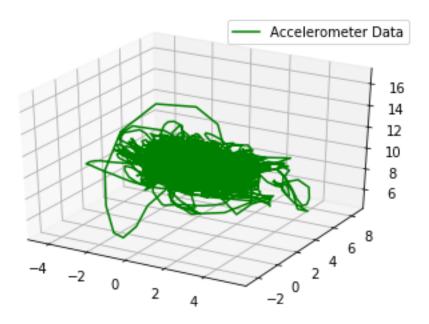
math178_hw06_jkath

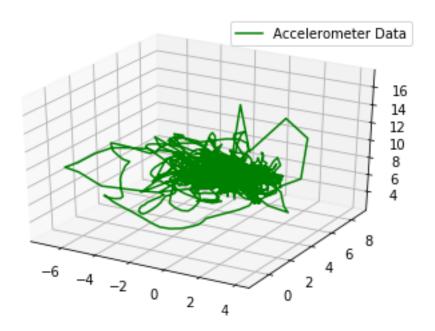
June 25, 2019

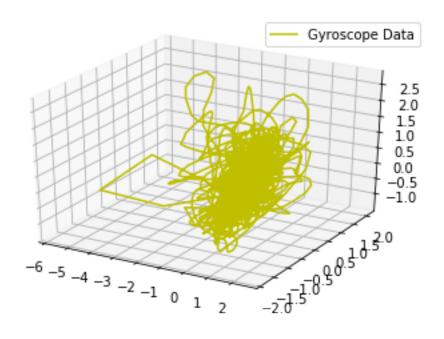
```
In [1]: """
        Created on Sun June 23 2019
        Qauthor: John Kath
        11 11 11
        # This import registers the 3D projection, but is otherwise unused.
        from mpl_toolkits.mplot3d import Axes3D # noqa: F401 unused import
        from pathlib import Path
        from typing import List
        import pandas as pd
        from pandas import DataFrame
        import numpy as np
        import matplotlib.pyplot as plt
In [2]: # data pre processing
        file_name_to_colume_names = {
            'Accelerometer.csv': ['Systime', 'EventTime', 'ActivityID', 'X', 'Y', 'Z', 'Phone_
            'Gyroscope.csv': ['Systime', 'EventTime', 'ActivityID', 'X', 'Y', 'Z', 'Phone_orie:
        }
In [3]: def read_file(user_id: str, user_session_id: str, file_name: str, colume_names: List[s:
            Read one of the csv files for a user
            :param user_id: user id
            :param user_session_id: user session id
            :param file_name: csv file name (key of file_name_to_colume_names)
            :param colume_names: a list of column names of the csv file (value of file_name_to
            :return: content of the csv file as pandas DataFrame
            # read data from csv
            filename = user_id + '_session_' + user_session_id + '_' + file_name
            csv_data = pd.read_csv(filename, names=colume_names)
            return pd.DataFrame(data=csv_data)
In [4]: # pick the user as well as activities and extract 3 out of 6 features
        data_acc = read_file('984799', '16', 'Accelerometer.csv', file_name_to_colume_names['A
        data_gyr = read_file('984799', '16', 'Gyroscope.csv', file_name_to_colume_names['Gyroscope.csv']
```

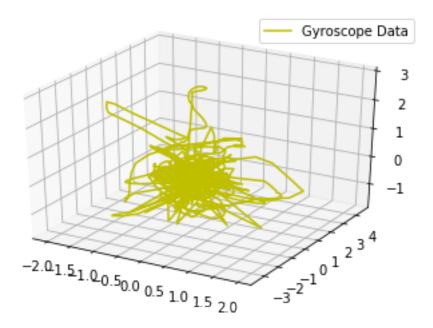
```
# print(data_acc.dtypes)
        # print(data_gyr.dtypes)
In [5]: # pick the user as well as activities and extract 3 out of 6 features
        data_acc_2 = read_file('151985', '2', 'Accelerometer.csv', file_name_to_colume_names['.
        data_gyr_2 = read_file('151985', '2', 'Gyroscope.csv', file_name_to_colume_names['Gyroscope.csv']
        # print(data_acc.dtypes)
        # print(data_gyr.dtypes)
In [6]: def plot_parametric_feature(x, y, z, label_name, color_name):
            # 3d parametric plot of feature
            plt.rcParams['legend.fontsize'] = 10
            fig = plt.figure()
            ax = fig.gca(projection='3d')
            ax.plot(x, y, z, label=label_name, color=color_name)
            ax.legend()
            plt.show()
In [7]: # visualize of the features you pick
        x_val = data_acc['X']
        y_val = data_acc['Y']
        z_val = data_acc['Z']
        plot_parametric_feature(x_val, y_val, z_val, 'Accelerometer Data', 'g')
```



```
In [8]: # visualize of the features you pick
    x_val = data_acc_2['X']
    y_val = data_acc_2['Y']
    z_val = data_acc_2['Z']
    plot_parametric_feature(x_val, y_val, z_val, 'Accelerometer Data', 'g')
```







```
In [11]: def plot_unit_sphere_feature(x, y, z, label_name, color_name):
             # 3d parametric plot of feature
             plt.rcParams['legend.fontsize'] = 10
             fig = plt.figure()
             ax = fig.gca(projection='3d')
             # make data for the sphere surface
             u = np.linspace(0, 2 * np.pi, 100)
             v = np.linspace(0, np.pi, 100)
             x_s = np.outer(np.cos(u), np.sin(v))
             y_s = np.outer(np.sin(u), np.sin(v))
             z_s = np.outer(np.ones(np.size(u)), np.cos(v))
             # plot the sphere surface
             ax.plot_surface(x_s, y_s, z_s,alpha=0.1)
             # plot the date points of normalized df_pick3 on the sphere
             ax.scatter(x, y, z, label=label_name, color=color_name)
             ax.legend()
             plt.show()
In [12]: def normalize(v: np.ndarray) -> np.ndarray:
             Calculate normalized vector
```

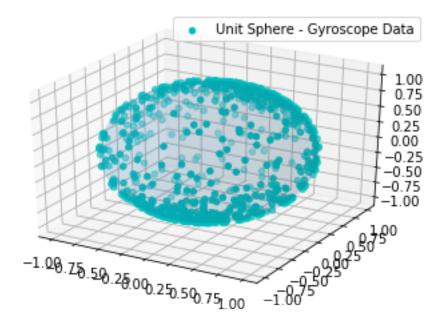
```
:param v: input vector
:return: normalized vector
"""

norm_v = np.linalg.norm(v)
if norm_v != 0:
    normalize_v = v / norm_v
else:
    normalize_v = v
return normalize v
```

In [13]: # calucate normalized vector and plot on sphere for the features you pick

```
data = data_gyr
unit_sphere_data = []
step_size = 50
for i in range(0, len(data['Systime']) - step_size, step_size):
    v = [data['X'][i], data['Y'][i], data['Z'][i]]
    unit_sphere_data.append(normalize(v).tolist())

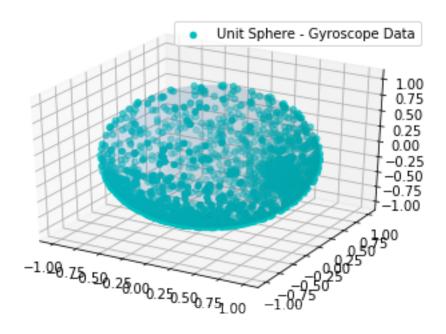
x_val = [row[0] for row in unit_sphere_data]
y_val = [row[1] for row in unit_sphere_data]
z_val = [row[2] for row in unit_sphere_data]
plot_unit_sphere_feature(x_val, y_val, z_val, 'Unit Sphere - Gyroscope Data', 'c')
```



In [14]: # calucate normalized vector and plot on sphere for the features you pick
 data = data_gyr_2

```
unit_sphere_data = []
step_size = 50
for i in range(0, len(data['Systime']) - step_size, step_size):
    v = [data['X'][i], data['Y'][i], data['Z'][i]]
    unit_sphere_data.append(normalize(v).tolist())

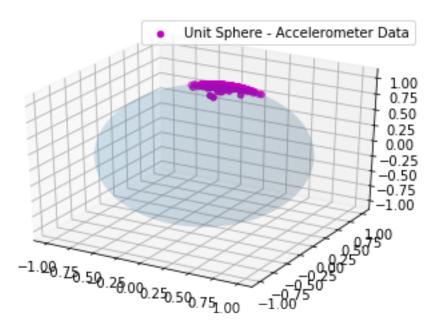
x_val = [row[0] for row in unit_sphere_data]
y_val = [row[1] for row in unit_sphere_data]
z_val = [row[2] for row in unit_sphere_data]
plot_unit_sphere_feature(x_val, y_val, z_val, 'Unit Sphere - Gyroscope Data', 'c')
```



In [15]: # calucate normalized vector and plot on sphere for the features you pick

```
data = data_acc
unit_sphere_data = []
step_size = 50
for i in range(0, len(data['Systime']) - step_size, step_size):
    v = [data['X'][i], data['Y'][i], data['Z'][i]]
    unit_sphere_data.append(normalize(v).tolist())

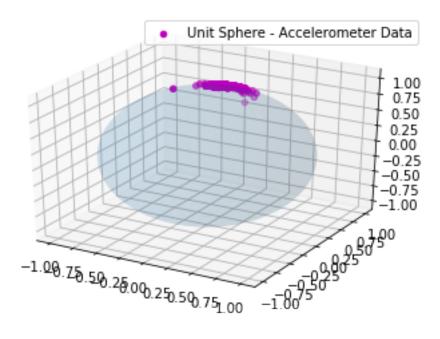
x_val = [row[0] for row in unit_sphere_data]
y_val = [row[1] for row in unit_sphere_data]
z_val = [row[2] for row in unit_sphere_data]
plot_unit_sphere_feature(x_val, y_val, z_val, 'Unit Sphere - Accelerometer Data', 'm')
```



In [16]: # calucate normalized vector and plot on sphere for the features you pick

```
data = data_acc_2
unit_sphere_data = []
step_size = 50
for i in range(0, len(data['Systime']) - step_size, step_size):
    v = [data['X'][i], data['Y'][i], data['Z'][i]]
    unit_sphere_data.append(normalize(v).tolist())

x_val = [row[0] for row in unit_sphere_data]
y_val = [row[1] for row in unit_sphere_data]
z_val = [row[2] for row in unit_sphere_data]
plot_unit_sphere_feature(x_val, y_val, z_val, 'Unit Sphere - Accelerometer Data', 'm')
```



In []: