# Homework 1

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## 1 Problem 1: Backpropogation in a simple Nueral Network

## 1.1 Part A: Dataset

The plot of the Two Moons dataset is displayed in Figure 1

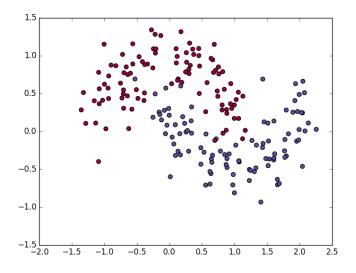


Figure 1: Two moons dataset displayed in matplotlib

## 1.2 Part B - Activation Functions

## 1.2.1 Part B1 - Implement activation functions

If you look in my code you can see I implemented the activations function.

#### 1.2.2 Part B2 - Derivative Derivations

#### Part B2.1 - Derivative for Sigmoid function

$$\sigma(z) = f(z) = \frac{1}{1 + e^{-z}} = (1 + e^{-z})^{-1}$$

$$\frac{df}{dz} := -1 * (1 + e^{-z})^{-2} * -e^{-z} = e^{-z} (1 + e^{-z})^{-2} \quad \text{(by chain rule)}$$

$$= \frac{e^{-z}}{(1 + e^{-z})^2}$$

$$= \frac{1 - e^{-z} + 1}{(1 + e^{-z})^2} \quad \text{(add and subtract a 1)}$$

$$= \frac{1 + e^{-z}}{(1 + e^{-z})^2} - \frac{1}{(1 + e^{-z})^2} \quad \text{(split terms)}$$

$$= \frac{1}{1 + e^{-z}} - \frac{1}{(1 + e^{-z})^2}$$

$$= \sigma(z) - \frac{1}{(1 + e^{-z})^2}$$

$$= \sigma(z) - \left(\frac{1}{(1 + e^{-z})}\right)^2$$

$$= \sigma(z) - \sigma(z)^2$$

$$f'(z) = \sigma(z)(1 - \sigma(z))$$

#### Part B2.2 - Derivative for Tanh function

$$f(z) = \tanh(z) = \frac{\sinh(z)}{\cosh(z)}$$

$$= \frac{e^z - e^{-z}}{e^z + e^{-z}}$$

$$\frac{df}{dz} := \frac{\cosh(z) * \sinh'(z) - \sinh(z) * \cosh'(z)}{(\cosh(z))^2} \quad \text{(by quotient rule)}$$

$$= \frac{\cosh(z)^2 - \sinh(z)^2}{(\cosh(z))^2}$$

$$= \frac{\cosh(z)^2}{\cosh(z)^2} - \frac{\sinh(z)^2}{\cosh(z)^2}$$

$$f'(z) = 1 - \tanh^2(z)$$

## Part B2.3 - Derivative for ReLu function

$$\label{eq:ReLu} \text{ReLu}(z) = f(z) = \max(0,z)$$
 
$$\boxed{\frac{df}{dz} := \left\{ \begin{array}{cc} 0 & z \leq 0 \\ 1 & z \geq 0 \end{array} \right.} \text{(I think the dirivitive here is pretty obvious)}$$

#### 1.2.3 Part B3 - Implement activation function gradiants

If you look in my code you can see I implemented the activations function gradiants.

#### 1.3 Part C - Build the Neural Network

If you look in my code you can see I implemented the feedforward and loss functions

## 1.4 Part D - Backpropogation Derivations

#### 1.4.1 Derivations of Backpropogation Equations

Keep in mind that the process for a single feedforward pass of the network is defined by the following equations with  $x \in \Re^p$  being a single data sample with p features,  $\mathbf{W_1} \in \Re^{n_1 \times p}$  is a weight matrix transitioning from the input later with p features to the number of units in hidden layer 1  $n_1$ ,  $b_1 \in \Re^{n_1}$  is a bias vector,  $z_1 \in \Re^{n_1}$  are a vector of potentials for layer 1,  $a_1 \in \Re^{n_1}$  the corresponding activations, and  $\hat{y}$  are the resulting probabilities.  $\mathbf{W_2} \in \Re^{n_2 \times n_1}$ ,  $a_1 \in \Re^{n_1}$ ,  $z_2 \in \Re^{n_2}$ 

$$z_1 = \mathbf{W_1}x + b_1$$

$$a_1 = \operatorname{actFun}(z_1)$$

$$z_2 = \mathbf{W_2}a_1 + b_2$$

$$a_2 = \hat{y} = \operatorname{softmax}(z_2)$$

Where the softmax function is given by:

$$\operatorname{softmax}(\mathbf{z})_c = \frac{e^{z_c}}{\sum_{d=1}^C e^{z_d}} = \frac{e^{z_c}}{\sum_C} \quad \text{for } c = 1 \cdots C$$

With a cross entropy loss function of:

$$L(y, \hat{y}) = -\frac{1}{N} \sum_{n \in N} \sum_{j \in C} y_{n,j} \log(\hat{y}_{n,j})$$

With y being a one hot vector of the correct label, N being the number of training examples and C being the number of classes.

For the following derivations, the derivative of the softmax  $\frac{\partial \hat{y}_i}{\partial z_j}$  is useful to know. It is calculated below. It is the derivative of  $\hat{y}$  with respect to one of the elements of the input vector z.

$$\hat{y} = \operatorname{softmax}(\mathbf{z})_c = \frac{e^{z_c}}{\sum_{d=1}^C e^{z_d}} = \frac{e^{z_c}}{\sum_C} \quad \text{for } c = 1 \cdots C$$

$$\operatorname{if } i = j : \quad \frac{\partial y_i}{\partial z_i} = \frac{\partial \frac{e^{z_i}}{\sum_C}}{\partial z_i}$$

$$= \frac{e^{z_i} \sum_C - e^{z_i} e^{z_i}}{\sum_C}$$

$$= \frac{e^{z_i}}{\sum_C} \frac{\sum_C - e^{z_i}}{\sum_C}$$

$$= \frac{e^{z_i}}{\sum_C} (1 - \frac{e^{z_i}}{\sum_C})$$

$$= y_i (1 - y_i)$$

$$\operatorname{if } i \neq j : \quad \frac{\partial y_i}{\partial z_j} = \frac{\partial \frac{e^{z_i}}{\sum_C}}{\partial z_j}$$

$$= \frac{0 - e^{z_i} e^{z_j}}{\sum_C}$$

$$= -\frac{e^{z_i}}{\sum_C} \frac{e^{z_j}}{\sum_C}$$

$$= -y_i y_i$$

The derivative of the cross entropy loss with respect to the second layer inputs are also a useful quantity to calculate, it is derived as follows. Note that I used the cross entropy for one example. Taking out the summation here makes things easier but I'll add it back in later.

$$\begin{split} \frac{\partial L}{\partial \hat{y}_j} \frac{\partial \hat{y}_j}{\partial z_{2i}} &= \frac{\partial L}{\partial z_{2i}} = -\sum_{j=1}^C \frac{\partial y_j log(\hat{y}_j)}{\partial z_i} \\ &= -\sum_{j=1}^C y_j \frac{\partial log(\hat{y}_j)}{\partial z_i} \\ &= -\sum_{j=1}^C y_j \frac{1}{\hat{y}_j} \frac{\partial \hat{y}_j}{\partial z_i} \\ &= -\frac{y_i}{\hat{y}_i} \frac{\partial \hat{y}_i}{\partial z_i} - \sum_{j\neq i}^C \frac{y_j}{\hat{y}_j} \frac{\partial \hat{y}_j}{\partial z_i} \quad \text{substitution from above derivation} \\ &= -\frac{y_i}{\hat{y}_i} \hat{y}_i (1 - \hat{y}_i) - \sum_{j\neq i}^C \frac{y_j}{\hat{y}_j} (-\hat{y}_j \hat{y}_i) \\ &= -y_i + y_i \hat{y}_i + \sum_{j\neq i}^C y_j \hat{y}_i \\ &= -y_i + \hat{y}_i \sum_{j=1}^C y_j \hat{y}_i \\ &= -y_i + \hat{y}_i \sum_{j=1}^C y_j \\ &= \hat{y}_i - y_i \end{split}$$

 $\frac{dL}{dW_2}$  **Derivation** We can rewrite the loss function with substituting in the feed-forward equations above as follows.

$$L(y, \hat{y}) = -\frac{1}{N} \sum_{n \in N} \sum_{j \in C} y_{n,j} \log(\hat{y}_{n,j})$$
$$\frac{\partial L}{\partial W_2} := \frac{\partial L}{\partial \hat{y}_{n,j}} \frac{\partial \hat{y}_{n,j}}{\partial z_2} \frac{\partial z_2}{\partial W_2}$$

Since j-th element of  $z_2$  is given by:

$$z_{2_j} = \sum_{k=0}^{n_1} w_{j,k} a_{1_k} + b_{2_j}$$

The derivitive of the j-th element of  $z_2$  w.r.t. weight  $w_{j,k}$  is then:

$$\begin{split} \frac{\partial z_{2_j}}{\partial w_{j,k}} &= a_{1_k} \\ \text{Using the derivation above for } \frac{\partial L}{\partial z_{2_j}} \\ \frac{\partial L}{\partial w_{2_{j,k}}} &= (\hat{y}_j - y_j) a_{1_k} \\ & \quad \vdots \\ \frac{dL}{dW_2} &= (\hat{\mathbf{y}} - \mathbf{y}) \mathbf{a_1^T} \in \Re^{n_2 \times n_1} \end{split}$$

The above equation only takes into consideration on data point.

We extend this to multiple samples by plugging in the summation we originally took out.

$$\boxed{\frac{dL}{dW_2} = \frac{1}{N} \sum_{n \in N} (\hat{\mathbf{y}}_{\mathbf{n}} - \mathbf{y}_{\mathbf{n}}) \mathbf{a}_{\mathbf{1}}^{\mathbf{T}} \in \Re^{n_2 \times n_1}}$$

 $\frac{dL}{db_2}$  **Derivation** This derivation will be fairly similar to the previous section except now the gradient looks as follows:

$$\frac{\partial L}{\partial b_2} := \frac{\partial L}{\partial \hat{y}_{n,j}} \frac{\partial \hat{y}_{n,j}}{\partial z_2} \frac{\partial z_2}{\partial b_2}$$

Since j-th element of  $z_2$  is given by:

$$z_{2_j} = \sum_{k=0}^{n_1} w_{j,k} a_{1_k} + b_{2_j}$$

The derivitive of the j-th element

of  $z_2$  w.r.t. bias  $b_{2_k}$  is then:

$$\frac{\partial z_{2_j}}{\partial b_{2_k}} = 1$$

Using the derivation above for

$$\frac{\partial L}{\partial b_{2_k}} = (\hat{y}_j - y_j)$$

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$$\frac{dL}{db_2} = \mathbf{\hat{y}} - \mathbf{y} \in \Re^{n_2}$$

The above equation only takes into consideration on data point.

We extend this to multiple samples by plugging in the summation we originally took out.

$$\boxed{\frac{dL}{db_2} = \frac{1}{N} \sum_{n \in N} \hat{\mathbf{y}}_{\mathbf{n}} - \mathbf{y}_{\mathbf{n}} \in \Re^{n_2}}$$

 $\frac{dL}{dW_1}$  **Derivation** We add one more layer to our previous derivation of  $\frac{dL}{dW_2}$  for this derivation. The derivative can be expanded as follows

$$\frac{\partial L}{\partial W_1} := \frac{\partial L}{\partial \hat{y}_{n,j}} \frac{\partial \hat{y}_{n,j}}{\partial z_2} \frac{\partial z_2}{\partial a_1} \frac{\partial a_1}{\partial z_1} \frac{\partial z_1}{\partial W_1}$$

So we need to figure out the term  $\frac{\partial z_2}{\partial a_1} \frac{\partial a_1}{\partial z_1} \frac{\partial z_1}{\partial W_1}$  by piecing to out. The *j*-th element of  $z_1$  is given by:

$$z_{1_j} = \sum_{i=0}^{p} w_{1_{j,i}} x_i + b_{1_j}$$

So the derivative w.r.t.  $w_{1_{j,i}}$  is then:

$$\frac{\partial z_{1_j}}{\partial w_{1_{i,j}}} = x_i$$

We know from part b that  $\frac{\partial a_1}{\partial z_1}$  is dependent on the type of activation function but we derived all the derivatives of the three activation functions above so stating the derivatives is redundant. See the above part B.

$$\frac{\partial a_1}{\partial z_1} = \operatorname{actFun}'(z_1)$$
 (See part B above)

The last part we need to derive is the  $\frac{\partial z_2}{\partial a_1}$  term.

Since the j-th element of  $z_2$  is given by:

$$z_{2_j} = \sum_{k=0}^{n_1} w_{2_{j,k}} a_{1_k} + b_{2_j}$$

we can conclude that the derivative w.r.t.  $a_{1_k}$  is given by

$$\frac{\partial z_{2_j}}{\partial a_{1_k}} = w_{2_{j,k}}$$

From above, we know that the other partial derivatives are

$$\frac{\partial L}{\partial \hat{y}_j}\frac{\partial \hat{y}_j}{\partial z_{2_i}} = \frac{\partial L}{\partial z_{2_i}} = \hat{y}_i - y_i$$

So if we piece this all together we come up with:

$$\frac{\partial L}{\partial w_{1_{k,p}}} := \frac{\partial L}{\partial \hat{y}_{n,c}} \frac{\partial \hat{y}_{n,c}}{\partial z_{2_c}} \frac{\partial z_{2_c}}{\partial a_{1_k}} \frac{\partial a_{1_k}}{\partial z_{1_k}} \frac{\partial z_{1_k}}{\partial w_{1_{k,p}}}$$

Which I changed some of the indexing to make the most sense. In this format  $n \in N, c \in C$ ,  $k \in \{0,...,n_1-1\}, p \in \{0,...,P-1\}$  with P input features. The resulting derivative with respect to one weight in the first layer  $w_{1_{k,p}}$  is then:

$$\frac{\partial L}{\partial w_{1_{k,p}}} = \sum_{c \in C} (\hat{y}_c - y_c) w_{2_{c,k}} \operatorname{actFun}'(z_{2_k}) x_p$$

and the extention to matrix form is then

$$\frac{\partial L}{\partial \mathbf{W_1}} = \sum_{c \in C} (\hat{y}_c - y_c) \mathbf{W_2} \odot \operatorname{actFun}'(\mathbf{z_2}) \mathbf{x^T} \in \Re^{n_1 \times n_2}$$

If there is morethan one sample (which there always is)

then we averageover all of the samples and the final solution is then

$$\frac{\partial L}{\partial \mathbf{W_1}} = \sum_{n \in N} \sum_{c \in C} (\hat{y}_{n,c} - y_{n,c}) \mathbf{W_2} \odot \operatorname{actFun'}(\mathbf{z_2}) \mathbf{x^T} \in \Re^{n_1 \times n_2}$$

 $\frac{dL}{db_1}$  **Derivation** The derivation is very similar to the  $\frac{dL}{dW_1}$  except the last part of the chain of partial derivatives is changed. The gradient equation of the Loss function with respect to a single bias term in the first layer is

$$\frac{\partial L}{\partial b_{1_k}} := \frac{\partial L}{\partial \hat{y}_{n,c}} \frac{\partial \hat{y}_{n,c}}{\partial z_{2_c}} \frac{\partial z_{2_c}}{\partial a_{1_k}} \frac{\partial a_{1_k}}{\partial z_{1_k}} \frac{\partial z_{1_k}}{\partial b_{1_k}}$$

So we only need to calculate  $\frac{\partial z_{1_k}}{\partial b_{1_k}}$  first. Let's look at how the k th value is calculated.

$$z_{1_k} = \sum_{i=0}^{p} w_{1_{k,i}} x_i + b_{1_k}$$

So the derivative w.r.t.  $b_{1_k}$  is then:

$$\frac{\partial z_{1_j}}{\partial b_{1_k}} = 1$$

The partial derivative  $\frac{\partial z_{1_k}}{\partial b_{1_k}}=1$  simplified the equation for the partial derivative of the loss function w.r.t.  $b_{1_k}$  as

$$\frac{\partial L}{\partial b_{1_k}} = \sum_{c \in C} (\hat{y}_c - y_c) w_{2_{c,k}} \operatorname{actFun}'(z_{2_k})$$

and the resulting matrix form is then

$$\frac{\partial L}{\partial \mathbf{b_1}} = \sum_{c \in C} (\hat{y}_c - y_c) \mathbf{W_2} \odot \operatorname{actFun'}(\mathbf{z_2}) \in \Re^{n_1}$$

If there is more than one sample (which there always is) then we have to sum up and average over all samples and the gradient becomes

$$\frac{\partial L}{\partial \mathbf{b_1}} = \sum_{n \in N} \sum_{c \in C} (\hat{y}_{n,c} - y_{n,c}) \mathbf{W_2} \odot \operatorname{actFun}'(\mathbf{z_2}) \in \Re^{n_1}$$

#### 1.4.2 Implementation of Derivations of Backpropagation Equations

If you look in my code you can see I implemented the backpropogation equations