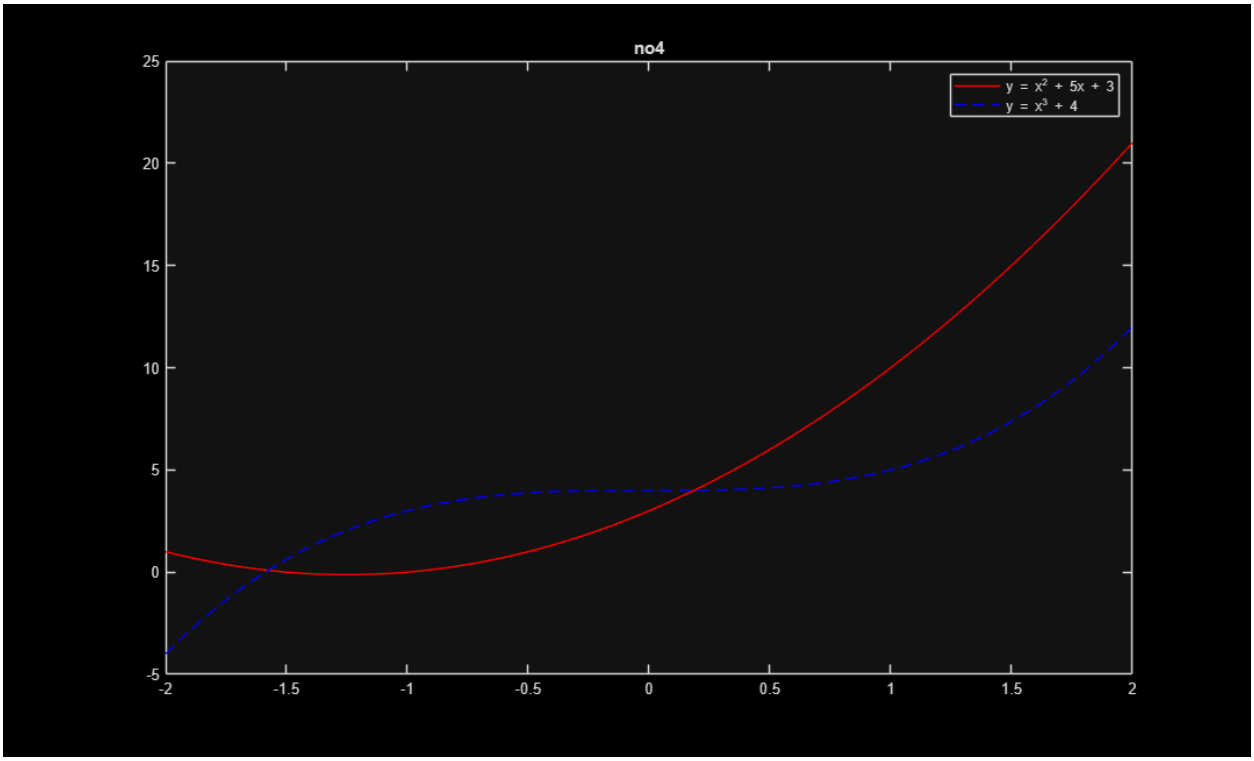
```
% CPE 3102 - FEEDBACK AND CONTROL SYSTEMS
% Group 3   TTh 10:30 AM - 1:30 PM LB265 TC
% Sarcol, Joshua S      BS-CpE 3        2025/09/10
% LE1 | Introduction to Matlab #1a

% 1a
A = [2 1 1;
     0 -3 4];

B = [3 -1 3;
     2 0 5];

no1a = A + B

% 1b
A = [1 2;
     3 0];

B = [1 3;
    0 -4];

no1b = 3*A - 2*B

% 1c
no1c = 5*A - 2*B

% 2
A = [1 2;
     3 0];

B = [2 -1;
     3 4];

C = [1 3;
     4 -1];

no2 = C * (A + B)

% 3
no3 = C*A + C*B

% 4
x = -2:0.01:2;
a = polyval([2 5 3], x);
b = polyval([1 0 0 4], x);

figure(1)
plot(x, a, "r")
hold on
plot(x, b, "b--")
legend(["y = x^2 + 5x + 3" "y = x^3 + 4"])
title("no4")
```

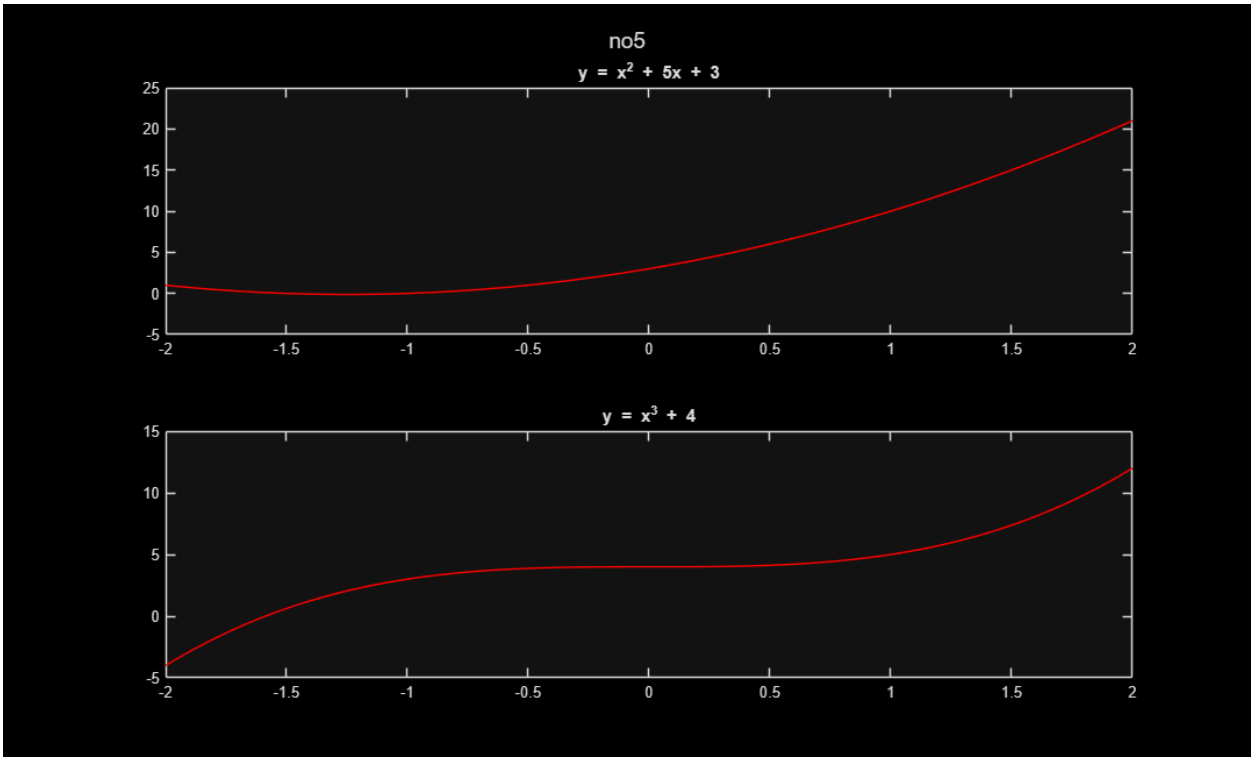
```
hold off

% 5
figure(2)
subplot(2, 1, 1)
plot(x, a, "r")
title("y = x^2 + 5x + 3")

subplot(2, 1, 2)
plot(x, b, "r")
title("y = x^3 + 4")

sgtitle("no5")

% 6a
p1 = [1 32 8 85 4 1 3 1];
no6a = roots(p1)

% 6b
p2 = [3 -1 24 9 6 2];
no6b = roots(p2)

% 6c
p3 = [1 77 11 1];
no6c = roots(p3)

% 7a
no7a = conv(p1, p2)

% 7b
no7b = conv(p1, p3)
```

```
no1a =

     5     0     4
     2    -3     9


no1b =

     1     0
     9     8


no1c =

     3     4
    15     8


no2 =

    21    13
```

```
     6     0


no3 =

    21    13
     6     0


no6a =

 -31.8324 + 0.0000i
  -0.0669 + 1.6287i
  -0.0669 - 1.6287i
   0.2275 + 0.3069i
   0.2275 - 0.3069i
  -0.2444 + 0.1458i
  -0.2444 - 0.1458i


no6b =

   0.3600 + 2.8093i
   0.3600 - 2.8093i
  -0.0216 + 0.4914i
  -0.0216 - 0.4914i
  -0.3435 + 0.0000i


no6c =

 -76.8570 + 0.0000i
  -0.0715 + 0.0889i
  -0.0715 - 0.0889i


no7a =

  Columns 1 through 6

           3          95          16        1024         413        2305

  Columns 7 through 12

         981         586         274          65          29          12

  Column 13

           2


no7b =

  Columns 1 through 6
```

```
     1     109    2483    1054    6669    1252

Columns 7 through 11

   209     247     111      14       1
```





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