 / 1000: loss 0.173782 val_acc 0.872600
iteration 700 / 1000: loss 0.134153 val acc 0.869900
iteration 800 / 1000: loss 0.124028 val_acc 0.875600
iteration 900 / 1000: loss 0.135791 val acc 0.875400
Validation accuracy:
                      0.8753
Train accuracy: 1.0
In [28]:
# Plot the loss function and train / validation accuracies
plt.rcParams['fiqure.fiqsize'] = (20.0, 10.0) # set default size of plots
plt.rcParams['image.interpolation'] = 'none'
plt.subplot(2, 1, 1)
plt.plot(stats['loss history'])
plt.title('Loss history')
plt.xlabel('Iteration')
plt.ylabel('Loss')
plt.subplot(2, 1, 2)
plt.plot(stats['train acc history'], 'r', label='train')
```

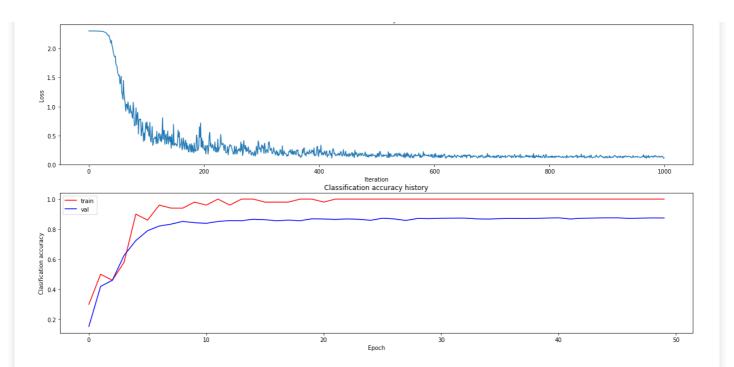
plt.plot(stats['val_acc_history'], 'b', label='val')

plt.title('Classification accuracy history')

plt.ylabel('Clasification accuracy')

plt.xlabel('Epoch')

plt.legend()
plt.show()



Training

Train a two layer neural network, update gradients with mini-batch data, optimize the loss with SGD.

```
In [29]:
```

```
input size = 28 * 28
hidden size = 200
num classes = 10
net = TwoLayerNet(input size, hidden size, num classes)
# Train the network
stats = net.train(X_train, y_train, X_val, y_val,
            num_iters=10000, batch_size=200,
            learning_rate=1e-3, learning_rate_decay=0.99,
            reg=0.2, verbose=True)
# Predict on the validation set
val_acc = (net.predict(X_val) == y_val).mean()
train acc = (net.predict(X train) == y train).mean()
print('Validation accuracy: ', val acc)
print('Train accuracy: ', train_acc)
iteration 0 / 10000: loss 2.302719 val acc 0.177200
iteration 100 / 10000: loss 0.533684 val_acc 0.853200
iteration 200 / 10000: loss 0.434884 val_acc 0.903300
iteration 300 / 10000: loss 0.426916 val acc 0.915500
iteration 400 / 10000: loss 0.329449 val_acc 0.923200
iteration 500 / 10000: loss 0.280096 val acc 0.930100
iteration 600 / 10000: loss 0.364125 val_acc 0.934200
iteration 700 / 10000: loss 0.230049 val_acc 0.944400
iteration 800 / 10000: loss 0.236645 val acc 0.943900
iteration 900 / 10000: loss 0.342598 val_acc 0.949800
iteration 1000 / 10000: loss 0.243022 val acc 0.950500
iteration 1100 / 10000: loss 0.197612 val acc 0.955100
iteration 1200 / 10000: loss 0.194853 val_acc 0.956800
iteration 1300 / 10000: loss 0.203275 val_acc 0.953800
iteration 1400 / 10000: loss 0.199616 val acc 0.959200
iteration 1500 / 10000: loss 0.204042 val_acc 0.960100
iteration 1600 / 10000: loss 0.220454 val acc 0.961300
iteration 1700 / 10000: loss 0.155319 val_acc 0.961400
iteration 1800 / 10000: loss 0.165589 val_acc 0.963400
iteration 1900 / 10000: loss 0.136104 val acc 0.964800
iteration 2000 / 10000: loss 0.171988 val_acc 0.964200
iteration 2100 / 10000: loss 0.191535 val acc 0.964200
iteration 2200 / 10000: loss 0.105715 val acc 0.966600
iteration 2300 / 10000: loss 0.157572 val_acc 0.966600
iteration 2400 / 10000: loss 0.126533 val acc 0.968800
iteration 2500 / 10000: loss 0.214473 val acc 0.969700
```

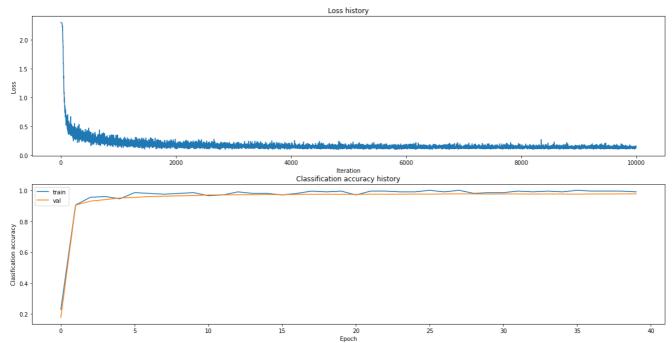
```
iteration 2600 / 10000: loss 0.196497 val acc 0.968000
iteration 2700 / 10000: loss 0.144251 val acc 0.969000
iteration 2800 / 10000: loss 0.197445 val acc 0.971300
iteration 2900 / 10000: loss 0.139035 val acc 0.971200
iteration 3000 / 10000: loss 0.136912 val acc 0.971300
iteration 3100 / 10000: loss 0.147913 val acc 0.971700
iteration 3200 / 10000: loss 0.160672 val acc 0.972100
iteration 3300 / 10000: loss 0.197933 val acc 0.970900
iteration 3400 / 10000: loss 0.132309 val acc 0.971700
iteration 3500 / 10000: loss 0.171102 val_acc 0.973300
iteration 3600 / 10000: loss 0.142207 val acc 0.970200
iteration 3700 / 10000: loss 0.143968 val acc 0.972800
iteration 3800 / 10000: loss 0.110243 val acc 0.972600
iteration 3900 / 10000: loss 0.146029 val acc 0.973100
iteration 4000 / 10000: loss 0.150605 val acc 0.973500
iteration 4100 / 10000: loss 0.132614 val acc 0.972900
iteration 4200 / 10000: loss 0.136608 val acc 0.972700
iteration 4300 / 10000: loss 0.163693 val acc 0.974300
iteration 4400 / 10000: loss 0.140017 val acc 0.974200
iteration 4500 / 10000: loss 0.121542 val acc 0.974600
iteration 4600 / 10000: loss 0.155492 val_acc 0.972800
iteration 4700 / 10000: loss 0.135610 val acc 0.974200
iteration 4800 / 10000: loss 0.144333 val_acc 0.973400
iteration 4900 / 10000: loss 0.115592 val acc 0.974800
iteration 5000 / 10000: loss 0.185787 val acc 0.973100
iteration 5100 / 10000: loss 0.130683 val_acc 0.973600
iteration 5200 / 10000: loss 0.142447 val acc 0.975000
iteration 5300 / 10000: loss 0.144028 val acc 0.974600
iteration 5400 / 10000: loss 0.146262 val acc 0.974400
iteration 5500 / 10000: loss 0.149073 val acc 0.974800
iteration 5600 / 10000: loss 0.138471 val acc 0.976000
iteration 5700 / 10000: loss 0.119887 val_acc 0.975000
iteration 5800 / 10000: loss 0.137560 val acc 0.975900
iteration 5900 / 10000: loss 0.125048 val acc 0.975700
iteration 6000 / 10000: loss 0.131658 val acc 0.975600
iteration 6100 / 10000: loss 0.116091 val acc 0.975800
iteration 6200 / 10000: loss 0.143486 val acc 0.976000
iteration 6300 / 10000: loss 0.114278 val_acc 0.976300
iteration 6400 / 10000: loss 0.178906 val acc 0.975800
iteration 6500 / 10000: loss 0.155745 val acc 0.976300
iteration 6600 / 10000: loss 0.117829 val acc 0.975600
iteration 6700 / 10000: loss 0.135782 val acc 0.974800
iteration 6800 / 10000: loss 0.122516 val_acc 0.976200
iteration 6900 / 10000: loss 0.118114 val acc 0.976500
iteration 7000 / 10000: loss 0.158092 val acc 0.976700
iteration 7100 / 10000: loss 0.111261 val acc 0.976000
iteration 7200 / 10000: loss 0.135220 val acc 0.975300
iteration 7300 / 10000: loss 0.143181 val acc 0.975500
iteration 7400 / 10000: loss 0.126919 val acc 0.976000
iteration 7500 / 10000: loss 0.153724 val acc 0.976500
iteration 7600 / 10000: loss 0.142910 val acc 0.976400
iteration 7700 / 10000: loss 0.145408 val acc 0.976000
iteration 7800 / 10000: loss 0.171962 val_acc 0.976400
iteration 7900 / 10000: loss 0.138958 val_acc 0.976700
iteration 8000 / 10000: loss 0.132925 val acc 0.975700
iteration 8100 / 10000: loss 0.151823 val acc 0.976100
iteration 8200 / 10000: loss 0.137548 val acc 0.976300
iteration 8300 / 10000: loss 0.114512 val acc 0.977100
iteration 8400 / 10000: loss 0.128543 val_acc 0.976700
iteration 8500 / 10000: loss 0.133159 val acc 0.975800
iteration 8600 / 10000: loss 0.118869 val acc 0.977200
iteration 8700 / 10000: loss 0.148800 val acc 0.977200
iteration 8800 / 10000: loss 0.122814 val acc 0.976300
iteration 8900 / 10000: loss 0.115378 val acc 0.976200
iteration 9000 / 10000: loss 0.132593 val acc 0.976200
iteration 9100 / 10000: loss 0.132601 val acc 0.976200
iteration 9200 / 10000: loss 0.133463 val acc 0.977000
iteration 9300 / 10000: loss 0.147167 val acc 0.977100
iteration 9400 / 10000: loss 0.128048 val_acc 0.977100
iteration 9500 / 10000: loss 0.124990 val_acc 0.976500
iteration 9600 / 10000: loss 0.123781 val_acc 0.976000
iteration 9700 / 10000: loss 0.110632 val acc 0.977200
iteration 9800 / 10000: loss 0.122848 val acc 0.976800
iteration 9900 / 10000: loss 0.144337 val acc 0.977100
Validation accuracy: 0.9758
Train accuracy: 0.9875
```

Debug the training

The loss history indicates whether loss is converging. Overfitting or underfitting can be observed from classification accuracy history. If there is a big gap between training accuracy and validation accuracy curves, the model is highly possible overfitting. Else if the training accuracy is low, and validation accuracy alike, the model might be underfitting. To avoid such occasions, fine tune the parameters with your observation on the plots.

In [30]:

```
# Plot the loss function and train / validation accuracies
plt.rcParams['figure.figsize'] = (20.0, 10.0) # set default size of plots
plt.rcParams['image.interpolation'] = 'none'
plt.subplot(2, 1, 1)
plt.plot(stats['loss history'])
plt.title('Loss history')
plt.xlabel('Iteration')
plt.ylabel('Loss')
plt.subplot(2, 1, 2)
plt.plot(stats['train acc history'], label='train')
plt.plot(stats['val_acc_history'], label='val')
plt.title('Classification accuracy history')
plt.xlabel('Epoch')
plt.ylabel('Clasification accuracy')
plt.legend()
plt.show()
```



Performance of the model

Now it's time to finally evaluate our model, with test set data.

```
In [31]:
```

```
test_acc = (net.predict(X_test) == y_test).mean()
print('Test accuracy: ', test_acc)
```

Test accuracy: 0.9771

Show some random image and predict using our model

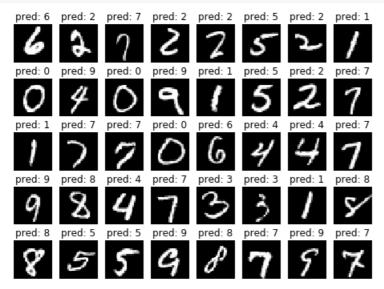
```
In [32]:
```

```
plt.rcParams['figure.figsize'] = (8.0, 6.0) # set default size of plots
plt.rcParams['image.interpolation'] = 'nearest'

row, col = 5, 8
y_test_pred = net.predict(X_test)
X_test_image = X_test.reshape(-1, 28, 28)
idx = np.random.choice(X_test.shape[0], row*col, replace=False)

for i in range(row):
    for j in range(col):
        plt_idx = idx[i*col+j]
        plt.subplot(row, col, i*col+j+1)
        plt.titple('pred: ' + str(y_test_pred[plt_idx]))
        plt.imshow(X_test_image[plt_idx,:,:])
        plt.axis('off')

plt.show()
```



Conclusion

Congratulations! You have successfully finished this project! The 2-layer plain neural network should accquire an accuracy of ~97.75%.

In []: