$$\frac{1}{41} \frac{\partial C}{\partial t} = D \frac{\partial x^2}{\partial x^2}$$

using V. Neumann

for Crank Nicolson, it was seen through experiments that even at Dt= 15 which is only one solution between 25 & 45 it still produced an accurate and stable answer

$$0 = \frac{Dot}{o \times 2} = \frac{(O.1)(1)}{0.05} = 2$$
 so even for $0 > \frac{1}{2} & 0 > 1$

His still good

Homework 3

Number 1 a)

Below is the plot for the diffusion equation using Runge-Kutta 4th Order Method. The time step used is 0.0125s as shown in the written work. It can be seen that the numerical solution at t=4s matches exactly on top of the analytical solution.

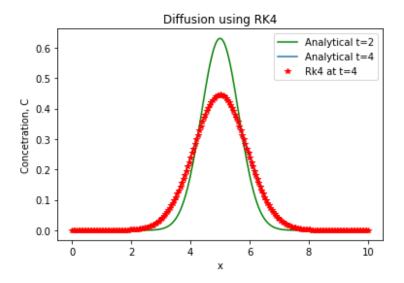


Figure 1: 1a) Diffusion Equation using Runge-Kutta 4

Number 1 b)

Below is the plot for the diffusion equation using Crank-Nicolson method. Upon experimenting with various time steps. It can be seen that it is stable even for high values of dt. The time step used below is t=1s which is the highest possible value that would make sense in this case. It can be seen that the numerical solution at t=4s still matches exactly on top of the analytical solution.

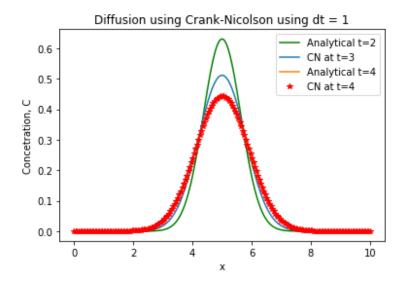


Figure 2: 1b) Diffusion Equation using Crank-Nicolson

Number 2)

Given the boundary conditions of the rectangular copper plate and the Laplace's equation, the analytical solution of the steady state was given and can be shown by the plot below.

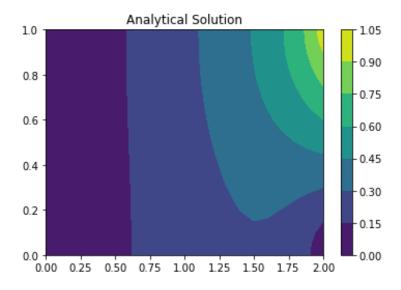


Figure 3: 2) Analytical Solution of the Laplace Equation

For this problem, this will be solved iteratively by using the given equation for the residual and prescribing a tolerance of 10^{-6}

Number 2 a)

The figure below shows the equation solved using Jacobi. The number of iterations can be seen at the summary at the end.

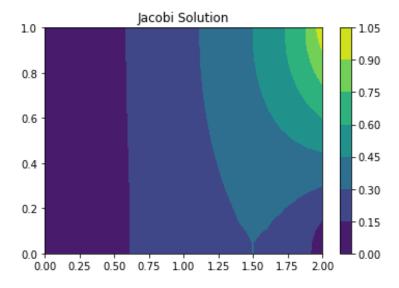


Figure 4: 2a) Laplace Equation using Jacobi

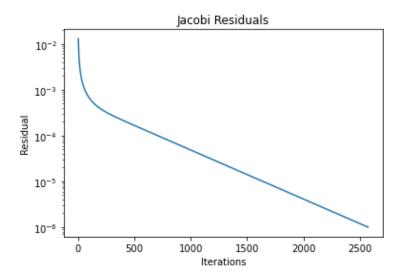


Figure 5: 2a) Residuals from Laplace Equation using Jacobi

Number 2 b)

The figure below shows the equation solved using Gauss-Seidel. It can be seen that it converges earlier than than the Jacobi solution. Using this method can have a bias when doing the i or j index first but when run both cases, did not pose any difference to the number of iterations.

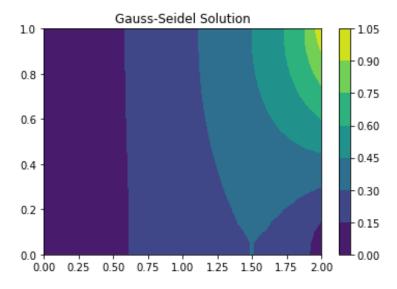


Figure 6: 2b) Laplace Equation using Gauss-Seidel

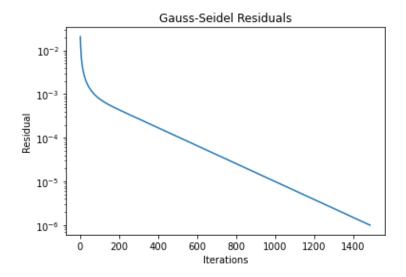


Figure 7: 2b) Residuals from Laplace Equation using Gauss-Seidel

Number 2 c)

The Successive-Over Relaxation (SOR) method was used across multiple values of w. The effect of w on iterations can be seen below. It can be seen that most of the iterations were higher than 2000 which was used as a ceiling. This shows that when using the wrong w, it can be more expensive to use.

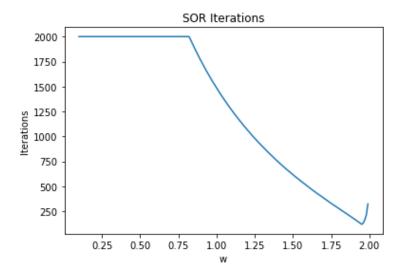


Figure 8: 2c) Effect of w on iterations using SOR

Using w=1.95 produced the lowest number of iterations and is used to produce the plot below.

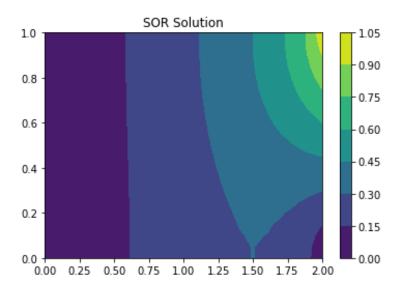


Figure 9: 2c) Laplace Equation using SOR



Figure 10: 2c) Residuals from Laplace Equation using SOR

The table below shows the number of iterations to convergence using the different methods.

	Jacobi	Gauss-Seidel	SOR
Iterations	2574	1486	118
Final Residual	9.978e-7	9.976e-7	9.643

Table 1: Validation Accuracy vs. Type of Activation Function with no Softmax

It can be seen from above that although all of the methods gave substantial results compared to the analytical solution, the number of iterations is drastically different. Gauss-Seidel is better than Jacobi. Using SOR drastically decreases the iterations given that the right value of w is used. If not, then it will be more computationally expensive to do so.

Appendix)

Python Code for 1

```
1 import numpy as np
2 import matplotlib.pyplot as plt
3 from numpy import linalg as la
5 \times 0 = 5
6 D = 0.1
  def Canal(x,t):
      return 1/(np.sqrt(4*np.pi*D*t)) * np.exp(-(x-x0)**2/(4*D*t))
10
  N = 200
11
12
x = np.linspace(0,10,N+1)
14 dx = 10/N
15 #print(dx)
dt = np.round(dx**2/(2*D),10)
^{17} #dt = 0.0142 # hmm only stops working at 0.0142
18 print(dt)
19 numt = int(np.floor(2/dt))
20 #print(numt)
21 t = np.linspace(2,4,numt+1)
22 #print(t[0])
23 #print(t[1])
print('CFL is', str(4*dt/dx))
```

```
26 def bound(f):
       f[0] = 0
27
       f[-1] = 0
28
29
       return f
30
31 cti = Canal(x,2)
32 bound(cti)
33 ctf = Canal(x,4)
34 bound(ctf)
36 ''' Right Hand Side Functions '''
37 def CS(f, n, i):
       RHS = D * (f[n][i+1] - 2*f[n][i] + f[n][i-1]) / (dx)**2
38
39
       return RHS
''', Left Hand Side Functions '''
41 def Rk4(f, n, i):
      k0 = CS(f,n,i)
42
       k1 = CS(f,n,i) + dt/2 * k0
43
44
       k2 = CS(f,n,i) + dt/2 * k1
      k3 = CS(f,n,i) + dt * k2
45
46
       df = (k0 + 2*k1 + 2*k2 + k3) / 6
      LHS = f[n][i] + dt * df
47
48
      return LHS
49
50
51 # Exact Solution at t=2 and t=4
52 fig, ax = plt.subplots()
53 ax.plot(x, cti)
54 ax.plot(x, ctf)
55 plt.show()
C = np.zeros((len(t), len(x)))
58 C[0] = cti
59 for n in range(len(t)-1):
      for i in np.arange(N):
           C[n+1][i] = Rk4(C, n, i)
61
       C[n+1] = bound(C[n+1])
62
64 # Analytical Solution
65 plt.plot(x, C[0], 'g', label='Analytical t=2')
66 #ax.plot(x, C[40],'g')
67 #ax.plot(x, C[80],'g')
68 #ax.plot(x, C[120],'g')
69 plt.plot(x, ctf, label='Analytical t=4')
70 plt.plot(x, C[-1],'r*', label='Rk4 at t=4')
71 plt.legend()
plt.title('Diffusion using RK4')
73 plt.xlabel('x')
74 plt.ylabel('Concetration, C')
75 plt.show()
78 #### Part 2 Crank Nicolson
79 dt = 1
80 # dt works even as high as 2
81 numt = int(np.floor(2/dt))
82 print(numt)
t = np.linspace(2,4,numt+1)
84 print(t)
85 print('CFL is', str(4*dt/dx))
87 C = np.zeros((len(t), len(x)))
88 C[0] = cti
89 for n in np.arange(1,len(t)):#range(len(t)-1):
90
       A = np.zeros((len(x), len(x)))
       B = np.zeros(len(x))
91
       d = D*dt/(2*dx**2)
92
       B[0] = 0
B[-1] = 0
93
94
       A[0][0] = 1
95
A \begin{bmatrix} -1 \end{bmatrix} \begin{bmatrix} -1 \end{bmatrix} = 1
```

```
#print(C[0])
97
98
       for i in np.arange(1,len(B)-1):
99
           A[i,i-1] = -d
           A[i,i] = 1+2*d
100
101
           A[i,i+1] = -d
           B[i] = d*C[n-1][i-1] + (1-2*d)*C[n-1][i] + d*C[n-1][i+1]
102
103
      C[n] = la.solve(A,B)
104
105
107 # Analytical Solution
plt.plot(x, C[0], 'g', label='Analytical t=2')
109 plt.plot(x, C[1], label = 'CN at t=3')
plt.plot(x, ctf, label='Analytical t=4')
plt.plot(x, C[-1],'r*', label='CN at t=4')
plt.legend()
plt.title('Diffusion using Crank-Nicolson using dt = 1')
plt.xlabel('x')
plt ylabel ('Concetration, C')
116 plt.show()
```

Python Code for 2

```
1 # -*- coding: utf-8 -*-
3 Created on Mon Dec 5 16:33:14 2022
5 Cauthor: jjser
8 import numpy as np
9 import matplotlib.pyplot as plt
10 import math
12 # Initializing Everything
13 ni = 21 # 20
14 nj = 21 # 20
15 x = np.zeros((ni,nj))
16 y = np.zeros((ni,nj))
dx = 2/(ni-1)
dy = 1/(nj-1)
19
  def bound(arr):
      ni,nj = arr.shape
21
      # Create top and bottom to be dy/dx = 0
22
23
      for i in range(ni):
          arr[i,0] = arr[i,1]
24
25
      for i in range(ni):
          arr[i,-1] = arr[i,-2]
26
27
      # Initialize boundary condition f(0) = 0
      arr[0,:] = 0
28
      # Initialize boundary condition f(y) = y
29
30
      for j in range(nj):
          arr[-1,j] = y[-1,j]
31
32
      return arr
33 def grid():
34
      # Initializing the Grid x and y
      for i in np.arange(0,ni): # goes from 1 to ni
35
          for j in np.arange(0,nj): # goes from 1 to nj
36
               x[i,j] = (i) * 2.0 / (ni-1)
37
               y[i,j] = (j) * 1.0 / (nj-1)
38
39
40
  def anal():
      u = np.zeros((ni,nj))
41
      for i in np.arange(0,ni): # goes from 1 to ni
42
          for j in np.arange(0,nj): # goes from 1 to nj
43
               u[i,j] = x[i,j] / 4
45
               for n in (np.arange(10) * 2 + 1):
                   u[i,j] -= 4 * (np.sinh(n*math.pi*x[i,j]) * np.cos(n*math.pi*y[i,j])) / ( (n*
      math.pi)**2 * np.sinh(2*n*math.pi)
      return u
47
48 def jaco():
```

```
49
       TOL = 1e-6
50
       res = 1
51
       MAXITE = 3000
       ite = 0
52
53
       resp = []
54
       u = np.zeros((ni,nj))
55
       u = bound(u)
56
       uk = u.copy()
       uk1 = u.copy()
57
       while res > TOL and ite < MAXITE:</pre>
58
           ite += 1
59
           res = 0
60
61
           for j in np.arange(1,nj-1): # goes from 2 to nj-1
               for i in np.arange(1,ni-1): # goes from 2 to ni-1
62
                   uk1[i,j] = ((uk[i-1,j] + uk[i+1,j])/dx**2 + (uk[i,j-1] + uk[i,j+1])/dy**2)
63
        * (1 / (2/dx**2 + 2/dy**2))
           # Compute Residual
           for i in np.arange(1,ni-1): # goes from 2 to ni-1
65
               for j in np.arange(1,nj-1): # goes from 2 to nj-1
66
                   res += (uk1[i,j]-uk[i,j])**2
67
           res = math.sqrt(res / ((ni-2)*(nj-2)))
68
69
           resp.append(res)
           uk = bound(uk1).copy()
70
71
       ufin = bound(uk1)
72
       return ufin, ite, resp
  def gase():
73
       TOL = 1e-6
74
       res = 1
       MAXITE = 2000
76
      ite = 0
       resp = []
78
79
       u = np.zeros((ni,nj))
       u = bound(u)
80
       uk = u.copy()
81
82
       uk1 = u.copy()
       while res > TOL and ite < MAXITE:
83
           ite += 1
84
           res = 0
85
86
           for j in np.arange(1,nj-1): # goes from 2 to nj-1
               for i in np.arange(1,ni-1): # goes from 2 to ni-1
87
                   uk1[i,j] = ((uk1[i-1,j] + uk1[i+1,j])/dx**2 + (uk1[i,j-1] + uk1[i,j+1])/dy
88
       **2 ) * (1 / (2/dx**2 + 2/dy**2) )
           # Compute Residual
89
           for i in np.arange(1,ni-1): # goes from 2 to ni-1
90
               91
                   res += (uk1[i,j]-uk[i,j])**2
92
           res = math.sqrt(res / ((ni-2)*(nj-2)))
93
           resp.append(res)
94
95
           uk = bound(uk1).copy()
       ufin = bound(uk1)
96
97
       return ufin, ite, resp
   def gase2():
98
       TOL = 1e-6
99
      res = 1
100
       MAXITE = 2000
101
102
       ite = 0
       resp = []
103
       u = np.zeros((ni,nj))
104
      u = bound(u)
105
106
       uk = u.copy()
107
       uk1 = u.copy()
       while res > TOL and ite < MAXITE:</pre>
108
109
           ite += 1
           res = 0
110
           for i in np.arange(1,ni-1): # goes from 2 to nj-1
111
               for j in np_arange(1,nj-1): # goes from 2 to ni-1
                   uk1[i,j] = ((uk1[i-1,j] + uk1[i+1,j])/dx**2 + (uk1[i,j-1] + uk1[i,j+1])/dy
       **2) * (1 / (2/dx**2 + 2/dy**2))
           # Compute Residual
114
           for i in np.arange(1,ni-1): # goes from 2 to ni-1
               for j in np.arange(1,nj-1): # goes from 2 to nj-1
                  res += (uk1[i,j]-uk[i,j])**2
```

```
118
           res = math.sqrt(res / ((ni-2)*(nj-2)))
119
           resp.append(res)
120
           uk = bound(uk1).copy()
       ufin = bound(uk1)
121
       return ufin, ite, resp
123 def sor(w):
124
       TOL = 1e-6
       res = 1
125
       MAXITE = 2000
126
       ite = 0
127
       resp = []
128
       u = np.zeros((ni,nj))
129
       #u = np.random.rand(ni,nj)
130
       u = bound(u)
       uk = u.copy()
       uk1 = u.copy()
133
       while res > TOL and ite < MAXITE:</pre>
134
           ite += 1
135
           res = 0
136
           for j in np.arange(1,nj-1): # goes from 2 to nj-1
               for i in np.arange(1,ni-1): # goes from 2 to ni-1
138
139
                   uk1[i,j] = w * ((uk1[i-1,j] + uk1[i+1,j])/dx**2 + (uk1[i,j-1] + uk1[i,j+1])
       /dy**2 ) * (1 / (2/dx**2 + 2/dy**2) ) + (1-w)*uk[i,j]
140
           # Compute Residual
           for i in np.arange(1,ni-1): # goes from 2 to ni-1
141
               for j in np.arange(1,nj-1): \# goes from 2 to nj-1
142
                   res += (uk1[i,j]-uk[i,j])**2
143
           res = math.sqrt(res / ((ni-2)*(nj-2)))
144
           #print(res)
145
           resp.append(res)
146
           uk = bound(uk1).copy()
147
148
       ufin = bound(uk1)
       return ufin, ite, resp
149
150
151 grid()
152
153 #### Analytical Solution
154 u = anal()
155 cs = plt.contourf(x,y,u)
156 plt.colorbar(cs)
plt.title('Analytical Solution')
158 plt.show()
159
160
161 #### Jacobi ####
162 u, ite, resp = jaco()
163 print(' #### Jacobi ####')
print('Iterations to Convergence:', str(ite))
print('Final residual: ', str(np.round(resp[-1],10)) )
166 cs = plt.contourf(x,y,u)
167 plt.colorbar(cs)
plt.title('Jacobi Solution')
169 plt.show()
plt.plot(np.arange(1,ite+1), resp)
plt title('Jacobi Residuals')
plt.xlabel('Iterations')
plt.ylabel('Residual')
174 plt.yscale('log')
175 plt.show()
176
177
178 #### Gauss-Seidel ####
179 u, ite, resp = gase()
180 print(' #### Gauss-Seidel ####')
print('Iterations to Convergence:', str(ite))
print('Final residual: ', str(np.round(resp[-1],10)) )
cs = plt.contourf(x,y,u)
plt.colorbar(cs)
plt.title('Gauss-Seidel Solution')
186 plt.show()
plt.plot(np.arange(1,ite+1), resp)
```

```
189 plt.title('Gauss-Seidel Residuals')
plt.xlabel('Iterations')
plt.ylabel('Residual')
plt.yscale('log')
193 plt.show()
194
195 #### Gauss-Seidel ####
u, ite, resp = gase2()
197 print(' #### Gauss-Seidel ####')
print('Iterations to Convergence:', str(ite))
print('Final residual: ', str(np.round(resp[-1],10)) )
200 cs = plt.contourf(x,y,u)
201 plt.colorbar(cs)
plt.title('Gauss-Seidel Solution')
203 plt.show()
204
205 plt.plot(np.arange(1,ite+1), resp)
206 plt title('Gauss-Seidel Residuals')
plt.xlabel('Iterations')
208 plt.ylabel('Residual')
209 plt.yscale('log')
210 plt.show()
211
212
#### Successive - Over Relaxation ###
214 wlist = np.arange(0.1,2,0.01)
215 itesor = np.zeros(len(wlist))
216 for i, w in enumerate(wlist):
      u, ite, resp = sor(w)
      itesor[i] = ite
218
219 plt.plot(wlist,itesor)
220 plt.title('SOR Iterations')
plt.xlabel('w')
222 plt.ylabel('Iterations')
223 plt.show()
224 m = np.argmin(itesor)
225 mini = np.min(itesor)
226 print(' #### SOR ####')
print('w at Minimum Iterations:', str(int(mini)) )
228 print('Minimum Iterations: ', str(np.round(wlist[m],5)) )
230 u, ite, resp = sor( np.round(wlist[m],5) )
231 print(' #### SOR ####')
232 print('Iterations to Convergence:', str(ite))
print('Final residual: ', str(np.round(resp[-1],10)) )
cs = plt.contourf(x,y,u)
235 plt.colorbar(cs)
plt.title('SOR Solution')
237 plt.show()
plt.plot(np.arange(1,ite+1), resp)
239 plt.title('SOR Residuals')
240 plt.xlabel('Iterations')
plt.ylabel('Residual')
plt.yscale('log')
243 plt.show()
```